

# Bayesian Networks I

# Part 1: Probability Refresher

# Notation

We will use the following notation (*same as we used for stochastic processes*):

$$P[X_1 = x_1 \wedge X_2 = x_2 \wedge \dots \wedge X_n = x_n] = P(x_1, x_2, \dots, x_n).$$

# Joint Distributions

Given random variables  $X_1, X_2, \dots, X_n$ , their joint distribution is the probability distribution on tuples  $(x_1, x_2, \dots, x_n)$  of their possible values, i.e. for us it will be given by:

$$P[X_1 = x_1 \wedge X_2 = x_2 \wedge \dots \wedge X_n = x_n] = P(x_1, x_2, \dots, x_n)$$

## Example:

$X_1$  is a binary random variable which is 1 if it rains and 0 otherwise,

$X_2$  is a binary random variable which is 1 if it is sunny and 0 otherwise,

$X_3$  is a binary random variable which is 1 if there is a rainbow and 0 otherwise.

Then  $P(1,0,1)$  is the probability that, at the same time: it rains, it is not sunny and there is a rainbow (*we would expect this probability to be close to 0*).

# Joint Distribution (Example)

$P(x_1, x_2, x_3)$  from the previous slide, i.e.  $P(\text{rains}, \text{sunny}, \text{rainbow})$ , represented as a table.

rains	sunny	rainbow	P
0	0	0	0.4
0	0	1	0
0	1	0	0.2
0	1	1	0
1	0	0	0.2
1	0	1	0
1	1	0	0.1
1	1	1	0.1

# Marginal Distributions

Given a joint distribution on random variables  $X_1, X_2, \dots, X_n$ , and their subset  $\mathcal{A} = \{X_{i_1}, X_{i_2}, \dots, X_{i_k}\} \subseteq \{X_1, X_2, \dots, X_n\}$ , the marginal distribution of the variables  $X_{i_1}, X_{i_2}, \dots, X_{i_k}$  is their distribution

$$P_{\mathcal{A}}(x_{i_1}, x_{i_2}, \dots, x_{i_k}) = P[X_{i_1} = x_{i_1} \wedge \dots \wedge X_{i_k} = x_{i_k}]$$

and it satisfies:

$$P_{\mathcal{A}}(x_{i_1}, x_{i_2}, \dots, x_{i_k}) = \sum_{x_{j_1}, x_{j_2}, \dots, x_{j_{n-k}}} P[X_{i_1} = x_{i_1} \wedge X_{i_2} = x_{i_2} \wedge \dots \wedge X_{i_k} = x_{i_k} \wedge X_{j_1} = x_{j_1} \wedge X_{j_2} = x_{j_2} \wedge \dots \wedge X_{j_{n-k}} = x_{j_{n-k}}]$$

Each of these  $x_{j_1}, \dots, x_{j_{n-k}}$  is summed over its range, e.g. if it is binary then over  $\{0,1\}$  etc.

# Marginal Distributions - Example (1/2)

Recall the table:

$X_1$ (rains)	$X_2$ (sunny)	$X_3$	$P$
0	0	0	0.4
0	0	1	0
0	1	0	0.2
0	1	1	0
1	0	0	0.2
1	0	1	0
1	1	0	0.1
1	1	1	0.1

What is the probability  $P[X_2 = 1]$ ? That is... What is the probability that it is sunny?

*In our notation,  $\mathcal{A} = \{X_2\}$ ,  $P_{\mathcal{A}}(x) = P[X_2 = x]$ . Or using the alternative notation when  $\mathcal{A}$  is a singleton, also  $P_{X_2}(x) = P[X_2 = x]$ .*

# Marginal Distributions - Example (2/2)

Recall the table:

$X_1$ (rains)	$X_2$ (sunny)	$X_3$	<b>P</b>
0	0	0	0.4
0	0	1	0
0	1	0	0.2
0	1	1	0
1	0	0	0.2
1	0	1	0
1	1	0	0.1
1	1	1	0.1

What is the probability  $P[X_2 = 1]$ ? That is... What is the probability that it is sunny?

$$P[X_2 = 1] = P(0,1,0) + P(0,1,1) + P(1,1,0) + P(1,1,1) = 0.2 + 0 + 0.1 + 0.1 = 0.4$$

# Conditional Distribution (1/2)

**Special case (two random variables  $X$  and  $Y$ ):**

Conditional probability of  $X$  given  $Y$  is defined as:

$$P[X = x | Y = y] = \frac{P[X = x \wedge Y = y]}{P[Y = y]} = \frac{P(x, y)}{P_Y(y)}.$$

Undefined for  $y$ 's that have zero probability, i.e. when  $P[Y = y] = 0$ .

We will use the notation  $P_{X|Y}(x | y) = P[X = x | Y = y]$ .

*(To simplify many formulas, we normally use the assumption that undefined  $\cdot 0 = 0$ , so for instance it will allow us to write  $P(x, y) = P_{X|Y}(x | y)P_Y(y) = P_{Y|X}(y | x)P_X(x)$  for all values  $x, y$ .)*

# Conditional Distribution (2/2)

## General case

Conditional probability of  $\mathbf{Y} = (X_{i_1}, X_{i_2}, \dots, X_{i_k})$  given  $\mathbf{Z} = (X_{j_1}, X_{j_2}, \dots, X_{j_l})$  is defined as:

$$P[\mathbf{Z} = \mathbf{z} | \mathbf{Y} = \mathbf{y}] = \frac{P[\mathbf{Z} = \mathbf{z} \wedge \mathbf{Y} = \mathbf{y}]}{P[\mathbf{Y} = \mathbf{y}]} = \frac{P_{\mathbf{Z}, \mathbf{Y}}(\mathbf{z}, \mathbf{y})}{P_{\mathbf{Y}}(\mathbf{y})},$$

where  $\mathbf{z} = (z_1, z_2, \dots, z_l)$  and  $\mathbf{y} = (y_1, y_2, \dots, y_k)$ .

# Conditional Distribution (Example)

Recall the table:

$X_1$ (rains)	$X_2$ (sunny)	$X_3$	<b>P</b>
0	0	0	0.4
0	0	1	0
0	1	0	0.2
0	1	1	0
1	0	0	0.2
1	0	1	0
1	1	0	0.1
1	1	1	0.1

What is the probability  $P[X_2 = 1 | X_3 = 1]$  ( $P_{X_2|X_3}(1 | 1)$ )? That is... What is the probability that it is sunny given that there is rainbow?

# Conditional Distribution (Example)

Recall the table:

$X_1$ (rains)	$X_2$ (sunny)	$X_3$	<b>P</b>
0	0	0	0.4
0	0	1	0
0	1	0	0.2
0	1	1	0
1	0	0	0.2
1	0	1	0
1	1	0	0.1
1	1	1	0.1

What is the probability  $P[X_2 = 1 | X_3 = 1]$  ( $P_{X_2|X_3}(1 | 1)$ )? That is... What is the probability that it is sunny given that there is rainbow?

$$P[X_2 = 1 \wedge X_3 = 1] = P_{\{X_2, X_3\}}(1, 1) = P(0, 1, 1) + P(1, 1, 1) = 0.1 + 0.1 = 0.2,$$

$$P[X_3 = 1] = P_{X_3}(1) = P(0, 0, 1) + P(0, 1, 1) + P(1, 0, 1) + P(1, 1, 1) = 0.2,$$

$$P[X_2 = 1 | X_3 = 1] = \frac{P[X_2 = 1 \wedge X_3 = 1]}{P[X_3 = 1]} = \frac{0.2}{0.2} = 1.$$

# **Part 2: Bayesian Networks - Motivation**

# Curse of Dimensionality

**Example:** Let's consider a joint distribution on 100 binary random variables. How large does the table representing this distribution need to be?

*Answer: The table will need to have  $2^{100}$  rows (which means  $2^{100} - 1$  parameters to set).*

**So, clearly, representing joint distributions exhaustively is not an option when we have more than a handful of examples.**

# Independence

**Definition (special case of two random variables):** Two random variables  $X$  and  $Y$  are said to be independent if

$$P[X = x \wedge Y = y] = P[X = x] \cdot P[Y = y]$$

for all possible values  $x$  and  $y$  (i.e. using the other notation, if  $P_{X,Y}(x, y) = P_X(x) \cdot P_Y(y)$  for all possible values  $x$  and  $y$ ).

# Joint Independence

**Definition:** Random variables  $X_1, X_2, \dots, X_n$  are independent if

$$P[X_1 = x_1 \wedge X_2 = x_2 \wedge \dots \wedge X_n = x_n] = P[X_1 = x_1] \cdot P[X_2 = x_2] \cdot \dots \cdot P[X_n = x_n]$$

for all values  $x_1, x_2, \dots, x_n$ .

# Joint Independence (Events)

**Note.** *For independence of a collection of events (recall that an event is a subset of the sample space), the situation is a bit more complicated.*

*Let  $A_1, A_2, \dots, A_n$  be events. Then these events are independent if*

$$P[A_{i_1} \wedge A_{i_2} \wedge \dots \wedge A_{i_k}] = P[A_{i_1}] \cdot P[A_{i_2}] \cdot \dots \cdot P[A_{i_k}]$$

*holds for every subset  $A_{i_1}, A_{i_2}, \dots, A_{i_k}$  of the events  $A_1, A_2, \dots, A_n$  and for every  $k > 0$ .*

# Independence Is Too Strict

**Question:** *How many parameters do we need to describe a distribution of  $n$  independent binary random variables?*

**Answer:** *We need only  $n$  parameters (compare this with  $2^n - 1$  that we need for a general distribution of  $n$  binary random variables).*

**Unfortunately, independence is a condition which is too strict for many distributions. Therefore we will need something else...**

**Example:** Independence holds e.g. when throwing  $n$  dice or when running independent trials of some experiment...

# Conditional Independence (1/4)

**Definition (special case of 3 random variables  $X, Y, Z$ ):**

**Definition 1:**  $X$  and  $Y$  are conditionally independent given  $Z$  if

$$P[X = x \wedge Y = y | Z = z] = P[X = x | Z = z] \cdot P[Y = y | Z = z]$$

holds for all values  $x, y, z$  (using the alternative notation:

$$P_{X,Y|Z}(x, y | z) = P_{X|Z}(x | z) \cdot P_{Y|Z}(y | z)).$$

**Definition 2:**  $X$  and  $Y$  are conditionally independent given  $Z$  if

$$P[X = x | Y = y \wedge Z = z] = P[X = x | Z = z]$$

holds for all values  $x, y, z$  (using the alternative notation:

$$P_{X|Y,Z}(x | y, z) = P_{X|Z}(x | z)).$$

# Conditional Independence (2/4)

**Notation:** The notation for  $X$  and  $Y$  are conditionally independent given  $Z$  is written:

$$X \perp\!\!\!\perp Y \mid Z$$

# Conditional Independence (3/4)

Why the two definitions are equivalent?

Proof: **Def. 1** => **Def. 2**.

$$\begin{aligned} P_{X|Y,Z}(x|y,z) &= \frac{P_{X,Y,Z}(x,y,z)}{P_{Y,Z}(y,z)} = \frac{P_{X,Y|Z}(x,y|z)P_Z(z)}{P_{Y|Z}(y|z)P_Z(z)} = \frac{P_{X,Y|Z}(x,y|z)}{P_{Y|Z}(y|z)} = \\ &= \frac{P_{X|Z}(x|z)P_{Y|Z}(y|z)}{P_{Y|Z}(y|z)} = P_{X|Z}(x|z). \end{aligned}$$

Similarly, we of course also have  $P_{Y|X,Z}(y|x,z) = P_{Y|Z}(y|z)$ .

# Conditional Independence (4/4)

Why the two definitions are equivalent?

Proof: **Def. 2** => **Def. 1**.

$$\begin{aligned} P_{X,Y|Z}(x, y | z) &= \frac{P_{X,Y,Z}(x, y, z)}{P_Z(z)} = \frac{P_{X|Y,Z}(x | y, z)P_{Y,Z}(y, z)}{P_Z(z)} = \\ &= \frac{P_{X|Y,Z}(x | y, z)P_{Y|Z}(y | z)P_Z(z)}{P_Z(z)} = P_{X|Y,Z}(x | y, z)P_{Y|Z}(y | z) = P_{X|Z}(x | z)P_{Y|Z}(y | z) \end{aligned}$$

# Conditional Independence (Example)

## Example:

*Alice throws a coin with sides marked by 0 and 1 (that will be  $X_1$ ). She then sends a message over noisy channels to Bob and Eve about the result of the coin flip. Since the channel is noisy, what Bob receives (that will be  $X_2$ ) and what Eve receives (that will be  $X_3$ ) is not necessarily the same as what Alice sent.*

*Assuming the noise in the two channels is independent, it holds*

$$X_2 \perp\!\!\!\perp X_3 \mid X_1$$

*That is, given the result of Alice's coin toss, what Bob and Eve observe is independent. However, without this conditioning, what Bob and Eve observe is not independent (imagine e.g. that the noise is small and corrupts the message only with probability 0.001...).*

# How Many Parameters?

**Question:** How many parameters would we need in the previous example (*we always use the fact that probabilities sum up to 1*)?

We can use:  $P_{X_1, X_2, X_3}(x_1, x_2, x_3) = P_{X_2|X_1}(x_2 | x_1)P_{X_3|X_1}(x_3 | x_1)P_{X_1}(x_1)$ .

**2 parameters for  $P_{X_2|X_1}$**  (*we need to determine  $P_{X_2|X_1}(0 | 1)$ , from which we can compute  $P_{X_2|X_1}(1 | 1) = 1 - P_{X_2|X_1}(0 | 1)$ , and similarly  $P_{X_3|X_1}(0 | 0)$ ...).*

**2 parameters for  $P_{X_3|X_1}$**  (*similar reasoning as above...*)

**1 parameter for  $P_{X_1}$ .**

**5 parameters in total.** *If we did not use conditional independence, we would need  $2^3 - 1 = 7$  parameters (this may not seem like much gain but it would be higher if we had more than three variables).*

# Multi-Variate Case

Both of the equivalent definitions of conditional independence are straightforwardly generalized into the multi-variate case:

**Definition 1:** Random vectors  $\mathbf{X}$  and  $\mathbf{Y}$  are conditionally independent given  $\mathbf{Z}$  if

$$P_{\mathbf{X},\mathbf{Y}|\mathbf{Z}}(\mathbf{x}, \mathbf{y} | \mathbf{z}) = P_{\mathbf{X}|\mathbf{Z}}(\mathbf{x} | \mathbf{z}) \cdot P_{\mathbf{Y}|\mathbf{Z}}(\mathbf{y} | \mathbf{z})$$

for all possible values of the vectors  $\mathbf{x}$ ,  $\mathbf{y}$ ,  $\mathbf{z}$ .

**Definition 2:** Random vectors  $\mathbf{X}$  and  $\mathbf{Y}$  are conditionally independent given  $\mathbf{Z}$  if

$$P_{\mathbf{X}|\mathbf{Y},\mathbf{Z}}(\mathbf{x} | \mathbf{y}, \mathbf{z}) = P_{\mathbf{X}|\mathbf{Z}}(\mathbf{x} | \mathbf{z})$$

for all possible values of the vectors  $\mathbf{x}$ ,  $\mathbf{y}$ ,  $\mathbf{z}$ .

# Trivial Factorization (Chain Rule)

Any joint distribution of a random vector  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  can be written as:

$$P_{\mathbf{X}}(x_1, x_2, \dots, x_n) = P_{X_1}(x_1)P_{X_2|X_1}(x_2 | x_1)P_{X_3|X_1, X_2}(x_3 | x_1, x_2) \dots P_{X_n|X_1, \dots, X_{n-1}}(x_n | x_1, \dots, x_{n-1})$$

# Trivial Factorization (Chain Rule)

Any joint distribution of a random vector  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  can be written as:

$$P_{\mathbf{X}}(x_1, x_2, \dots, x_n) = P_{X_1}(x_1)P_{X_2|X_1}(x_2 | x_1)P_{X_3|X_1, X_2}(x_3 | x_1, x_2) \dots P_{X_n|X_1, \dots, X_{n-1}}(x_n | x_1, \dots, x_{n-1})$$

*The above can be simplified if we know that some conditional independencies hold, e.g. if  $X_2$  and  $X_3$  are conditionally independent given  $X_1$  then we can replace  $P_{X_3|X_1, X_2}(x_3 | x_1, x_2)$  by  $P_{X_3|X_1}(x_3 | x_1)$  etc.*

# Part 3: Bayesian Networks

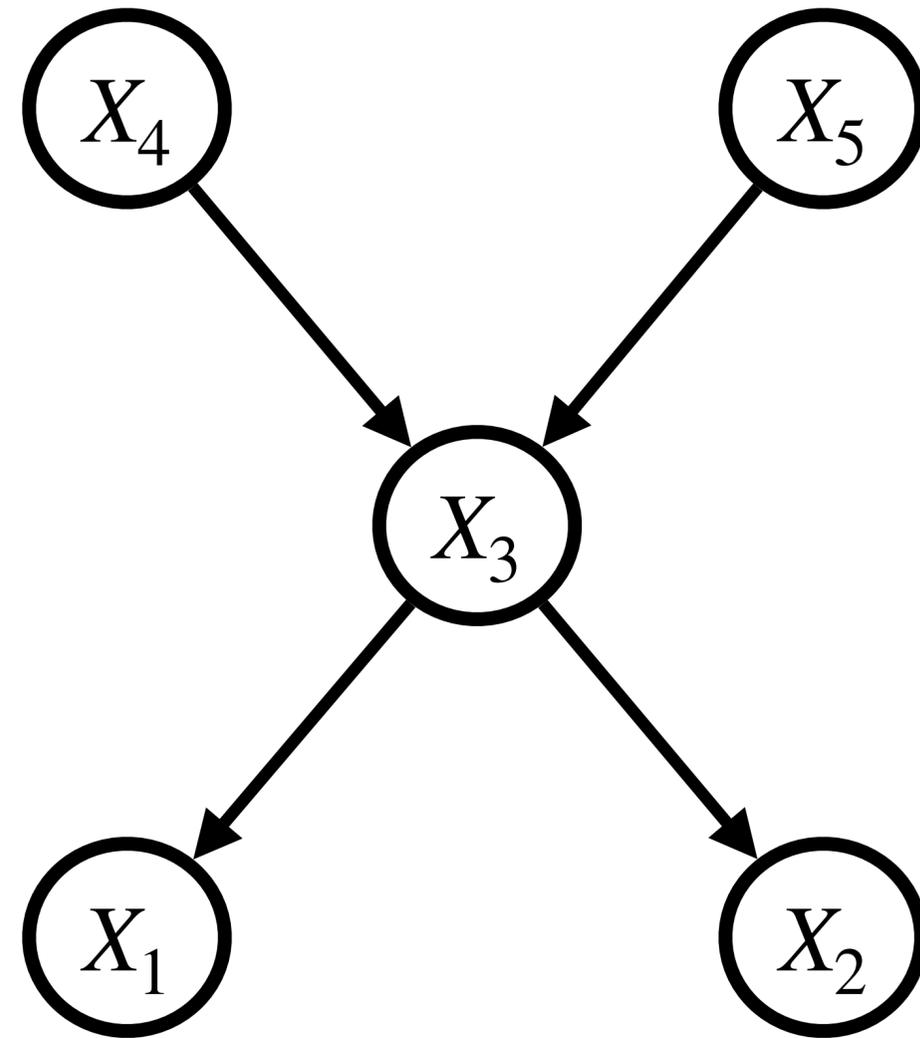
# Bayesian Network

**Let:**  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be a random vector and let  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  denote a vector of values.

**Definition:** A Bayesian network for a joint distribution of the random vector  $\mathbf{X}$  is given by:

- A directed acyclic graph  $G$ . The nodes of  $G$  correspond to the random variables  $X_1, X_2, \dots, X_n$ .
- For every random variable  $X_i$ , a conditional distribution of  $X_i$  given its parents.

# Bayesian Network (The Graph)



# Bayesian Networks: Notation

**Let:**  $\mathbf{X} = (X_1, X_2, \dots, X_n)$  be a random vector and let  $\mathbf{x} = (x_1, x_2, \dots, x_n)$  denote a vector of values. Let

**Notation:** To simplify notation in what follows, we will denote by

$\text{Par}(X_i)$  ... the vector of parents of  $X_i$  (the random variables corresponding to the parents)

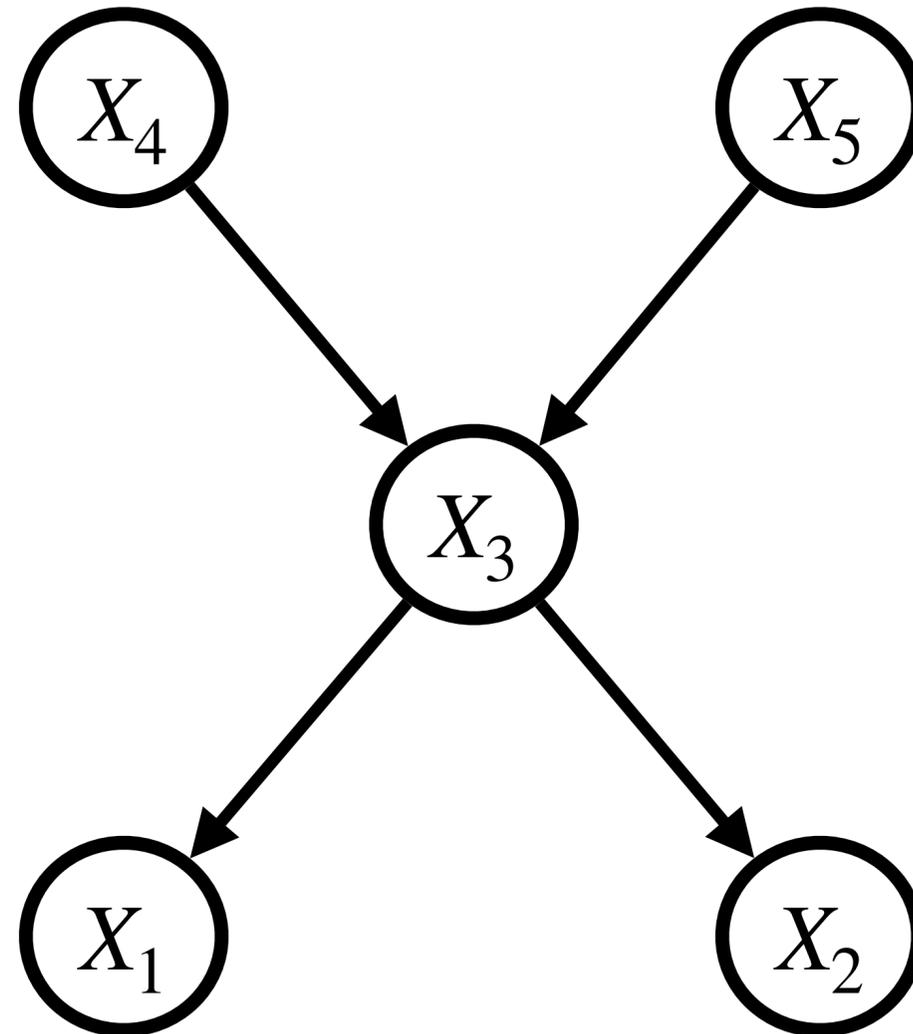
$\text{par}_{\mathbf{x}}(X_i)$  ... the vector of **values** of the parents of  $X_i$  (the values are supposed to be taken from the vector of values  $\mathbf{x}$ ).

# Bayesian Network Distribution

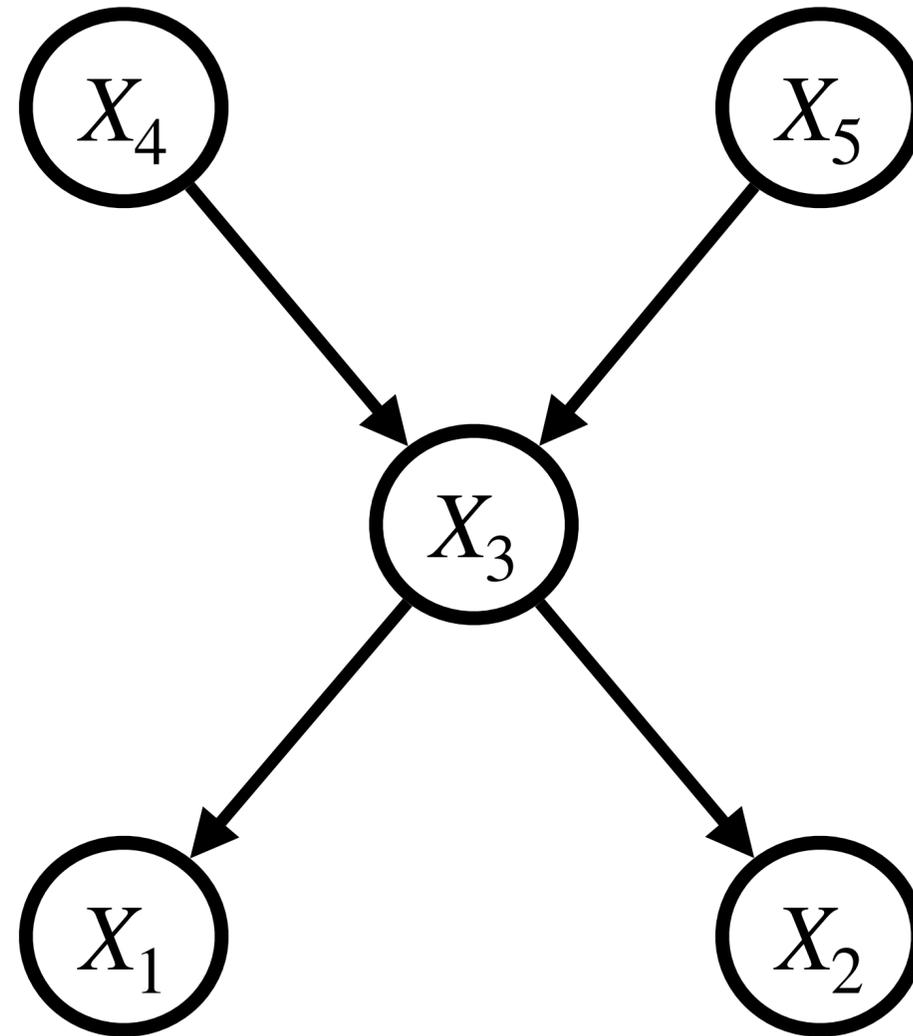
Given a BN with a graph  $G$ , the BN induces the following distribution:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P_{X_i | Par(X_i)} (x_i | \text{par}_{\mathbf{x}}(X_i)).$$

# Bayesian Network: Example (1/3)



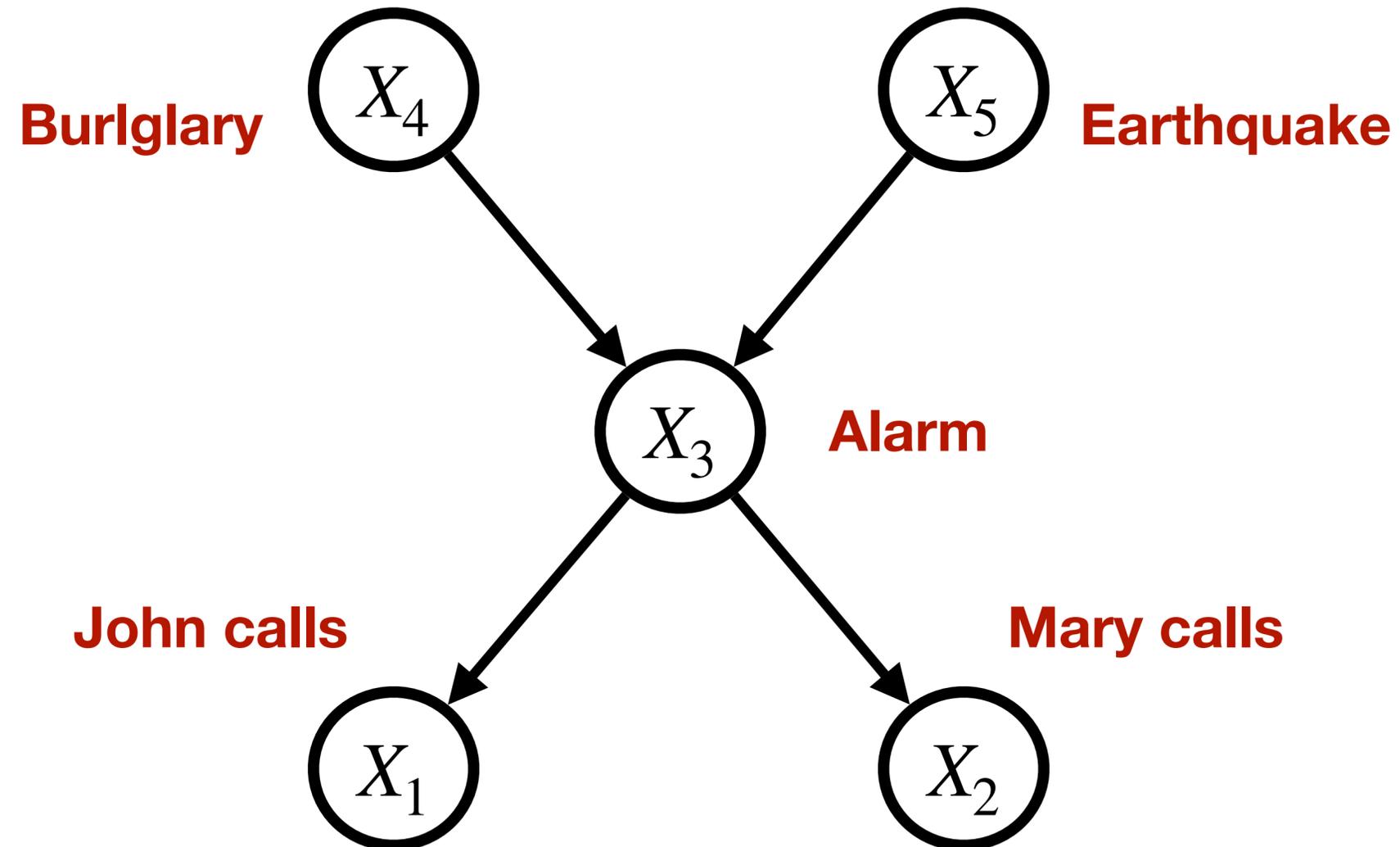
# Bayesian Network: Example (2/3)



$$P(x_1, \dots, x_5) = P_{X_4}(x_4)P_{X_5}(x_5)P_{X_3|X_4, X_5}(x_3 | x_4, x_5)P_{X_1|X_3}(x_1 | x_3)P_{X_2|X_3}(x_2 | x_3)$$

# Bayesian Network: Example (3/3)

Let's make the example concrete



$$P(x_1, \dots, x_5) = P_{X_4}(x_4)P_{X_5}(x_5)P_{X_3|X_4, X_5}(x_3 | x_4, x_5)P_{X_1|X_3}(x_1 | x_3)P_{X_2|X_3}(x_2 | x_3)$$

# Conditional Independence in BNs

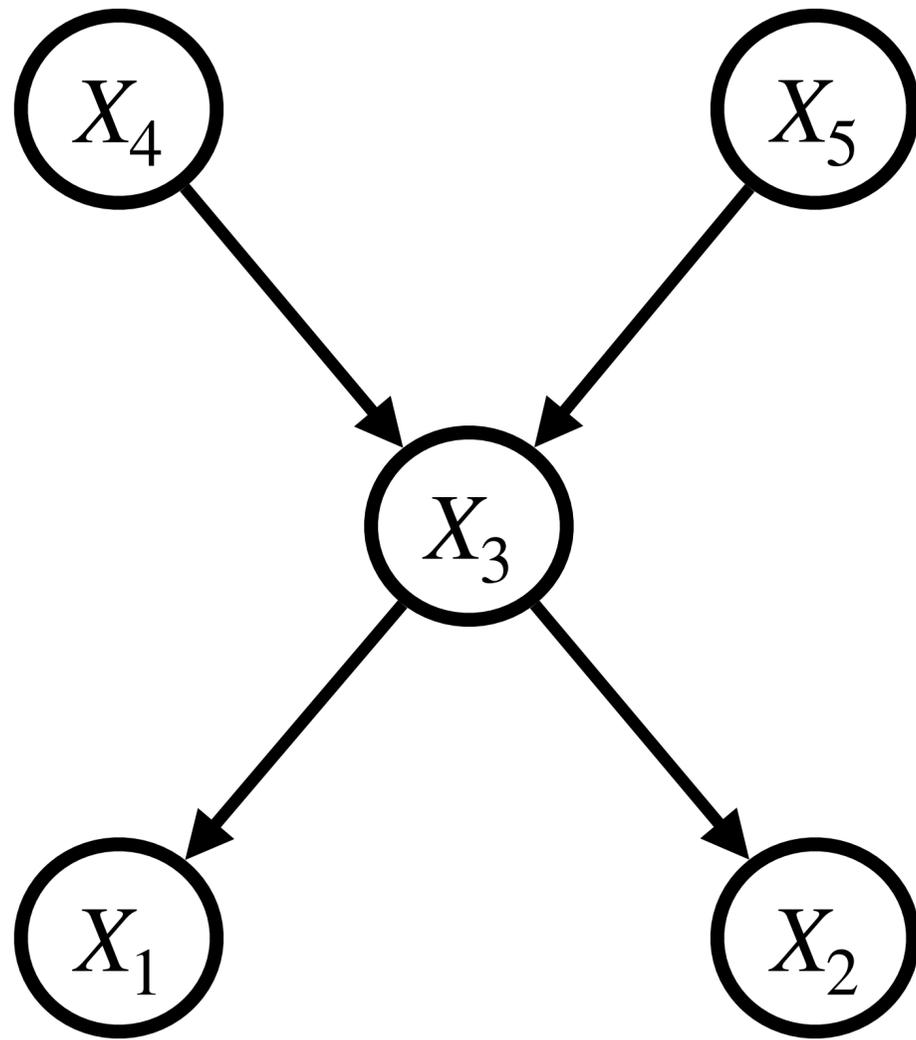
**What are the conditional independence assumptions behind BNs?**

The main one is that, for every  $X_i$ :  $X_i$  is conditionally independent of its ancestors given its parents.

**This can be equivalently stated as follows:**

Let  $Anc(X_i)$  be the ancestors of  $X_i$ , i.e. nodes in the BN from which  $X_i$  can be reached.

$$P_{X_i|Par(X_i)}(x_i | par_{\mathbf{x}}(X_i)) = P_{X_i|Anc(X_i)}(x_i | anc_{\mathbf{x}}(X_i)).$$



$$P_{X_1|X_3}(x_1 | x_3) = P_{X_1|X_3, X_4, X_5}(x_1 | x_3, x_4, x_5)$$

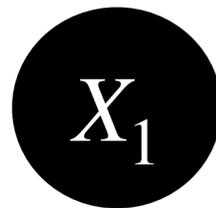
$$P_{X_2|X_3}(x_2 | x_3) = P_{X_2|X_3, X_4, X_5}(x_2 | x_3, x_4, x_5)$$

# Part 4: More on Conditional Independence (D-Separation)

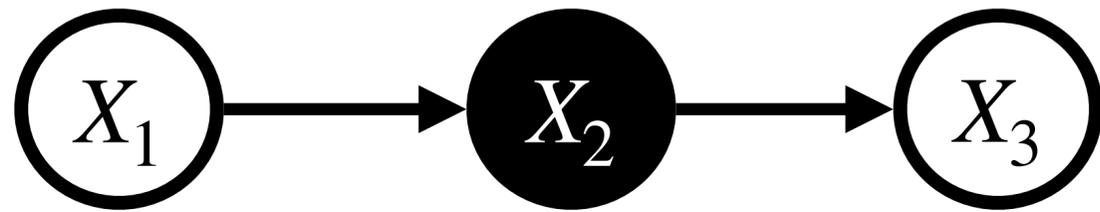
# More Conditional Independencies?

In general, a BN encodes many conditional independencies. We will now learn to recognize them.

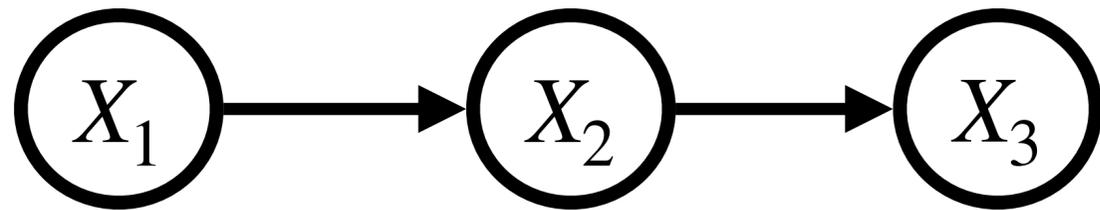
In what follows, nodes on which we condition will be shown as full black ovals, e.g.:



# Causal Chain (1/2)



$$X_1 \perp\!\!\!\perp X_3 \mid X_2$$



$X_1$  and  $X_3$  not independent (unconditionally)

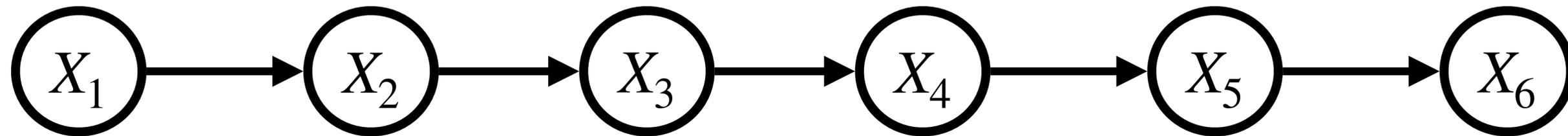
# Causal Chain (2/2)

The conditional independence part can be shown as follows:

$$\begin{aligned} P_{X_1, X_3 | X_2}(x_1, x_3 | x_2) &= \frac{P_{X_1, X_2, X_3}(x_1, x_2, x_3)}{P_{X_2}(x_2)} = \\ &= \frac{P_{X_1}(x_1)P_{X_2|X_1}(x_2 | x_1)P_{X_3|X_2}(x_3 | x_2)}{P_{X_2}(x_2)} = \underbrace{\frac{P_{X_1}(x_1)P_{X_2|X_1}(x_2 | x_1)}{P_{X_2}(x_2)}}_{=P_{X_1|X_2}(x_1|x_2)} P_{X_3|X_2}(x_3 | x_2) = \\ &= P_{X_1|X_2}(x_1 | x_2)P_{X_3|X_2}(x_3 | x_2) \end{aligned}$$

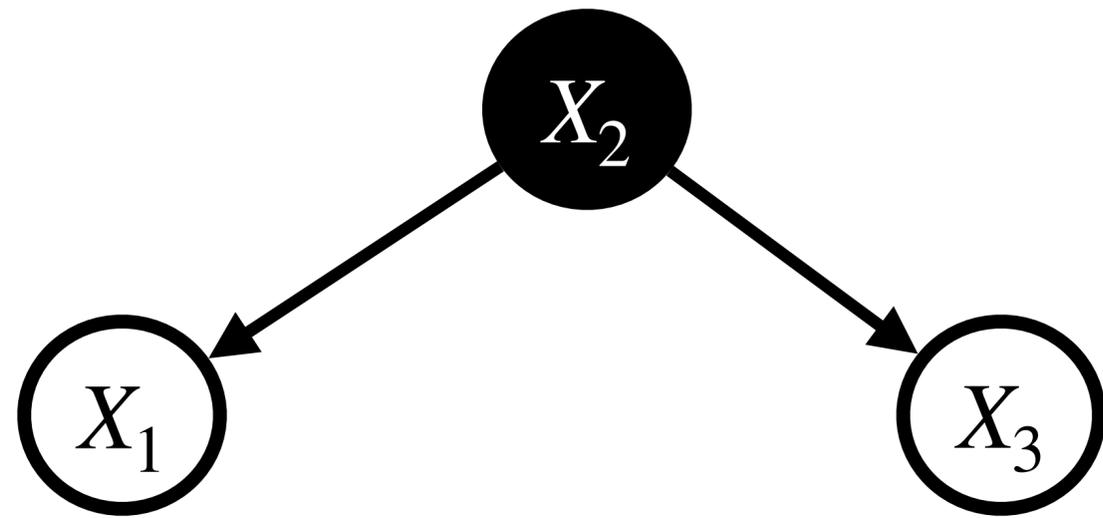
# Causal Chain: Example

You know one example already... Markov process.

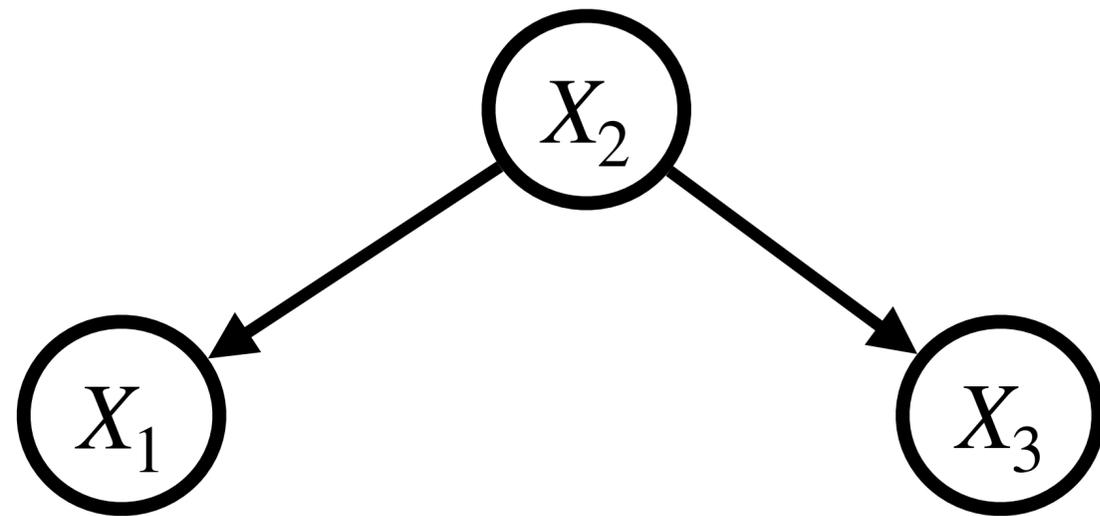


The possible values of each  $X_i$  are the states from the state space  $\mathcal{S}$ .

# Common Cause (1/2)



$$X_1 \perp\!\!\!\perp X_3 \mid X_2$$



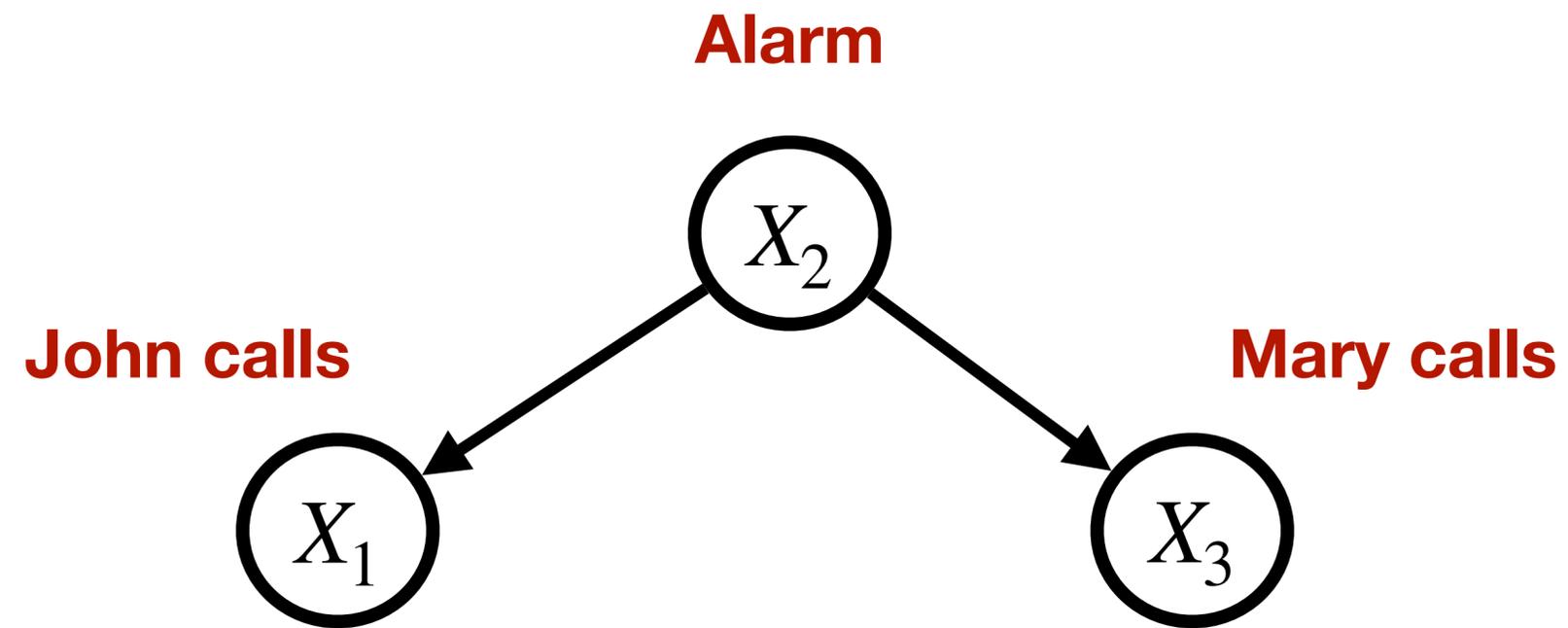
$X_1$  and  $X_3$  not independent (unconditionally)

# Common Cause (2/2)

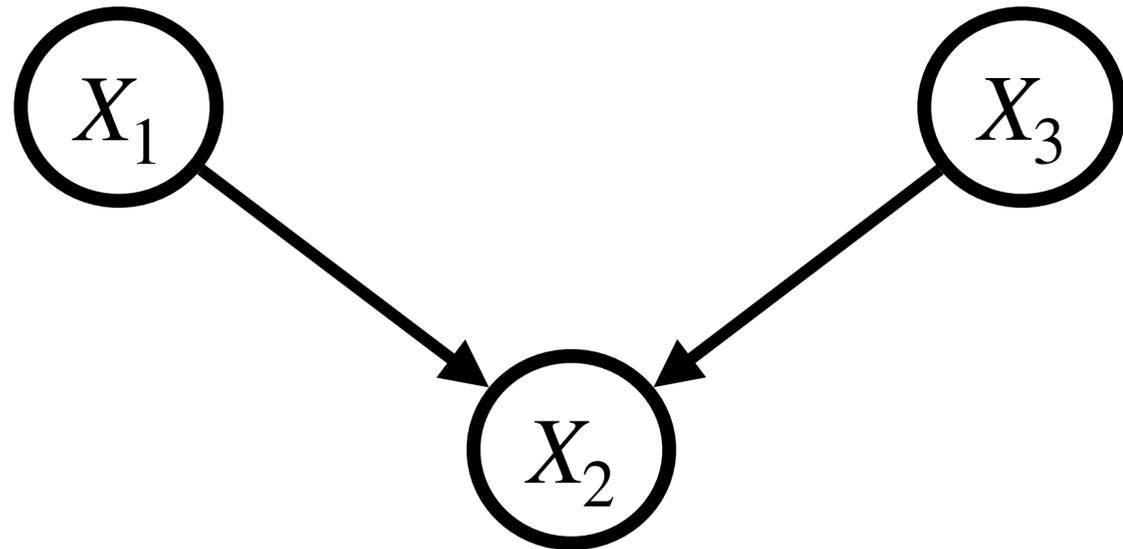
The conditional independence part can be shown as follows:

$$\begin{aligned} P_{X_1, X_3 | X_2}(x_1, x_3 | x_2) &= \frac{P_{X_1, X_2, X_3}(x_1, x_2, x_3)}{P_{X_2}(x_2)} = \\ &= \frac{P_{X_1 | X_2}(x_1 | x_2) P_{X_3 | X_2}(x_3 | x_2) P_{X_2}(x_2)}{P_{X_2}(x_2)} = P_{X_1 | X_2}(x_1 | x_2) P_{X_3 | X_2}(x_3 | x_2). \end{aligned}$$

# Common Cause: Example

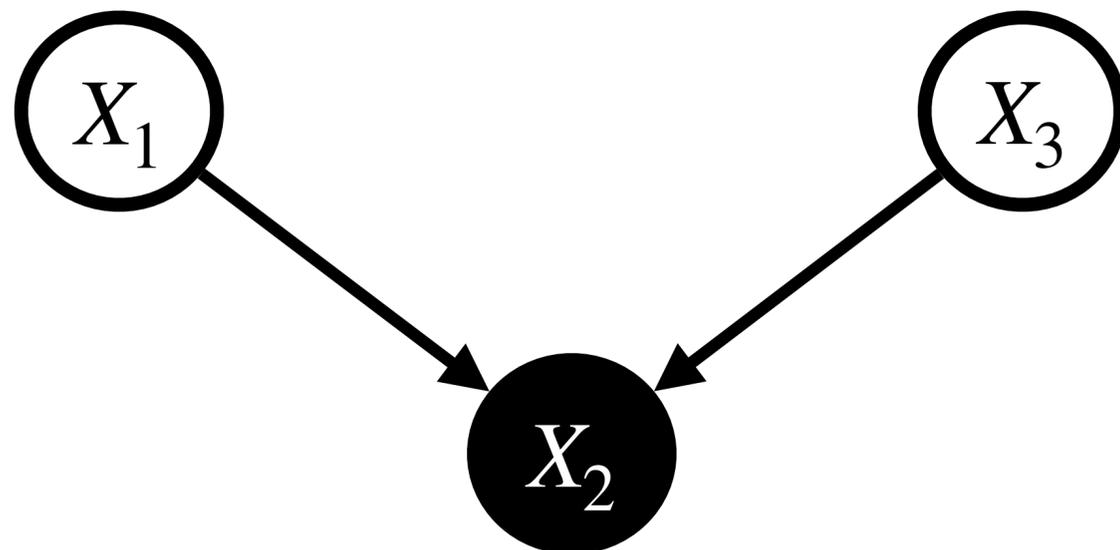


# Common Effect (1/2)



**Independent unconditionally**

$$X_1 \perp\!\!\!\perp X_3$$



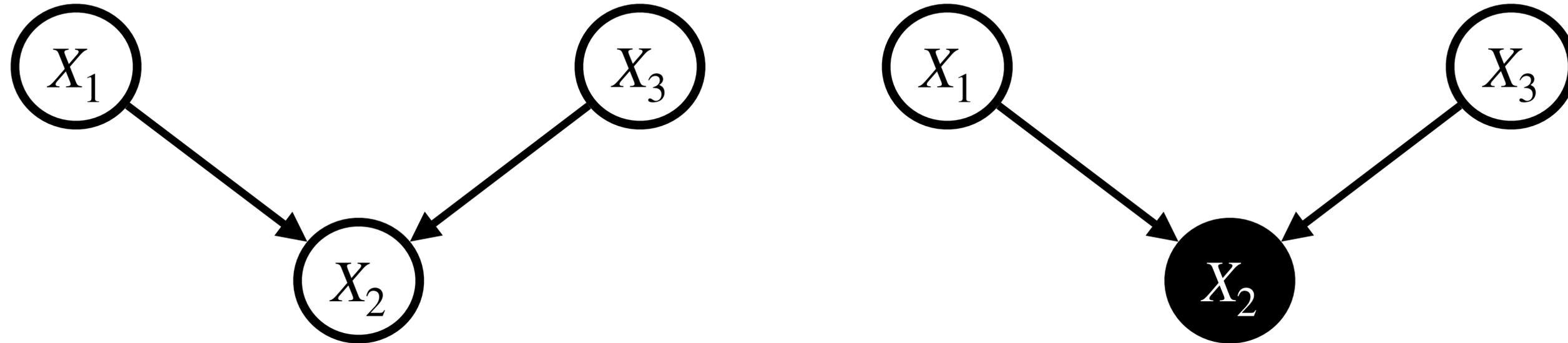
**But  $X_1$  and  $X_3$  are NOT independent given the value of  $X_2$ !!!!**

# Common Effect (2/2)

The independence part can be shown as follows:

$$\begin{aligned} P_{X_1, X_3}(x_1, x_3) &= \sum_{x_2} P_{X_1, X_2, X_3}(x_1, x_2, x_3) = \sum_{x_2} P_{X_2|X_1, X_3}(x_2 | x_1, x_3) P_{X_1}(x_1) P_{X_3}(x_3) = \\ &= P_{X_1}(x_1) P_{X_3}(x_3) \underbrace{\sum_{x_2} P_{X_2|X_1, X_3}(x_2 | x_1, x_3)}_{=1} = P_{X_1}(x_1) P_{X_3}(x_3). \end{aligned}$$

# Common Effect: Example



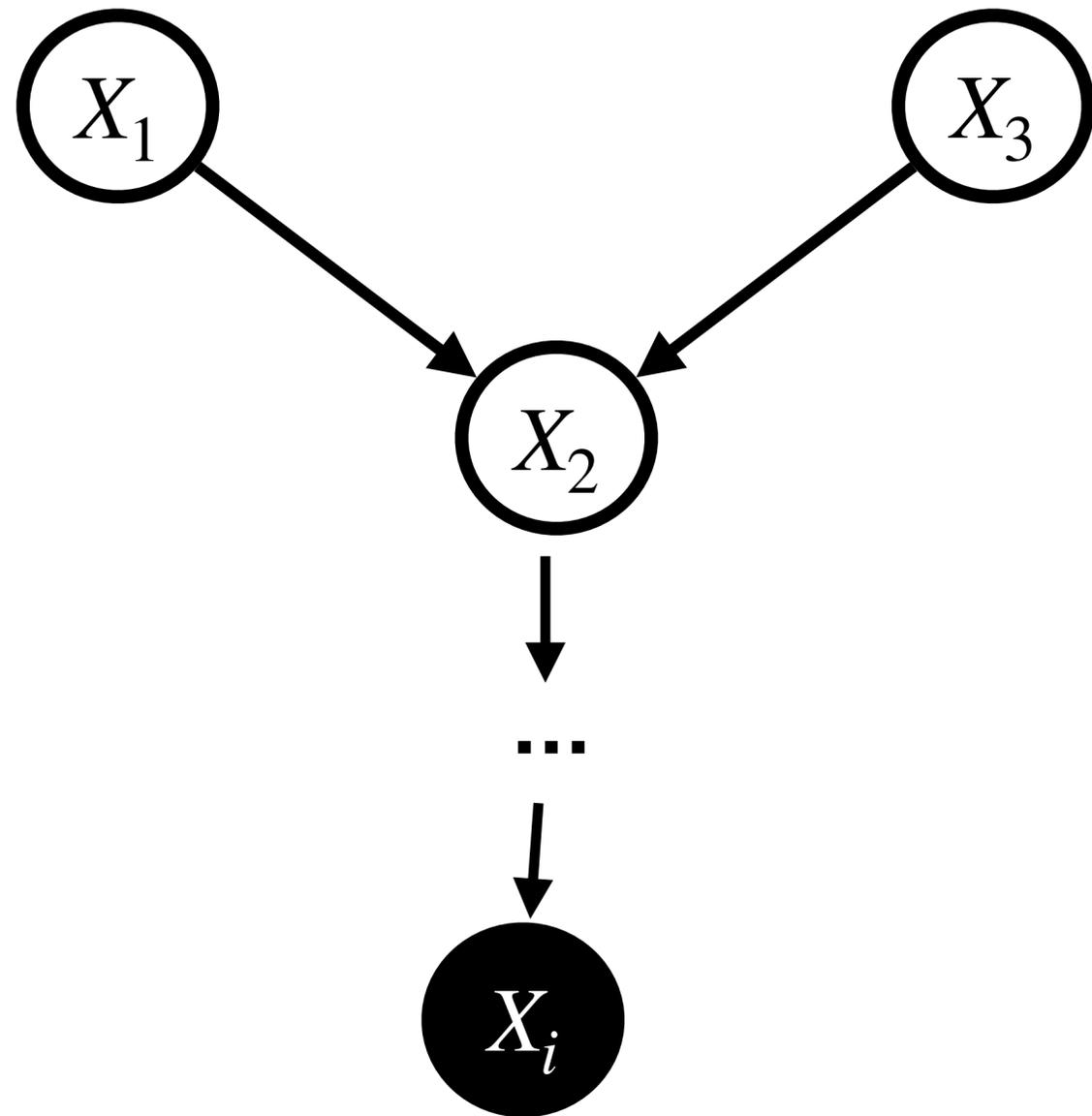
$X_1$  ... flip a coin (the result is 0 or 1)

$X_3$  ... flip a coin (the result is 0 or 1)

$$X_2 = X_1 \oplus X_3.$$

**Then if we do not condition on  $X_2$ ,  $X_1$  and  $X_3$  are independent, but if we do condition on  $X_2$  then just fixing the value of  $X_1$  determines the value of  $X_3$ , so they are not conditionally independent given  $X_2$ !**

# Common Effect - Descendants



$X_1$  and  $X_3$  are **NOT** independent  
given the value of  $X_i$ !!!!

# D-Separation

Given a Bayesian network and a set of variables  $\mathcal{E}$  that are conditioned on, we will want to detect those random variables that are conditionally independent given the values of the variables in  $\mathcal{E}$ .

**Two variables  $X_1$  and  $X_2$  are conditionally independent given  $\mathcal{E}$  if there is no **active path** connecting them.**

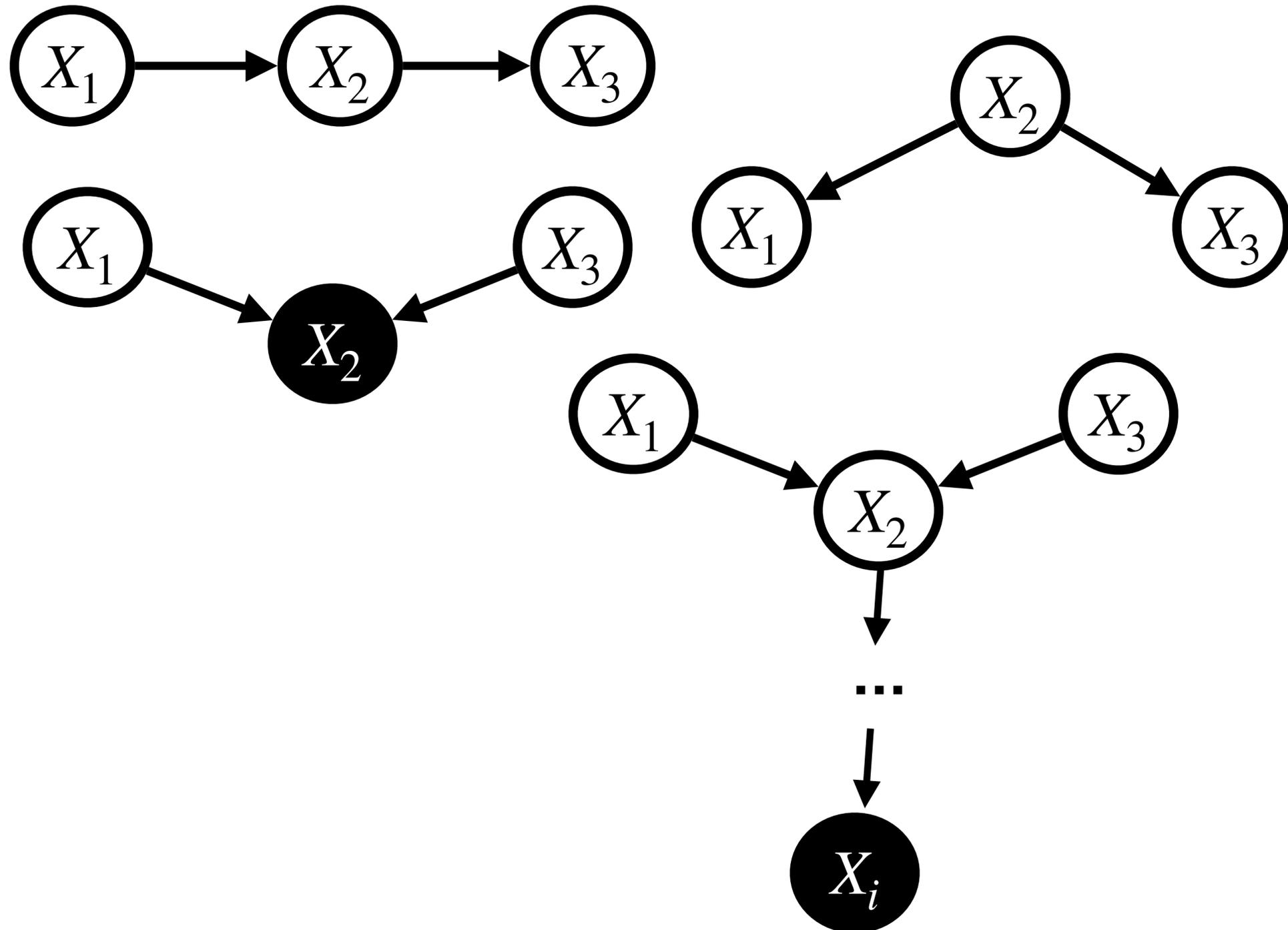
# Active Path (1/3)

We will be checking all **undirected** paths between the two variables (i.e. ignoring the direction of the edges).

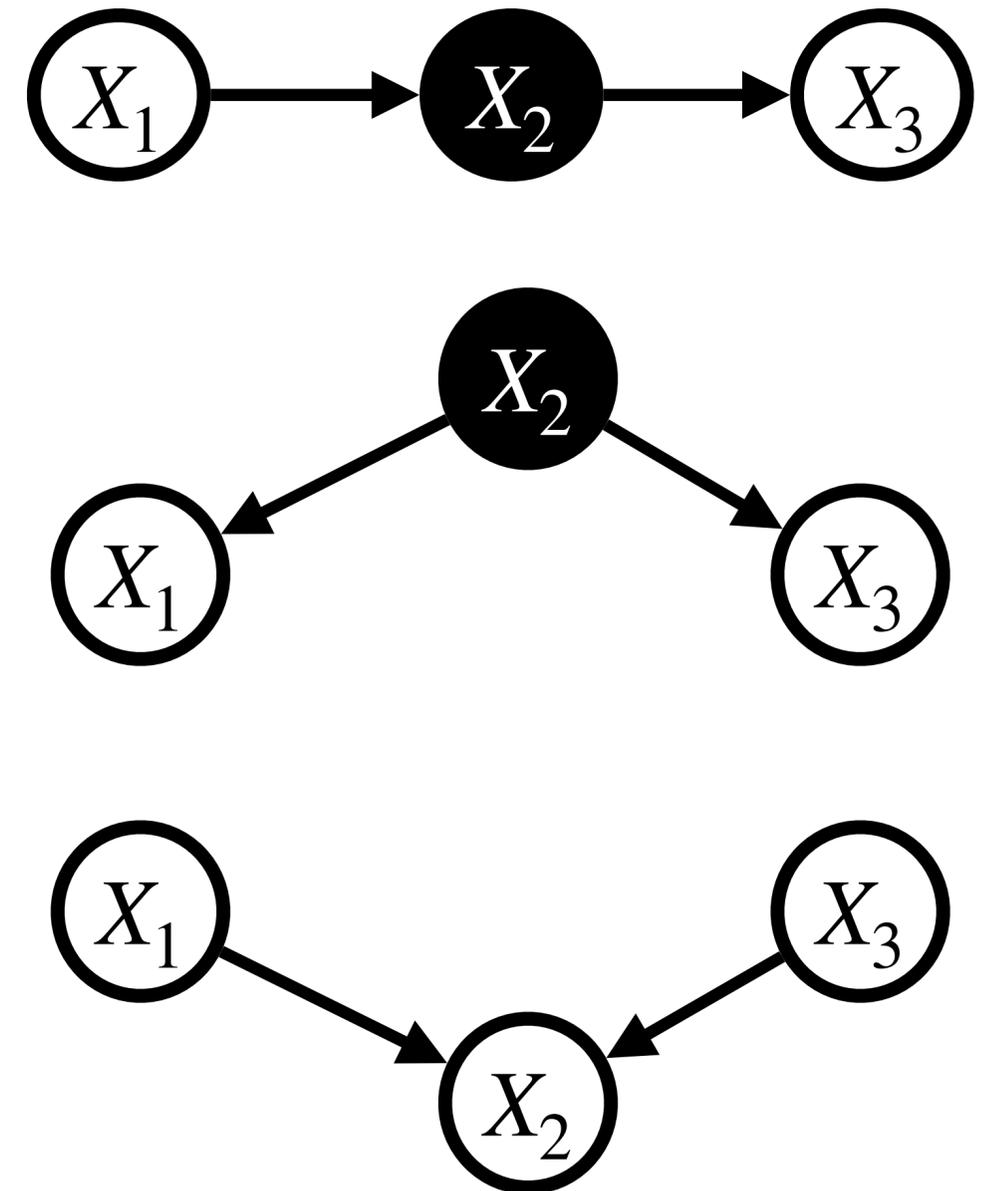
**Terminology:** Nodes which we condition on will be called **observed nodes** and the others **unobserved nodes**.

# Active Path (2/3)

Active triples:



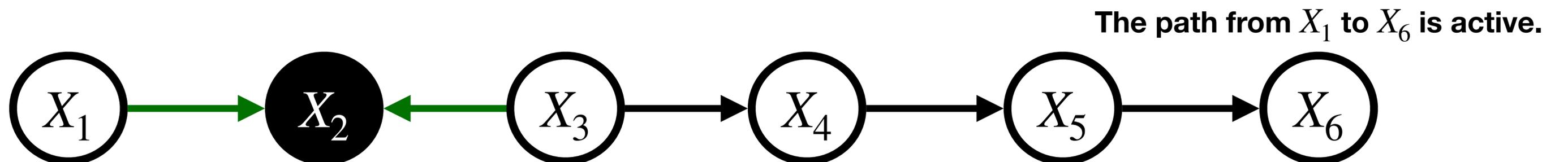
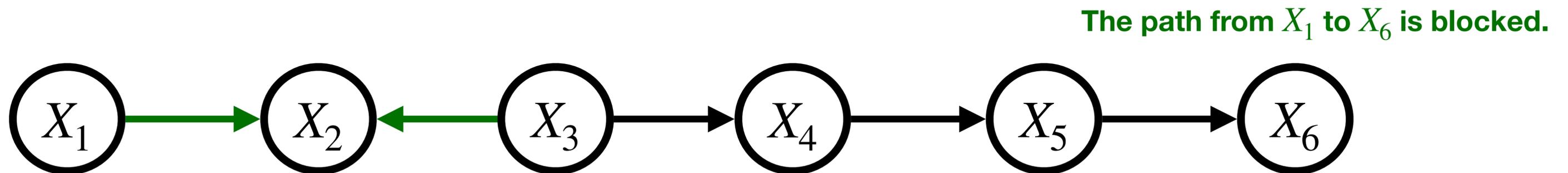
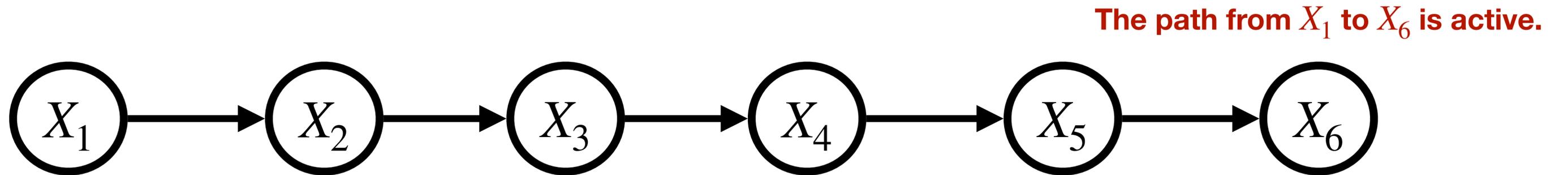
Blocked triples:



# Active Path (3/3)

**Definition:** A path is active if all triples along it are active. Otherwise it is blocked.

## EXAMPLES:

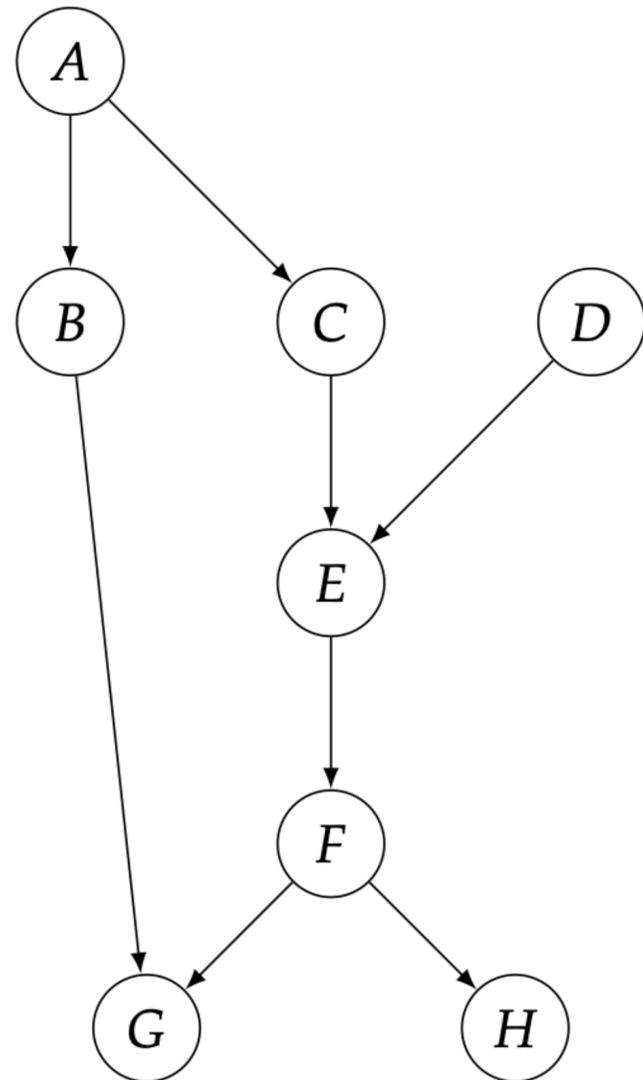


# D-Separation: Example (*from P. Pošík*)

## D-sep examples

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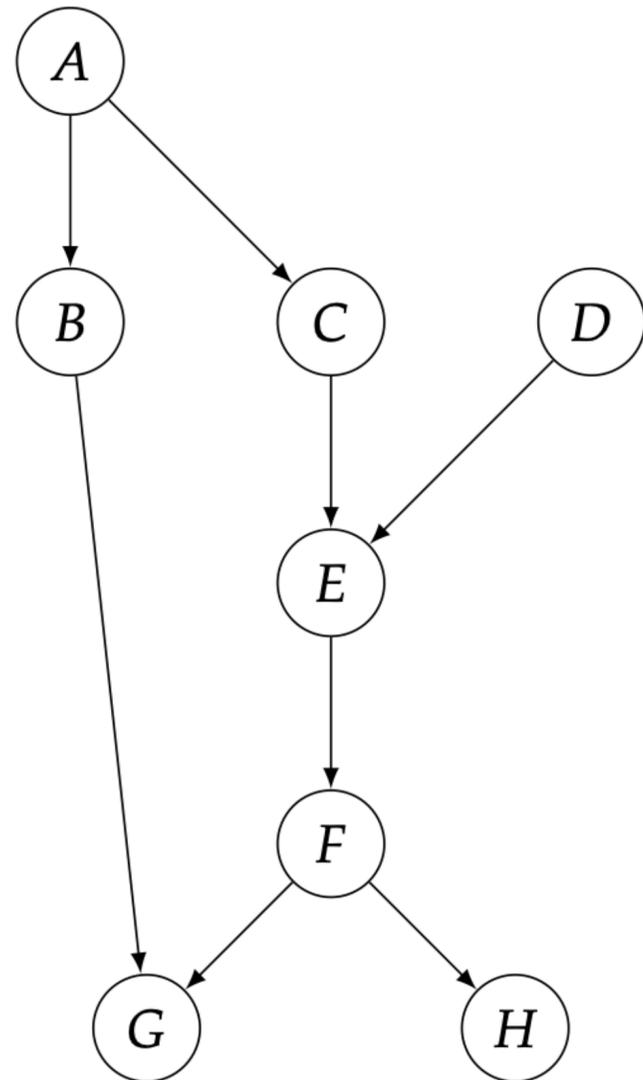
$B \perp\!\!\!\perp C \mid A?$



# D-Separation: Example (*from P. Pošík*)

## D-sep examples

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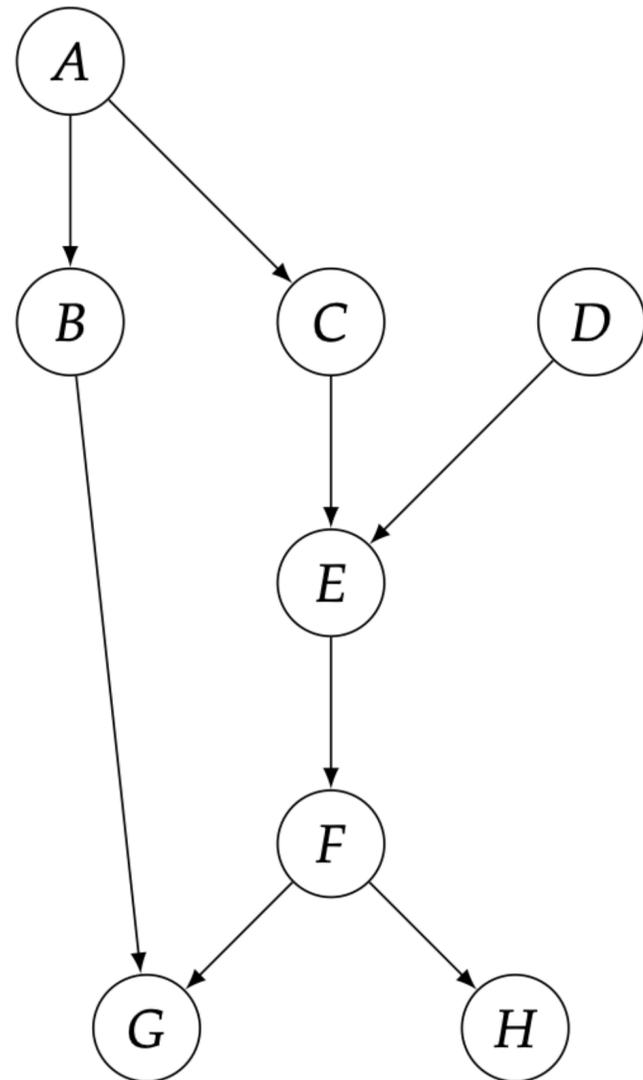


$B \perp\!\!\!\perp C | A$ ? YES! Why?

- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

# D-Separation: Example (from P. Pošík)

## D-sep examples



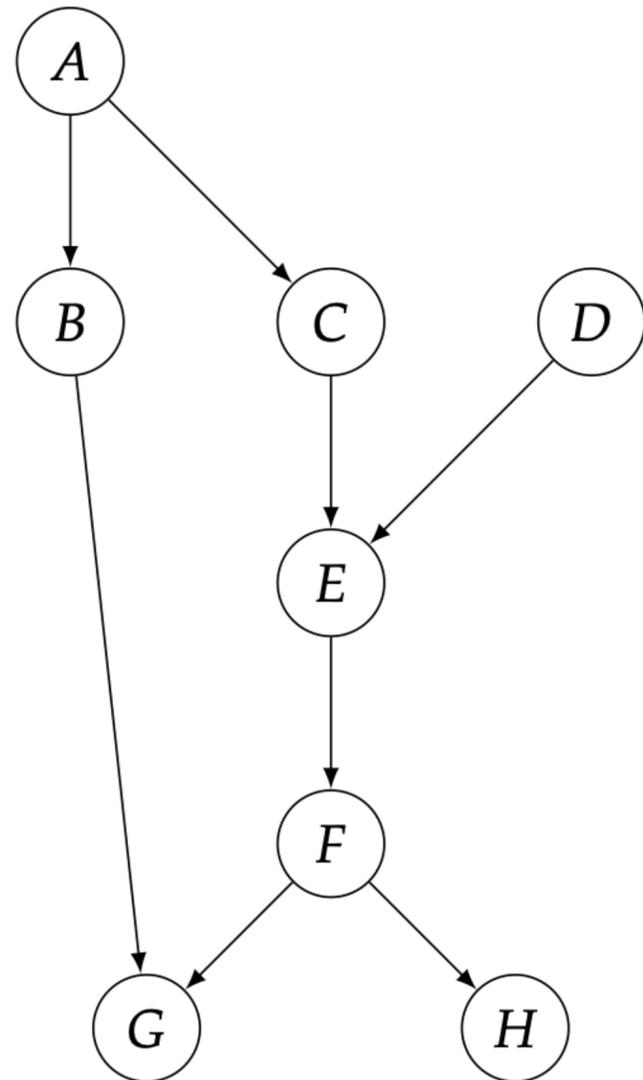
$B \perp\!\!\!\perp C | A$ ? YES! Why?

- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

$A \perp\!\!\!\perp F | E$ ?

# D-Separation: Example (*from P. Pošík*)

## D-sep examples



$B \perp\!\!\!\perp C | A$ ? YES! Why?

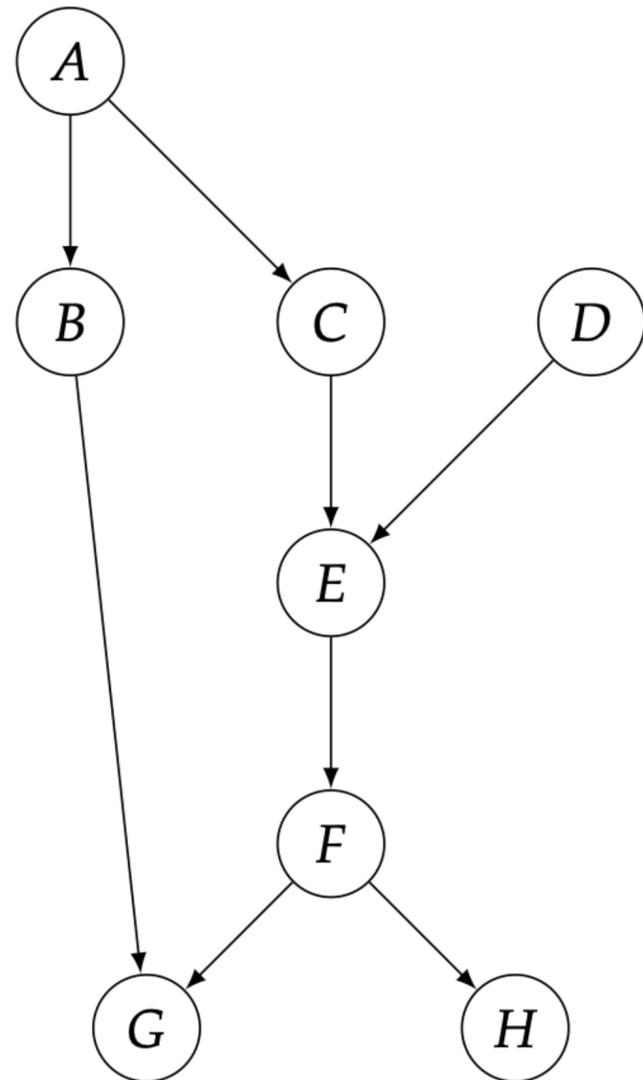
- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

$A \perp\!\!\!\perp F | E$ ? YES! Why?

- $A, C, E, F$  blocked by evidence on  $E$
- $A, B, G, F$  not active — missing evidence on  $G$

# D-Separation: Example (from P. Pošík)

## D-sep examples



$B \perp\!\!\!\perp C | A$ ? YES! Why?

- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

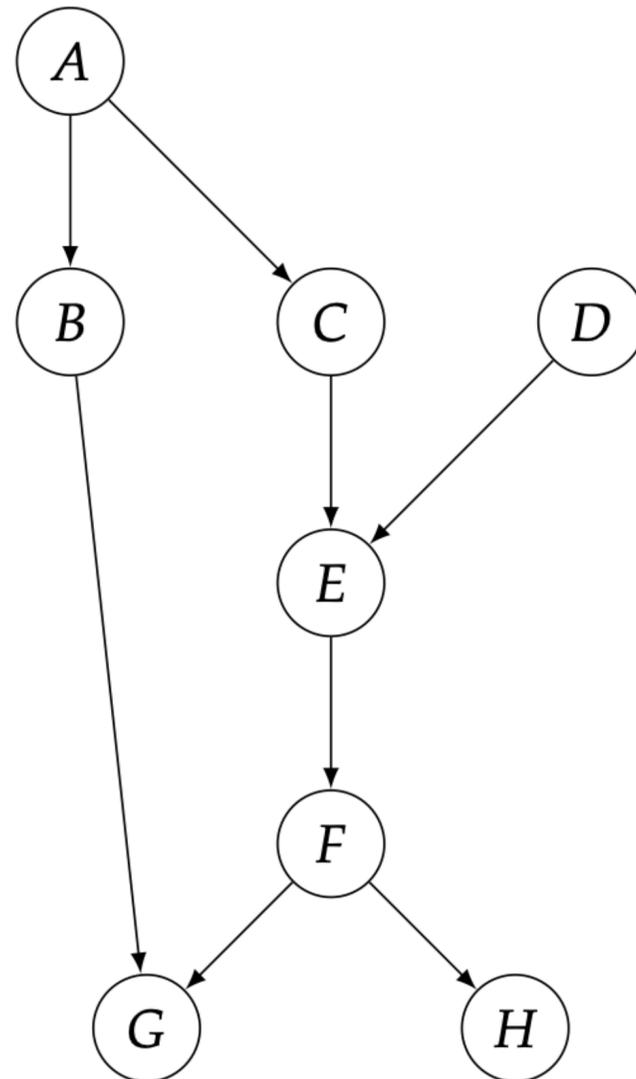
$A \perp\!\!\!\perp F | E$ ? YES! Why?

- $A, C, E, F$  blocked by evidence on  $E$
- $A, B, G, F$  not active — missing evidence on  $G$

$C \perp\!\!\!\perp D | F$ ?

# D-Separation: Example (*from P. Pošík*)

## D-sep examples



$B \perp\!\!\!\perp C | A$ ? YES! Why?

- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

$A \perp\!\!\!\perp F | E$ ? YES! Why?

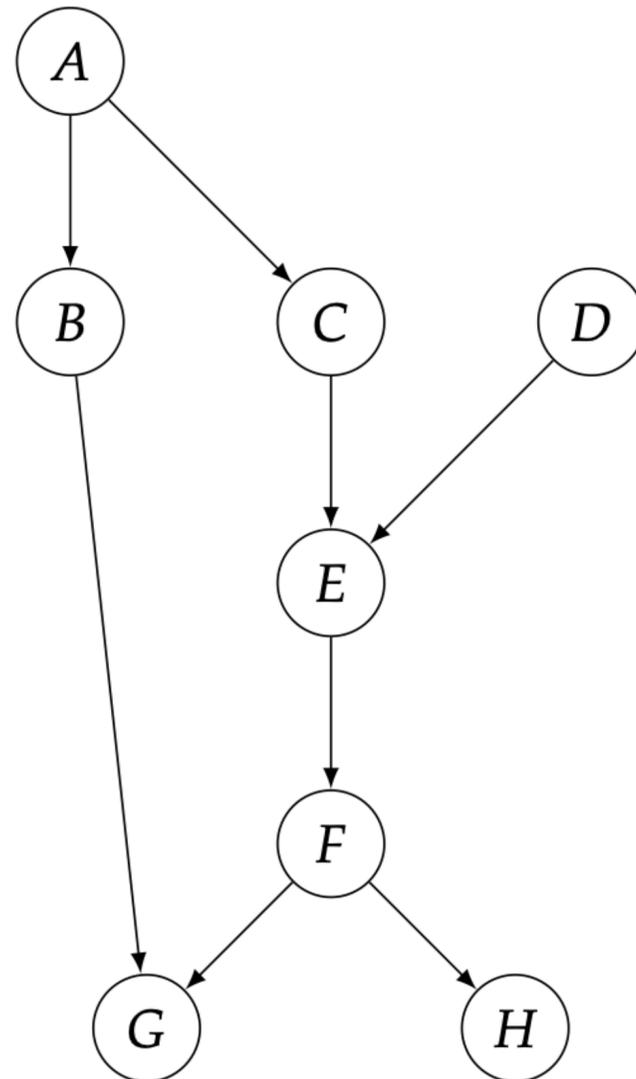
- $A, C, E, F$  blocked by evidence on  $E$
- $A, B, G, F$  not active — missing evidence on  $G$

$C \perp\!\!\!\perp D | F$ ? NO! Why?

- $C, A, B, G, F, E, D$  is blocked by evidence on  $F$  and by missing evidence on  $G$
- $C, E, D$  is activated by the evidence on  $F$  which is a descendant of  $E$ .

# D-Separation: Example (from P. Pošík)

## D-sep examples



$B \perp\!\!\!\perp C | A$ ? YES! Why?

- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

$A \perp\!\!\!\perp F | E$ ? YES! Why?

- $A, C, E, F$  blocked by evidence on  $E$
- $A, B, G, F$  not active — missing evidence on  $G$

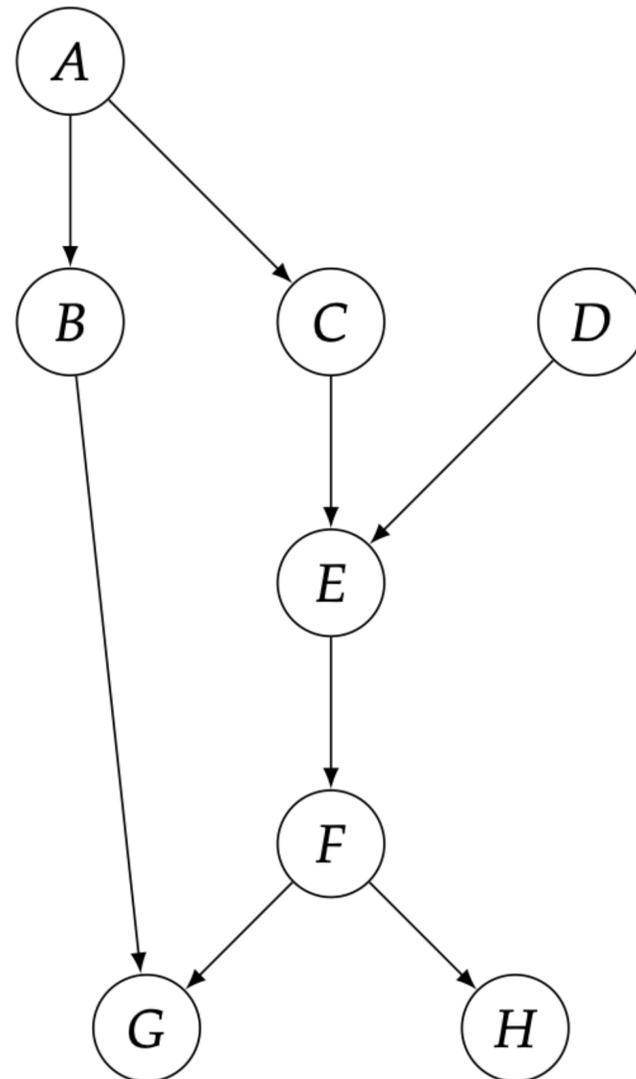
$C \perp\!\!\!\perp D | F$ ? NO! Why?

- $C, A, B, G, F, E, D$  is blocked by evidence on  $F$  and by missing evidence on  $G$
- $C, E, D$  is activated by the evidence on  $F$  which is a descendant of  $E$ .

$A \perp\!\!\!\perp G | \{B, F\}$ ?

# D-Separation: Example (from P. Pošík)

## D-sep examples



$B \perp\!\!\!\perp C | A$ ? YES! Why?

- $B, A, C$  blocked by evidence on  $A$
- $B, G, F, E, C$  not active — missing evidence on  $G$

$A \perp\!\!\!\perp F | E$ ? YES! Why?

- $A, C, E, F$  blocked by evidence on  $E$
- $A, B, G, F$  not active — missing evidence on  $G$

$C \perp\!\!\!\perp D | F$ ? NO! Why?

- $C, A, B, G, F, E, D$  is blocked by evidence on  $F$  and by missing evidence on  $G$
- $C, E, D$  is activated by the evidence on  $F$  which is a descendant of  $E$ .

$A \perp\!\!\!\perp G | \{B, F\}$ ? YES! Why?

- $A, B, G$  blocked by evidence on  $B$
- $A, C, E, F, G$  blocked by evidence on  $F$

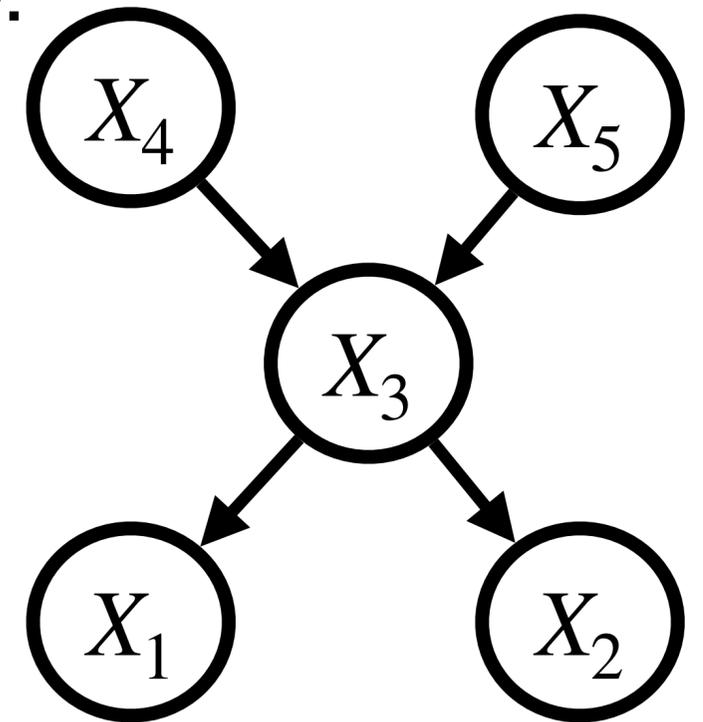
You will learn better ways to detect d-separation... but not in this lecture.

# **Part 5: Variable Elimination (First Look Into Inference)**

# Marginal Inference

**Problem:** Given a BN on random variables  $X_1, X_2, \dots, X_n$ , compute the probability  $P_{X_{i_1}, X_{i_2}, \dots, X_{i_k}}(x_{i_1}, x_{i_2}, \dots, x_{i_k})$ , where  $X_{i_1}, X_{i_2}, \dots, X_{i_k}$  is a subset of the random variables  $X_1, X_2, \dots, X_n$ .

**Example:** Compute  $P_{X_1, X_5}(x_1, x_5)$  from the BN shown here:



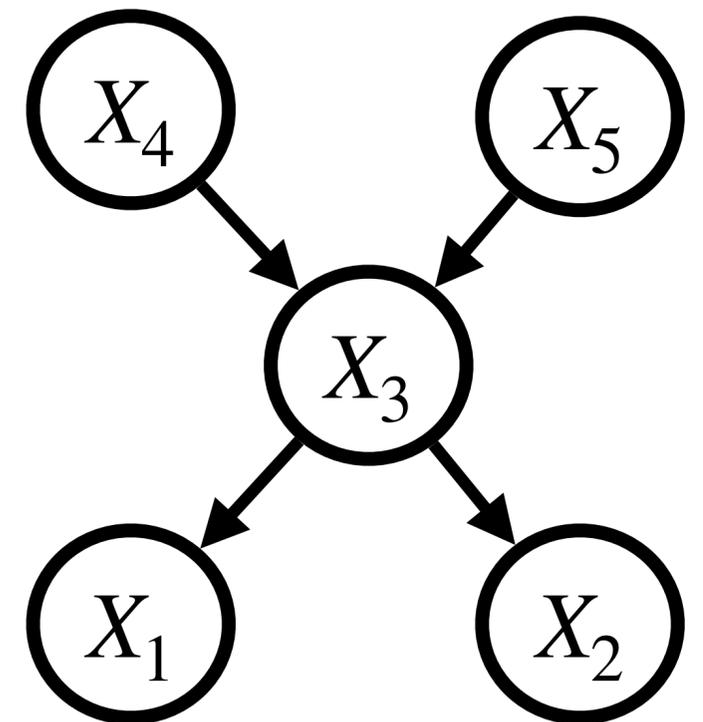
# Naive Approach

**Naive idea (we won't be able to do better in the worst case):**

Compute the following sum explicitly:

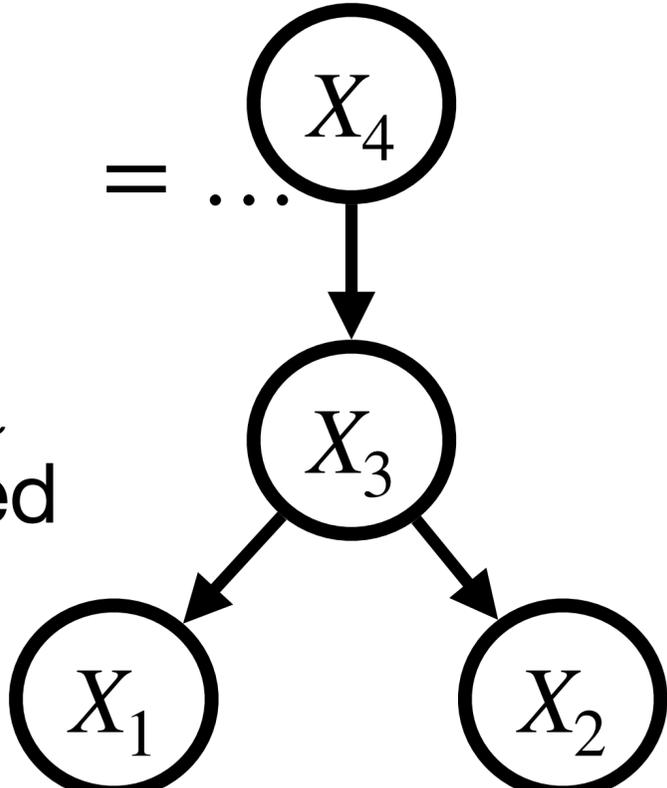
$$P_{X_1}(x_1) = \sum_{x_2} \sum_{x_3} \sum_{x_4} \sum_{x_5} P_{X_1, \dots, X_5}(x_1, x_2, x_3, x_4, x_5).$$

*This will have exponential complexity in the number of random variables.*



# Variable Elimination: Basic Idea

$$P_{X_1}(x_1) = \sum_{x_2} \sum_{x_3} \sum_{x_4} P_{X_4}(x_4) P_{X_3|X_4}(x_3 | x_4) P_{X_1|X_3}(x_1 | x_3)$$

$$= \sum_{x_3} P_{X_1|X_3}(x_1 | x_3) \sum_{x_2} P_{X_2|X_3}(x_2 | x_3) \underbrace{\left( \sum_{x_4} P_{X_4}(x_4) P_{X_3|X_4}(x_3 | x_4) \right)}_{\text{function of } x_3, \text{ it can be cached}} = \dots$$


```
graph TD; X4((X4)) --> X3((X3)); X3 --> X1((X1)); X3 --> X2((X2));
```

# Next Lecture

We will finish variable elimination... And we will talk about inference in general.