# Landmarks

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# Planners & Heuristics

FF	FF (relaxed plan) heuristic
FD-MS	Merge&Shrink heuristic
FD-LMCut	LM-Cut heuristic
LAMA	FF + Landmark heuristic
mercury	Red-Black relaxation

### What is an action landmark?

- 1. An action which is used in at least one plan.
- 2. An action which must be used in all plans.
- 3. All actions in the optimal plan.

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- 2. An action which must be used in all plans.
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#### Answer:

2. An action which must be used in all plans.

### What is a disjunctive action landmark?

- 1. A set of actions from which at least one must be used in all plans.
- 2. A set of actions which all must be used in all plans.
- 3. A set of actions from which at least one must be used in all optimal plans..

#### Answer:

### What is a disjunctive action landmark?

- A set of actions from which at least one must be used in all plans.
- 2. A set of actions which all must be used in all plans.
- A set of actions from which at least one must be used in all optimal plans..

#### **Answer:**

1. A set of actions from which at least one must be used in all plans.

### A landmark-based heuristic

- 1. is allways admissible.
- 2. is never admissible.
- 3. can be either admissible or inadmissible.

#### Answer:

. . .

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#### Answer:

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## LM-Cut

- Admissible landmark-based heuristic
- Lower estimate of optimal relaxed plan
- Using disjunctive action landmarks
  - Set of actions from which at least one must be in each relaxed plan
- Note: add i and g facts and respective 0-cost actions

### LM-Cut – The idea

- Find preconditions which justify the cost of actions
  - Using h<sub>max</sub>
- Construct a justification graph using only those preconditions
- Find a cut in the justification graph
  - The cut forms a disjunctive action landmark
- Discount the cost of the least-cost action in the landmark from the costs of all actions in the landmark
  - Results in cost-partitioning
- Start all over again (with the modified costs)
  - Until  $h_{max}(g)=0$

## LM-Cut – The cut

- In the justification graph J
- Find all facts p from which g is reachable by a 0-cost path → Vg
- Find all facts p' reachable from i without visiting a fact in V\*
- Edges between facts in V\* and Vg form the cut