

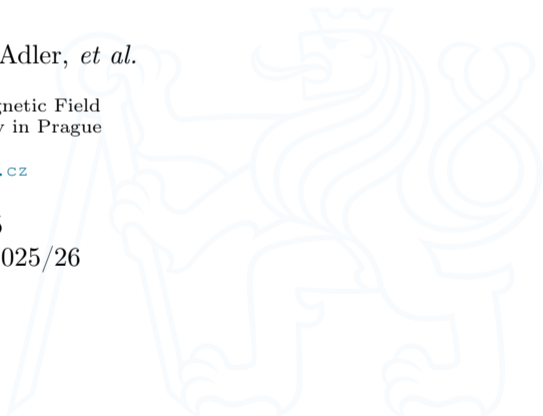
Lecture 2: Vectors & Matrices

B0B17MTB, BE0B17MTB – MATLAB

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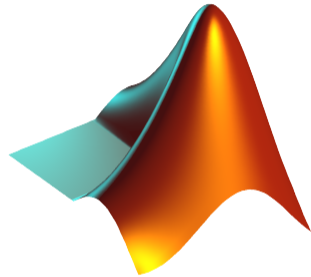
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1. MATLAB Editor
2. Matrix Creation
3. Operations with Matrices
4. Exercises



MATLAB Editor



- ▶ It is often required to evaluate certain sequence of commands repeatedly \Rightarrow utilization of MATLAB scripts (plain ASCII coding).
- ▶ The best option is to use MATLAB Editor,
 - ▶ which can be opened using the following command:

```
>> edit
```

- ▶ A script is a sequence of statements what we have been up to now typing in the command line.
 - ▶ All the statements are executed one by one upon the launch of the script.
 - ▶ The script operates over MATLAB base workspace data.
 - ▶ Scripts are suitable for quick analysis and solving problems involving multiple statements.
- ▶ There are specific naming conventions for scripts (and also for functions as we will see later).



The screenshot shows the MATLAB Editor window with a script named 'why.m'. The script contains a function that generates a random sentence based on a switch statement. The function is defined as follows:

```

1
2
3
4 % WHY(N) provides the N-th answer.
5 % Please embellish or modify this function to suit your own tastes.
6
7 % Copyright 1984-2014 The MathWorks, Inc.
8
9
10 if nargin > 0
11     dftit = rng(m,'Uniform');
12 end
13 switch randi(10)
14     case 1
15         a = special_case;
16     case {2, 3, 4}
17         a = phrase;
18     otherwise
19         a = sentence;
20 end
21 a{1} = upper(a{1});
22 disp(a);
23 if nargin > 0
24     rng(dftit);
25 end
26
27
28
29 function a = special_case
30 switch randi(10)
31     case 1
32         a = 'why not?';
33     case 2
34         a = 'don''t ask!';
35     case 3
36         a = 'it''s your karma.';
37     case 4
38         a = 'stupid question!';
39     case 5
40         a = 'how should I know?';
41     case 6
42         a = 'can you rephrase that?';
43     case 7
44         a = 'it should be obvious.';
45     case 8
46         a = 'the devil made me do it.';
47     case 9
48         a = 'the computer did it.';
49     case 10
50         a = 'the customer is always right.';

```



Script Execution, m-files

- ▶ To execute a script:
 - ▶ F5 function key in MATLAB Editor,
 - ▶ Current folder → select script → context menu → Run,
 - ▶ Current folder → select script → F9,
 - ▶ from the command line:

```
>> script_name
```

- ▶ Scripts are stored as so called m-files, .m
- ▶ **Caution:** If you have Mathematica installed, the .m files may be launched by Mathematica.



Data in Scripts

- ▶ Scripts can use data located in Workspace.
- ▶ Variables remain in the Workspace even after the calculation is finished.
- ▶ Operations on data in scripts are performed in the base Workspace.
- ▶ MATLAB carries out commands **sequentially**.

Useful Functions for Script Generation I.



- ▶ Function `disp` displays value of a variable in Command Window.
 - ▶ Without displaying variable's name and the equation sign "=".
 - ▶ Can be combined with a text (more on that later).
 - ▶ Often it is advantageous to use more complicated but robust function `fprintf`.

```
a = 2^13 - 1;  
b = [8*a 16*a];  
b
```

```
a = 2^13 - 1;  
b = [8*a 16*a];  
disp(b);
```



Useful Functions for Script Generation II.

- ▶ Function `input` is used to enter variables.
 - ▶ If the function is terminated unexpectedly, the input request is repeated

```
A = input('Enter parameter A: ');
```

- ▶ It is possible to enter strings as well:

```
str = input('Enter String str', 's');
```



Script Commenting

▶ MAKE COMMENTS!!

- ▶ Important/complicated parts of code.
- ▶ Description of functionality, ideas, change of implementation.

▶ Typical single-line comment:

```
% create matrix, sum all members  
matX = [1, 2, 3, 4, 5];  
sumX = sum(matX); % sum of matrix
```

▶ Multiple-line comment:

```
{  
This is a multiple-line comment.  
Mostly, it is more appropriate to use  
more single-line comments.  
}
```

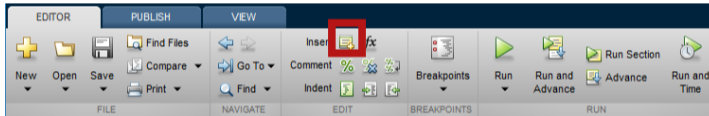
▶ Cell mode enables to separate script into more blocks.

```
matX = [1, 2, 3, 4, 5];  
%% CELL mode (must be enabled in Editor)  
sumX = sum(matX);
```



Cell Mode in MATLAB Editor

- ▶ Cells enable to separate the code into smaller, logically compacted parts.
 - ▶ Separator `%%`.
 - ▶ The separation is visual only, but it is possible to execute a single cell – shortcuts **CTRL+ENTER** and **CTRL+SHIFT+ENTER**.





Entering Matrices Using “:” I.

- ▶ Large vectors and matrices with regularly increasing elements can be typed in using colon operator.

- ▶ a is the smallest element (“from”), x is increment, b is the largest element (“to”)

```
A = a:x:b
```

```
>> A = 1:4:13
A =
    1    5    9   13
```

- ▶ b doesn't have to be an element of the series.
 - ▶ Last element $N \cdot x$ then follows the inequality:

$$|a + N \cdot x| \leq |b|$$

- ▶ If x is omitted, the increment is set equal to 1.

```
A = a:b
```

```
>> A = 1:4:10
A =
    1    5    9
```

```
>> A = 3:8
A =
    3    4    5    6    7    8
```



Entering Matrices Using “:” II.

- ▶ Using the colon operator “:” create:
 - ▶ Following vectors

$$\begin{aligned}\mathbf{u} &= [1 \ 3 \ \dots \ 99] \\ \mathbf{v} &= [25 \ 20 \ \dots \ -5]^T\end{aligned}$$

- ▶ Matrix

- ▶ Caution, the third column can't be created using colon operator “:” only,

$$\mathbf{T} = \begin{bmatrix} -4 & 1 & \frac{\pi}{2} \\ -5 & 2 & \frac{\pi}{4} \\ -6 & 3 & \frac{\pi}{6} \end{bmatrix}$$

but can be created using “:” and dot operator “.” (*we will see later*).





Entering Matrices Using “:” II.

- ▶ Using the colon operator “:” create:
 - ▶ Following vectors

$$\mathbf{u} = [1 \ 3 \ \dots \ 99]$$

$$\mathbf{v} = [25 \ 20 \ \dots \ -5]^T$$

```
u = 1:2:99
v = (25:-5:-5) .'
```

- ▶ Matrix

- ▶ Caution, the third column can't be created using colon operator “:” only,

$$\mathbf{T} = \begin{bmatrix} -4 & 1 & \frac{\pi}{2} \\ -5 & 2 & \frac{\pi}{4} \\ -6 & 3 & \frac{\pi}{6} \end{bmatrix}$$

```
T = [-4:-1:-6; 1:3; pi/2 pi/4 pi/6] .'
```

but can be created using “:” and dot operator “.” (*we will see later*).

```
T = [-4:-1:-6; 1:3; pi./(2:2:6)] .'
```

```
T = [(-4:-1:-6) .' (1:3) .' (pi./(2:2:6)) .'
```



Entering Matrices Using linspace, logspace I.

- ▶ Colon operator defines vector with **evenly spaced** points.
- ▶ In the case when **a vector with a fixed number of elements** is required, use linspace:

```
A = linspace(a, b, N);
```

```
>> A = linspace(0, 2, 5)
A =
    0    0.5000    1.0000    1.5000    2.0000
```

- ▶ When the N parameter is left out, the vector with 100 elements is generated:

```
A = linspace(a, b);
```

- ▶ The function logspace works analogically, except that logarithmic scale is used:

```
A = logspace(a, b, N);
```



Entering Matrices Using `linspace`, `logspace` II.

- ▶ Create a vector of 100 evenly spaced points in the interval $[-1.15, 75.4]$.
- ▶ Create a vector of 201 evenly spaced points in the interval $[-100, 100]$ sorted in descending order.
- ▶ Create a vector with spacing of -10 in the interval $[100, -100]$ sorted in descending order.
 - ▶ Try both options using `linspace` and colon `“:”`.



Entering Matrices Using `linspace`, `logspace` II.

- ▶ Create a vector of 100 evenly spaced points in the interval $[-1.15, 75.4]$.

```
u = linspace(-1.15, 75.4)
```

- ▶ Create a vector of 201 evenly spaced points in the interval $[-100, 100]$ sorted in descending order.

```
v = linspace(100, -100, 201)
```

- ▶ Create a vector with spacing of -10 in the interval $[100, -100]$ sorted in descending order.

- ▶ Try both options using `linspace` and colon `“:”`.

```
v = 100:-10:-100
```

```
v = linspace(100, -100, 200/10+1)
```



Entering Matrices Using Functions I.

- ▶ Special types of matrices of given sizes are needed quite often.
 - ▶ MATLAB offers a number of functions to serve the purpose.
- ▶ Example: matrix filled with zeros
 - ▶ Will be used frequently.

```
zeros(m)           % matrix of size [m x m]
zeros(m, n)        % matrix of size [m x n]
zeros(m, n, p, ..) % matrix of size [m x n x p x ..]
zeros([m,n])       % matrix of size [m x n]

B = zeros(m, 'single') % matrix of size [m x n], of type 'single'

% see documentation for other options
```



Entering Matrices Using Functions II.

- ▶ Following useful functions analogical to the `zeros` function are available

| | |
|---------------------------------|---|
| <code>ones</code> | matrix filled with ones |
| <code>eye</code> | identity matrix |
| <code>nan, inf</code> | matrix filled with NaN, matrix filled with Inf |
| <code>magic</code> | matrix suitable for MATLAB experiments, notice its properties |
| <code>rand, randn, randi</code> | matrix filled with random numbers coming from uniform and normal distribution, matrix filled with uniformly distributed random integers |
| <code>randperm</code> | returns vector containing random permutation of numbers |
| <code>diag</code> | creates diagonal matrix or returns diagonal of a matrix |
| <code>blkdiag</code> | construct block diagonal matrix from input arguments |
| <code>cat</code> | groups several matrices into one |
| <code>true, false</code> | creates a matrix of logical ones and zeros |

- ▶ For further functions see MATLAB → Mathematics → Elementary Mathematics → Constants and Test Matrices.



Entering Matrices Using Functions III.

- ▶ Create following matrices
 - ▶ use MATLAB functions
 - ▶ begin with matrices you find easy to cope with.

$$\mathbf{M}_1 = \begin{bmatrix} \text{NaN} & \text{NaN} \\ \text{NaN} & \text{NaN} \end{bmatrix}$$

$$\mathbf{M}_2 = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\mathbf{M}_3 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -5 \end{bmatrix}$$

$$\mathbf{M}_4 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$





Entering Matrices Using Functions III.

- ▶ Create following matrices
 - ▶ use MATLAB functions
 - ▶ begin with matrices you find easy to cope with.

$$\mathbf{M}_1 = \begin{bmatrix} \text{NaN} & \text{NaN} \\ \text{NaN} & \text{NaN} \end{bmatrix}$$

$$\mathbf{M}_2 = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\mathbf{M}_3 = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -5 \end{bmatrix}$$

$$\mathbf{M}_4 = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

```
M1 = nan(2)
```

```
M2 = ones(1, 4)
```

```
M3 = diag([2 3 -5])
```

```
M4 = diag([1 1 1], 1)
```

```
M4 = [zeros(4, 1) [eye(3); zeros(1, 3)]]
```

```
M4 = diag(ones(3, 1), 1)
```



Entering Matrices Using Functions IV.

- ▶ Try to create an empty three-dimensional array of type double.

```
A1 = zeros(0, 0, 0) % or ones(...) etc.
```

- ▶ Can you find another option?

```
A2 = double.empty(0, 0, 0)
```

- ▶ empty is hidden (but public) method of all non-abstract classes in MATLAB.



Dealing with Sparse Matrices

- ▶ MATLAB provides support for working with sparse matrices.
 - ▶ Most of the elements of sparse matrices are zeros and it pays off to store them in a more efficient manner.

- ▶ To create a sparse matrix S out of matrix A :

```
S = sparse(A)
```

- ▶ Conversion of a sparse matrix to a full matrix:

```
B = full(S)
```

- ▶ In the case of need see Help for other functions.



Entering Matrices

- ▶ Quite often, there are several options how to create a given matrix.
 - ▶ It is possible to use an **output of one function as an input of another** function in MATLAB:

- ▶ Consider:

- ▶ clarity,
- ▶ simplicity,
- ▶ speed,
- ▶ convention.

```
plot(diag(randn(10, 1), 1))
```

- ▶ E.g. band matrix with “1” on main diagonal and with “2” and “3” on secondary diagonals.

```
N = 10;
diag(ones(N, 1)) + diag(2 * ones(N - 1, 1), 1) + diag(3 * ones(N - 1, 1), -1)
```

- ▶ Can be done using `for` cycle as well (see later in the semester).
- ▶ Some other idea?



Transpose and Matrix Conjugate

- ▶ Pay attention to situations where the matrix is complex, $\mathbf{A} \in \mathbb{C}^{M \times N}$.
- ▶ There are two operations:

| | | | |
|-----------------------|--|---------------------------|-----|
| transpose | $\mathbf{A}^T = [A_{ij}]^T = [A_{ji}]$ | transpose(A) ← don't use | A.' |
| transpose + conjugate | $\mathbf{A}^H = [A_{ij}]^H = [\mathbf{A}^*]^T$ | ctranspose(A) ← don't use | A' |

```
>> A = magic(2) + 1j * magic(2) '
A =
 1.0000 + 1.0000i   3.0000 + 4.0000i
 4.0000 + 3.0000i   2.0000 + 2.0000i
```

```
>> A.'
ans =
 1.0000 + 1.0000i   4.0000 + 3.0000i
 3.0000 + 4.0000i   2.0000 + 2.0000i
```

```
>> A'
ans =
 1.0000 - 1.0000i   4.0000 - 3.0000i
 3.0000 - 4.0000i   2.0000 - 2.0000i
```



Matrix Operations I.

- ▶ There are other useful functions apart from transpose (`transpose`) and matrix diagonal (`diag`):

```
P = magic(4)
```

- ▶ upper triangular matrix,

```
U = triu(P)
```

- ▶ lower triangular matrix,

```
L = tril(P)
```

- ▶ a matrix can be modified taking into account secondary diagonals as well

```
V = triu(P, -1)
```

$$\mathbf{P} = \begin{bmatrix} 16 & 2 & 3 & 13 \\ 5 & 11 & 10 & 8 \\ 9 & 7 & 6 & 12 \\ 4 & 14 & 15 & 1 \end{bmatrix}$$

$$\mathbf{U} = \begin{bmatrix} 16 & 2 & 3 & 13 \\ 0 & 11 & 10 & 8 \\ 0 & 0 & 6 & 12 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\mathbf{L} = \begin{bmatrix} 16 & 0 & 0 & 0 \\ 5 & 11 & 0 & 0 \\ 9 & 7 & 6 & 0 \\ 4 & 14 & 15 & 1 \end{bmatrix}$$

$$\mathbf{V} = \begin{bmatrix} 16 & 2 & 3 & 13 \\ 5 & 11 & 10 & 8 \\ 0 & 7 & 6 & 12 \\ 0 & 0 & 15 & 1 \end{bmatrix}$$



Matrix Operations II.

- ▶ Function `repmat` is used to copy (part of) a matrix.

```
B = repmat(A, m, n)
```

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} & A_{13} \end{bmatrix}$$

```
B = repmat(A, 1, 2)
C = repmat(A, [2, 1])
```

$$\mathbf{B} = \begin{bmatrix} \boxed{A_{11} \quad A_{12} \quad A_{13}} & \boxed{A_{11} \quad A_{12} \quad A_{13}} \end{bmatrix}$$

$$\mathbf{C} = \begin{bmatrix} \boxed{A_{11} \quad A_{12} \quad A_{13}} \\ \boxed{A_{11} \quad A_{12} \quad A_{13}} \end{bmatrix}$$

- ▶ `repmat` is a very fast function.
 - ▶ Comparison of execution time of creation a $10^4 \times 10^4$ matrix filled with pi (HW, SW and MATLAB version dependent):

```
X = ones(1e4) % computed in 0.71s
Y = repmat(1, 1e4, 1e4) % computed in 0.4s, BUT... don't use it
```

- ▶ It is for you to consider the way of matrix creation...



Matrix Operations III.

- ▶ Function `reshape` is used to rearrange a matrix

```
B = reshape(A, m, n)
```

- ▶ e.g.

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}$$

```
C = reshape(A, [4, 1])
D = reshape(A, 1, 4)
D = reshape(A, [], 4)
```

$$\mathbf{C} = \begin{bmatrix} A_{11} \\ A_{21} \\ A_{12} \\ A_{22} \end{bmatrix}$$

$$\mathbf{D} = [A_{11} \quad A_{21} \quad A_{12} \quad A_{22}]$$



Matrix Operations IV.

- ▶ Following functions are used to swap the order of

- ▶ columns: `fliplr`,

$$B = \text{fliplr}(A)$$

- ▶ rows: `flipud`,

$$C = \text{flipud}(A)$$

- ▶ row-wise or column-wise: `flip`.

$$\begin{aligned} B &= \text{flip}(A, 1) \\ C &= \text{flip}(A, 2) \end{aligned}$$

- ▶ Indexing gives the same results (*see later*).

- ▶ The following function is used to rotate an array

$$\begin{aligned} D &= \text{rot90}(A) \\ E &= \text{rot90}(A, 2) = \text{fliplr}(\text{flipud}(A)) \end{aligned}$$

$$A = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \end{bmatrix}$$

$$B = \begin{bmatrix} A_{13} & A_{12} & A_{11} \\ A_{23} & A_{22} & A_{21} \end{bmatrix}$$

$$C = \begin{bmatrix} A_{21} & A_{22} & A_{23} \\ A_{11} & A_{12} & A_{13} \end{bmatrix}$$

$$\begin{bmatrix} A_{11} & \cdots & A_{1n} \\ \vdots & \ddots & \vdots \\ A_{m1} & \cdots & A_{mn} \end{bmatrix}$$

$\frac{\pi}{2}k$



Matrix Operations V.

- ▶ Circular shift is also available.
 - ▶ Can be carried out along an arbitrary dimension (row-wise/column-wise).
 - ▶ Can be carried out in both directions (back/forth).
- ▶ Consider the difference between `flip` and `circshift`.

```
B = circshift(A, -2)
C = circshift(A, [-2 1])
```

$$\mathbf{B} = \begin{bmatrix} A_{31} & A_{32} & A_{33} \\ A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \end{bmatrix}$$

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \\ A_{31} & A_{32} & A_{33} \end{bmatrix}$$

$$\mathbf{C} = \begin{bmatrix} A_{33} & A_{31} & A_{32} \\ A_{13} & A_{11} & A_{12} \\ A_{23} & A_{21} & A_{22} \end{bmatrix}$$



Matrix Operations VI.

- Convert matrix \mathbf{A} into the form of matrices \mathbf{A}_1 to \mathbf{A}_4 .

$$\mathbf{A} = [1 \text{ pi}; \exp(1) \text{ -1i}]$$

$$\mathbf{A} = \begin{bmatrix} 1 & \pi \\ e & -i \end{bmatrix}$$

- Use `repmat`, `reshape`, `triu`, `tril` and `conj`.

$$\mathbf{A}_1 = \begin{bmatrix} 1 & \pi & 1 & \pi & 1 & \pi \\ e & -i & e & -i & e & -i \end{bmatrix}$$

$$\mathbf{A}_2 = [1 \quad \pi \quad e \quad -i]$$

$$\mathbf{A}_3 = \begin{bmatrix} 1 & \pi \\ e & +i \\ 1 & \pi \\ e & +i \\ 1 & \pi \\ e & +i \end{bmatrix}$$

$$\mathbf{A}_4 = \begin{bmatrix} 1 & \pi & 0 & 0 & 0 & 0 \\ e & -i & e & 0 & 0 & 0 \\ 0 & \pi & 1 & \pi & 0 & 0 \\ 0 & 0 & e & -i & e & 0 \\ 0 & 0 & 0 & \pi & 1 & \pi \\ 0 & 0 & 0 & 0 & e & -i \end{bmatrix}$$



Matrix Operations VI.

- Convert matrix \mathbf{A} into the form of matrices \mathbf{A}_1 to \mathbf{A}_4 .

$$\mathbf{A} = [1 \ \pi; \exp(1) \ -1i]$$

$$\mathbf{A} = \begin{bmatrix} 1 & \pi \\ e & -i \end{bmatrix}$$

- Use `repmat`, `reshape`, `triu`, `tril` and `conj`.

$$\mathbf{A}_1 = \begin{bmatrix} 1 & \pi & 1 & \pi & 1 & \pi \\ e & -i & e & -i & e & -i \end{bmatrix}$$

$$\mathbf{A}_2 = [1 \ \pi \ e \ -i]$$

$$\mathbf{A}_3 = \begin{bmatrix} 1 & \pi \\ e & +i \\ 1 & \pi \\ e & +i \\ 1 & \pi \\ e & +i \end{bmatrix}$$

$$\mathbf{A}_4 = \begin{bmatrix} 1 & \pi & 0 & 0 & 0 & 0 \\ e & -i & e & 0 & 0 & 0 \\ 0 & \pi & 1 & \pi & 0 & 0 \\ 0 & 0 & e & -i & e & 0 \\ 0 & 0 & 0 & \pi & 1 & \pi \\ 0 & 0 & 0 & 0 & e & -i \end{bmatrix}$$

$$\mathbf{A}_1 = \text{repmat}(\mathbf{A}, [1 \ 3])$$

$$\mathbf{A}_3 = \text{repmat}(\text{conj}(\mathbf{A}), [3 \ 1])$$

$$\mathbf{A}_2 = \text{reshape}(\mathbf{A}.', [1 \ 4])$$

$$\mathbf{A}_4 = \text{triu}(\text{tril}(\text{repmat}(\mathbf{A}, 3), 1), -1)$$

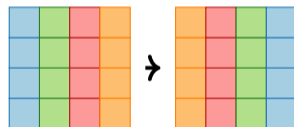


Matrix Operations VII.

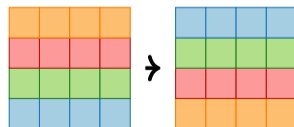
- ▶ Create the following matrix (use advanced techniques)

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 1 & 2 & 3 \\ 0 & 2 & 4 & 0 & 2 & 4 \\ 0 & 0 & 5 & 0 & 0 & 5 \end{bmatrix}$$

- ▶ Create matrix **B** by swapping columns in matrix **A**.



- ▶ Create matrix **C** by swapping rows in matrix **B**.





Matrix Operations VII.

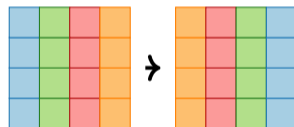
- ▶ Create the following matrix (use advanced techniques)

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 1 & 2 & 3 \\ 0 & 2 & 4 & 0 & 2 & 4 \\ 0 & 0 & 5 & 0 & 0 & 5 \end{bmatrix}$$

```
A = [1:3; 0:2:4; 0 0 5];
A = repmat(A, [1 2])
```

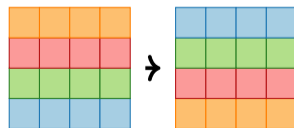
- ▶ Create matrix **B** by swapping columns in matrix **A**.

```
B = fliplr(A)
```



- ▶ Create matrix **C** by swapping rows in matrix **B**.

```
C = flipud(B)
```





Matrix Operations VIII. – Tensor Products

Kronecker tensor product

$$K = \text{kron}(A, B)$$

- Convolution kernel A is applied to a mask B.

Example:

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \otimes \frac{1}{2} \begin{bmatrix} 1 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 \end{bmatrix}$$

$$\text{kron}([0 \ 1; 1 \ 0], [1/2, -1/2])$$

Tensor product

$$C = \text{tensorprod}(A, B, \text{dimA}, \text{dimB})$$

- Inner product

$$\sum_n \cdots \sum_k \sum_j A_{jk \cdots n} B_{jk \cdots n} = c$$

- Outer product

$$[A_{jk \cdots n}][B_{pq \cdots t}] = [C_{jk \cdots npq \cdots t}]$$

- Tensor product

$$\sum_j \cdots \sum_p \sum_j A_{jk \cdots n} B_{pq \cdots t} = [C_{k \cdots npq \cdots t}]$$



Matrix Operations IX.

- ▶ Compare and interpret following commands.

```
x = (1:5) .'           % entering vector
x = repmat(x, [1 10]); % 1. option
X = x(:, ones(10, 1)); % 2. option
```

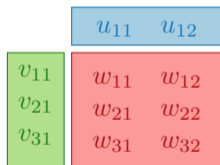
- ▶ repmat is powerful, but whenever possible, replace it with implicit expansion.



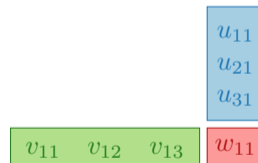
Vector and Matrix Operations

- ▶ Remember that matrix multiplication is not commutative, i.e. $\mathbf{AB} \neq \mathbf{BA}$.
- ▶ Remember that vector-vector multiplication results in

$$\mathbf{v}_{M,1} \mathbf{u}_{1,N} = \mathbf{w}_{M,N}$$



$$\mathbf{v}_{1,M} \mathbf{u}_{M,1} = \mathbf{w}_{1,1}$$



...pay attention to the dimensions of matrices!



Element-by-element Vector Product

- ▶ It is possible to multiply arrays of the same size in the element-by-element manner in MATLAB.
 - ▶ Result of the operation is an array.
 - ▶ Size of all arrays are the same, *e.g.*, in the case of 1×3 vectors:

$$\mathbf{a} = [a_1 \quad a_2 \quad a_3] \quad \mathbf{b} = [b_1 \quad b_2 \quad b_3]$$

```
>> a*b
```

 $[a_1 \quad a_2 \quad a_3]$
 $[b_1 \quad b_2 \quad b_3]$
 \rightarrow

Error using *
(Inner matrix dimensions must agree.)

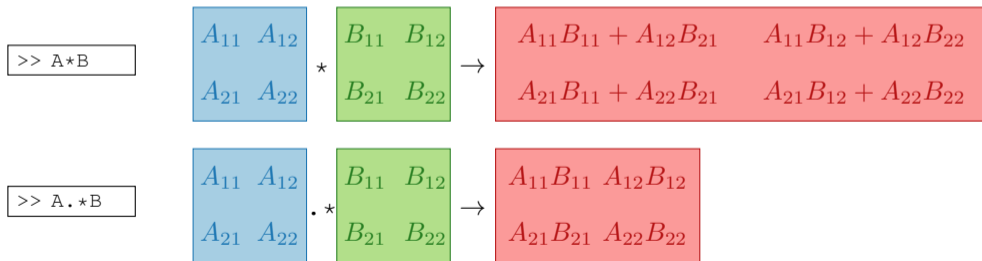
```
>> a.*b
```

 $[a_1 \quad a_2 \quad a_3]$
 $[b_1 \quad b_2 \quad b_3]$
 \rightarrow
 $[a_1b_1 \quad a_2b_2 \quad a_3b_3] = [a_i b_i]$



Element-by-element Matrix Product

- ▶ If element-by-element multiplication of two matrices of the same size is needed, use the `.*` operator.
 - ▶ It is so called *Hadamard product*/*element-wise product*/*Schur product*: $\mathbf{A} \circ \mathbf{B}$.
 - ▶ These two cases of multiplication are distinguished:





Compatible Array Size

- ▶ Since MATLAB version R2016b most two-input (binary) operators support arrays that have *compatible sizes*.
 - ▶ Variables have compatible sizes if their sizes are either the same or one of them is 1 (for all dimensions).
- ▶ Examples:
 - ▶ \circ represents arbitrary two-input element-wise operator (+, -, .*, ./, &, <, ==, ...).

$$\begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array} \circ \begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array} = \begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array}$$

$$\begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array} \circ \begin{array}{c} [2 \times 1] \\ \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \end{array} \end{array} = \begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array}$$

$$\begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array} \circ \begin{array}{c} [1 \times 1] \\ \square \end{array} = \begin{array}{c} [2 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array}$$

$$\begin{array}{c} [3 \times 1] \\ \begin{array}{|c|} \hline \square \\ \hline \square \\ \hline \square \\ \hline \end{array} \end{array} \circ \begin{array}{c} [1 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \end{array} \end{array} = \begin{array}{c} [3 \times 2] \\ \begin{array}{|c|c|} \hline \square & \square \\ \hline \square & \square \\ \hline \square & \square \\ \hline \end{array} \end{array}$$

$$\begin{array}{c} [4 \times 3 \times 1] \\ \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \end{array} \end{array} \circ \begin{array}{c} [1 \times 3 \times 3] \\ \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \end{array} \end{array} = \begin{array}{c} [4 \times 3 \times 3] \\ \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \end{array} \end{array}$$

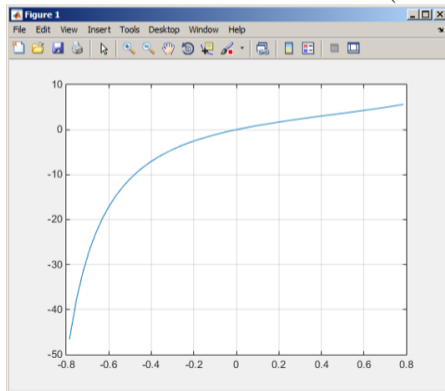


Element-wise Operations I.

- ▶ Elements-wise operations can be applied to vectors as well in MATLAB. Element-wise operations can be usefully combined with vector functions.
- ▶ It is possible, quite often, to eliminate 1 or even 2 for-loops!!!
- ▶ These operations are exceptionally efficient → allow use of so called **vectorization** (see later).

$$f(x) = \frac{10}{(x+1)} \tan(x), \quad x \in \left[-\frac{\pi}{4}, \frac{\pi}{4}\right]$$

```
x = -pi/4:pi/100:pi/4;
fx = 10 ./ (1 + x) .* tan(x);
plot(x, fx)
grid on
```





Element-wise Operations II.

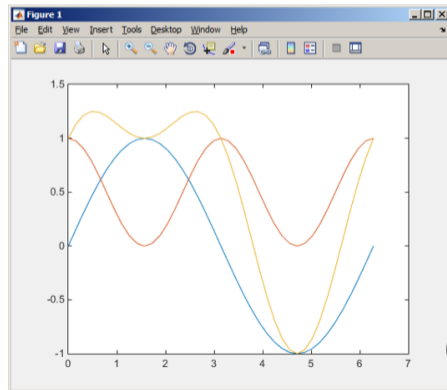
- ▶ Evaluate functions of the variable $x \in [0, 2\pi]$:
- ▶ Evaluate the functions in evenly spaced points of the interval, the spacing is $\Delta x = \pi/20$.
- ▶ For verification use:


```
plot(x, f1, x, f2, x, f3)
```

$$f_1(x) = \sin(x)$$

$$f_2(x) = \cos^2(x)$$

$$f_3(x) = f_1(x) + f_2(x)$$





Element-wise Operations II.

- ▶ Evaluate functions of the variable $x \in [0, 2\pi]$:
- ▶ Evaluate the functions in evenly spaced points of the interval, the spacing is $\Delta x = \pi/20$.

```
x = 0:pi/20:2*pi;
f1 = sin(x);
f2 = cos(x).^2;
f3 = f1 + f2;
```

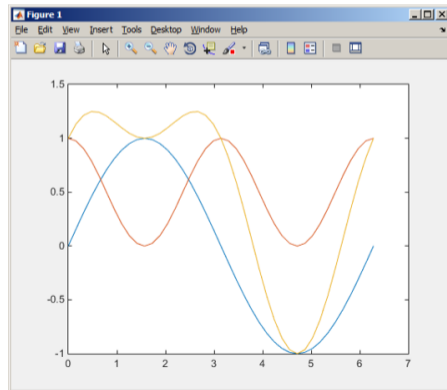
- ▶ For verification use:

```
plot(x, f1, x, f2, x, f3)
```

$$f_1(x) = \sin(x)$$

$$f_2(x) = \cos^2(x)$$

$$f_3(x) = f_1(x) + f_2(x)$$





Element-wise Operations III.

- ▶ Depict graphically following functional dependency in the interval $x \in [0, 5\pi]$.
- ▶ Plot the result using the following function:

$$f_4(x) = \frac{-\cos(3x)}{\cos(x) \sin\left(x - \frac{\pi}{5}\right) - \pi}$$

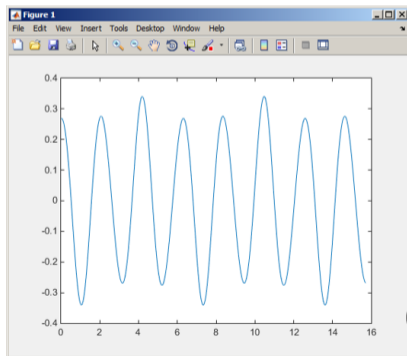
```
plot(x, f4)
```

- ▶ Explain the difference in the way of multiplication of matrices of the same size.

```
>> A*B
```

```
>> A.*B
```

```
>> A' .*B
```





Element-wise Operations III.

- ▶ Depict graphically following functional dependency in the interval $x \in [0, 5\pi]$.
- ▶ Plot the result using the following function:

```
clear; clc;
x = linspace(0, 5*pi, 1e5);
f4 = (-cos(3*x)) ./ ...
(cos(x) .* sin(x - pi / 5) - pi);
plot(x, f4)
```

- ▶ Explain the difference in the way of multiplication of matrices of the same size.

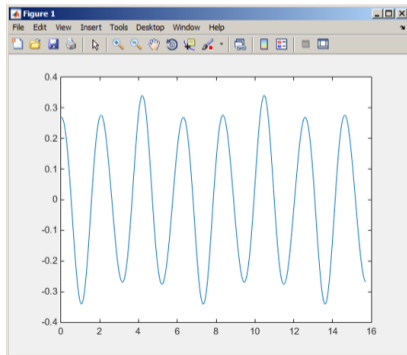
```
>> A*B
```

```
>> A.*B
```

```
>> A' .* B
```

$$f_4(x) = \frac{-\cos(3x)}{\cos(x) \sin\left(x - \frac{\pi}{5}\right) - \pi}$$

```
plot(x, f4)
```

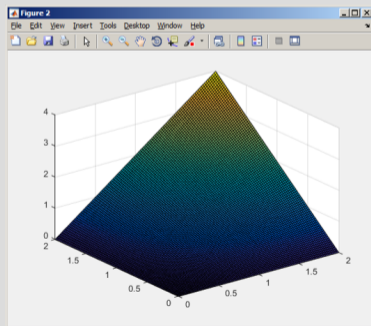




Element-wise Operation IV.

- ▶ Evaluate the function $f(x, y) = xy$, $x, y \in [0, 2]$, use 101 evenly spaced points in both x and y .
- ▶ The evaluation can be carried out either using vectors, matrix element-wise vectorization or using two for loops.
 - ▶ Plot the result using `surf(x, y, f)`.
 - ▶ When ready, also try $f(x, y) = x^{0.5}y^2$ on the same interval.

```
x = linspace(0, 2, 101);
y = x.';
f = x.*y;
figure;
surf(x, y, f)
```

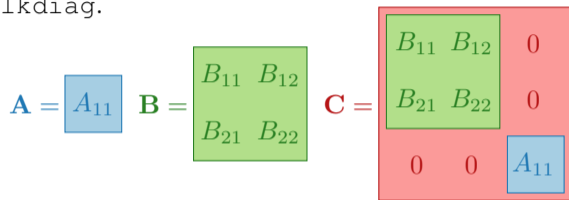




Matrix Operations

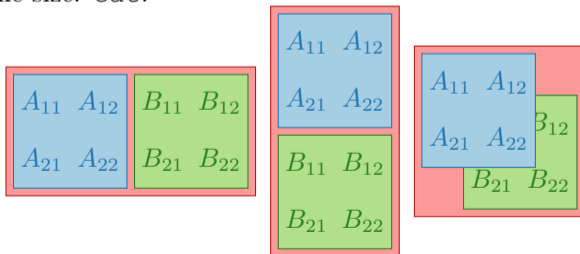
- ▶ Construct block diagonal matrix: blkdiag.

```
A = 1;
B = [2 3; -4 -5];
C = blkdiag(B, A);
```



- ▶ Arranging two matrices of the same size: cat.

```
A = eye(2); B =
ones(2);
C = cat(2, A, B)
C = cat(1, A, B)
C = cat(3, A, B)
```





Size of Matrices and Other Structures I.

- ▶ It is often needed to know sizes of matrices and arrays.
- ▶ Function `size` returns vector giving the size of a matrix/array.

```
A = randn(3, 5);
d = size(A) % d = [3 5]
```

- ▶ Function `length` returns largest dimension of an array.

```
length(A) = max(size(A))
```

```
A = randn(3, 5, 8);
e = length(A) % e = 8
```

- ▶ Function `ndims` returns number of dimensions of a matrix/array.

```
ndims(A) = length(size(A))
```

```
m = ndims(A) % m = 3
```

- ▶ Function `numel` returns number of elements of a matrix/array.

```
numel(A) = prod(size(A))
```

```
n = numel(A) % n = 120
```

- ▶ Functions `height` and `width` return number of rows and columns, respectively.



Size of Matrices and Other Structures II.

- ▶ Create an arbitrary 3D array.
 - ▶ You can make use of the following commands:

```
A = rand(2 + randi(10), 3 + randi(5));  
A = cat(3, A, rot90(A, 2))
```

- ▶ And now:
 - ▶ Find out the size of A.
 - ▶ Find the number of elements of A.
 - ▶ Find out the number of elements of A in the “longest” dimension.
 - ▶ Find out the number of dimensions of A.



Size of Matrices and Other Structures II.

- ▶ Create an arbitrary 3D array.
 - ▶ You can make use of the following commands:

```
A = rand(2 + randi(10), 3 + randi(5));  
A = cat(3, A, rot90(A, 2))
```

- ▶ And now:

- ▶ Find out the size of A.

```
size(A)
```

- ▶ Find the number of elements of A.

```
numel(A)
```

- ▶ Find out the number of elements of A in the “longest” dimension.

```
length(A)
```

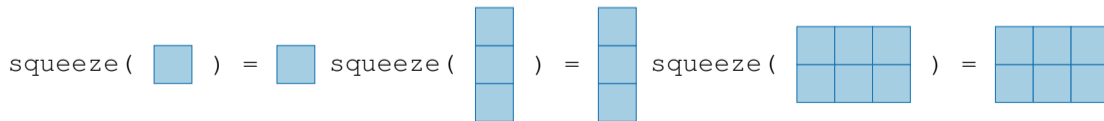
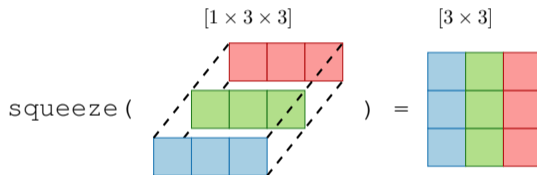
- ▶ Find out the number of dimensions of A.

```
ndims(A)
```



Squeeze

- ▶ Function `squeeze` removes dimension of an array with length 1.
 - ▶ If the input is scalar, vector or array without any dimension of the length 1, the output is identical to the input.





Function gallery

- ▶ Function enabling to create a vast set of matrices that can be used for MATLAB code testing.
- ▶ Most of the matrices are special-purpose.
 - ▶ Function gallery offers significant coding time reduction for advanced MATLAB users.
- ▶ See: doc [gallery](#)
- ▶ Try for instance:

```
gallery('pei', 5, 4)  
gallery('leslie', 10)  
gallery('clement', 8)
```

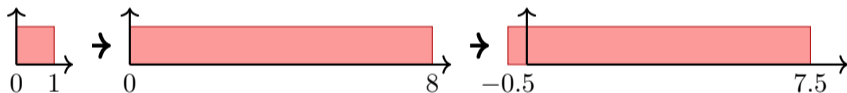
Exercises



Exercise I.

- ▶ Create matrix \mathbf{M} of size `size(M) = [3 4 2]` containing random numbers coming from uniform distribution on the interval $[-0.5, 7.5]$.

$$I(x) = (I_{\max} - I_{\min}) \text{rand}(\dots) + I_{\min}$$





Exercise I.

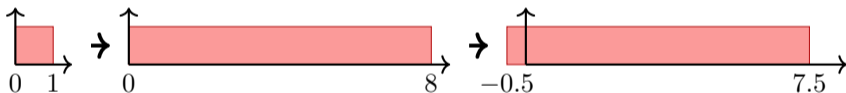
- ▶ Create matrix \mathbf{M} of size `size(M) = [3 4 2]` containing random numbers coming from uniform distribution on the interval $[-0.5, 7.5]$.

$$I(x) = (I_{\max} - I_{\min}) \text{rand}(\dots) + I_{\min}$$

```
rand( )
```

```
8*rand( )
```

```
8*rand( ) - 0.5
```



```
M = 8*rand(3, 4, 2) - 0.5
```



Exercise II.

- Consider the operation $a1^a2$. Is this operation applicable to the following cases?

| | |
|-------------------|---------------|
| $a1$ – matrix | $a2$ – scalar |
| $a1$ – matrix | $a2$ – matrix |
| $a1$ – matrix | $a2$ – vector |
| $a1$ – scalar | $a2$ – scalar |
| $a1$ – scalar | $a2$ – matrix |
| $a1, a2$ – matrix | $a1.^a2$ |

You can always create the matrices $a1$, $a2$ and make a test ...



Exercise II.

- Consider the operation $a1^a2$. Is this operation applicable to the following cases?

| | | |
|-----------------|-------------|-----|
| a1 – matrix | a2 – scalar | YES |
| a1 – matrix | a2 – matrix | NO |
| a1 – matrix | a2 – vector | NO |
| a1 – scalar | a2 – scalar | YES |
| a1 – scalar | a2 – matrix | YES |
| a1, a2 – matrix | $a1.^a2$ | YES |

You can always create the matrices $a1$, $a2$ and make a test ...



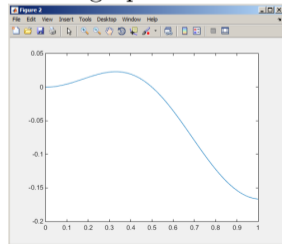
Exercise III.

- Make corrections to the following piece of code to get values of the function $f(x)$ for 200 points on the interval $[0, 1]$:

```
% erroneous code
x = linspace(0, 1);
clear;
g = x^3+1; H = x+2;
y = cos xpi; z = x.^2;
f = y*z/gh
```

$$f(x) = \frac{x^2 \cos(\pi x)}{(x^3 + 1)(x + 2)}$$

- Find out the value of the function for $x = 1$ by direct accessing the vector.
- What is the value of the function for $x = 2$?
- To check, plot the graph of the function $f(x)$.





Exercise III.

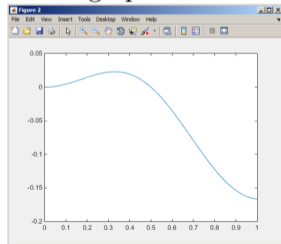
- ▶ Make corrections to the following piece of code to get values of the function $f(x)$ for 200 points on the interval $[0, 1]$:

```
% erroneous code
x = linspace(0, 1);
clear;
g = x^3+1; H = x+2;
y = cos xpi; z = x.^2;
f = y*z/gh
```

```
% correct code
clear;
x = linspace(0, 1, 200);
g = x.^3+1; h = x+2;
y = cos(x*pi); z = x.^2;
f = y.*z./(g.*h)
plot(x, f);
```

$$f(x) = \frac{x^2 \cos(\pi x)}{(x^3 + 1)(x + 2)}$$

- ▶ Find out the value of the function for $x = 1$ by direct accessing the vector.
- ▶ What is the value of the function for $x = 2$?
- ▶ To check, plot the graph of the function $f(x)$.





Exercise IV.

- ▶ Create a random matrix \mathbf{M} of size $N \times N$ containing only 0 and 1 elements.
- ▶ Compute the percentage of 0 elements in matrix.
- ▶ Compute number of 1 elements on the matrix main diagonal.



Exercise IV.

- ▶ Create a random matrix \mathbf{M} of size $N \times N$ containing only 0 and 1 elements.

```
M = randi([0 1], 5, 5);
```

- ▶ Compute the percentage of 0 elements in matrix.

```
percentage = 100 - 100 * sum(sum(M)) / numel(M);
```

- ▶ Compute number of 1 elements on the matrix main diagonal.

```
mainDiagonal = diag(M);  
n = sum(mainDiagonal);
```



Exercise V.a

- ▶ A proton, carrying a charge of $Q = 1.602 \cdot 10^{-19}$ C with a mass of $m = 1.673 \cdot 10^{-31}$ kg enters a homogeneous magnetic and electric field in the direction of the z axis in the way that the proton follows a helical path; the initial velocity of the proton is $v_0 = 1 \cdot 10^7$ ms⁻¹. The intensity of the magnetic field is $B = 0.1$ T, the intensity of the electric field is $E = 1 \cdot 10^5$ Vm⁻¹
- ▶ Velocity of the proton among the z axis is $v = \frac{QE}{m}t + v_0$,
 - ▶ where t is time, traveled distance along the z axis is $z = \frac{1}{2} \frac{QE}{m}t^2 + v_0t$,
 - ▶ radius of the helix is $r = \frac{vm}{BQ}$,
 - ▶ frequency of orbiting the helix is $f = \frac{v}{2\pi r}$,
 - ▶ the x and y coordinates of the proton are $x = r \cos(2\pi ft)$, $y = r \sin(2\pi ft)$.

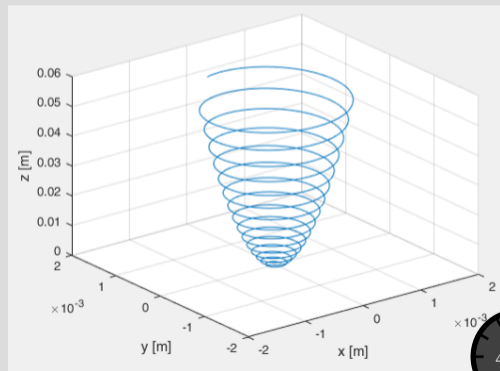


Exercise V.b

- Plot the path of the proton in space in the time interval from 0 ns to 1 ns in 1001 points using function `comet3(x, y, z)`.

```
clear; clc; close all;
```

```
comet3(x, y, z);
```





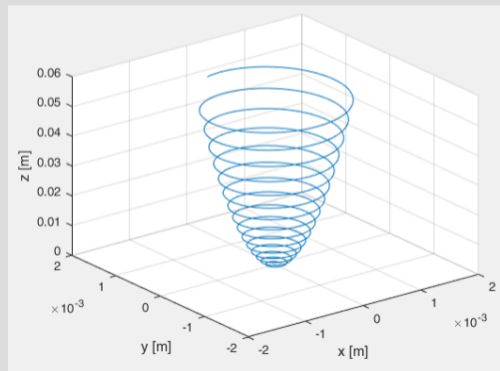
Exercise V.b

- Plot the path of the proton in space in the time interval from 0 ns to 1 ns in 1001 points using function `comet3(x, y, z)`.

```
clear; clc; close all;

m = 1.673e-31; Q = 1.609e-19;
v0 = 1e7; E = 1e5; B = 0.1;
t = linspace(0, 1e-9, 1001);
v = Q * E * t / m + v0;
z = 0.5 * Q * E / m * t .^ 2 + v0 * t;
r = v * m / (B * Q);
f = v / (2 * pi * r);
x = r .* sin(2 * pi * f * t);
y = r .* cos(2 * pi * f * t);

comet3(x, y, z);
```



Questions?

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Summer semester 2025/26

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