# **Graphical probabilistic models – inference**

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http://cw.felk.cvut.cz/wiki/courses/ae4m33rzn/start

# Agenda

#### Bayesian networks

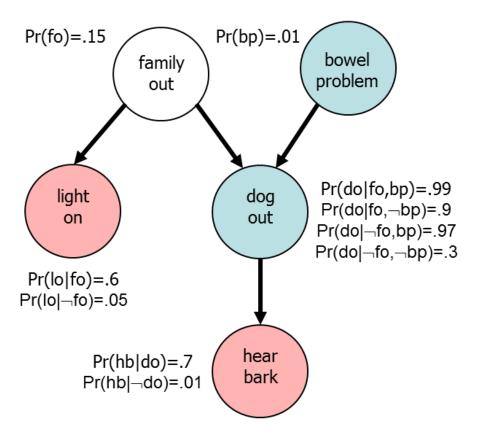
- fundamental tasks,
- exact inference and its complexity
  - straightforward enumeration
    - \* easy to understand but inefficient computes joint probabilities,
    - \* descends to the level of atomic events,
  - acceleration by variable elimination,
- exact × approximate algorithms,
  - rejection sampling,
  - likelihood weighting,
  - Gibbs sampling,

#### **Bayesian networks – fundamental tasks**

- inference reasoning, deduction
  - from observed events assumes on probability of other events,
  - observations ( $\mathbf{E}$  a set of evidence variables,  $\mathbf{e}$  a particular event),
  - target variables ( $\mathbf{Q}$  a set of query variables,  $\mathbf{Q}$  a particular query variable),
  - $\Pr(\mathbf{Q}|\mathbf{e})$ , resp.  $\Pr(Q \in \mathbf{Q}|\mathbf{e})$  to be found,
  - network is known (both graph and CPTs),
- learning network parameters from data
  - network structure (graph) is given,
  - "only" quantitative parameters (CPTs) to be optimized,
- learning network structure from data
  - propose an optimal network structure
    - \* which edges of the complete graph shall be employed?,
  - too many arcs  $\rightarrow$  complicated model,
  - too few arcs  $\rightarrow$  inaccurate model.

### **Probabilistic network** – inference by enumeration

- Let us observe the following events:
  - no barking heard,
  - the door light is on.
- What is the prob of family being out?
  - searching for  $Pr(fo|lo, \neg hb)$ .
- Will observation influence the target event?
  - light on supports departure hypothesis,
  - no barking suggests dog inside,
  - the dog is in house when it is
    - \* rather healthy,
    - \* the family is at home.



#### inference by enumeration

- conditional probs calculated by summing the elements of joint probability table,
- how to find the joint probabilities (the table is not given)?
  - BN definition suggests:

$$\begin{split} Pr(FO, BP, DO, LO, HB) = \\ = Pr(FO)Pr(BP)Pr(DO|FO, BP)Pr(LO|FO)Pr(HB|DO) \end{split}$$

- answer to the question?
  - conditional probability definition suggests:  $Pr(fo|lo, \neg hb) = \frac{Pr(fo, lo, \neg hb)}{Pr(lo, \neg hb)}$
  - by joint prob marginalization we get:

$$\begin{split} Pr(fo, lo, \neg hb) &= \sum_{BP, DO} Pr(fo, BP, DO, lo, \neg hb) \\ Pr(fo, lo, \neg hb) &= Pr(fo, bp, do, lo, \neg hb) + Pr(fo, bp, \neg do, lo, \neg hb) + \\ &+ Pr(fo, \neg bp, do, lo, \neg hb) + Pr(fo, \neg bp, \neg do, lo, \neg hb) = .15 \times .01 \times .99 \times .6 \times .3 + .15 \times .01 \times .01 \times .6 \times .99 + .15 \times .99 \times .9 \times .6 \times .3 + .15 \times .99 \times .1 \times .6 \times .99 = .033 \\ Pr(lo, \neg hb) &= Pr(fo, lo, \neg hb) + Pr(\neg fo, lo, \neg hb) = .066 \end{split}$$

#### **Probabilistic network** – inference by enumeration

- after substitution:

$$Pr(fo|lo, \neg hb) = \frac{Pr(fo, lo, \neg hb)}{Pr(lo, \neg hb)} = \frac{.033}{.066} = 0.5$$

- posterior probability  $Pr(fo|lo, \neg hb)$  is higher then the prior Pr(fo) = 0.15.

- can we assume on complexity?
  - instead of  $2^5 1$ =31 probs (either conditional or joint) 10 is needed only,
  - however, joint probs are enumerated to answer the query

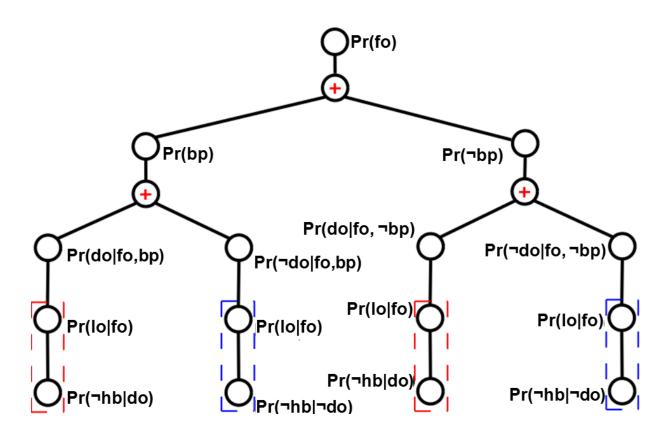
\* it is easy to show that inference remains a NP-hard problem,

to simply move summations left-to-right makes a difference, but not a principal one
 \* see the evaluation tree on the next slide,

$$\begin{split} Pr(fo, lo, \neg hb) &= \sum_{BP, DO} Pr(fo, BP, DO, lo, \neg hb) = \\ &= Pr(fo) \sum_{BP} Pr(BP) \sum_{DO} Pr(DO|fo, BP) Pr(lo|fo) Pr(\neg hb|DO) \end{split}$$

- inference by enumeration is an intelligible, but unfortunately inefficient procedure,
- solution: minimize recomputations, special network types or approximate inference.

#### Inference by enumeration – evaluation tree



• Complexity: time  $\mathcal{O}(n2^d)$ , memory  $\mathcal{O}(n)$ 

-n ... the number of variables, e ... the number of evidence variables, d=n-e,

- resource of inefficiency: recomputations ( $Pr(lo|fo) \times Pr(\neg hb|DO)$  for each BP value)
  - variable ordering makes a difference Pr(lo|fo) shall be moved forward.

#### variable elimination procedure

- 1. pre-computes **factors** to remove the inefficiency shown in the previous slide
  - factors serve for recycling the earlier computed intermediate results,
  - some variables are eliminated by summing them out,

 $\sum_{P} f_1 \times \cdots \times f_k = f_1 \times \cdots \times f_i \times \sum_{P} f_{i+1} \times \cdots \times f_k = f_1 \times \cdots \times f_i \times f_{\bar{P}}$ , assumes that  $f_1, \ldots, f_i$  do not depend on P,

when multiplying factors, the pointwise product is computed  $f_1(x_1, ..., x_j, y_1, ..., y_k) \times f_2(y_1, ..., y_k, z_1, ..., z_l) = f(x_1, ..., x_j, y_1, ..., y_k, z_1, ..., z_l)$ 

eventual enumeration over  $P_1$  variable, which takes all (two) possible values  $f_{\bar{P}_1}(P_2, ..., P_k) = \sum_{P_1} f_1(P_1, P_2, ..., P_k)$ ,

 execution efficiency is influenced by the variable ordering when computing, (finding the best order is NP-hard problem, can be optimized heuristically too),

# **Inference by enumeration – straightforward improvements**

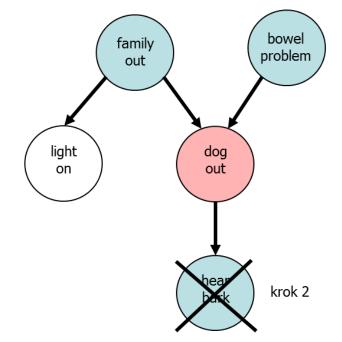
#### variable elimination procedure

- 2. does not consider variables irrelevant to the query
  - all the leaves that are neither query nor evidence variable,
  - the rule can be applied recursively.

• example: Pr(lo|do)

- what is prob that the door light is shining if the dog is in the garden?
- we will enumerate Pr(LO, do), since:

$$Pr(lo|do) = \frac{Pr(lo,do)}{Pr(do)} = \frac{Pr(lo,do)}{Pr(lo,do) + Pr(\neg lo,do)}$$



### Inference by enumeration – variable elimination

• HB is irrelevant to the particular query, why?

$$\sum_{HB} Pr(HB|do) = 1$$

$$\begin{aligned} Pr(LO, do) &= \sum_{FO, BP, HB} Pr(FO) Pr(BP) Pr(do|FO, BP) Pr(LO|FO) Pr(HB|do) = \\ &= \sum_{FO} Pr(FO) Pr(LO|FO) \sum_{BP} Pr(BP) Pr(do|FO, BP) \sum_{HB} Pr(HB|do) \end{aligned}$$

• after omitting the last invariant, **factorization** may take place

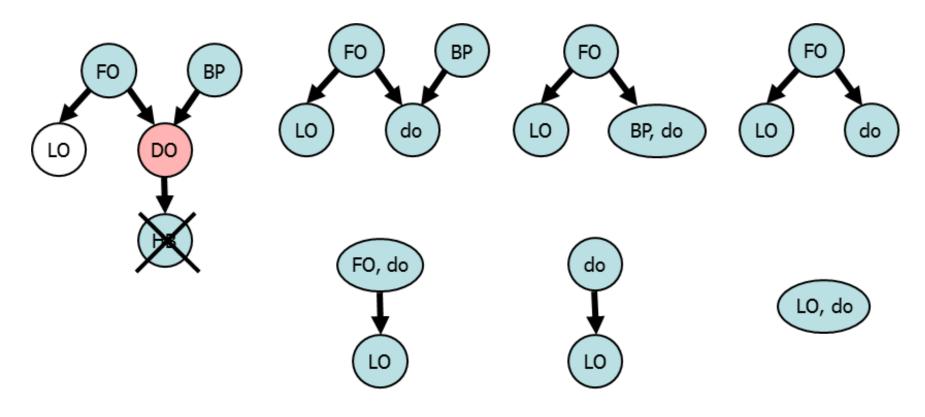
$$\begin{split} Pr(LO, do) &= \sum_{FO} Pr(FO) Pr(LO|FO) \sum_{BP} Pr(BP) Pr(do|FO, BP) = \\ &= \sum_{FO} Pr(FO) Pr(LO|FO) f_{\overline{BP}}(do|FO) = \sum_{FO} f_{\overline{BP}, do}(FO) Pr(LO|FO) = \\ &= f_{\overline{FO}, \overline{BP}, do}(LO) \end{split}$$

having the last factor (a table of two elements), one can read

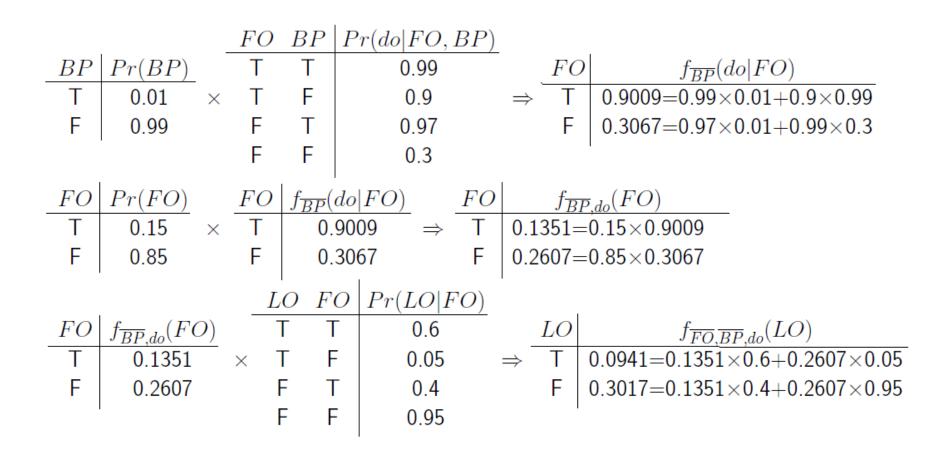
$$Pr(lo|do) = \frac{f_{\overline{FO},\overline{BP},do}(lo)}{f_{\overline{FO},\overline{BP},do}(lo) + f_{\overline{FO},\overline{BP},do}(\neg lo)} = \frac{0.0941}{0.0941 + 0.3017} = \frac{0.0941}{0.3958} = 0.24$$

## Variable elimination – factor computations

- factors are enumerated from CPTs by summing out variables
  - $\text{ sum out BP: } CPT(DO) \And CPT(BP) \rightarrow f_{\overline{BP}}(do|FO)$
  - reformulate into: CPT(FO) &  $f_{\overline{BP}}(do|FO) \rightarrow f_{\overline{BP},do}(FO)$
  - $-\text{ sum out FO: } f_{\overline{BP},do}(FO) \And CPT(LO) \rightarrow f_{\overline{FO},\overline{BP},do}(LO)$



#### Variable elimination – factor computations



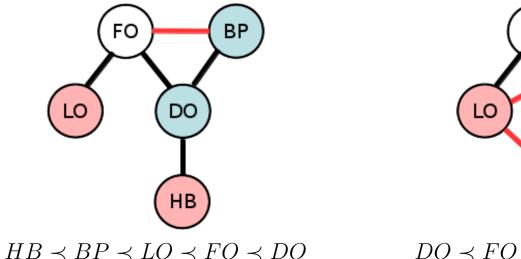
# Inference by enumeration – comparison of the number of operations

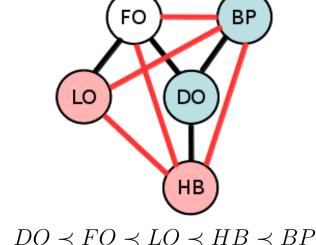
- let us take the last example
  - namely the total number of sums and products in Pr(LO, do),
  - (the final Pr(lo|do) enumeration is identical for all procedures),
- naïve enumeration, no evaluation tree
  - 4 products (5 vars)  $\times 2^4$  (# atomic events on unevidenced variables) +  $2^4 2$  sums,
  - in total 78 operations,
- using evaluation tree and a proper reordering of variables
  - takes the ordering

 $Pr(LO, do) = \sum_{FO} Pr(FO) Pr(LO|FO) \sum_{BP} Pr(BP) Pr(do|FO, BP) \sum_{HB} Pr(HB|do)$ 

- in total 38 operations,
- with variable elimination on top of that
  - in total 14 operations (6 in Tab1, 2 in Tab2, 6 in Tab3).

- Given by the network structure and the variable ordering
  - exponential in the size of the largest clique in the induced graph,
  - somewhere between linear and NP-hard,
- induced graph
  - undirected graph, the edge exists if two variables both appear in some intermediate factor induced by the given variable ordering,





# Variable elimination – variable ordering

minimize the number of fill edges in induced graph

- edges introduced in the elimination step,
- NP-hard problem in general
  - greedy local methods often find near-optimal solution,
  - min-fill heuristic

\* vertex cost is the number of edges added to the graph due to its elimination,

- always take the node that minimizes the heuristic, no backtrack.

• Step 1:

 $Pr(FO, \ldots, HB) = f_{FO}(FO)f_{BP}(BP)f_{DO}(DO, FO, BP)f_{LO}(LO, FO)f_{HB}(HB, DO)$ 

var	intermediate factor	min-fill
FO	$f_{FO}(FO)f_{DO}(DO, FO, BP)f_{LO}(LO, FO)$	3
BP	$f_{BP}(BP)f_{DO}(DO, FO, BP)$	1
DO	$f_{DO}(DO, FO, BP)f_{HB}(HB, DO)$	3
LO	$f_{LO}(LO,FO)$	0
HB	$f_{HB}(HB, DO)$	0

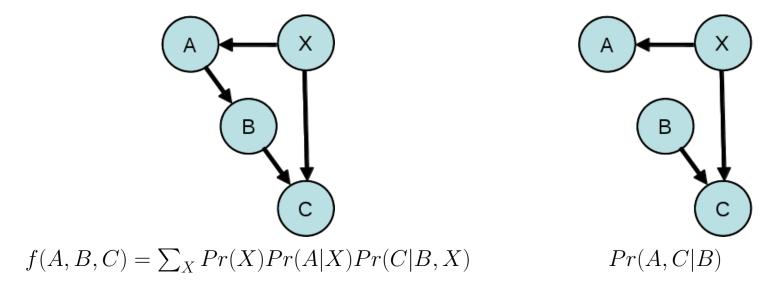
# **Semantics of factors**

Factors

- multidimensional arrays (the same as CPTs),
- often correspond to marginal or conditional probabilities,
- $-% \left( {{\left( {{{\rm{initialized}}{\rm{with}}\;{\rm{CPTs}}} \right)}} \right)$  constants  ${\rm{CPTs}}$  ,
- some intermediate factors differ from any probability in the network

\* eliminate X from the left network,

- \* the resulting factor does not agree with any prob in the left network,
- \* it gives a conditional prob in the right network.



# **Approximate inference by stochastic sampling**

- a general Monte-Carlo method, samples from the joint prob distribution,
- estimates the target conditional probability (query) from a sample set,
- the joint prob distribution is not explicitly given, its factorization is available only (network),
- the most straightforward is direct forward sampling
  - 1. topologically sort the network nodes
    - for every edge it holds that parent comes before its children in the ordering,
  - 2. instantiate variables along the topological ordering

- take  $Pr(P_j | parents(P_j))$ , randomly sample  $P_j$ ,

- 3. repeat step 2 for all the samples (the sample size M is given a priori),
- from samples to probabilities?
  - $Pr(q|\mathbf{e}) \approx \frac{N(q,\mathbf{e})}{N(\mathbf{e})}$
  - samples that contradict evidence not used,
  - forward sampling gets inefficient if  $Pr(\mathbf{e})$  is small,
- rejection sampling brings a slight improvement
  - rejects partially generated samples as soon as they violate the evidence event  $e_{i}$ ,
  - sample generation may stop early.

### **Rejection sampling – example**

- FAMILY example, estimate  $Pr(fo|lo, \neg hb)$ 
  - 1. topologically sort the network nodes

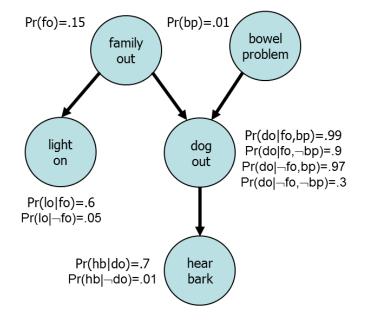
- e.g.,  $\langle FO, BP, LO, DO, HB \rangle$  (or  $\langle BP, FO, DO, HB, LO \rangle$ , etc.)

2. instantiate variables along the topological ordering

$$- Pr(FO) \rightarrow \neg fo, Pr(BP) \rightarrow \neg bp,$$
  
 $Pr(LO|\neg fo) \rightarrow lo, Pr(DO|\neg fo, \neg bp) \rightarrow \neg do, Pr(HB|\neg do) \rightarrow \neg hb$ 

- sample agrees with the evidence  $\mathbf{e} = lo \wedge \neg hb$ , no rejection needed,
- 3. generate 1000 samples, repeat step 2,
- let N(fo, lo, ¬hb) is 491 (the number of samples with the given values of three variables under consideration),
- in rejection sampling  $N(\mathbf{e})$  necessarily equals M,

$$-Pr(fo|lo, \neg hb) \approx \frac{N(q, \mathbf{e})}{N(\mathbf{e})} = \frac{491}{1000} = 0.491$$



# Likelihood weighting

- Likelihood weighting is a sampling method that avoids necessity to reject samples
  - the values of  ${f E}$  are fixed, the rest of variables is sampled only,
  - however, not all events are equally probable, samples need to be weighted,
  - the weight equals to the likelihood of the event given the evidence,

• 
$$\forall$$
 samples  $p^m = \{P_1 = p_1^m, \dots, P_n = p_n^m\}$ ,  $m \in \{1, \dots, M\}$ 

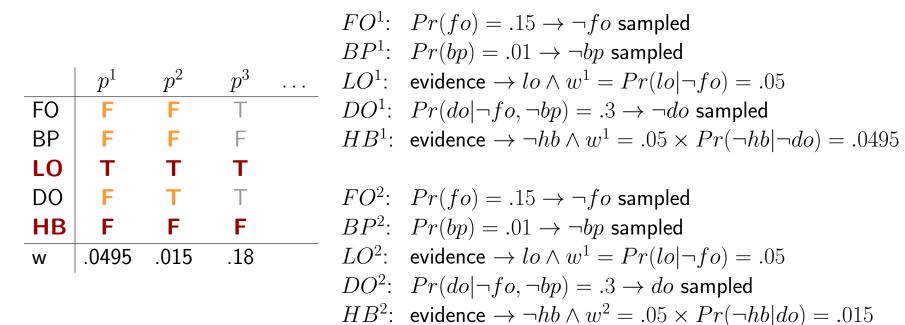
- 1.  $w^m \leftarrow 1$  (initialize the sample weight)
- 2.  $\forall j \in \{1, \ldots, n\}$  (instantiate variables along the topological ordering)
  - if  $P_j \in \mathbf{E}$  then take  $p_j^m$  from  $\mathbf{e}$  and  $w^m \leftarrow w^m \times Pr(P_j | parents(P_j))$ ,
  - otherwise randomly sample  $p_j^m$  from  $Pr(P_j|parents(P_j))$ ,
- from samples to probabilities?
  - evidence holds in all samples (by definition),
  - weighted averaging is applied to find  $Pr(Q = P_i | \mathbf{e})$

$$Pr(p_i|\mathbf{e}) \approx \frac{\sum_{m=1}^{M} w^m \delta(p_i^m, p_i)}{\sum_{m=1}^{M} w^m} \ \delta(i, j) = \begin{cases} 1 & \text{for } i = j \\ 0 & \text{for } i \neq j \end{cases}$$

- nevertheless, samples may have very low weights
  - it can also turn out inefficient in large networks with evidences occuring late in the ordering.

#### Likelihood weighting – example

• let us approximate  $Pr(fo|lo, \neg hb)$  (its exact value computed earlier is 0.5),



• a very rough estimate having 3 samples only

$$Pr(fo|lo, \neg hb) \approx \frac{.18}{.0495 + .015 + .18} = .74$$

# **Gibbs sampling**

- a Markov chain method the next state depends purely on the current state
  - state = sample, generates dependent samples!
  - as it is a **Monte-Carlo** method as well  $\rightarrow$  MCMC,
- efficient sampling method namely when some of BN variable states are known
  - it again samples nonevidence variables only, the samples never rejected,
- sampling process samples  $p^m = \{P_1 = p_1^m, \dots, P_n = p_n^m\}$ ,  $m \in \{1, \dots, M\}$ 
  - 1. fix states of all observed variables from E (in all samples),
  - 2. the other variables initialized in  $p^0$  randomly,

3. generate 
$$p^{m}$$
 from  $p^{m-1}$  ( $\forall P_{i} \notin E$ )  
 $-p_{1}^{m} \leftarrow Pr(P_{1}|p_{2}^{m-1}, \dots, p_{n}^{m-1}),$   
 $-p_{2}^{m} \leftarrow Pr(P_{2}|p_{1}^{m}, p_{3}^{m-1}, \dots, p_{n}^{m-1}),$   
 $-\dots,$   
 $-p_{n}^{m} \leftarrow Pr(P_{n}|p_{1}^{m}, \dots, p_{n-1}^{m}),$ 

4. repeat step 3 for  $m \in \{1, \ldots, M\}$ .

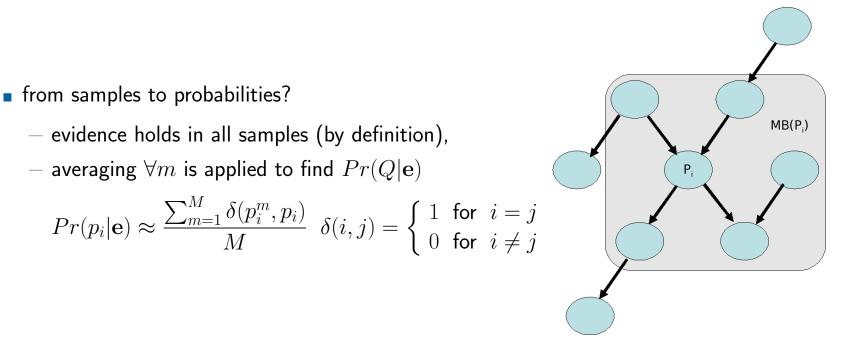
# **Gibbs sampling**

• probs  $Pr(P_i|P_1, \ldots, P_{i-1}, P_{i+1}, \ldots, P_n) = Pr(P_i|P \setminus P_i)$  not explicitly given ...

- to enumerate them, only their BN neighborhood needs to be known

$$Pr(P_i|P \setminus P_i) \propto Pr(P_i|parents(P_i)) \prod_{\forall P_j, P_i \in parents(P_j)} Pr(P_j|parents(P_j))$$

- the neighborhood is called Markov blanket (MB),
- -MB covers the node, its parents, its children and their parents,
- $-MB(P_i)$  is the minimum set of nodes that d-separates  $P_i$  from the rest of the network.



#### **Gibbs sampling – example**

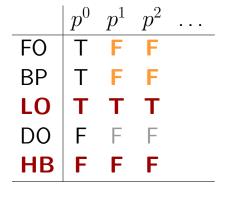
• let us approximate  $Pr(fo|lo, \neg hb)$  (its exact value computed earlier is 0.5),

#### $p^0$ : random init of unevidenced variables

$$\begin{array}{ll} FO^1 \!\!: & Pr^*(fo) \propto Pr(fo) \times Pr(lo|fo) \times Pr(\neg do|fo, bp) \\ & Pr^*(\neg fo) \propto Pr(\neg fo) \times Pr(lo|\neg fo) \times Pr(\neg do|\neg fo, bp) \\ & Pr^*(fo) \propto .15 \times .6 \times .01 = 9 \times 10^{-4} \rightarrow \times \alpha_{FO}^1 = .41 \\ & Pr^*(\neg fo) \propto .85 \times .05 \times .03 = 1.275 \times 10^{-3} \rightarrow \times \alpha_{FO}^1 = .59 \\ & \alpha_{FO}^1 = \frac{1}{Pr^*(fo) + Pr^*(\neg fo)} = 460 \\ BP^1 \!\!: & Pr^*(bp) \propto Pr(bp) \times Pr(\neg do|\neg fo, bp) = .01 \times .03 = .0003 \\ & Pr^*(\neg bp) \propto Pr(\neg bp) \times Pr(\neg do|\neg fo, \neg bp) = .99 \times .7 = 0.693 \\ & \alpha_{BP}^1 = \frac{1}{Pr^*(bp) + Pr^*(\neg bp)} = 1.44 \rightarrow Pr^*(bp) = 4 \times 10^{-4} \\ DO^1 \!\!: & \text{ by analogy, } |MB(DO)| = 5 \end{array}$$

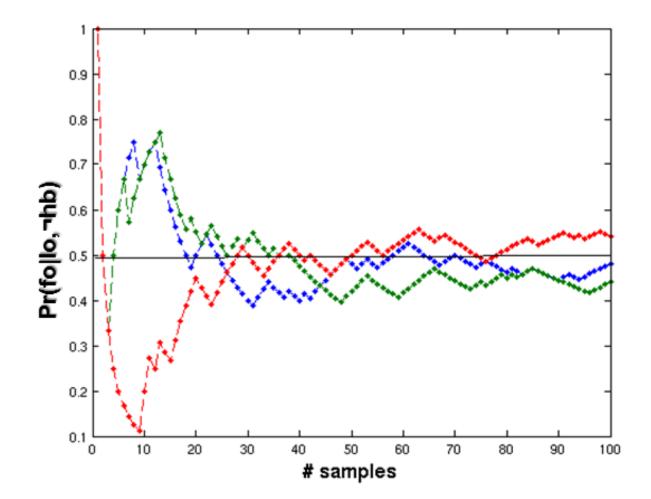
 $FO^2$ : BP value was switched, substitution is  $Pr(DO|FO, \neg bp)$  $Pr^*(fo) = .21 Pr^*(\neg fo) = .79$ 

$$BP^2$$
: the same probs as is sample 1



# **Gibbs sampling – example**

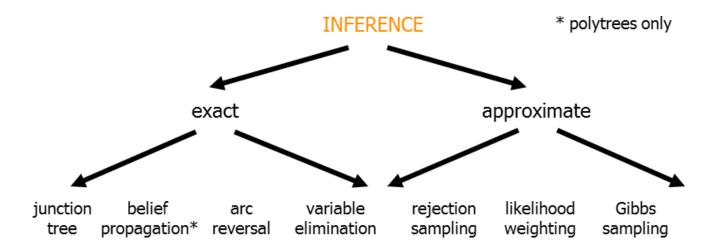
- BN Matlab Toolbox, aproximation of  $Pr(fo|lo, \neg hb)$ ,
- gibbs\_sampling\_inf\_engine, three independent runs with 100 samples.



# **Summary**

- independence and conditional independence remarkably simplify prob model
  - still, BN inference remains generally NP-hard wrt the number of network variables,
  - inference complexity grows with the number of network edges
    - \* naïve Bayes model linear complexity,
    - \* general complexity estimate from the size of maximal clique of induced graph,
  - inference complexity can be reduced by constraining model structure
     \* special network types (singly connected), e.g. trees one parent only,
  - inference time can be shorten when exact answer is not required

\* approximate inference, typically (but not only) stochastic sampling.



Russell, Norvig: AI: A Modern Approach, Uncertain Knowledge and Reasoning (Part V)

- probabilistic reasoning (chapter 14 or 15, depends on the edition),
- online on Google books: http://books.google.com/books?id=8jZBksh-bUMC,
- Norvig's videos on probabilistic inference:
  - \* http://www.youtube.com/watch?v=q5DHnmHtVmc&feature=plcp,
- Koller, Friedman: Probabilistic Graphical Models: Principles and Techniques.
  - book: http://pgm.stanford.edu/, chapter II, inference, variable elimination,
  - coursera: https://www.coursera.org/course/pgm.