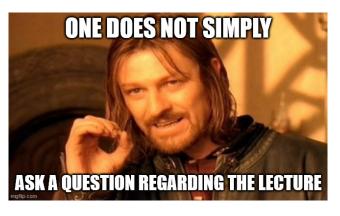
Landmark heuristics

Michaela Urbanovská

PUI Tutorial Week 4

Lecture check

• Any questions regarding the lecture?



Feedback

- Specific suggestions on how to improve the lectures (I passed that information)
- Overall good scores
- Thank you!

LM-Cut

LM-Cut Heuristic

- Relaxation heuristic
- Uses disjunctive operator landmarks
- Admissible (and actually very successful) heuristic

Things we need to know to compute it

- Disjunctive operator landmark
 - Operator supporter
 - Justification graph
 - s-t cut

Disjunctive operator landmark

Disjunctive operator landmark $L \subseteq O$ is set of operators such that every plan π contains at least one operator $o \in L$.

Example

Suppose we have problem with 2 existing plans:

•
$$\pi_1 = (o_1, o_2, o_3, o_4)$$

•
$$\pi_2 = (o_1, o_5, o_2, o_6)$$

Which of the following sets are disjunctive operator landmarks?

0 { o_1 }

 $\{o_1, o_2, o_3, o_4\}$

 $\{o_1, o_3\}$

 $\{o_3, o_4\}$

 o_2, o_3

 $\{o_4, o_6\}$

LM-Cut

Disjunctive operator landmark

Disjunctive operator landmark $L \subseteq O$ is set of operators such that every plan π contains at least one operator $o \in L$.

Example

Suppose we have problem with 2 existing plans:

•
$$\pi_1 = (o_1, o_2, o_3, o_4)$$

$$\bullet$$
 $\pi_2 = (o_1, o_5, o_2, o_6)$

Which of the following sets are disjunctive operator landmarks?

- $\{o_1\}$
- \bullet { o_1, o_3 }
- $\{o_2, o_3\}$

- \bullet { o_1, o_2, o_3, o_4 }
- $\{o_3, o_4\}$
- $\{o_4, o_6\}$

Delta function

• Function Δ_1 from previous tutorial (h^{max})

```
 \begin{array}{l} \bullet \ \Delta_1(s,f) = \\ \begin{cases} 0 & \text{if } f \in s, \\ \inf & \text{if } \forall o \in O : f \notin add(o), \\ \min\{c(o) + \Delta_1(s,o) | o \in O, f \in add(o)\} & \text{otherwise}. \\ \end{cases}
```

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LM-Cut

Supporter of an operator

Supporter is a fact.

Function $supp(o) = argmax_{f \in pre(o)} \Delta_1(s, f)$ maps each operator $o \in O$ to its **supporter**.

(s denotes the state where we compute the heuristic estimate)

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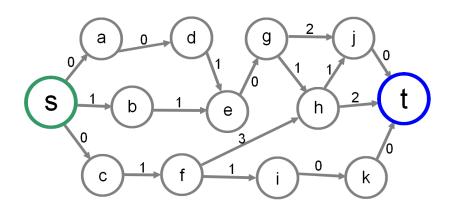
Justification graph

G = (N, E) is a **directed labeled** multigraph.

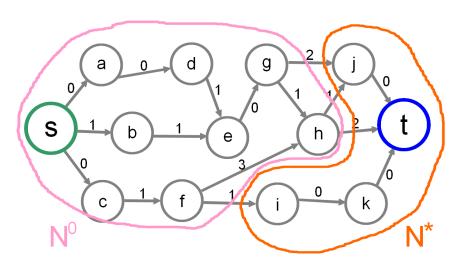
- $N = \{n_f | f \in F\}$ (set of nodes)
- $E = \{(n_s, n_t, o) | o \in O, s = supp(o), t \in add(o)\}$ (set of edges)
- Edge e = (a, b, l) denotes edge from a to b with label l

s-t cut

- s-t cut $C(G, s, t) = (N^0, N^* \cup N^b)$
- partitioning of nodes from the **justification graph** G = (N, E)
- ullet N^* contains nodes from which t can be reached with zero-cost path
- ullet N^0 contains nodes which can be reached from s without passing any node from N^*
- $N^b = N \setminus (N^0 \cup N^*)$ (all the other nodes)



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15 end

```
Algorithm 2: Algorithm for computing h^{lm-cut}(s).
```

```
Input: \Pi = \langle \mathcal{F}, \mathcal{O}, s_{init}, s_{goal}, \mathbf{c} \rangle, state s
    Output: h^{lm-cut}(s)
 1 if h^{\max}(\Pi, s_{init}) = \infty then
        h^{lm-cut}(s) \leftarrow \infty and terminate;
 3 end
 4 h<sup>lm-cut</sup>(s) ← 0;
 5 \Pi_1 = \langle \mathcal{F}' = \mathcal{F} \cup \{I, G\}, \mathcal{O}' = \mathcal{O} \cup \{o_{init}, o_{qoal}\}, s'_{init} = \{I\}, s'_{qoal} = \{G\}, c_1 \rangle, where
      \operatorname{pre}(o_{init}) = \{I\}, \operatorname{add}(o_{init}) = s, \operatorname{del}(o_{init}) = \emptyset, \operatorname{pre}(o_{goal}) = s_{goal}, \operatorname{add}(o_{goal}) = \{G\},
      del(o_{goal}) = \emptyset, c_1(o_{init}) = 0, c_1(o_{goal}) = 0, and c_1(o) = c(o) for all o \in \mathcal{O};
 6 i \leftarrow 1;
 7 while h^{\max}(\Pi_i, s'_{i=i}) \neq 0 do
          Construct a justification graph G_i from \Pi_i:
          Construct an s-t-cut C_i(G_i, n_I, n_G) = (N_i^0, N_i^* \cup N_i^b);
 g
          Create a landmark L_i as a set of labels of edges that cross the cut C_i, i.e., they
10
           lead from N_i^0 to N_i^*;
          m_i \leftarrow \min_{o \in I_i} c_i(o);
11
          h^{lm-cut}(s) \leftarrow h^{lm-cut}(s) + m_i;
12
          Set \Pi_{i+1} = \langle \mathcal{F}', \mathcal{O}', s'_{init}, s'_{ooal}, c_{i+1} \rangle, where c_{i+1}(o) = c_i(o) - m_i if o \in L_i, and
13
           c_{i+1}(o) = c_i(o) otherwise;
         i \leftarrow i + 1:
14
```

06

```
Algorithm 2: Algorithm for computing h^{lm-cut}(s).
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```

Recap

- You should be able to compute and implement LM-Cut
- Everything you need to do the assignment 1!

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The End



Feedback form link

