# Statistical Machine Learning (BE4M33SSU) Lecture 1.

Czech Technical University in Prague

# **Course format**



Teachers: Jan Drchal, Vojtech Franc and Jakub Paplhám

**Format:** 1 lecture & 1 seminar per week (6 credits)

Seminars: Solving theoretical assignments; explaining and discussing homeworks.

### Homeworks:

- 1. Automaticaly evaluated: You have to submit a Python code.
- 2. Manually evaluated: You have to submit i) PDF report and ii) a Python code.

### Grading:

- Thresholds for passing: at least 50% of the regular points in the practical labs and at least 50% of the regular points in the exam.
- 40% homeworks + 60% written exam = 100% (+ bonus points)

### **Prerequisites:**

- probability theory and statistics (A0B01PSI)
- pattern recognition and machine learning (AE4B33RPZ)
- optimisation (AE4B33OPT)

### More details: https://cw.fel.cvut.cz/wiki/courses/be4m33ssu/start

# Goals



The aim of statistical machine learning is to develop systems (models and algorithms) for solving prediction tasks given a set of examples and some prior knowledge about the task.

Machine learning has been successfully applied e.g. in areas

- email spam detection,
- computer vision,
- credit scoring,
- medical diagnosis,
- recommendation systems,
- speech recognition,
- network intrusion,
- natural language processing,
- and many others

You will gain skills to construct learning systems for typical applications by successfully combining appropriate models and learning methods.

# **Prediction problem**



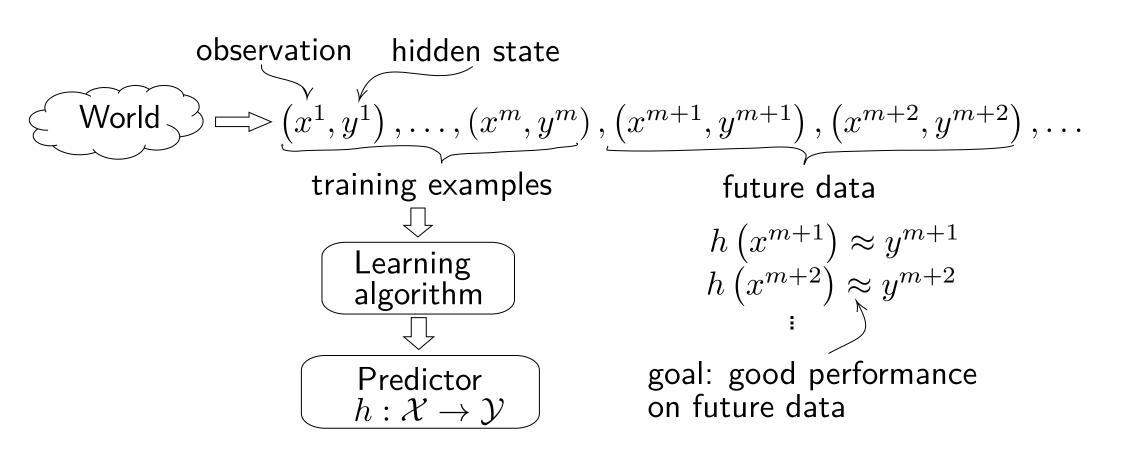
**Example:** Given data representing weight of adult males and females:

weight [kg]	99	65	83	76	77	•••
gender	male	female	male	male	female	•••

we want a predictor which outputs a person's gender given his/her weight.

- Input observations (features)  $x \in \mathcal{X}$ ; x can be: a categorical variable, a scalar, a real valued vector, a tensor, a sequence of values, an image, a labelled graph, ldots
- Hidden state (target variable, output)  $y \in \mathcal{Y}$ ; y can be: see above
- **Prediction strategy (predictor)**  $h: \mathcal{X} \to \mathcal{Y}$ ; depending on the type of  $\mathcal{Y}$ :
  - y is a categorical variable  $\Rightarrow$  classification
  - y is a real valued variable  $\Rightarrow$  regression

# **Machine learning**



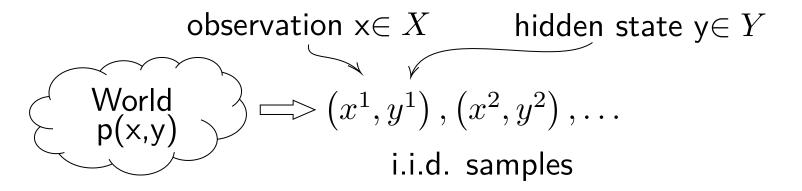
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5/14

### Main assuption: i.i.d. data





- **Data:**  $(x^1, y^1), (x^2, y^2), \ldots, (x^n, y^n)$  are samples drawn from independent and identically distributed (i.i.d.) pairs of random vars  $(X^1, Y^1), (X^2, Y^2), \ldots$
- Identically distributed:

$$p(X^1 = x, Y^1 = y) = p(X^2 = x, Y^2 = y) = \dots = p(X^n = x, Y^n = y), \quad \forall x \in \mathcal{X}, y \in \mathcal{Y}$$

Remark: we will use p(x, y) instead of p(X = x, Y = y).

• Independent: the occurrence of one pair does not affect the occurrence of another:

$$p(x^1, y^1, x^2, y^2, \dots, x^n, y^n) = p(x^1, y^1) p(x^2, y^2) \cdots p(x^n, y^n)$$

### The optimal predictor

Loss function  $\ell: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}_+$  penalises wrong predictions, i.e.  $\ell(y, \hat{y})$  is the loss for predicting  $\hat{y} = h(x)$  when y is the true state. *Example: 0/1-loss* 

$$\ell(y, \hat{y}) = \begin{cases} 0 & \text{if } y = \hat{y} \\ 1 & \text{if } y \neq \hat{y} \end{cases}$$

**Expected risk (a.k.a. generalization error)** evaluates the performance of a predictor  $h: \mathcal{X} \to \mathcal{Y}$  on unseen data:

$$R(h) = \int \sum_{y \in \mathcal{Y}} \ell(y, h(x)) \ p(x, y) \ \mathrm{d}x = \mathbb{E}_{(x, y) \sim p} \Big[ \ell(y, h(x)) \Big]$$

The expected risk R(h) represents the average loss  $\ell(y, h(x))$  when evaluated over large i.i.d. sample  $(x^1, y^1), \ldots, (x^n, y^n)$ :

$$\frac{1}{n}\Big(\ell(y^1, h(x^1)) + \ell(y^2, h(x^2)) + \dots + \ell(y^n, h(x^n))\Big) \xrightarrow{p} R(h)$$

Bayes optimal predictor:

$$h^* \in \underset{h \in \mathcal{Y}^{\mathcal{X}}}{\arg\min} R(h) \quad \Rightarrow \quad h^*(x) = \underset{\hat{y} \in \mathcal{Y}}{\arg\min} \sum_{y \in \mathcal{Y}} p(y \mid x) \ell(y, \hat{y})$$

### Data split for learning and evaluation

• Setup: we have only samples i.i.d drawn from an unknown p(x, y).

$$\underbrace{\left(\begin{matrix} \mathsf{World} \\ p(x,y) \end{matrix}\right)}_{\text{training set}} = \underbrace{\left(x^1,y^1\right),\ldots,\left(x^m,y^m\right),\left(x^{m+1},y^{m+1}\right),\ldots,\left(x^{m+l},y^{m+l}\right),\ldots}_{\text{test set}}$$

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8/14

• Learning: find  $h: \mathcal{X} \to \mathcal{Y}$  with small generalization error R(h) using training (sequence) set

$$\mathcal{T}^m = ((x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m)$$
 drawn i.i.d. from  $p(x, y)$ 

• **Evaluation**: estimate the expected risk R(h) of a given predictor  $h: \mathcal{X} \to \mathcal{Y}$  using *test* (sequence) set

$$\mathcal{S}^{l} = ((x^{i}, y^{i}) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, l)$$
 drawn i.i.d. from  $p(x, y)$ 

### **Evaluation**

• **Goal:** Given a predictor  $h: \mathcal{X} \to \mathcal{Y}$  and a test set  $\mathcal{S}^{l} = ((x^{i}, y^{i}) \in \mathcal{X} \times \mathcal{Y} \mid i = 1, ..., l)$ drawn i.i.d. from an <u>unknown</u> distribution p(x, y), estimate is the expected risk

9/14

$$R(h) = \mathbb{E}_{(x,y) \sim p}[\ell(y,h(x))]$$

• Approach:

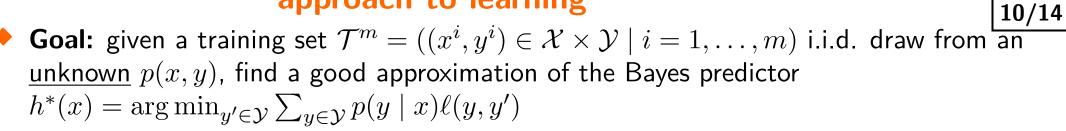
• Estimate the expected risk R(h) by computing the empirical risk (test error)

$$R_{\mathcal{S}^{l}}(h) = \frac{1}{l} \left( \ell(y^{1}, h(x^{1})) + \dots + \ell(y^{l}, h(x^{l})) \right) = \frac{1}{l} \sum_{i=1}^{l} \ell(y^{i}, h(x^{i}))$$

#### Issues:

• How much can R(h) deviate from  $R_{S^l}(h)$ ? Lecture: "Predictor Evaluation"

# Empirical Risk Minimization (a.k.a discriminative) approach to learning



Approach:

- Use prior knowledge to choose a hypothesis space  $\mathcal{H} \subset \mathcal{Y}^{\mathcal{X}} = \{h \colon \mathcal{X} \to \mathcal{Y}\}$
- Approximate the expected risk R(h) by the empirical risk (training error)

$$R_{\mathcal{T}^m}(h) = \frac{1}{m} \left( \ell(y^1, h(x^1)) + \dots + \ell(y^m, h(x^m)) \right) = \frac{1}{m} \sum_{i=1}^m \ell(y^i, h(x^i))$$

• Learn the predictor by minimizing the emprical risk:

$$h_m \in \operatorname*{arg\,min}_{h \in \mathcal{H}} R_{\mathcal{T}^m}(h)$$

#### Issues:

- How much can R(h) deviate from  $R_{\mathcal{T}^m}(h)$ ? How does it depend on  $\mathcal{H}$ ? Lecture: "Empirical Risk Minimization"
- How much can  $R(h_m)$  deviate from  $R(h^*)$  ? Lecture: "PAC learning"

# Instances of ERM approach



Learning algorithms implementing the Empirical risk minimization approach, i.e.

 $h_m \in \operatorname*{arg\,min}_{h \in \mathcal{H}} R_{\mathcal{T}^m}(h)$ 

differ in the choice of the hypothesis space  $\mathcal{H} \subset \mathcal{Y}^{\mathcal{X}}$  and the loss  $\ell \colon \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}_+$ .

- Support Vector Machines:  $\mathcal{H} = \{h(x) = \operatorname{sign}(\langle \phi(x), w \rangle + b)\}$  is a space of linear classifiers;  $\ell$  is the hinge loss.
  - Lecture: "Support Vector Machines"

• Neural networks:  $\mathcal{H} = \{h(x) = h_L(\cdots(h_2(h_1(x)))\cdots)\}$  is a space of neural networks;  $\ell$  is e.g. cross-entropy loss or  $L_2$ -loss.

• Two lectures: "Supervised learning of deep neural networks" and "SGD"

Ensemble predictors:  $\mathcal{H} = \{h(x) = \psi(h_1(x)\alpha_1 + h_2(x)\alpha_2 + \cdots + h_L(x)\alpha_L)\}$  is a space of predictors that combine predictions of multiple models;  $\ell$  is e.g. logistic loss or  $L_2$  loss.

• Two lectures: "Ensembling I" and "Ensembling II"

### **Generative Learning**



• **Goal:** given a training set  $\mathcal{T}^m = ((x^i, y^i) \in \mathcal{X} \times \mathcal{Y} \mid i = 1, ..., m)$  i.i.d. draw from an <u>unknown</u> p(x, y), find a good approximation of the Bayes predictor  $h^*(x) = \arg \min_{y' \in \mathcal{Y}} \sum_{y \in \mathcal{Y}} p(y \mid x) \ell(y, y')$ 

### Approach:

- Use the training set  $\mathcal{T}^m$  to find  $\hat{p}(x,y)$  that approximates the true p.d. p(x,y).
- Use the estimated p.d.  $\hat{p}(x,y)$  to construct the plugin Bayes predictor

$$\hat{h}(x) = \underset{y' \in \mathcal{Y}}{\arg\min} \sum_{y \in \mathcal{Y}} \hat{p}(y \mid x) \ell(y, y')$$

### Maximum Likelihood estimation:

- Assume the true p.d. p(x, y) is in some parametrized family of distributions  $\mathcal{P} = \{p_{\theta}(x, y) \mid \theta \in \Theta\}.$
- Find ML estimate of the parameters  $\theta_m = \underset{\theta \in \Theta}{\arg \max} \frac{1}{m} \sum_{i=1}^m \log p_{\theta}(x^i, y^i)$ .
- Insert  $\hat{p}(x,y) = p_{\theta_m}(x,y)$  to the plugin Bayes predictor.
- Two lectures: "Maximum Likelihood Estimator" and "Expectation-Maximization Algorithm"

# **Generative Learning**



### Bayesian Learning:

- Assume the true p.d. p(x, y) is in some parametrized family of distributions  $\mathcal{P} = \{ p(x, y \mid \theta) \mid \theta \in \Theta \}.$
- Interpret the unknown parameter  $\theta \in \Theta$  as a random variable.
- Assume we know the prior distribution  $p(\theta)$  on  $\Theta.$
- Approach 1: <u>MAP estimate</u>

$$\theta_m = \underset{\theta \in \Theta}{\operatorname{arg\,max}} p(\theta \mid \mathcal{T}^m)$$

and set  $\hat{p}(x, y) = p(x, y \mid \theta_m)$ .

• Approach 2: Bayesian inference

$$h(x, \mathcal{T}^m) = \operatorname*{arg\,max}_{y \in \mathcal{Y}} \int_{\Theta} p(x, y \mid \theta) \, p(\theta \mid \mathcal{T}^m) d\theta$$

• Lecture: "Bayesian Learning"

## **Generative vs. Discriminative Learning**



### Training data:

- if  $\mathcal{T}^m = \left\{ (x^i, y^i) \in \mathcal{X} \times \mathcal{Y} \mid i = 1, \dots, m \right\} \Rightarrow$  supervised learning
- if  $\mathcal{T}^m = \left\{ x^i \in \mathcal{X} \mid i = 1, \dots, m \right\} \Rightarrow$  unsupervised learning
- if  $\mathcal{T}^m = \mathcal{T}_l^{m_1} \bigcup \mathcal{T}_u^{m_2}$ , with labelled training data  $\mathcal{T}_l^{m_1}$  and unlabelled training data  $\mathcal{T}_u^{m_2}$  $\Rightarrow$  semi-supervised learning

#### Comparison of discriminative and generative learning

	discriminative approach	generative generative	
supervised data	yes	yes	
semi-supervised data	(yes)	yes	
unsupervised data	no	yes	
prediction uncertainty	no	yes	
theoretical guarantees	yes	(no)	