

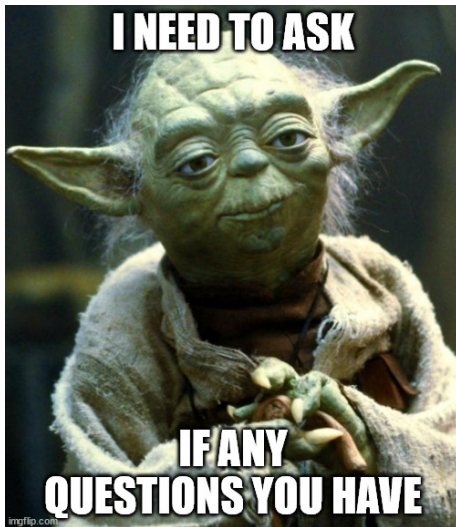
# Abstraction heuristics

## Merge & Shrink

Michaela Urbanovská

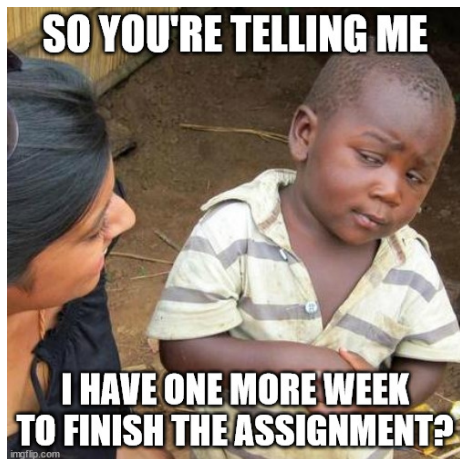
PUI Tutorial  
Week 7

- Any questions regarding the lecture?



# Organization stuff

- Lectures reorganized
- Tutorials reorganized in response
- Assignment 1 deadline moved by a week
- New deadline: **11.4.2022**

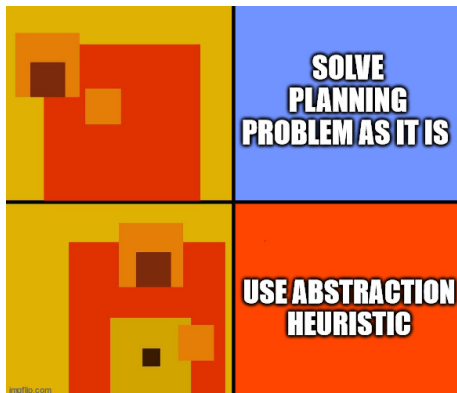


# Obtaining heuristics

- Many different possible ways to obtain a heuristic in general
- One general idea: solve a **simplified** version of the problem
  - relaxation
  - abstraction

# Obtaining heuristics

- Many different possible ways to obtain a heuristic in general
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  - relaxation
  - abstraction
- This week: **abstraction**



- Simplification of the problem
- Making the problem smaller by dropping state distinctions

Transition system  $\mathcal{T} = \langle S, L, T, I, G \rangle$

- $S$  - finite set of states
- $L$  - finite set of labels
- $T \subseteq S \times L \times S$  - transition relation
- $I \subseteq S$  - set of initial states
- $G \subseteq S$  - set of goal states
- $c(l) \in \mathbb{R}_0^+, \forall l \in L$  - cost function for each label

## Transition system for problem $P$

Transition system  $\mathcal{T}(P)$  is defined for FDR problem  $P = \langle V, O, s_{init}, s_{goal}, C \rangle$ .

The mapping goes as followed:

- $S$  is set of states over  $V$
- $L = O$
- $T = \{(s, o, t) \mid res(o, s) = t\}$
- $I = \{s_{init}\}$
- $G = \{s \mid s \in S, s \text{ is consistent with } s_{goal}\}$

## Abstraction definition

- Let's have two transition systems  $\mathcal{T}^1 = \langle S^1, L, T^1, I^1, G^1 \rangle$  and  $\mathcal{T}^2 = \langle S^2, L, T^2, I^2, G^2 \rangle$  with the same set of labels  $L$ .
- Let's have an **abstraction function**  $\alpha : S^1 \mapsto S^2$  which maps  $S^1$  to  $S^2$ .
- $S^2$  is an **abstraction** of  $S^1$  if
  - $\forall s \in I^1$  holds that  $\alpha(s) \in I^2$
  - $\forall s \in G^1$  holds that  $\alpha(s) \in G^2$
  - $\forall (s, l, t) \in T^1$  holds that  $(\alpha(s), l, \alpha(t)) \in T^2$



## Abstraction heuristic

Let  $P$  denote an FDR planning task and  $\mathcal{A}$  denote an **abstraction** of its transition system  $\mathcal{T}(P)$ .

**Abstraction heuristic** induced by  $\mathcal{A}$  and  $\alpha$  is the function

$$h^{A,\alpha} = h_{\mathcal{A}}^*(\alpha(s)), \forall s \in S$$

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## Synchronized product

Given two transition systems  $\mathcal{T}^1 = \langle S^1, L, T^1, I^1, G^1 \rangle$  and  $\mathcal{T}^2 = \langle S^2, L, T^2, I^2, G^2 \rangle$  with the same labels, their **synchronized product**  $\mathcal{T}^1 \otimes \mathcal{T}^2 = \mathcal{T}$  is a transition system  $\mathcal{T} = \langle S, L, T, I, G \rangle$ , where

- $S = S^1 \times S^2$
- $T = \{((s_1, s_2), l, (t_1, t_2)) \mid (s_1, l, t_1) \in T^1, (s_2, l, t_2) \in T^2\}$
- $I = I^1 \times I^2$
- $G = G^1 \times G^2$

- Different types of abstraction heuristics
- How to select  $\alpha$ ?
- In this tutorial: **merge & shrink**
- Consists of
  - merging = computing synchronized products of the abstractions
  - shrinking = abstracting the abstractions further
- There are many strategies...so we will just focus on the main thought behind it

# Merge & Shrink heuristic

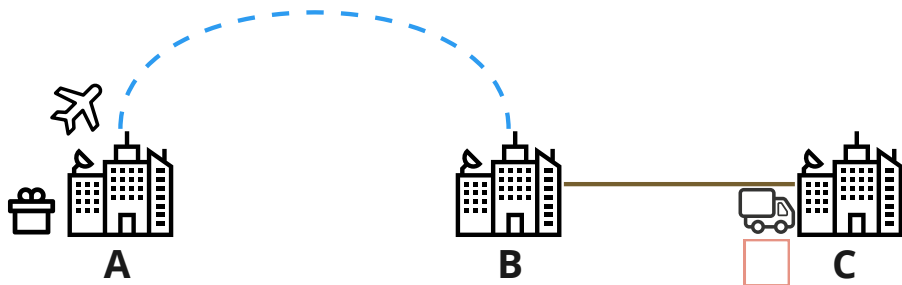
## Transition systems $\mathcal{T}^1$ and $\mathcal{T}^2$

- $L^1 = L^2 = \{a, b, c, d, e\}$
- $S^1 = \{A, B, C, D\}$
- $T^1 = \{(A, a, B), (B, b, C), (C, c, A), (A, d, A), (A, e, D)\}$
- $I^1 = \{A\}$
- $G^1 = \{A, C\}$
- $S^2 = \{X, Y, Z\}$
- $T^2 = \{(X, a, Y), (X, a, Z), (Y, b, Z), (Z, c, Y), (Z, d, Y), (Z, e, Z)\}$
- $I^2 = \{X\}$
- $G^2 = \{X\}$

Let's compute synchronized product!

# Logistics example

Let's try an example we know well...



# FDR representation

FDR problem  $P = \langle V, O, s_I, s_G, c \rangle$

$V = \{a, t, p\}$

$D_a = \{A, B\}$   $D_t = \{B, C\}$   $D_p = \{A, B, C, a, t\}$

$s_I = \{a = A, t = C, p = A\}$

$s_G = \{p = C\}$

|     | pre      | eff | c |
|-----|----------|-----|---|
| fAB | a=A      | a=B | 1 |
| fBA | a=B      | a=A | 1 |
| dBC | t=B      | t=C | 1 |
| dCB | t=C      | t=B | 1 |
| laA | a=A, p=A | p=a | 1 |
| laB | a=B, p=B | p=a | 1 |
| ltB | t=B, p=B | p=t | 1 |
| ltC | t=C, p=C | p=t | 1 |
| uaA | p=a, a=A | p=A | 1 |
| uaB | p=a, a=B | p=B | 1 |
| utB | p=t, t=B | p=B | 1 |
| utC | p=t, t=C | p=C | 1 |

- One possible representation is by **atomic projections**
- One transition system for one variable from  $V = \{a, t, p\}$

 $\mathcal{T}^a$ 

$$S^a = \{aA, aB\}$$

$$I^a = \{aA\}$$

$$G^a = \{aA, aB\}$$

 $\mathcal{T}^t$ 

$$S^t = \{tB, tC\}$$

$$I^t = \{tC\}$$

$$G^t = \{tB, tC\}$$

 $\mathcal{T}^p$ 

$$S^p =$$

$$\{pA, pB, pC, pa, pt\}$$

$$I^p = \{pA\}$$

$$G^p = \{pC\}$$

# Transitions in atomic projections

$$L = \{fAB, fBA, dBC, dCB, laA, laB, uaA, uaB, ltB, ltC, utB, utC\}$$



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$$T^a = \{(aA, fAB, aB), (aB, fBA, aA)\}$$

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$$T^t = \{(tB, dBC, tC), (tC, dCB, tB)\}$$

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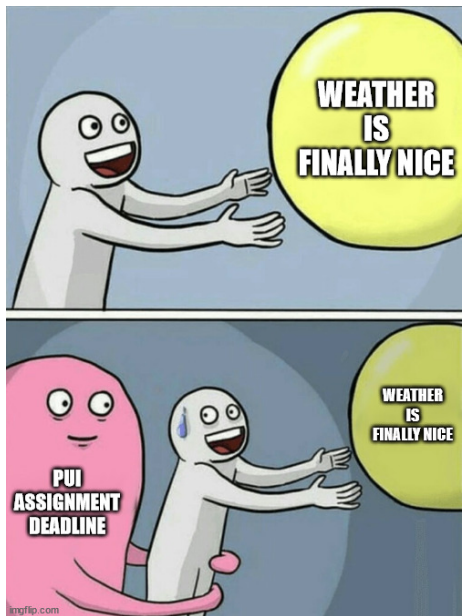
$$T^t = \{(tB, dBC, tC), (tC, dCB, tB)\}$$

$$T^p = \{(pA, laA, pa), (pa, uaA, pA), (pa, uaB, pB), (pB, laB, pa), \\ (pB, ltB, pt), (pt, utB, pB), (pt, utC, pC), (pC, ltC, pt)\}$$

- 1 Create atomic projections (one per variable)
- 2 Merge two arbitrary transition systems (synchronized product)
- 3 Shrink the new transition graph (merge states together to create smaller abstraction)
- 4 Repeat 2 and 3 until you're left with one abstraction in which you can find the solution

- How to create synchronized product
- Atomic projections
- Merge & Shrink main principle
  - **merging** = creating synchronized products of two transition systems
  - **shrinking** = creating smaller abstraction

# The End



[Feedback form link](#)

