

Electroencephalography and Magnetoencephalography

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January 12, 2006

Overview

- ▶ EEG
- ▶ MEG
- ▶ Physiological background
- ▶ Localization. Direct and inverse problems
- ▶ Differential methods (FDM, FEM)
- ▶ Integral methods (3 flavours BEM)
- ▶ Fast Multipole Method
- ▶ Inverse Problem

Some images courtesy of CTF, INRIA, Arye Nehorai, and others.

Electroencephalography (EEG)



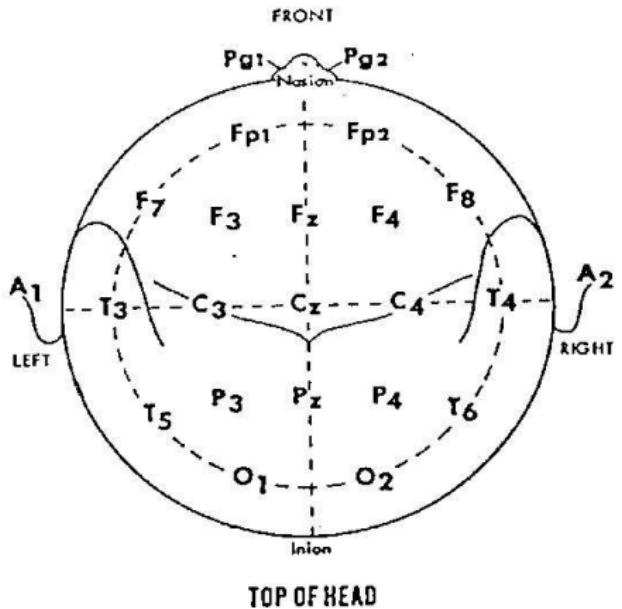
- ▶ Hans Berger, 1920s
- ▶ 16 ~ 64 electrodes
- ▶ $100 \mu\text{V}$ on the scalp ($1 \sim 2 \text{ mV}$ on the cortex)

Reference

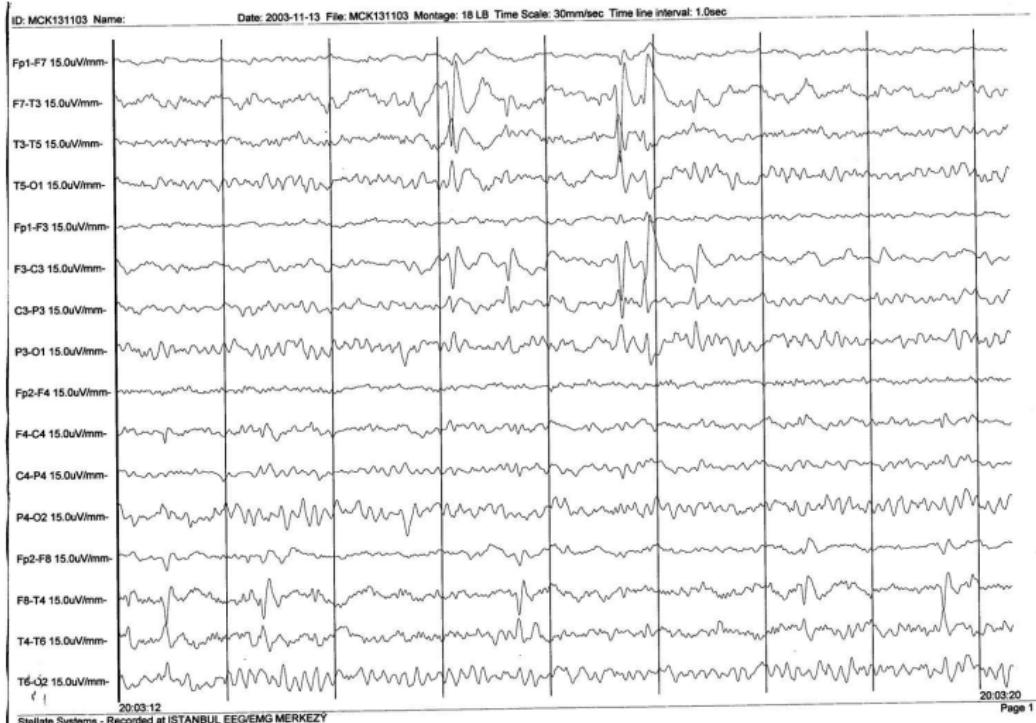
- ▶ Common reference (Wilson terminal)
- ▶ Averaged reference
- ▶ Bipolar derivation (differences)

Reference can be changed a posteriori.

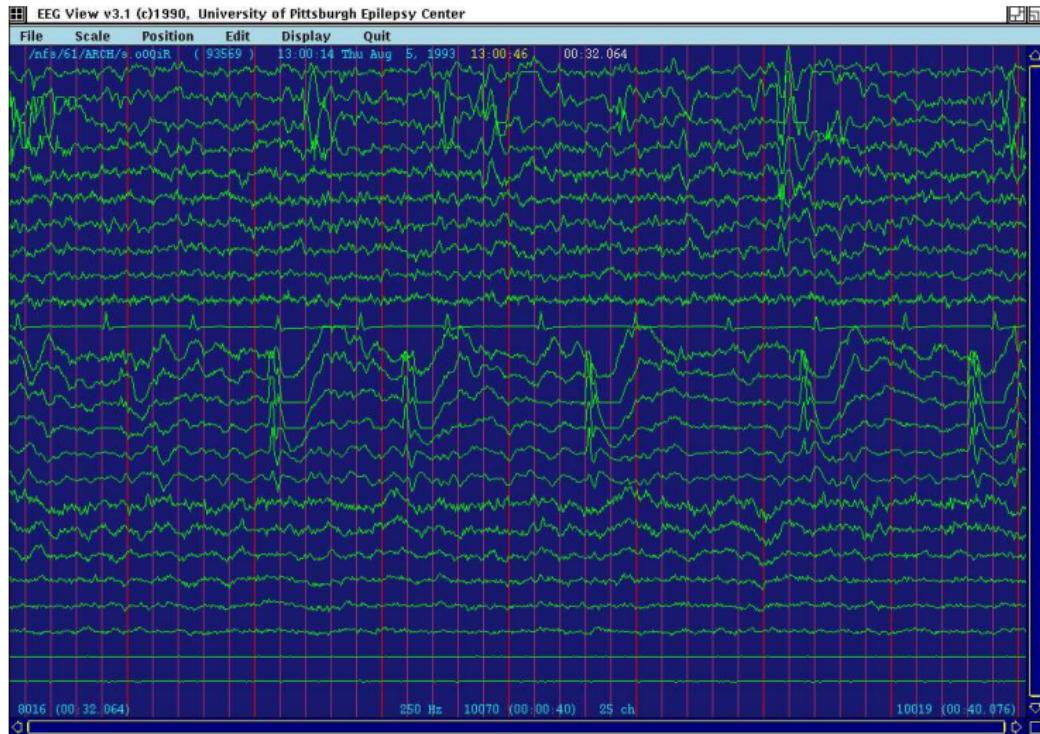
Standard electrode layout



EEG output



EEG output



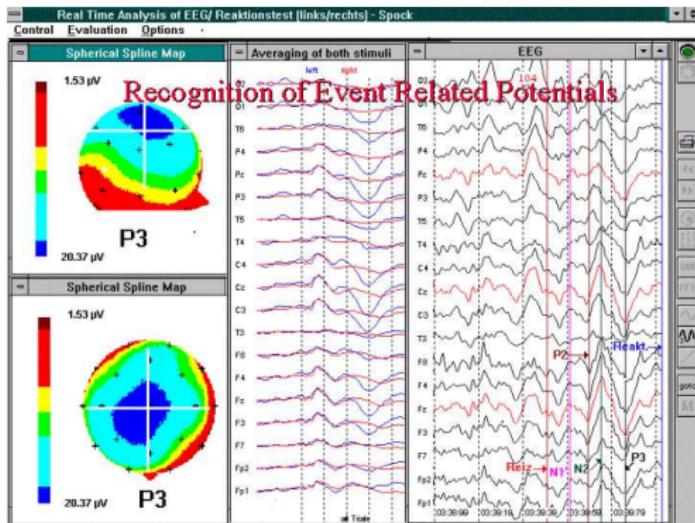
EEG waves

- Alpha** 8 ~ 12 Hz — relaxed, alert consciousness state, eyes closed.
From 2 years of age. (Berger's wave)
- Beta** > 12 Hz — active, busy, anxious thinking, concentration.
Dominant frequencies — pathologies, drug effects.
- Gamma** 26 ~ 80 Hz — higher mental activity, perception, problem solving, fear, consciousness.
- Delta** < 4 Hz — young children, encephalopathies, lesions. Deep sleep.
- Theta** 4 ~ 8 Hz — drowsiness, childhood~young adulthood, hyperventilation, hypnosis, lucid dreams, light sleep
- SMR** (sensorimotor rhythm) 12 ~ 16 Hz — physical stillness, body presence.

EEG analysis, diagnostics

- ▶ Very high time resolution
- ▶ No or crude localization
- ▶ Awake/sleep, sleep phases
- ▶ Epilepsy
- ▶ Pathologies, lesions
- ▶ Effects of opiates, anesthetics

Event related potential



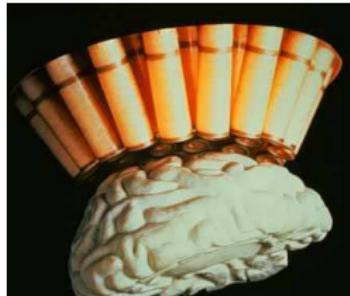
- ▶ Repetitive action
- ▶ Averaging out noise
- ▶ Visual/acoustic/somatosensory evoked potential (electric stimulation, median nerve)

Magnetoencephalography

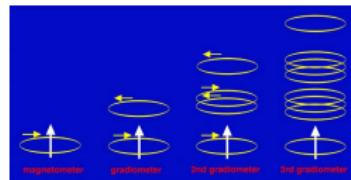


- ▶ Measuring (very weak) magnetic fields ($\sim 10^{-14}$ T = 100 fT)
- ▶ Shielded room, superconductive sensors

MEG sensors



SQUID array



Gradiometers

- ▶ Superconducting Quantum Interference Device
- ▶ Josephson junction
- ▶ flux transformer feedback loop

MEG & EEG measurements

EEG: Voltage

$$v_i = \langle V, \mu_i^e \rangle \approx V(\mathbf{x}_i)$$

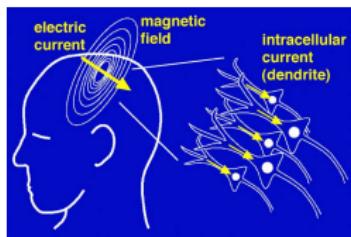
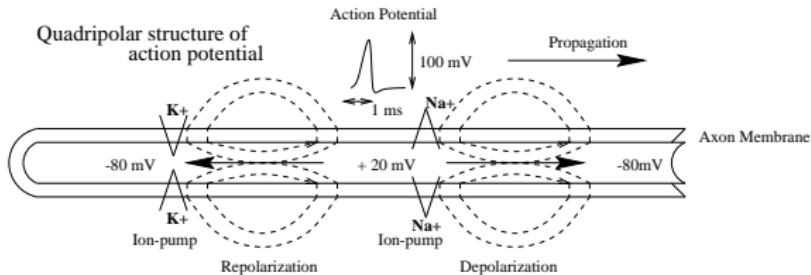
MEG: Projection of the magnetic field intensity

$$b_j = \langle \mathbf{B}, \mu_j^m \rangle \approx (\mathbf{B} \cdot \mathbf{n}_j)(\mathbf{x}_i)$$

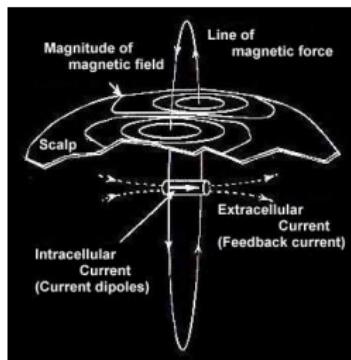
Gradiometers (real and virtual):

$$\mathbf{b} = W \mathbf{b}_{\text{raw}}$$

Currents in the brain

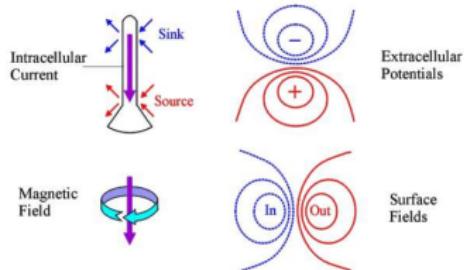
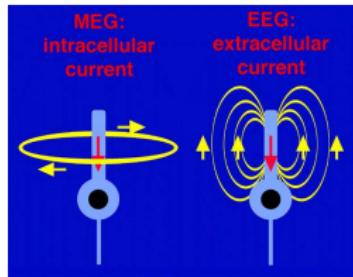


Primary currents $\mathbf{J}^p [\text{A}/\text{m}^2]$

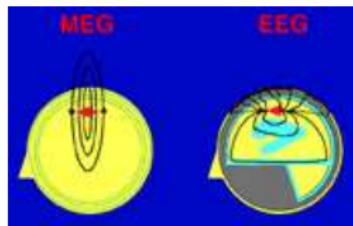


MEG versus EEG

Complementarity

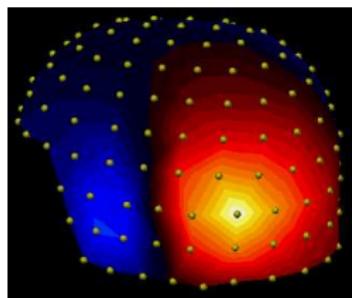
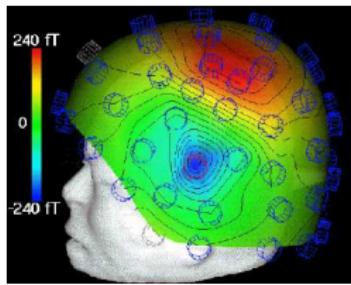


EEG Distortion



EEG much cheaper

EEG/MEG topography



- Better reconstruction needed.

Task – Inverse problem

From measurements $\mathbf{m} = [v_1, \dots, v_{N_e}, b_1, \dots, b_{N_m}]$
estimate primary currents \mathbf{J}^p .

- First we need to solve the forward problem.

Forward problem

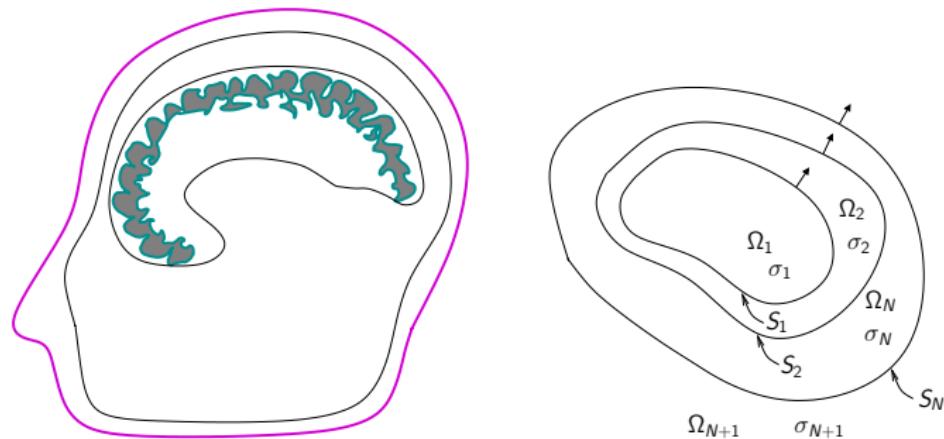
Find V and \mathbf{B} from \mathbf{J}^p

- ▶ Head modeling.
- ▶ Solving field equations.

Necessary prerequisite for solving the inverse problem.

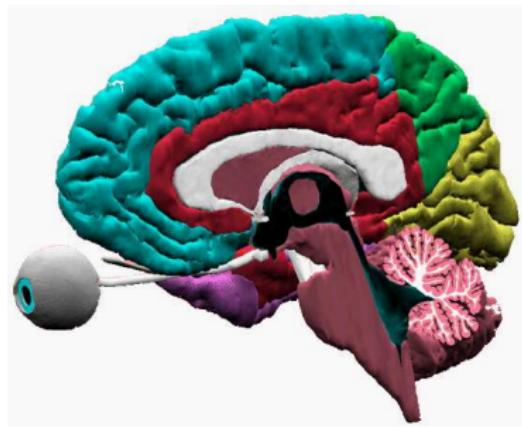
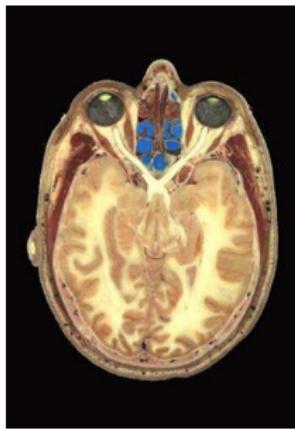
Classical head model

Nested surfaces:



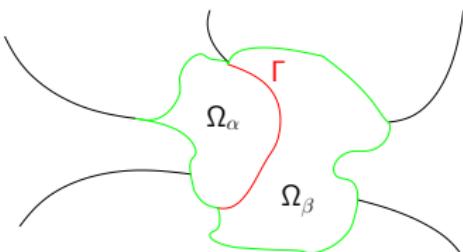
Nested volumes Ω_i with conductivities σ_i , separated by surfaces S_j .

Real head



Images from the Visible Human and Digital Anatomist projects.

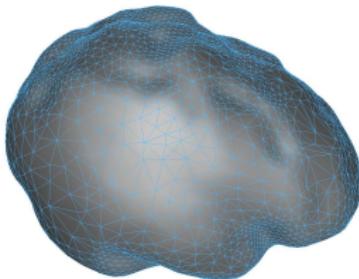
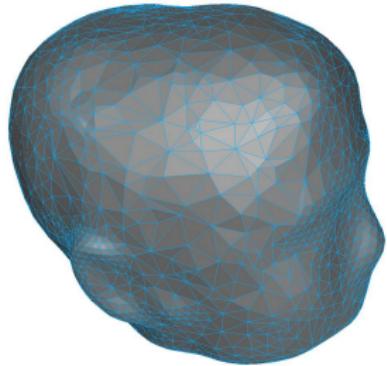
Generalized topology head model



- ▶ $N + 1$ disjoint open sets $\Omega_1, \dots, \Omega_{N+1}$ partitioning \mathbb{R}^3 .
- ▶ Boundaries $S_{\alpha\beta} = \partial\Omega_\alpha \cap \partial\Omega_\beta$ are empty or decomposable into a finite number of connected regular surfaces.
- ▶ → Boundaries $S_{\alpha\beta}$ are regular (a.e.).

High-resolution realistic model

Head meshes:



with about 13000 points and 26000 faces

→ 34000 unknowns.

Field equations

Maxwell equations (in void):

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \cdot \mathbf{B} = 0 \quad \nabla \times \mathbf{B} = \mu_0 \left(\mathbf{J} + \epsilon_0 \frac{\partial \mathbf{E}}{\partial t} \right)$$

$$\epsilon_0 \approx 8.85 \cdot 10^{-12} \text{ [Fm}^{-1}\text{]}, \quad \mu_0 = 4\pi \cdot 10^{-7} \text{ [Hm}^{-1}\text{]}, \quad \epsilon_0 \mu_0 c^2 = 1$$

Quasistatic approximation:

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad \nabla \times \mathbf{E} = 0 \quad \rightarrow \quad \mathbf{E} = -\nabla V$$

$$\nabla \cdot \mathbf{B} = 0 \quad \nabla \times \mathbf{B} = \mu_0 \mathbf{J} \quad \rightarrow \quad \nabla \cdot \mathbf{J} = 0$$

Field equations

Quasistatic approximation:

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad \nabla \times \mathbf{E} = 0 \quad \rightarrow \quad \mathbf{E} = -\nabla V$$

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Conductive medium: (conductivity $\sigma [\Omega^{-1}m^{-1}]$)

$$\mathbf{J} = \mathbf{J}^p + \sigma \mathbf{E} = \mathbf{J}^p - \sigma \nabla V$$

$$\boxed{\nabla \cdot (\sigma \nabla V) = \nabla \cdot \mathbf{J}^p}$$



Field equations

Quasistatic approximation:

$$\begin{aligned}\nabla \cdot \mathbf{E} &= \frac{\rho}{\epsilon_0} & \nabla \times \mathbf{E} &= 0 & \rightarrow & \mathbf{E} = -\nabla V \\ \nabla \cdot \mathbf{B} &= 0 & \nabla \times \mathbf{B} &= \mu_0 \mathbf{J} & \rightarrow & \nabla \cdot \mathbf{J} = 0\end{aligned}$$

Conductive medium: (conductivity $\sigma [\Omega^{-1}m^{-1}]$)

$$\mathbf{J} = \mathbf{J}^p + \sigma \mathbf{E} = \mathbf{J}^p - \sigma \nabla V$$

$$\nabla \cdot (\sigma \nabla V) = \nabla \cdot \mathbf{J}^p$$

Magnetic field:

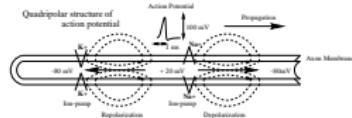
$$\mathbf{B} = \frac{\mu_0}{4\pi} \int_{\Omega} \mathbf{J}(\mathbf{r}') \times \nabla_{\mathbf{r}'} \frac{1}{\|\mathbf{r} - \mathbf{r}'\|} d\mathbf{r}'$$

Current sources

- ▶ Current “dipole” \mathbf{q} [Am]:

$$\mathbf{q} = \mathbf{J} \Delta / \Delta S$$

$$\mathbf{J}_{\text{dip}}(\mathbf{x}) = \mathbf{q} \delta_{\mathbf{p}} = \mathbf{q} \delta(\mathbf{x} - \mathbf{p})$$



Dipole field

$$V_{\text{dip}}(\mathbf{x}) = \frac{1}{4\pi\sigma} \frac{\mathbf{q} \cdot (\mathbf{p} - \mathbf{x})}{\|\mathbf{p} - \mathbf{x}\|^3}$$

Surface versus volume methods

Solve $\nabla(\sigma \nabla V) = f = \nabla \mathbf{J}^p$ for V .

- ▶ Volume methods
 - ▶ unknowns ($V(\mathbf{x})$) in the volume $\mathbf{x} \in \Omega \subset \mathbb{R}^3$
 - ▶ differential equations
- ▶ Surface methods
 - ▶ conductivity piecewise constant
 - ▶ unknowns ($V(\mathbf{x})$) on a set of surfaces $\mathbf{x} \in S_i(\mathbb{R}^2)$
 - ▶ integral equations

Finite difference method

$$\nabla(\sigma \nabla V) = f$$

- ▶ Regular grid:

$$v_{ij} = V(hi, hj)$$

- ▶ Finite difference approximation

for example $\Delta V \approx \frac{1}{4h^2} \begin{bmatrix} & 1 & \\ 1 & -4 & 1 \\ & 1 & \end{bmatrix} * v$

- ▶ Linear system of equations: $A\mathbf{v} = \mathbf{b}$
- ▶ Where $\sigma = \text{const}$ \rightarrow stationarity \rightarrow FFT solution

Finite element method

$$\nabla(\sigma \nabla V) = f$$

- ▶ Test functions ϕ_j

$$\langle \nabla(\sigma \nabla V), \phi_j \rangle = \langle f, \phi_j \rangle$$

- ▶ Discretize $V = \sum_i v_i \phi_i$

$$\begin{aligned} \sum_i v_i \langle \nabla(\sigma \nabla \phi_i), \phi_j \rangle &= \langle f, \phi_j \rangle \\ - \sum_i v_i \sigma_i \langle \nabla \phi_i, \nabla \phi_j \rangle &= \langle f, \phi_j \rangle \end{aligned}$$

- ▶ Linear **symmetric** system $\mathbf{Av} = \mathbf{b}$

Surface metehod / Boundary element method

- ▶ Mathematical basis
- ▶ Representation theorem
- ▶ Integral representations
 - ▶ Single layer formulation
 - ▶ Double layer formulation
 - ▶ Symmetric formulation

The Green connection

Suppose constant σ : $\boxed{\Delta u = f}$

- ▶ Green function (Nedelec's convention)

$$G(\mathbf{r}, \mathbf{r}') = \frac{1}{4\pi \|\mathbf{r} - \mathbf{r}'\|} \quad -\Delta_{\mathbf{r}} G(\mathbf{r}, \mathbf{r}') = \delta(\mathbf{r} - \mathbf{r}') = \delta_{\mathbf{r}'}$$

- ▶ Stokes theorem

$$\int_{\partial\Omega} \mathbf{g}(\mathbf{r}) \cdot d\mathbf{s}(\mathbf{r}) = \int_{\Omega} \nabla \cdot \mathbf{g}(\mathbf{r}) d\mathbf{r}$$

The Green connection

- ▶ Stokes theorem

$$\int_{\partial\Omega} \mathbf{g}(\mathbf{r}) \cdot d\mathbf{s}(\mathbf{r}) = \int_{\Omega} \nabla \cdot \mathbf{g}(\mathbf{r}) d\mathbf{r}$$

- ▶ First Green identity

$$\mathbf{g} = u \nabla v \quad \rightarrow \quad \int_{\partial\Omega} u \nabla v \, d\mathbf{s}(\mathbf{r}) = \int_{\Omega} \nabla u \nabla v + u \Delta v \, d\mathbf{r}$$

The Green connection

- ▶ First Green identity

$$\mathbf{g} = u \nabla v \quad \rightarrow \quad \int_{\partial\Omega} u \nabla v \, d\mathbf{s}(\mathbf{r}) = \int_{\Omega} \nabla u \nabla v + u \Delta v \, d\mathbf{r}$$

- ▶ Second Green identity

$$\int_{\partial\Omega} u \nabla v - v \nabla u \, d\mathbf{s}(\mathbf{r}) = \int_{\Omega} u \Delta v - v \Delta u \, d\mathbf{r}$$

$$\int_{\partial\Omega} u \partial_{\mathbf{n}'} v - v \partial_{\mathbf{n}'} u \, ds(\mathbf{r}) = \int_{\Omega} u \Delta v - v \Delta u \, d\mathbf{r}$$

The Green connection

- ▶ Second Green identity

$$\int_{\partial\Omega} u \partial_{\mathbf{n}'} v - v \partial_{\mathbf{n}'} u \, ds(\mathbf{r}) = \int_{\Omega} u \Delta v - v \Delta u \, d\mathbf{r}$$

- ▶ Third Green identity

$$v = -G(\mathbf{r}, \mathbf{r}'), \quad \Delta u = 0 \quad \rightarrow$$

$$\nu u(\mathbf{r}) = \int_{\partial\Omega} G(\mathbf{r}, \mathbf{r}') \partial_{\mathbf{n}'} u(\mathbf{r}') - u \partial_{\mathbf{n}'} G(\mathbf{r}, \mathbf{r}') \, ds(\mathbf{r}')$$

$$\nu = \begin{cases} 1, & \mathbf{r} \in \Omega \\ 1/2, & \mathbf{r} \in \partial\Omega \\ 0, & \mathbf{r} \in \mathbb{R}^3 \setminus \overline{\Omega} \end{cases}$$

Representation theorem

Third Green identity:

$$\int_{\partial\Omega} G(\mathbf{r}, \mathbf{r}') \partial_{\mathbf{n}'} u(\mathbf{r}') - u(\mathbf{r}') \partial_{\mathbf{n}'} G(\mathbf{r}, \mathbf{r}') \, ds(\mathbf{r}') = \begin{cases} u(\mathbf{r}), & \mathbf{r} \in \Omega \\ u(\mathbf{r})/2, & \mathbf{r} \in \partial\Omega \\ 0, & \mathbf{r} \in \mathbb{R}^3 \setminus \overline{\Omega} \end{cases}$$

$$\Delta u^{\text{int}} = 0 \quad \text{in } \Omega, \quad \Delta u^{\text{ext}} = 0 \quad \text{in } \mathbb{R}^3 \setminus \overline{\Omega}, \quad u^{\text{ext}} \xrightarrow{\|\mathbf{r}\| \rightarrow \infty} O(\|\mathbf{r}\|^{-1})$$

$$\int_{\partial\Omega} G(\mathbf{r}, \mathbf{r}') [\partial_{\mathbf{n}'} u](\mathbf{r}') - \partial_{\mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [u](\mathbf{r}') \, ds(\mathbf{r}') = \begin{cases} u^{\text{int}}(\mathbf{r}), & \mathbf{r} \in \Omega \\ u^{\text{ext}}(\mathbf{r}), & \mathbf{r} \in \mathbb{R}^3 \setminus \overline{\Omega} \\ \frac{u^{\text{int}} + u^{\text{ext}}}{2}(\mathbf{r}), & \mathbf{r} \in \partial\Omega \end{cases}$$

where $[u] = u^{\text{int}}(\mathbf{r}') - u^{\text{ext}}(\mathbf{r}')$, $[\partial_{\mathbf{n}'} u] = \partial_{\mathbf{n}'}^- u^{\text{int}}(\mathbf{r}') - \partial_{\mathbf{n}'}^+ u^{\text{ext}}(\mathbf{r}')$

Extended representation theorem

- Regular case, $\mathbf{r} \in \mathbb{R}^3 \setminus \partial\Omega$.

$$\mathbf{p} = \sigma \nabla V, \quad \nabla \cdot \mathbf{p} = 0, \quad \text{in } \mathbb{R}^3 \setminus \partial\Omega$$

$$-p(\mathbf{r}) = \int_{\partial\Omega} \sigma \partial_{\mathbf{n}, \mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [V](\mathbf{r}') - \partial_{\mathbf{n}} G(\mathbf{r}, \mathbf{r}') [p](\mathbf{r}') ds(\mathbf{r}')$$

$$V(\mathbf{r}) = \int_{\partial\Omega} -\partial_{\mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [V](\mathbf{r}') + \sigma^{-1} G(\mathbf{r}, \mathbf{r}') [p](\mathbf{r}') ds(\mathbf{r}')$$

where $p = \mathbf{p} \cdot \mathbf{n}$, $[V] = V^- - V^+$, $[p] = p^- - p^+$

Extended representation theorem

- ▶ Limit case, $\mathbf{r} \in \partial\Omega$.

$$\mathbf{p} = \sigma \nabla V, \quad \nabla \cdot \mathbf{p} = 0, \quad \text{in } \mathbb{R}^3 \setminus \partial\Omega$$

$$-p^\pm(\mathbf{r}) = \pm \frac{[p]}{2} + \int_{\partial\Omega} \sigma \partial_{\mathbf{n}, \mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [V] - \partial_{\mathbf{n}} G(\mathbf{r}, \mathbf{r}') [p] \, ds(\mathbf{r}')$$

$$V^\pm(\mathbf{r}) = \mp \frac{[u]}{2} + \int_{\partial\Omega} -\partial_{\mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [V] + \sigma^{-1} G(\mathbf{r}, \mathbf{r}') [p] \, ds(\mathbf{r}')$$

where $p = \mathbf{p} \cdot \mathbf{n}$, $[V] = V^- - V^+$, $[p] = p^- - p^+$

Extended representation theorem

- Operator form, $\mathbf{r} \in \partial\Omega$.

$$-p^\pm(\mathbf{r}) = \pm \frac{[p]}{2} + \int_{\partial\Omega} \sigma \partial_{\mathbf{n}, \mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [V] - \partial_{\mathbf{n}} G(\mathbf{r}, \mathbf{r}') [p] \, ds(\mathbf{r}')$$

$$V^\pm(\mathbf{r}) = \mp \frac{[u]}{2} + \int_{\partial\Omega} -\partial_{\mathbf{n}'} G(\mathbf{r}, \mathbf{r}') [V] + \sigma^{-1} G(\mathbf{r}, \mathbf{r}') [p] \, ds(\mathbf{r}')$$

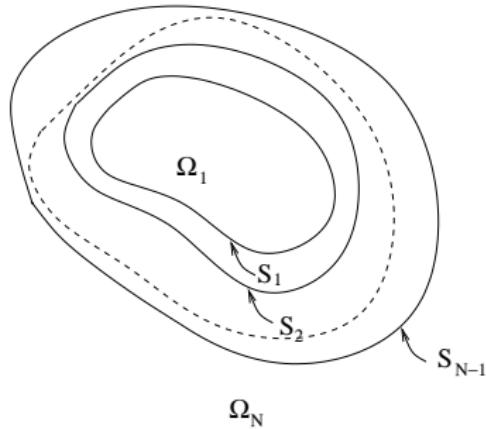
$$\begin{aligned} -p^\pm(\mathbf{r}) &= \sigma \mathcal{N}[V] + (\pm \frac{\mathcal{J}}{2} - \mathcal{D}^*)[p] \\ V^\pm(\mathbf{r}) &= (\mp \frac{\mathcal{J}}{2} - \mathcal{D})[V] + \sigma^{-1} \mathcal{S}[p] \end{aligned}$$

where $p = \sigma \partial_{\mathbf{n}} V$

BEM problem

Solve:

$$\Delta V = f \quad \text{in } \cup \Omega_i$$
$$[\sigma \partial_{\mathbf{n}} V] = [V] = 0 \quad \text{on } S_i$$



$$f = \sum_{i=1}^N f_{\Omega_i}$$

$$v_{\Omega_i}(\mathbf{r}) = -f_{\Omega_i} * G(\mathbf{r})$$

BEM — Single layer formulation

$$v_s = \sum_{i=1}^N v_{\Omega_i} / \sigma_i \quad \text{verifies} \quad \sigma \Delta v_s = f$$

Consider: $u_s = V - v_s \rightarrow [u_s]_j = 0$

$$\rightarrow u_s = \sum_{i=1}^N \delta_{ji} \xi_{S_i} \quad \xi_{S_i} = [p]_i$$

From: $[\sigma \partial_n V] = 0 \rightarrow [\sigma \partial_n u_s] = -[\sigma \partial_n v_s]$

From the representation theorem:

$$\partial_n v_s = \frac{\sigma_j + \sigma_{j+1}}{2(\sigma_{j+1} - \sigma_j)} \xi_{S_j} - \sum_{i=1}^N \mathcal{D}_{ji}^* \xi_{S_i}$$

BEM — Double layer formulation

$$v_d = \sum_{i=1}^N v_{\Omega_i} \quad \text{verifies} \quad \Delta v_d = f$$

Consider: $u_d = \sigma V - v_d \rightarrow [\partial_n u_d]_j = 0$

$$\rightarrow u_d = \sum_{i=1}^N \mathcal{D}_{ji} \mu_{S_i}$$

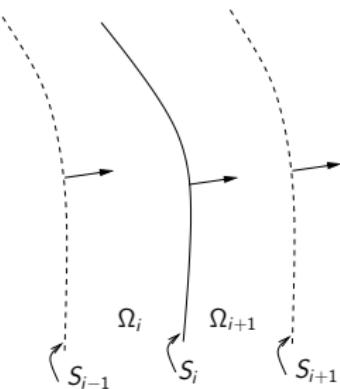
$$\mu_{S_i} = -[u_d]_i = (\sigma_{i+1} - \sigma_i) V_{S_i}$$

From: $[V] = 0 \rightarrow \sigma_{j+1}(u_d + v_d)^- = \sigma_j(u_d + v_d)^+$

From the representation theorem:

$$v_d = \frac{\sigma_j + \sigma_{j+1}}{2} V_{S_j} - \sum_{i=1}^N (\sigma_{i+1} - \sigma_i) \mathcal{D}_{ji} V_{S_i}$$

BEM – Symmetric formulation



Consider:

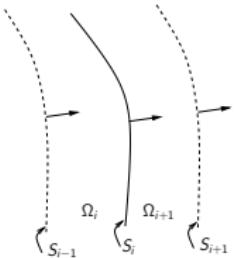
$$u_{\Omega_i} = \begin{cases} V - v_{\Omega_i}/\sigma_i & \text{in } \Omega_i \\ -v_{\Omega_i}/\sigma_i & \text{in } \mathbb{R}^3 \setminus \overline{\Omega}_i \end{cases}$$

$$[u_{\Omega_i}]_i = V_{S_i}, \quad [u_{\Omega_i}]_{i-1} = -V_{S_{i-1}}$$

Define:

$$p_{S_i} = \sigma_i [\partial_n u_{\Omega_i}]_i = \sigma_i (\partial_n V)_{S_i}^- = \sigma_{i+1} (\partial_n V)_{S_i}^+$$

BEM – Symmetric formulation



From the extended representation theorem:

$$\begin{aligned}(u_{\Omega_i})_{S_i}^- &= (V - v_{\Omega_i}/\sigma_i)_{S_i}^- \\&= \frac{V_{S_i}}{2} + \mathcal{D}_{i,i-1} V_{S_{i-1}} - \mathcal{D}_{ii} V_{S_i} - \sigma_i^{-1} \mathcal{S}_{i,i-1} p_{S_{i-1}} + \sigma_i^{-1} \mathcal{S}_{ii} p_{S_i} \\(u_{\Omega_{i+1}})_{S_i}^+ &= (V - v_{\Omega_{i+1}}/\sigma_{i+1})_{S_i}^+ \\&= \frac{V_{S_i}}{2} + \mathcal{D}_{ii} V_{S_i} - \mathcal{D}_{i,i+1} V_{S_{i+1}} - \sigma_{i+1}^{-1} \mathcal{S}_{ii} p_{S_i} + \sigma_{i+1}^{-1} \mathcal{S}_{i,i+1} p_{S_{i+1}}\end{aligned}$$

BEM – Symmetric formulation

Subtract:

$$\begin{aligned}\sigma_{i+1}^{-1}(v_{\Omega_{i+1}})_{S_i} - \sigma_i^{-1}(v_{\Omega_i})_{S_i} = \\ \mathcal{D}_{i,i-1} V_{S_{i-1}} - 2\mathcal{D}_{ii} V_{S_i} + \mathcal{D}_{i,i+1} V_{S_{i+1}} \\ - \sigma_i^{-1} \mathcal{S}_{i,i-1} p_{S_{i-1}} + (\sigma_i^{-1} + \sigma_{i+1}^{-1}) \mathcal{S}_{ii} p_{S_i} - \sigma_{i+1}^{-1} \mathcal{S}_{i,i+1} p_{S_{i+1}}\end{aligned}$$

and also:

$$\begin{aligned}(\partial_n v_{\Omega_{i+1}})_{S_i} - (\partial_n v_{\Omega_i})_{S_i} = \\ \sigma_i \mathcal{N}_{i,i-1} V_{S_{i-1}} - (\sigma_i + \sigma_{i+1}) \mathcal{N}_{ii} V_{S_i} + \sigma_{i+1} \mathcal{N}_{i,i+1} V_{S_{i+1}} \\ - \mathcal{D}_{i,i-1}^* p_{S_{i-1}} + 2\mathcal{D}_{ii}^* p_{S_i} - \mathcal{D}_{i,i+1}^* p_{S_{i+1}}\end{aligned}$$

BEM – Symmetric formulation

$$\begin{bmatrix}
 (\sigma_1 + \sigma_2)N_{11} & -2\mathcal{D}_{11}^* & -\sigma_2 N_{12} & \mathcal{D}_{12}^* \\
 -2\mathcal{D}_{11} & (\sigma_1^{-1} + \sigma_2^{-1})\mathcal{S}_{11} & \mathcal{D}_{12} & -\sigma_2^{-1}\mathcal{S}_{12} \\
 -\sigma_2 N_{21} & \mathcal{D}_{21}^* & (\sigma_2 + \sigma_3)N_{22} & -2\mathcal{D}_{22}^* \\
 \mathcal{D}_{21} & -\sigma_2^{-1}\mathcal{S}_{21} & -2\mathcal{D}_{22} & (\sigma_2^{-1} + \sigma_3^{-1})\mathcal{S}_{22} \\
 & & -\sigma_3 N_{32} & \mathcal{D}_{32}^* \\
 & & \mathcal{D}_{32} & (\sigma_3 + \sigma_4)N_{33} \\
 & & \mathcal{D}_{32} & -2\mathcal{D}_{33} \\
 & & \mathcal{D}_{32} & (\sigma_3^{-1} + \sigma_4^{-1})\mathcal{S}_{33} \\
 & & & \vdots \\
 & & & \vdots \\
 & & & (\sigma_{N-1} + \sigma_N)N_{N-1,N-1} & -2\mathcal{D}_{N-1,N-1}^* & -\sigma_N N_{N-1,N} \\
 & & & -2\mathcal{D}_{N-1,N-1} & (\sigma_{N-1}^{-1} + \sigma_N^{-1})\mathcal{S}_{N-1,N-1} & \mathcal{D}_{N-1,N} \\
 & & & -\sigma_N N_{N,N-1} & \mathcal{D}_{N,N-1} & \sigma_N N_{N,N}
 \end{bmatrix}$$

$$\begin{bmatrix}
 V_{S_1} \\
 \rho S_1 \\
 V_{S_2} \\
 \rho S_2 \\
 V_{S_3} \\
 \rho S_3 \\
 \vdots \\
 V_{S_N}
 \end{bmatrix} = \begin{bmatrix}
 (\partial_n v_{\Omega_1})_{S_1} - (\partial_n v_{\Omega_2})_{S_1} \\
 \sigma_2^{-1}(v_{\Omega_2})_{S_1} - \sigma_1^{-1}(v_{\Omega_1})_{S_1} \\
 (\partial_n v_{\Omega_2})_{S_2} - (\partial_n v_{\Omega_3})_{S_2} \\
 \sigma_3^{-1}(v_{\Omega_3})_{S_2} - \sigma_2^{-1}(v_{\Omega_2})_{S_2} \\
 (\partial_n v_{\Omega_3})_{S_3} - (\partial_n v_{\Omega_4})_{S_3} \\
 \sigma_4^{-1}(v_{\Omega_4})_{S_3} - \sigma_3^{-1}(v_{\Omega_3})_{S_3} \\
 \vdots \\
 (\partial_n v_{\Omega_N})_{S_N}
 \end{bmatrix}$$

Discretization in BEM

- Discretize unknowns ($\varphi_i = \text{P0,P1}$)

$$\xi(\mathbf{r}) = \sum_i \xi_i \varphi_i(\mathbf{r})$$

- Test functions ($\psi_j = \delta, \text{P0}, \text{P1}$)



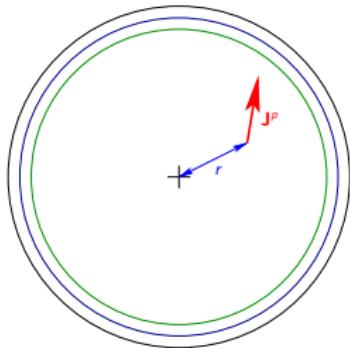
$$\left\langle \frac{\xi}{2}(\mathbf{r}) - \int_{\partial\Omega} \xi(\mathbf{r}') \partial_{\mathbf{n}} G(\mathbf{r}, \mathbf{r}') \, ds(\mathbf{r}'), \psi_j \right\rangle = \langle \partial_{\mathbf{n}} V_0, \psi_j \rangle$$

$$\sum_i \xi_i \left(\frac{1}{2} \langle \phi_i, \psi_j \rangle - \int_{\partial\Omega \times \partial\Omega} \varphi_i(\mathbf{r}') \partial_{\mathbf{n}} G(\mathbf{r}, \mathbf{r}') \psi_j(\mathbf{r}) \, ds^2(\mathbf{r}', \mathbf{r}') \right) = \langle \partial_{\mathbf{n}} V_0, \psi_j \rangle$$

- Linear system of equations: $\mathbf{A}\boldsymbol{\xi} = \mathbf{b}$

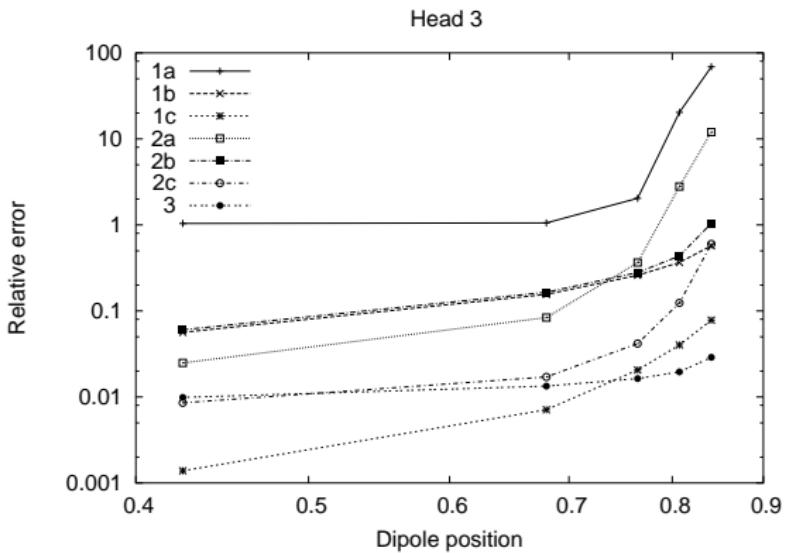
BEM accuracy

- ▶ Analytical solution



- ▶ Relative error $\|V - V_{\text{anal}}\|_{\ell_2} / \|V_{\text{anal}}\|_{\ell_2}$
- ▶ Dipoles at $0.50R, 0.80R, 0.90R, 0.95R, 0.98R$
- ▶ Spherical head phantoms with
 $N_V = 3 \times 42, 3 \times 162, 3 \times 642$

BEM accuracy



Fast Multipole Method – Motivation

$$\Gamma \mathbf{x} = \mathbf{y}$$

- ▶ Solution methods
 - ▶ **Direct**, e.g. LU decomposition.
Complexity $O(P^3)$, memory $O(P^2)$
 - ▶ **Iterative**, e.g. GMRES, uses products $\Gamma \mathbf{v}$.
Complexity $O(MP^2)$, memory $O(P)$

Number of elements P , number of iterations M .

- ▶ Fast Multipole Method
 - ▶ Calculate $\mathbf{y} = \Gamma \mathbf{v}$ in $O(P \log P)$ time.
 - ▶ Approximative, hierarchical

Multipole expansion

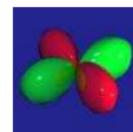
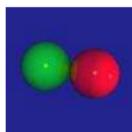
Typical element:

$$\Gamma_{i,j} = \iint_{\substack{\mathbf{r} \in \text{supp } \psi_i \\ \mathbf{r}' \in \text{supp } \varphi_j}} \nabla' \frac{1}{\|\mathbf{r} - \mathbf{r}'\|} \cdot \mathbf{n}_j \varphi_j(\mathbf{r}') \psi_i(\mathbf{r}) d\mathbf{s}^2(\mathbf{r}', \mathbf{r})$$

$$\boxed{\nabla' \frac{1}{\|\mathbf{r} - \mathbf{r}'\|} = - \sum_{\substack{n=0 \dots \infty \\ m=-n \dots n}} \nabla' I_n^{-m}(\mathbf{M}_p - \mathbf{r}') O_n^m(\mathbf{r} - \mathbf{M}_p)}$$

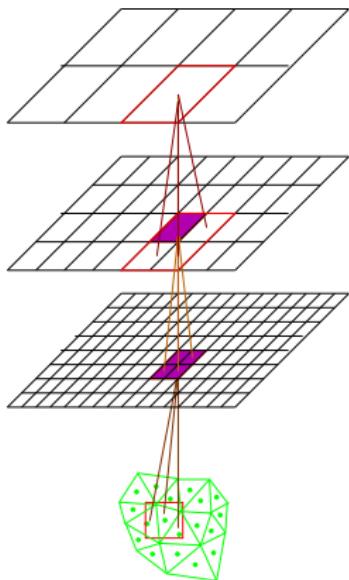
Spherical harmonics

$$I_n^{-m}, O_n^m:$$



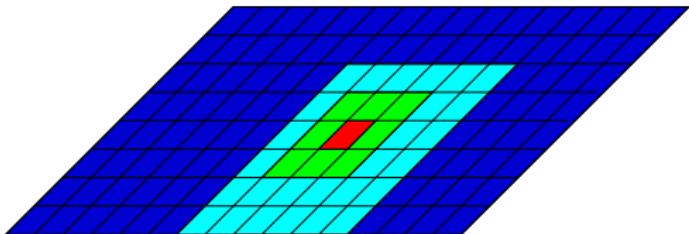
FMM – Algorithm

Build an oct-tree:



FMM – Algorithm

Levels involved:



Level 2

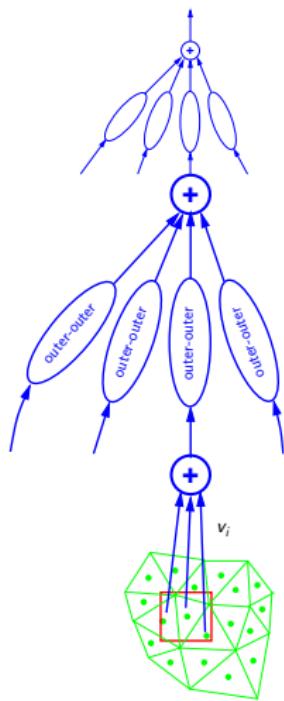
Level 1 – suburb

Treated locally

Cell considered

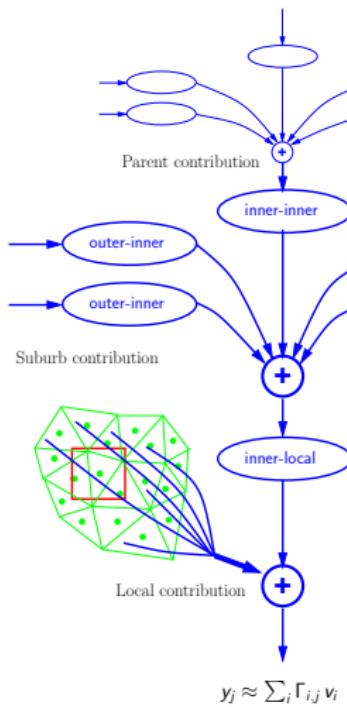
FMM – Algorithm

Sweep-up → outer fields

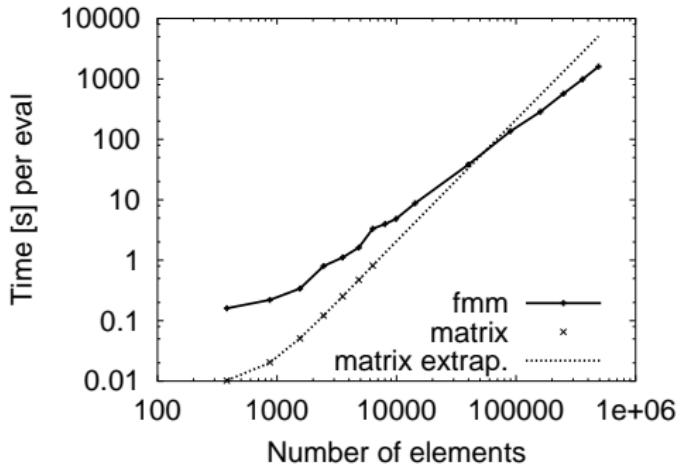


FMM – Algorithm

Sweep-down → result



FMM – Speed-Up



Single-level FMM, $O(P^{4/3})$, faster for $P \gtrapprox 70000$ triangles.

MEG/EEG, Conclusions

- ▶ MEG, EEG, brain function analysis
- ▶ Excellent time-resolution, bad spatial resolution
- ▶ Standard diagnostic use
- ▶ Combination with other methods (fMRI, PET) desirable
- ▶ Localization is a hard inverse problem
- ▶ Solution methods — FDM, FEM, BEM methods
- ▶ BEM formulations, single/double/symmetric
- ▶ Implementation, discretization
- ▶ Fast Multipole Method for acceleration