IMPLEMENTING A MULTIAGENT SYSTEM

Karel Horák

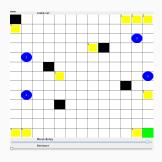
BE4M36MAS - Multiagent systems

MINING WORLD

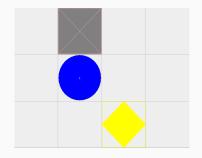
MINING WORLD

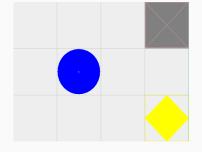
Find, collect and carry all gold stones from their location to a depot!

- Miners do not know positions of gold stones and depots — they must find them
- They may carry at most one gold stone at a time
- They have limited range of sight (8-neighbourhood)



MINING WORLD — PERCEPTS





Visible: (gold,2,2), (depot,1,0)

No objects visible!

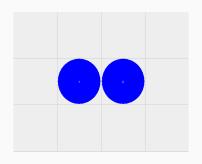
MINING WORLD — ACTIONS

- left(), right(), up(), down() movement in the grid
- pick(), drop() manipulating gold stones
- sense() use it to update your percepts (nearly no delay)

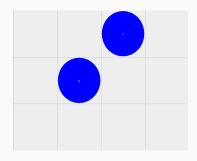
MINING WORLD — PROBLEM 1

Gold stones are heavy.

 \rightarrow there must be another miner in 4-neighbourhood for pick()



pick() succeeds

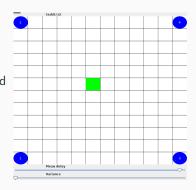


pick() fails

SCENARIOS & GRADING

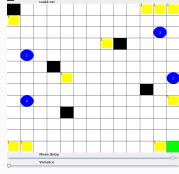
Gold stones are **added in runtime** \rightarrow Your miners must be able to find them at any time

2 points



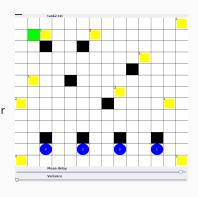
- You are racing the time now
- Your miners should not be much slower than (inefficient) reference solution (if your agents actively pursue the

(if your agents actively pursue their goal, you will have no problems) 1 point



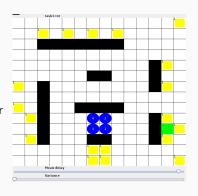
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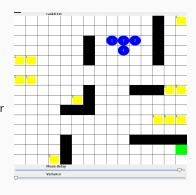
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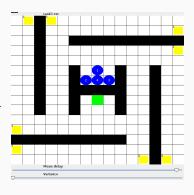
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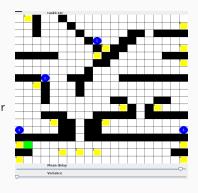
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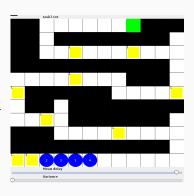
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MINING WORLD — COMPETITION

You can get 1 more point for implementing a fast mining team.

A competition between your submissions will be held

ightarrow Performance of your miners will be evaluated based on **Scenarios 2-8** (Multiple runs will be performed, you get i points for being ith within the run, top 25% submissions with lowest number of total points get 1 point)

REPORT

You are asked to submit a short report:

- What approach have you used for discovering gold stones and depots?
- How have you solved synchronization problems?
- What issues have you encountered and how have you overcome them?

• ..

Reward: 1 point

Deadline: 2. 11. 2020 04:00

IMPLEMENTATION

• Think before implementation

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- Be prepared for possible issues!

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- Keep it simple!

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- Do not try to hack the framework!

To start with the implementation,

Follow the Instructions on Courseware

ACTIONS & SENSING

- In the AbstractAgent class
- right(), left(), up(), down(), drop(), pick()
- Sensor input is returned from all actions. Also, there is a special action just for sensing: sense().

BASIC COMMUNICATION

- send: sendMessage(agentID, messageObject)
- read: Message m = readMessage();

HINTS

To be successful, you will probably need

- to communicate between agents,
- to have a representation of the environment,
- to plan somehow, at least for a short time horizon,
- and to cooperate and distribute the task between agents

NEXT

NEXT TUTORIAL

Normal-Form Games by Dominik Seitz

ASSIGNMENT 1 CONSULTATIONS

Link to poll