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Convex Hull of a simple polygon: algorithm of Lee

Pavla Balíková

CONTENT

Basic information about Lee's algorithm

• The algorithm in steps

Complexity

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LEE'S ALGORITHM (1983)

Decomposition plane to regions – different actions

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• Vertices are enumerated counterclockwise

No collinear points

Input - connected simple polyline

no self-intersections of lines



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EXPLANATION OF ALGORITHM

- 1. Locate the vertex with minimum y-coordinate
- 2. Push it on the stack
- 3. Push the next vertex counterclockwise
- 4. Call the next vertex active vertex (AV)
- 5. If the active vertex is NOT to the left of L
 - Delete the top element of the stack
 - If only Ymin is left, push the active vertex and get the next one

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- Recompute L
- Go back to (5)

EXPLANATION OF ALGORITHM

- 6. If the AV is to the left of L
- Case 1: AV is in the pocket of the top two vertices of the stack
 - Ignore the AV, make the next vertex active and go back to (5).
- 8. Case 2: AV is not in the pocket, but is inside the convex polygon of the stack
 - Ignore the active vertex, make the next vertex active and go back to (5)

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- 9. Case 3: otherwise
 - Push the AV onto the stack
 - Recompute L and go back to (5)

COMPLEXITY

- Space O(n) stack
- Time O(n)
 - No sorting points
 - Input connected simple polyline

SOURCES

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