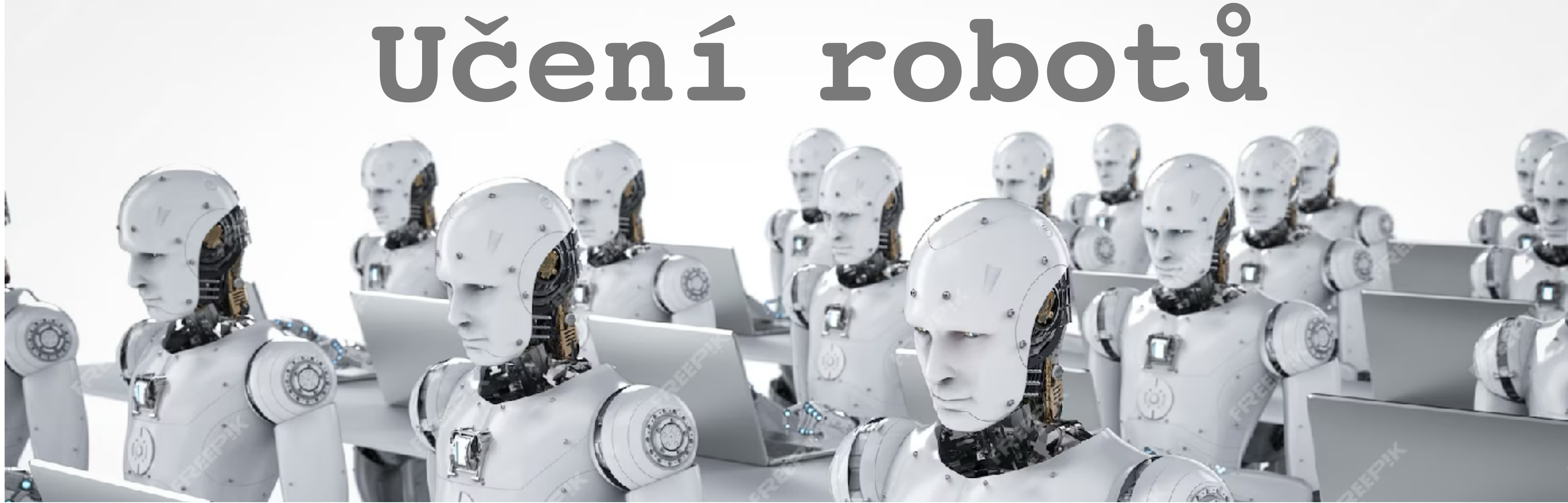


Učení robotů



Learning 101

Engineering view on learning, issues, regression, classification.

Pre-requisites:

- just an elementary linear algebra

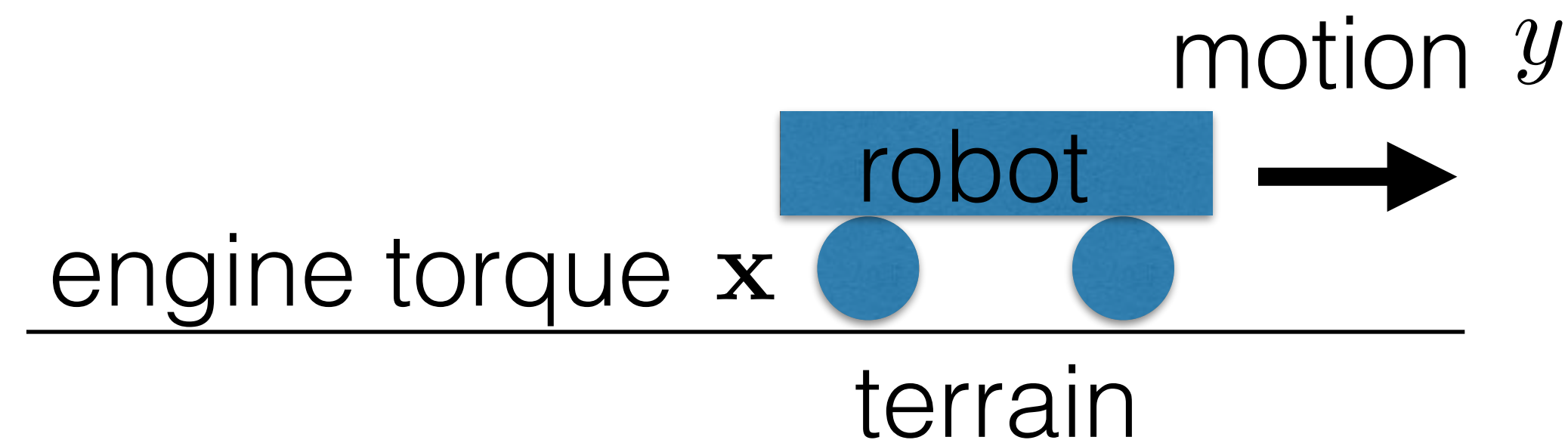
Karel Zimmermann

Czech Technical University in Prague

Faculty of Electrical Engineering, Department of Cybernetics

Motivation example: estimation of a motion model

- Which method will you use to build a motion model?

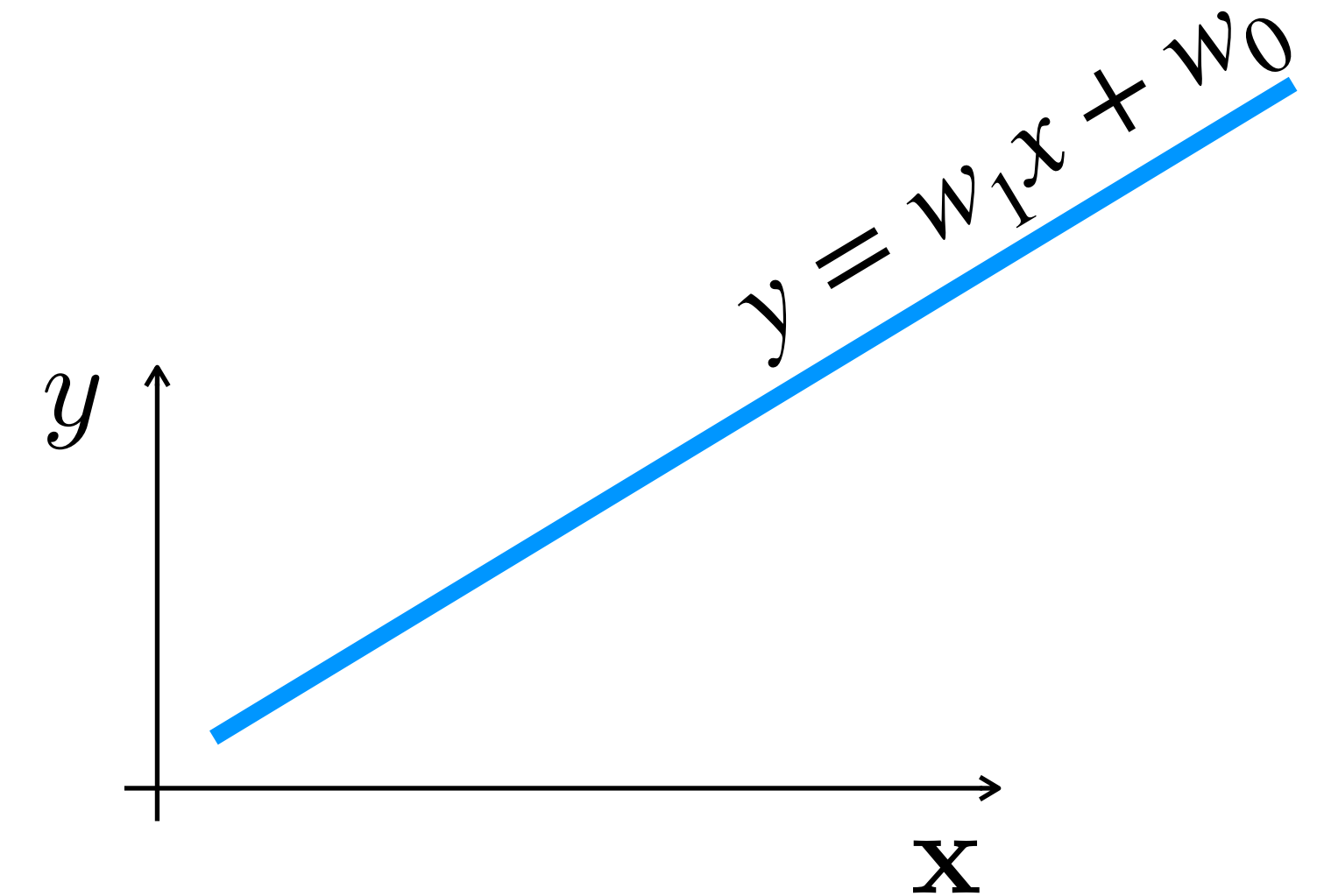
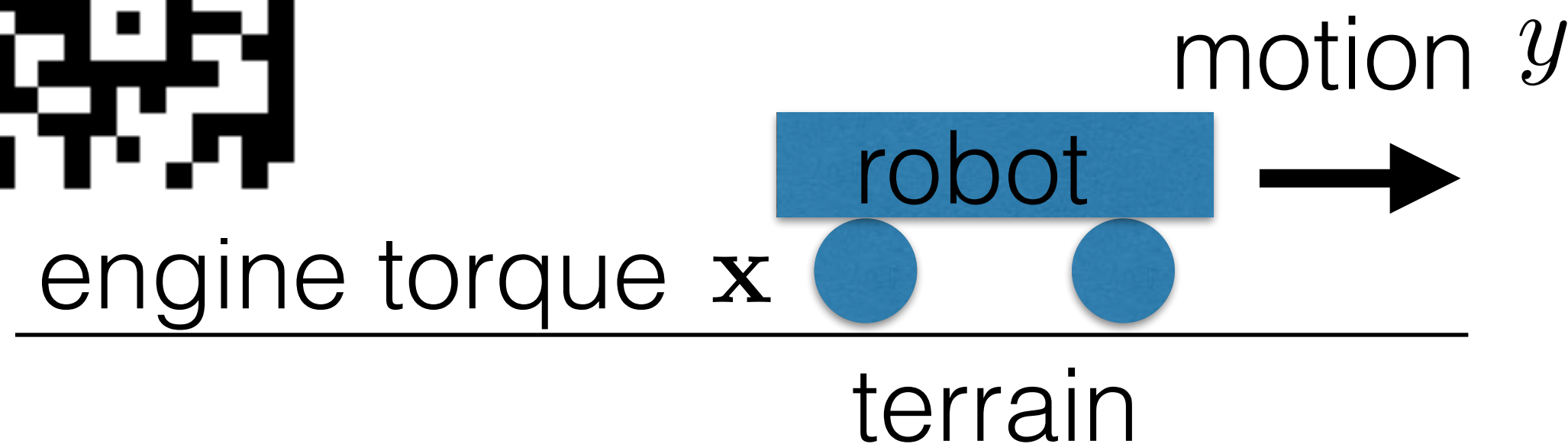


Motivation example: estimation of a motion model

- Which method will you use to build a motion model?
- Algorithm that maps x on y (or prob distr of y)

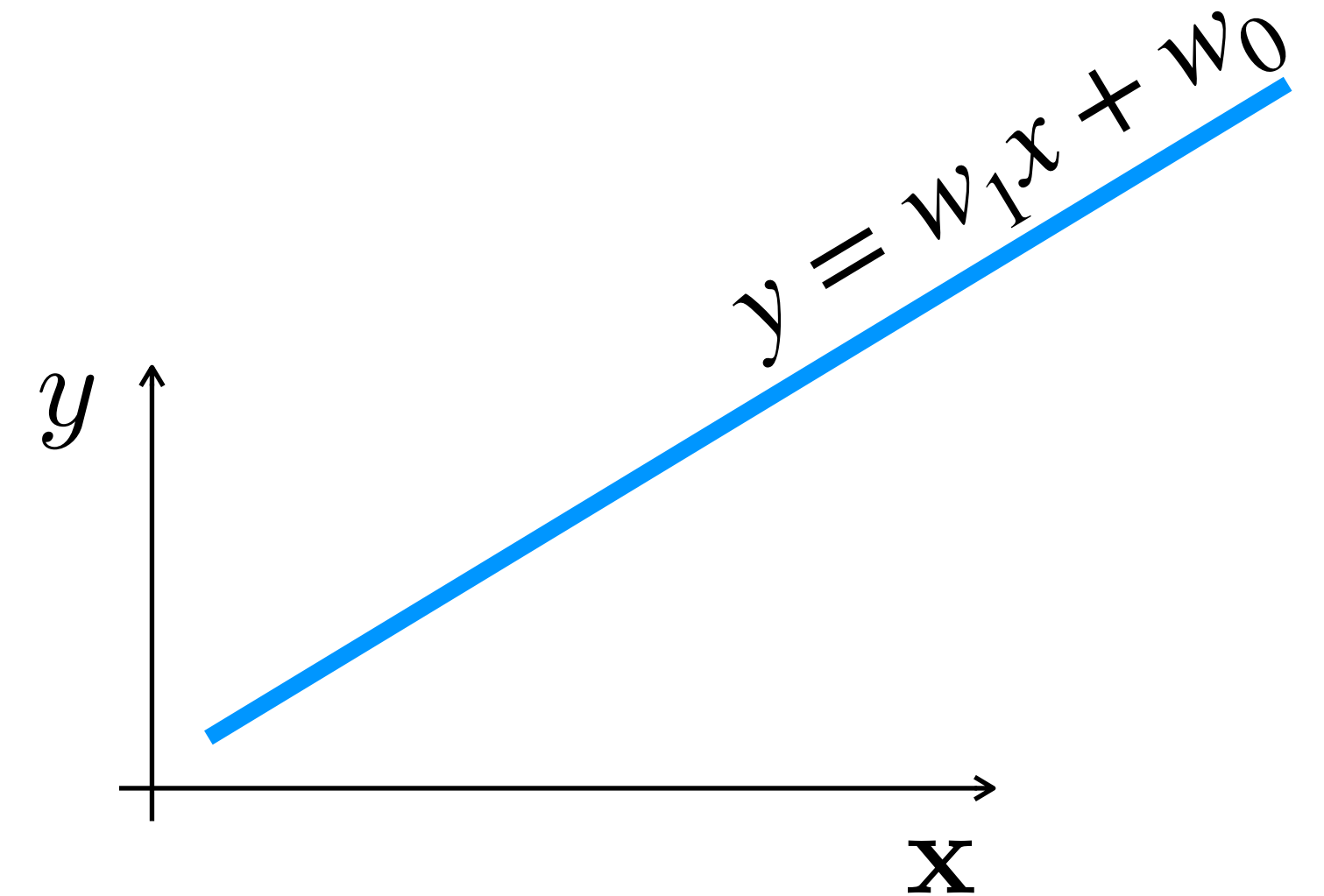
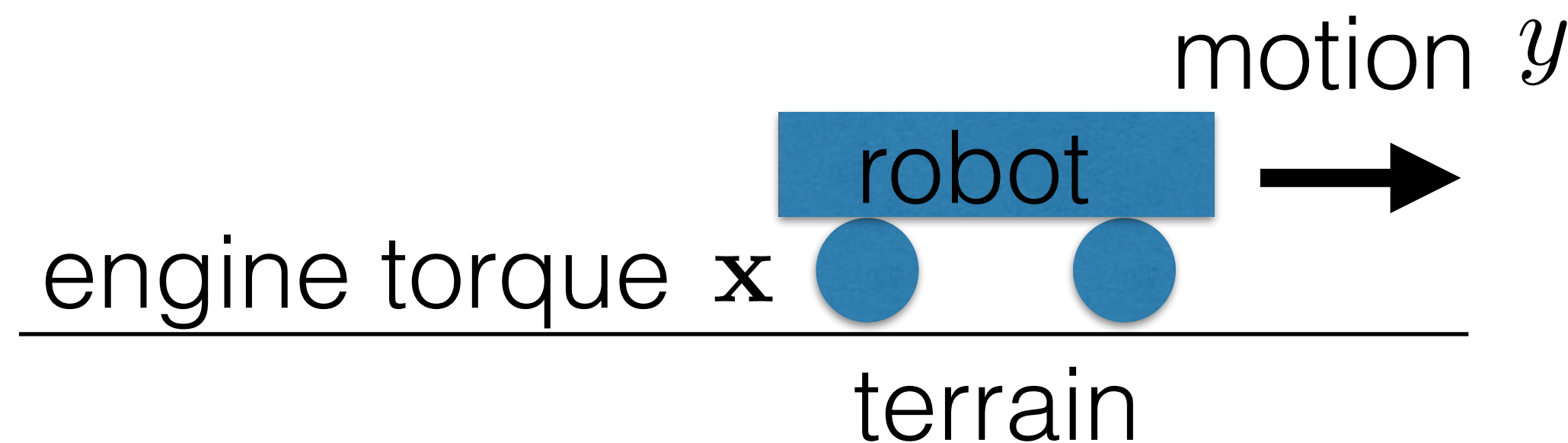


Do you know linear regression?



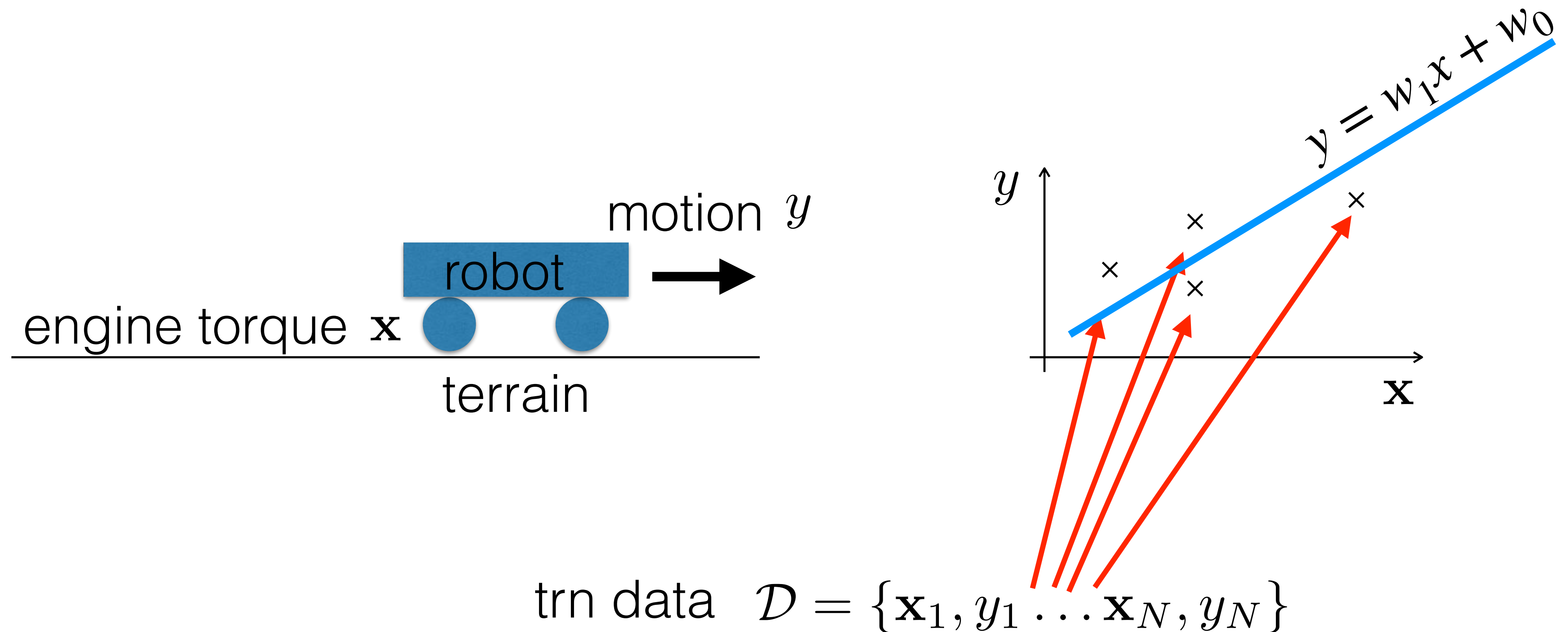
Motivation example: estimation of a motion model

- Which method will you use to build a motion model?
- Algorithm that maps x on y (or probab distr of y)
- This algorithm has some parameters \Rightarrow how to find them? \Rightarrow trn data+loss+opt



Motivation example: estimation of a motion model

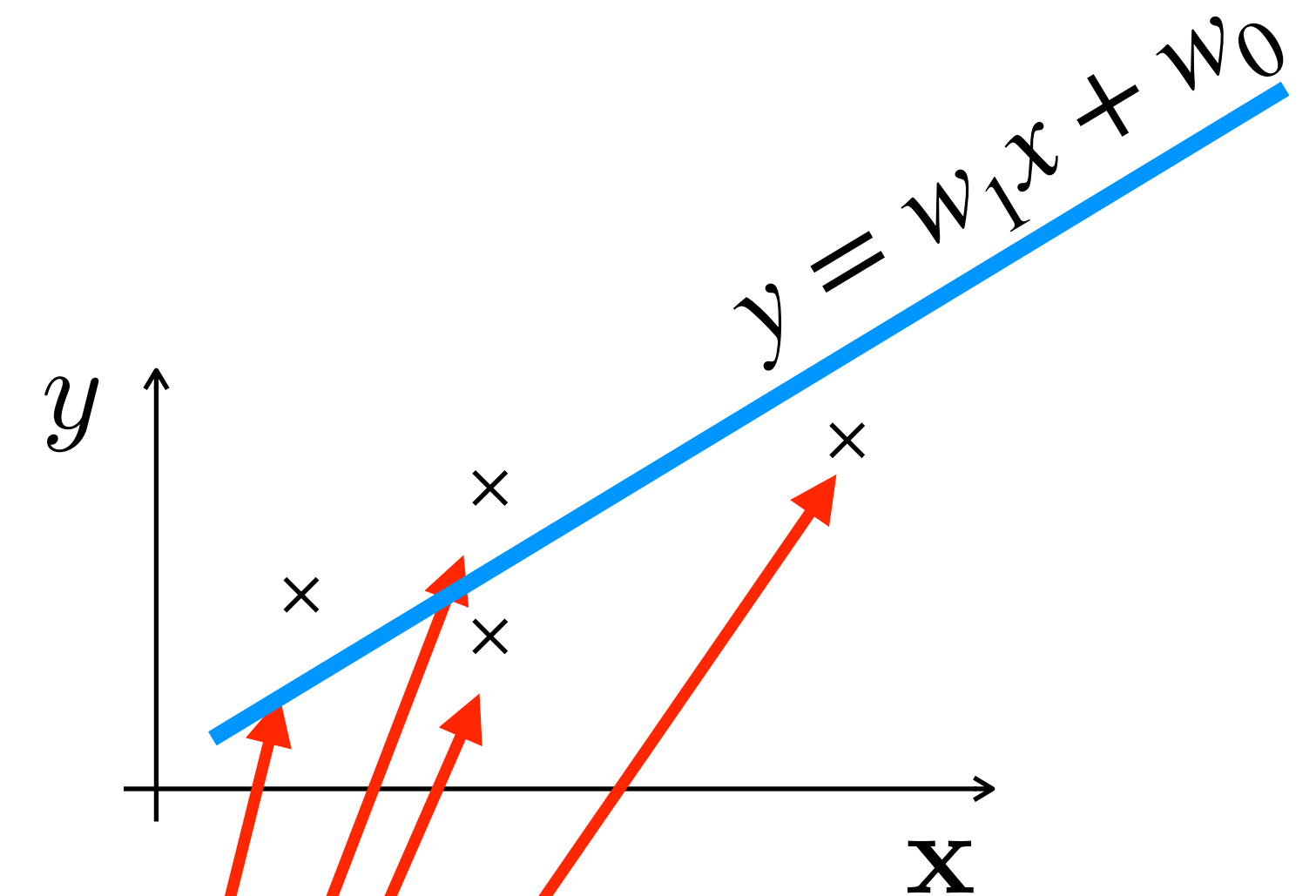
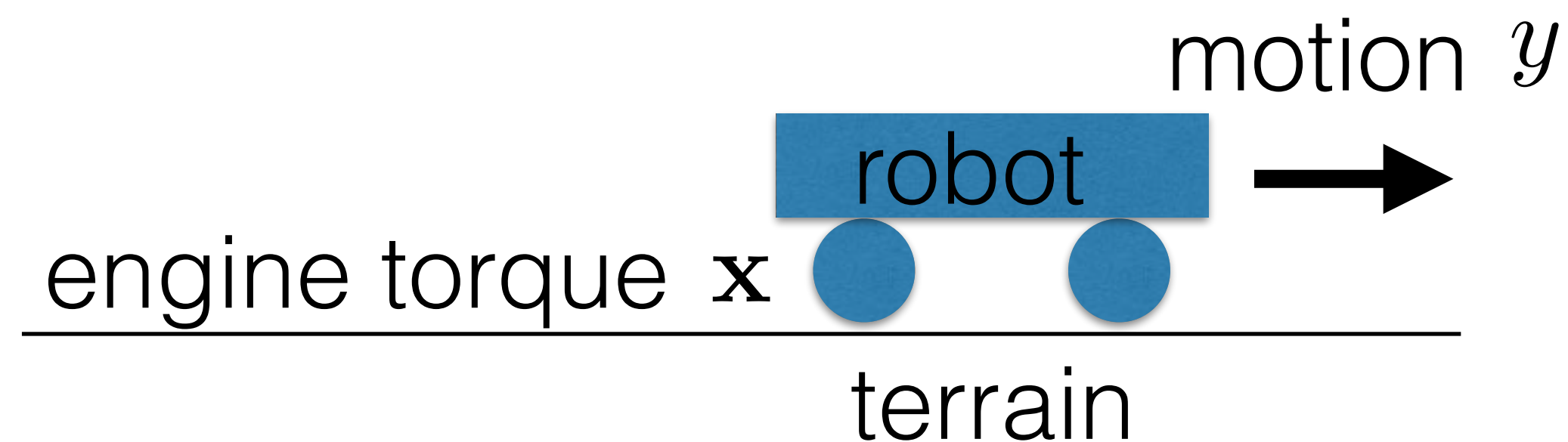
- Which method will you use to build a motion model?
- Algorithm that maps x on y (or probab distr of y)
- This algorithm has some parameters \Rightarrow how to find them? \Rightarrow +loss+opt



Motivation example: estimation of a motion model

- Let's implement it! loss = ???

opt = ???



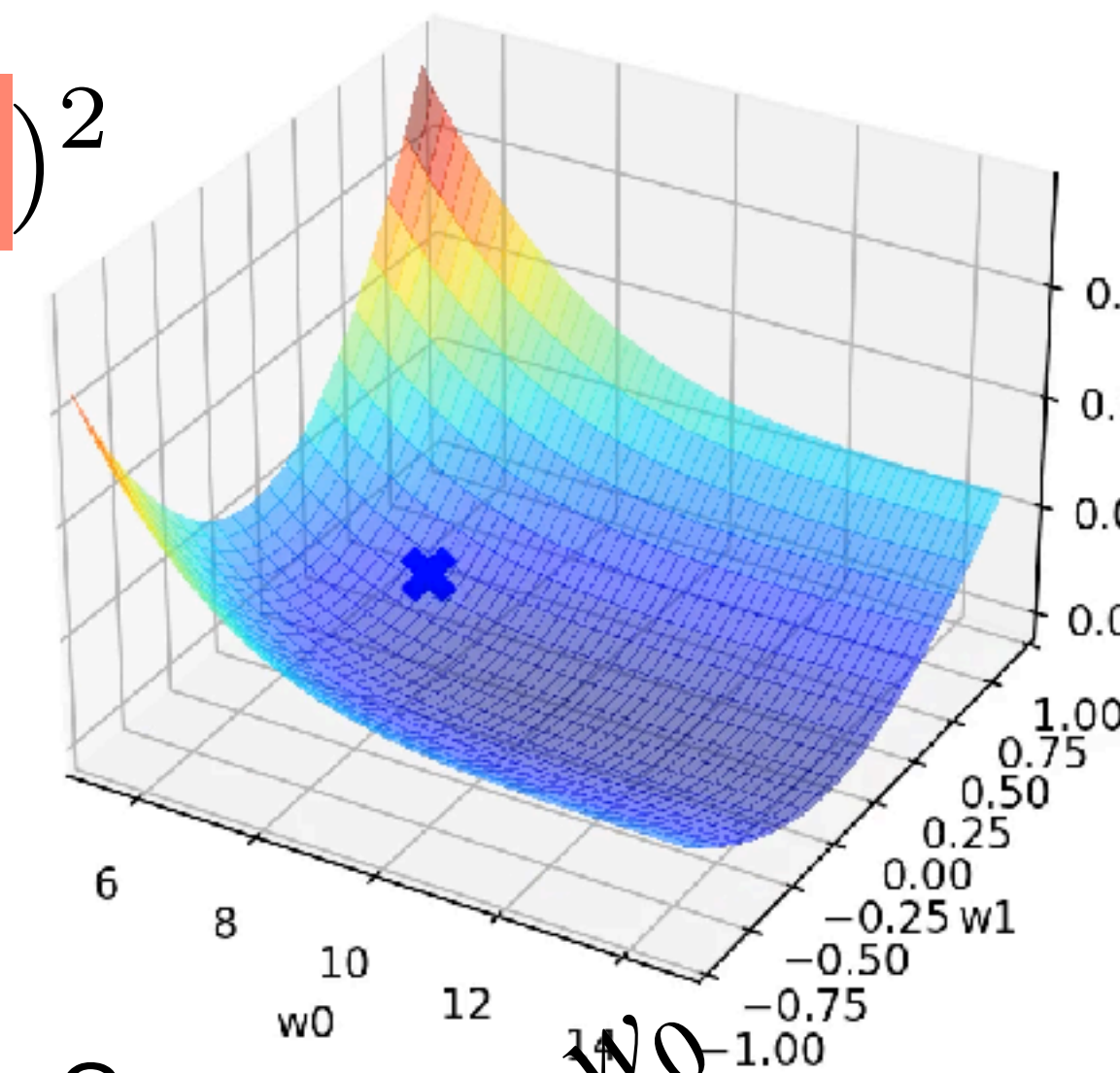
trn data $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

Motivation example: estimation of a motion model

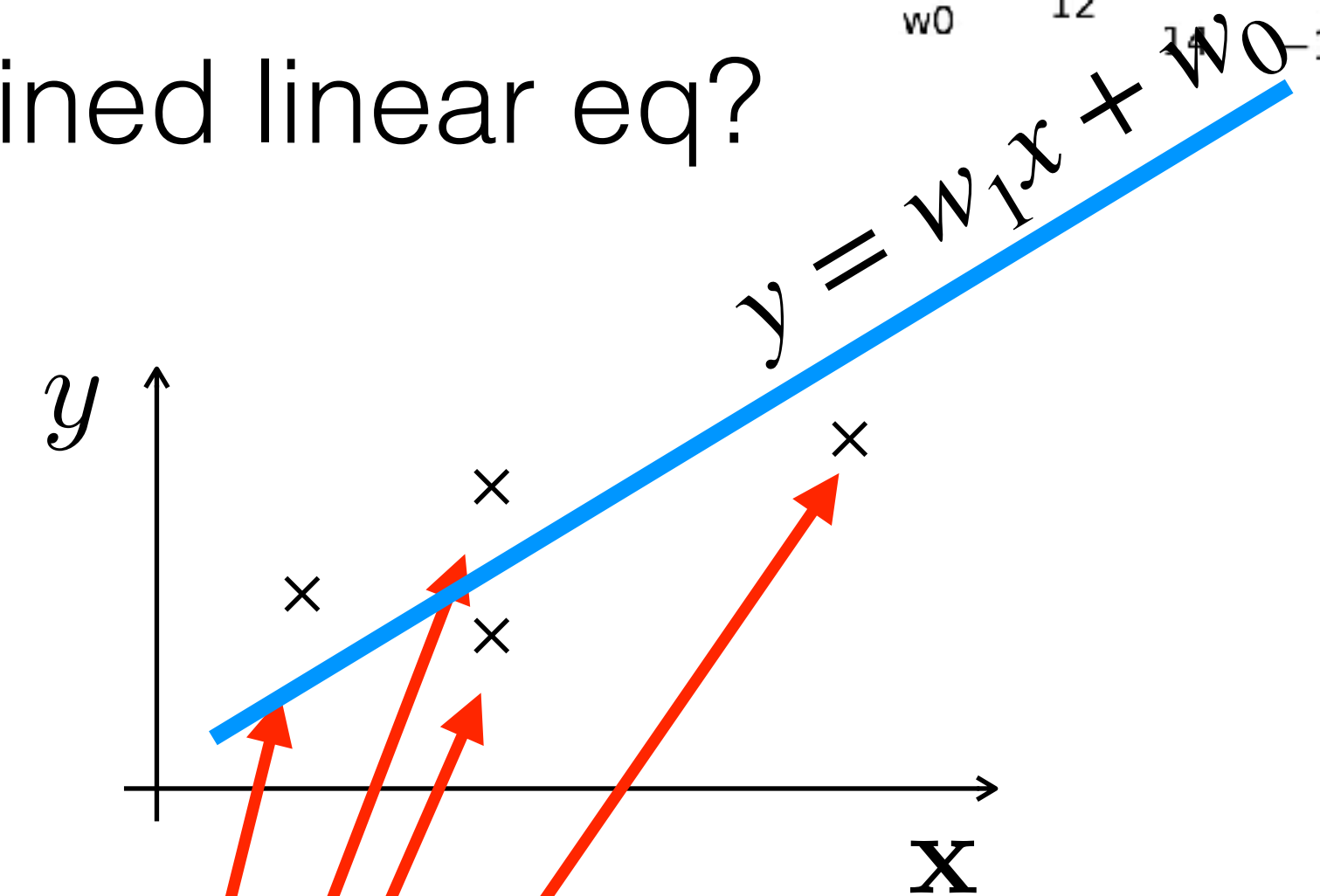
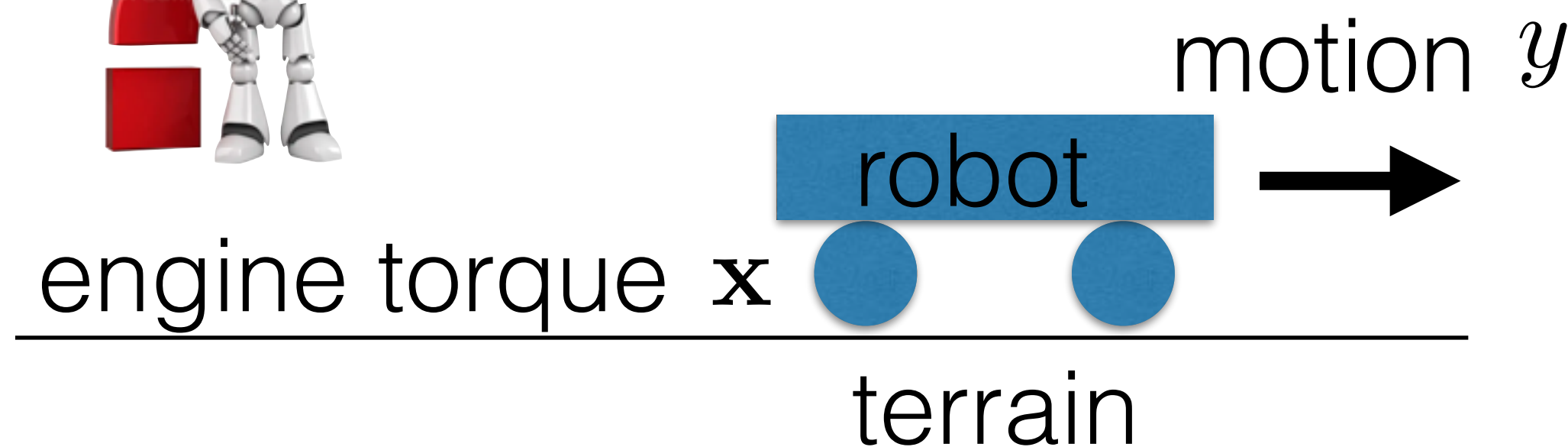
- Let's implement it!

loss: $\arg \min_{\mathbf{w}} \sum_i (w_1 x_i + w_0 - y_i)^2$

```
opt = w = np.array([-2.0, 2.0])
      for i in range(0, 10):
        loss = np.sum( (w[0] * x + w[1] - y)**2 )
        w = w - 0.1 * grad(loss, w)
```



- Which functions can be fitted through overdetermined linear eq?

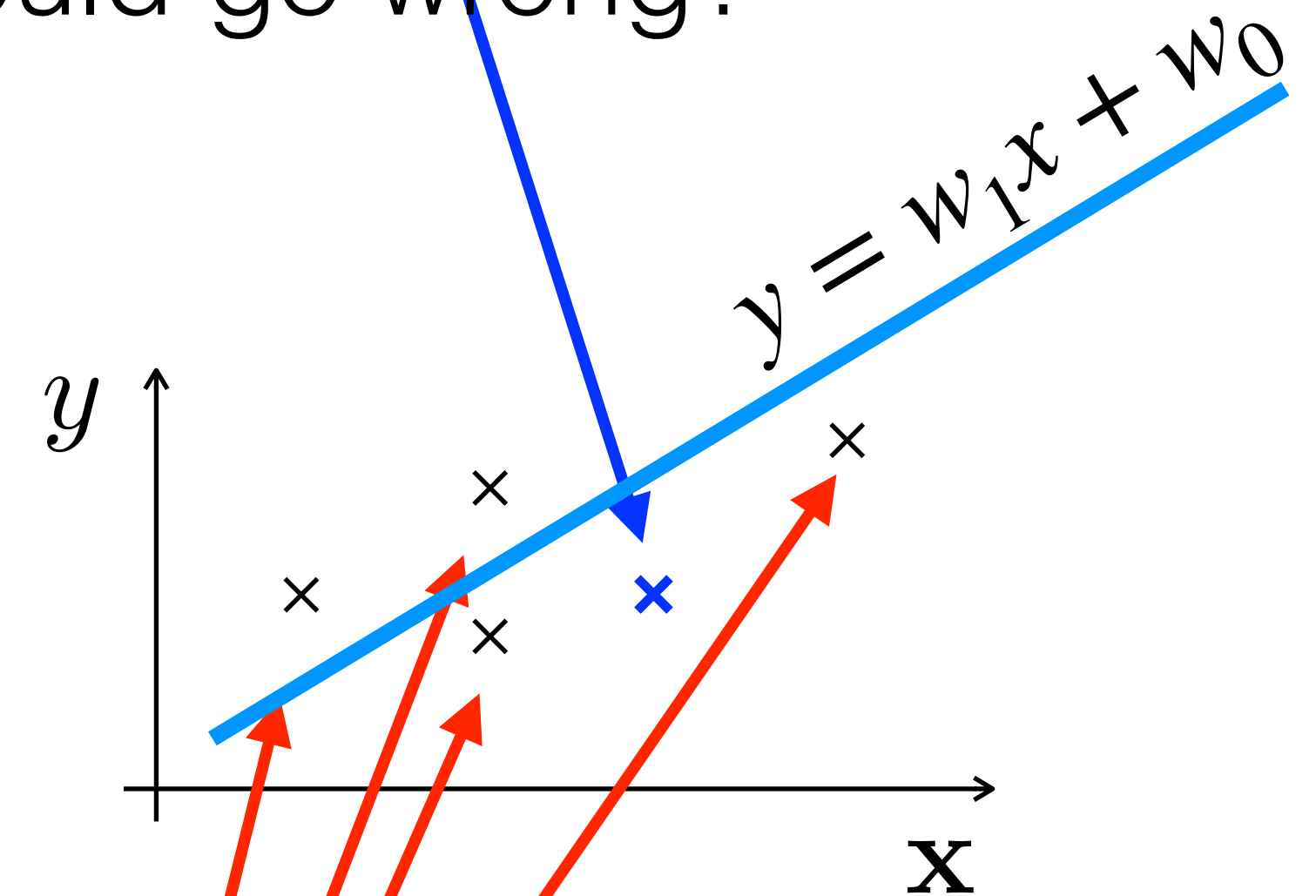
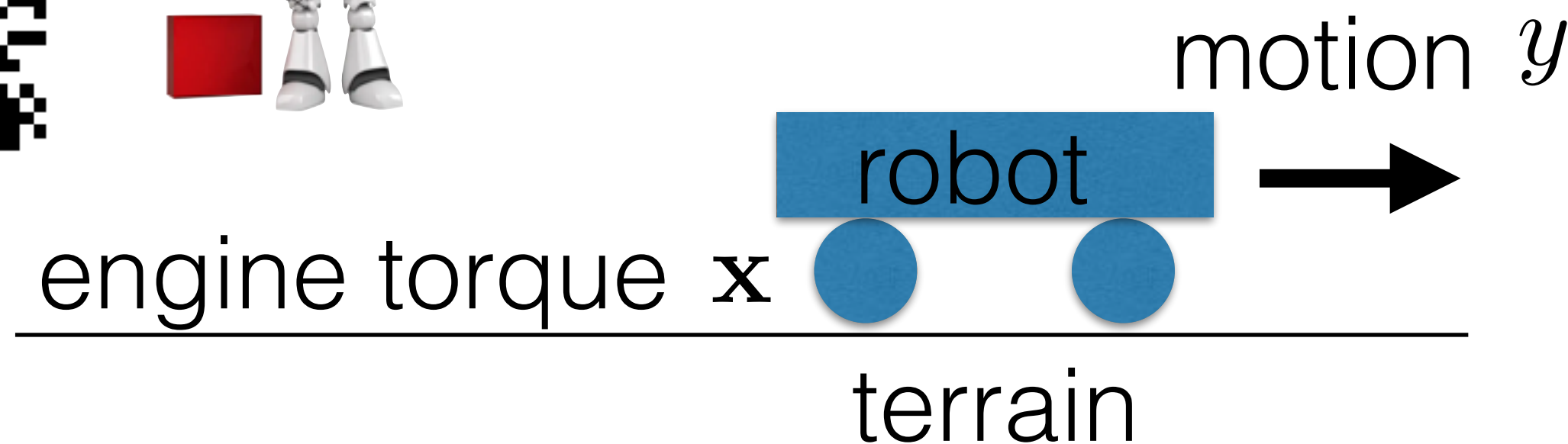


trn data $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

Motivation example: estimation of a motion model

- What do I need to build a motion model?
- Algorithm that maps x on y (or prob distr of y)
- This algorithm has some parameters \Rightarrow how to find them? \Rightarrow loss+trn data+opt
- How to decide that the algorithm works well? \Rightarrow tst data
- What if the algorithm does not work well? What could go wrong?

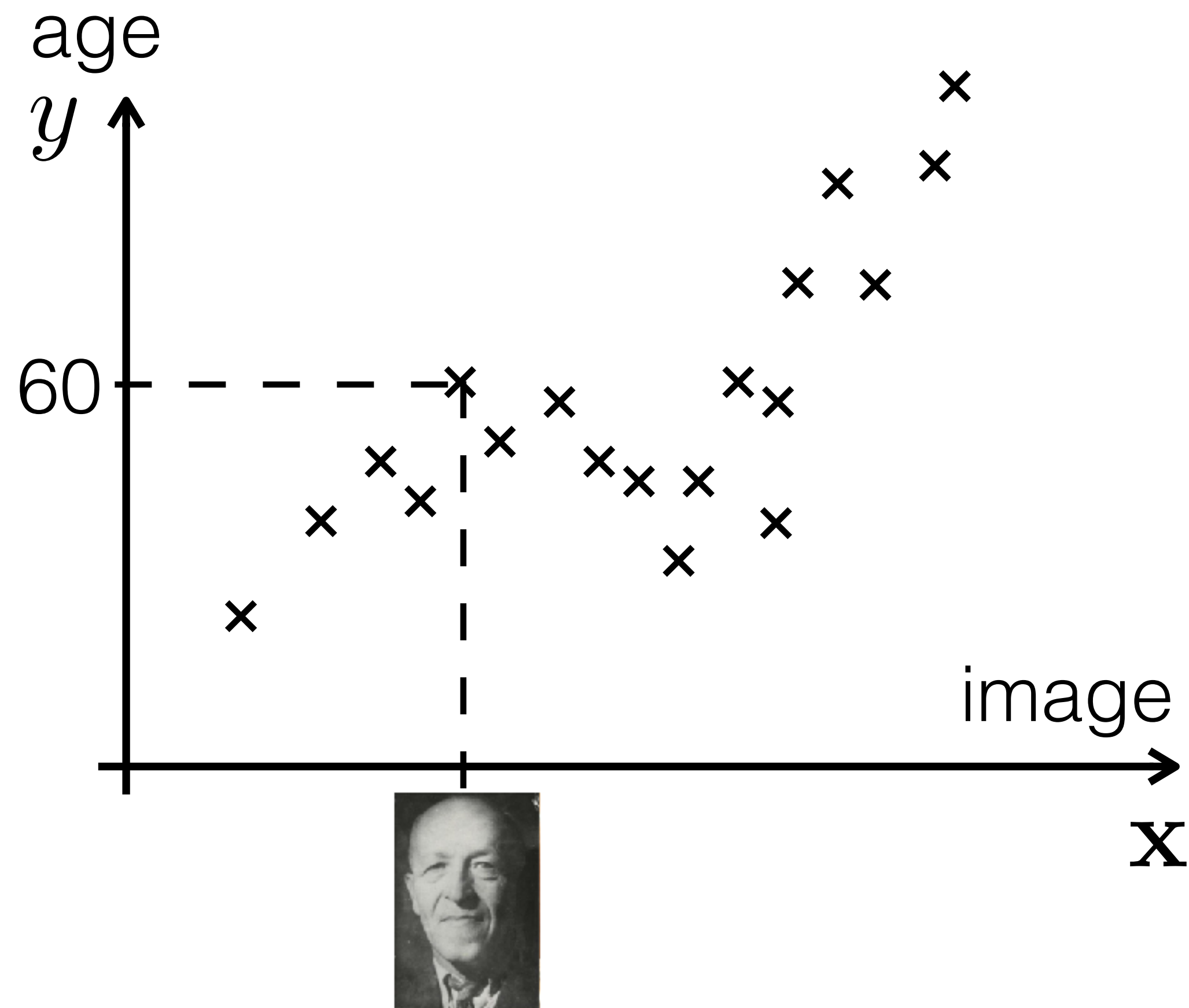
SOLVED



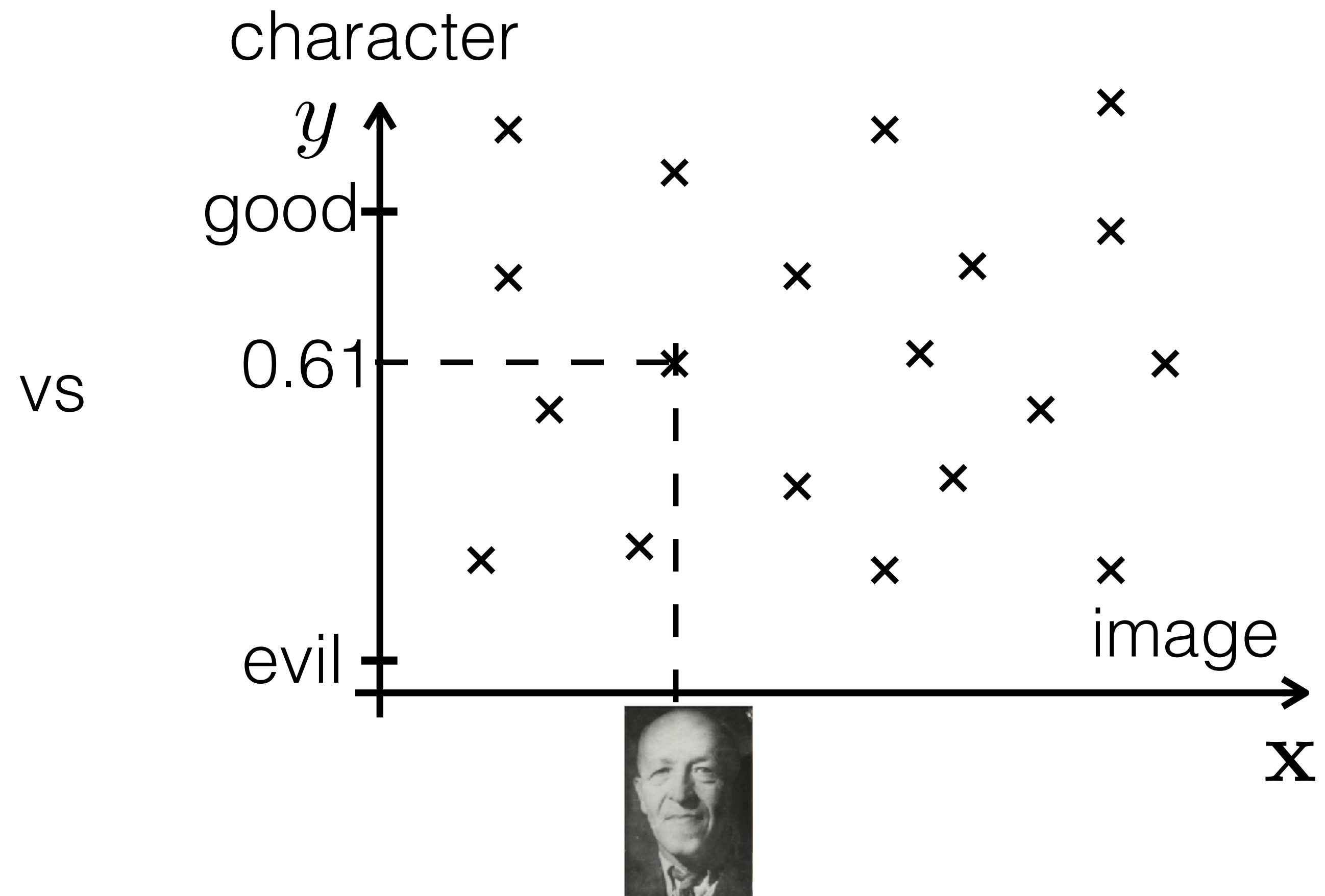
trn data $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

What can go wrong: **inputs x does not allow to predict y**

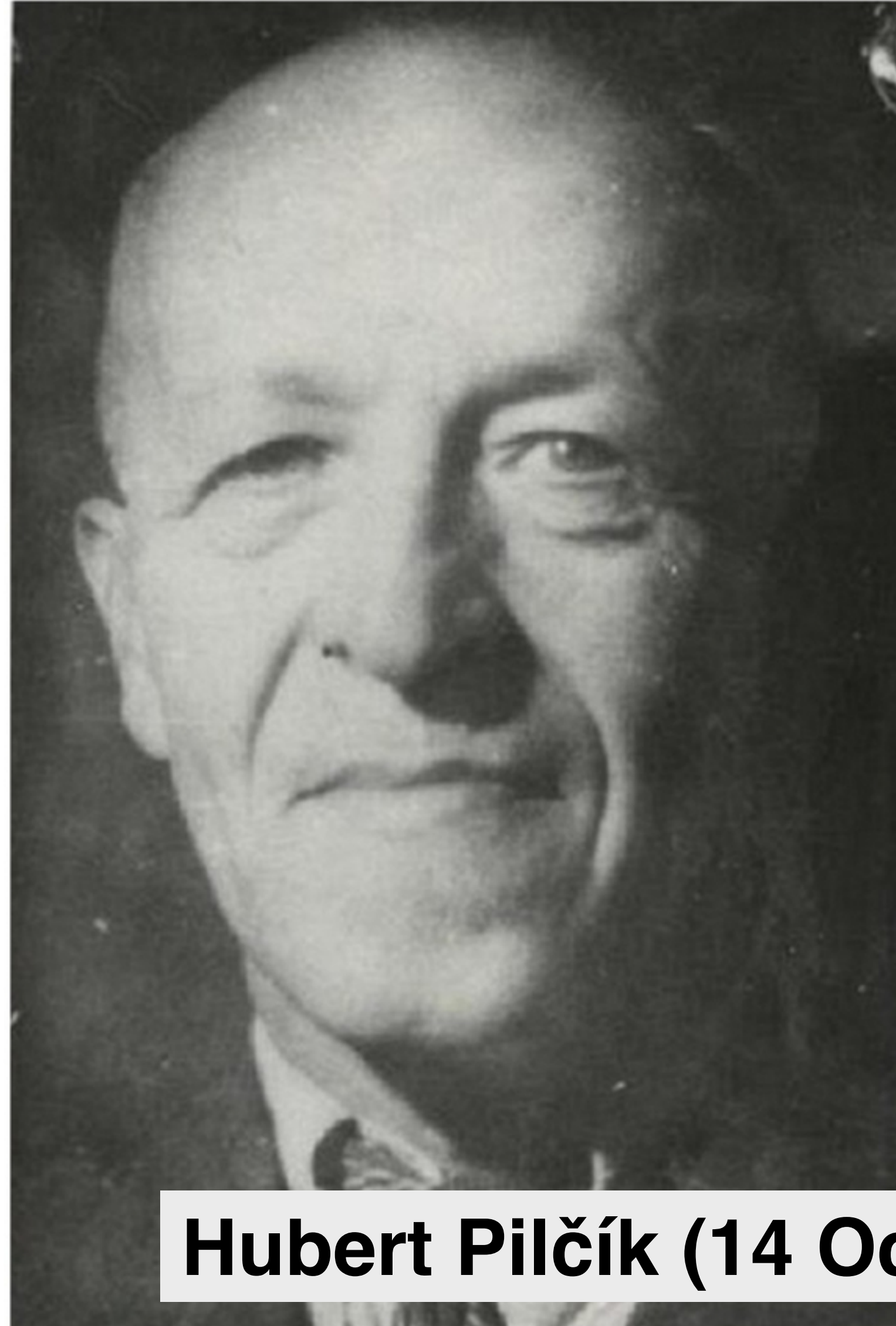
predicting person's age from face image



predicting human character
from face pictures



What can go wrong: **inputs x does not allow to predict y**



Hubert Pilčík (14 October 1891 – 9 September 1951)

A Deep Neural Network Model to Predict Criminality Using Image Processing
<https://medium.com/@CoalitionForCriticalTechnology/abolish-the-techtoprisonpipeline-9b5b14366b16>

What can go wrong: **inputs x does not allow to predict y**



- Nazi V-2
- US Apollo program



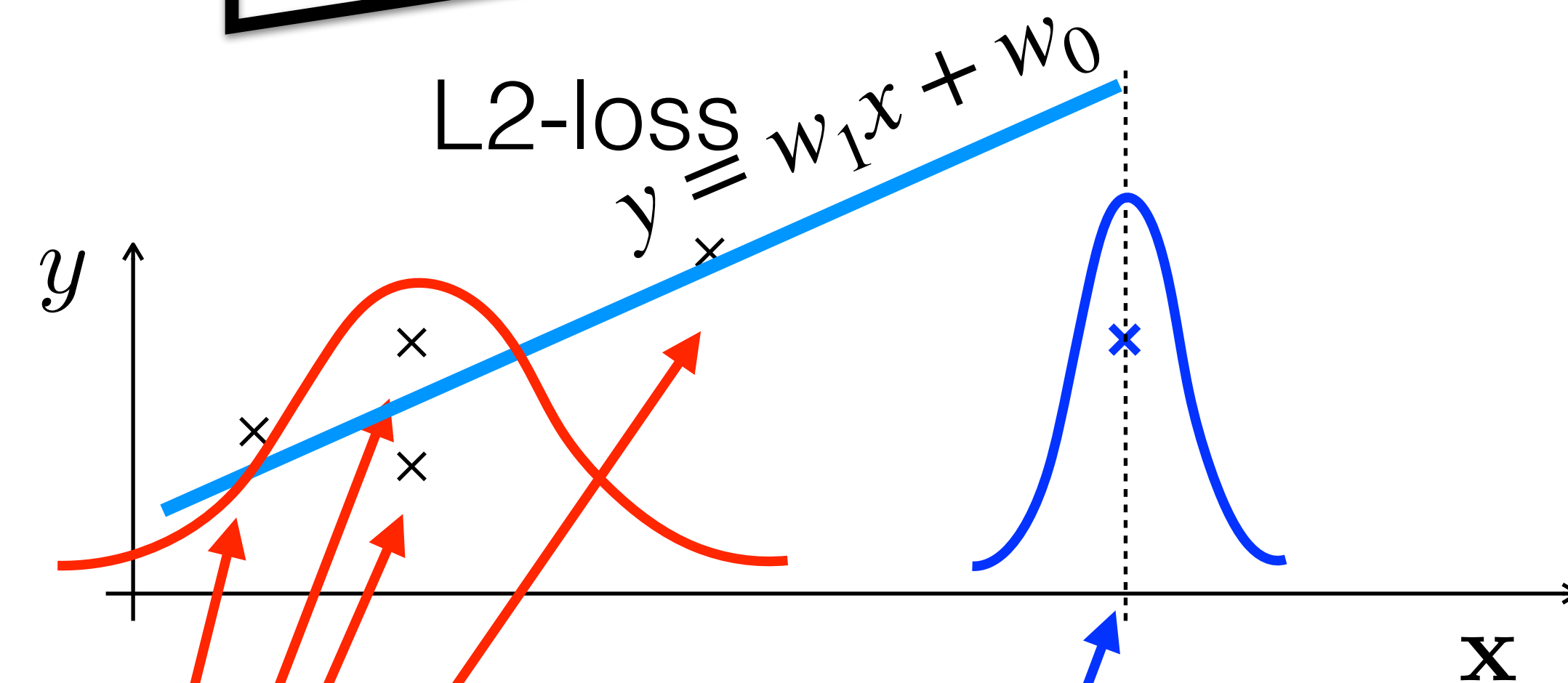
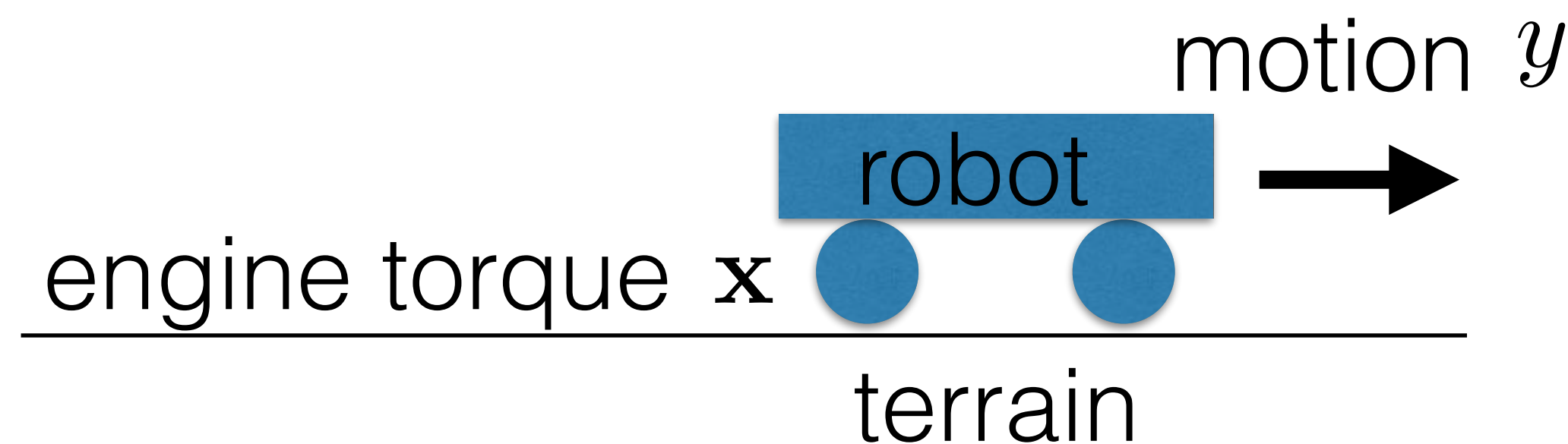
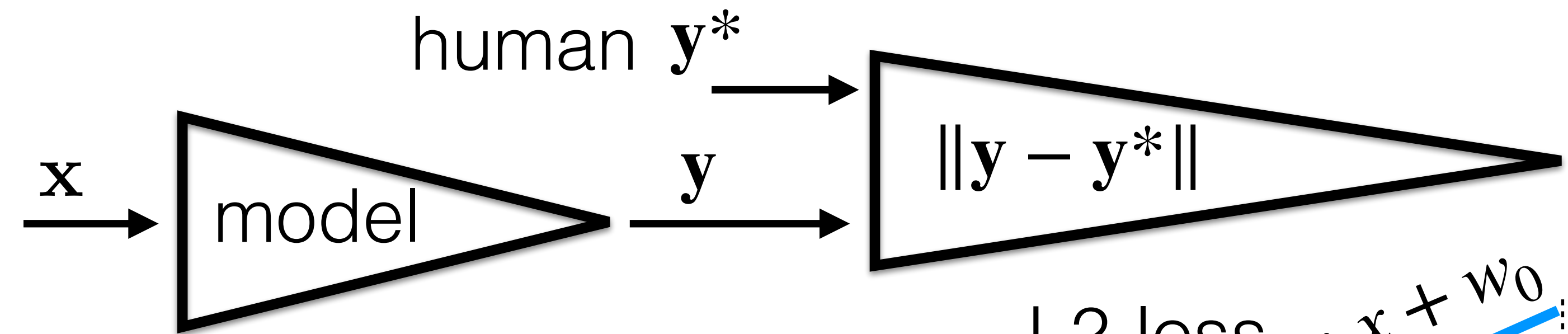
- Kalman filter

What can go wrong: **trn/tst data distribution mismatch**

- Day/night, summer/winter, USA/China, young/old people, American/Indian English

[NVidia, CVPR, 2016] Does this suffer from trn/tst distribution mismatch?

Statistical consistency



trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

tst data:

What can go wrong: **trn/tst data distribution mismatch**

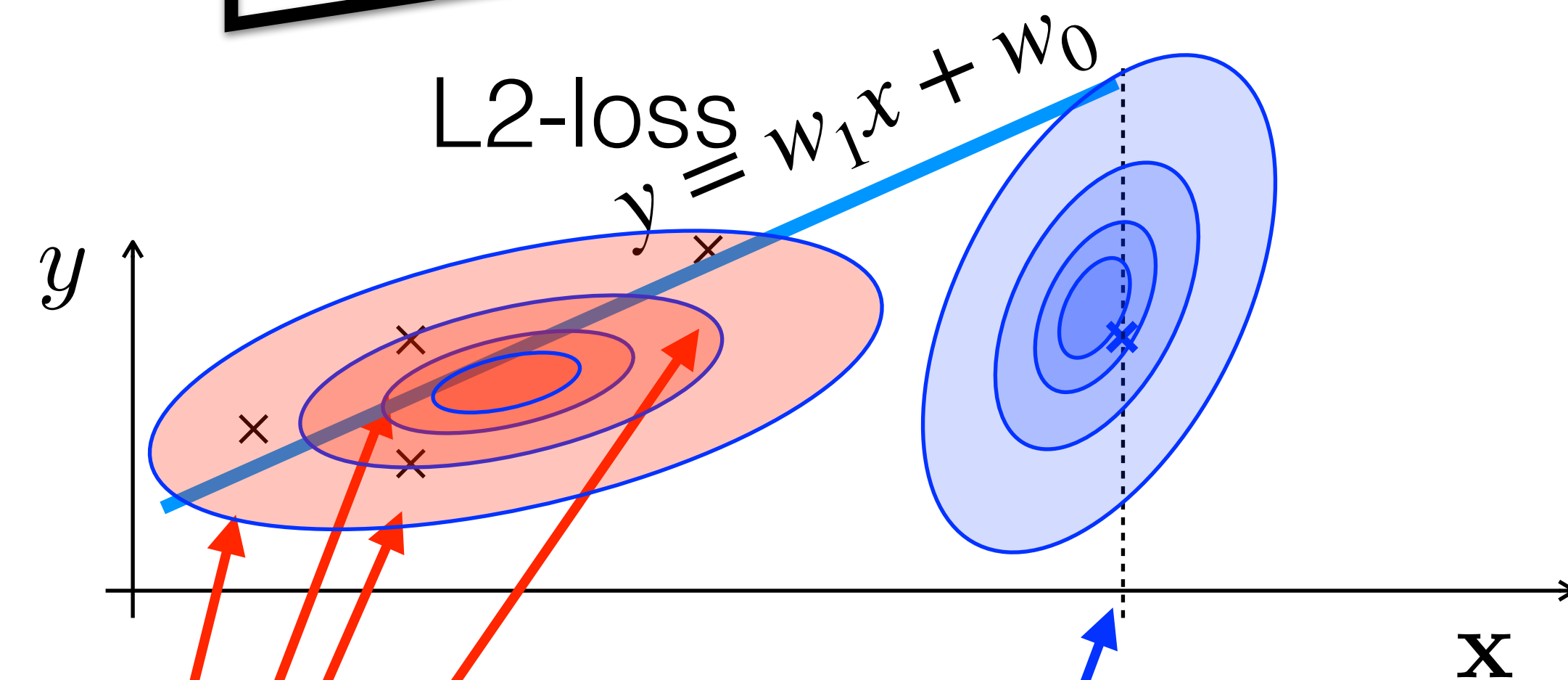
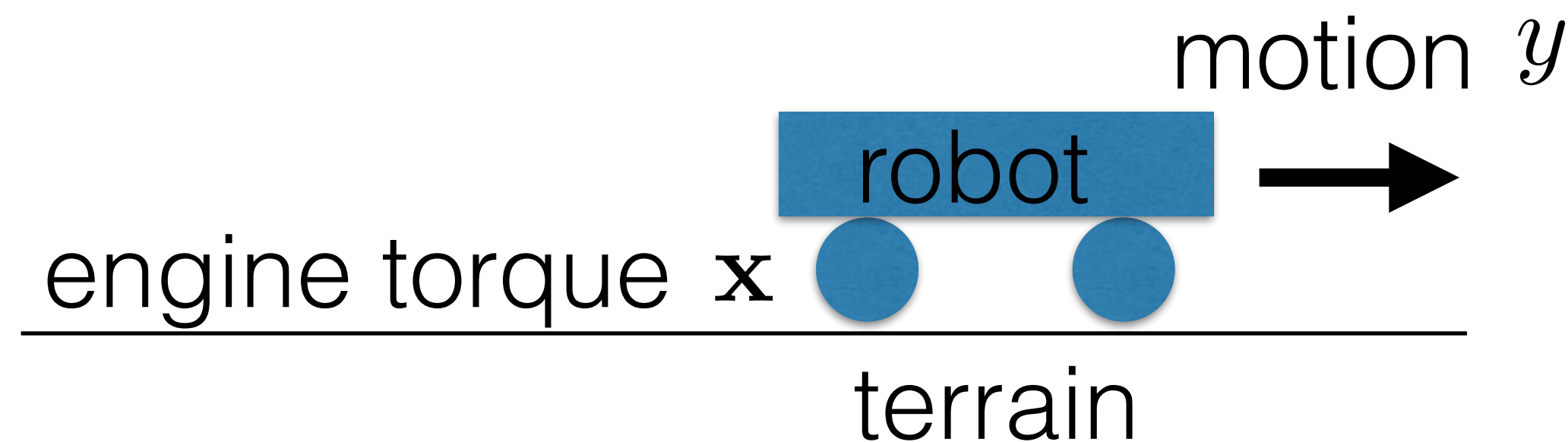
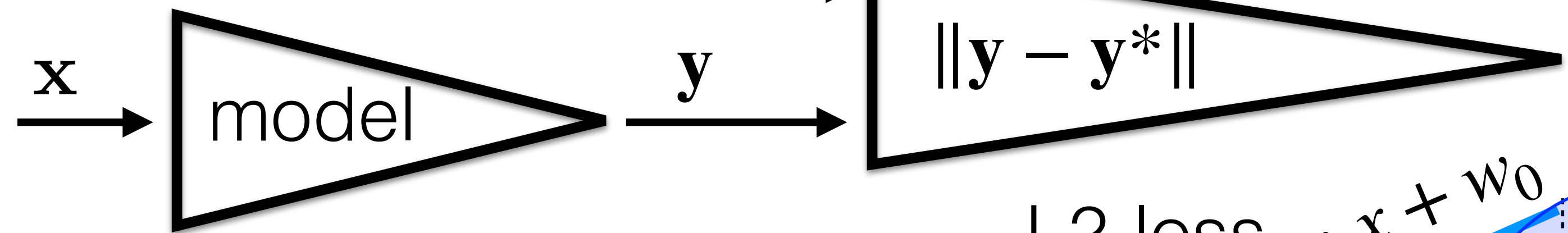
- Day/night, summer/winter, USA/China, young/old people, American/Indian English

[NVidia, CVPR, 2016]

Does this suffer from trn/tst distribution mismatch?

Statistical consistency

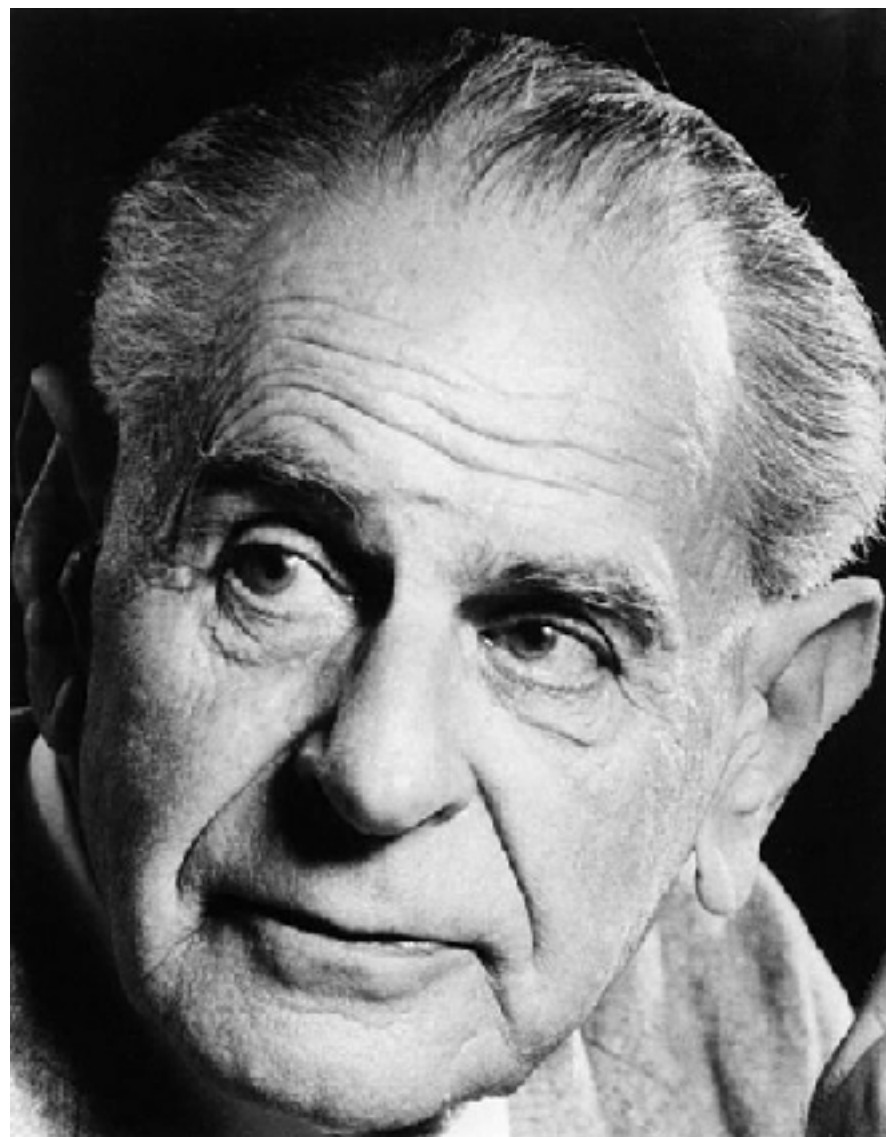
human y^*



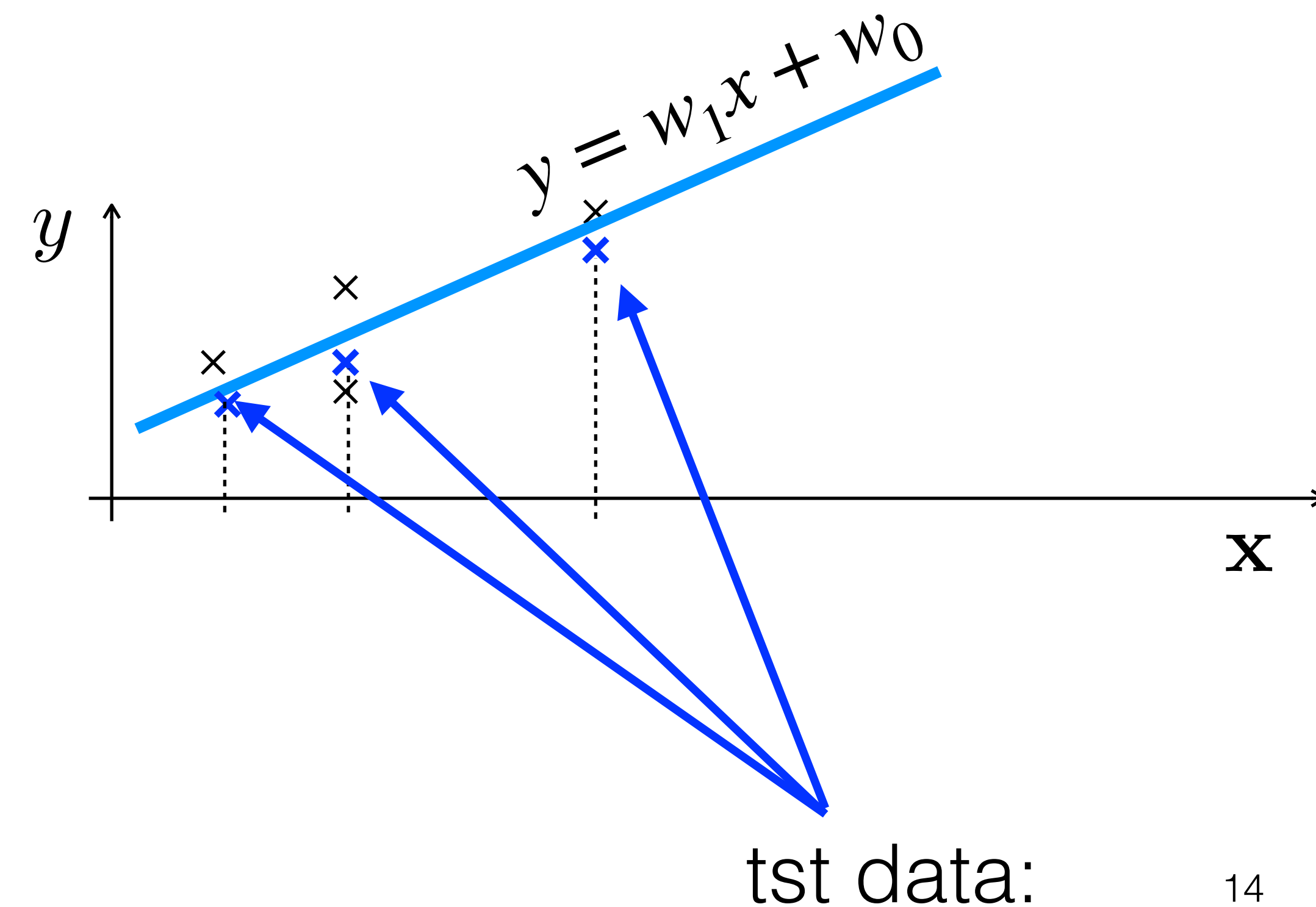
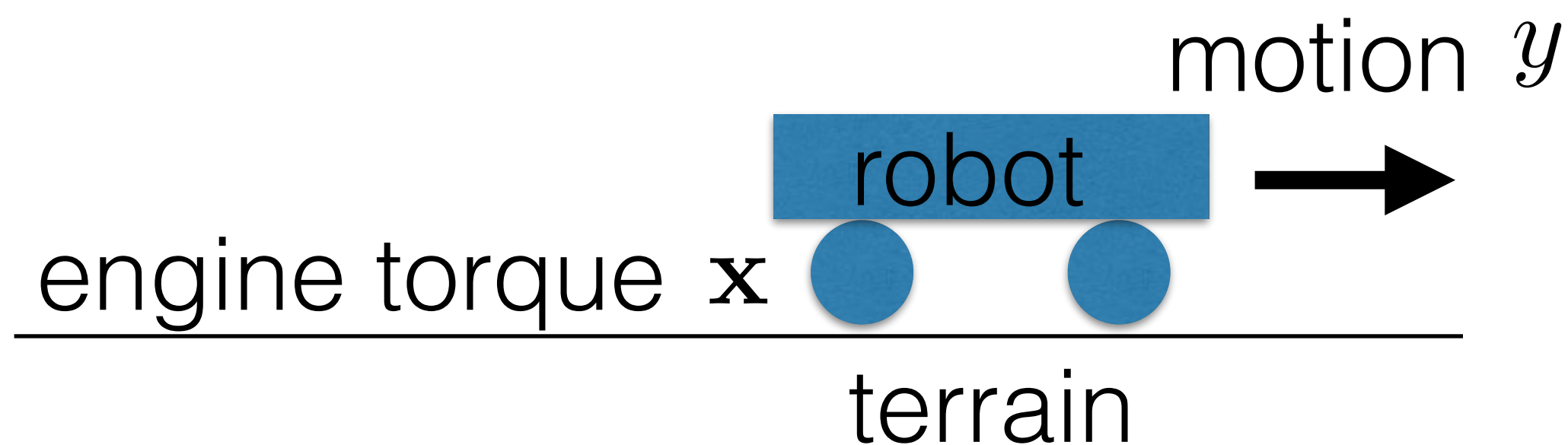
trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

tst data:

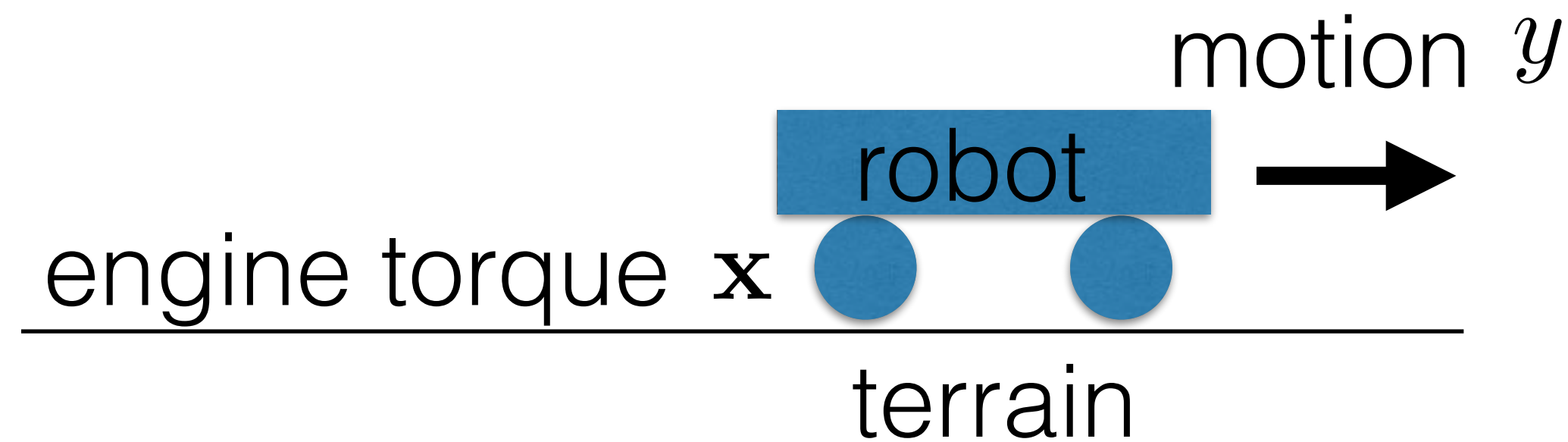
What can go wrong: **trn/tst data are too similar**



Humans subconsciously selects testing data that that are consistent with their proposed solution.



What can go wrong: **inappropriate model**

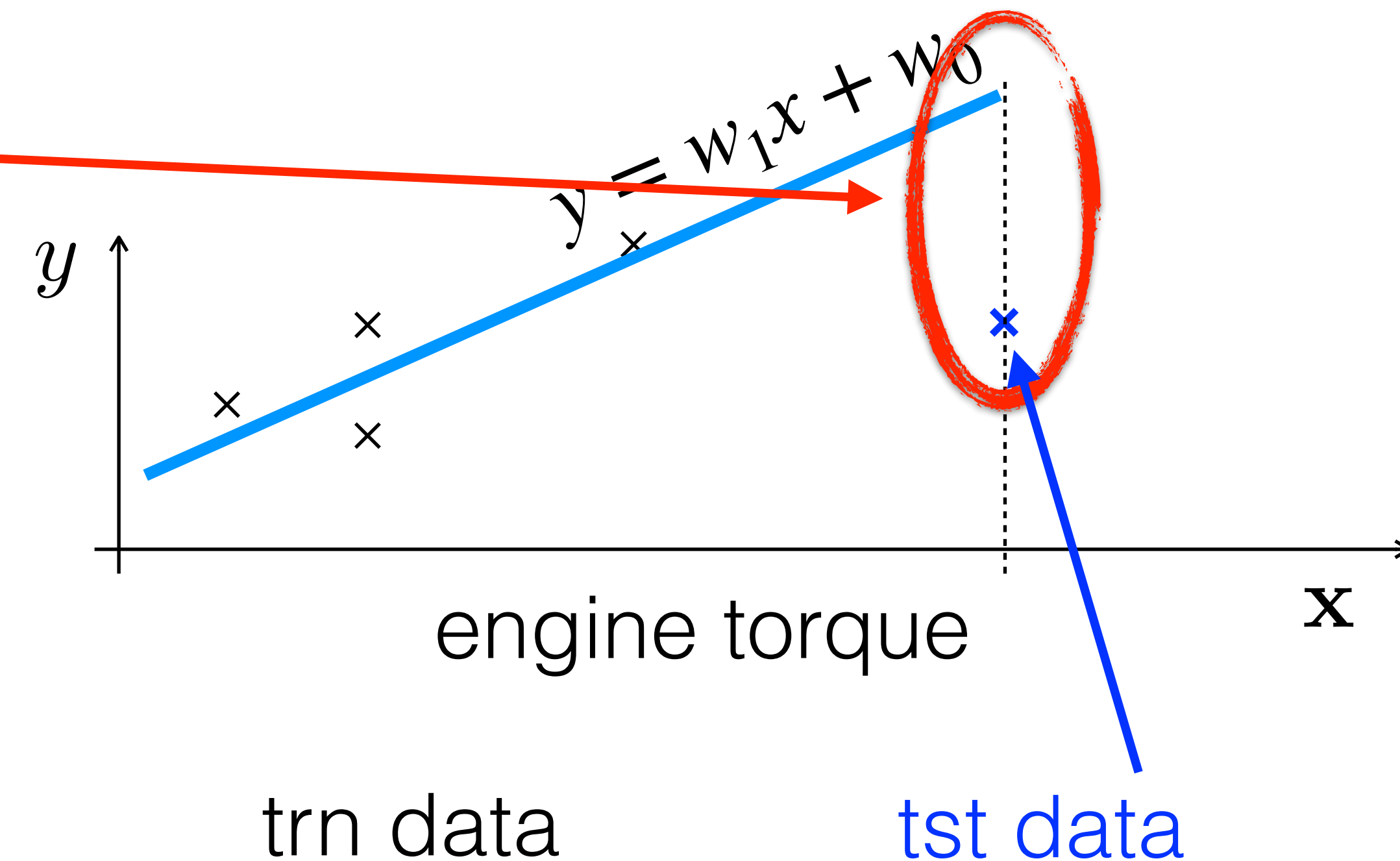


linear function \Rightarrow underfitting

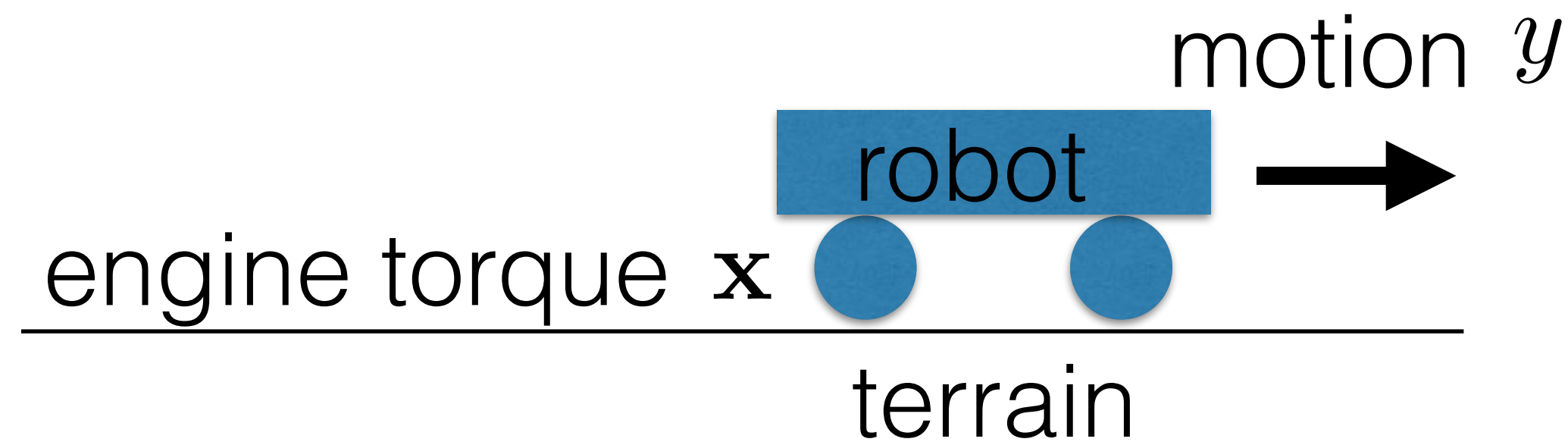
Underfitting:

- bad generalization due to oversimplified model

robot's motion



What can go wrong: **inappropriate model**

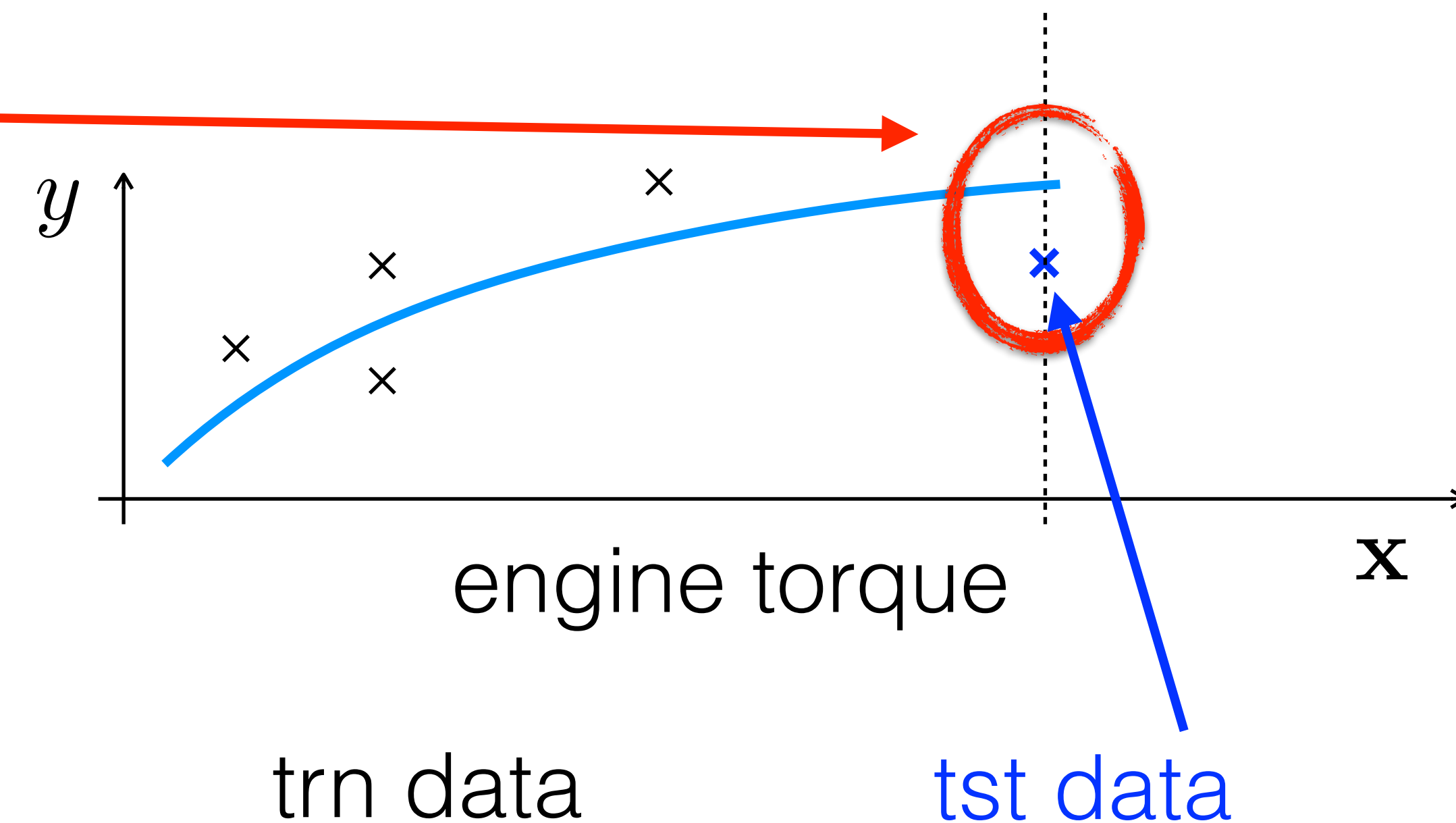


log function => good fit

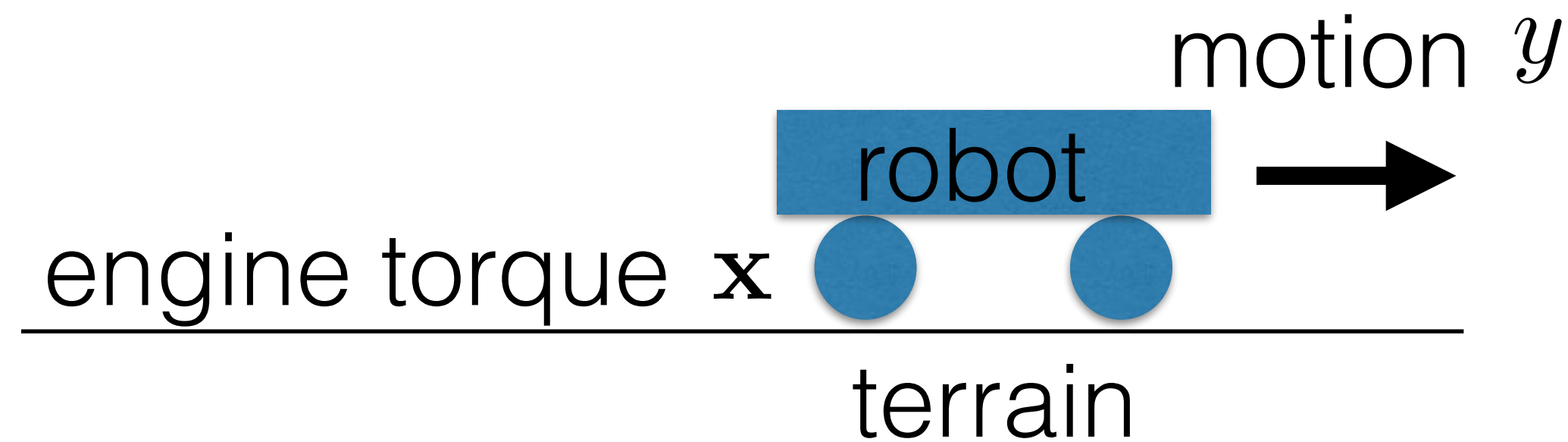
Good model provides:

- good generalization
(less sensitive to trn/tst mismatch)

robot's
motion



What can go wrong: **inappropriate model**

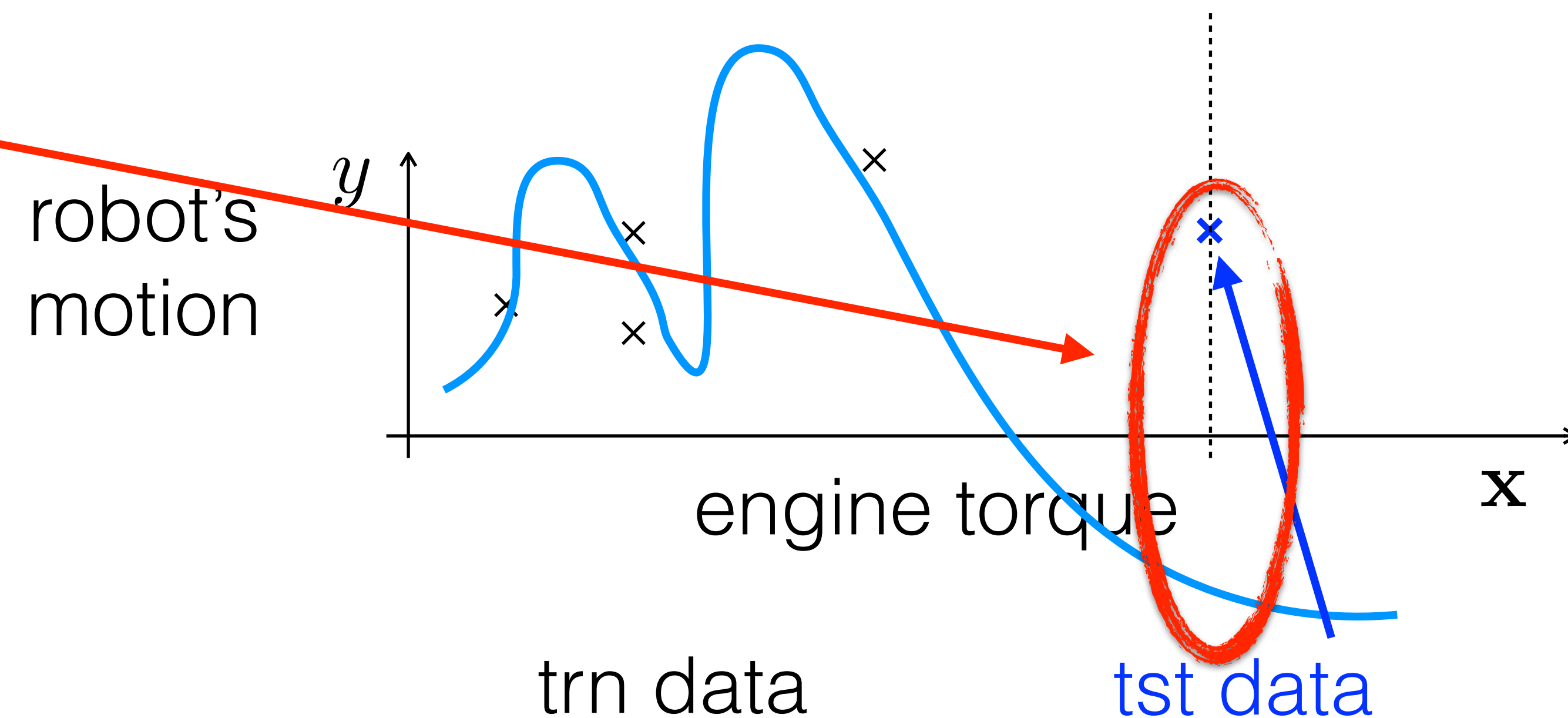


Overfitting:

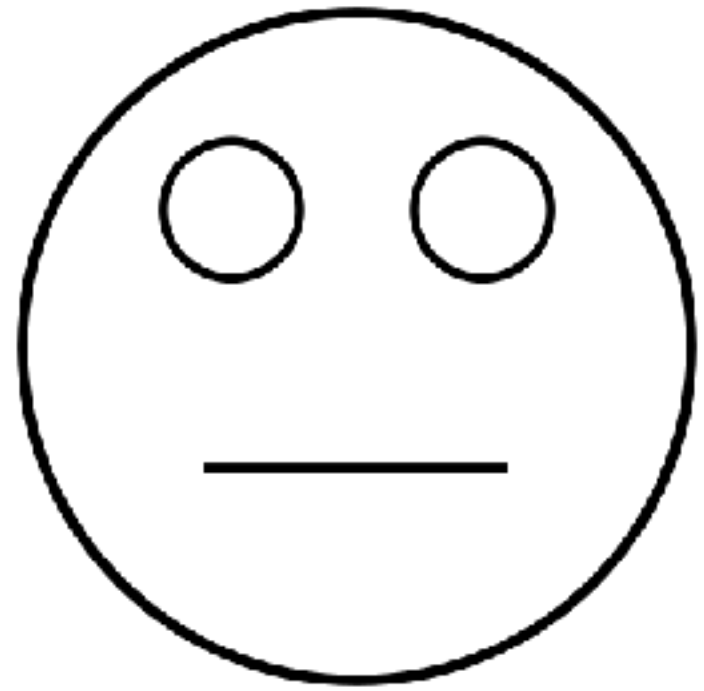
- bad generalization due to overcomplex model

Do humans overfit?

complicated function=>overfitting

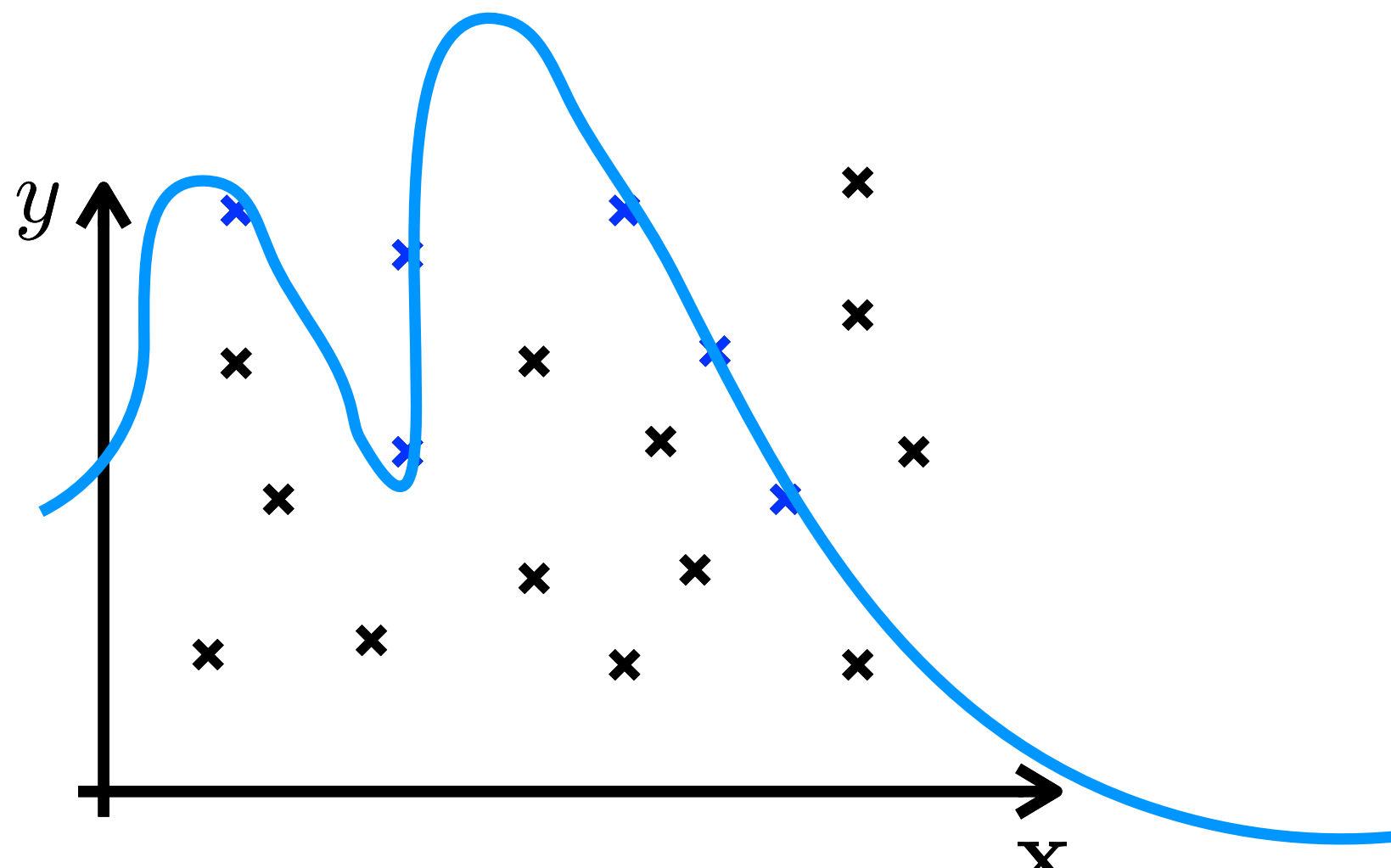


What can go wrong: **inappropriate model**



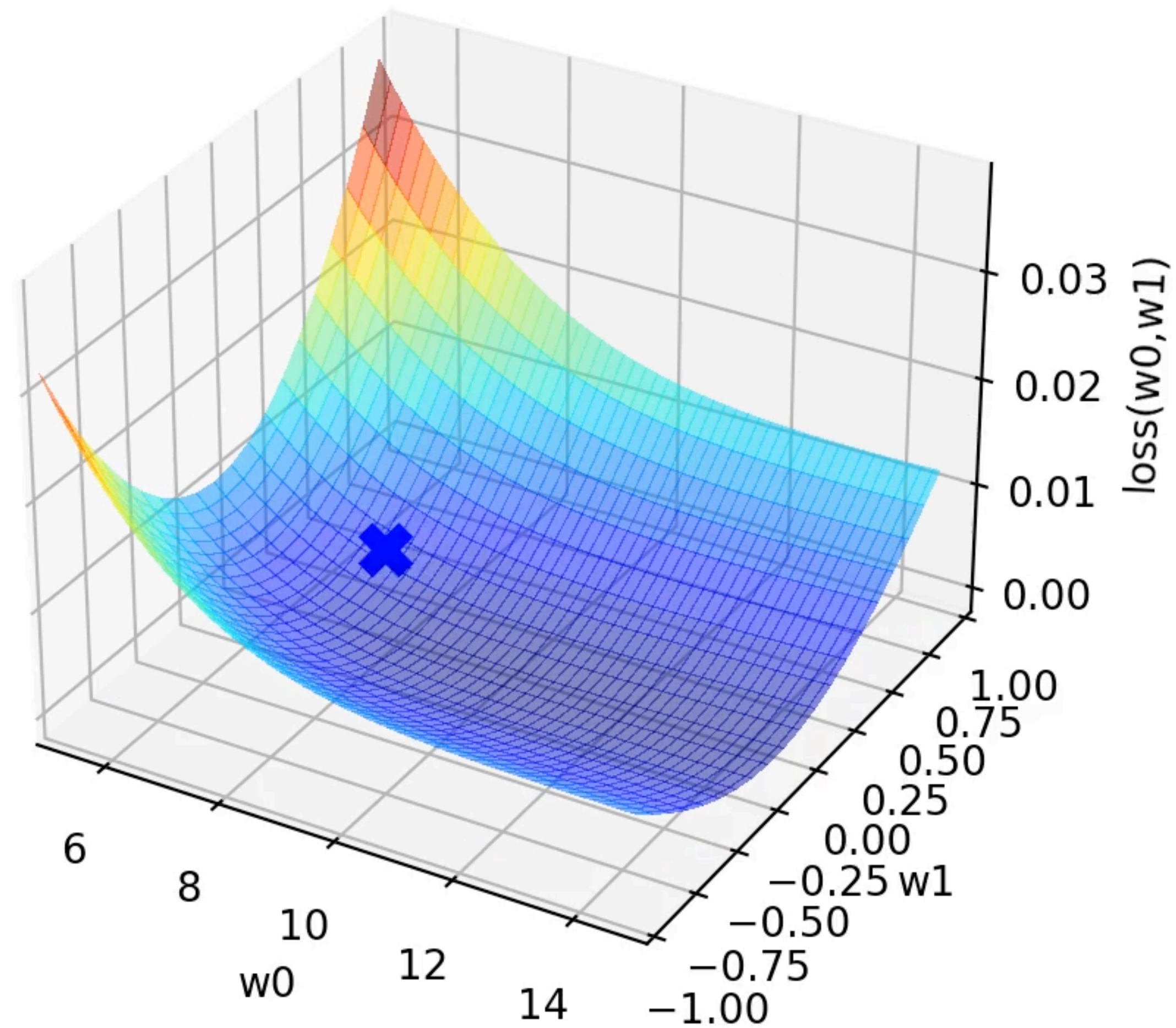
Do humans overfit?

Apofenia=human overfitting

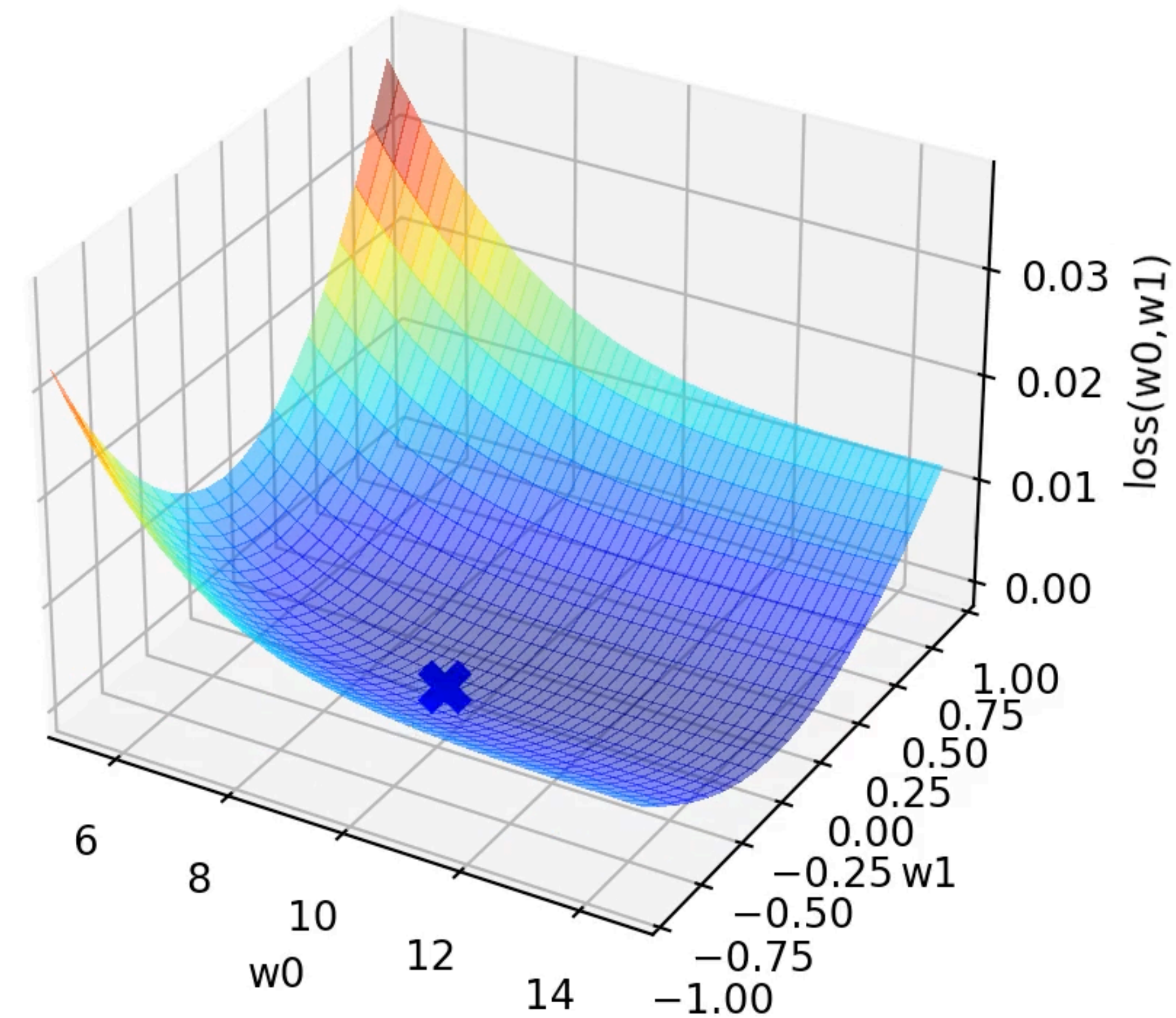


What can go wrong: **learning fails to find good model parameters**
due to hyper-parameters, local optima, bad initialization ...

reasonable learning rate

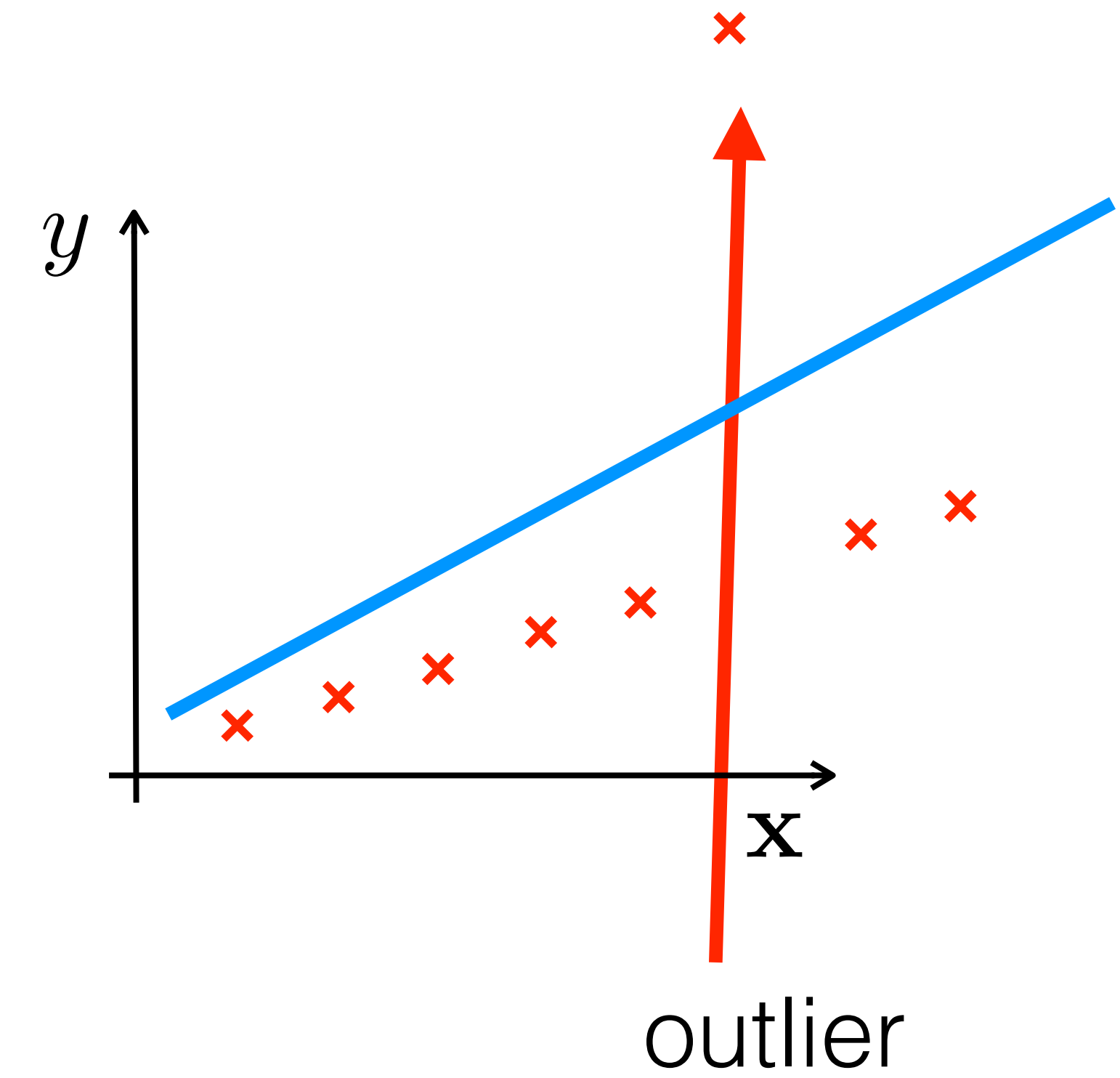
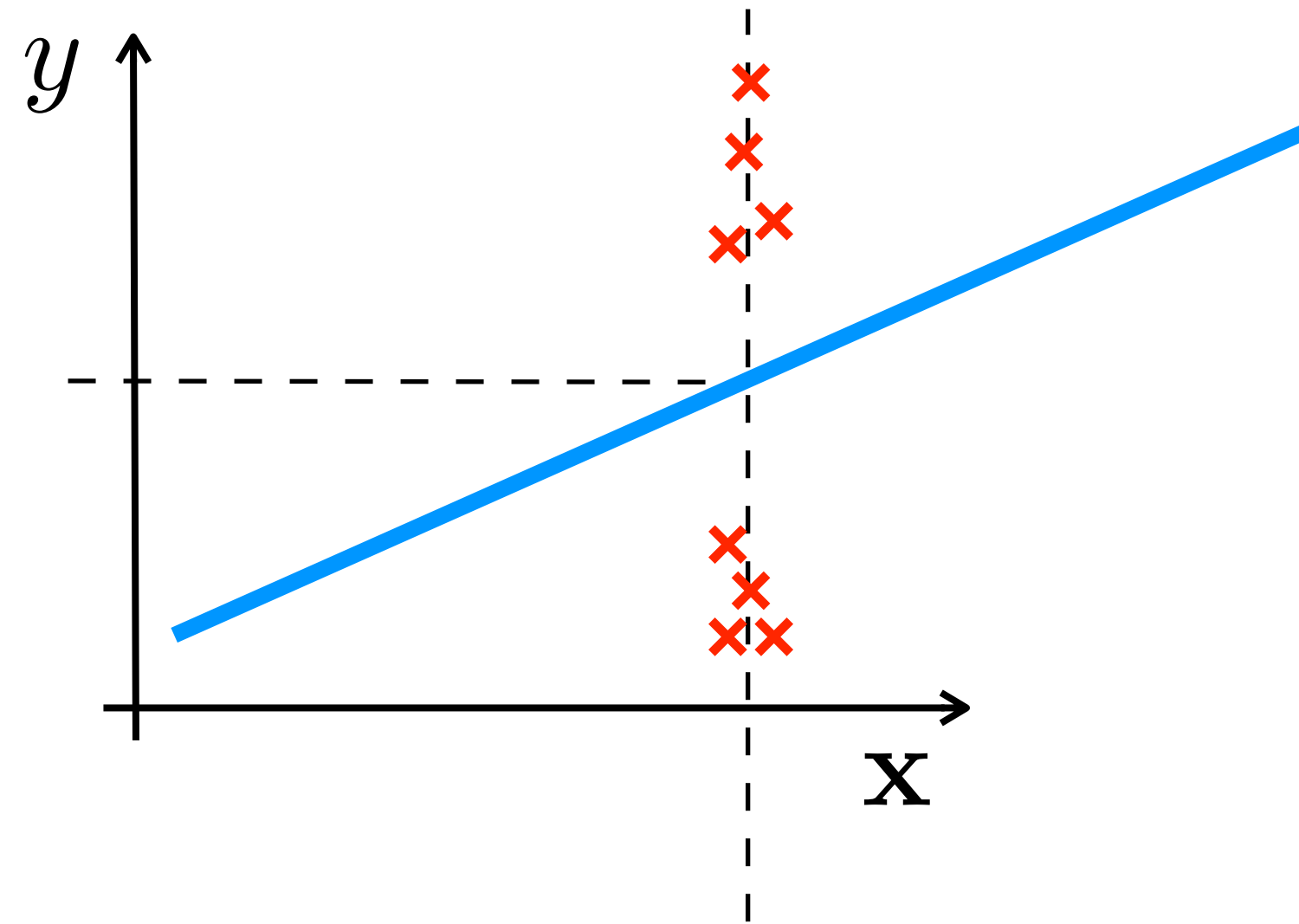


too big learning rate

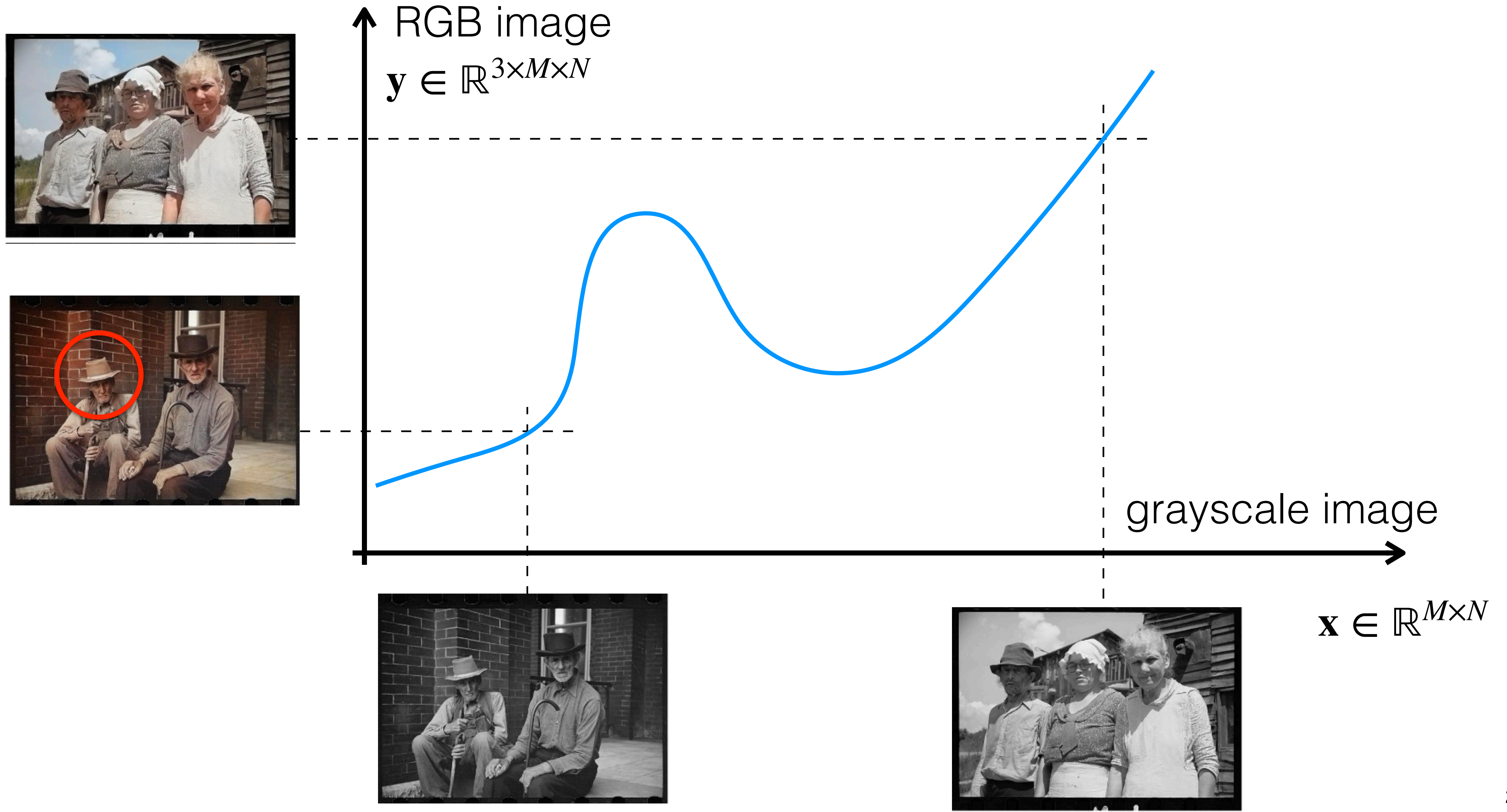


What can go wrong: **inappropriate choice of loss function**

left/right steering



What can go wrong: **inappropriate choice of loss function**

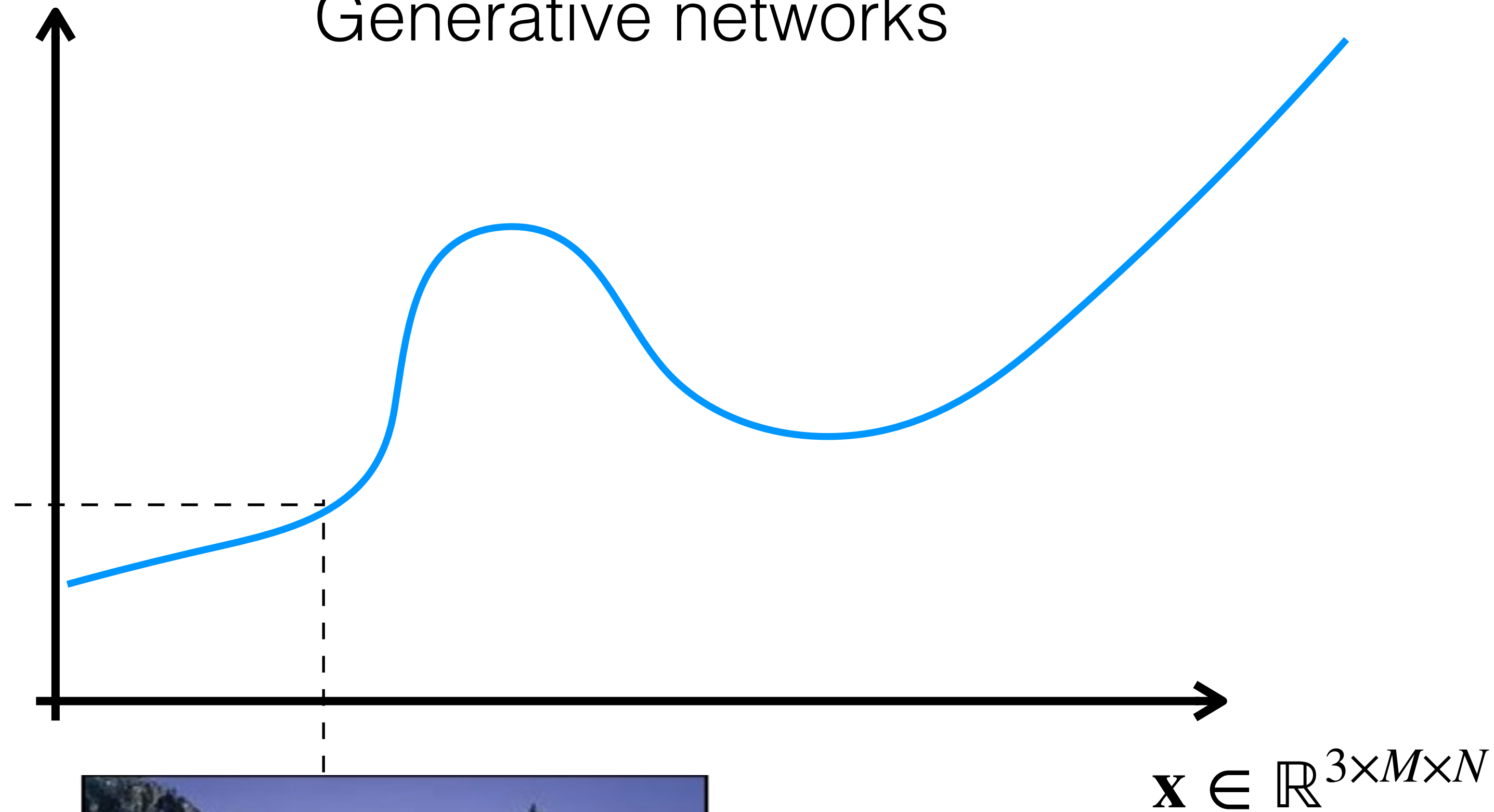


What can go wrong: **inappropriate choice of loss function**

$$\mathbf{y} \in \mathbb{R}^{3 \times M \times N}$$

Generative networks

winter image

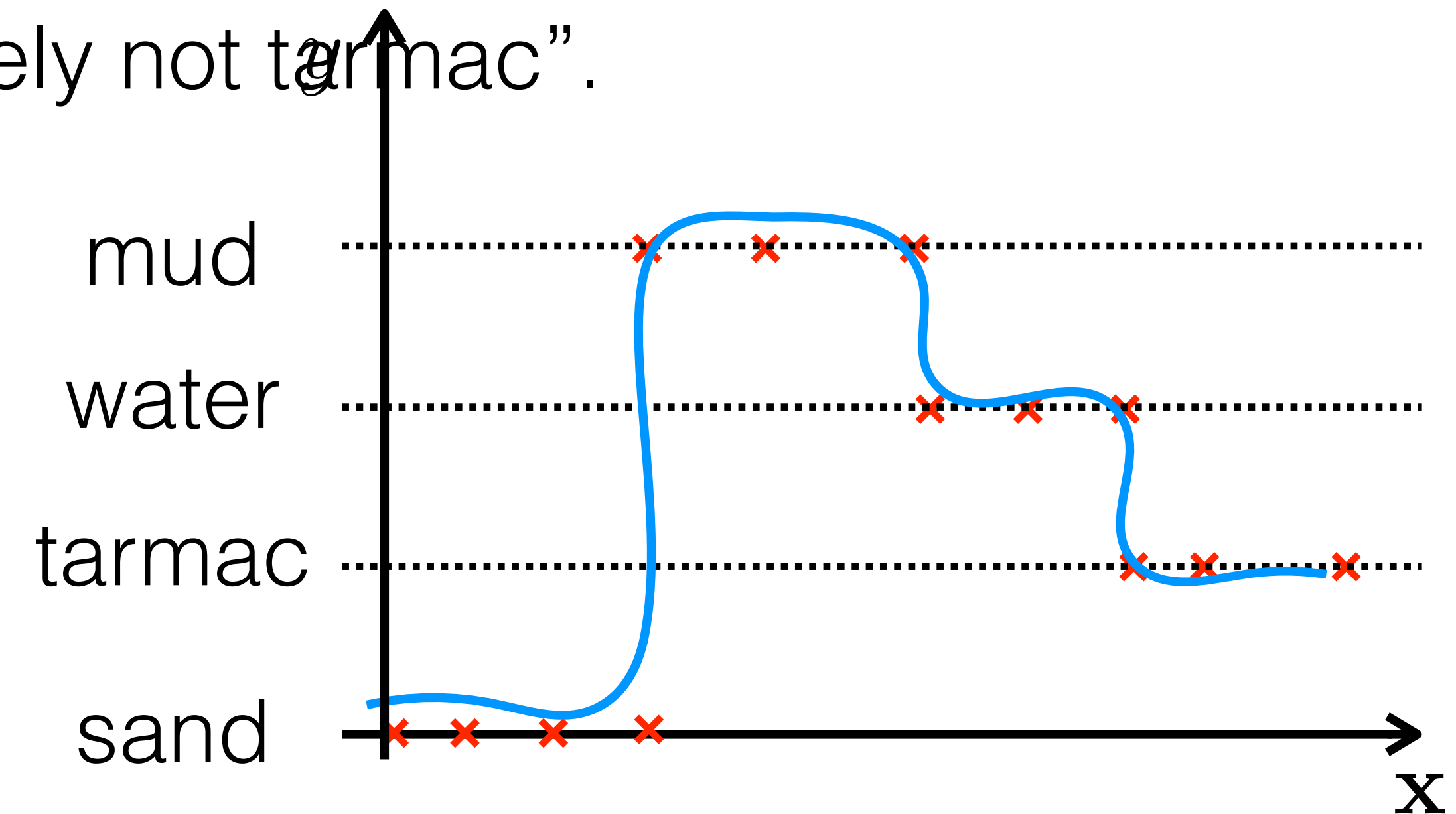
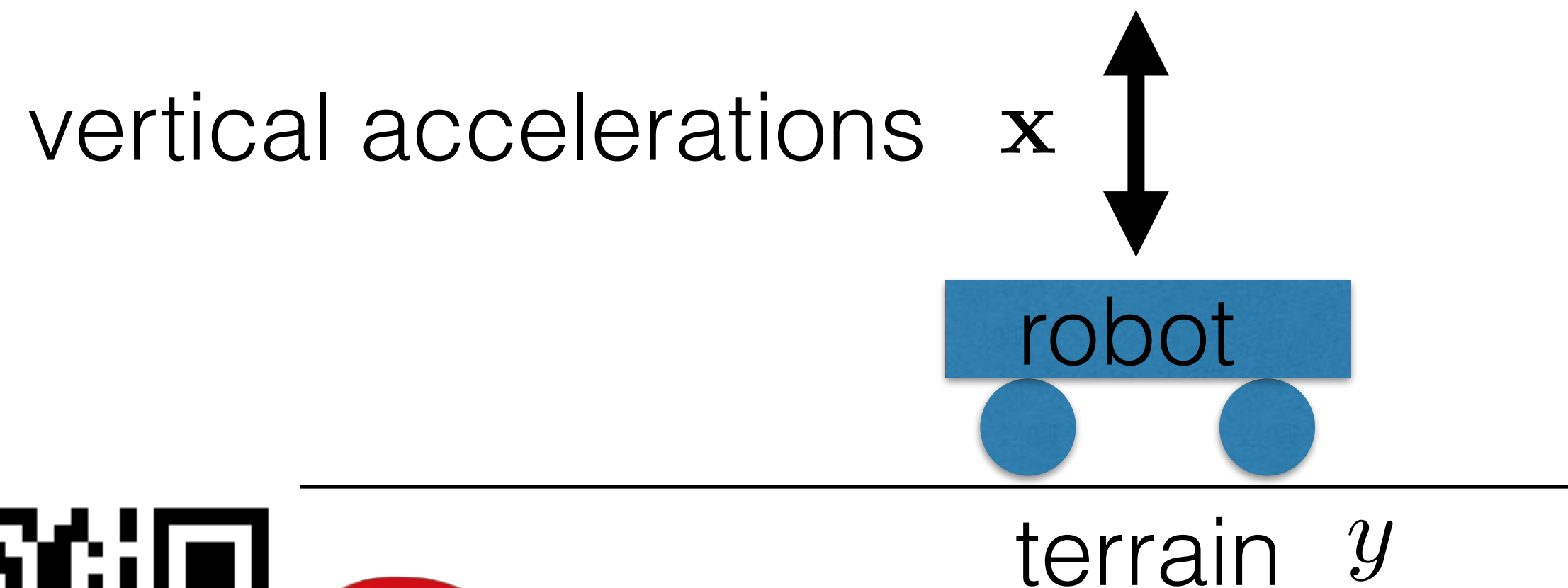


summer image

What can go wrong: **inappropriate choice of architecture**

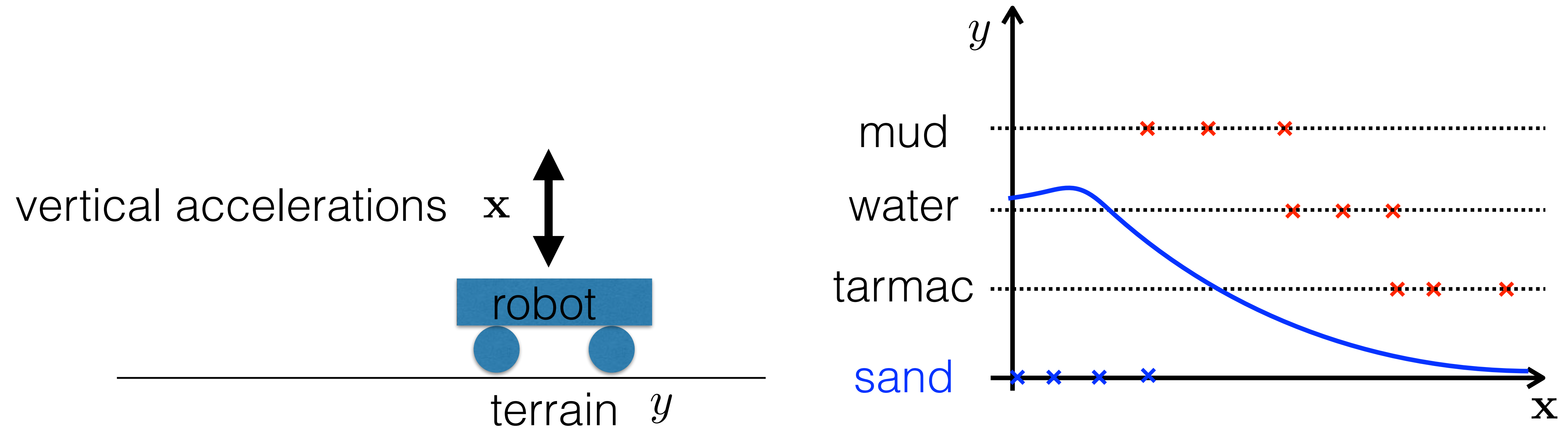
- Can I treat problem as regression?
- Suffers from:
 - complicated optimization,
 - enforced ordering
 - loss for misclasifying mud-to-water << mud-to-sand)
 - cannot model: “mud or sand but definitely not tarmac”.

Motivation example: classification



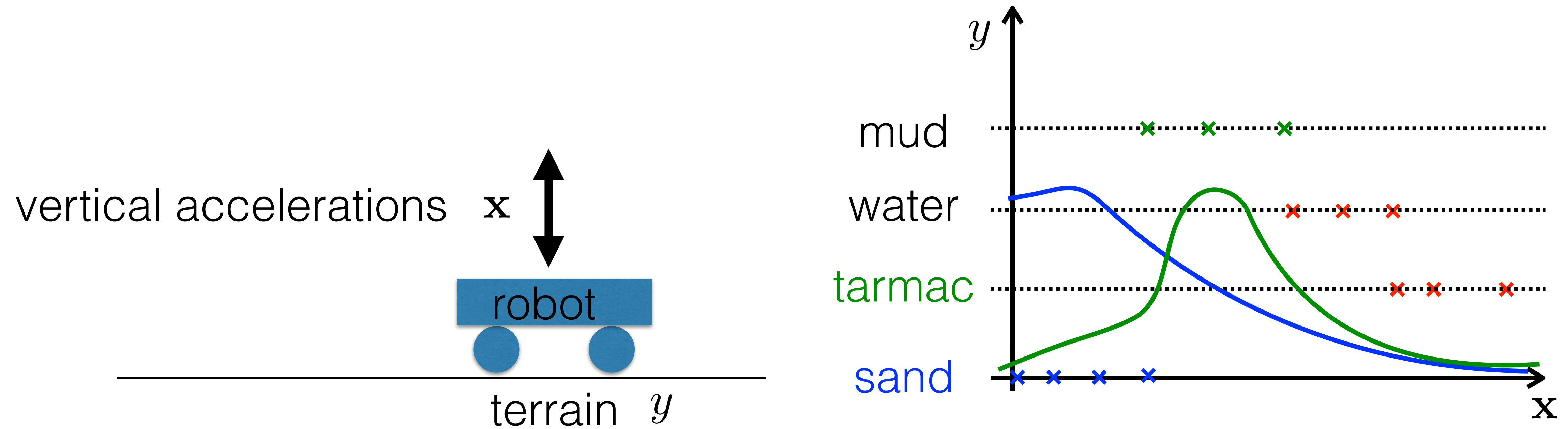
trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

Motivation example: classification



trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

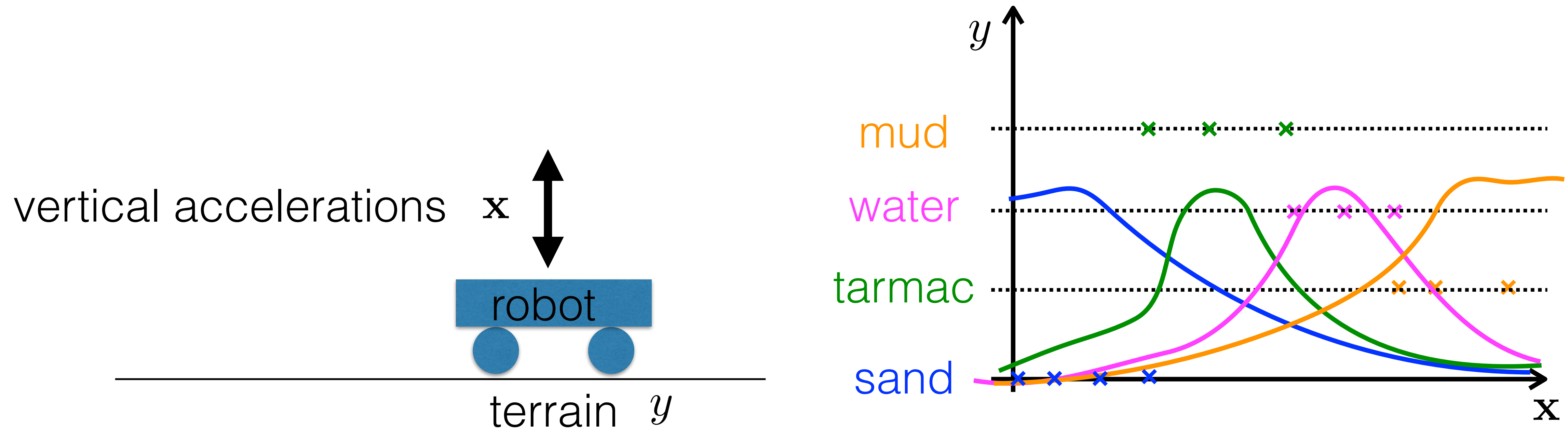
Motivation example: classification



trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

Motivation example: classification

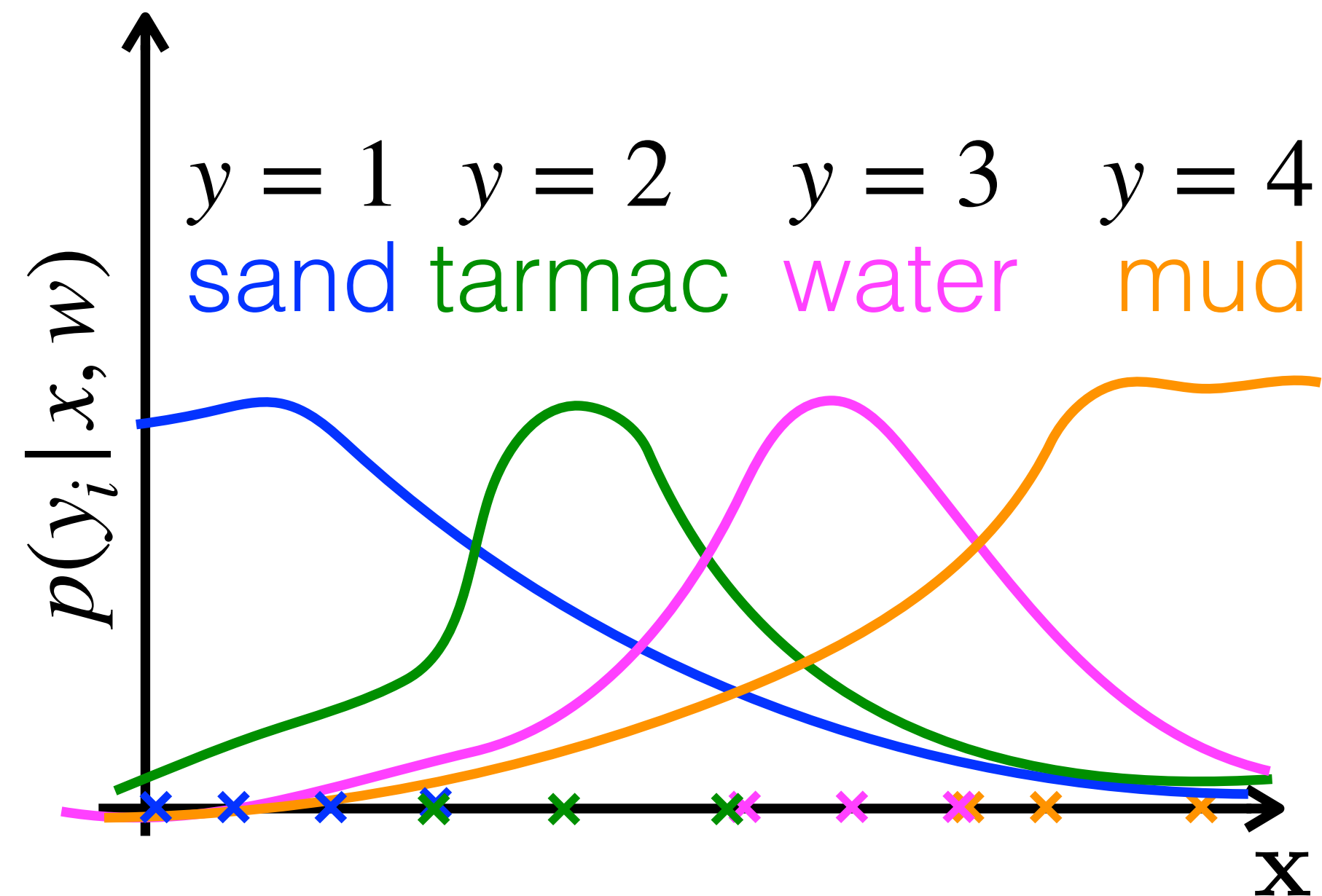
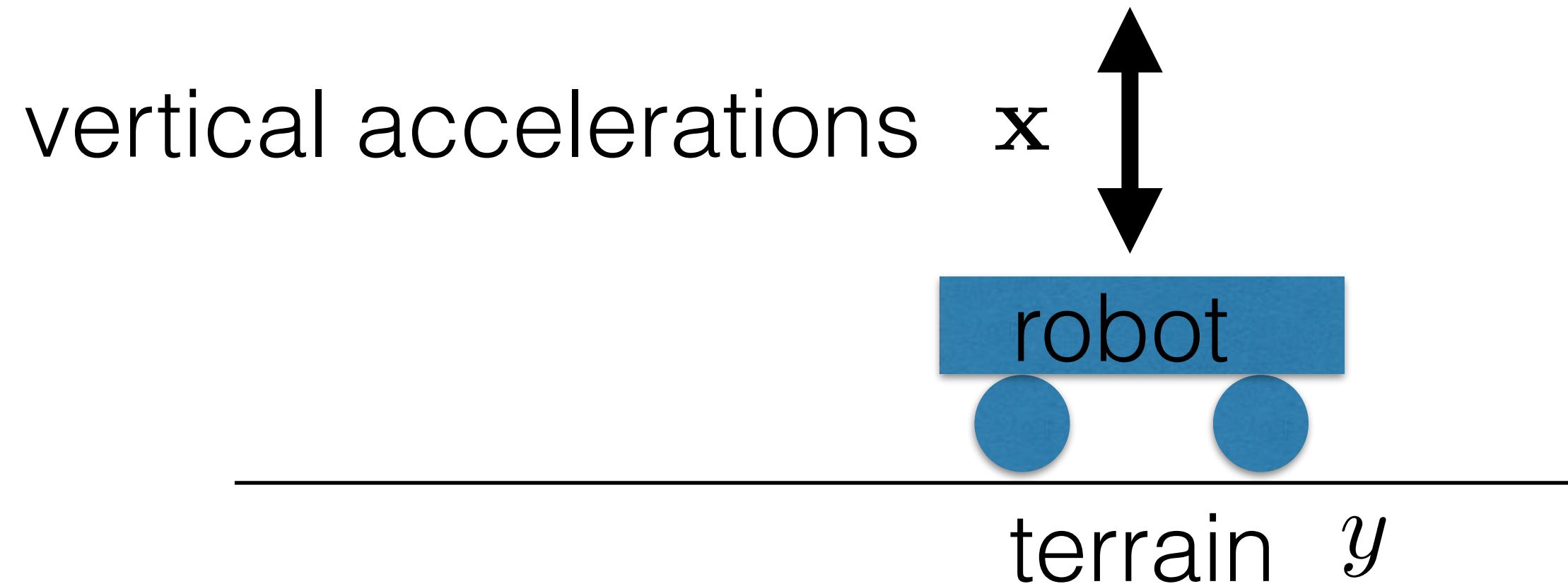
- 4 functions predicting class probabilities $p(y_1 | x, w_1)$, $p(y_2 | x, w_2)$, \dots



trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

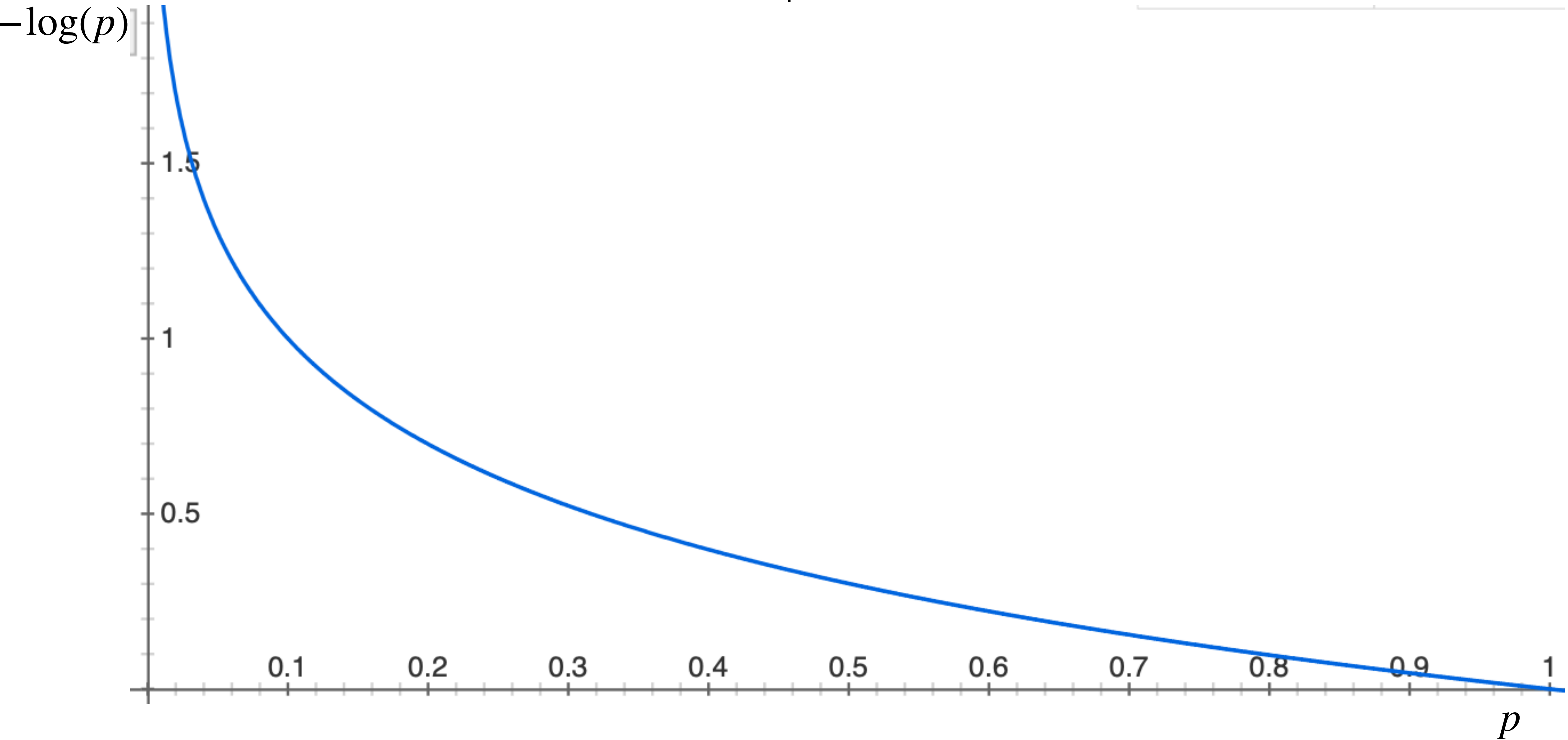
Motivation example: classification

- 4 functions predicting class probabilities $p(y_1 | x, w_1), p(y_2 | x, w_2), \dots$
- that sum up to one over classes for given x $\sum_i p(y_i | x, w) = 1$
- Learning:
 - Substitute blue points to blue function, etc... => “p”
 - Define loss that pushes “p”-values up
- Can you guess a suitable shape of loss function?
 - $\text{loss} = -\log(p)$



trn data: $\mathcal{D} = \{\mathbf{x}_1, y_1 \dots \mathbf{x}_N, y_N\}$

Motivation example: classification



Competencies required for the test T1

- Model (or Architecture/Program) with parameters => learning
- Learning = loss + trn data + optimization procedure
- Evaluation = measuring performance (not necessary loss) on tst data
- What could go wrong?
 - inputs x does not allow to predict y
 - trn/tst data distribution mismatch
 - model does not generalize well
 - learning fails to find good parameters
 - inappropriate choice of loss function
 - inappropriate choice of architecture (overfit, underfit, regression/classification)
- Regression vs Classification
- **Next lecture:** Linear classification of RGB images