

## 2. Random fields (undirected graphical models)

- A  $K$ -valued random field  $S$  is a collection  $\{S_i \mid i \in V\}$  of  $K$ -valued random variables
  - $i \in V$  can be: pixels, object parts, .....
  - $k \in K$  can be: colours, segment labels, depth values, poses of object parts, .....
- As usual,  $S \in K^{|V|} \cong \mathcal{S}$  denotes a realisation  $s_i \in K, i \in V$
- $p \in \mathcal{P}$  denotes a joint p.d.  $p: \mathcal{S} \rightarrow \mathbb{R}_+$

### Questions:

- 1) What is the dimension of  $\mathcal{P}$ ? , Which  $p \in \mathcal{P}$  is the simplest?
- 2) We fix marginal distributions  $p(s_i) = \mu_i(s_i)$  for each  $S_i$ . This decreases the dimension of  $\mathcal{P}$  by ...? Which  $p$  is the simplest?
- 3) We equip  $V$  with a graph structure  $(V, E)$  and fix pairwise marginal distributions  $p(s_i, s_j) = \mu_{ij}(s_i, s_j)$  for all edges  $\{i, j\} \in E$ . This decreases the dimension of  $\mathcal{P}$  by ...? Which  $p$  is the simplest?
- 4) We equip  $V$  with a hypergraph structure and ...  
.....

A. Exponential families

- $S = \{S_i \mid i \in V\}$  is a  $K$ -valued random field
- $\Phi: \mathcal{S} = K^{|V|} \rightarrow \mathbb{R}^n$  is a random vector

Consider the task

$$\inf_p \left\{ \sum_{s \in \mathcal{S}} p(s) \log p(s) \mid \mathbb{E}_p(\Phi) = \mu, \sum_{s \in \mathcal{S}} p(s) = 1 \right\}$$

Lagrange function

$$L(p) = \sum_{s \in \mathcal{S}} p(s) \log p(s) - \langle u, \mathbb{E}_p(\Phi) - \mu \rangle - \lambda \left[ \sum_{s \in \mathcal{S}} p(s) - 1 \right]$$

$$\dots \rightarrow p_u(s) = \exp[\langle u, \Phi(s) \rangle - \log Z(u)]$$

Assign. 3 in Seminar 1  $\Rightarrow$

If there  $\exists$  a strictly positive  $\bar{p}$  s.t.  $\mathbb{E}_{\bar{p}}(\Phi) = \mu$   
then  $p_u$  is a unique solution

Questions

(1) Which  $\mu \in \mathbb{R}^n$  qualify?

$$\mathbb{E}_{\bar{p}}(\Phi) = \sum_{s \in \mathcal{S}} \bar{p}(s) \Phi(s) = \mu, \quad \bar{p}(s) > 0 \quad \forall s \in \mathcal{S} \Leftrightarrow$$

$\mu$  lies in the interior of  $\text{conv } \Phi(\mathcal{S})$

where  $\Phi(\mathcal{S}) = \{\Phi(s) \mid s \in \mathcal{S}\}$

(2)  $u \mapsto \mu$ ? Yes, because

$$\nabla \log Z(u) = \nabla \log \sum_{s \in \mathcal{S}} e^{\langle u, \Phi(s) \rangle} =$$

$$= \frac{1}{Z(u)} \sum_{s \in \mathcal{S}} e^{\langle u, \Phi(s) \rangle} \Phi(s) = \mathbb{E}_u(\Phi) = \mu$$

(3)  $\mu \mapsto u$ ? (provided that  $\mu \in \text{int}(\text{conv}(\Phi(\mathcal{S})))$ )

No, not always.  $p_u$  is unique, but not  $u$ !

$$\langle u, \varphi(s) \rangle - \log Z(u) = \langle \tilde{u}, \varphi(s) \rangle - \log Z(\tilde{u}) \quad \forall s \in \mathcal{S}$$

$$\hookrightarrow \langle u - \tilde{u}, \varphi(s) \rangle = \text{const}_s \quad \forall s \in \mathcal{S}$$

$$\{u \in \mathbb{R}^n \mid \langle u, \varphi(s) \rangle = \text{const}_s \quad \forall s \in \mathcal{S}\} = L^\perp$$

$$\text{aff}(\Phi(\mathcal{S})) = \varphi(s_0) - \underbrace{\text{span}(\Phi(\mathcal{S}) - \varphi(s_0))}_L$$

for any  $s_0 \in \mathcal{S}$

Suppose we write

$$\text{aff} \Phi(\mathcal{S}) = \{u \in \mathbb{R}^n \mid Au = b\} \quad \text{where } A: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

then  $L = \text{Ker } A$  and  $L^\perp = \text{Im } A^T$

Answer:

• if  $\text{aff} \Phi(\mathcal{S}) = \mathbb{R}^n \Rightarrow \mu \mapsto u$  is a mapping

• if  $\text{aff} \Phi(\mathcal{S}) = \{u \in \mathbb{R}^n \mid Au = b\} \neq \mathbb{R}^n \Rightarrow$

we can reparametrise  $u$  by

$$u \rightarrow u + A^T \psi, \quad \psi \in \mathbb{R}^m$$

and have

$$\langle u + A^T \psi, \varphi(s) \rangle = \langle u, \varphi(s) \rangle + \langle \psi, b \rangle$$

$$\log Z(u + A^T \psi) = \log Z(u) + \langle \psi, b \rangle$$

## B. Graphical models (undirected)

- $S = \{S_i \mid i \in V\}$  is a  $K$ -valued random field
- $(V, E)$  is an undirected graph
- Fix pairwise marginal distributions  $p(s_i, s_j) = \mu_{ij}(s_i, s_j)$  for all edges  $\{i, j\} \in E$

Under these constraints: search joint p.d. with maximal entropy ( $\approx$  minimal information)

Everything said in A. applies here because: Any marginal probability  $p(s_i = k, s_j = k')$  can be seen as the expectation of a random variable

Hence: If  $\mu_{ij}(s_i, s_j)$  defines a valid set of marginal distributions, then the task has a unique solution

$$p_u(s) = \frac{1}{Z(u)} \exp \left[ \sum_{\{i, j\} \in E} u_{ij}(s_i, s_j) \right]. \quad (*)$$

However, the potentials  $u_{ij} : K^2 \rightarrow \mathbb{R}$  are defined up to reparametrisations.

The distribution  $p_u$  is a Gibbs random field and factorises over the edges of the graph  $(V, E)$

Problems: All tasks

a) given potentials  $u_{ij} : K^2 \rightarrow \mathbb{R} \forall \{i,j\} \in E$ , compute

$$\cdot Z(u) = \sum_{s \in \mathcal{S}} \exp \left[ \sum_{\{i,j\} \in E} u_{ij}(s_i, s_j) \right] \quad \text{and/or}$$

\cdot marginal prob's  $p_u(s_i)$ ,  $p_u(s_i, s_j)$ ,

b) check whether  $\mu_{ij} : K^2 \rightarrow \mathbb{R}_+ \forall \{i,j\} \in E$  represent a valid system of pairwise marginals,

c) given a valid system of marginals  $\mu_{ij} : K^2 \rightarrow \mathbb{R}_+ \forall \{i,j\} \in E$ , compute the potentials  $u_{ij}$

d) given potentials  $u_{ij}$  find the most probable ~~configura~~ realisations

$$\operatorname{argmax}_{s \in \mathcal{S}} p_u(s)$$

are NP-hard. Polynomial time complexity algorithms exist if  $(V, E)$  is acyclic.

### 3. The most probable realisation of a GRF

- $S = \{S_i \mid i \in V\}$  is a  $K$ -valued random field
- $(V, E)$  is an undirected graph
- The joint distribution  $p(S)$  is a Gibbs random field

Task: Find

$$\begin{aligned} & \operatorname{argmax}_{S \in \mathcal{S}} \frac{1}{Z(u)} \exp \sum_{ij \in E} u_{ij}(s_i, s_j) = \\ & = \operatorname{argmax}_{S \in \mathcal{S}} \sum_{ij \in E} u_{ij}(s_i, s_j) \end{aligned}$$

Remark 1 The task is solvable in polynomial time if  $K$  is completely ordered and all functions  $-u_{ij} : K^2 \rightarrow \mathbb{R}$  are submodular w.r.t. the ordering. ■

Abstract view on the task:

$$\operatorname{argmax}_{S \in \mathcal{S}} \langle u, \varphi(S) \rangle \quad \text{discrete task}$$

relax it to

$$\operatorname{argmax}_{P \in \mathcal{P}} \sum_{S \in \mathcal{S}} p(S) \langle u, \varphi(S) \rangle = \operatorname{argmax}_{P \in \mathcal{P}} \langle u, \mathbb{E}_P(\varphi) \rangle$$

Notice that for a GRF  $\mathbb{E}_P(\varphi) \hat{=}$  pairwise marginals of  $p$

The task reads

$$\langle u, \mu \rangle \rightarrow \max_{\mu}$$

$$\text{s.t. } \mu \in \text{conv } \Phi(\mathcal{S})$$

It is a linear optimisation task, but  $\text{conv } \Phi(\mathcal{S})$  is "complicated". Thus, relax the task to a simpler polytope  $L \supset \text{conv } \Phi(\mathcal{S})$

Back to GRFs

$$\sum_{ij \in E} \sum_{s_i, s_j \in K} \mu_{ij}(s_i, s_j) u_{ij}(s_i, s_j) \rightarrow \max_{\mu}$$

$$\text{s.t. } \sum_{s_i, s_j} \mu_{ij}(s_i, s_j) = 1 \quad \forall \{i, j\} \in E$$

$$\sum_{s_j} \mu_{ij}(s_i, s_j) = \sum_{s_e} \mu_{ie}(s_i, s_e) \quad \forall i, j, e: \{i, j\}, \{i, e\} \in E \\ \forall s_i \in K$$

$$\mu > 0$$

What have we done from abstract perspective:

$$\langle u, \mu \rangle \rightarrow \max_{\mu}$$

$$\text{s.t. } \mu \in [\text{aff } \Phi(\mathcal{S})] \cap \mathbb{R}_+^n$$

The constraint can be written as (see sec. 2)

$$\begin{cases} A\mu = b \\ \mu \geq 0 \end{cases}$$

where  $\text{aff } \mathcal{P}(s) = \{ \mu \in \mathbb{R}^n \mid A\mu = b \}$

The relaxed task reads

$$\langle u, \mu \rangle \rightarrow \max_{\mu}$$

$$\text{s.t. } A\mu = b$$

$$\mu \geq 0$$

Its dual task is

$$\langle b, \psi \rangle \rightarrow \min_{\psi}$$

$$\text{s.t. } A^T \psi$$

Remember:  $\psi$  and  $A^T \psi$  describe reparametrisations!

"Translate" this back to the domain of GRFS  $\rightarrow$   
assignment for seminar