

# Digital Image

(B4M33DZO, Summer 2024)

## Lecture 8: Image Registration 1

<https://cw.fel.cvut.cz/wiki/courses/b4m33dzo/start>

**Daniel Sýkora & Ondřej Drbohlav**

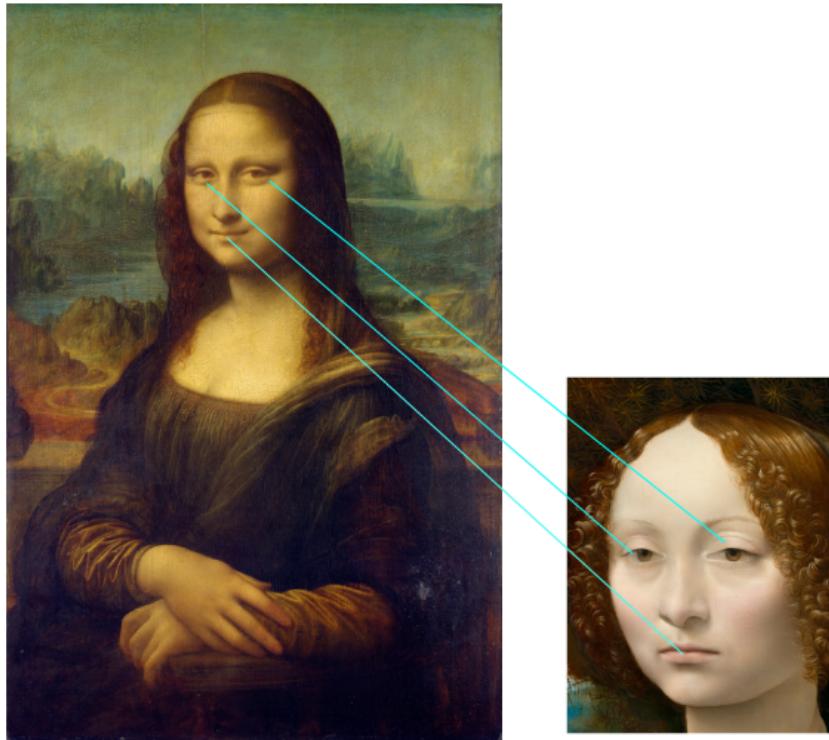
Department of Cybernetics

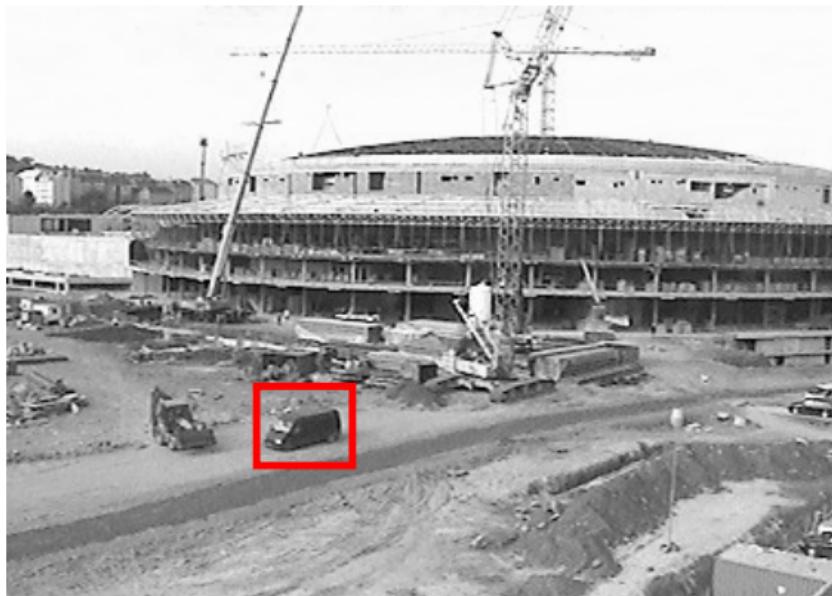
Faculty of Electrical Engineering

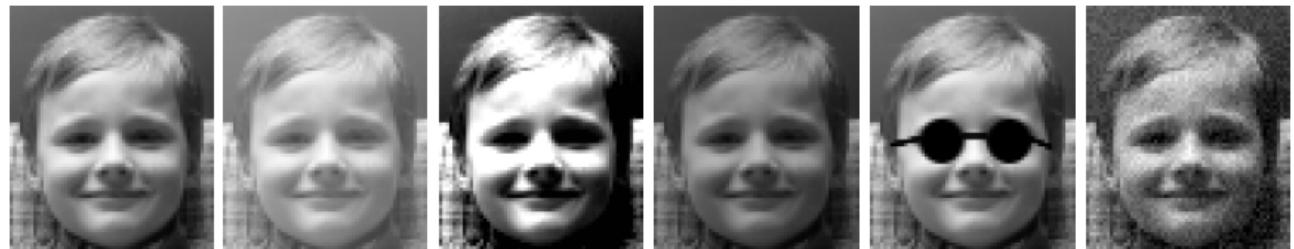
Czech Technical University in Prague

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**Sum of absolute differences (SAD):**  $\sum_x \sum_y |\mathbf{A}[x, y] - \mathbf{B}[x, y]|$



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**Cross-correlation:**

$$\sum_x \sum_y \mathbf{A}(x, y) \cdot \mathbf{B}(x, y)$$



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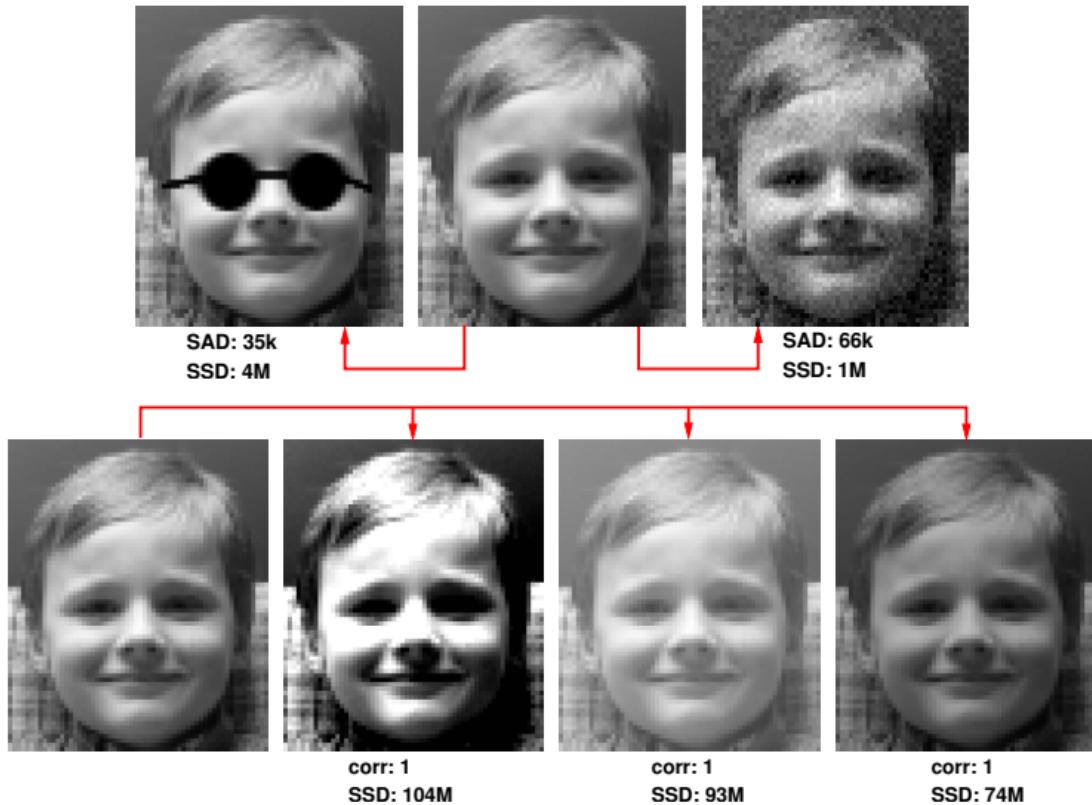
$$\sum_x \sum_y \mathbf{A}[x, y]^2 - 2 \cdot \mathbf{A}[x, y] \cdot \mathbf{B}[x, y] + \mathbf{B}[x, y]^2$$

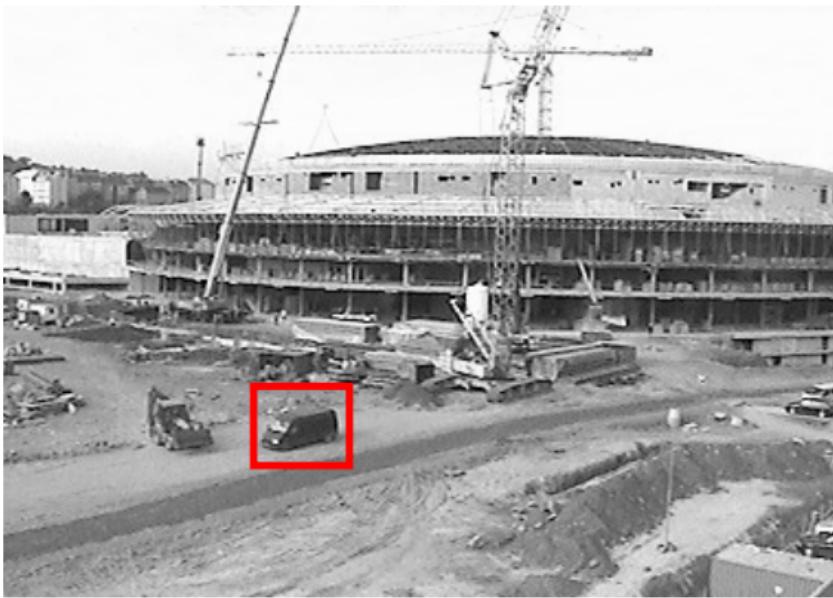
**Normalized cross-correlation:**

$$\frac{1}{\sigma_{\mathbf{A}} \sigma_{\mathbf{B}}} \sum_x \sum_y \left( \mathbf{A}(x, y) - \hat{\mathbf{A}} \right) \cdot \left( \mathbf{B}(x, y) - \hat{\mathbf{B}} \right)$$

(invariant to brightness & contrast changes)

# Image similarity



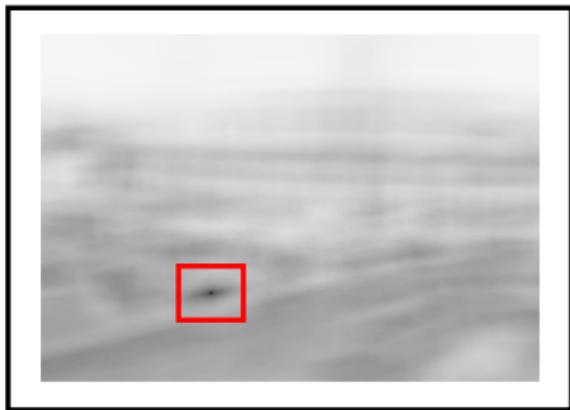
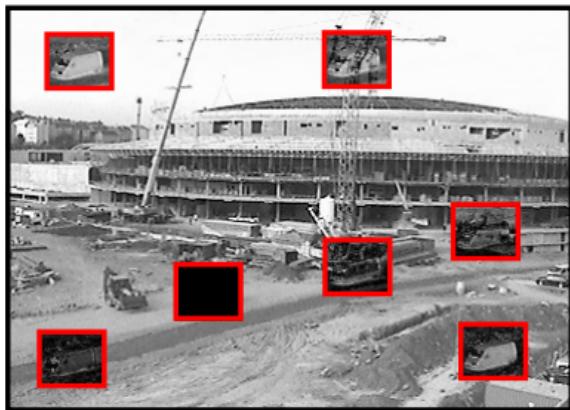


Minimize similarity metric  $\circ$  over all possible shifts:

$$\arg \min_{[\mathbf{s}, \mathbf{t}]} \sum_x \sum_y \mathbf{A}[x + \mathbf{s}, y + \mathbf{t}] \circ \mathbf{B}[x, y]$$

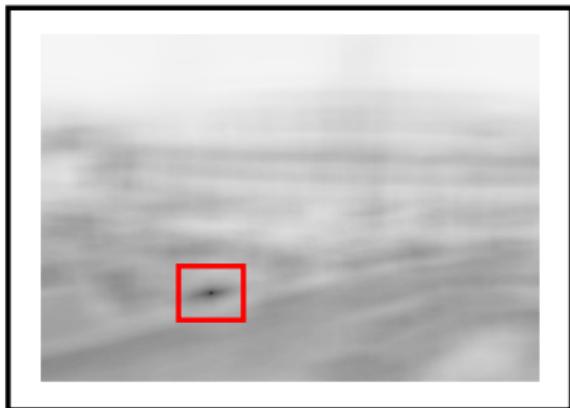
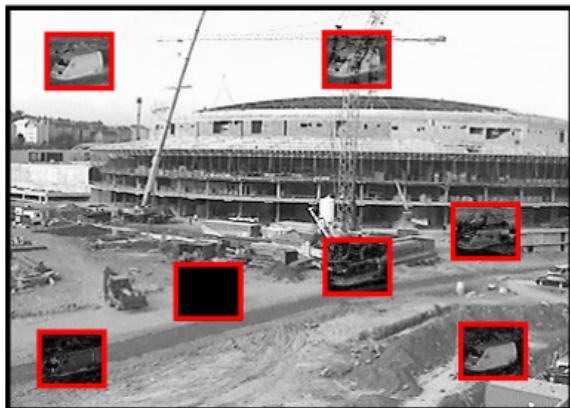
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**Problem:** complexity of block matching is  $\mathcal{O}(|\mathbf{A}| \cdot |\mathbf{B}|)$ .

**SSD ( $\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$ , global minimum):**

$$\arg \min_{[\mathbf{s}, \mathbf{t}]} \sum_{x=0}^w \sum_{y=0}^h (\mathbf{A}[x + \mathbf{s}, y + \mathbf{t}] - \mathbf{B}[x, y])^2 =$$

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$$\arg \min_{[\mathbf{s}, \mathbf{t}]} \left( \sum_{x=\mathbf{s}}^{s+w} \sum_{y=\mathbf{t}}^{t+h} \mathbf{A}[x, y]^2 - 2 \sum_{x=0}^w \sum_{y=0}^h \mathbf{A}[x + \mathbf{s}, y + \mathbf{t}] \cdot \mathbf{B}[x, y] \right)$$

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Summed area table:

$$\sum_{x=\mathbf{s}}^{\mathbf{s}+w} \sum_{y=\mathbf{t}}^{\mathbf{t}+h} \mathbf{A}[x, y]^2 = \Sigma[\mathbf{s}, \mathbf{t}] - \Sigma[\mathbf{s} + w, \mathbf{t}] - \Sigma[\mathbf{s}, \mathbf{t} + h] + \Sigma[\mathbf{s} + w, \mathbf{t} + h]$$

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$$\sum_{x=\mathbf{s}}^{\mathbf{s}+w} \sum_{y=\mathbf{t}}^{\mathbf{t}+h} \mathbf{A}[x, y]^2 = \Sigma[\mathbf{s}, \mathbf{t}] - \Sigma[\mathbf{s} + w, \mathbf{t}] - \Sigma[\mathbf{s}, \mathbf{t} + h] + \Sigma[\mathbf{s} + w, \mathbf{t} + h]$$

**Fourier convolution theorem:**

$$\sum_{x=0}^w \sum_{y=0}^h \mathbf{A}[x + \mathbf{s}, y + \mathbf{t}] \cdot \mathbf{B}[x, y] = \mathcal{F}^{-1} \{ \mathcal{F}\{\mathbf{A}\} \cdot \mathcal{F}\{\mathbf{B}^+\} \} [\mathbf{s}, \mathbf{t}]$$

**Phase correlation ( $\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$ , local minimum):**

$$\mathbf{A}[x, y] * \delta(\textcolor{green}{s}, \textcolor{green}{t}) = \mathbf{B}[x, y] \iff \mathcal{A}[u, v] \cdot e^{2\pi i(u\textcolor{green}{s}+v\textcolor{green}{t})} = \mathcal{B}[u, v]$$

Phase correlation ( $\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$ , local minimum):

$$\mathbf{A}[x, y] * \delta(\textcolor{brown}{s}, \textcolor{brown}{t}) = \mathbf{B}[x, y] \iff \mathcal{A}[u, v] \cdot e^{2\pi i(u\textcolor{brown}{s}+v\textcolor{brown}{t})} = \mathcal{B}[u, v]$$

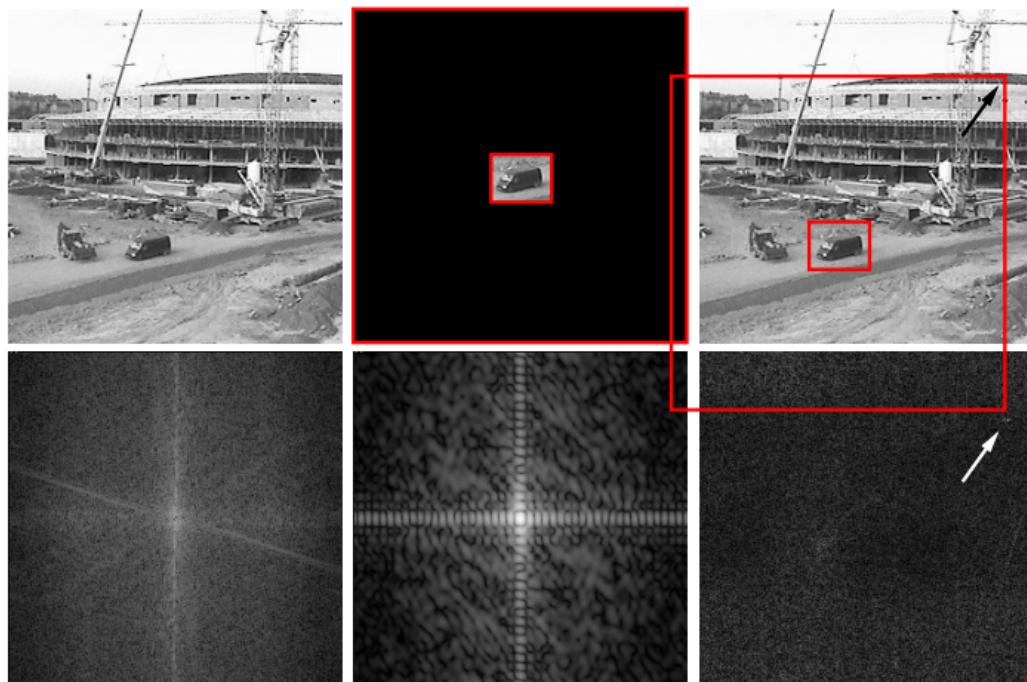
$$\frac{\mathcal{A}^*[u, v] \cdot \mathcal{B}[u, v]}{|\mathcal{A}[u, v]|^2} = e^{2\pi i(u\textcolor{brown}{s}+v\textcolor{brown}{t})} \implies \delta(\textcolor{brown}{s}, \textcolor{brown}{t})$$

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Phase correlation ( $\mathcal{O}(|A| \cdot \log |A|)$ , local minimum):



**Polar transformation:**

**rotation**     $\implies$     **translation on y-axis**

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$$r = \sqrt{(x - x_c)^2 + (y - y_c)^2}$$

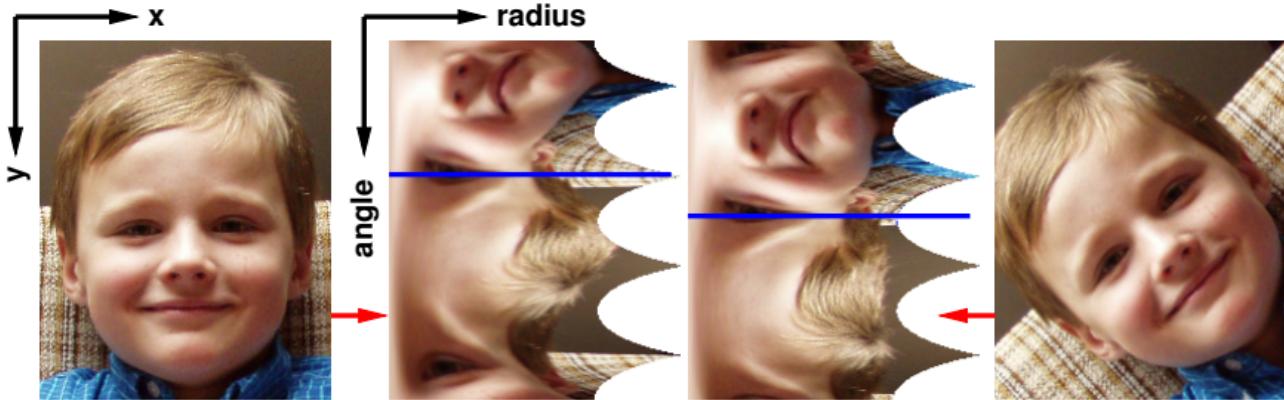
$$\alpha = \arctan \frac{y - y_c}{x - x_c}$$

## Polar transformation:

**rotation**  $\implies$  **translation on y-axis**

$$r = \sqrt{(x - x_c)^2 + (y - y_c)^2}$$

$$\alpha = \arctan \frac{y - y_c}{x - x_c}$$



**Log-polar transformation:**

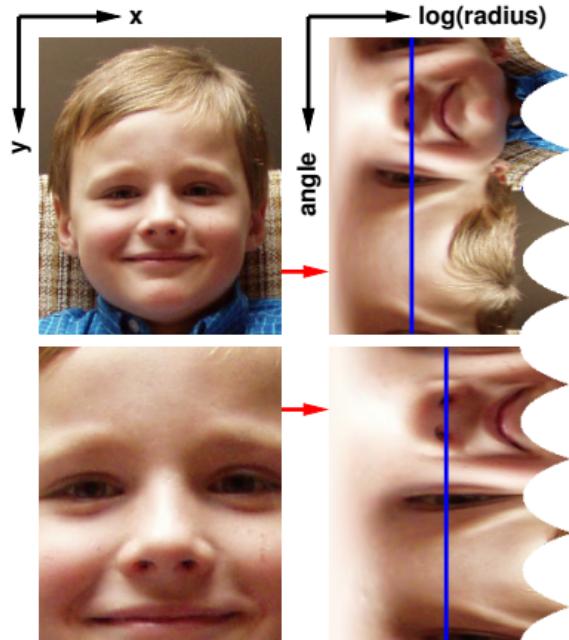
scale     $\implies$    translation on x-axis  
rotation     $\implies$    translation on y-axis

## Log-polar transformation:

scale  $\implies$  translation on x-axis  
rotation  $\implies$  translation on y-axis

$$r = \log \left( \sqrt{(x - x_c)^2 + (y - y_c)^2} \right)$$

$$\alpha = \arctan \frac{y - y_c}{x - x_c}$$



## Fourier-Mellin transformation:

1. Estimate rotation and scale using frequency domain.
2. Resample image to have the same rotation and scale.
3. Use standard phase correlation to estimate translation.

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