

# Modelica

## Diskrétní a hybridní systémy

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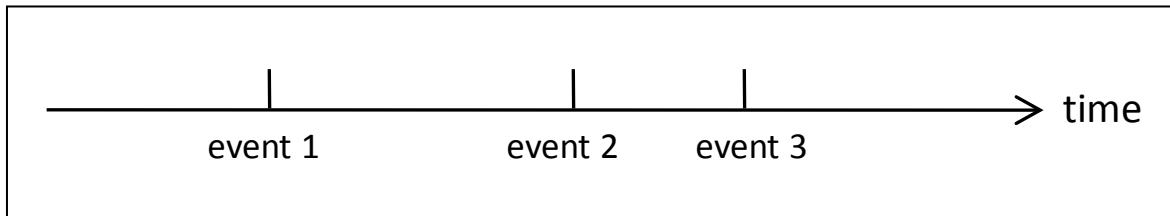
*Použity části z přednášek Petera Fritzsóna Discrete Events and Hybrid Systems*

# Do teď jsme probírali spojité modely

- Co je to spojitý model? Co je to spojitý systém?
- V přírodě (makrosvět) většinou spojitý
- Potřebujeme zjednušovat

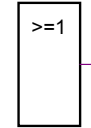
# Diskrétní systémy

- Změna stavu pouze v „clock“
- V mezičase setrvalé

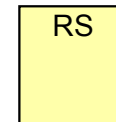


# Digitální systémy

- Modelica.Electric.Digital
  - Hradla, RS, D
  - Logic, nikoli Boolean!
  - Logic hodnota;

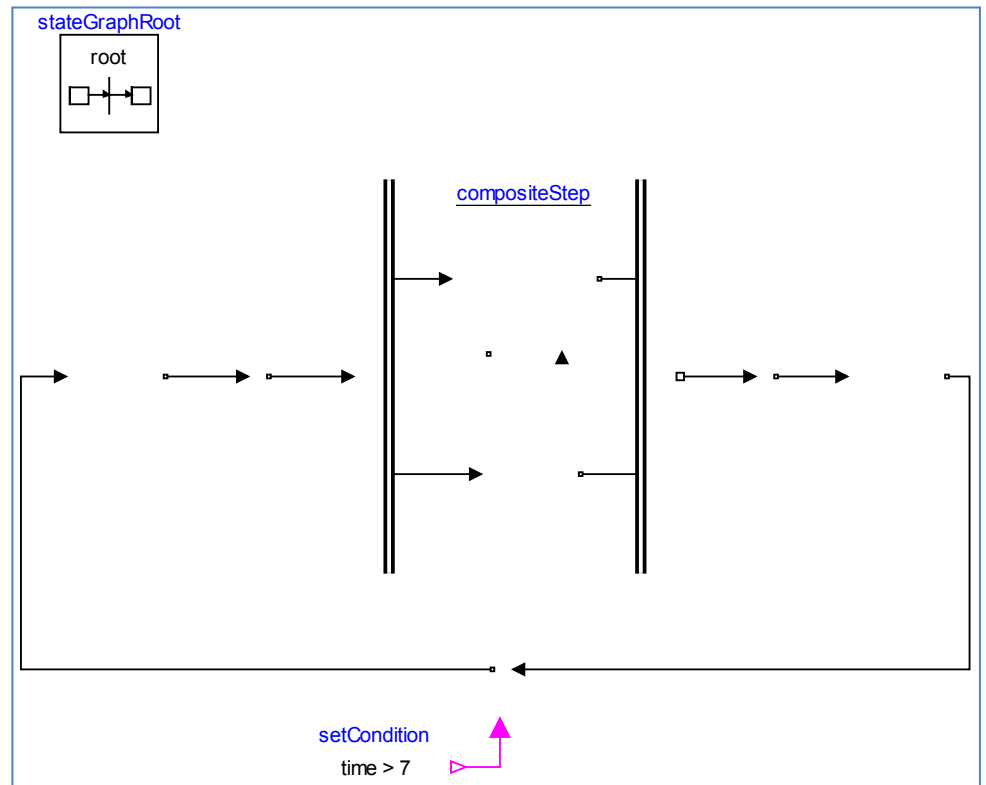
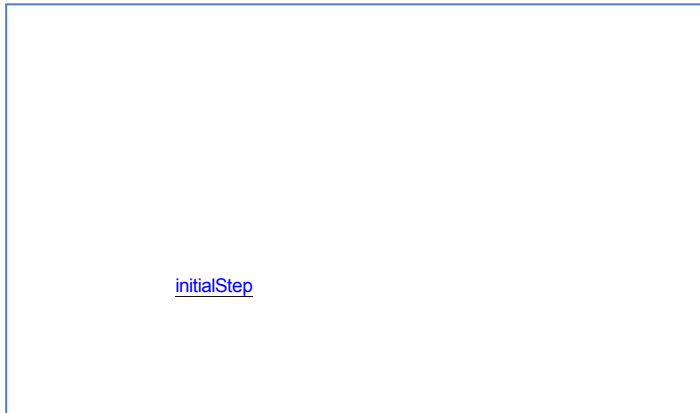


| Logic value | Meaning         |
|-------------|-----------------|
| 'U'         | Uninitialized   |
| 'X'         | Forcing Unknown |
| '0'         | Forcing 0       |
| '1'         | Forcing 1       |
| 'Z'         | High Impedance  |
| 'W'         | Weak Unknown    |
| 'L'         | Weak 0          |
| 'H'         | Weak 1          |
| '-'         | Don't care      |



# Modelica.StateGraph

- Pro simulace stavových automatů



# Základní diskrétní typy

- Boolean
- Integer
- Discrete Real

Spojité

- Real

# Základ – if-equation

- If-equation

- `if x > 5 then`
  - `k = true;`
  - `x = whatever;`
- `elseif`
  - ...
- `else`
  - `k = false;`
  - `x = whatever2;`
- `end;`

- **Pozor:**

- Stejný počet rovnic ve VŠECH větvích
- Vždy musí být **else** (pokud se jednoznačně nevyklučuje)

# If-expressions

- If-expresssion

Boolean returning;

equation

returning = if velocity < 0.0 then true else false;

- nebo

Boolean returning;

equation

returning = velocity < 0.0;

- Cílový překlad

- Dá se zapsat také jako if-equation:

Boolean returning;

equation

if velocity < 0.0 then

returning = true;

else

returning = false;

end if;



# Event creation – if

*if-equations, if-statements, and if-expressions*

```
if <condition> then
  <equations>
elseif <condition> then
  <equations>
else
  <equations>
end if;
```

```
model Diode "Ideal diode"
  extends TwoPin;
  Real s;
  Boolean off;
equation
  off = s < 0;
  if off then
    v=s
  else
    v=0;
  end if;
  i = if off then 0 else s;
end Diode;
```

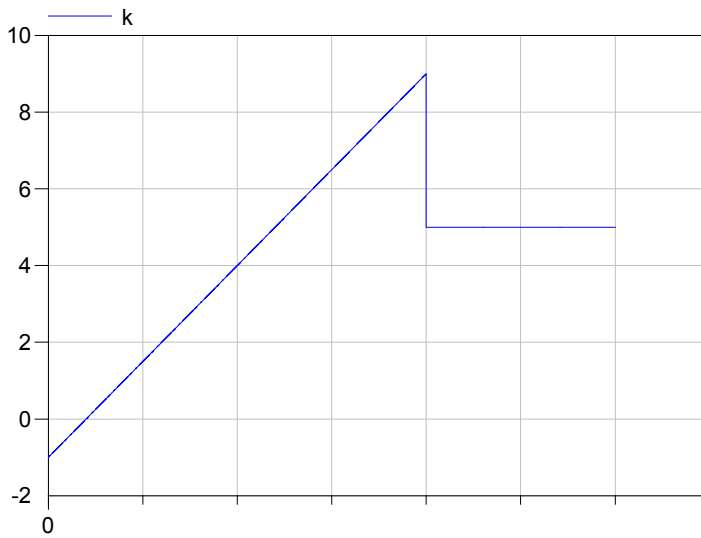
False if  $s < 0$

If-equation choosing  
equation for  $v$

If-expression

# IF

- Jakýkoli if-equation musí být rozepsatelný do if-expression
  - Nemožno míchat s der
- Musí být pokryty všechny možnosti
- Postupuje se shora!



```
Real k;  
Real m;  
equation  
  der(m) = 1;  
  if time <= 20 then  
    k = 0.5*m - 1;  
  elseif time < 1 then  
    // ignorováno  
    k = 0;  
  else  
    k = 5;  
  end if;
```

# Time

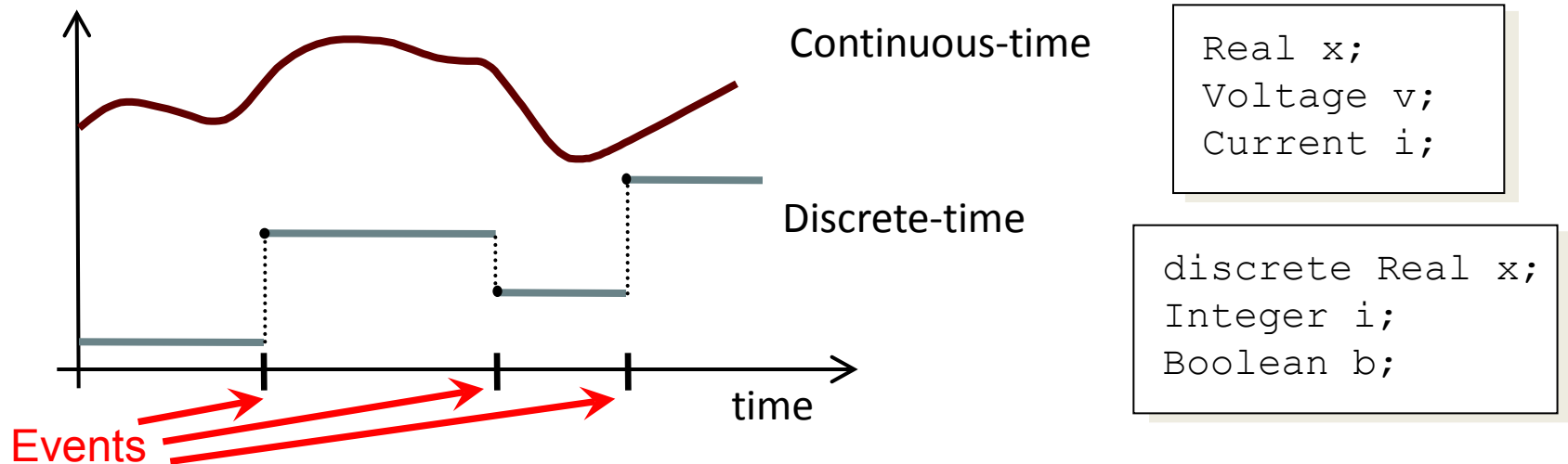
- Časová pozice
  - time
    - s\_boolean = time > 30;
    - Je\_pozde = if time > 14.15 then true else false;
    - cas = time;
    - when time > 20. then
      - casZlomu = time;
    - end when;

# Co to jsou EVENTS

- Události nespojitosti
  - Zastaví se výpočet integrace, nalezne se přesný čas události
    - (Přesný ale není naprosto přesný)
    - Chyba: nelze hledat přesnou rovnost
      - Místo toho např.  $m > 3$  and  $m < 3 + 1e-6$
- ```
Real m;  
equation  
if m == 3 then  
    ...  
end if;
```
- Od času události platí rovnice v druhé větvi *if*

# Hybrid Modeling

Hybrid modeling = continuous-time + discrete-time modeling



- A *point* in time that is instantaneous, i.e., has zero duration
- An *event condition* so that the event can take place
- A set of *variables* that are associated with the event
- Some *behavior* associated with the event, e.g. *conditional equations* that become active or are deactivated at the event

# When

- *If* rozděljuje, KTERÉ rovnice použít
- Rovnice *when* se provedou POUZE při události
  - When se chová trochu jako algorithm
  - Máme stop-stav

# Event creation – when

## *when-equations*

```
when <conditions> then  
  <equations>  
end when;
```



Equations only active at event times

## Time event

```
when time >= 10.0 then  
  ...  
end when;
```

Only dependent on time, can be scheduled in advance

## State event

```
when sin(x) > 0.5 then  
  ...  
end when;
```

Related to a state. Check for zero-crossing

# Event Priority

Erroneous multiple definitions, single assignment rule violated

```
model WhenConflictX // Erroneous model: two equations define x
  discrete Real x;
  equation
  when time>=2 then // When A: Increase x by 1.5 at time=2
    x = pre(x)+1.5;
  end when;
  when time>=1 then // When B: Increase x by 1 at time=1
    x = pre(x)+1;
  end when;
end WhenConflictX;
```

Using event priority  
to avoid erroneous  
multiple definitions

```
model WhenPriorityX
  discrete Real x;
  equation
  when time>=2 then // Higher priority
    x = pre(x)+1.5;
  elseif time>=1 then // Lower priority
    x = pre(x)+1;
  end when;
end WhenPriorityX;
```

**Pozor na Dymolu!**



# Vnoření if a when

- Ify můžeme vnořovat (vždy lze vygenerovat if-expression)
- Wheny vnořovat nelze!
- Ify do whenů však lze

# Reinit

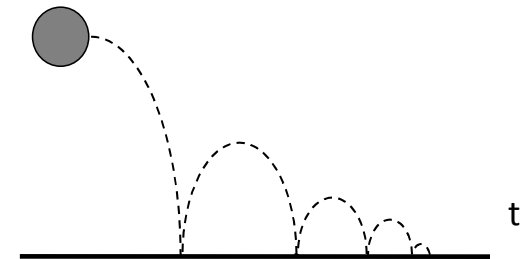
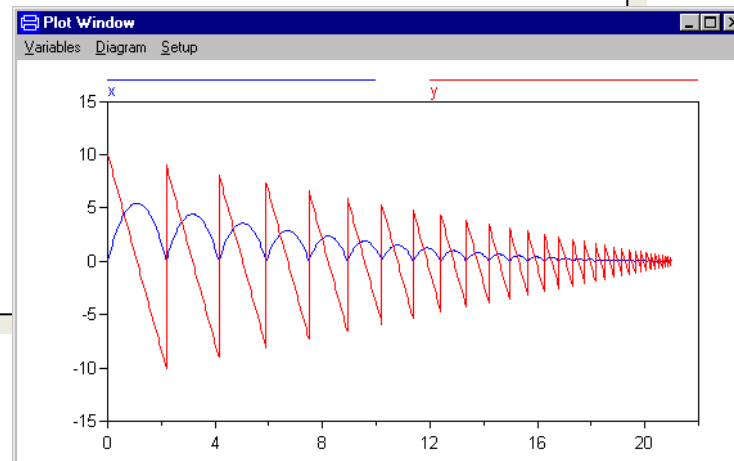
- Reinit nám dovolí měnit hodnoty spojité proměnné
- Lze použít pouze na proměnné, které se někde vyskytují v `der(__)`
  - Jinak můžeme použít diskrétní proměnnou
- Pouze ve WHEN
  - `reinit(veličina, hodnota);`
  - `reinit(rychlost, 0.0);`
- Bouncing ball

# Discontinuous Changes to Variables at Events via When-Equations/Statements

The value of a *discrete-time* variable can be changed by placing the variable on the left-hand side in an equation within a when-equation, or on the left-hand side of an assignment statement in a when-statement

The value of a *continuous-time* state variable can be instantaneously changed by a reinit-equation within a when-equation

```
model BouncingBall "the bouncing ball model"  
  parameter Real g=9.18; //gravitational acc.  
  parameter Real c=0.90; //elasticity constant  
  Real x(start=0), y(start=10);  
equation  
  der(x) = y;  
  der(y)=-g;  
  when x<0 then  
    reinit(y, -c*y);  
  end when;  
end BouncingBall;
```



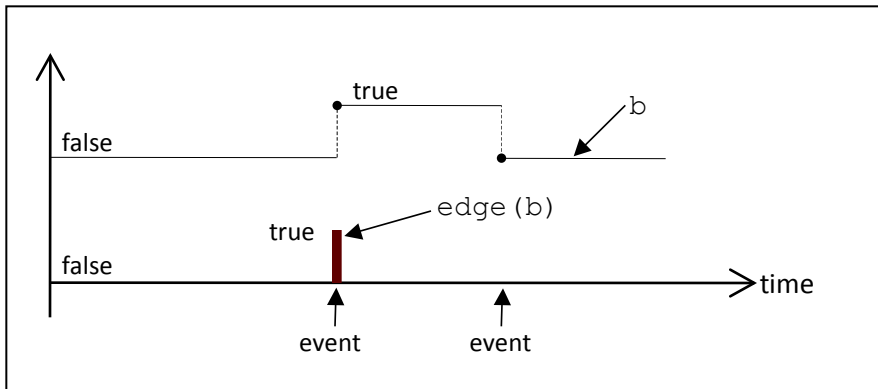
# Čím odpálíme eventy?

if (a > 3 and b < 1) or (C\_boolean and D\_integer == 4) then

- if/when time > 3.14159265358
  - if/when sample(start, interval)
  - if/when edge(x)
  - if/when change(x)
- 
- a\_bool = edge(x);
  - c\_booo = change(a\_booo);

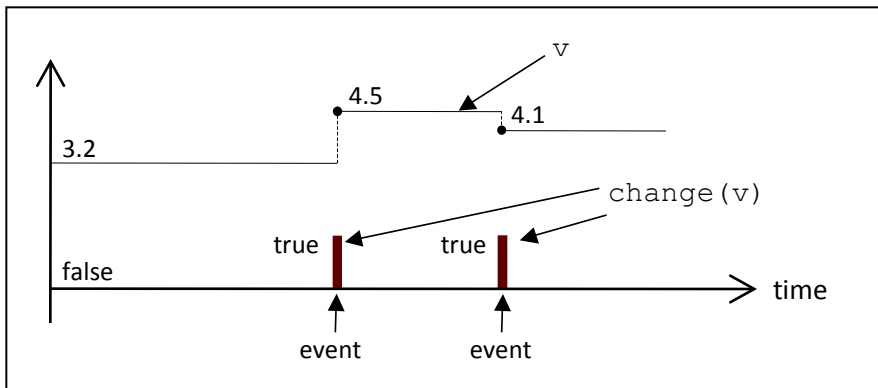
# Detecting Changes of Boolean Variables Using `edge()` and `change()`

## Detecting changes of boolean variables using `edge()`



The expression `edge(b)` is true at events when `b` switches from false to true

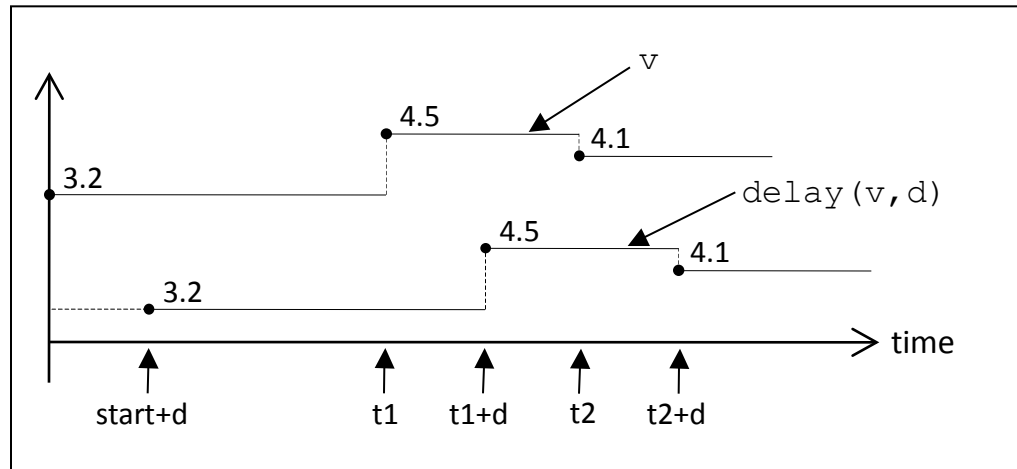
## Detecting changes of discrete-time variables using `change()`



The expression `change(v)` is true at instants when `v` changes value

# Creating Time-Delayed Expressions

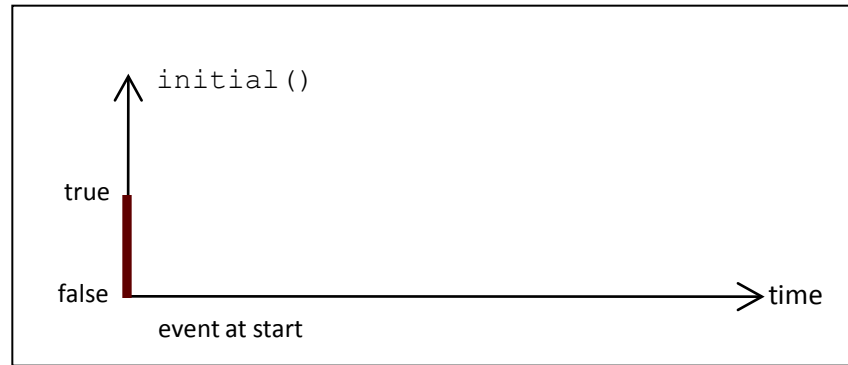
Creating time-delayed expressions using `delay()`



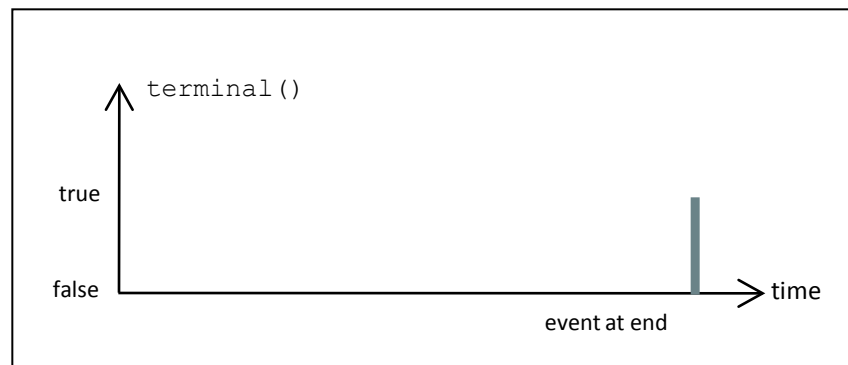
In the expression `delay(v, d)`  $v$  is delayed by a delay time  $d$

# initial and terminal events

Initialization actions are triggered by `initial()`

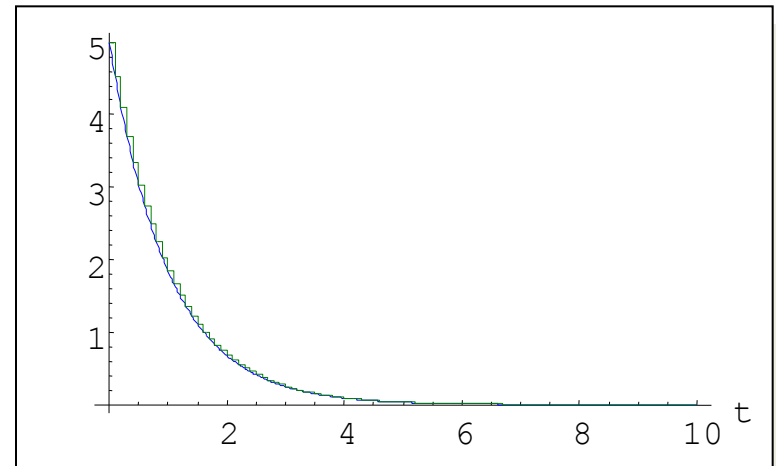


Actions at the end of a simulation are triggered by `terminal()`



# A Sampler Model

```
model Sampler
  parameter Real sample_interval = 0.1;
  Real x(start=5);
  Real y;
equation
  der(x) = -x;
  when sample(0, sample_interval) then
    y = x;
  end when;
end Sampler;
```



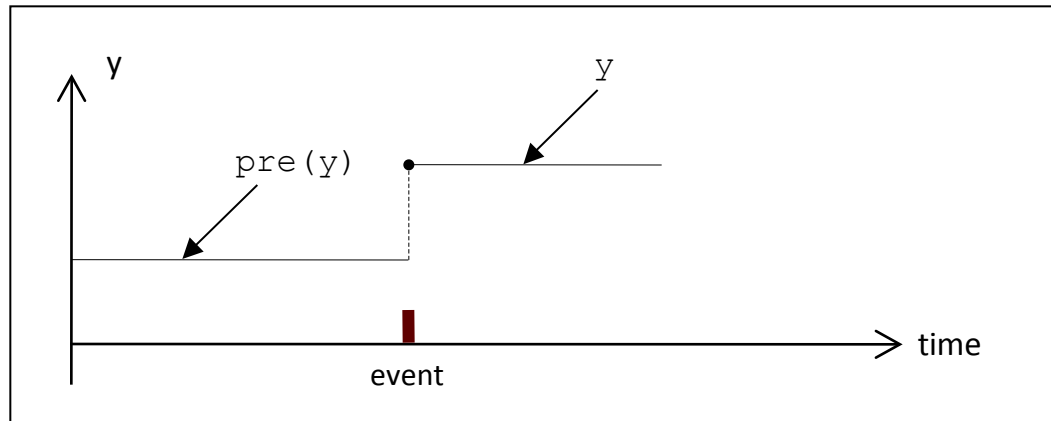


# PRE

- Předešlá hodnota
- ~ jiná proměnná

# Obtaining Predecessor Values of a Variable Using `pre()`

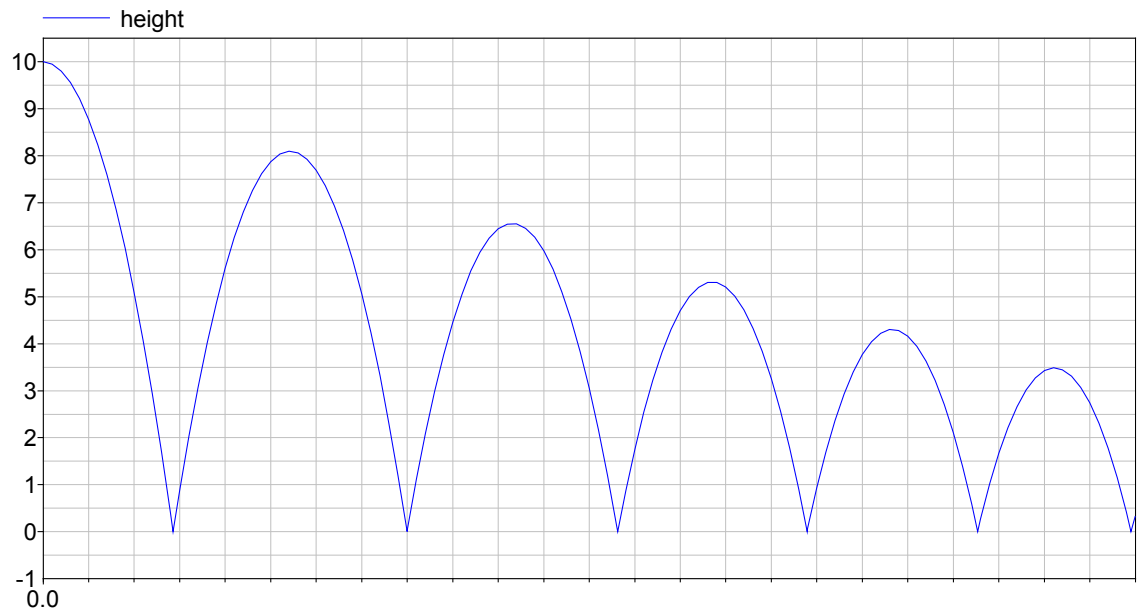
At an event, `pre(y)` gives the previous value of `y` immediately before the event, except for event iteration of multiple events at the same point in time when the value is from the previous iteration



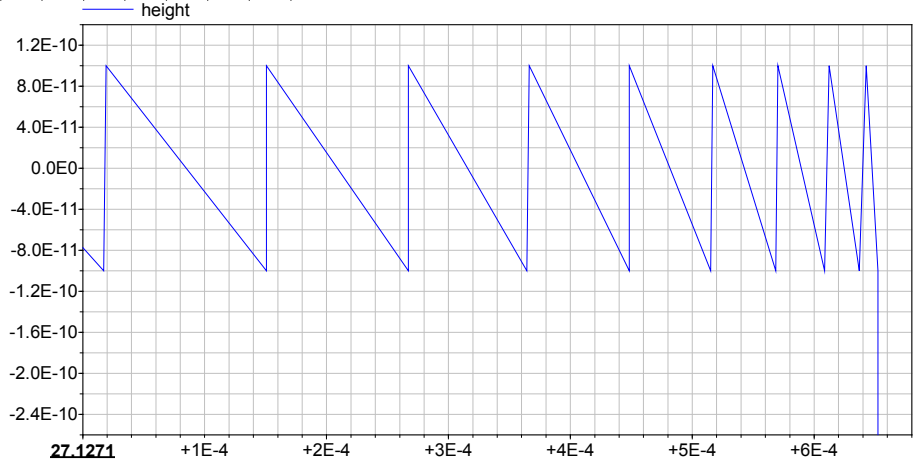
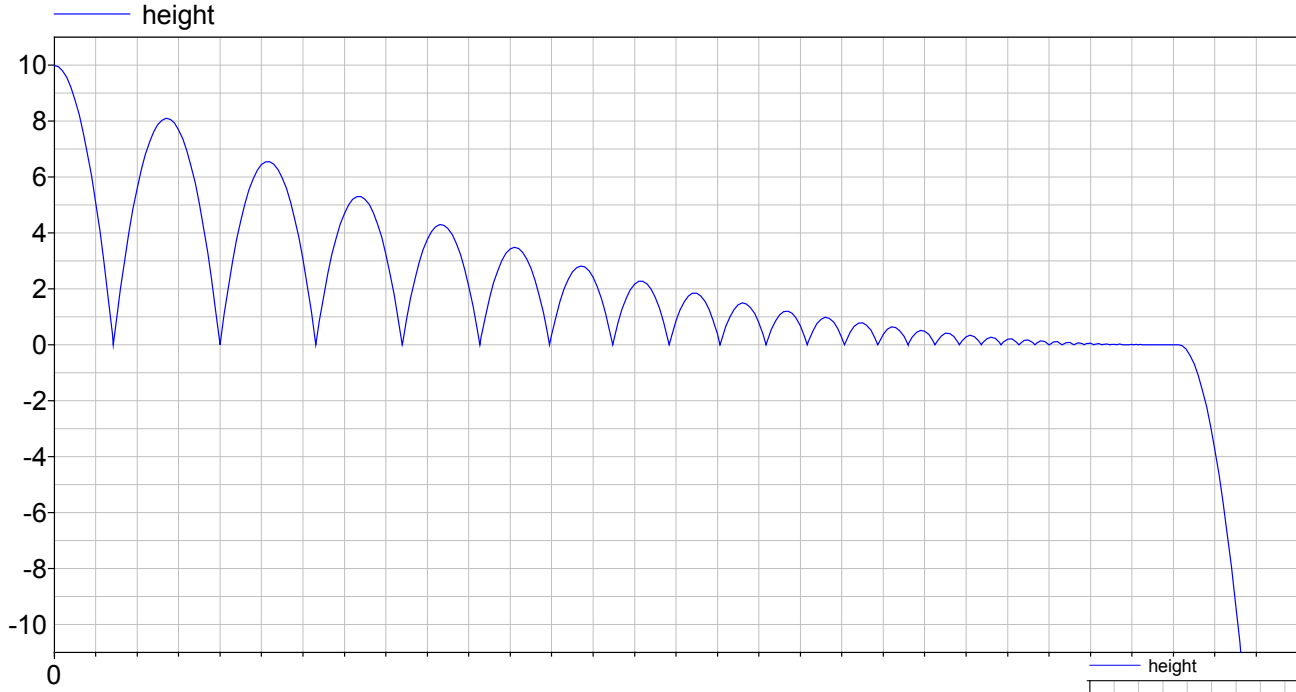
- The variable `y` has one of the basic types `Boolean`, `Integer`, `Real`, `String`, or `enumeration`, a subtype of those, or an array type of one of those basic types or subtypes
- The variable `y` is a discrete-time variable
- The `pre` operator can *not* be used within a function

# Zeno effect – bouncing ball - 1

```
model BouncingBall "the bouncing ball model - crash at T=27.5"  
parameter Real g=9.81; //gravitational acc.  
parameter Real c=0.90; //elasticity constant  
Real height(start=10);  
Real velocity(          start=0);  
equation  
  der(height) = velocity;  
  der(velocity)=-g;  
  when height<0 then  
    reinit(velocity, -c*velocity);  
  end when;  
end BouncingBall;
```



# Zeno effect – bouncing ball - 2



# Zeno effect – bouncing ball - 3

- Řešení

- Dát si na to pozor

- Terminate simulation

```
when height < 1e-6 then  
  terminate("Propadli sme podlahou");  
end when;
```

- Rozlišit Letí / stojí

# Terminating a Simulation

The `terminate()` function is useful when a wanted result is achieved and it is no longer useful to continue the simulation. The example below illustrates the use:

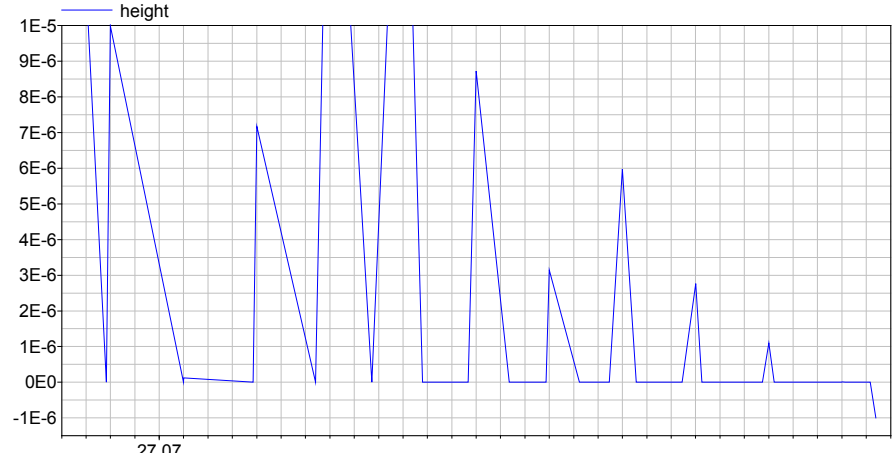
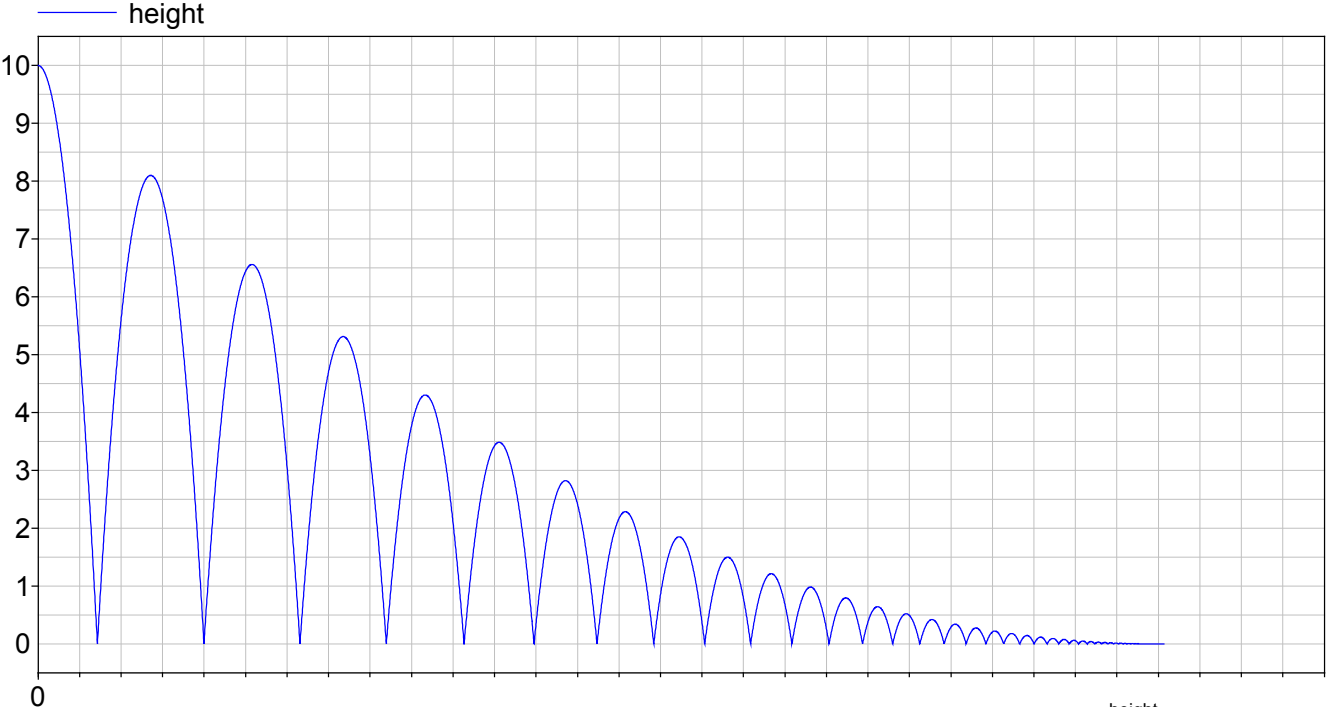
```
model terminationModel
  Real y;
  equation
    y = time;
    when y >5 then
      terminate("The time has elapsed 5s");
    end when;
end terminationModel;
```

terminate

Simulation ends before  
reaching time 10

```
simulate(terminationModel, startTime = 0, stopTime = 10)
```

# Zeno effect – bouncing ball - 4



# Dioda

$i$   
→

—



# Dioda

- Jednoduše:
- Zavíráme a otvíráme jen proudem?
- Pozor na nulu!

```
if i < 0 then  
    v = Roff*i;  
else  
    v = Ron*i;  
end if;
```

```
If v < 0 then  
    v = Roff*i;  
else  
    v = Ron*i;  
end if;
```

# Dioda 2

- Pomocí vložené proměnné

```
off = s < 0;
```

```
if off then
```

```
    v = s;
```

```
else
```

```
    v = 0;
```

```
end if;
```

```
i = if off then 0 else s;
```

- Anebo lépe

```
off = s < 0;
```

```
//off – s je napeti, not off – s je proud
```

```
v = s * (if off then 1 else Ron);
```

```
i = s * (if off then 1/Roff else 1);
```

# Modelica.Electrical.Analog.Ideal.IdealDiode

```
constant Modelica.SIunits.Voltage unitVoltage= 1 annotation(HideResult=true);
```

```
constant Modelica.SIunits.Current unitCurrent= 1 annotation(HideResult=true);
```

```
equation
```

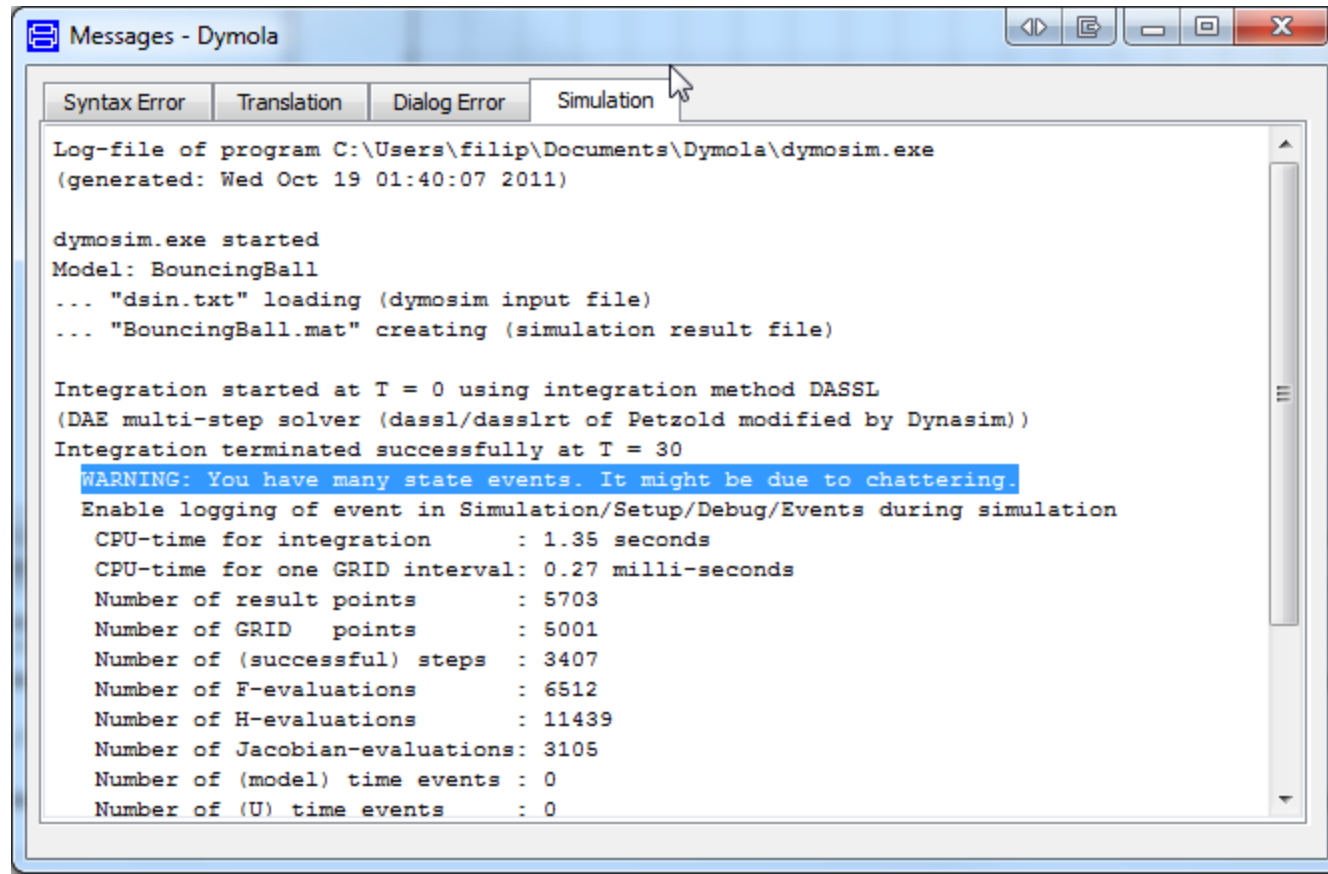
```
off = s < 0;
```

```
v = (s*unitCurrent)*(if off then 1 else Ron) + Vknee;
```

```
i = (s*unitVoltage)*(if off then Goff else 1) + Goff*Vknee;
```

# Možné problémy

- Chattering – někde nám to příliš kmitá
- Numerika, numerika, numerika..



```
Messages - Dymola
Syntax Error Translation Dialog Error Simulation
Log-file of program C:\Users\filip\Documents\Dymola\dymosim.exe
(generated: Wed Oct 19 01:40:07 2011)

dymosim.exe started
Model: BouncingBall
... "dsin.txt" loading (dymosim input file)
... "BouncingBall.mat" creating (simulation result file)

Integration started at T = 0 using integration method DASSL
(DAE multi-step solver (dassl/dasslrt of Petzold modified by Dynasim))
Integration terminated successfully at T = 30
WARNING: You have many state events. It might be due to chattering.
Enable logging of event in Simulation/Setup/Debug/Events during simulation
CPU-time for integration      : 1.35 seconds
CPU-time for one GRID interval: 0.27 milli-seconds
Number of result points      : 5703
Number of GRID points       : 5001
Number of (successful) steps : 3407
Number of F-evaluations      : 6512
Number of H-evaluations      : 11439
Number of Jacobian-evaluations: 3105
Number of (model) time events : 0
Number of (U) time events    : 0
```

**Příklady!!**

# Shrnutí

- Co to je hybridní simulace
- Rozdíl mezi if a when
- Reinit
- Numerické problémy
- terminate()