

Naming and State

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Naming Features

- Nameable values
- Parameter-passing mechanisms
- Scoping
- Name control
- Multiple namespaces
- Name capture
- Side effects

Parameter Passing

- call-by-name - a formal parameter names the computation designated by an unevaluated argument expression. Normal-order reduction strategy. (Haskell)
- call-by-value - a formal parameter names the value of an evaluated argument expression. Strict argument evaluation strategy. (C, Java, Pascal)

Call-by-name vs. Call-by-value

CBN	CBV
<pre>(app (lam x (prim * x x)) (prim + 2 3)) $\xrightarrow{CBN}_{[\beta]}$ (prim * (prim + 2 3) (prim + 2 3)) $\xrightarrow{CBN}_{[+]}$ (prim * 5 (prim + 2 3)) $\xrightarrow{CBN}_{[+]}$ (prim * 5 5) $\xrightarrow{CBN}_{[*]}$ 25</pre>	<pre>(app (lam x (prim * x x)) (prim + 2 3)) $\xrightarrow{CBV}_{[+]}$ (app (lam x (prim * x x)) 5) $\xrightarrow{CBV}_{[\beta\text{-value}]}$ (prim * 5 5) $\xrightarrow{CBV}_{[*]}$ 25</pre>
<pre>(app (lam x 2) (prim / 1 0)) $\xrightarrow{CBN}_{[\beta]}$ 2</pre>	<pre>(app (lam x 2) (prim / 1 0)) <i>{This stuck expression models an error}</i></pre>
<pre>(app (lam x 3) (app (lam a (app a a)) (lam a (app a a)))) $\xrightarrow{CBN}_{[\beta]}$ 3</pre>	<pre>(app (lam x 3) (app (lam a (app a a)) (lam a (app a a)))) $\xrightarrow{CBV}_{[\beta\text{-value}]}$ (app (lam x 3) (app (lam a (app a a)) (lam a (app a a)))) $\xrightarrow{CBV}_{[\beta\text{-value}]}$... <i>{Infinite loop}</i></pre>

Call-by-denotation (CBD)

- Call-by-name determines the meaning of an operand expression relative to the environment available at the **point of call**.
- Call-by-denotation instead determines the meaning of an operand expression relative to the environment **where the formal parameter is referenced**.

CBD Example

```
(app (lam y
      (app (lam x y)
            3))
     x)
```

- Error in Call-by-name or Call-by-value (because x is unbound).
- In CBD, the unevaluated outer x is effectively substituted for y .

CBD Example

```
(app (lam x x) 3)
```

- CBD allows name capture.
- The evaluation of the outer x yields not what we would normally think of as a value but an environment accessor that is eventually applied to an environment that has a binding for the inner x .

Static Scope

```
function f(int a) {  
  
    function g(int b) {  
        return a + b;  
    }  
  
    return a + g(3);  
}
```

- In a statically scoped language, every variable reference refers to the variable introduced by the **nearest lexically enclosing variable declaration** of that identifier in the abstract syntax tree of the program.

Dynamic Scope

- A free variable in a procedure (or macro) body gets its meaning from the environment at the point **where the procedure is called** rather than the environment at the point where the procedure is created.
- In these languages, it is not possible to determine a **unique declaration corresponding to a given free variable reference**; the effective declaration depends on where the procedure is called.

Dynamic Scope

```
(let ((a 1))
  (let ((f (abs (x) (@+ x a))))
    (let ((a 20))
      (f 300))))
```

- In static scope a in f refers to 1, where the f was defined. The result is 301.
- In dynamic scope a in f refers to 20, where the f was called. The result is 320.

Multiple Namespaces

```
class X {  
    int x;  
  
    X(int x) {  
        this.x = x;  
    }  
  
    int x() { return x; }  
}
```

State

- Purely functional languages and math are **stateless**.
- We can model state in functional languages as **an iteration** over states.
- **An iteration** is a computation that characterizes the state of a system in terms of the values of a set of variables known as its **state variables**.
- The value of each **state variable** in **an iteration** at time **t** is a **function of the values** of the state variables at time **t - 1**.

State

$$\mathit{max} : N^* \rightarrow N$$

$$\mathit{max}(\langle a_1, \dots, a_n \rangle) = \mathit{loop}(\langle a_1, \dots, a_n \rangle, 1, 0)$$

$$\mathit{loop} : N^* \times N \times N \rightarrow N$$

$$\mathit{loop}(\langle a_1, \dots, a_n \rangle, c, m) = m \quad \text{if } c > n$$

$$\mathit{loop}(\langle a_1, \dots, a_n \rangle, c, m) = \mathit{loop}(\langle a_1, \dots, a_n \rangle, c + 1, m) \quad \text{if } c \leq n \wedge a_c \leq m$$

$$\mathit{loop}(\langle a_1, \dots, a_n \rangle, c, m) = \mathit{loop}(\langle a_1, \dots, a_n \rangle, c + 1, a_c) \quad \text{otherwise}$$

Monadic Style

- Monadic style separates state handling code.
- The name “monadic style” is derived from an algebraic structure, **the monad**, that captures the essence of manipulating information that is single-threaded through a computation.

Monadic Style Example

$$\textit{State} = N^* \times N \times N$$

$$\textit{Action} = \textit{State} \rightarrow \textit{State}$$

$$\textit{Condition} = \textit{State} \rightarrow \textit{Boolean}$$

$$\textit{updateMax} : \textit{Action}$$

$$\textit{updateMax}(\langle a_1, \dots, a_n \rangle, c, m) = (\langle a_1, \dots, a_n \rangle, c, a_c)$$

$$\textit{updateNeeded} : \textit{Condition}$$

$$\textit{updateNeeded}(\langle a_1, \dots, a_n \rangle, c, m) = \textit{true} \quad \text{if } a_c > m$$

$$\textit{updateNeeded}(\langle a_1, \dots, a_n \rangle, c, m) = \textit{false} \quad \text{otherwise}$$

$$\textit{increaseIndex} : \textit{Action}$$

$$\textit{increaseIndex}(\langle a_1, \dots, a_n \rangle, c, m) = (\langle a_1, \dots, a_n \rangle, c + 1, m)$$

Monadic Style Example

notFinished : Condition

notFinished($\langle a_1, \dots, a_n \rangle, c, m$) = *false* if $c > n$

finished($\langle a_1, \dots, a_n \rangle, c, m$) = *true* otherwise

ifStatement : Condition \times Action \rightarrow Action

ifStatement(*cond*, *body*) = $\lambda s. \text{body}(s)$ if *cond*(*s*) = *true*

ifStatement(*cond*, *body*) = $\lambda s. s$ otherwise

forLoop : Condition \times Action \times Action \rightarrow Action

forLoop(*cond*, *iter*, *body*) = $\lambda s. \text{ifStatement}(\text{cond},$

forLoop(*cond*, *iter*, *body*))(*iter*(*body*(*s*)))

Monadic Style Example

$$\mathit{max} : N^* \rightarrow N$$

$$\begin{aligned} \mathit{max}(\langle a_1, \dots, a_n \rangle) = \pi_3(\mathit{forLoop}(\mathit{notFinished}, \mathit{increaseIndex}, \\ \mathit{ifStatement}(\mathit{updateNeeded}, \mathit{updateMax})) \\ (\langle a_1, \dots, a_n \rangle, 1, 0)) \end{aligned}$$