

Scheduling

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Obsah

- 1 Introduction to Scheduling
 - Methodology Overview
 - Real Problem Examples
 - Terminology
- 2 Classification of Scheduling Problems
 - Machine environment
 - Job Characteristics
 - Optimization
- 3 Local Search Methods
 - General
 - Tabu Search



Time, schedules, and resources ^[RN10]

- Classical planning representation
 - What to do
 - What order
- Extensions
 - How long an action takes
 - When it occurs
- Scheduling
 - Temporal constraints,
 - Resource constraints.
- Examples
 - Airline scheduling,
 - Which aircraft is assigned to which flights
 - Departure and arrival time,
 - A number of employees is limited.
 - An aircraft crew, that serves during one flight, cannot be assigned to another flight.



General Approach ^[Rud13]

Introduction

- Graham's classification of scheduling problems

General solving methods

- Exact solving method
 - Branch and bound methods
- Heuristics
 - dispatching rules
 - beam search
 - local search:
simulated annealing, tabu search, genetic algorithms
- Mathematical programming: formulation
 - linear programming
 - integer programming
- Constraining satisfaction programming



Specific approach ^[Rud13]

- **Project planning:** project representation, critical path, time and cost trading, working force
- **Scheduling:** dispatching rules, branch and bound method, beam search,
- **Scheduling in manufacturing:** line with flexible time, with fixed time, with parallel working stations.
- **Reservations:** interval scheduling, reservation system with reserves.
- **Timetabling:** scheduling with operators, scheduling with work force.
- **Scheduling of employees:** free day scheduling, work shift scheduling, cyclic shift scheduling.
- **University scheduling:** theory and practice



Schedule ^[Rud13]

Schedule:

- determined by **tasks assignments to given times slots using given resources**, where the tasks should be performed

Complete schedule:

- all tasks of a given problem are covered by the schedule

Partial schedule:

- some tasks of a given problem are not resolved/assigned

Consistent schedule:

- a schedule in which **all constraints are satisfied** w.r.t. resource and tasks, e.g.
 - at most one tasks is performed on a signal machine with a unit capacity

Consistent complete schedule vs. consistent partial schedule

Optimal schedule:

- the assignments of tasks to machines is optimal w.r.t. to a given optimization criterion, e.g..
 - $\min C_{max}$: makespan (completion time of the last task) is minimum

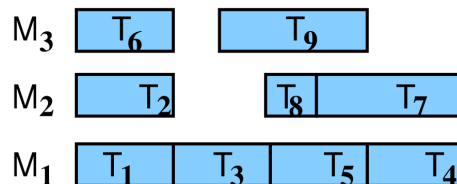


Terminology of Scheduling [Rud13]

Scheduling

concerns optimal allocation or assignment of **resources**, to a set of **tasks or activities** over **time**

- limited amount of resources,
 - gain maximization given constraints
- Machines $M_i, i = 1, \dots, m$
 - Jobs $J_j, j = 1, \dots, n$
 - **(i, j) an operation** or processing of jobs j on machine i
 - a job can be composed from several operations,
 - example: job 4 has three operations with non-zero processing time $(2,4),(3,4),(6,4)$, i.e. it is performed on machines 2,3,6



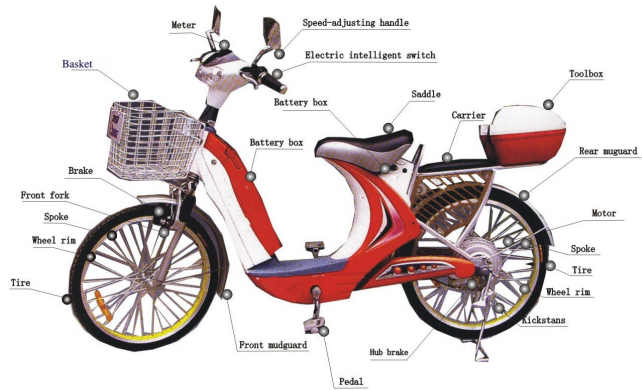
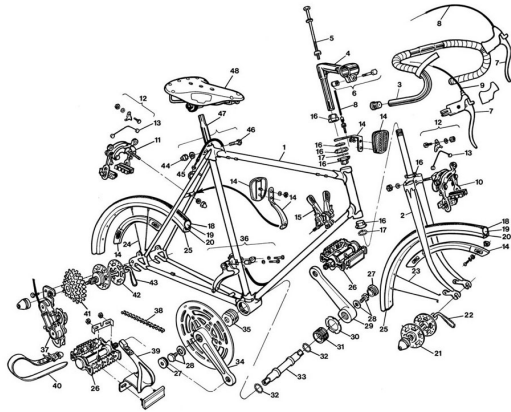
Machine-oriented Gantt chart

Static and dynamic parameters of jobs [Rud13]

- Static parameters of job
 - **processing time** p_{ij}, p_j :
processing time of job j on machine i
 - **release date of j** r_j :
earliest starting time of jobs j
 - **due date** d_j :
committed completion time of job j (preference)
 - vs. **deadline**:
time, when job j must be finished at latest (requirement)
 - **weight** w_j :
importance of job j relatively to other jobs in the system
- Dynamic parameters of job
 - **start time** S_{ij}, S_j :
time when job j is started on machine i
 - **completion time** C_{ij}, C_j :
time when job j execution on machine i is finished



Example: bike assembly [Rud13]

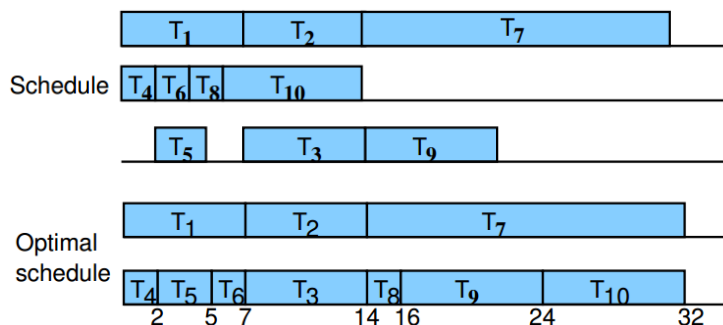
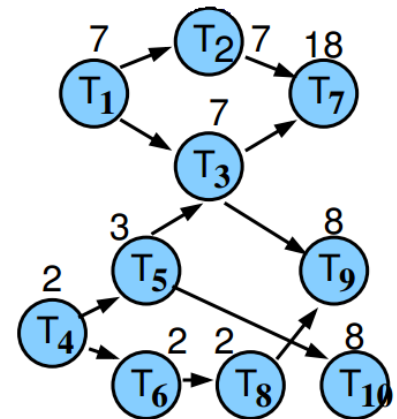


- 10 jobs with given processing time
- Precedence constraints
 - a given job can be executed after a specified subset of jobs
- Non-preemptive jobs
 - jobs cannot be interrupted
- Optimization criteria
 - makespan minimization
 - worker number minimization



Example: bike assembly [Rud13]

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Scheduling Examples ^[Rud13]

- Scheduling of semiconductor manufacturing
 - a large amount of heterogenous products,
 - different amounts of produced items,
 - machine setup cost, required processing time guarantees
- Scheduling of supply chains
 - ex. a forest region → paper production → products from paper → distribution centers → end user
 - manufacturing cost, transport, storage minimization,
- Scheduling of paper production
 - input - wood, output - paper roles, expensive machines, different sorts of papers,
 - storage minimization
- Car assembly lines
 - manufacturing of different types of cars with different equipment,
 - throughput optimization, load balancing
- Lemonade filling into bottles
 - 4 flavors, each flavor has its own filling time,
 - cycle time minimization, one machine



Scheduling Examples II ^[Rud13]

- Scheduling of hospital nurses
 - different numbers of nurses in working days and weekends,
 - weaker requirements for night shift rostering,
 - assignment of nurses to shifts, requirement satisfaction, cost minimization
- Grid computing scheduling
 - clusters, supercomputers, desktops, special devices,
 - scheduling of computation jobs and related resources,
 - scheduling of data transfers and data processing
- University scheduling
 - Time and rooms selection for subject education at universities
 - constraints given for subject placement,
 - preference requirements for time and room optimization,
 - minimization of overlapping subjects for all students,



Scheduling vs. timetabling ^[Rud13]

Scheduling . . . scheduling/planning

- resource allocation for given constraints over objects placed in time-space so that total cost of given resources is minimized,
- focus is given on **object ordering**, precedence conditions
 - ex. manufacturing scheduling: operation ordering determination, time dependencies of operation is important,
- **schedule**: specifies space and time information

Timetabling

- resource allocation for given constraints over objects placed in time-space so that given criteria are met as much as possible,
- focus is given on **time placement of objects**
- **time horizon is often given in advance** (a number of scheduled slots)
 - ex. education timetabling: time and a place is assigned to subjects
- **timetable**: shows when and where events are performed.

Sequencing and Rostering ^[Rud13]

Sequencing

- for given constraints:
 - a construction of job order in which they will be executed
- **sequence**
 - an order in which jobs are executed
- ex. lemonade filling into bottles

Rostering

- resource allocation for given constraints into slots using patterns
- **roster**
 - a list of person names, that determines what jobs are executed and when
- ex. a roster of hospital nurses, a roster of bus drivers

Graham's classification ^[Rud13, Nie10]Graham's classification $\alpha|\beta|\gamma$

(Many) Scheduling problems can be described by a three field notation

- α : the machine environment
 - describes a way of job assignments to machines
- β : the job characteristics,
 - describes constraints applied to jobs
- γ : the objective criterion to be minimized
- complexity for combinations of scheduling problems

Examples

- $P3|prec|C_{max}$: bike assembly
- $Pm|r_j|\sum w_j C_j$: parallel machines

Machine Environment α ^[Rud13, Nie10]

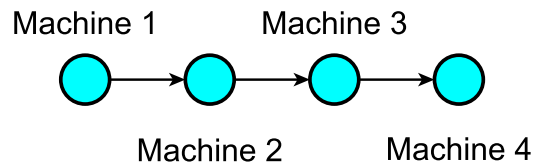
- **Single machine** ($\alpha = 1$): $1|\dots|\dots$
- **Identical parallel machines** Pm
 - m identical machines working in parallel with the same speed
 - each job consist of a single operation,
 - each job processed by any of the machines m for p_j time units
- **Uniform parallel machines** Qm
 - processing time of job j on machine i propotional to its speed v_i
 - $p_{ij} = p_j/v_i$
 - ex. several computers with processor different speed
- **Unrelated parallel machines** Rm
 - machine have different speed for different jobs
 - machine i process job j with speed v_{ij}
 - $p_{ij} = p_j/v_{ij}$
 - ex. vector computer computes vector tasks faster than a classical PC



Shop Problems ^[Rud13, Nie10]

• Shop Problems

- each task is executed sequentially on several machines
 - job j consists of several operations (i, j)
 - operation (i, j) of jobs j is performed on machine i with time p_{ij}
 - ex: job j with 4 operations $(1, j), (2, j), (3, j), (4, j)$



- Shop problems are classical studied in details in **operations research**
- Real problems are often more complicated
 - utilization of knowledge on subproblems or simplified problems in solutions



Flow shop α ^[Rud13, Nie10]

• Flow shop F_m

- m machines in series
- each job has to be processed on each machine
- all jobs follow the same route:
 - first machine 1, then machine 2, ...
- if the jobs have to be processed in the same order on all machines, we have a **permutation** flow shop

• Flexible flow shop FF_s

- a generalization of flow shop problem
- s phases, a set of parallel machines is assigned to each phase
- i.e. flow shop with s parallel machines
- each job has to be processed by all phases in the same order
 - first on a machine of phase 1, then on a machine of phase 2, ...
- the task can be performed on any machine assigned to a given phase



Open shop & job shop [Rud13, Nie10]

- **Job shop J_m**
 - flow shop with m machines
 - each job has its individual predetermined route to follow
 - processing time of a given jobs might be zero for some machines
 - $(i, j) \rightarrow (k, j)$ specifies that job j is performed on machine i earlier than on machine k
 - example: $(2, j) \rightarrow (1, j) \rightarrow (3, j) \rightarrow (4, j)$
- **Open shop O_m**
 - flow shop with m machines
 - processing time of a given jobs might be zero for some machines
 - no routing restrictions (this is a scheduling decision)

Constraints β [Rud13, Nie10]

- **Precedence constraints $prec$**
 - linear sequence, tree structure
 - for jobs a, b we write $a \rightarrow b$, with meaning of $S_a + p_a \leq S_b$
 - example: bike assembly
- **Preemptions $pmtn$**
 - a job with a higher priority interrupts the current job
- **Machine suitability M_j**
 - a subset of machines M_j , on which job j can be executed
 - room assignment: appropriate size of the classroom
 - games: a computer with a HW graphical library
- **Work force constraints W, W_ℓ**
 - another sort of machines is introduced to the problem
 - machines need to be served by operators and jobs can be performed only if operators are available, operators W
 - different groups of operators with a specific qualification can exist, W_ℓ is a number of operators in group ℓ



Constraints (continuation) β [Rud13, Nie10]

- **Routing constraints**

- determine on which machine jobs can be executed,
- an order of job execution in shop problems
 - job shop problem: an operation order is given in advance
 - open shop problem: a route for the job is specified during scheduling

- **Setup time and cost** $s_{ijk}, c_{ijk}, s_{jk}, c_{jk}$

- depend on execution sequence
- s_{ijk} time for execution of job k after job j on machine i
- c_{ijk} cost of execution of job k after job j on machine i
- s_{jk}, c_{jk} time/cost independent on machine
- examples
 - lemonade filling into bottles
 - travelling salesman problem $1|s_{jk}|C_{max}$

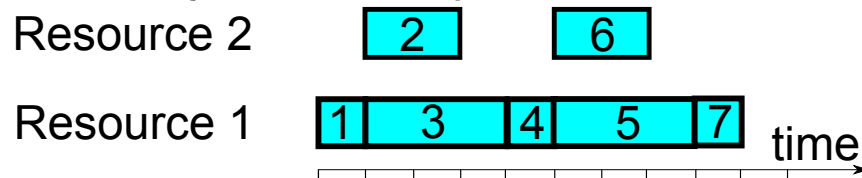


Optimization: throughput and makespan γ [Rud13]

- **Makespan** C_{max} : maximum completion time

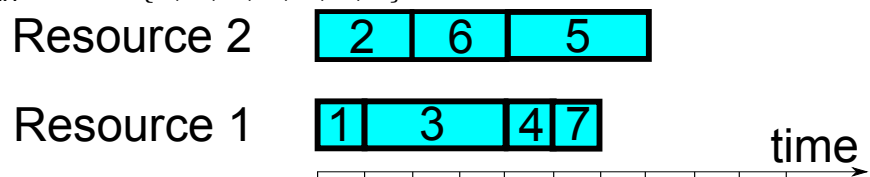
$$C_{max} = \max(C_1, \dots, C_n)$$

- Example: $C_{max} = \max\{1, 3, 4, 5, 8, 7, 9\} = 9$



- **Goal: makespan minimization** often

- maximizes **throughput**
- ensures **uniform load of machines** (*load balancing*)
- example: $C_{max} = \max\{1, 2, 4, 5, 7, 4, 6\} = 7$



- It is a basic criterion that is used very often.

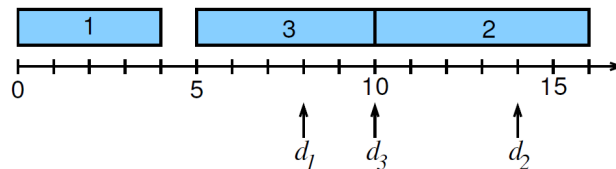


Optimization: Lateness γ [Rud13]

- Lateness of job j : $L_{max} = C_j - d_j$
- Maximum lateness L_{max}

$$L_{max} = \max(L_1, \dots, L_n)$$

- Goal: maximum lateness minimization
- Example:

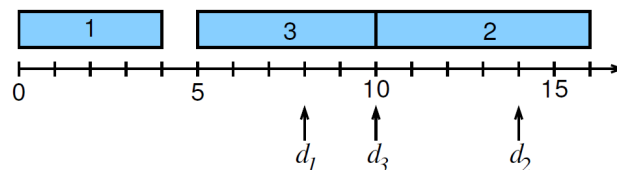


$$\begin{aligned} L_{max} &= \max(L_1, L_2, L_3) = \\ &= \max(C_1 - d_1, C_2 - d_2, C_3 - d_3) = \\ &= \max(4 - 8, 16 - 14, 10 - 10) = \\ &= \max(-4, 2, 0) = 2 \end{aligned}$$

Optimization: tardiness γ [Rud13]

- Job tardiness j : $T_j = \max(C_j - d_j, 0)$
- Total tardiness

$$\sum_{j=1}^n T_j$$



- Goal: total tardiness minimization
- Example: $T_1 + T_2 + T_3 =$

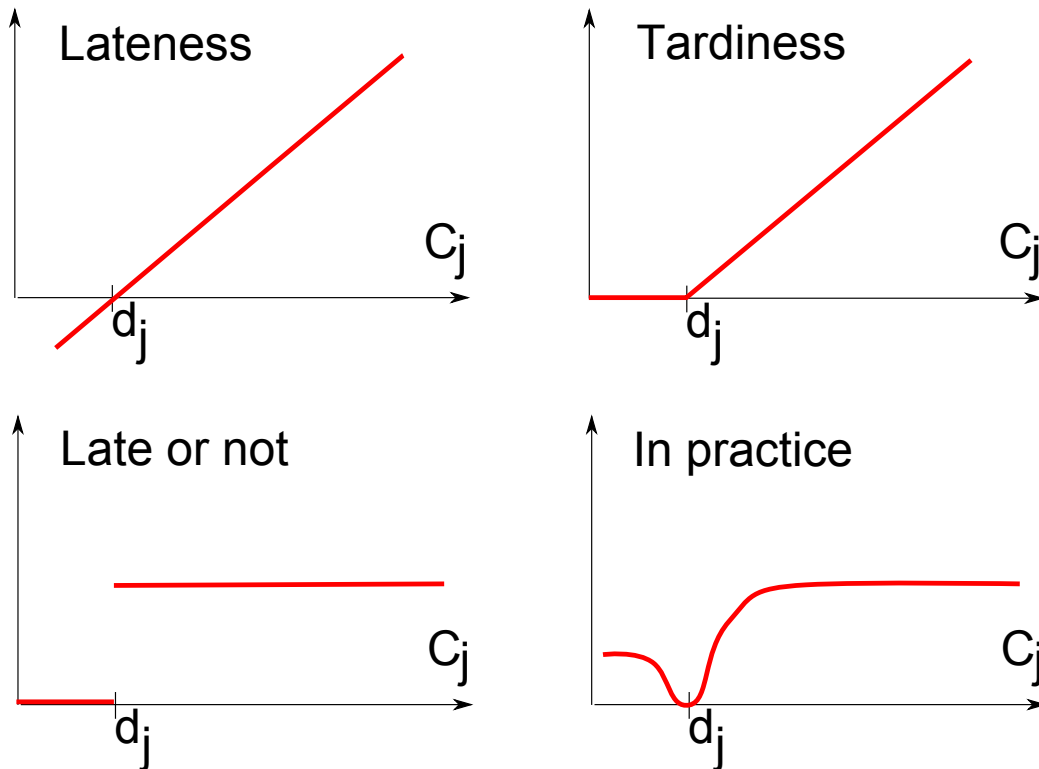
$$\begin{aligned} &= \max(C_1 - d_1, 0) + \max(C_2 - d_2, 0) + \max(C_3 - d_3, 0) = \\ &= \max(4 - 8, 0) + \max(16 - 14, 0) + \max(10 - 10, 0) = \\ &= 0 + 2 + 0 = 2 \end{aligned}$$

- Total weighted tardiness

$$\sum_{j=1}^n w_j T_j$$

- Goal: total weighted tardiness minimization



Criteria Comparison γ [Rud13]

Constructive vs. local methods [Rud13]

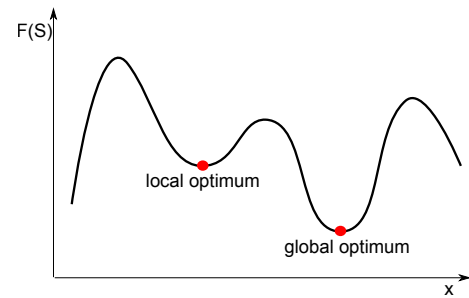
- **Constructive methods**
 - Start with the empty schedule
 - Add step by step other jobs to the schedule so that the schedule remains consistent
- **Local search**
 - Start with a complete non-consistent schedule
 - trivial: random generated
 - Try to find a better "similar" schedule by local modifications.
 - Schedule quality is evaluated using optimization criteria
 - ex. makespan
 - optimization criteria assess also schedule consistency
 - ex. a number of violated precedence constraints
- **Hybrid approaches**
 - combinations of both methods



Local Search Algorithm [Rud13]

1 Initialization

- $k = 0$
- Select an initial schedule S_0
- Record the current best schedule:
 $S_{best} = S_0$ a $cost_{best} = F(S_0)$



2 Select and update

- **Select a schedule** from **neighborhood**: $S_{k+1} \in N(S_k)$
- if no element $N(S_k)$ satisfies **schedule acceptance criterion** then the algorithm finishes
- if $F(S_{k+1}) < cost_{best}$ then
 $S_{best} = S_{k+1}$ a $cost_{best} = F(S_{k+1})$

3 Finish

- if the stop constraints are satisfied then the algorithm finishes
- otherwise $k = k + 1$ and continue with step 2.



Single machine + nonpreemptive jobs [Rud13]

• Schedule representation

- permutations n jobs
- example with six jobs: 1, 4, 2, 6, 3, 5

• Neighborhood definition

- **pairwise exchange of neighboring jobs**
 - $n - 1$ possible schedules in the neighborhood
 - example: 1, 4, 2, 6, 3, 5 is modified to 1, 4, 2, 6, 5, 3
- or **select an arbitrary job from the schedule and place it to an arbitrary position**
 - $\leq n(n - 1)$ possible schedules in the neighborhood
 - example: from 1, 4, 2, 6, 3, 5 we select randomly 4 and place it somewhere else: 1, 2, 6, 3, 4, 5



Criteria for Schedule Selection [Rud13]

- Criteria for schedule selection
 - **Criterion for schedule acceptance/refuse**
- The main difference among a majority of methods
 - to accept a better schedule all the time?
 - to accept even worse schedule sometimes?
- methods
 - probabilistic
 - **random walk**: with a small probability (ex. 0.01) a worse schedule is accepted
 - **simulated annealing**
 - deterministic
 - **tabu search**: a tabu list of several last state/modifications that are not allowed for the following selection is maintained



Tabu Search [Rud13]

- **Deterministic criterion for schedule acceptance/refuse**
- **Tabu list** of several last schedule modifications is maintained
 - each new modification is stored on the top of the tabu list
 - ex. of a store modification: exchange of jobs j and k
 - **tabu list = a list of forbidden modifications**
 - the neighborhood is constrained over schedules, that do not require a change in the tabu list
 - a protection against cycling
 - example of a trivial cycling:
the first step: exchange jobs 3 and 4, the second step: exchange jobs 4 and 3
 - a fixed length of the list (often: 5-9)
 - the oldest modifications of the tabu list are removed
 - too small length: cycling risk increases
 - too high length: search can be too constrained
- **Aspiration criterion**
 - determines when it is possible to make changes in the tabu list
 - ex. a change in the tabu list is allowed if $F(S_{best})$ is improved.



Tabu Search Algorithm ^[Rud13]

- 1
 - $k = 1$
 - Select an initial schedule S_1 using a heuristics,
 $S_{best} = S_1$
- 2
 - Choose $S_c \in N(S_k)$
 - If the modification $S_k \rightarrow S_c$ is forbidden because it is in the tabu list then continue with step 2
- 3
 - If the modification $S_k \rightarrow S_c$ is not forbidden by the tabu list then $S_{k+1} = S_c$,
store the reverse change to the top of the tabu list
move other positions in the tabu list one position lower
remove the last item of the tabu list
 - if $F(S_c) < F(S_{best})$ then $S_{best} = S_c$
- 4
 - $k = k + 1$
 - if a stopping condition is satisfied then finish
otherwise continue with step 2.

Example: tabu list ^[Rud13]

A schedule problem with $1|d_j| \sum w_j T_j$

- remind: $T_j = \max(C_j - d_j, 0)$

úlohy	1	2	3	4
p_j	10	10	13	4
d_j	4	2	1	12
w_j	14	12	1	12

- Neighborhood: all schedules obtained by pair exchange of neighbor jobs
- Schedule selection from the neighborhood: select the best schedule
- Tabu list: pairs of jobs (j, k) that were exchanged in the last two modifications
- Apply tabu search for the initial solution $(2, 1, 4, 3)$
- Perform four iterations



Example: tabu list - solution I [Rud13]

jobs	1	2	3	4
p_j	10	10	13	4
d_j	4	2	1	12
w_j	14	12	1	12

$$S_1 = (2, 1, 4, 3)$$

$$F(S_1) = \sum w_j T_j = 12 \cdot 8 + 14 \cdot 16 + 12 \cdot 12 + 1 \cdot 36 = 500 = F(S_{best})$$

$$F(1, 2, 4, 3) = 480$$

$$F(2, \underline{4}, \underline{1}, 3) = 436 = F(S_{best})$$

$$F(2, 1, 3, 4) = 652$$

Tabu list: $\{(1, 4)\}$

$$S_2 = (2, 4, 1, 3), F(S_2) = 436$$

$$F(\underline{4}, \underline{2}, 1, 3) = 460$$

$$F(2, 1, 4, 3) (= 500) \text{ tabu!}$$

$$F(2, 4, 3, 1) = 608$$

Tabu list: $\{(2, 4), (1, 4)\}$

$$S_3 = (4, 2, 1, 3), F(S_3) = 460$$

$$F(2, 4, 1, 3) (= 436) \text{ tabu!}$$

$$F(4, \underline{1}, \underline{2}, 3) = 440$$

$$F(4, 2, 3, 1) = 632$$

Tabu list: $\{(2, 1), (2, 4)\}$



Example: tabu list - solution II [Rud13]

jobs	1	2	3	4
p_j	10	10	13	4
d_j	4	2	1	12
w_j	14	12	1	12

$$S_3 = (4, 2, 1, 3), F(S_3) = 460$$

$$F(2, 4, 1, 3) (= 436) \text{ tabu!}$$

$$F(4, \underline{1}, \underline{2}, 3) = 440$$

$$F(4, 2, 3, 1) = 632$$

Tabu list: $\{(2, 1), (2, 4)\}$

$$S_4 = (4, 1, 2, 3), F(S_4) = 440$$

$$F(\underline{1}, \underline{4}, 2, 3) = 408 = F(S_{best})$$

$$F(4, 2, 1, 3) (= 460) \text{ tabu!}$$

$$F(4, 1, 3, 2) = 586$$

Tabu list: $\{(4, 1), (2, 1)\}$

$$F(S_{best}) = 408$$



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