

# Parallel Genetic Algorithms

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## Motivation

GAs applied on complex tasks need long run times to solve the problem:

- ✓ What is usually the most time-consuming task when solving real-world problems?
    - ✗ Fitness evaluation!!!
      - ✓ In complex tasks solved by GAs, chromosome is long, often genotype-phenotype mapping must be applied, ...
      - ✓ In GP, when evolving classifiers, functions, or programs, the fitness must be assessed by measuring the success when applying the classifier, function, or program on a set of training task instances
    - ✗ In EDAs, model building is very time consuming!
- ⇒ PARALLELIZE!!!
- ✓ Which of the above can be parallelized easily???

## Agenda

How can we parallelize?

1. Run several independent GAs in parallel.
2. Run single GA, but distribute the time consuming things to parallel machines. (**Master-slave model.**)
3. Run several *almost independent* GAs in parallel; exchange a few individuals from time to time. (**Island model.**)
4. Run single GA with selection that takes only a few individuals into account. (**Spatially embedded model.**)
5. Run hybrid parallel GA. (**Hierarchical model.**)
6. Other, less standard possibilities. (**Injection model, heterogenous PGA.**)

But first:

- ✓ The difference between parallel model and parallel implementation.

## Parallel Implementation vs. Parallel Model

### Sequential implementation:

- ✓ The algorithm is able to run on a single machine in a single process, often in a single thread only.

### Parallel implementation:

- ✓ The algorithm is able to take advantage of multiple CPU cores or multiple machines.

### The effect of parallelization:

- ✓ Reduction in the solution time by *adding a computational power*.
- ✓ The speed-up should be proportional to the number of parallel machines.

### Possible combinations:

- ✓ Sequential implementation of the global model (usual case, simple GA)
- ✓ Parallel implementation of the global model (master-slave, brute-force speed-up)
- ✓ Sequential implementation of a parallel model (modified behavior)
- ✓ Parallel implementation of a parallel model (modified behavior, brute-force speed-up)

### Global model:

- ✓ The population is not divided in any way, the selection operator can consider all individuals.

### Parallel model:

- ✓ The population is somehow divided into subpopulations, which limits mainly the selection operator.

### The effect of parallelization:

- ✓ Changes the algorithm behavior substantially.

## Parallelization of the Global Model

### Master-slave model

#### Master

- ✓ runs the evolutionary algorithm, and
- ✓ controls the slaves, distributes the work.

#### Slaves

- ✓ take batches of individuals from the master,
- ✓ evaluate them, and
- ✓ send their fitness back to master.

#### Other possibilities:

- ✓ Sometimes we can parallelize also initialization, mutation, and (with a bit of care) crossover.
- ✓ The hardest parts to parallelize are selection and replacement.
- ✓ When does the parallelization actually pay off???

Master-slave implementation does not change the behavior of the global model.

- ✓ Hints on implementation (locking, synchronizing) can be found in [Luk09, chap. 5].

[Luk09] Sean Luke. *Essentials of Metaheuristics*. 2009. available at <http://cs.gmu.edu/~sean/book/metaheuristics/>.

**Island Model**

Also called *coarse-grained PGA* or *multi-deme GA*:

- ✓ By far the most often used model of PGA.
- ✓ Population divided into several subpopulations (demes).
- ✓ Demes evolve independently. *Almost*.

**Migration:**

- ✓ Occasionally, the demes exchange some individuals.

The profit from island model:

- ✓ Demes are smaller:
  - ✗ converge faster,
  - ✗ can converge to different local optima, but
  - ✗ can converge prematurely.
- ✓ Thanks to migration, new, *potentially good* (not random), genetic material can be obtained from other demes.

DEMO: Island model of PGA applied on TSP

<http://labe.felk.cvut.cz/~posik/pga>

**Migration**

**Migration topology:** Where should we take the migrants from and where should we put them?

- ✓ static: given in advance, does not change during evolution
- ✓ dynamic: the sources and targets are chosen right before particular migration event
  - ✗ can take the similarity of demes into account when choosing sources and targets
- ✓ degree of connectivity (DOC),  $\delta$ :
  - ✗ the number of demes used as sources of migrants for another deme in one particular migration event
  - ✗ topologies with the same DOC exhibit similar behavior
  - ✗ in a comparison of fully-connected topology, 4D hypercube,  $4 \times 4$  toroidal net, and one-way and two-way rings, densely connected topologies were able to find the global optimum with lower number of evaluation

**Migration trigger:** When should we run the migration?

- ✓ static schedule: migrate every  $n^{\text{th}}$  generation, at predefined time instants
- ✓ feedback trigger: migrate when it is needed, when the deme diversity drops below certain level
  - ✗ initiated by a source deme or by a target deme
  - ✗ diversity  $\rightarrow$  convergence; population convergence vs. convergence in time

## Migration (cont.)

**Migration type:** Can the migration events occur individually or in batches?

- ✓ batch: all migration events occur in the same time, all demes send emigrants to their targets and take the immigrants from their sources
- ✓ individual: a migration event (migrants move from one deme to another) can occur any time, independently of other events

**Migration selection and replacement strategy:**

Which individuals should be selected as emigrants? Which individuals should be replaced by immigrants?

- ✓ Best, worst
- ✓ Best, random
- ✓ Random, worst

**Migration count:** How many individuals should we migrate?

- ✓ often chosen from the interval

$$n_{\text{mig}} \in \left(1, \frac{\text{deme size}}{\delta + 1}\right)$$

**Other possibilities, issues:**

- ✓ sometimes, migration is described as *synchronous* or *asynchronous*, not used here; the meaning is not clear: synchronous with time vs. synchronous with other mig. event
- ✓ increase the fitness of migrants so that they can influence the target deme at least for 1 generation
- ✓ term *epoch* in the context of PGAs describes the part of evolution between 2 migration events

## Other Parallel Models

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### Spatially Embedded Model

Also called *fine-grained PGA*:

- ✓ Population has a structure (1D grid, 2D toroidal grid, 3D cube, etc.)
- ✓ Each individual has a position in this structure.
- ✓ Individuals are allowed to breed with only nearby neighbors. Replace individual in certain slot with children bred from neighbors of this slot.
- ✓ The best individuals do not spread in the population so fast. Diversity promotion.
- ✓ Easy parallelization via multithreading.
- ✓ Very efficient model for *vector processors*, often found on GPUs:
  - ✗ many identical operations can be performed in parallel at one time

## Model Combinations

### Hierarchical model:

- ✓ various combinations of the above mentioned models, e.g.
- ✓ island model where each deme uses master-slave fitness evaluation,
- ✓ island model where each deme uses spatially embedded model, etc.

### Heterogenous model:

- ✓ Each deme uses a different optimizer
  - ✗ Different parameter settings
  - ✗ Different operators of selection, crossover, mutation and/or replacement
  - ✗ Completely different optimization algorithm (local search, differential evolution, ...)
  - ✗ Can each deme use a *different fitness function*???

## Injection Model

Heterogenous island model where

- ✓ each deme uses a different fitness function!!!
- ✓ Usable when many quality criteria must be assessed; each deme
  - ✗ concentrates on one criterion and
  - ✗ submits partial solutions to other demes to be reworked using another criterion.
- ✓ Each deme preserves solutions of high quality when only its particular criterion is applied.

**Summary**

- ✓ Parallelization can increase the speed the EA:
  - ✗ parallel implementations
  - ✗ parallel models
- ✓ Parallel models change the behavior of the EA:
  - ✗ they can reduce the danger of premature convergence and speed-up the algorithm in the same time.
- ✓ There are many possibilities on parallelization:
  - ✗ the optimal decision depends on the (parallel) computer architecture and on the task being solved
  - ✗ all possibilities introduce their own set of tunable parameters :-)