Inference in Description Logics

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Our plan







Inference Problems

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We have introduced syntax and semantics of the language \mathcal{ALC} . Now, let's look on automated reasoning. Having a \mathcal{ALC} theory $\mathcal{K} = (\mathcal{T}, \mathcal{A})$. For TBOX \mathcal{T} and concepts $C_{(i)}$, we want to decide whether

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(unsatisfiability) concept *C* is *unsatisfiable*, i.e. $\mathcal{T} \models C \sqsubseteq \bot$? (subsumption) concept C_1 subsumes concept C_2 , i.e. $\mathcal{T} \models C_2 \sqsubseteq C_1$?

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All these tasks can be reduced to unsatisfiability checking of a single concept ...

Reducting Subsumption to Unsatisfiability

Example

These reductions are straighforward – let's show, how to reduce subsumption checking to unsatisfiability checking. Reduction of other inference problems to unsatisfiability is analogous.

$$(\forall \mathcal{I})(\mathcal{I} \models \mathcal{T} \Longrightarrow \qquad \mathcal{I} \models \underset{\mathcal{T}}{\mathsf{C}_1} \sqsubseteq \underset{\mathcal{C}_2}{\mathsf{C}_2}) \qquad \text{iff}$$

$$(\forall \mathcal{I})(\mathcal{I} \models \mathcal{T} \Longrightarrow \qquad C_1^{\mathcal{I}} \subseteq C_2^{\mathcal{I}}) \qquad \text{iff}$$

$$(\forall \mathcal{I})(\mathcal{I} \models \mathcal{T} \Longrightarrow \ C_{\mathbf{1}}^{\mathcal{I}} \cap (\Delta^{\mathcal{I}} \setminus C_{\mathbf{2}}^{\mathcal{I}}) \subseteq \emptyset \quad \text{ if } \quad$$

$$(\forall \mathcal{I})(\mathcal{I} \models \mathcal{T} \Longrightarrow \mathcal{I} \models \mathcal{C}_1 \sqcap \neg \mathcal{C}_2 \sqsubseteq \bot \quad \text{iff}$$
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 (consistency checking) ABOX A is consistent w.r.t. T (in short if K is consistent).

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- (instance retrieval) find all individuals *a*, for which $\mathcal{T} \cup \mathcal{A} \models C(a)$.

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All these tasks, as well as concept unsatisfiability checking, can be reduced to consistency checking. Under which condition and how ?

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Reduction of concept unsatisfiability to theory consistency

Example

Consider an \mathcal{ALC} theory $\mathcal{K} = (\mathcal{T}, \mathcal{A})$, a concept C and a fresh individual a_f not occuring in \mathcal{K} :

$$(\mathcal{T} \models \mathcal{C} \sqsubseteq \bot) \qquad \text{iff} \\ (\forall \mathcal{I})(\mathcal{I} \models \mathcal{T} \Longrightarrow \mathcal{I} \models \mathcal{C} \sqsubseteq \bot) \qquad \text{iff} \\ (\forall \mathcal{I})(\mathcal{I} \models \mathcal{T} \Longrightarrow \mathcal{C}^{\mathcal{I}} \subseteq \emptyset) \qquad \text{iff} \\ \neg [(\exists \mathcal{I})(\mathcal{I} \models \mathcal{T} \land \mathcal{C}^{\mathcal{I}} \nsubseteq \emptyset)] \qquad \text{iff} \\ \neg [(\exists \mathcal{I})(\mathcal{I} \models \mathcal{T} \land a_{f}^{\mathcal{I}} \in \mathcal{C}^{\mathcal{I}})] \qquad \text{iff} \\ (\mathcal{T}, \{\mathcal{C}(a_{f})\}) \quad \text{is inconsistent} \end{cases}$$

Note that for more expressive description logics than \mathcal{ALC} , the ABOX has to be taken into account as well due to its interaction with TBOX.

Inference Algorithms

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We will introduce tableau algorithms.

Tableaux Algorithms (TAs) serve for checking theory consistency in a simple manner: "Consistency of the given ABOX A w.r.t. TBOX T (resp. consistency of theory K) is proven if we succeed in constructing a model of T ∪ A." (resp. theory K)

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- TAs are not new in DL they were known for FOL as well.

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completion graph is a labeled oriented graph $G = (V_G, E_G, L_G))$, where each node $x \in V_G$ is labeled with a set $L_G(x)$ of concepts and each edge $\langle x, y \rangle \in E_G$ is labeled with a set of edges $L_G(\langle x, y \rangle)^2$

²Next in the text the notation is often shortened as $L_G(x,y)$ instead of $L_G(\langle x,y \rangle)$

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direct clash occurs in a completion graph $G = (V_G, E_G, L_G))$, if $\{A, \neg A\} \subseteq L_G(x)$, or $\bot \in L_G(x)$, for some atomic concept A and a node $\mathbf{x} \in V_{C}$

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Do not mix with notion of complete graphs known from graph theory.

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Completion Graphs (2)

We define also $\mathcal{I} \models G$ iff $\mathcal{I} \models \mathcal{A}_G$, where \mathcal{A}_G is an ABOX constructed from G, as follows

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- $R(a_1, a_2)$ for each edge $\langle a_1, a_2 \rangle \in E_G$ and each role $R \in L_G(a_1, a_2)$

Tableau Algorithm for \mathcal{ALC} with empty TBOX

let's have $\mathcal{K} = (\mathcal{T}, \mathcal{A})$. For a moment, consider for simplicity that $\mathcal{T} = \emptyset$.

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0 (Preprocessing) Transform all concepts appearing in \mathcal{K} to the "negational normal form" (NNF) by equivalent operations known from propositional and predicate logics. As a result, all concepts contain negation \neg at most just before atomic concepts, e.g. $\neg(C_1 \sqcap C_2)$ is equivalent (de Morgan rules) to $\neg C_1 \sqcup \neg C_2$).

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 - ▶ Sets $V_{G_0}, E_{G_0}, L_{G_0}$ are smallest possible with these properties.

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Tableau algorithm for ALC without TBOX (2)

2 (Consistency Check) Current algorithm state is S. If each $G \in S$ contains a direct clash, terminate with result "INCONSISTENT"

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- 2 (Consistency Check) Current algorithm state is S. If each $G \in S$ contains a direct clash, terminate with result "INCONSISTENT"
- 3 (Model Check) Let's choose one $G \in S$ that doesn't contain a direct clash. If G is complete w.r.t. rules shown next, the algorithm terminates with result "CONSISTENT"
- 4 (Rule Application) Find a rule that is applicable to G and apply it. As a result, we obtain from the state S a new state S'. Jump to step 2.

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 \rightarrow_{\sqcap} rule

if $(C_1 \sqcap C_2) \in L_G(a)$ and $\{C_1, C_2\} \nsubseteq L_G(a)$ for some $a \in V_G$.

 \rightarrow_{\Box} rule

if $(C_1 \sqcap C_2) \in L_G(a)$ and $\{C_1, C_2\} \not\subseteq L_G(a)$ for some $a \in V_G$. then $S' = S \cup \{G'\} \setminus \{G\}$, where $G' = (V_G, E_G, L_{G'})$, and $L_{G'}(a) = L_G(a) \cup \{C_1, C_2\}$ and otherwise is the same as L_G .

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 $\begin{array}{l} \text{if } (C_1 \sqcup C_2) \in L_G(a) \text{ and } \{C_1, C_2\} \cap L_G(a) = \emptyset \text{ for some } a \in V_G. \\ \text{then } S' = S \cup \{G_1, G_2\} \setminus \{G\}, \text{ where } G_{(1|2)} = (V_G, E_G, L_{G_{(1|2)}}), \text{ and} \\ L_{G_{(1|2)}}(a) = L_G(a) \cup \{C_{(1|2)}\} \text{ and otherwise is the same as } L_G. \end{array}$

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\rightarrow_{\exists} rule

if $(\exists R \cdot C) \in L_G(a_1)$ and there exists no $a_2 \in V_G$ such that $R \in L_G(a_1, a_2)$ and at the same time $C \in L_G(a_2)$.

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TA Run Example

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Let's check consistency of the ontology $\mathcal{K}_2 = (\emptyset, \mathcal{A}_2)$, where $\mathcal{A}_2 = \{(\exists maDite \cdot Muz \sqcap \exists maDite \cdot Prarodic \sqcap \neg \exists maDite \cdot (Muz \sqcap Prarodic))(JAN)\}).$

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$$\{G_0\} \xrightarrow{\sqcap-\mathsf{rule}} \{G_1\} \xrightarrow{\exists-\mathsf{rule}} \{G_2\} \xrightarrow{\exists-\mathsf{rule}} \{G_3\} \xrightarrow{\forall-\mathsf{rule}} \{G_4\}, \text{ where } G_4 \text{ is}$$



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Example

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- Now, we have to apply the ⊔-rule to the concept ¬Muz ⊔ ¬Rodic either in the label of node "0", or in the label of node "1". Its application e.g. to node "1" we obtain the state {G₅, G₆} (G₅ left, G₆ right)



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Inference in Description Logics

Example

. . .

We see that G₅ contains a direct clash in node "1". The only other option is to go through the graph G₆. By application of ⊔-rule we obtain the state {G₅, G₇, G₈}, where G₇ (left), G₈ (right) are derived from G₆:



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Inference in Description Logics

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• G₇ is complete and without direct clash.

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Example

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- after application of any of the following rules →_□, →_∃, →_∀ graph G is either enriched with a new node, new edge, or labeling of an existing node/edge is enriched. All these operations are finite.

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• Soundness of the TA can be verified as follows. For any $\mathcal{I} \models \mathcal{A}_{G_i}$, it must hold that $\mathcal{I} \models \mathcal{A}_{G_{i+1}}$. We have to show that application of each rule preserves consistency. As an example, let's take the \rightarrow_{\exists} rule:

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- For other rules, the soundness is shown in a similar way.

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Completeness

- To prove completeness of the TA, it is necessary to construct a model for each complete completion graph G that doesn't contain a direct clash. Canonical model \mathcal{I} can be constructed as follows:
 - the domain $\Delta^{\mathcal{I}}$ will consist of all nodes of *G*.

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- What about complexity of the algorithm ?
 - ► P-SPACE (between NP and EXP-TIME).

General Inclusions

We have presented the tableau algorithm for consistency checking of $\mathcal{K} = (\emptyset, \mathcal{A})$. How the situation changes when $\mathcal{T} \neq \emptyset$?

• consider \mathcal{T} containing axioms of the form $C_i \sqsubseteq D_i$ for $1 \le i \le n$. Such \mathcal{T} can be transformed into a single axiom

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where \top_C denotes a concept $(\neg C_1 \sqcup D_1) \sqcap \ldots \sqcap (\neg C_n \sqcup D_n)$

 for each model *I* of the theory *K*, each element of Δ^{*I*} must belong to *T*^{*I*}_{*C*}. How to achieve this ?

What about this ? \rightarrow_{\square} rule

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\rightarrow_{\sqsubset} \mathsf{rule}
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Example

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Consider $\mathcal{K}_3 = (\{Muz \sqsubseteq \exists maRodice \cdot Muz\}, \mathcal{A}_2)$. Then \top_C is $\neg Muz \sqcup \exists maRodice \cdot Muz$. Let's use the introduced TA enriched by $\rightarrow_{\sqsubseteq}$ rule. Repeating several times the application of rules $\rightarrow_{\sqsubseteq}, \rightarrow_{\sqcup}, \rightarrow_{\exists}$ to G_7 (that is not complete w.r.t. to $\rightarrow_{\sqsubseteq}$ rule) from the previous example we get

Example



 \ldots this algorithm doesn't necessarily terminate \odot .

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Inference in Description Logics

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- For \mathcal{ALC} it can be shown that so called *subset blocking* is enough:
 - In completion graph G a node x (not present in ABOX A) is blocked by node y, if there is an oriented path from y to x and L_G(x) ⊆ L_G(y).
- exists rule is only applicable if the node a₁ in its definition is not blocked by another node.

Blocking in TA (2)

• In the previous example, the blocking ensures that node "2" is blocked by node "0" and no other expansion occurs. Which model corresponds to such graph ?

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- Introduced TA with subset blocking is sound, complete and finite decision procedure for \mathcal{ALC} .

Let's play ...

http://krizik.felk.cvut.cz/km/dl/index.html

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From ALC to OWL(2)-DL

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Extending $\dots \mathcal{ALC} \dots$

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Extending $\dots \mathcal{ALC} \dots$

- We have introduced *ALC*, together with a decision procedure. Its expressiveness is higher than propositional calculus, still it is insufficient for many practical applications.
- Let's take a look, how to extend ALC while preserving decidability.

Extending $\dots ALC \dots (2)$

 ${\cal N}$ (Number restructions) are used for restricting the number of successors in the given role for the given concept.

syntax (concept)	semantics
$(\geq n R)$	$\left \left\{ a \middle \left \{b \mid (a,b) \in \mathbf{R}^{\mathcal{I}} \} \right \geq n \right. \right $
$(\leq n R)$	$\left\{ a \middle \left \{ b \mid (a, b) \in \mathbf{R}^{\mathcal{I}} \} \right \leq n \right\}$
(= n R)	$\left\{ a \middle \left \{ b \mid (a, b) \in \mathbf{R}^{\mathcal{I}} \} \right = n \right\}$

Example

Concept *Woman* \sqcap (\leq 3 *hasChild*) denotes women who have at most 3 children.

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Example

- Concept Woman □ (≤ 3 hasChild) denotes women who have at most 3 children.
- What denotes the axiom $Car \sqsubseteq (\geq 4 hasWheel)$?

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Example

- Concept *Woman* \sqcap (\leq 3 *hasChild*) denotes women who have at most 3 children.
- What denotes the axiom $Car \sqsubseteq (\geq 4 hasWheel)$?
- ... and $Bicycle \equiv (= 2 hasWheel)$?

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Extending $\dots ALC \dots$ (3)

Q (Qualified number restrictions) are used for restricting the number of successors of the given type in the given role for the given concept.

Syntax (concept)	Semantics
$(\geq n R C)$	$\left\{ \mathbf{a} \middle \left \{ b \mid (\mathbf{a}, b) \in \mathbf{R}^{\mathcal{I}} \land b^{\mathcal{I}} \in \mathbf{C}^{\mathcal{I}} \} \right \ge n \right\}$
$(\leq n R C)$	$\left\{ \mathbf{a} \middle \left \{ b \mid (\mathbf{a}, b) \in \mathbf{R}^{\mathcal{I}} \land b^{\mathcal{I}} \in \mathbf{C}^{\mathcal{I}} \} \right \leq n \right\}$
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Example

Concept Woman □ (≥ 3 hasChild Man) denotes women who have at least 3 sons.

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Extending $\dots ALC \dots (3)$

Q (Qualified number restrictions) are used for restricting the number of successors of the given type in the given role for the given concept.

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$(\geq n R C)$	$\left\{ \boldsymbol{a} \middle \left \{ \boldsymbol{b} \mid (\boldsymbol{a}, \boldsymbol{b}) \in \boldsymbol{R}^{\mathcal{I}} \land \boldsymbol{b}^{\mathcal{I}} \in \boldsymbol{C}^{\mathcal{I}} \} \right \geq \boldsymbol{n} \right\}$
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Example

- Concept Woman □ (≥ 3 hasChild Man) denotes women who have at least 3 sons.
- What denotes the axiom $Car \sqsubseteq (\geq 4 hasPart Wheel)$?

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Example

- Concept Woman □ (≥ 3 hasChild Man) denotes women who have at least 3 sons.
- What denotes the axiom $Car \sqsubseteq (\geq 4 hasPart Wheel)$?
- Which qualified number restrictions can be expressed in \mathcal{ALC} ?

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Extending $\dots \mathcal{ALC} \dots (4)$

 ${\cal O}$ (Nominals) can be used for naming a concept elements explicitely.

 $\frac{\text{syntax (concept) semantics}}{\{a_1, \dots, a_n\}} \qquad \{a_1^{\mathcal{I}}, \dots, a_n^{\mathcal{I}}\}$

Example

Concept {MALE, FEMALE} denotes a gender concept that must be interpreted with at most two elements. Why at most ?

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Example

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 $\begin{array}{l} \hline Continent \equiv \\ \{EUROPE, ASIA, AMERICA, AUSTRALIA, AFRICA, ANTARCTICA\} ? \end{array}$

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 $\dots \mathcal{ALC} \dots (5)$

 $\mathcal I$ (Inverse roles) are used for defining role inversion.

 $\frac{\text{syntax (role)}}{R^{-}} \qquad \frac{\text{semantics}}{(R^{\mathcal{I}})^{-1}}$

Example

Role *hasChild*⁻ denotes the relationship *hasParent*.

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 $\dots \mathcal{ALC} \dots (5)$

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Example

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- What denotes axiom *Person* \sqsubseteq (= 2 *hasChild*⁻) ?

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Example

- Role hasChild⁻ denotes the relationship hasParent.
- What denotes axiom *Person* \sqsubseteq (= 2 *hasChild*⁻)?
- What denotes axiom *Person* $\sqsubseteq \exists hasChild^- \cdot \exists hasChild \cdot \top$?

Extending $\dots \mathcal{ALC} \dots$ (6)

 trans (Role transitivity axiom) denotes that a role is transitive. Attention – it is not a transitive closure operator.

 $\begin{array}{ll} \text{syntax (axiom)} & \text{semantics} \\ \hline trans(R) & R^{\mathcal{I}} \text{ is transitive} \end{array}$

Example

Role *isPartOf* can be defined as transitive, while role *hasParent* is not. What about roles *hasPart*, *hasPart⁻*, *hasGrandFather⁻*? Extending $\dots \mathcal{ALC} \dots$ (6)

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Example

- Role *isPartOf* can be defined as transitive, while role *hasParent* is not. What about roles *hasPart*, *hasPart⁻*, *hasGrandFather⁻*?
- What is a transitive closure of a relationship ? What is the difference between a transitive closure of *hasDirectBoss^T* and *hasBoss^T*.

Extending $\dots ALC \dots (7)$

 \mathcal{H} (Role hierarchy) serves for expressing role hierarchies (taxonomies) – similarly to concept hierarchies.

syntax (axiom)semantics $R \sqsubseteq S$ $R^{\mathcal{I}} \subseteq S^{\mathcal{I}}$

Example

Role *hasMother* can be defined as a special case of the role *hasParent*.

Extending $\dots ALC \dots (7)$

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syntax (axiom)semantics $R \sqsubseteq S$ $R^{\mathcal{I}} \subseteq S^{\mathcal{I}}$

Example

- Role *hasMother* can be defined as a special case of the role *hasParent*.
- What is the difference between a concept hierarchy *Mother* \sqsubseteq *Parent* and role hierarchy *hasMother* \sqsubseteq *hasParent*.

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Extending $\dots \mathcal{ALC} \dots (8)$

 ${\cal R}$ (role extensions) serve for defining expressive role constructs, like role chains, role disjunctions, etc.

syntax	semantics
$R \circ S \sqsubseteq P$	$R^{\mathcal{I}} \circ S^{\mathcal{I}} \sqsubseteq P^{\mathcal{I}}$
<i>Dis</i> (<i>R</i> , <i>R</i>)	$R^{\mathcal{I}} \cap S^{\mathcal{I}} = \emptyset$
∃ R · Self	$\{a (a,a)\in {\sf R}^{\mathcal I}\}$

Example

How would you define the role *hasUncle* by means of *hasSibling* and *hasParent* ?

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Extending $\dots \mathcal{ALC} \dots (8)$

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- How would you define the role hasUncle by means of hasSibling and hasParent ?
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Example

- How would you define the role hasUncle by means of hasSibling and hasParent ?
- how to express that R is transitive, using a role chain ?
- Whom does the following concept denote $Person \sqcap \exists likes \cdot Self$?

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• From the previously introduced extensions, two prominent decidable supersets of *ALC* can be constructed:

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 - NEXPTIME for \mathcal{SHOIN}
 - ► N2EXPTIME for *SROIQ*

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• How to express e.g. that "A cousin is someone whose parent is a sibling of your parent." ?

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- ... we need rules, like

 $\begin{array}{ll} \textit{hasCousin}(?c_1,?c_2) \leftarrow &\textit{hasParent}(?c_1,?p_1),\textit{hasParent}(?c_2,?p_2),\\ &\textit{Man}(?c_2),\textit{hasSibling}(?p_1,?p_2) \end{array}$

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• in general, each variable can bind domain elements (similarly to undistinguished variables in the next lecture); however, such version is *undecidable*.

DL-safe rules

DL-safe rules are decidable conjunctive rules where each variable **only binds individuals** (i.e. representation of domain elements, not domain elements themselves).

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Modal Logic introduces modal operators - possibility/necessity, used in multiagent systems.

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Modal Logic introduces modal operators - possibility/necessity, used in multiagent systems.

Example

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Modal Logic introduces modal operators - possibility/necessity, used in multiagent systems.



Modal Logic introduces modal operators - possibility/necessity, used in multiagent systems.

Example (□ represents e.g. the "believe" operator of an agent) □(Man □ Person □ ∀hasFather · Man) (1)

• As ALC is a syntactic variant to a multi-modal propositional logic, where each role represents the accessibility relationa between worlds in Kripke structure, the previous example can be transformed to the modal logic as:

Vague Knowledge - fuzzy, probabilistic and possibilistic extensions

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Modal Logic introduces modal operators - possibility/necessity, used in multiagent systems.

Vague Knowledge - fuzzy, probabilistic and possibilistic extensions

Data Types (D) allow integrating a data domain (numbers, strings), e.g. *Person* $\sqcap \exists hasAge \cdot 23$ represents the concept describing "23-years old persons".

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