

# Parallel Genetic Algorithms

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## Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

Summary

GAs applied on complex tasks need long run times to solve the problem:

- ✓ What is usually the most time-consuming task when solving real-world problems?

## Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

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- ✓ What is usually the most time-consuming task when solving real-world problems?
  - ✗ Fitness evaluation!!!
    - ✓ In complex tasks solved by GAs, chromosome is long, often genotype-phenotype mapping must be applied, ...
    - ✓ In GP, when evolving classifiers, functions, or programs, the fitness must be assessed by measuring the success when applying the classifier, function, or program on a set of training task instances

## Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

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## Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

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## Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

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- ✓ Which of the above can be parallelized easily???

# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

---

Other Parallel Models

---

Summary

---

How can we parallelize?

# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

---

Other Parallel Models

---

Summary

---

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# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

Summary

How can we parallelize?

1. Run several independent GAs in parallel.
2. Run single GA, but distribute the time consuming things to parallel machines.  
(**Master-slave model.**)

# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

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How can we parallelize?

1. Run several independent GAs in parallel.
2. Run single GA, but distribute the time consuming things to parallel machines. (**Master-slave model.**)
3. Run several *almost independent* GAs in parallel; exchange a few individuals from time to time. (**Island model.**)

# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

Summary

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# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

Summary

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5. Run hybrid parallel GA. (**Hierarchical model.**)

# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

Summary

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5. Run hybrid parallel GA. (**Hierarchical model.**)
6. Other, less standard possibilities. (**Injection model, heterogenous PGA.**)

# Agenda

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models

Summary

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But first:

- ✓ The difference between parallel model and parallel implementation.

# Parallel Implementation vs. Parallel Model

## Sequential implementation:

- ✓ The algorithm is able to run on a single machine in a single process, often in a single thread only.

## Parallel implementation:

- ✓ The algorithm is able to take advantage of multiple CPU cores or multiple machines.

## The effect of parallelization:

- ✓ Reduction in the solution time by *adding a computational power*.
- ✓ The speed-up should be proportional to the number of parallel machines.

## Global model:

- ✓ The population is not divided in any way, the selection operator can consider all individuals.

## Parallel model:

- ✓ The population is somehow divided into subpopulations, which limits mainly the selection operator.

## The effect of parallelization:

- ✓ Changes the algorithm behavior substantially.

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## Possible combinations:

- ✓ Sequential implementation of the global model (usual case, simple GA)
- ✓ Parallel implementation of the global model (master-slave, brute-force speed-up)
- ✓ Sequential implementation of a parallel model (modified behavior)
- ✓ Parallel implementation of a parallel model (modified behavior, brute-force speed-up)

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Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Master-slave model

Island Model

---

Other Parallel Models

---

Summary

---

## Parallelization of the Global Model

# Master-slave model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Master-slave model

Island Model

Other Parallel Models

Summary

## Master

- ✓ runs the evolutionary algorithm, and
- ✓ controls the slaves, distributes the work.

## Slaves

- ✓ take batches of individuals from the master,
- ✓ evaluate them, and
- ✓ send their fitness back to master.

## Other possibilities:

- ✓ Sometimes we can parallelize also initialization, mutation, and (with a bit of care) crossover.
- ✓ The hardest parts to parallelize are selection and replacement.
- ✓ When does the parallelization actually pay off???

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Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Master-slave model

Island Model

Other Parallel Models

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Master-slave implementation does not change the behavior of the global model.

- ✓ Hints on implementation (locking, synchronizing) can be found in [Luk09, chap. 5].

[Luk09] Sean Luke. *Essentials of Metaheuristics*. 2009. available at <http://cs.gmu.edu/~sean/book/metaheuristics/>.

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

**Island Model**

Island Model

Migration

Migration (cont.)

Other Parallel Models

---

Summary

---

# Island Model

# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

---

Summary

---

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- ✓ By far the most often used model of PGA.

# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

---

Summary

---

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# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

---

Summary

---

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# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

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# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

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# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

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The profit from island model:

- ✓ Demes are smaller:
  - ✗ converge faster,
  - ✗ can converge to different local optima, but
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# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

Summary

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# Island Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Island Model

Migration

Migration (cont.)

Other Parallel Models

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DEMO: Island model of PGA applied on TSP

<http://labe.felk.cvut.cz/~posik/pga>

**Migration topology:** Where should we take the migrants from and where should we put them?

- ✓ static: given in advance, does not change during evolution
- ✓ dynamic: the sources and targets are chosen right before particular migration event
  - ✗ can take the similarity of demes into account when choosing sources and targets

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- ✓ degree of connectivity (DOC),  $\delta$ :
  - ✗ the number of demes used as sources of migrants for another deme in one particular migration event
  - ✗ topologies with the same DOC exhibit similar behavior
  - ✗ in a comparison of fully-connected topology, 4D hypercube,  $4 \times 4$  toroidal net, and one-way and two-way rings, densely connected topologies were able to find the global optimum with lower number of evaluation

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- ✓ static schedule: migrate every  $n^{\text{th}}$  generation, at predefined time instants
- ✓ feedback trigger: migrate when it is needed, when the deme diversity drops below certain level

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  - ✗ diversity  $\rightarrow$  convergence; population convergence vs. convergence in time

**Migration type:** Can the migration events occur individually or in batches?

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- ✓ term *epoch* in the context of PGAs describes the part of evolution between 2 migration events



Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

---

**Other Parallel Models**

Spatially Embedded  
Model

Model Combinations

Injection Model

Summary

---

## Other Parallel Models

# Spatially Embedded Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

---

Island Model

---

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations

Injection Model

Summary

---

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- ✓ Population has a structure (1D grid, 2D toroidal grid, 3D cube, etc.)
- ✓ Each individual has a position in this structure.

# Spatially Embedded Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations

Injection Model

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# Spatially Embedded Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations

Injection Model

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# Spatially Embedded Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations

Injection Model

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# Spatially Embedded Model

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations  
Injection Model

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- ✓ Easy parallelization via multithreading.
- ✓ Very efficient model for *vector processors*, often found on GPUs:
  - ✗ many identical operations can be performed in parallel at one time

# Model Combinations

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations

Injection Model

Summary

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# Model Combinations

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

**Model Combinations**

Injection Model

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## Heterogenous model:

- ✓ Each deme uses a different optimizer
  - ✗ Different parameter settings
  - ✗ Different operators of selection, crossover, mutation and/or replacement
  - ✗ Completely different optimization algorithm (local search, differential evolution, ...)



# Model Combinations

Motivation

Agenda

Parallel Implementation  
vs. Parallel Model

Parallelization of the  
Global Model

Island Model

Other Parallel Models  
Spatially Embedded  
Model

Model Combinations

Injection Model

Summary

## Hierarchical model:

- ✓ various combinations of the above mentioned models, e.g.
- ✓ island model where each deme uses master-slave fitness evaluation,
- ✓ island model where each deme uses spatially embedded model, etc.

## Heterogenous model:

- ✓ Each deme uses a different optimizer
  - ✗ Different parameter settings
  - ✗ Different operators of selection, crossover, mutation and/or replacement
  - ✗ Completely different optimization algorithm (local search, differential evolution, ...)
  - ✗ Can each deme use a *different fitness function*???

# Injection Model

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Summary

Heterogenous island model where

- ✓ each deme uses a different fitness function!!!
- ✓ Usable when many quality criteria must be assessed; each deme
  - ✗ concetrates on one criterion and
  - ✗ submits partial solutions to other demes to be reworked using another criterion.
- ✓ Each deme preserves solutions of high quality when only its particular criterion is applied.

- Motivation
- Agenda
- Parallel Implementation vs. Parallel Model
- Parallelization of the Global Model
- Island Model
- Other Parallel Models
- Summary**
- Summary

# Summary

# Summary

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Agenda

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Other Parallel Models

Summary

Summary

- ✓ Parallelization can increase the speed the EA:
  - ✗ parallel implementations
  - ✗ parallel models

# Summary

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Summary

- ✓ Parallelization can increase the speed the EA:
  - ✗ parallel implementations
  - ✗ parallel models
- ✓ Parallel models change the behavior of the EA:
  - ✗ they can reduce the danger of premature convergence and speed-up the algorithm in the same time.

# Summary

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Agenda

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Summary

- ✓ Parallelization can increase the speed the EA:
  - ✗ parallel implementations
  - ✗ parallel models
- ✓ Parallel models change the behavior of the EA:
  - ✗ they can reduce the danger of premature convergence and speed-up the algorithm in the same time.
- ✓ There are many possibilities on parallelization:
  - ✗ the optimal decision depends on the (parallel) computer architecture and on the task being solved
  - ✗ all possibilities introduce their own set of tunable parameters :-)