

# Linear Models for Regression and Classification, Learning

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# Supervised Learning

A training multi-set of examples is available. Correct answers (hidden state, class, the quantity we want to predict) are *known* for all training examples.

## Classification :

- ▶ Nominal dependent variable
- ▶ Examples: predict spam/ham based on email contents, predict 0/1/.../9 based on the image of a number, etc.

## Regression :

- ▶ Quantitative/continuous dependent variable
- ▶ Examples: predict temperature in Prague based on date and time, predict height of a person based on weight and gender, etc.

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There are more kinds of machine learning:

- Self-supervised
- Unsupervised
- Weakly supervised
- ...

but this lecture will be about fully supervised learning

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# Learning by minimization of empirical risk

- ▶ Given the set of parametrized strategies  $\delta: \mathcal{X} \rightarrow \mathcal{D}$ , penalty/loss function  $\ell: \mathcal{S} \times \mathcal{D} \rightarrow \mathbb{R}$ , the quality of each strategy  $\delta$  could be described by the risk

$$R(\delta) = \sum_{s \in \mathcal{S}} \sum_{x \in \mathcal{X}} P(x, s) \ell(s, \delta(x)),$$

but  $P$  is unknown.

- ▶ We thus use the **empirical risk**  $R_{\text{emp}}$  error on training (multi)set  $\mathcal{T} = \{(x^{(i)}, s^{(i)})\}_{i=1}^N$ ,  $x \in \mathcal{X}$ ,  $s \in \mathcal{S}$ :

$$R_{\text{emp}}(\delta) = \frac{1}{N} \sum_{(x^{(i)}, s^{(i)}) \in \mathcal{T}} \ell(s^{(i)}, \delta(x^{(i)})).$$

- ▶ Optimal strategy  $\delta^* = \operatorname{argmin}_{\delta} R_{\text{emp}}(\delta)$ .
- ▶ We expect the data are from the right distribution.

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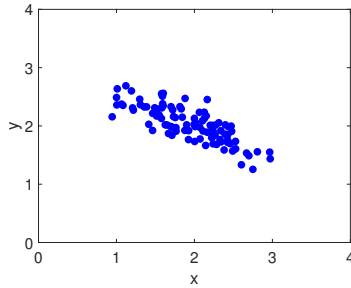
## Notes

Examples of some method: Perceptron, neural networks, classification trees, ...

It is essentially about statistic, out-of distribution data are always problematic. We can help somewhat to make the methods a bit more robust - to generalize more. Remember regularization trick we learned last week (Laplacian smoothing)?

## Quiz: Line fitting

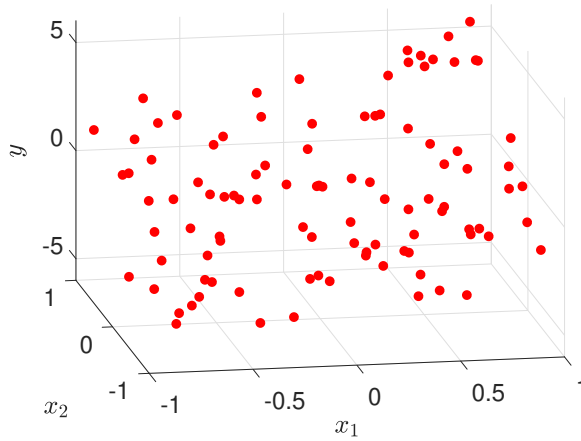
We would like to fit a line of the form  $\hat{y} = w_0 + w_1x$  to the following data:



The parameters of a line with a good fit will likely be

- A  $w_0 = -1, w_1 = -2$
- B  $w_0 = -\frac{1}{2}, w_1 = 1$
- C  $w_0 = 3, w_1 = -\frac{1}{2}$
- D  $w_0 = 2, w_1 = \frac{1}{3}$

# Linear regression: Illustration



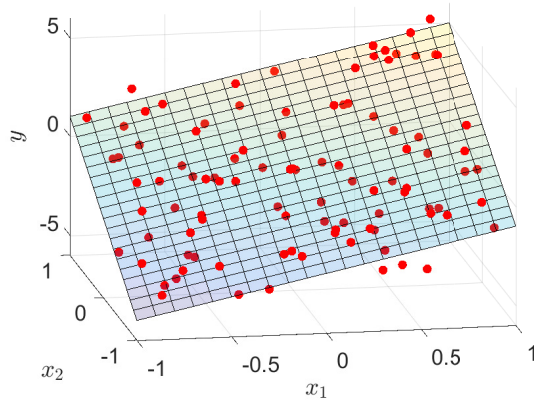
Given a dataset of input vectors  $\mathbf{x}^{(i)}$  and the respective values of output variable  $y^{(i)}$  ...

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## Notes

For instance, think about fitting a plane to Lidar automotive data

# Linear regression: Illustration



... we would like to find a linear model of this dataset ...

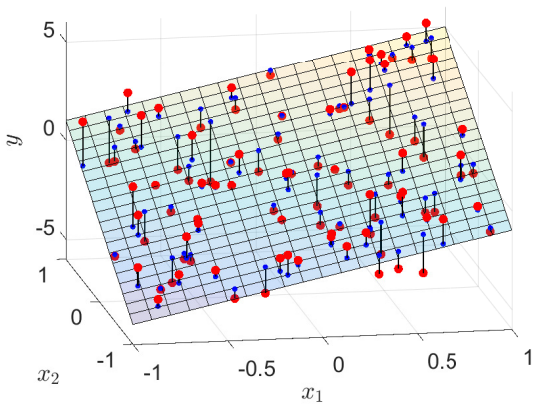
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For instance, think about fitting a plane to Lidar automotive data



# Linear regression: Illustration



... minimizing the errors between target values and the model predictions.

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# Regression

*Reformulating Linear algebra in a machine learning language.*

**Regression task** is a supervised learning task, i.e.

- ▶ a training (multi)set  $\mathcal{T} = \{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(N)}, y^{(N)})\}$  is available, where
- ▶ the labels  $y^{(i)}$  are *quantitative*, often *continuous* (as opposed to classification tasks where  $y^{(i)}$  are nominal).
- ▶ Its purpose is to model the relationship between independent variables (inputs)  $\mathbf{x} = (x_1, \dots, x_D)$  and the dependent variable (output)  $y$ .

# Linear Regression

**Linear regression** is a particular regression model which assumes (and learns) linear relationship between the inputs and the output:

$$\hat{y} = \delta(\mathbf{x}) = w_0 + w_1x_1 + \dots + w_Dx_D = w_0 + \langle \mathbf{w}, \mathbf{x} \rangle = w_0 + \mathbf{w}^\top \mathbf{x},$$

where

- ▶  $\hat{y}$  is the model *prediction* (*estimate* of the true value  $y$ ),
- ▶  $\delta(\mathbf{x})$  is the decision strategy (a linear model in this case),
- ▶  $w_0, \dots, w_D$  are the coefficients of the linear function (weights),  $w_0$  is the *bias*,
- ▶  $\langle \mathbf{w}, \mathbf{x} \rangle$  is a *dot product* of vectors  $\mathbf{w}$  and  $\mathbf{x}$  (scalar product),
- ▶ which can be also computed as a matrix product  $\mathbf{w}^\top \mathbf{x}$  if  $\mathbf{w}$  and  $\mathbf{x}$  are *column vectors*, i.e. matrices of size  $[D \times 1]$ .

## Notation remarks

### Homogeneous coordinates :

- ▶ If we add “1” as the first element of  $\mathbf{x}$  so that  $\mathbf{x} = (1, x_1, \dots, x_D)$ , and
- ▶ include the bias term  $w_0$  in the vector  $\mathbf{w}$  so that  $\mathbf{w} = (w_0, w_1, \dots, w_D)$ , then

$$\hat{y} = \delta(\mathbf{x}) = w_0 \cdot 1 + w_1 x_1 + \dots + w_D x_D = \langle \mathbf{w}, \mathbf{x} \rangle = \mathbf{w}^\top \mathbf{x}.$$

Matrix notation: If we organize the data  $\mathcal{T}$  into matrices  $\mathbf{X}$  and  $\mathbf{y}$ , such that

$$\mathbf{X} = \begin{pmatrix} 1 & \dots & 1 \\ \mathbf{x}^{(1)} & \dots & \mathbf{x}^{(M)} \end{pmatrix} \quad \text{and} \quad \mathbf{y} = (y^{(1)}, \dots, y^{(M)}).$$

and similarly with  $\hat{\mathbf{y}}$ , then we can write a batch computation of predictions for all data in  $\mathbf{X}$  as

$$\hat{\mathbf{y}} = (\delta(\mathbf{x}^{(1)}), \dots, \delta(\mathbf{x}^{(M)})) = (\mathbf{w}^\top \mathbf{x}^{(1)}, \dots, \mathbf{w}^\top \mathbf{x}^{(M)}) = \mathbf{w}^\top \mathbf{X}.$$

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What are dimensions of  $\hat{\mathbf{y}}, \mathbf{w}, \mathbf{X}$ ?

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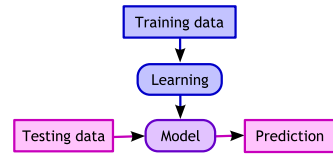
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What are dimensions of  $\hat{\mathbf{y}}, \mathbf{w}, \mathbf{X}$ ?

# Two operation modes

Any ML model has 2 operation modes:

1. learning (training, fitting) of  $\delta$  and
2. application of  $\delta$  (testing, making predictions).



The dec. strategy  $\delta$  can be viewed as a function of 2 variables:  $\delta(x, \mathbf{w})$ .

Model application: ( Inference ) Given  $\mathbf{w}$ , we can manipulate  $x$  to make predictions:

$$\hat{y} = \delta(x, \mathbf{w}) = \delta_{\mathbf{w}}(x).$$

Model learning: Given  $\mathcal{T}$ , we can tune the model parameters  $\mathbf{w}$  to fit the model to the data:

$$\mathbf{w}^* = \underset{\mathbf{w}}{\operatorname{argmin}} R_{\text{emp}}(\delta_{\mathbf{w}}) = \underset{\mathbf{w}}{\operatorname{argmin}} J(\mathbf{w}, \mathcal{T})$$

$J(\mathbf{w}, \mathcal{T})$  and  $\ell(\mathbf{w}, \mathcal{T})$  are closely related. Optimization criterion  $J()$  is a broader term.  $\ell()$  essentially measures discrepancy between true data and the predictions. How to train the model?

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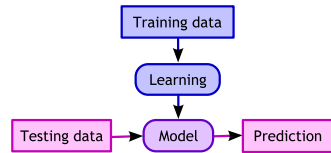
All  $\ell()$  can be used as  $J()$  but not the other way round.

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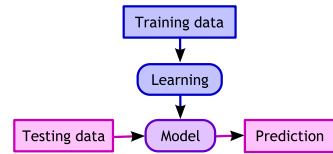
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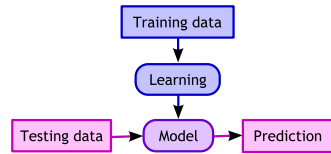
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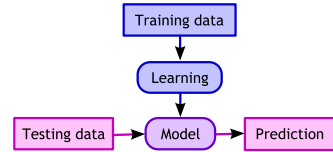
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# Simple (univariate) linear regression

## Simple regression

- ▶  $\mathbf{x}^{(i)} = x^{(i)}$ , i.e., the examples are described by a single feature (they are 1-dimensional).
- ▶ Find parameters  $w_0, w_1$  of a linear model  $\hat{y} = w_0 + w_1 x$  given a training (multi)set  $\mathcal{T} = \{(x^{(i)}, y^{(i)})\}_{i=1}^N$ .

How to fit a line depending on the number of training examples  $N$ :

- ▶  $N = 1$  (1 equation, 2 parameters)  $\Rightarrow \infty$  linear functions with zero error
- ▶  $N = 2$  (2 equations, 2 parameters)  $\Rightarrow 1$  linear function with zero error
- ▶  $N \geq 3$  ( $> 2$  equations, 2 parameters)  $\Rightarrow$  no linear function with zero error (in general)  
 $\Rightarrow$  a line which minimizes the "size" of error  $y - \hat{y}$  can be fitted:

$$\mathbf{w}^* = (w_0^*, w_1^*) = \underset{w_0, w_1}{\operatorname{argmin}} R_{\text{emp}}(w_0, w_1) = \underset{w_0, w_1}{\operatorname{argmin}} J(w_0, w_1, \mathcal{T}).$$

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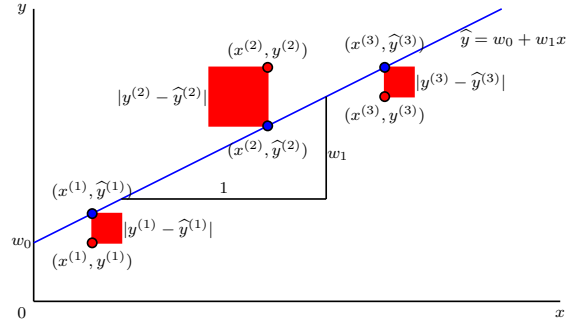
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# The least squares method

Choose such parameters  $\mathbf{w}$  which minimize the *mean squared error* (MSE)

$$\begin{aligned} J_{MSE}(\mathbf{w}) &= \frac{1}{N} \sum_{i=1}^N \left( y^{(i)} - \hat{y}^{(i)} \right)^2 \\ &= \frac{1}{N} \sum_{i=1}^N \left( y^{(i)} - \delta_{\mathbf{w}}(\mathbf{x}^{(i)}) \right)^2. \end{aligned}$$



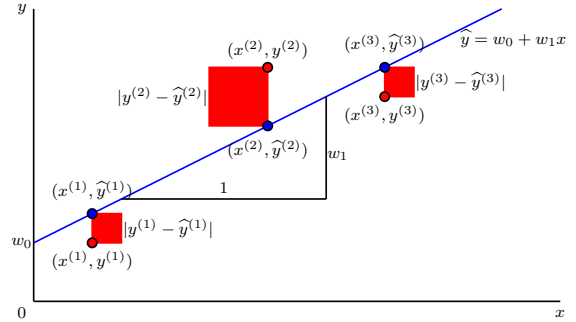
Is there a (closed-form) solution? Explicit solution:

$$w_1 = \frac{\sum_{i=1}^N (x^{(i)} - \bar{x})(y^{(i)} - \bar{y})}{\sum_{i=1}^N (x^{(i)} - \bar{x})^2} = \frac{s_{xy}}{s_x^2} = \frac{\text{covariance of } X \text{ and } Y}{\text{variance of } X} \quad w_0 = \bar{y} - w_1 \bar{x}$$

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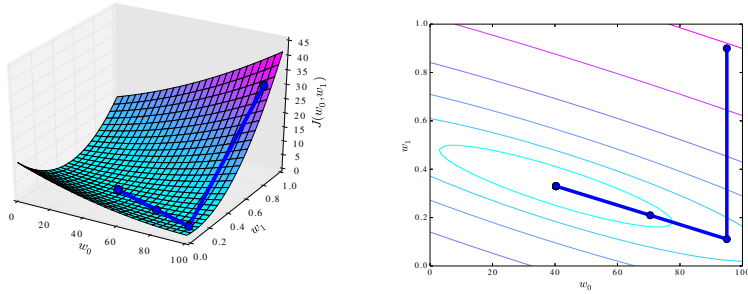


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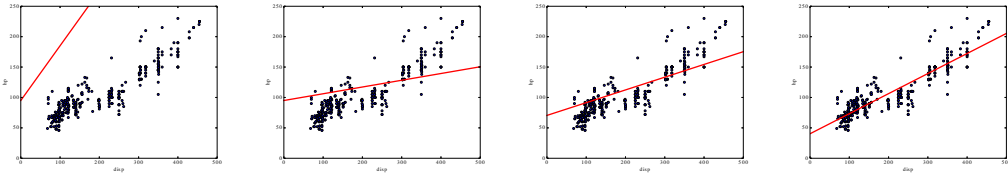
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# Universal fitting method: minimization of cost function $J$

The landscape of  $J$  in the space of parameters  $w_0$  and  $w_1$ :



Gradually better linear models found by an optimization method (BFGS):



## Notes

Bottom images from left to right correspond to points on the polyline above.

# Gradient descent algorithm

Given a function  $J(w_0, w_1)$  that should be minimized,

- ▶ start with a guess of  $w_0$  and  $w_1$  and
- ▶ change it, so that  $J(w_0, w_1)$  decreases, i.e.
- ▶ update our current guess of  $w_0$  and  $w_1$  by taking a step in the direction opposite to the gradient:

$$\mathbf{w} \leftarrow \mathbf{w} - \alpha \nabla J(w_0, w_1), \text{ i.e.}$$

$$w_i \leftarrow w_i - \alpha \frac{\partial}{\partial w_i} J(w_0, w_1),$$

where all  $w_i$ s are updated simultaneously and  $\alpha$  is a **learning rate** (step size).



# Gradient descent for MSE minimization

For the cost function

$$J(w_0, w_1) = \frac{1}{N} \sum_{i=1}^N \left( y^{(i)} - \delta_{\mathbf{w}}(x^{(i)}) \right)^2 = \frac{1}{N} \sum_{i=1}^N \left( y^{(i)} - (w_0 + w_1 x^{(i)}) \right)^2,$$

the gradient can be computed as

$$\frac{\partial}{\partial w_0} J(w_0, w_1) = -\frac{2}{N} \sum_{i=1}^N \left( y^{(i)} - \delta_{\mathbf{w}}(x^{(i)}) \right)$$

$$\frac{\partial}{\partial w_1} J(w_0, w_1) = -\frac{2}{N} \sum_{i=1}^N \left( y^{(i)} - \delta_{\mathbf{w}}(x^{(i)}) \right) x^{(i)}$$

# Multivariate linear regression

- ▶  $\mathbf{x}^{(i)} = (x_1^{(i)}, \dots, x_D^{(i)})^\top$ , i.e. the examples are described by more than 1 feature (they are  $D$ -dimensional).
- ▶ Find parameters  $\mathbf{w} = (w_0, \dots, w_D)^\top$  of a linear model  $\hat{y} = \mathbf{w}^\top \mathbf{x}$  given the training (multi)set  $\mathcal{T} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^N$ .

Training: foreach ( $i$ ):  $y^{(i)} = \mathbf{w}^\top \mathbf{x}^{(i)}$ .

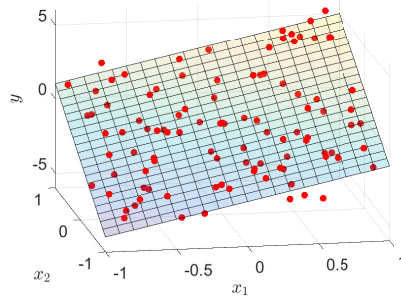
In the matrix form:

$$\mathbf{y} = \mathbf{w}^\top \mathbf{X}$$

What is the dimension of  $\mathbf{X}$ ?

- A  $(D+1) \times (D+1)$
- B  $(D+1) \times N$
- C  $N \times (D+1)$
- D  $N \times N$

The model is a *hyperplane* in the  $(D+1)$  dimensional space.



## Notes

Re-write set of ( $i$ ) equations in to a matrix form:

$$\mathbf{y} = \mathbf{w}^\top \mathbf{X}$$

Inspect dimensions, how are the elements constructed? Quiz

# Multivariate linear regression

- ▶  $\mathbf{x}^{(i)} = (x_1^{(i)}, \dots, x_D^{(i)})^\top$ , i.e. the examples are described by more than 1 feature (they are  $D$ -dimensional).
- ▶ Find parameters  $\mathbf{w} = (w_0, \dots, w_D)^\top$  of a linear model  $\hat{y} = \mathbf{w}^\top \mathbf{x}$  given the training (multi)set  $\mathcal{T} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^N$ .

Training: foreach ( $i$ ):  $y^{(i)} = \mathbf{w}^\top \mathbf{x}^{(i)}$ .

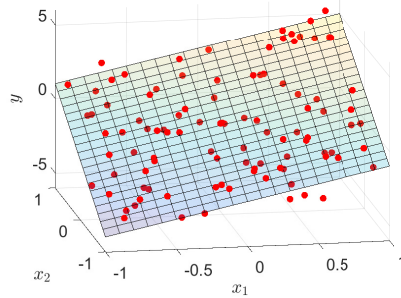
In the matrix form:

$$\mathbf{y} = \mathbf{w}^\top \mathbf{X}$$

What is the dimension of  $\mathbf{X}$ ?

- A  $(D + 1) \times (D + 1)$
- B  $(D + 1) \times N$
- C  $N \times (D + 1)$
- D  $N \times N$

The model is a *hyperplane* in the  $(D + 1)$  dimensional space.



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## Notes

Re-write set of ( $i$ ) equations in to a matrix form:

$$\mathbf{y} = \mathbf{w}^\top \mathbf{X}$$

Inspect dimensions, how are the elements constructed? Quiz

# Multivariate linear regression: learning

## 1. Numeric optimization of $J(\mathbf{w}, T)$ :

- ▶ Works as for simple regression, it only searches a space with more dimensions.
- ▶ Sometimes one needs to tune some parameters of the optimization algorithm to work properly (learning rate in gradient descent, etc.).
- ▶ May be slow (many iterations needed), but works even for very large  $D$ .

## 2. Normal equation:

$$\mathbf{w}^* = (\mathbf{X}\mathbf{X}^T)^{-1}\mathbf{X}\mathbf{y}^T$$

- ▶ Method to solve for the optimal  $\mathbf{w}^*$  analytically!
- ▶ No need to choose optimization algorithm parameters. No iterations.
- ▶ Needs to compute  $(\mathbf{X}\mathbf{X}^T)^{-1}$ , which is  $O((D+1)^3)$ . Becomes intractable for large  $D$ .

---

### Notes

$D$  could be quite big! Think about pixel values in images! We, humans are used to low dimensions - world is 3D, not the machine.

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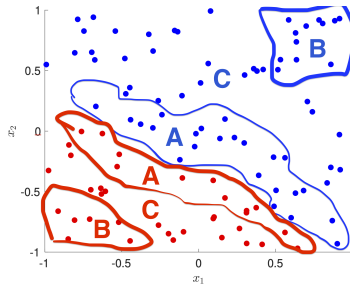
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# Classification

- ▶ Binary classification
- ▶ Discriminant function
- ▶ Classification as a regression problem (linear, logistic regression)
- ▶ What is the right loss function?
- ▶ Etalon classifier (meeting nearest neighbour and linear classifier)
- ▶ Accuracy vs precision

## Quiz: Importance of training examples



Intuitively, which of the training data points should have the biggest influence on the decision whether a new, unlabeled data point shall be red or blue?

- A Those which are closest to data points with the opposite color.
- B Those which are farthest from the data points of the opposite color.
- C Those which are near the middle of the points with the same color.
- D None. All of the data points have the same importance.

---

### Notes

TS note: A,B,C can be visualized as areas in the figure

# Binary classification task

Let's have a training dataset  $T = \{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(N)}, y^{(N)})\}$ :

- ▶ each example described by a vector  $\mathbf{x} = (x_1, \dots, x_D)$ ,
- ▶ labeled with the correct class  $y \in \{+1, -1\}$ .

The goal:

- ▶ Find the classifier (decision strategy/rule)  $\delta$  that minimizes the empirical risk  $R_{\text{emp}}(\delta)$ .



# Discriminant function

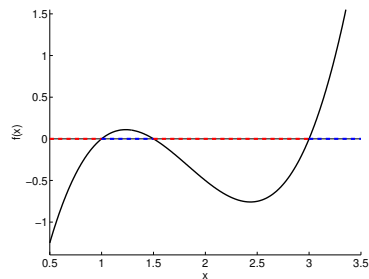
## Discriminant function $f(\mathbf{x})$ :

- ▶ It assigns a real number to each observation  $\mathbf{x}$ , may be linear or non-linear.
- ▶ For 2 classes, 1 discriminant function is enough.
- ▶ It is used to create a **decision rule** (which then assigns a class to an observation):

$$\hat{y} = \delta(\mathbf{x}) = \begin{cases} +1 & \text{iff } f(\mathbf{x}) > 0, \text{ and} \\ -1 & \text{iff } f(\mathbf{x}) < 0. \end{cases}$$

i.e.  $\hat{y} = \delta(\mathbf{x}) = \text{sign}(f(\mathbf{x}))$ .

- ▶ Decision boundary:  $\{\mathbf{x} | f(\mathbf{x}) = 0\}$
- ▶ Linear classification: the decision boundaries must be linear.
- ▶ *Learning* then amounts to finding (suitable parameters of) function  $f$ .



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## Notes

Linearity is required for the decision boundary not for the discriminant function itself!

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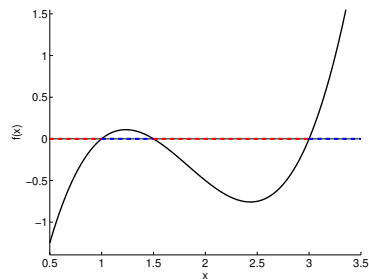
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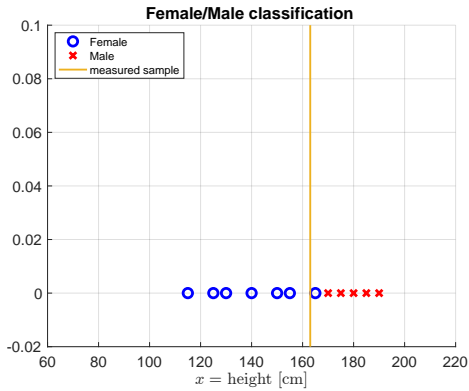
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Linearity is required for the decision boundary not for the discriminant function itself!

# Example: Female/Male classification based on height

Training (multi)set  $\mathcal{T} = \{(x^{(i)}, s^{(i)})\}_{i=1}^N$ ,  $x^{(i)} \in \mathcal{X}$ ,  $s^{(i)} \in \mathcal{S} = \{F, M\}$

$i$	1	2	3	4	5	6	7	8	9	10	11	12
Height $x^{(i)}$	115	125	130	140	150	155	165	170	175	180	185	190
Gender $s^{(i)}$	F	F	F	F	F	F	F	M	M	M	M	M



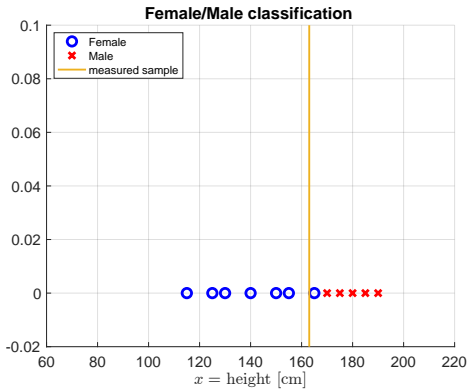
## Notes

Run `onedim_linclass_learning`

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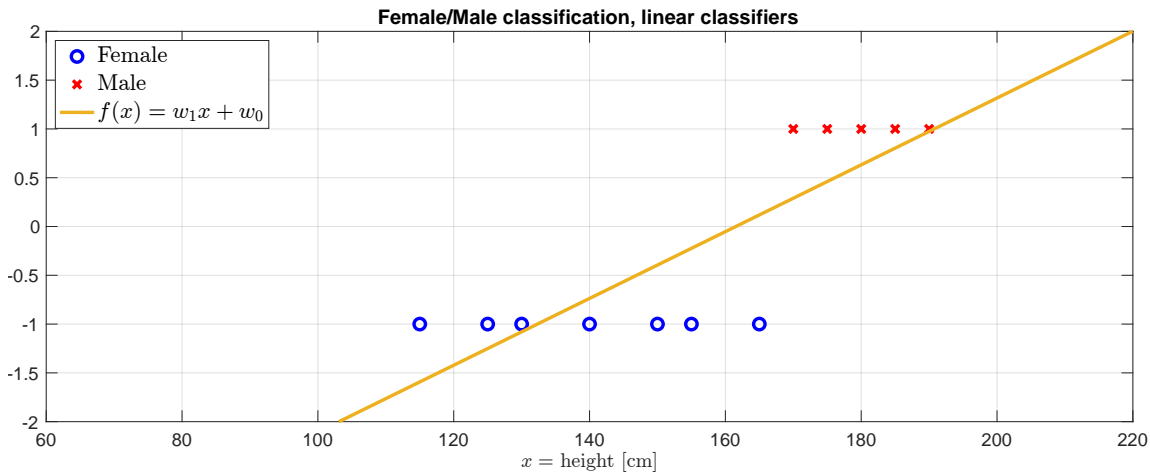
A new point to classify:  $x^Q = 163$

Which class does  $x^Q$  belong to?  $d^Q = ?$

## Notes

Run `onedim_linclass_learning`

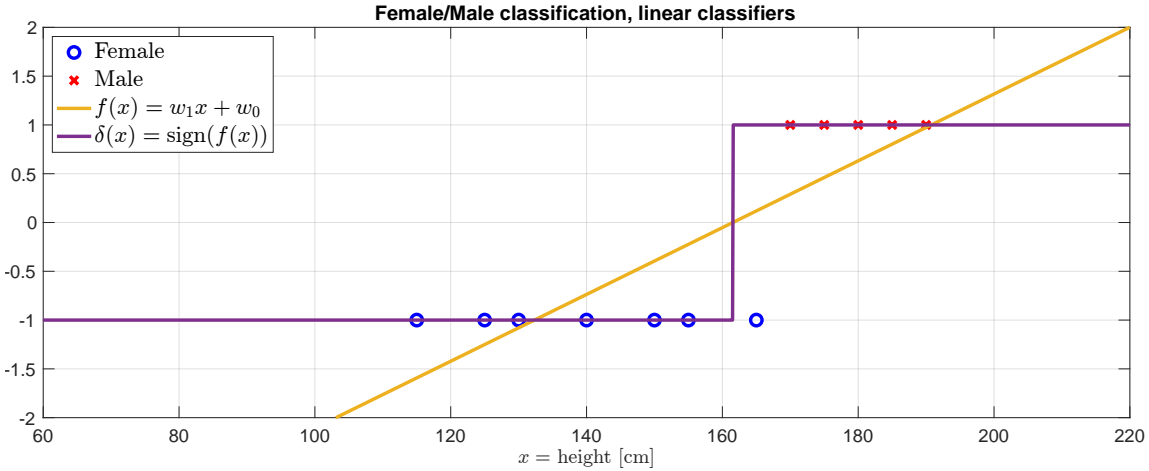
# Linear function LSQ fit



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**Notes**

# Linear function LSQ fit, discriminant function



Notes

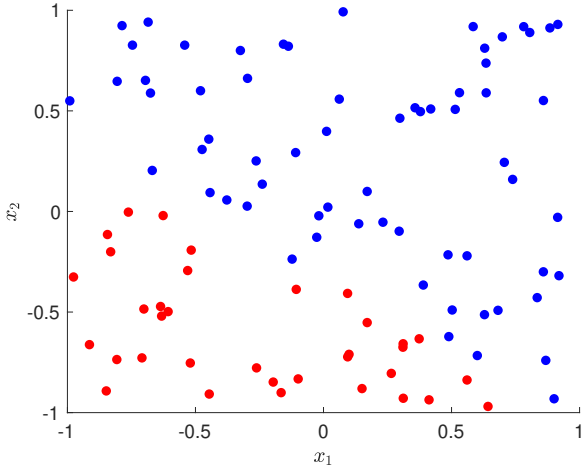
# Can we do better than fitting a linear function?

Recap the naive linear approach first.

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Notes

# Learning linear classifier: naive approach, illustration



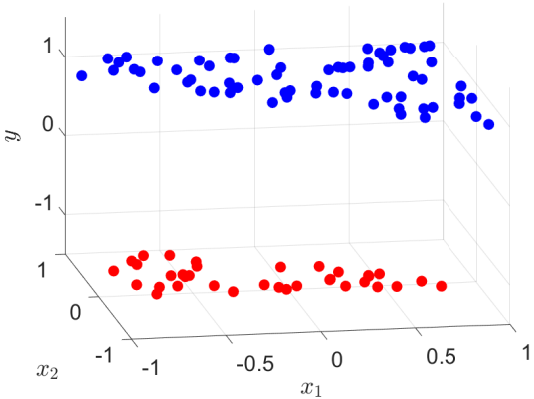
Given a dataset of input vectors  $\mathbf{x}^{(i)}$  and their classes  $y^{(i)}$  ...

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Notes

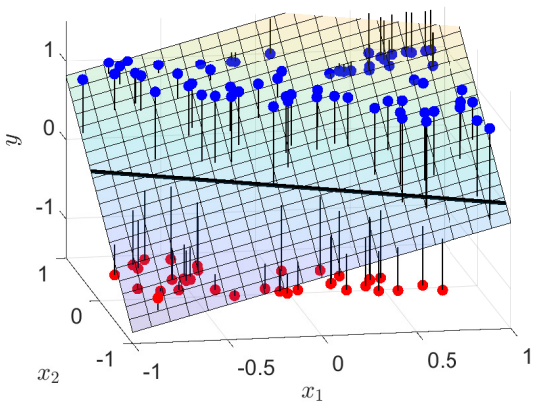


# Learning linear classifier: naive approach, illustration



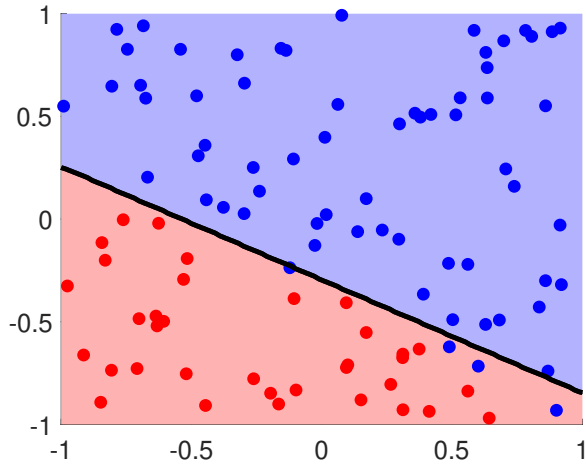
... we shall encode the class label as  $y = -1$  and  $y = 1$  ...

# Learning linear classifier: naive approach, illustration



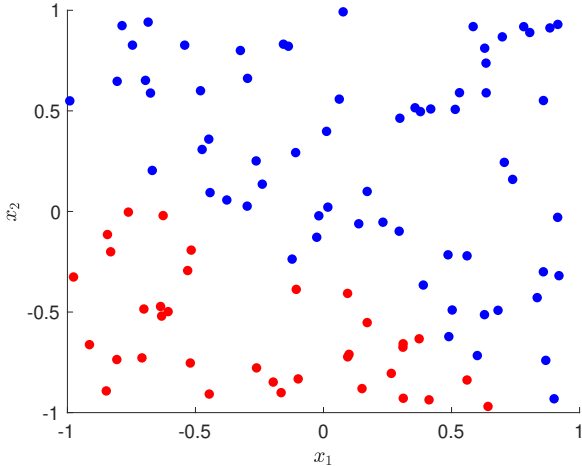
... and fit a linear discriminant function by minimizing MSE as in regression. The contour line  $y = 0$  ...

## Learning linear classifier: naive approach, illustration



... then forms a linear decision boundary in the original 2D space.  
But is such a classifier good in general?

# Fitting a better function: Logistic regression

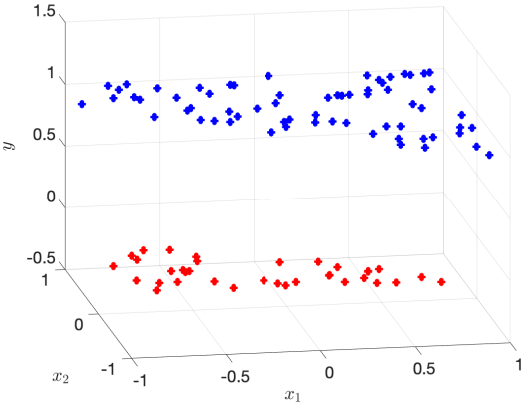


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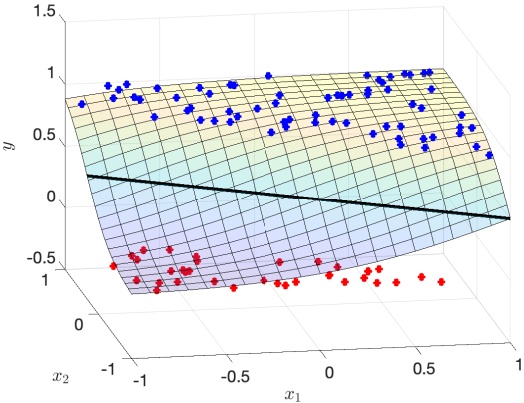
Notes

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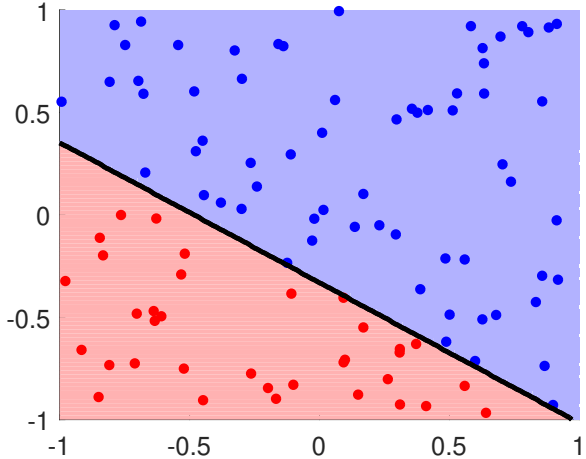
... we shall encode the class label as  $y = 0$  and  $y = 1$  ...

# Fitting a better function: Logistic regression



...and fit a sigmoidal discriminant function with the threshold 0.5 ...

# Fitting a better function: Logistic regression



... which forms a linear decision boundary in the original 2D space.

# Logistic regression model

**Logistic regression** uses a discriminant function which is a nonlinear transformation of the values of a linear function

$$f_{\mathbf{w}}(\mathbf{x}) = g(\mathbf{w}^{\top} \mathbf{x}) = \frac{1}{1 + e^{-\mathbf{w}^{\top} \mathbf{x}}},$$

where  $g(z) = \frac{1}{1 + e^{-z}}$  is the **sigmoid** function (a.k.a **logistic** function).

Interpretation of the model:

- ▶  $f_{\mathbf{w}}(\mathbf{x})$  is interpreted as an estimate of the probability that  $\mathbf{x}$  belongs to class 1.
- ▶ The decision boundary is defined using a different level-set:  $\{\mathbf{x} : f_{\mathbf{w}}(\mathbf{x}) = 0.5\}$ .
- ▶ *Logistic regression is a classification model!*
- ▶ The discriminant function  $f_{\mathbf{w}}(\mathbf{x})$  itself is not linear anymore; but the *decision boundary is still linear!*
- ▶ Thanks to the sigmoidal transformation, logistic regression is much less influenced by examples far from the decision boundary!

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## Notes

Try to draw the course of the function by hand.



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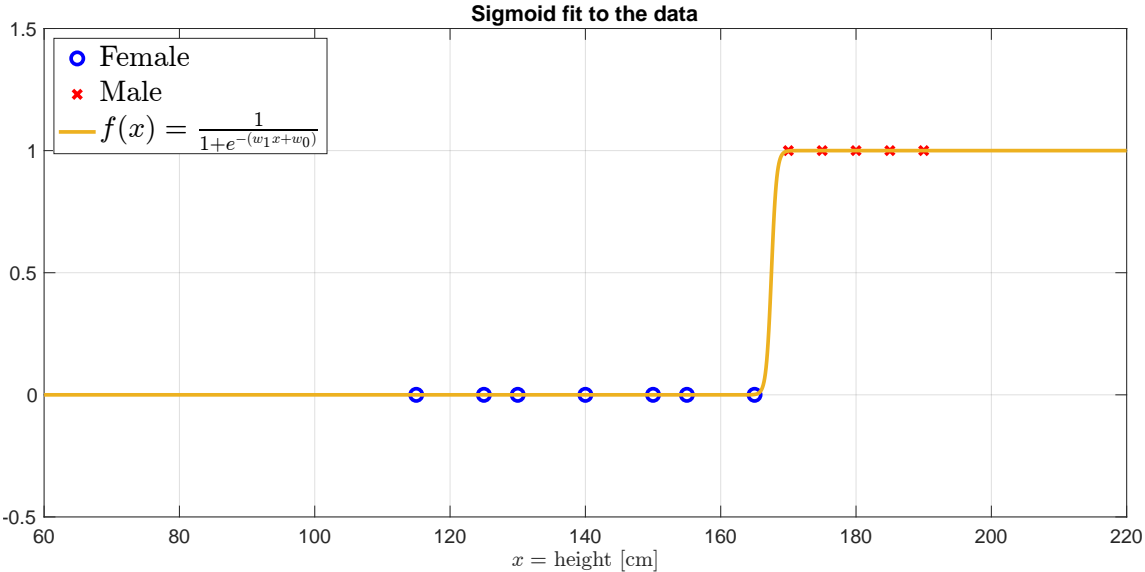
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# Sigmoid LSQ fit

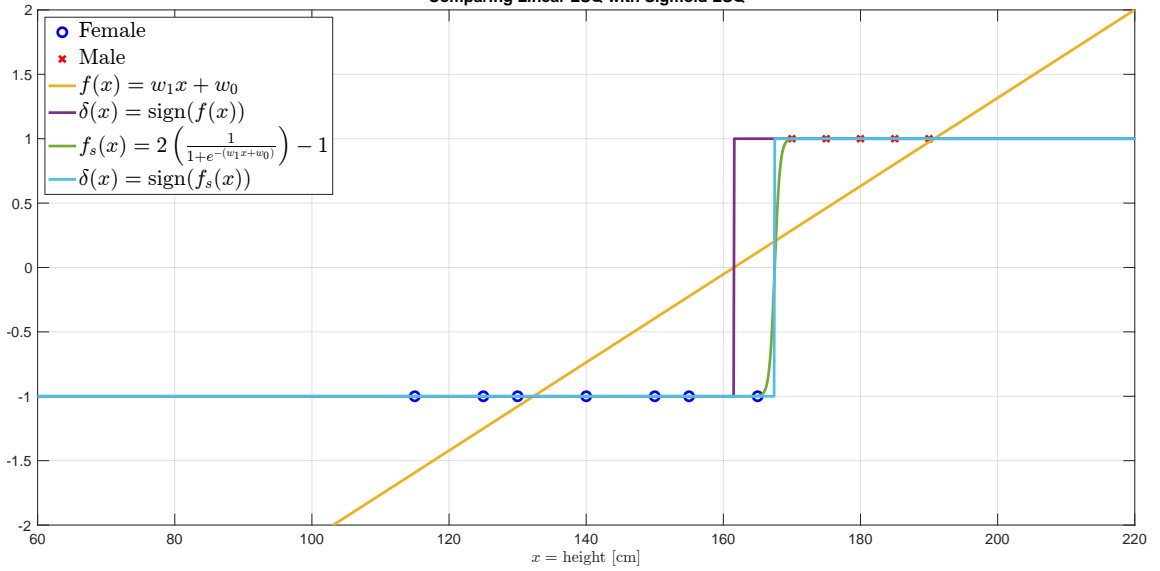


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## Notes

# Comparing Linear and Sigmoid LSQ fit

Comparing Linear LSQ with Sigmoid LSQ



# What is the proper loss function $\ell$ ?

To train the logistic regression model, one can minimize the  $J_{MSE}$  criterion:

- ▶ results in a non-convex, multimodal landscape which is hard to optimize.

Log. reg. uses a loss function called cross-entropy :

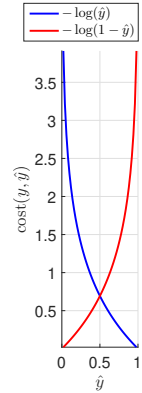
$$J(\mathbf{w}, \mathcal{T}) = \frac{1}{N} \sum_{i=1}^N \ell(y^{(i)}, f_{\mathbf{w}}(\mathbf{x}^{(i)})), \text{ where}$$

$$\ell(y, \hat{y}) = \begin{cases} -\log(\hat{y}) & \text{if } y = 1 \\ -\log(1 - \hat{y}) & \text{if } y = 0 \end{cases}$$

which can be rewritten in a single expression as

$$\ell(y, \hat{y}) = -y \cdot \log(\hat{y}) - (1 - y) \cdot \log(1 - \hat{y}).$$

- ▶ simpler to optimize for numerical solvers.



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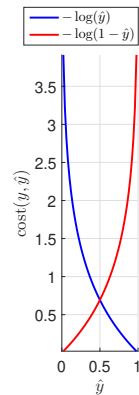
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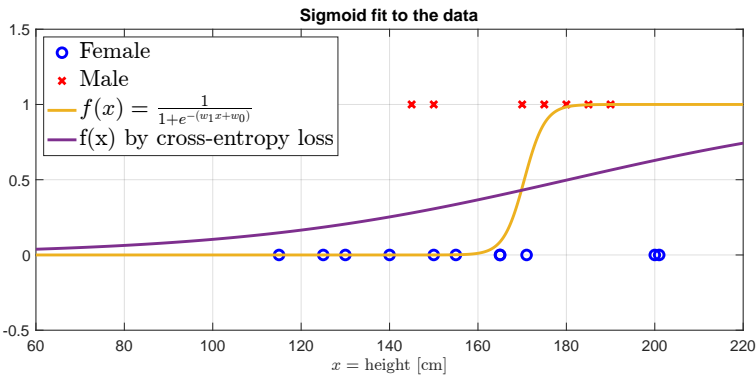
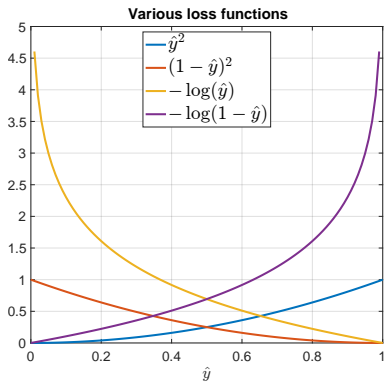
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# MSE vs cross entropy loss



Sigmoidal  $f(x)$  can be also interpreted as  $p(s = \text{Male} | x)$  – Learning **Discriminative model** directly.

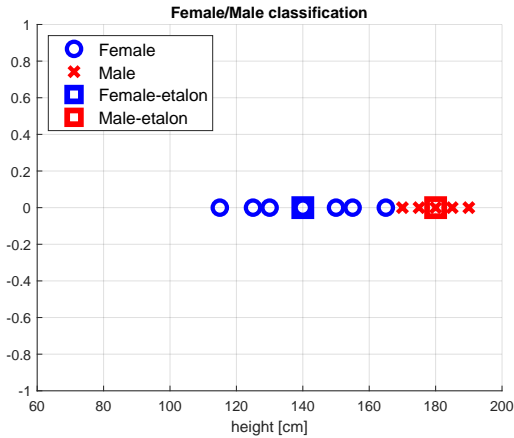
Cross-entropy loss strongly penalizes hard errors, complete mismatches.

---

## Notes

# Alternative idea: F/M classification – Etalons

Represent each class by a single example called *etalon*! (Or by a very small number of etalons.)



$$e_F = \text{ave}(\{x^{(i)} : s^{(i)} = F\}) = 140$$
$$e_M = \text{ave}(\{x^{(i)} : s^{(i)} = M\}) = 180$$

Based on etalons:  $d_Q = ?$

A  $d_Q = F$

B  $d_Q = M$

C Both classes equally likely

D Cannot provide any decision

Classify as  $d^Q = \text{argmin}_{s \in \mathcal{S}} \text{dist}(x^Q, e_s)$

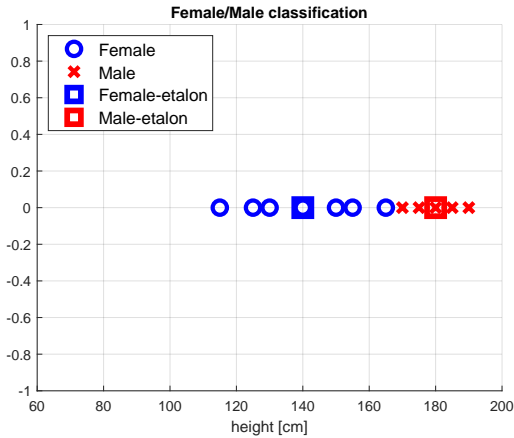
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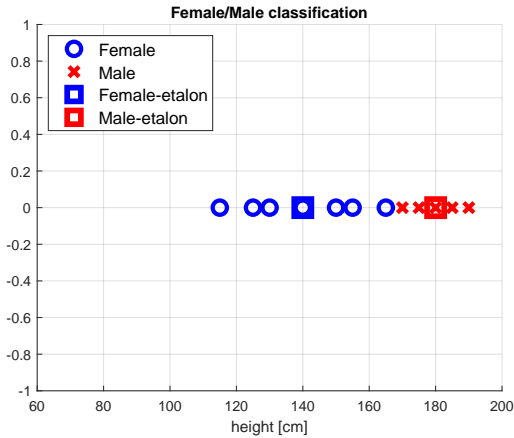
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# Etalon classifier is a Linear classifier

Assuming  $\text{dist}(x, e) = (x - e)^2$ , then

$$\begin{aligned} \operatorname{argmin}_{s \in S} \text{dist}(x, e_s) &= \operatorname{argmin}_{s \in S} (x - e_s)^2 = \operatorname{argmin}_{s \in S} \underbrace{(x^2)}_{\text{const.}} - 2e_s x + e_s^2 = \\ &= \operatorname{argmin}_{s \in S} (-2e_s x + e_s^2) = \operatorname{argmax}_{s \in S} \left( \underbrace{e_s x - \frac{1}{2} e_s^2}_{\text{linear function of } x} \right) \end{aligned}$$

Multiclass classification: each class  $s$  has a linear discriminant function  $f_s(x) = a_s x + b_s$  and

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Binary classification: a single linear discriminant function  $g(x)$  is sufficient and

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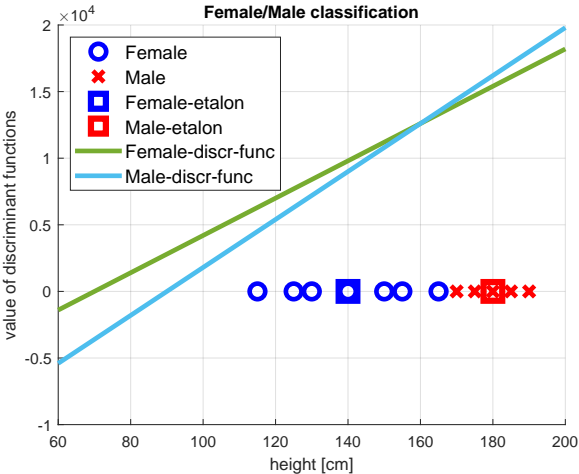
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# Example: F/M – Linear discriminant functions based on etalons

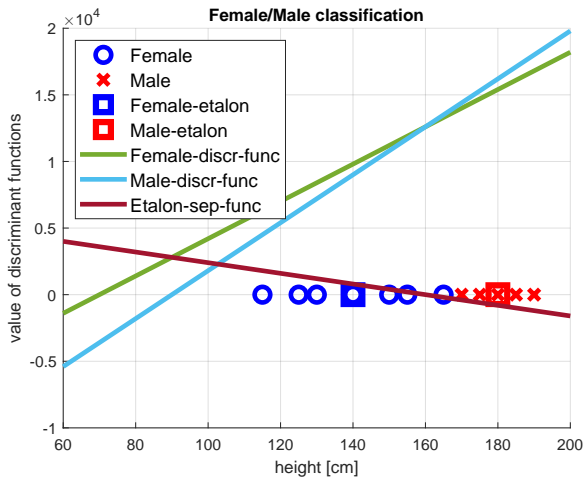


Discriminant functions for 2 classes:

$$\begin{aligned}
 f_F(x) &= a_F x + b_F = \\
 &= e_F x - \frac{1}{2} e_F^2 = 140x - 9800 \\
 f_M(x) &= a_M x + b_M = \\
 &= e_M x - \frac{1}{2} e_M^2 = 180x - 16200
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Notes

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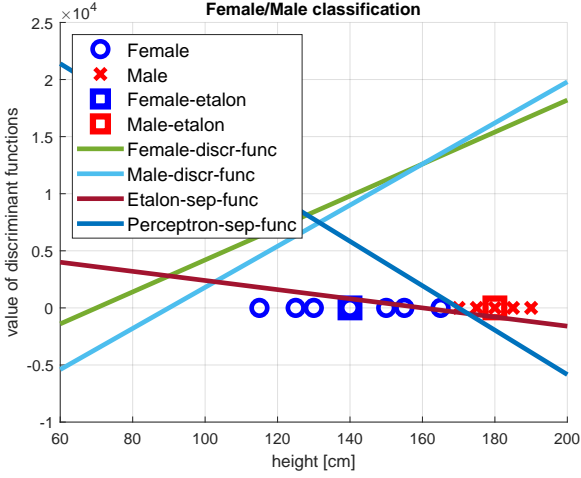
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$$f_M(x) = a_M x + b_M = e_M x - \frac{1}{2} e_M^2 = 180x - 16200$$

A single discriminant function separating 2 classes:

$$g(x) = f_F(x) - f_M(x) = -40x + 6400$$

# Example: F/M – Can we do better etalons?



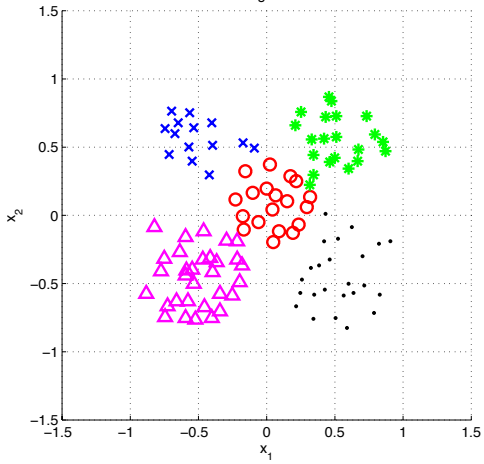
Etalon-based linear classifier makes some errors.

A perceptron algorithm may be used to find a zero-error classifier (if one exists).

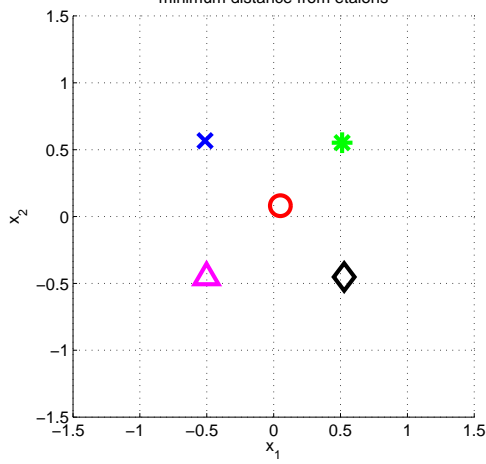
## Notes

# Etaion based classification

Pentagon data



minimum distance from etalons



Represent  $\vec{x}$  by **etalon**,  $\vec{e}_s$  per each class  $s \in S$ .

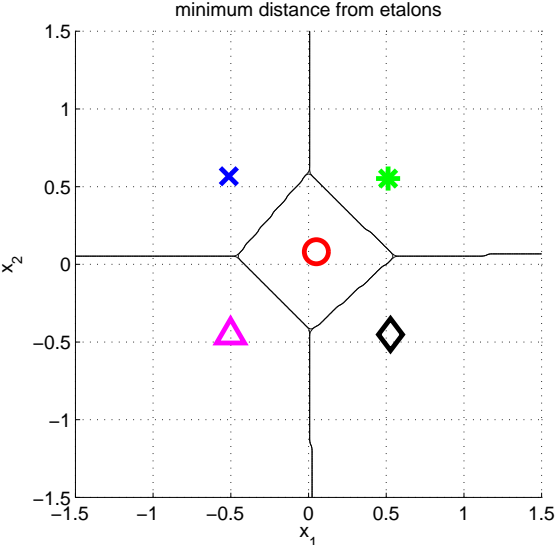
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## Notes



# Separate etalons

$$s^* = \arg \min_{s \in S} \|\vec{x} - \vec{e}_s\|^2$$

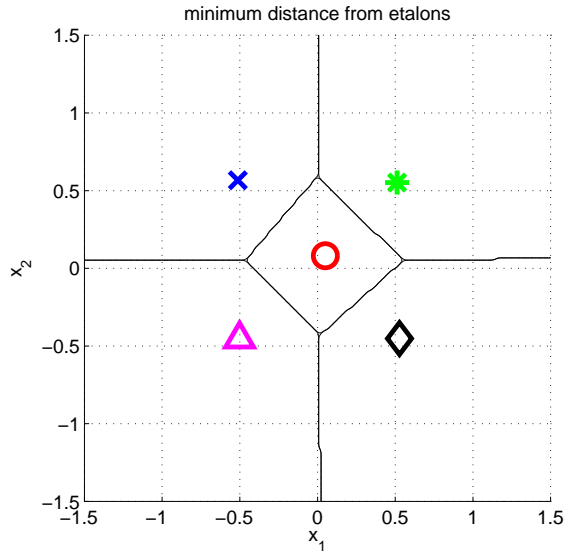


## What etalons?

If  $\mathcal{N}(\vec{x}|\vec{\mu}, \Sigma)$ ; all classes same covariance matrices, then

$$\vec{e}_s \stackrel{\text{def}}{=} \vec{\mu}_s = \frac{1}{|\mathcal{X}^s|} \sum_{i \in \mathcal{X}^s} \vec{x}_i^s$$

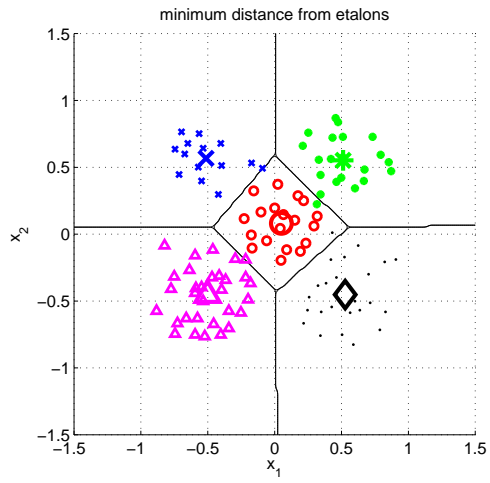
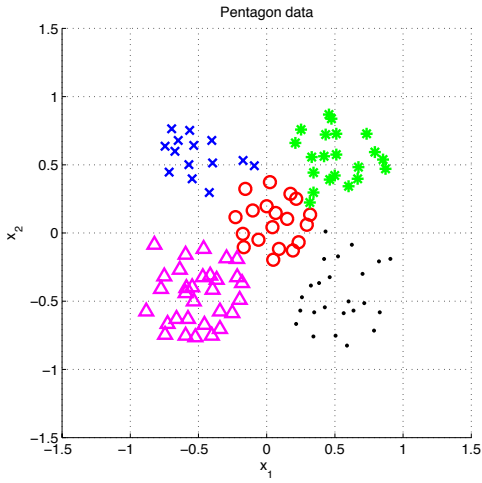
and separating hyperplanes halve distances between pairs.



### Notes

$$\mathcal{N}(\vec{x}|\vec{\mu}, \Sigma) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} \exp\left\{-\frac{1}{2}(\vec{x} - \vec{\mu})^\top \Sigma^{-1}(\vec{x} - \vec{\mu})\right\}$$

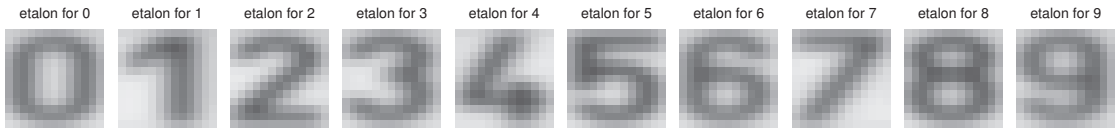
# Etalon based classification, $\vec{e}_s = \vec{\mu}_s$



## Notes

Some wrongly classified samples. We like the simple idea. Are there better etalons? How to find them?

# Digit recognition - etalons $\vec{e}_s = \vec{\mu}_s$



Figures from [7].

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## Notes

Keep in mind, that etalon – mean value is a kind of handcrafted heuristics. In general, it does not optimize (minimize) any loss function.

# Bayesian Discriminant functions $f(\vec{x}, s)$ , $g_s(\vec{x})$

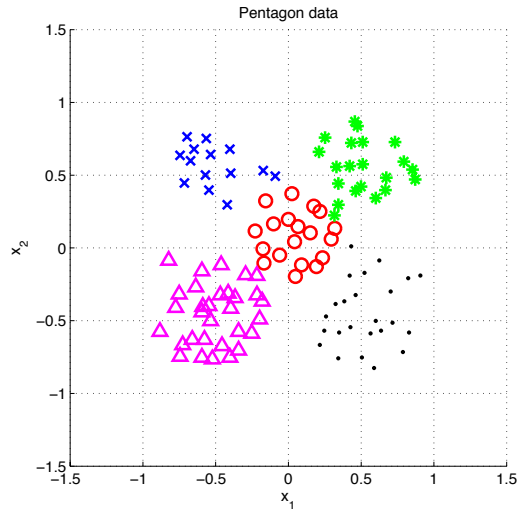
$$s^* = \operatorname{argmax}_{s \in \mathcal{S}} f(\vec{x}, s)$$

Bayes:

$$s^* = \operatorname{argmax}_{s \in \mathcal{S}} P(s|\vec{x}) = \frac{P(\vec{x} | s)P(s)}{P(\vec{x})}$$

Discriminant function:

$$f(\vec{x}, s) = g_s(\vec{x}) = P(\vec{x} | s)P(s)$$



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## Notes

Normal distribution for general dimensionality D:

$$\mathcal{N}(\vec{x}|\vec{\mu}, \Sigma) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} \exp\left\{-\frac{1}{2}(\vec{x} - \vec{\mu})^\top \Sigma^{-1}(\vec{x} - \vec{\mu})\right\}$$

Discriminant function:

$$s^* = \operatorname{argmax}_{s \in \mathcal{S}} f(\vec{x}, s) = P(s)\mathcal{N}(\vec{x}|\vec{\mu}, \Sigma) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\Sigma|^{1/2}} \exp\left\{-\frac{1}{2}(\vec{x} - \vec{\mu})^\top \Sigma^{-1}(\vec{x} - \vec{\mu})\right\}$$

How about learning  $f(\vec{x}, s)$  directly without explicit modeling of underlying probabilities?

What about  $f(\vec{x}, s) = \vec{w}_s^\top \vec{x} + w_{s0}$

# Etalon classifier – Linear classifier, generalization to higher dimensions

$$\begin{aligned} s^* &= \arg \min_{s \in S} \|\vec{x} - \vec{e}_s\|^2 = \arg \min_{s \in S} (\vec{x}^\top \vec{x} - 2 \vec{e}_s^\top \vec{x} + \vec{e}_s^\top \vec{e}_s) = \\ &= \arg \min_{s \in S} \left( \vec{x}^\top \vec{x} - 2 \left( \vec{e}_s^\top \vec{x} - \frac{1}{2} (\vec{e}_s^\top \vec{e}_s) \right) \right) = \\ &= \arg \min_{s \in S} (\vec{x}^\top \vec{x} - 2 (\vec{e}_s^\top \vec{x} + b_s)) = \\ &= \boxed{\arg \max_{s \in S} (\vec{e}_s^\top \vec{x} + b_s)} = \arg \max_{s \in S} g_s(\vec{x}). \end{aligned} \quad b_s = -\frac{1}{2} \vec{e}_s^\top \vec{e}_s$$

Linear function (plus offset)

$$g_s(\mathbf{x}) = \mathbf{w}_s^\top \mathbf{x} + w_{s0}$$

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## Notes

The result is a *linear discriminant function* – hence etalon classifier is a linear classifier.

We classify into the class with highest value of the discriminant function.

$\mathbf{w}_s$  is a generalized etalon. How do we find it? Such that it is better than just the mean of the class members in the training set.

# Learning and decision

**Learning** stage - learning models/function/parameters from data.

**Decision** stage - decide about a query  $\vec{x}$ .

What to learn?

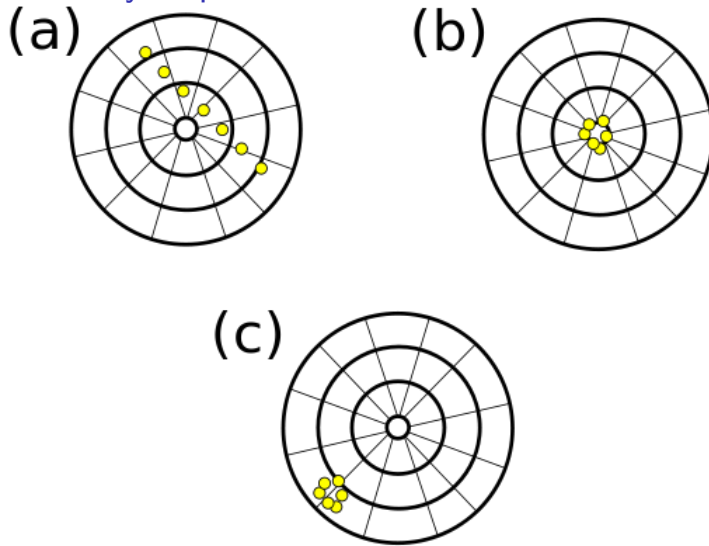
- ▶ **Generative model** : Learn  $P(\vec{x}, s)$ . Decide by computing  $P(s|\vec{x})$ .
- ▶ **Discriminative model** : Learn  $P(s|\vec{x})$ .
- ▶ **Discriminant function** : Learn  $g(\vec{x})$  which maps  $\vec{x}$  directly into class labels.

---

## Notes

Generative models because by sampling from them it is possible to generate synthetic data points  $\vec{x}$ .

## Accuracy vs precision



[https://commons.wikimedia.org/wiki/File:Precision\\_vs\\_accuracy.svg](https://commons.wikimedia.org/wiki/File:Precision_vs_accuracy.svg)

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### Notes

Accuracy: how close (is your model) to the truth. Precision: how consistent/stable

In German:

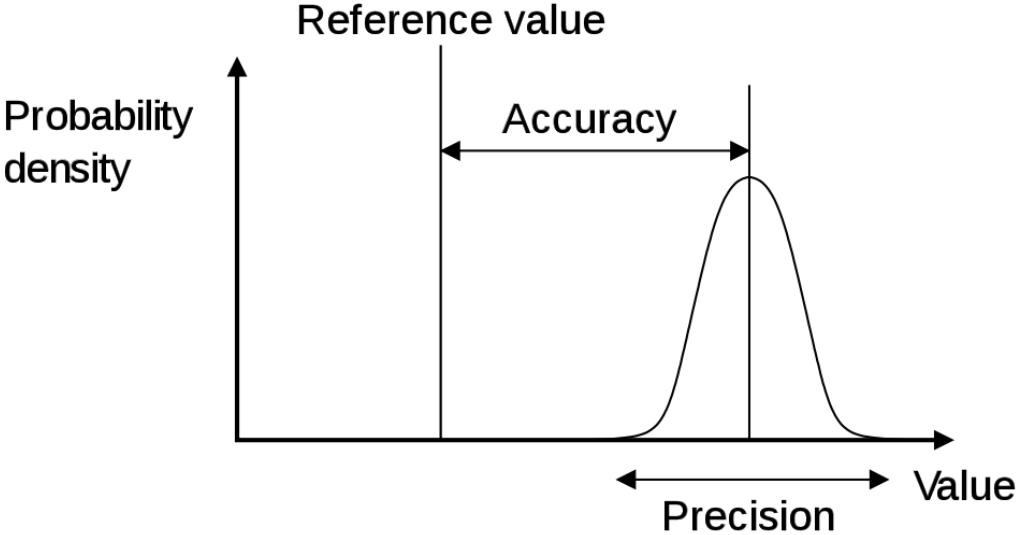
- Accuracy: Richtigkeit
- Precision: Präzision
- Both together: Genauigkeit

In Czech:

- Accuracy: Věrnost, přesnost.
- Precision: Rozptyl.



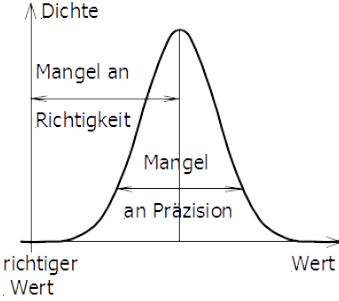
# Accuracy vs precision



[https://en.wikipedia.org/wiki/Accuracy\\_and\\_precision](https://en.wikipedia.org/wiki/Accuracy_and_precision)

### Notes

Accuracy: how close (is your model) to the truth. Precision: how consistent/stable. Think about terms *bias* and *error*. I



# References I

Further reading: Chapter 18 of [6], or chapter 4 of [1], or chapter 5 of [2]. Many figures created with the help of [3]. You may also play with demo functions from [7].  
Human deciding and predicting under noise, [4] (in Czech [5])

[1] Christopher M. Bishop.

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[2] Richard O. Duda, Peter E. Hart, and David G. Stork.

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John Wiley & Sons, 2nd edition, 2001.

[3] Vojtěch Franc and Václav Hlaváč.

Statistical pattern recognition toolbox.

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## References II

- [4] D. Kahneman, O. Sibony, and C.R. Sunstein.  
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- [5] D. Kahneman, O. Sibony, and C.R. Sunstein.  
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*Artificial Intelligence: A Modern Approach*.  
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<http://aima.cs.berkeley.edu/>.
- [7] Tomáš Svoboda, Jan Kybic, and Hlaváč Václav.  
*Image Processing, Analysis and Machine Vision — A MATLAB Companion*.  
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