

Deep Learning Essentials

3. Maximum Likelihood Estimation (MLE), KL Divergence

Where does loss function come from, what causes overfitting?

Lukáš Neumann



Motivating example: Fair coin

- TASK #1: We have a coin and we want to estimate what is the probability of Heads
 - Fair coin = probability of heads and tails is the same
 - In statistics, fair coin is term for a sequence of trials, each with a probability of 1/2



https://izbicki.me/blog/how-to-create-an-unfair-coin-and-prove-it-with-math.html



- 1. We assume data come from some distribution $\mathbf{p}(\mathbf{x}; \boldsymbol{\theta})$, where $\boldsymbol{\theta}$ are some parameters of the distribution
- 2. We observe data coming from the distribution $\mathbf{p}(\mathbf{x}; \boldsymbol{\theta})$, i.e. we have <u>training data</u>
- 3. We want to find the (unknown) value of θ
- How? We pick the $oldsymbol{ heta}$ which maximizes the probability that we actually had observed the data we did



- How? We pick the $oldsymbol{\theta}$ which maximizes the probability that we actually had observed the data we did
- We define the likelihood function $L(\theta)$ of the training data

$$L(\mathbf{\theta}) = \prod_{i=1}^{N} \mathbf{p}(\mathbf{x}_i; \mathbf{\theta})$$

• and find parameters θ^* which maximize the likelihood

$$\mathbf{\theta}^* = \operatorname*{argmax}_{\mathbf{\theta}} L(\mathbf{\theta})$$

- TASK #1: We have a coin and we want to estimate what is the probability for Heads
- Independent trials, each trial has only two outcomes \rightarrow Bernoulli distribution

$$\mathbf{p}(\text{heads}) = \kappa$$

 $\mathbf{p}(\text{tails}) = 1 - \kappa$

- In our training data, we have observed H times heads and T times tails
- The likelihood function is then given as

$$L(\kappa) = \prod_{i=1}^{N} \mathbf{p}(\mathbf{x}_i; \kappa) = \mathbf{p}(\text{heads})^{H} \mathbf{p}(\text{tails})^{T} = \kappa^{H} (1 - \kappa)^{T}$$

- We want find κ which maximizes likelihood $L(\kappa)$
- We take the derivative $\frac{\partial L}{\partial \kappa}$ and set it to 0
- In practice, is almost always easier to maximize log-likelihood rather than likelihood itself
 - logarithm is monotonically increasing function, it does not change the minimum

$$L(\kappa) = \kappa^{H} (1 - \kappa)^{T}$$

$$\log L(\kappa) = \log \kappa^{H} (1 - \kappa)^{T}$$

$$l(\kappa) = H \cdot \log \kappa + T \cdot \log (1 - \kappa)$$

$$\frac{\partial l}{\partial \kappa} = \frac{H}{\kappa} - \frac{T}{1 - \kappa} = 0$$

$$T \cdot \kappa = H \cdot (1 - \kappa)$$

$$\kappa = \frac{H}{H + T}$$

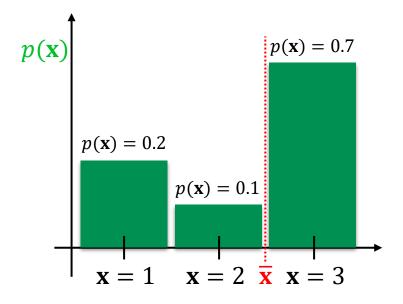




Coin	Heads	Tails	κ
0	53	47	0.53
1	55	45	0.55
2	49	51	0.49
3	41	59	0.41
4	39	61	0.39
5	27	73	0.27
6	0	100	0

Mean

$$\overline{\mathbf{x}} = \sum_{\mathbf{x}} p(\mathbf{x}) \cdot \mathbf{x} = \mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})}[\mathbf{x}] = 0.2 \cdot 1 + 0.1 \cdot 2 + 0.7 \cdot 3 = 2.5$$





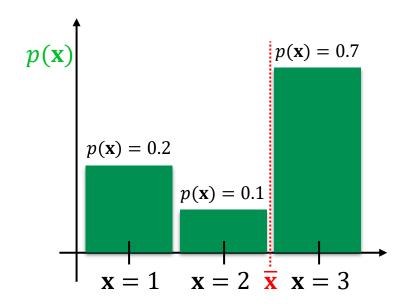


Mean

$$\overline{\mathbf{x}} = \sum_{\mathbf{x}} p(\mathbf{x}) \cdot \mathbf{x} = \mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})}[\mathbf{x}] = 0.2 \cdot 1 + 0.1 \cdot 2 + 0.7 \cdot 3 = 2.5$$

Average

$$\approx \frac{1}{N} \sum_{i} \mathbf{x}_{i} = \frac{1}{10} (1 + 1 + 2 + 3 + 3 + 3 + 3 + 3 + 3 + 3) = 2.5$$
where $\mathbf{x}_{i} \sim p$



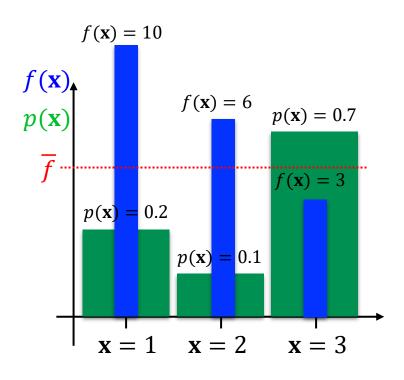


Mean

$$\overline{f} = \sum_{\mathbf{x}} p(\mathbf{x}) \cdot f(\mathbf{x}) = \mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})} [f(\mathbf{x})] = 0.2 \cdot 10 + 0.1 \cdot 6 + 0.7 \cdot 3 = 4.7$$

Average

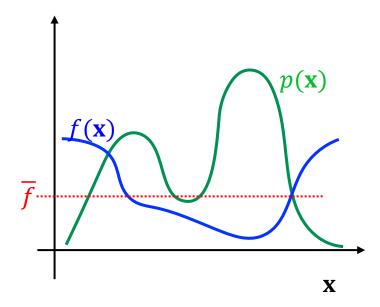
$$\approx \frac{1}{N} \sum_{i} f(\mathbf{x}_{i}) = \frac{1}{10} (10 + 10 + 6 + 3 + 3 + 3 + 3 + 3 + 3 + 3) = 4.7$$





For continuous case

$$\overline{f} = \int_{\mathbf{x}} p(\mathbf{x}) \cdot f(\mathbf{x}) d\mathbf{x} = \mathbb{E}_{\mathbf{x} \sim p(\mathbf{x})} [f(\mathbf{x})] \approx \frac{1}{N} \sum_{i} f(\mathbf{x}_{i})$$

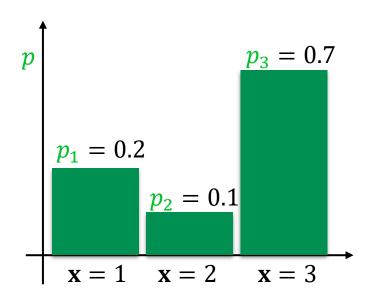


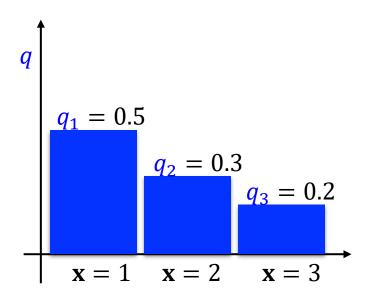
KL-divergence

 Kullback–Leibler (KL) divergence measures of how much the probability distribution p is similar to q

$$D_{KL}(p \parallel q) = \sum_{i} p_{i} \cdot \log \frac{p_{i}}{q_{i}}$$

 Informally, it measures the "expected surprise" when using q as approximation of p





$$D_{KL}(p \parallel q) = 0.2 \cdot \log \frac{0.2}{0.5} + 0.1 \cdot \log \frac{0.1}{0.3} + 0.7 \cdot \log \frac{0.7}{0.2} = 0.2535$$

KL-divergence

Kullback–Leibler (KL) divergence measures of how much the probability distribution p is similar to q

$$D_{KL}(p \parallel q) = \sum_{i} p_{i} \cdot \log \frac{p_{i}}{q_{i}}$$

- Informally, it measures the "expected surprise" when using q as approximation of p
 - What if $q_k = p_k$?
 - What if $q_k \to 0$ and $p_k > 0$? $D_{KL}(p \parallel q) \to \infty$
 - Is it symmetrical?

$$D_{KL}(p \parallel q) = 0$$

$$D_{KL}(p \parallel q) \rightarrow \infty$$

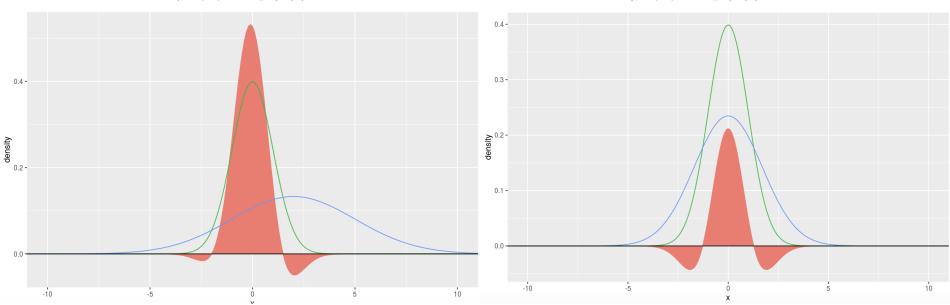
$$D_{KL}(p \parallel q) \neq D_{KL}(q \parallel p)$$

KL-Divergence

$$D_{KL}(p(\mathbf{x}) \parallel q(\mathbf{x})) = \int_{\mathbf{x}} p(\mathbf{x}) \cdot \log \frac{p(\mathbf{x})}{q(\mathbf{x})} d\mathbf{x}$$

$$D_{KL}(p(\mathbf{x}) \parallel q(\mathbf{x})) = 0.8764$$

$$D_{KL}(p(\mathbf{x}) \parallel q(\mathbf{x})) = 0.2036$$



https://gnarlyware.com/blog/kl-divergence-online-demo/

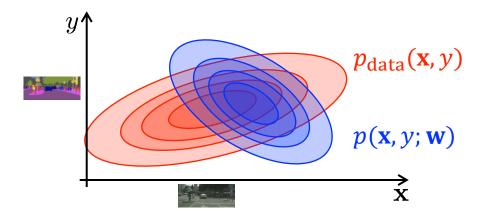


• Most tasks come in this form: given x, estimate y



- The (x, y) tuples are from an unknown distribution $p_{data}(x, y)$
- We try to approximate it by $p(\mathbf{x}, y; \mathbf{w})$
- We search for parameters (weights) w that makes $p(\mathbf{x}, y; \mathbf{w})$ close to $p_{\text{data}}(\mathbf{x}, y)$

$$\mathbf{w}^{\star} = \underset{\mathbf{w}}{\operatorname{argmin}} D_{KL}(p_{\operatorname{data}}(\mathbf{x}, \mathbf{y}) \parallel p(\mathbf{x}, \mathbf{y}; \mathbf{w}))$$



• We search for parameters (weights) w that makes $p(\mathbf{x}, y; \mathbf{w})$ close to $p_{\text{data}}(\mathbf{x}, y)$

$$\mathbf{w}^{*} = \underset{\mathbf{w}}{\operatorname{argmin}} D_{KL}(p_{\text{data}}(\mathbf{x}, y) \parallel p(\mathbf{x}, y; \mathbf{w})) = \underset{\mathbf{w}}{\operatorname{argmin}} \int_{(\mathbf{x}, y)} p_{\text{data}}(\mathbf{x}, y) \cdot \log \frac{p_{\text{data}}(\mathbf{x}, y)}{p(\mathbf{x}, y; \mathbf{w})}$$

$$= \underset{\mathbf{w}}{\operatorname{argmin}} \mathbb{E}_{(\mathbf{x}, y) \sim p_{\text{data}}(\mathbf{x}, y)} [\log \frac{p_{\text{data}}(\mathbf{x}, y)}{p(\mathbf{x}, y; \mathbf{w})}]$$

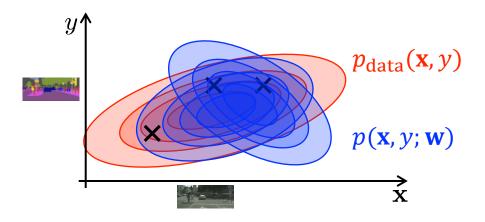
$$= \underset{\mathbf{w}}{\operatorname{argmin}} \mathbb{E}_{(\mathbf{x}, y)} [\log p_{\text{data}}(\mathbf{x}, y) - \log p(y \mid \mathbf{x}; \mathbf{w}) p(\mathbf{x})]$$

$$= \underset{\mathbf{w}}{\operatorname{argmin}} \mathbb{E}_{(\mathbf{x}, y)} [-\log p(y \mid \mathbf{x}; \mathbf{w})]$$

$$\approx \underset{\mathbf{w}}{\operatorname{argmin}} \frac{1}{N} \sum_{(\mathbf{x}_{i}, y_{i}) \sim p_{\text{data}}(\mathbf{x}, y)} [-\log p(y_{i} \mid \mathbf{x}_{i}; \mathbf{w})] \qquad \text{MLE: } \left(\underset{\mathbf{w}}{\operatorname{argmax}} \prod_{(\mathbf{x}_{i}, y_{i})} p(y_{i} \mid \mathbf{x}_{i}; \mathbf{w})\right)$$

• We search for parameters (weights) w that makes $p(\mathbf{x}, y; \mathbf{w})$ close to $p_{\text{data}}(\mathbf{x}, y)$

$$\mathbf{w}^* = \underset{\mathbf{w}}{\operatorname{arg}} \frac{1}{N} \sum_{(\mathbf{x}_i, y_i) \sim p_{\operatorname{data}}(\mathbf{x}, y)} [-\log p(y_i | \mathbf{x}_i; \mathbf{w})]$$

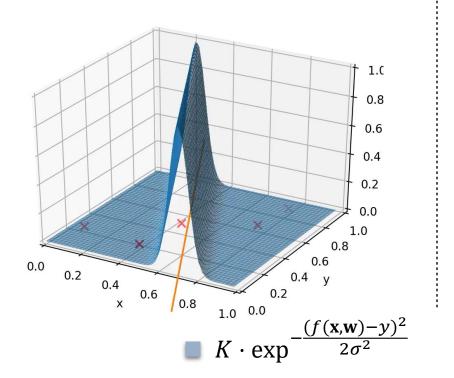




$$\mathbf{w}^{\star} = \operatorname{arg}_{\mathbf{w}}^{\min} \frac{1}{N} \sum_{(\mathbf{x}_{i}, y_{i}) \sim p_{\text{data}}(\mathbf{x}, y)} [-\log p(y_{i} | \mathbf{x}_{i}; \mathbf{w})]$$

Regression

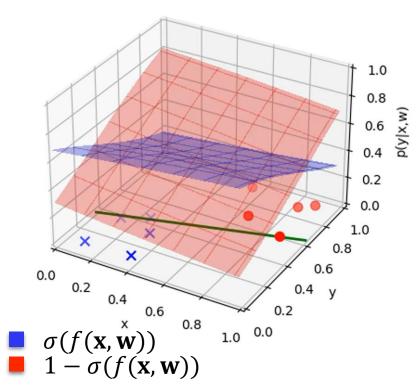
$$p(y|\mathbf{x}; \mathbf{w}) = \mathcal{N}(y; f(\mathbf{x}, \mathbf{w}), \sigma^2) = K \exp^{-\frac{(f(\mathbf{x}, \mathbf{w}) - y)^2}{2\sigma^2}}$$
$$\mathcal{L}(\mathbf{w}) = \frac{1}{N} \sum_{i} (f(\mathbf{x}_i, \mathbf{w}) - y_i)^2$$



Classification

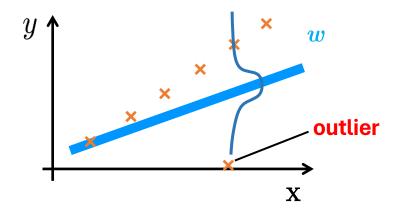
$$p(y|\mathbf{x}; \mathbf{w}) = \sigma(f(\mathbf{x}, \mathbf{w}))$$

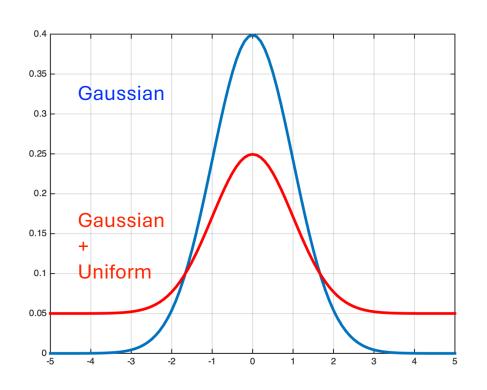
$$\mathcal{L}(\mathbf{w}) = \frac{1}{N} \sum_{i} \log(1 + \exp(-y_i f(\mathbf{x}_i, \mathbf{w})))$$

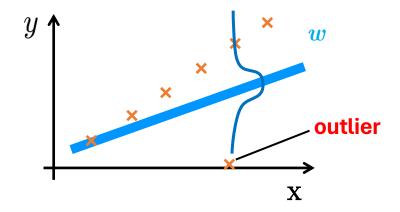




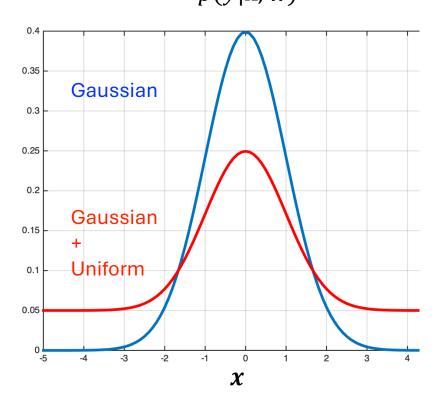
- Lecture 01: What can go wrong
- Why does the outlier skew our model?





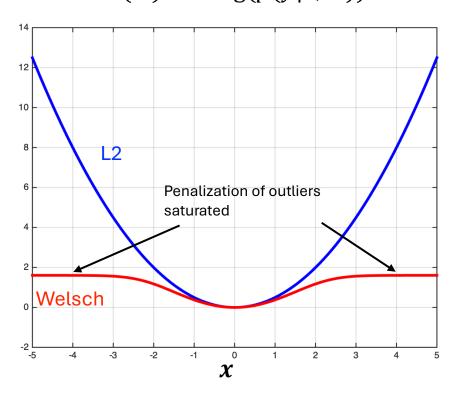


Probability distributions $p(y|\mathbf{x}, \mathbf{w})$



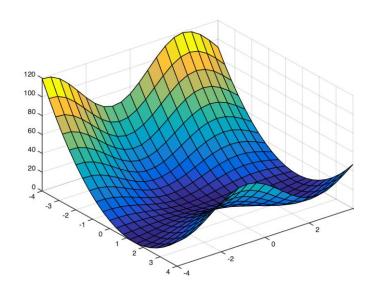
Corresponding losses

$$\mathcal{L}(\mathbf{w}) = -\log(p(y|\mathbf{x}, \mathbf{w}))$$



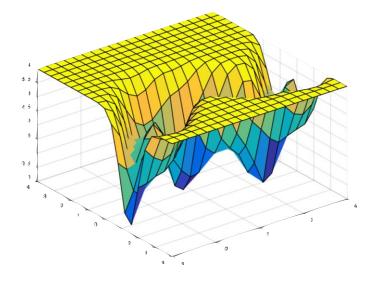


L2 landscape



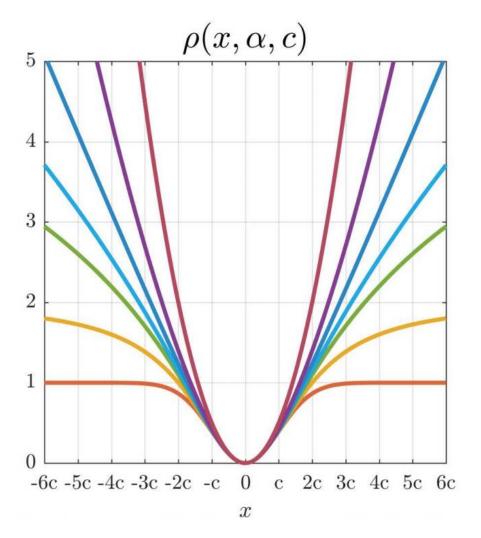
- Uniform noise not modeled
- GD-friendly landscape
- Gradient length encodes distance
- Easy to optimize

Welsch landscape



- Uniform noise modeled
- GD-unfriendly landscape
- Non-convex: Large narrow plateaus with zero gradient
- Good initialization required





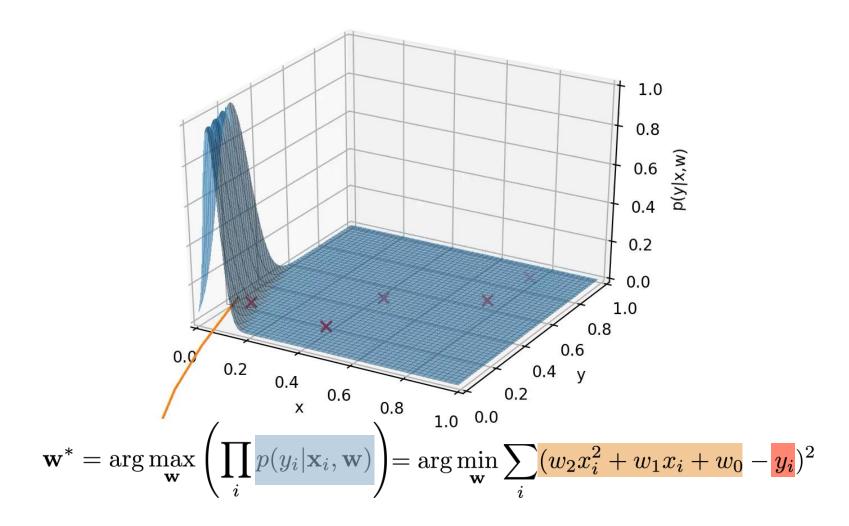
$$ho(x, lpha, c) = rac{|lpha - 2|}{lpha} \left(\left(rac{(x/c)^2}{|lpha - 2|} + 1
ight)^{lpha/2} - 1
ight)$$

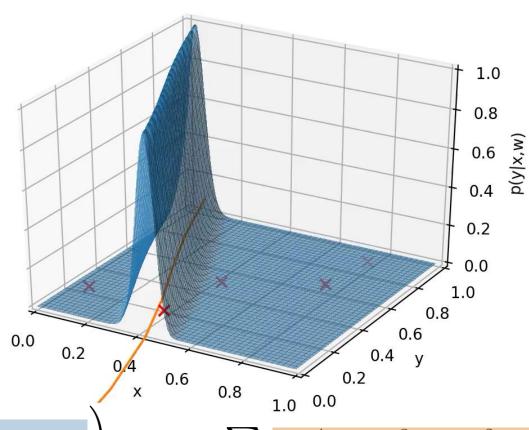
Barron, Jonathan T., "A general and adaptive robust loss function.", CVPR 2019.



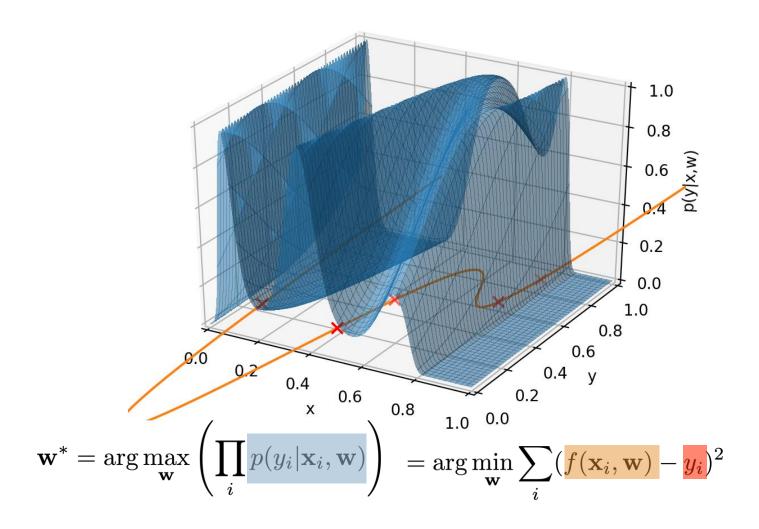
Summary

- Maximum Likelihood = Minimum KL-divergence = Minimum "-log(p)"loss
- Different losses suffer from different issues
- There are trade-offs between loss function expressivity and our ability to optimize them





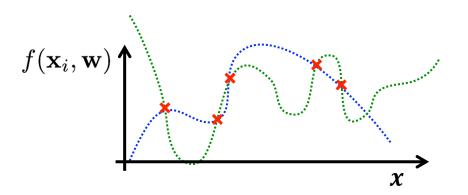
$$\mathbf{w}^* = \arg\max_{\mathbf{w}} \left(\prod_{i} \frac{p(y_i | \mathbf{x}_i, \mathbf{w})}{p(y_i | \mathbf{x}_i, \mathbf{w})} \right) = \arg\min_{\mathbf{w}} \sum_{i} (\frac{w_4 x_i^4 + w_3 x_i^3 + w_2 x_i^2 + w_1 x_i + w_0}{v_1 + w_2 x_i^2 + w_1 x_i + w_0} - \frac{y_i}{y_i})^2$$





Ockham's razor

- "Many stories consistent with a broken vase.
 Lepricons can be involved in any explanation"
- Use the simplest (the most apriori probable) explanation





William of Ockham (1287-1347)



https://en.wikipedia.org/wiki/Occam%27s_razor



- Phaistos Disc
 - 16cm disc
 - 45 distinct symbols (Unicode ©)
 - 242 characters in total
- People "deciphered" the disc as:
 - Religious text
 - Text commemorating military victory
 - Teaching tool
 - Board game
 - Calendar
 - Modern creation to attract archeology funding
- Many stories consistent with a sequence of visual symbols



01D0 🐧 PHAISTOS DISC SIGN PEDESTRIAN

101D1 🔻 PHAISTOS DISC SIGN PLUMED HEAD

101D2 PHAISTOS DISC SIGN TATTOOED HEAD

101D3 PHAISTOS DISC SIGN CAPTIVE

101D4 🏚 PHAISTOS DISC SIGN CHILD

101D5 🖁 PHAISTOS DISC SIGN WOMAN

101D6 \(\triangle \) PHAISTOS DISC SIGN HELMET

101D7 PHAISTOS DISC SIGN GAUNTLET

101D8 A PHAISTOS DISC SIGN TIARA

101D9 PHAISTOS DISC SIGN ARROW

101DA 🕴 PHAISTOS DISC SIGN BOW

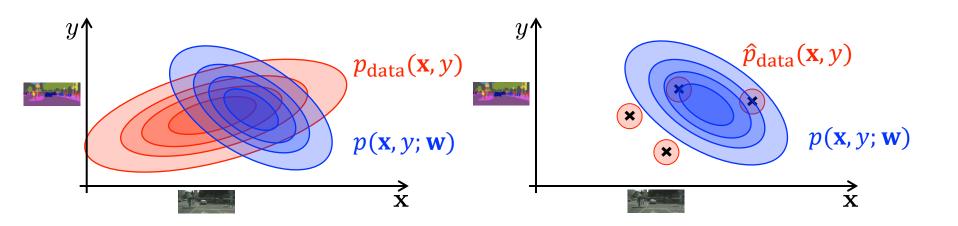
101DB @ PHAISTOS DISC SIGN SHIELD

• We search for parameters (weights) w that makes $p(\mathbf{x}, y; \mathbf{w})$ close to $p_{\text{data}}(\mathbf{x}, y)$

$$\mathbf{w}^* = \underset{\mathbf{w}}{\operatorname{argmin}} D_{KL}(p_{\operatorname{data}}(\mathbf{x}, \mathbf{y}) \parallel p(\mathbf{x}, \mathbf{y}; \mathbf{w}))$$

- Because $p_{\text{data}}(\mathbf{x}, \mathbf{y})$ is unknown, we use a set of samples (=training set)
- But since the training set is finite, it has a different distribution $\hat{p}_{\text{data}}(\mathbf{x}, \mathbf{y})$

$$\mathbf{w}^* = \underset{\mathbf{w}}{\operatorname{argmin}} D_{KL}(p_{\text{data}}(\mathbf{x}, y) \parallel p(\mathbf{x}, y; \mathbf{w})) \neq \underset{\mathbf{w}}{\operatorname{argmin}} D_{KL}(\hat{p}_{\text{data}}(\mathbf{x}, y) \parallel p(\mathbf{x}, y; \mathbf{w}))$$

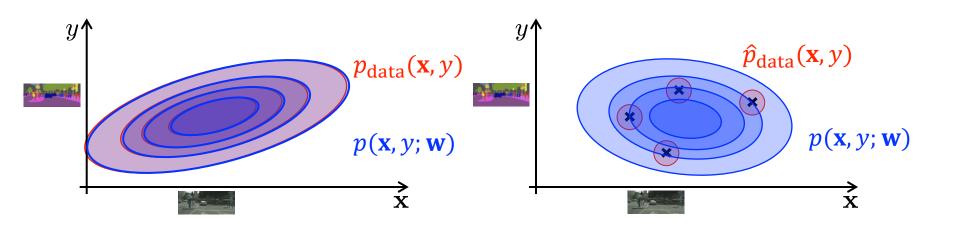


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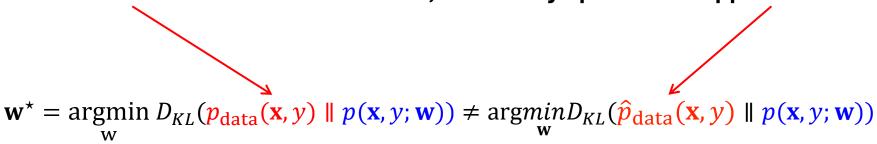
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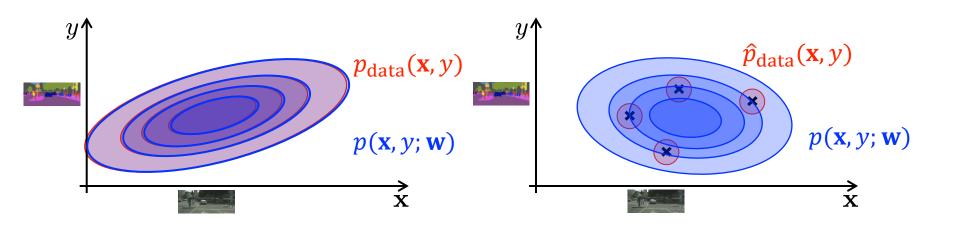
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In machine learning we try to optimize
 a criterion we don't have access to, so we only optimize its approximation







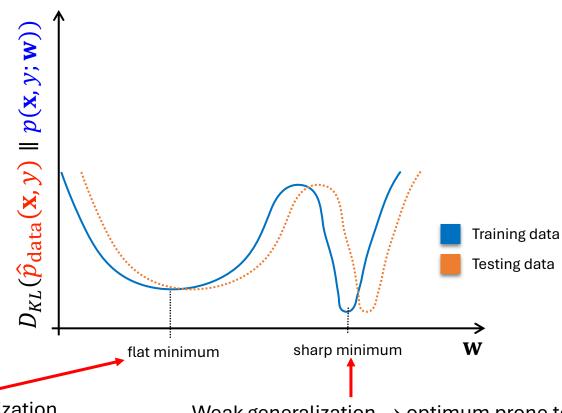
1) Always use the right tool

- Use the right $p(\mathbf{x}, y; \mathbf{w})$ that generates only "shapes" similar to $p_{\text{data}}(\mathbf{x}, y)$
- Embed prior knowledge (physics, geometry, biology...) about the problem into network architecture
- Examples:
 - Projective transformation of pinhole cameras (for camera calibration or stereo)
 - Geometry of Euclidean motion (for point cloud alignment, direct kinematic tasks)
 - Motion model for robots
 - Structure of animal cortex (CNNs)





Which minimum is better?

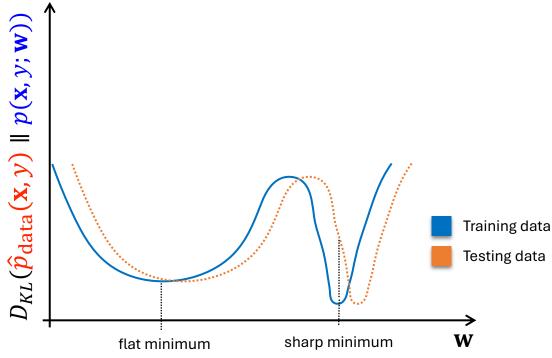


Good generalization
Testing error remains small

Weak generalization \rightarrow optimum prone to overfitting Error grows fast with a small training/testing data shift

- 2) Avoid sharp minima of $D_{KL}(\widehat{p}_{data}(\mathbf{x}, \mathbf{y}) \parallel p(\mathbf{x}, \mathbf{y}; \mathbf{w}))$
- Optimization techniques (e.g. SGD with momentum)
- Loss function (e.g. $\min\limits_{w} \max\limits_{\|\epsilon\|_2 \leq \rho} L_{train}(w+\epsilon)$)

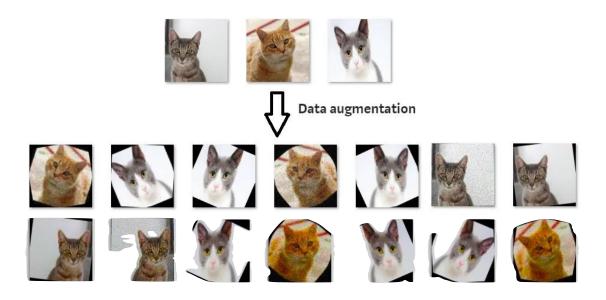
Foret, Pierre, et al. "Sharpness-aware Minimization for Efficiently Improving Generalization." ICLR 2021





3) Get more training data

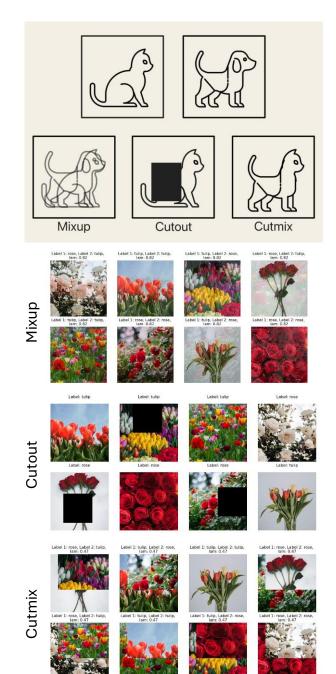
- Generate (almost infinite) dataset through data augmentation
- In every training pass, the networks actually "sees" different image





3) Get more training data

- Generate (almost infinite) dataset through data augmentation
- In every training pass, the networks actually "sees" different inputs
- Commonly used augmentations:
 - Horizontal (and vertical) flipping
 - Rotation
 - Random crop and resize
 - Color jittering (brightness, contrast, hue)
 - Gaussian noise / blur
 - Mixup, Cutout, Cutmix (for image classification)





- Summary
 - Optimization ≠ Machine learning, optimization can lead to overfitting
 - Always use the right tool, incorporate prior knowledge
 - Prefer simpler solutions, less is sometimes more
 - Use as much training data as possible, more is sometimes more ©



Competencies gained for the test

- Derive MLE estimate of a given distribution
- Understand connection between KL divergence, loss, optimization and machine
- Understand underfitting, overfitting and model architectures
- How to reduce overfitting