## Question 1.

Let X contain all real numbers from [0;1] which can be represented using 256 bits. Let  $\mathcal{H}=X$ , and let the decision be given by  $H\in\mathcal{H}$  as

$$h(x) = 1 \text{ iff } x > H$$

Determine an m such that with probability at least 0.9,  $\operatorname{err}(h) < 0.1$ , where h is an arbitrary hypothesis from  $\mathcal{H}$  consistent with m i.i.d. examples from X. Estimate it

- (a) without using any *textbook* lower bounds
- (b) using the lower bound  $m > \frac{1}{\epsilon} \ln \frac{|\mathcal{H}|}{\delta}$
- (c) using the lower bound  $m > \frac{8}{\epsilon} \left( \text{VC}(\mathcal{H}) \cdot \ln \frac{16}{\epsilon} + \ln \frac{2}{\delta} \right)$

## **Answer:**

We have

$$\epsilon = 0.1$$

$$\delta = 1 - 0.9 = 0.1$$

$$|\mathcal{H}| = 2^{256}$$

(a) For a fixed h, the probability that it is "bad"  $(\text{err}(h) > \epsilon)$  and still consistent with m i.i.d. observations is at most  $(1 - \epsilon)^m = 0.9^m$ .

For an arbitrary  $h \in \mathcal{H}$ , we can bound the probability of at least one of them being "bad" by

$$\sum_{h \in \mathcal{H}} (1 - \epsilon)^m = |\mathcal{H}| (1 - \epsilon)^m = 2^{256} 0.9^m$$

We want this probability to be smaller than  $\delta$ :

$$|\mathcal{H}|(1-\epsilon)^m < \delta$$

$$m \ge \log_{1-\epsilon} \frac{\delta}{|\mathcal{H}|}$$

i.e.,

$$m > \log_{0.9} \frac{0.1}{2^{256}} \approx 1707$$
 examples (smallest such  $m$ ) (1)

(b)

$$m > \frac{1}{\epsilon} \ln \frac{|\mathcal{H}|}{\delta}$$
  
 $m > \frac{1}{0.1} \ln \frac{2^{256}}{0.1} \approx 1798$  examples (smallest such  $m$ )

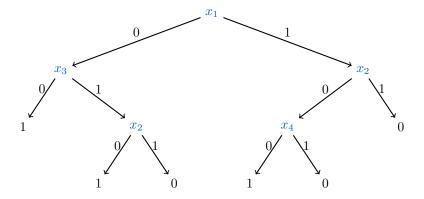
which is slightly greater than before because the upper bound  $(1 - \epsilon)^m < e^{-\epsilon m} (\epsilon > 0)$  is used in the derivation of the formula.

(c)  $VC(\mathcal{H}) = 1$  because a single number from X can evidently be shattered (classified positively or negatively by hypotheses from  $\mathcal{H}$ ) but two different numbers from X cannot be shattered: the smaller cannot be made positive while the larger is negative.

$$m > \frac{8}{\epsilon} \left( \text{VC}(\mathcal{H}) \cdot \ln \frac{16}{\epsilon} + \ln \frac{2}{\delta} \right) \approx 646 \text{ examples}$$

## Question 2.

Consider the following decision tree:



- (a) Express the tree as a 3-DNF.
- (b) Express the tree as a 3-CNF.
- (c) How can we use (modify) the generalization algorithm to learn k-decision trees in the PAC learning model?

## **Answer:**

(a) A 3-DNF is a disjunction of minterms conjoining at most 3 literals.

We construct each minterm by following one path to a positive label. By disjoining all those paths, we get the final DNF tree representation.

$$(\neg x_1 \land \neg x_3) \lor (\neg x_1 \land x_3 \land \neg x_2) \lor (x_1 \land \neg x_2 \land \neg x_4)$$

(b) A 3-CNF is a conjunction of maxterms (clauses) disjoining at most 3 literals.

We can use the fact that a negation of a DNF is a CNF. We can't negate the DNF constructed above directly, since then, we would consider paths going into the negative labels. However, we can construct a DNF going into the negative labels and negate that, giving us a CNF capturing the paths going into the positive labels.

$$\neg ((\neg x_1 \land x_3 \land x_2) \lor (x_1 \land \neg x_2 \land x_4) \lor (x_1 \land x_2))$$

We could also construct the CNF directly. Consider each path to a negative label and "do everything in your power to avoid going down that path". For example, considering the "path"  $\langle \neg x_1, x_3, x_2 \rangle$ , construct the clause  $(x_1 \vee \neg x_3 \vee \neg x_2)$ . Regardless of the strategy used, the final 3-CNF reads as

$$(x_1 \vee \neg x_3 \vee \neg x_2) \wedge (\neg x_1 \vee x_2 \vee \neg x_4) \wedge (\neg x_1 \vee \neg x_2)$$

(c) We can use the fact following from the exercises above that k-DT  $\subseteq k$ -CNF (k-DNF). Hence, we will use the generalization algorithm for learning k-CNFs (k-DNFs). Each clause (minterm) will be encoded by a new propositional variable and then we will simply be learning a conjunction (disjuction). There will be  $\sum_{i=1}^{k} {n \choose i} 2^i \leq \text{poly}(n)$  propositions, hence we will also learn efficiently. We won't be learning properly, though.

Using the adapted algorithm, we will be learning k-DTs in the mistake bound learning model, which implies that we will also be learning them in the PAC model.