



Bioinformatika

Hidden Markov

Models

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(some slides are courtesy of Mark Craven, U. of Wisconsin)

Motivation

- ← What is a gene?

Motivation

- ⤵ What is a gene?
- ⤵ Can you formalize a gene as a regular expression?

Motivation

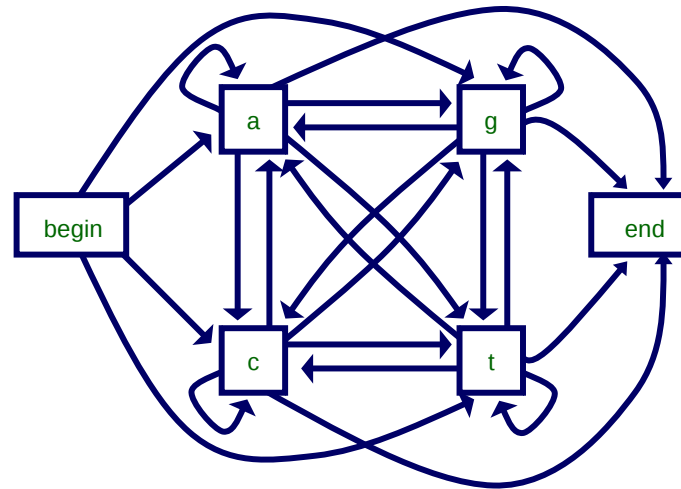
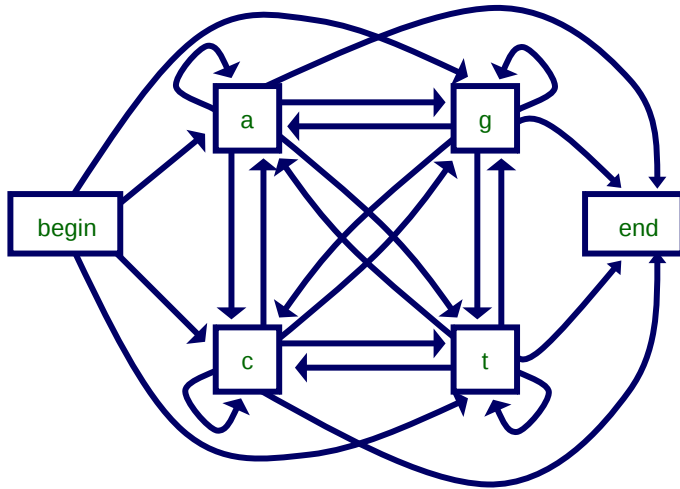
- ← What is a gene?
- ← Can you formalize a gene as a regular expression?
- ← What is HMM?

Motivation

- ↩ What is a gene?
- ↩ Can you formalize a gene as a regular expression?
- ↩ What is HMM?
- ↩ What are the general tasks with HMMs?

Motivation

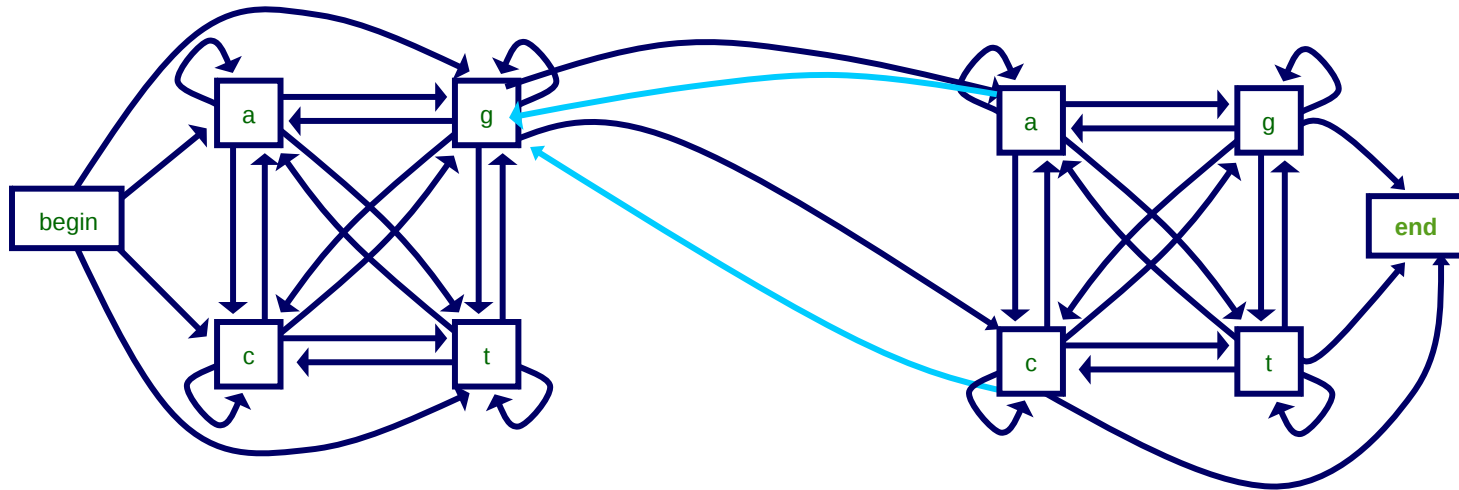
1. Train two MMs: one to represent represent CpG regions, the other to the background (nCpG)



- Given a new sequence, use two models to *classify* the sequence (CpG or nCpG).
- Given a new sequence, find the CpG islands within (**?!?**)

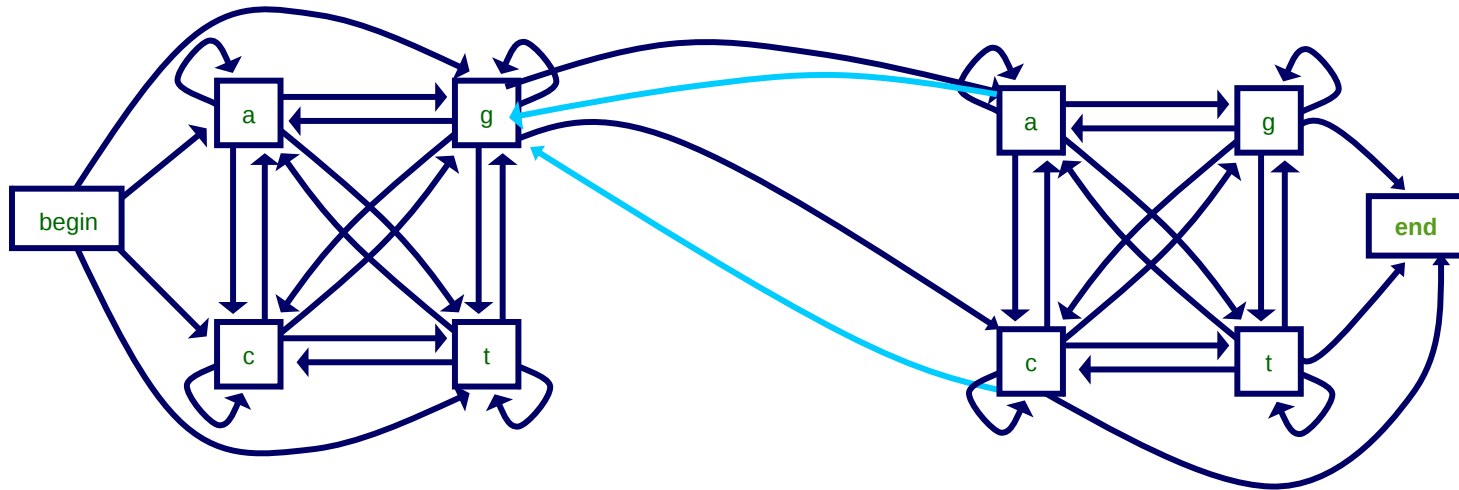
Motivation

1. Train two MMs: one to represent represent CpG regions, the other to the background (nCpG)



Motivation

1. Train two MMs: one to represent represent CpG regions, the other to the background (nCpG)



2. Join the 2 models into one HMM:

$$\rightarrow \{a, c, t, g\} \rightarrow \{a_{\text{CpG}}, a_{\text{nCpG}}, c_{\text{CpG}}, c_{\text{nCpG}}, t_{\text{CpG}}, t_{\text{nCpG}}, g_{\text{CpG}}, g_{\text{nCpG}}\}$$

3. Segment a sequence as a maximum likely walk through the state space.

Hidden Markov Model

$$M = (A, S, P_t, P_e)$$

$$\leftarrow A = \{a, c, t, g\}$$

$$\leftarrow S = \{s_1, \dots, s_K\}$$

$$\leftarrow P_t : S \times S \rightarrow [0, 1]$$

$$\leftarrow P_e : S \times A \rightarrow [0, 1]$$

$$\begin{aligned} P(x_1, \dots, x_L; s_1, \dots, s_L) &= \\ &= P(s_1) \cdot P(x_1 | s_1) \cdot P(x_2 | s_2) \cdot P(s_2 | s_1) \cdot \\ &\cdot \dots \cdot P(x_L | s_L) \cdot P(s_L | s_{L-1}) \\ &\text{with } x_i \in A, s_i \in S \end{aligned}$$

Sequence Annotation

Given:

- ↪ observed sequence $\mathbf{x} \in \{a, c, t, g\}^L$
- ↪ model $M = (A, S, P_t, P_e)$

Find:

- ↪ max. likely labeling $\mathbf{s} \in S^L \rightarrow$ Viterbi alg.

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But how have the P_t, P_e been learnt??

- ↻ Supervised: $T = \{(\mathbf{x}_i, \mathbf{s}_i)\}_{i=1 \dots N}$ where $\mathbf{x}_i \in A^*, \mathbf{s}_i \in S^*$

Sequence Annotation

Given:

- ↻ observed sequence $\mathbf{x} \in \mathbf{A}^L$
- ↻ model $M = (A, S, P_t, P_e)$

Find:

- ↻ max. likely labeling $s \in S^L \rightarrow$ Viterbi alg.

But how have the P_t, P_e been learnt??

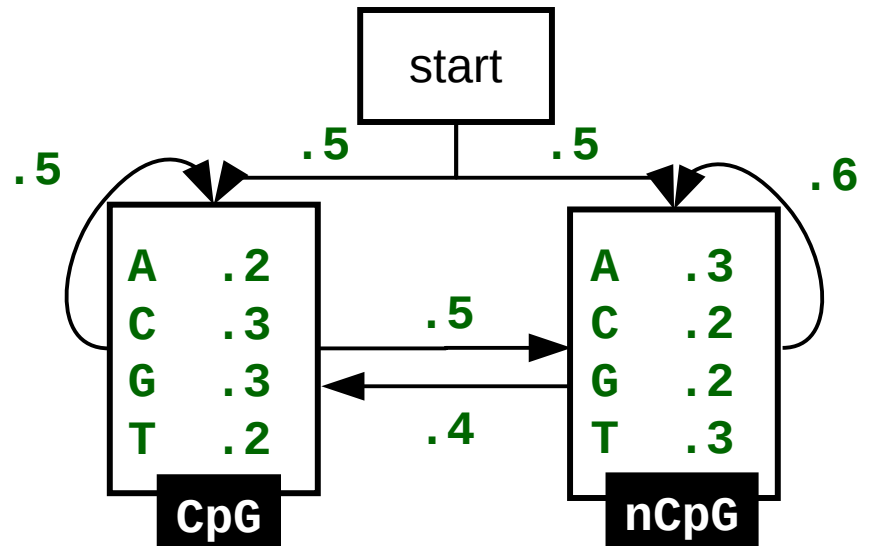
- ↻ Supervised: $T = \{(\mathbf{x}_i, \mathbf{s}_i)\}_{i=1\dots N}$ where $\mathbf{x}_i \in A^*$, $\mathbf{s}_i \in S^*$
- ↻ Unsupervised: $T = \{\mathbf{x}_i\}_{i=1\dots N}$ where $\mathbf{x}_i \in A^*$
 - Expectation-Maximization \rightarrow Baum-Welsh alg. (later)

Viterbi algorithm

Ex: Naive model of CpG detection

$$s^* = \arg \max_{s_0 \dots s_N \in S^N} p(x_0 \dots x_N; s_0 \dots s_N)$$

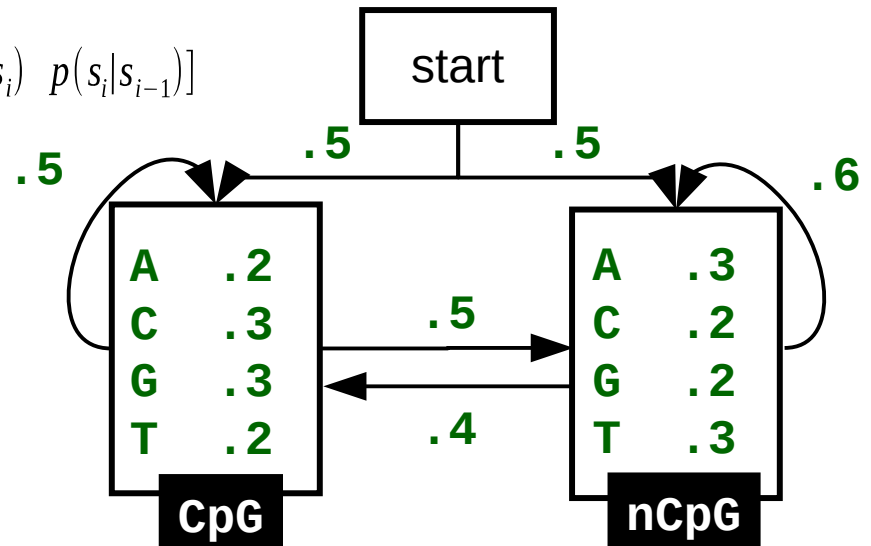
$$p(x_1 \dots x_N; s_1 \dots s_N) = \prod_{i=1}^N p(x_i | s_i) p(s_i | s_{i-1}),$$
$$p(s_0) = 1$$



Viterbi algorithm (ex.)

	ϵ	A	T	G	G	C	A	C	T	A
START	1	0	0	0	0	0	0	0	0	0
CpG	0									
nCpG	0									

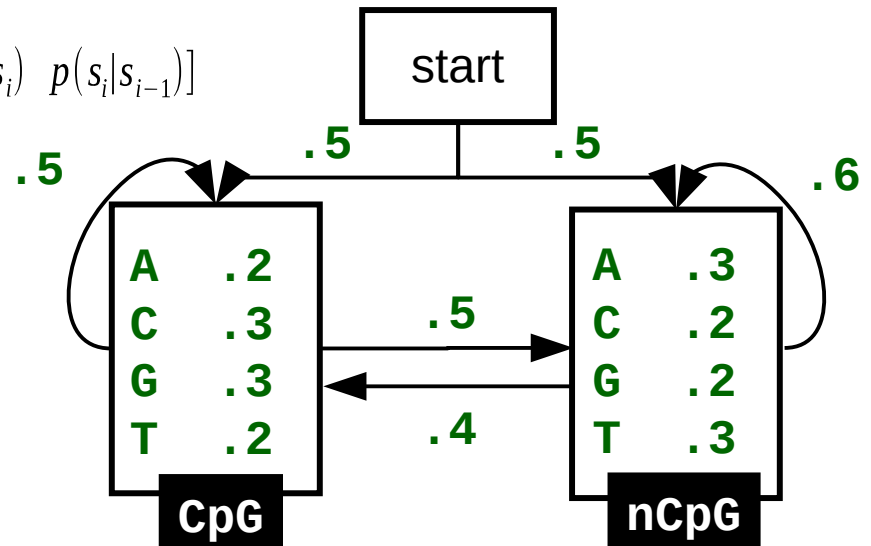
$$\max_{s_i \in S} p(x_0 \dots x_i | s_i) = \max_{s_{i-1} \in S} [p(x_0 \dots x_{i-1} | s_{i-1}) \max_{s_i \in S} p(x_i | s_i) p(s_i | s_{i-1})]$$



Viterbi algorithm (ex.)

	ϵ	A	T	G	G	C	A	C	T	A
START	1	0	0	0	0	0	0	0	0	0
CpG	0	1 x .2 x .5 0 x .2 x .5 0 x .2 x .4 .1								
nCpG	0	1 x .3 x .5 0 x .3 x .5 0 .3 xx .6 .15								

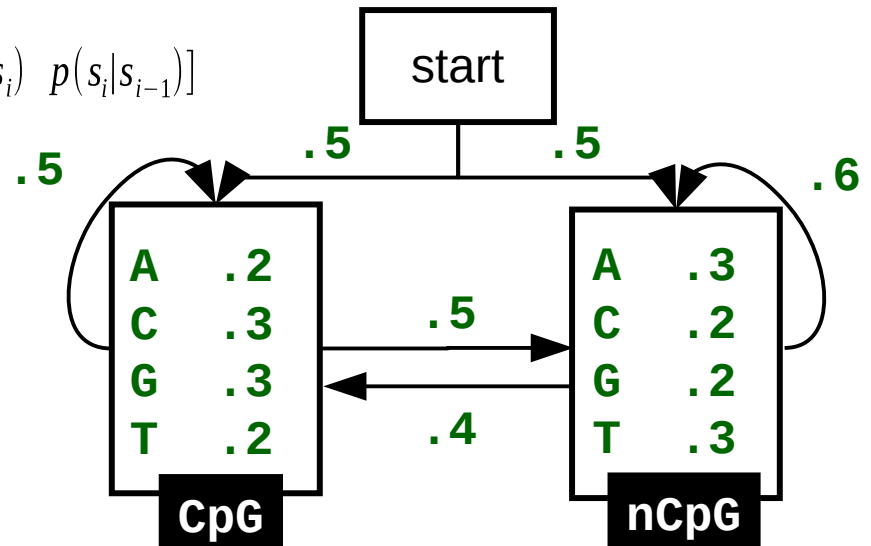
$$\max_{s_i \in S} p(x_0 \dots x_i | s_i) = \max_{s_{i-1} \in S} [p(x_0 \dots x_{i-1} | s_{i-1}) \max_{s_i \in S} p(x_i | s_i) p(s_i | s_{i-1})]$$



Viterbi algorithm (ex.)

	ϵ	A	T	G	G	C	A	C	T	A
START	1	0	0	0	0	0	0	0	0	0
CpG	0	1 x .2 x .5 0 x .2 x .5 0 x .2 x .4 .1	0 x .2 x .5 .1 x .2 x .5 .15 x .2 x .4 .012							
nCpG	0	1 x .3 x .5 0 x .3 x .5 0 .3 x .6 .15	0 x .3 x .5 .1 x .3 x .5 .15 x .3 x .6 .027							

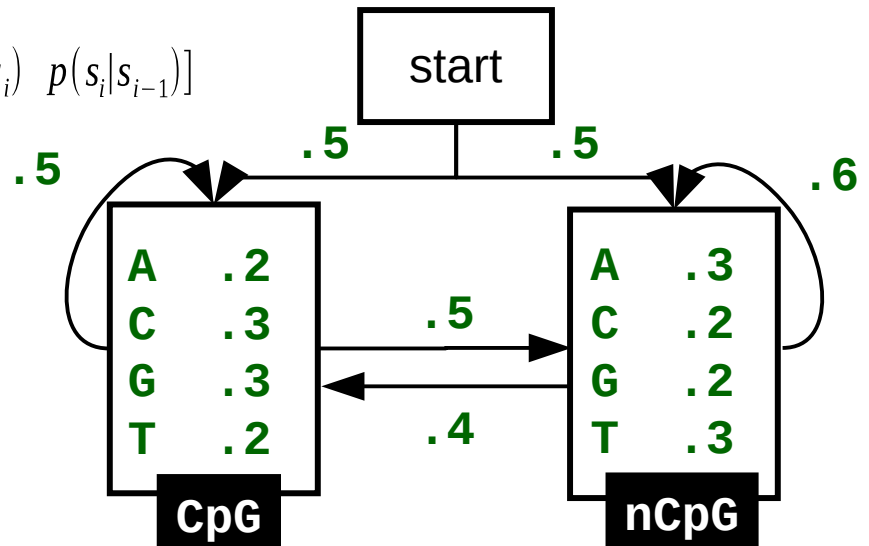
$$\max_{s_i \in S} p(x_0 \dots x_i | s_i) = \max_{s_{i-1} \in S} [p(x_0 \dots x_{i-1} | s_{i-1}) \max_{s_i \in S} p(x_i | s_i) p(s_i | s_{i-1})]$$



Viterbi algorithm (ex.)

	ϵ	A	T	G	G	C	A	C	T	A
START	1	0	0	0	0	0	0	0	0	0
CpG	0	$1 \times .2 \times .5$ $0 \times .2 \times .5$ $0 \times .2 \times .4$ $.1$	$0 \times .2 \times .5$ $.1 \times .2 \times .5$ $.15 \times .2 \times .4$ $.012$	0	$.012 \times .3 \times .5$ $.027 \times .3 \times .4$ $.0032$	0 $.0032 \times .3 \times .5$ $.0032 \times .3 \times .4$ $5e-4$	0 $.012 \times .3 \times .5$ $.027 \times .3 \times .4$ $5e-5$			
nCpG	0	$1 \times .3 \times .5$ $0 \times .3 \times .5$ $0.3 \times .6$ $.15$	$0 \times .3 \times .5$ $.1 \times .3 \times .5$ $.15 \times .3 \times .6$ $.027$	0	$.012 \times .2 \times .5$ $.027 \times .2 \times .6$ $.0032$ $4e-4$	0 $.0032 \times .2 \times .5$ $.0032 \times .2 \times .6$ $4e-5$				

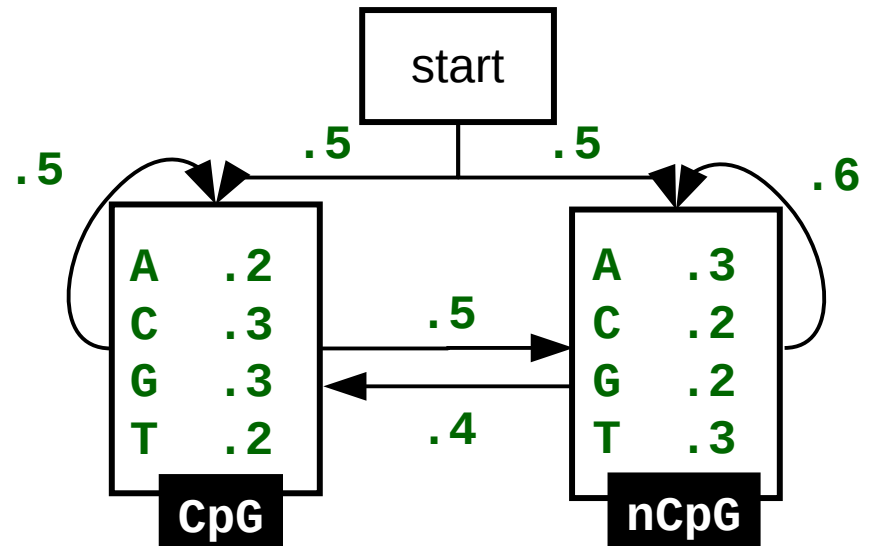
$$\max_{s_i \in S} p(x_0 \dots x_i | s_i) = \max_{s_{i-1} \in S} [p(x_0 \dots x_{i-1} | s_{i-1}) \max_{s_i \in S} p(x_i | s_i) p(s_i | s_{i-1})]$$



Viterbi algorithm (ex.)

	ϵ	A	T	G	G	C	A	C	T	A
START	0	-inf	-inf	-inf	-inf	-inf	-inf	-inf	-inf	-inf
CpG	-inf	ln.2+0+ln.5 ln.2+ -inf +ln.5 ln.2+ -inf +ln.4 -2.30	ln.2+ -inf +ln.5 ln.2+0+ln.5 ln.2+ln.15+ln.4 -2.3							
nCpG	-inf	ln.3+0+ln.5 ln.3+ -inf +ln.5 ln.3+ -inf +ln.6 -1.9	-inf ln.3+ln.1+ln.5 ln.3+ln.15+ln.6 -1.9							

$$\arg \max_{s_i \in S} p(x_0 \dots x_i | s_i) = \arg \max_{s_i \in S} \log p(x_0 \dots x_i | s_i)$$



Viterbi alg. – pseudocode

```
function VITERBI( O, S,  $\pi$ , Y, A, B ) : X
  for each state  $s_i$  do
     $T1[i,1] \leftarrow \pi_i \cdot B_{iy1}$ 
     $T2[i,1] \leftarrow 0$ 
  end for
  for  $i \leftarrow 2, 3, \dots, T$  do
    for each state  $s_j$  do

      end for
    end for

     $x_T \leftarrow s_T$ 
    for  $i \leftarrow T, T-1, \dots, 2$  do
       $z_{i-1} \leftarrow T2[z_i, i]$ 
       $x_{i-1} \leftarrow s_{z_{i-1}}$ 
    end for
    return X
  end function
```

Assignment – Gene Finding

- ⬅ <http://www.biostat.wisc.edu/~craven/776/hw3.html>
- ⬅ **You can use an existing implementation of Viterbi alg.**
- ⬅ 15 pt.

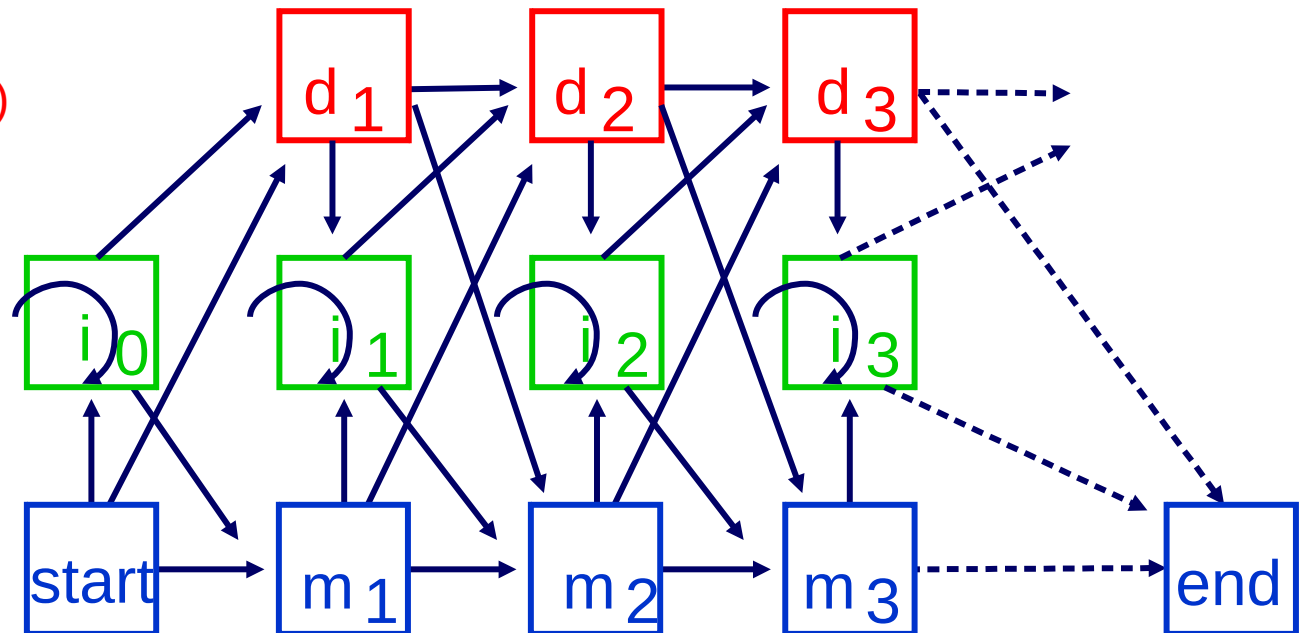
Profile HMM

ATTGCC- A TT--
ATGGCC- A TT--
ATC-CA- A TTTT
ATCTTC- - TT--
ATTGCCG A TT--

Delete states (silent)

Insert states

Match states



Profile HMM – Exercise

bat	AG - - - C
rat	A - AA - C
cat	AG - AA -
dog	- GAC - C
fox	AC - - - G
	XXXXXX

Given the alignment:

- ← Make a profile HMM

Profile HMM – Exercise

bat	AG--C
rat	A-AA-C
cat	AG-AA-
dog	-GAC-C
fox	AC--G
	12-3-4

⬅ Heuristic:

```
if #('-') < #('X') - 1:  
    if pos == '-':  
        pos = '-'  
    else:  
        pos = 'X'  
else:  
    pos = '*'
```


Profile HMM – Exercise

bat	AG---C
rat	A-AA-C
cat	AG-AA-
dog	-GAC-C
fox	AC---G
	12---3

⬅ **... more regularized:**

```
if #('-') < #('X') - 1:  
    if pos == '-':  
        pos = '-'  
    else:  
        pos = 'X'  
else:  
    pos = '*'
```

Profile HMM – Exercise

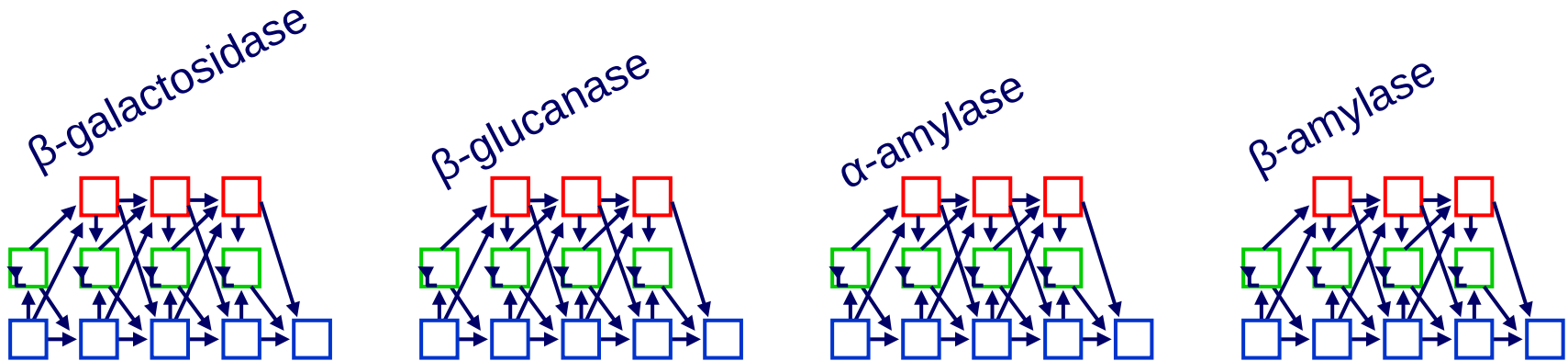
bat AG---C
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dog -GAC-C
fox AC---G
 12---3

ass AGG

- ↻ Make a profile model M
- ↻ Compute the probability that a new (non-aligned) sequence has been generated by M :

$$P(AGG|M) = p_M(A|s_1)p_M(s_1)p_M(G|s_2)p_M(s_2|s_1)p_M(G|s_3)p_M(s_3|s_2)$$

Sequence Categorization



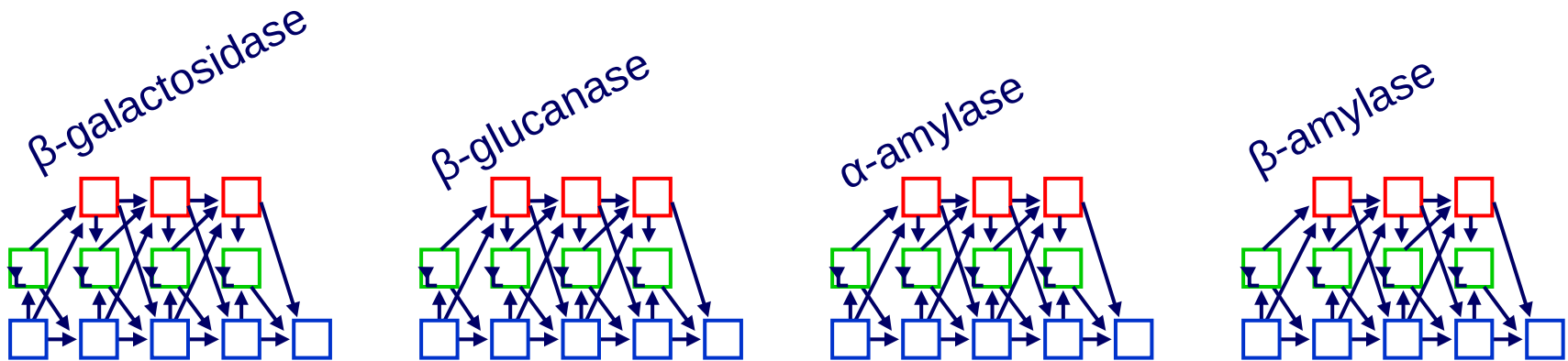
Given:

- ⌚ observed sequence $\mathbf{x} \in A^L$
- ⌚ Set of K models $\{M_k = (A, S, P_t, P_e)\}$ of K families

Do:

- ⌚ categorize \mathbf{x} into one of the families

Sequence Categorization



Given:

- ↻ observed sequence $\mathbf{x} \in \{a, c, t, g\}^L$
- ↻ Set of K models $\{M_k = (A, S, P_t, P_e)\}$ of K families

Do:

- ↻ categorize \mathbf{x} into one of the families

$$p(\alpha\text{-amyl}|x_1 \dots x_L) < p(\beta\text{-gluc}|x_1 \dots x_L)$$

$$p(\alpha\text{-amyl}) p(x_1 \dots x_L | \alpha\text{-amyl}) < p(\beta\text{-gluc}) p(x_1 \dots x_L | \beta\text{-gluc})$$

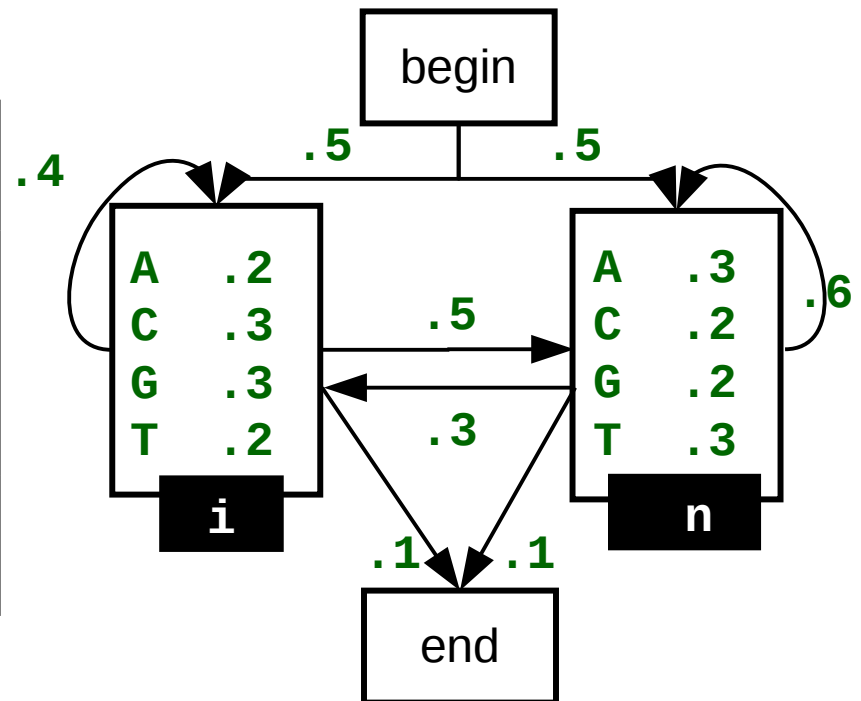
$$p(x_1 \dots x_L | c) = \sum_{s_1 \dots s_L \in S^L} p(x_1 \dots x_L; s_1 \dots s_L | c) = \sum_{s_1 \dots s_L \in S^L} p_c(x_1 | s_1) p_c(s_1) \prod_{i=1}^L p_c(x_i | s_i) p(s_i | s_{i-1})$$

Forward algorithm (ex.)

$$\sum_{s_1, s_2, s_3 \in S^3} p(\text{CAG}, s_1 s_2 s_3) = \sum_{s_1 \in \{i, n\}} p(\text{C}|s_1) p(s_1|\text{b}) \sum_{s_2 \in \{i, n\}} p(\text{G}|s_2) p(s_2|s_1) \sum_{s_3 \in \{i, n\}} p(\text{A}|s_3) p(s_3|s_2) p(\text{e}|s_3)$$

$$T[i, j] = \sum_k T[k, i-1] * p(s_i|s_k) * p(x_i|s_i)$$

	ϵ	C	G	A	ϵ
begin	1	0	0	0	0
i	0	0	0	0	0
n	0	0	0	0	0
end		0	0	0	0

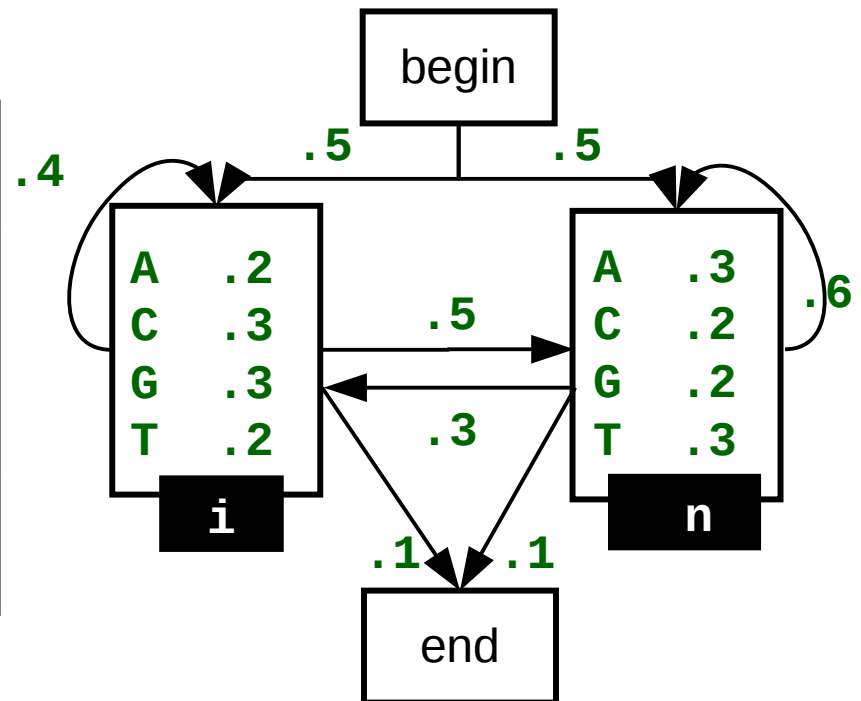


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	ϵ	C	G	A	ϵ
begin	1	0	0	0	0
i	0	1 x .5 x .3 0 x .4 x .3 0 x .3 x .3 .15	0	0	0
n	0	0	0	0	0
end		0	0	0	0

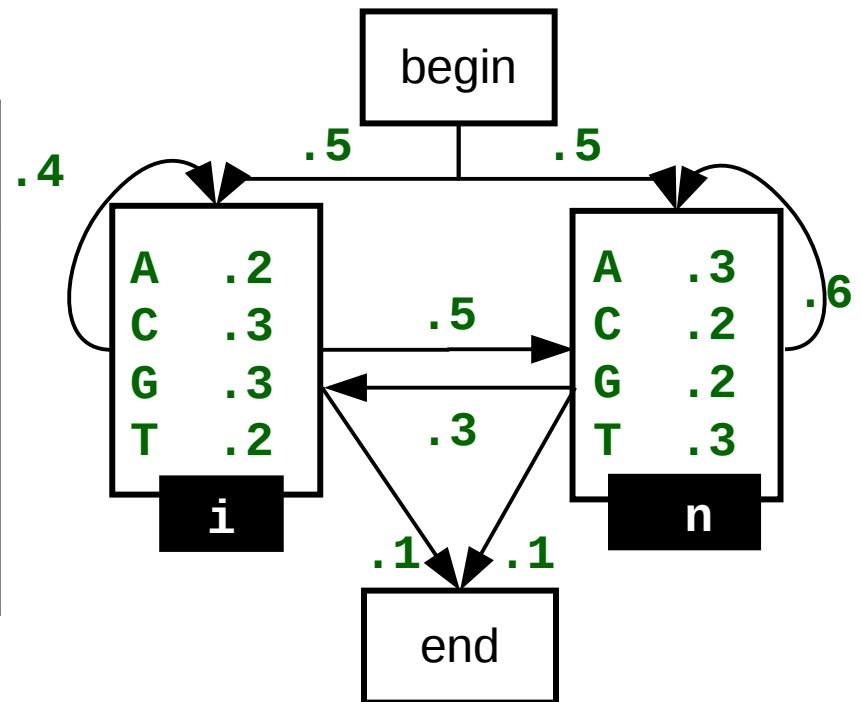


Forward algorithm (ex.)

$$\sum_{s_1 s_2 s_3 \in S^3} p(\text{CAG}, s_1 s_2 s_3) = \sum_{s_1 \in \{i, n\}} p(\text{C}|s_1) p(s_1|b) \sum_{s_2 \in \{i, n\}} p(\text{G}|s_2) p(s_2|s_1) \sum_{s_3 \in \{i, n\}} p(\text{A}|s_3) p(s_3|s_2) p(e|s_3)$$

$$T[i, j] = \sum_k T[k, i-1] * p(s_i|s_k) * p(x_i|s_i)$$

	ϵ	C	G	A	ϵ
begin	1	0	0	0	0
I	0	$1 \times .5 \times .3$ $0 \times .4 \times .3$ $0 \times .3 \times .3$.15	0	0	0
N	0	$1 \times .5 \times .2$ $0 \times .5 \times .2$ $0 \times .6 \times .2$.1	0	0	0
end		0	0	0	0

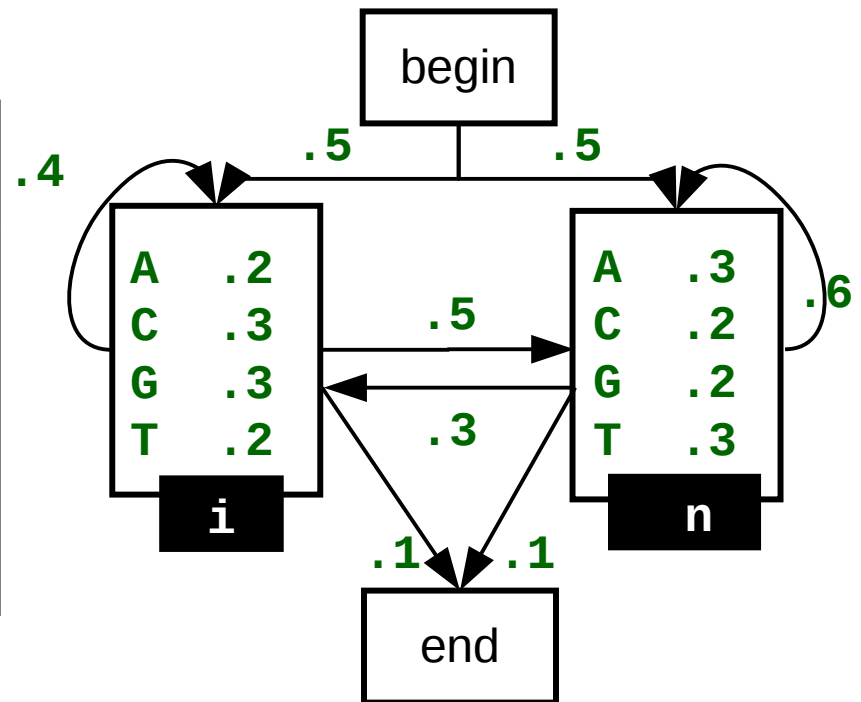


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$$\sum_{s_1, s_2, s_3 \in \mathcal{S}^3} p(\text{CAG}, s_1 s_2 s_3) = \sum_{s_1 \in \{i, n\}} p(\text{C}|s_1) p(s_1|b) \sum_{s_2 \in \{i, n\}} p(\text{G}|s_2) p(s_2|s_1) \sum_{s_3 \in \{i, n\}} p(\text{A}|s_3) p(s_3|s_2) p(e|s_3)$$

$$T[i, j] = \sum_k T[k, i-1] * p(s_i | s_k) * p(x_i | s_i)$$

	ϵ	C	G	A	ϵ
begin	1	0	0	0	0
I	0	$1 \times .5 \times .3$ $0 \times .4 \times .3$ $0 \times .3 \times .3$.15	$0 \times .5 \times .3$ $.15 \times .4 \times .3$ $.1 \times .3 \times .3$.026	0	0
N	0	$1 \times .5 \times .2$ $0 \times .5 \times .2$ $0 \times .6 \times .2$.1	$0 \times .5 \times .2$ $.15 \times .5 \times .2$ $.1 \times .6 \times .2$.027	0	0
end		0	0	0	0

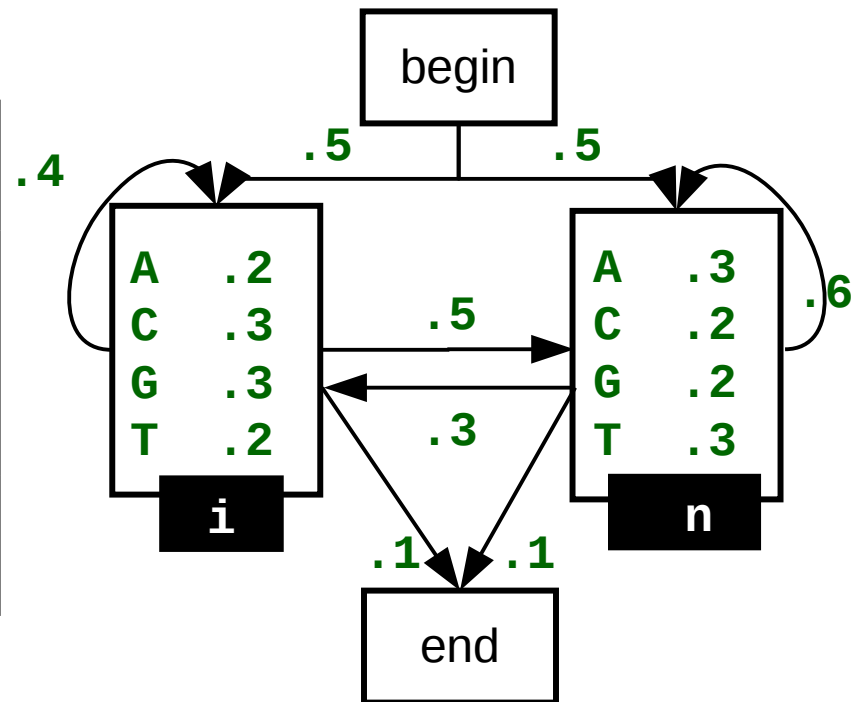


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$$T[i, j] = \sum_k T[k, i-1] * p(s_i | s_k) * p(x_i | s_i)$$

	ϵ	C	G	A	ϵ
begin	1	0	0	0	0
I	0	$1 \times .5 \times .3$ $0 \times .4 \times .3$ $0 \times .3 \times .3$.15	$0 \times .5 \times .3$ $.15 \times .4 \times .3$ $.1 \times .3 \times .3$.026	$0 \times .5 \times .2$ $0.026 \times .4 \times .2$ $.027 \times .3 \times .2$.004	0
N	0	$1 \times .5 \times .2$ $0 \times .5 \times .2$ $0 \times .6 \times .2$.1	$0 \times .5 \times .2$ $.15 \times .5 \times .2$ $.1 \times .6 \times .2$.027	$0 \times .5 \times .3$ $.026 \times .5 \times .3$ $.027 \times .6 \times .3$.009	0
end		0	0	0	0

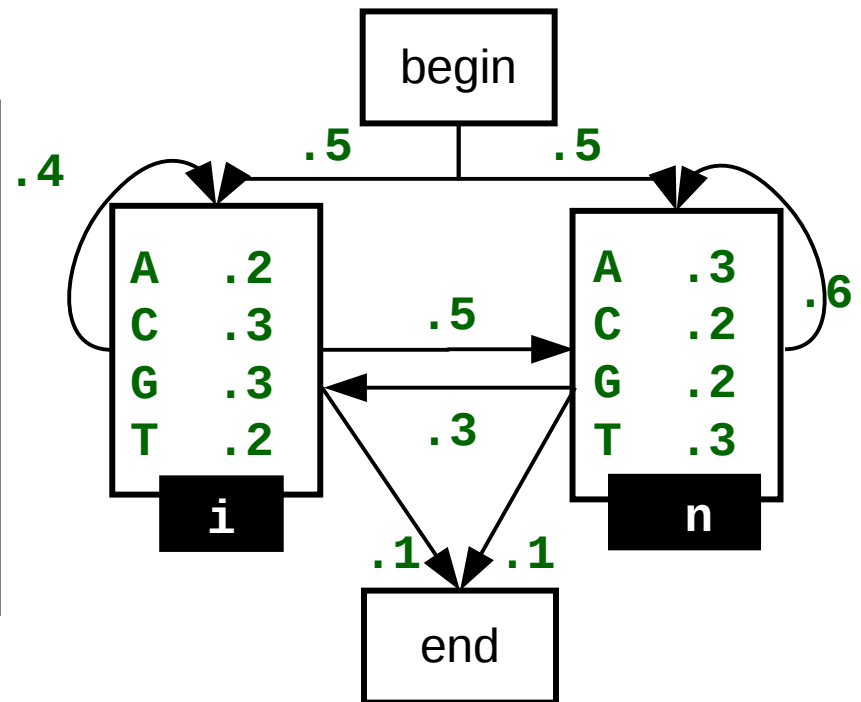


Forward algorithm (ex.)

$$\sum_{s_1, s_2, s_3 \in S^3} p(\text{CAG}, s_1 s_2 s_3) = \sum_{s_1 \in \{i, n\}} p(\text{C}|s_1) p(s_1|b) \sum_{s_2 \in \{i, n\}} p(\text{G}|s_2) p(s_2|s_1) \sum_{s_3 \in \{i, n\}} p(\text{A}|s_3) p(s_3|s_2) p(e|s_3)$$

$$T[i, j] = \sum_k T[k, i-1] * p(s_i | s_k) * p(x_i | s_i)$$

	ϵ	C	G	A	ϵ
begin	1	0	0	0	0
I	0	$1 \times .5 \times .3$ $0 \times .4 \times .3$ $0 \times .3 \times .3$.15	$0 \times .5 \times .3$ $.15 \times .4 \times .3$ $.1 \times .3 \times .3$.026	$0 \times .5 \times .2$ $0.026 \times .4 \times .2$ $.027 \times .3 \times .2$.004	0
N	0	$1 \times .5 \times .2$ $0 \times .5 \times .2$ $0 \times .6 \times .2$.1	$0 \times .5 \times .2$ $.15 \times .5 \times .2$ $.1 \times .6 \times .2$.027	$0 \times .5 \times .3$ $.026 \times .5 \times .3$ $.027 \times .6 \times .3$.009	0
end		0	0	0	$0 \times .5$ $.004 \times .1$ $.009 \times .1$.0013



Profile HMM – Exercise

bat **AG** - - - **C**
 rat **A** - **AA** - **C**
 cat **AG** - **AA** -
 dog - **GAC** - **C**
 fox **AC** - - - **G**
 12 - - - **3**

- ↪ Make a profile model M
- ↪ Compute the probability that a new (non-aligned) sequence has been generated by M :

$$P(\text{AGG}|M) = p_M(A|s_1)p_M(s_1)p_M(G|s_2)p_M(s_2|s_1)p_M(G|s_3)p_M(s_3|s_2)$$

ass AGG

$$T[i, j] = \sum_k T[k, i-1] * p(s_i | s_k) * p(x_i | s_i)$$

$$T[i, j] = \sum_k T[k, i] * p(s_i | s_k)$$

Profile HMM – Exercise

bat **AG** - - - -
rat **A** - **AA** - **C**
cat **AG** - **AA** -
dog - **GAC** - **C**
fox **AC** - - - **G**
 12 - - - **3**

- ↻ Make a profile model M
- ↻ Employ M to align the sequence.

$$P(\text{AGG}|M) = p_M(A|s_1)p_M(s_1)p_M(G|s_2)p_M(s_2|s_1)p_M(G|s_3)p_M(s_3|s_2)$$

ass **AGG**

$$T[i, j] = \max_k T[k, i-1] + \log p(s_i | s_k) + \log p(x_i | s_i)$$

$$S[i, j] = \operatorname{argmax}_k S[k, i-1] + \log p(s_i | s_k) + \log p(x_i | s_i)$$

$$T[i, j] = \max_k T[k, i] + \log p(s_i | s_k)$$

$$S[i, j] = \max_k T[k, i] + \log p(s_i | s_k)$$

Sum-up

- ↩ Sequence categorization into family of sequences (Forward alg.)
- ↩ Sequence anotation: CpG detection, gene finding (Viterbi alg.)
- ↩ Learning ***hidden*** parameters (Baum-Welsh alg.)