

Statistical Machine Learning (BE4M33SSU)

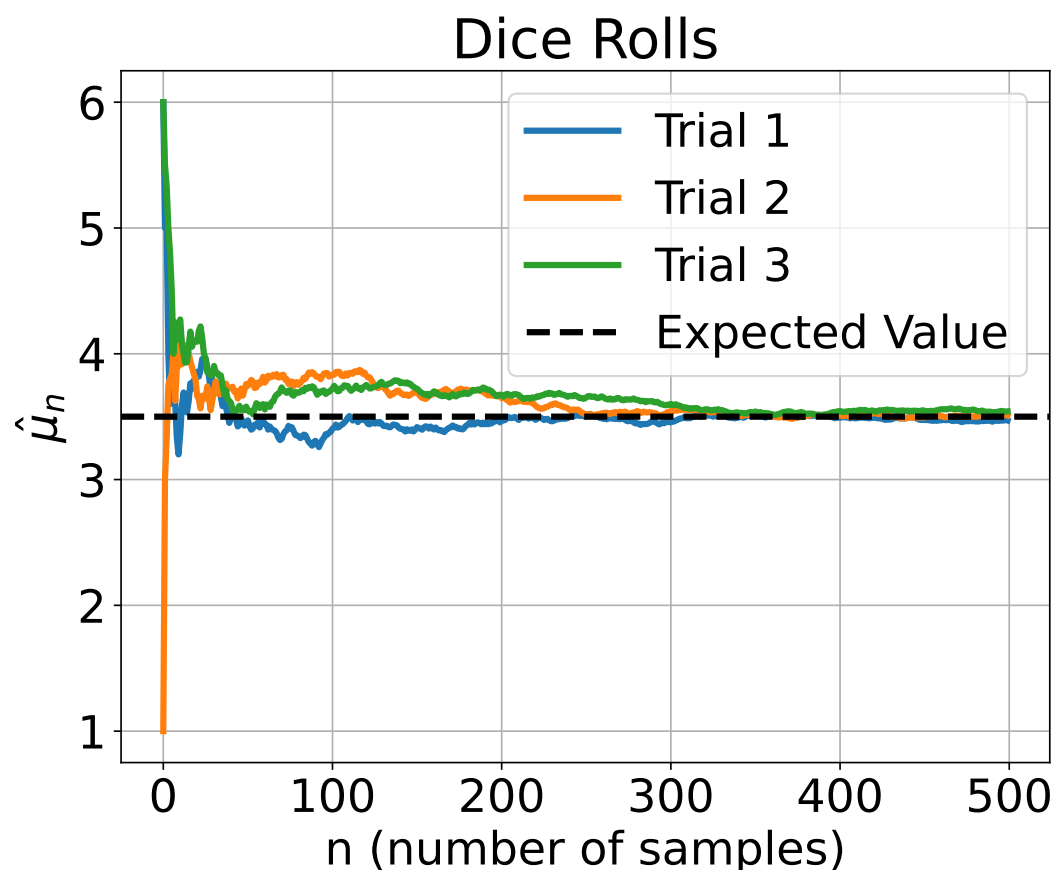
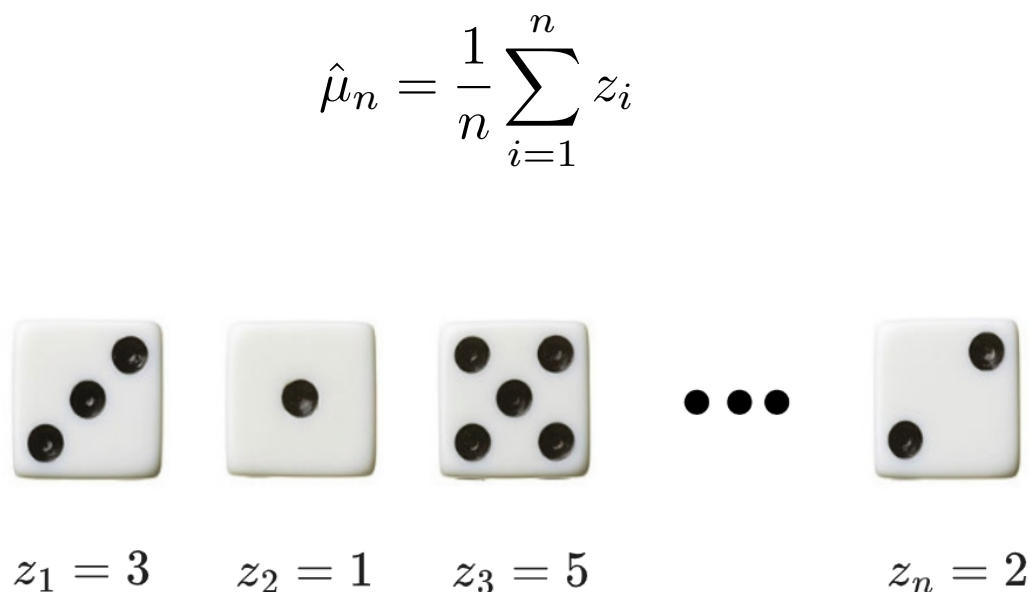
Lecture 2: Predictor Evaluation and Empirical Risk Minimization.

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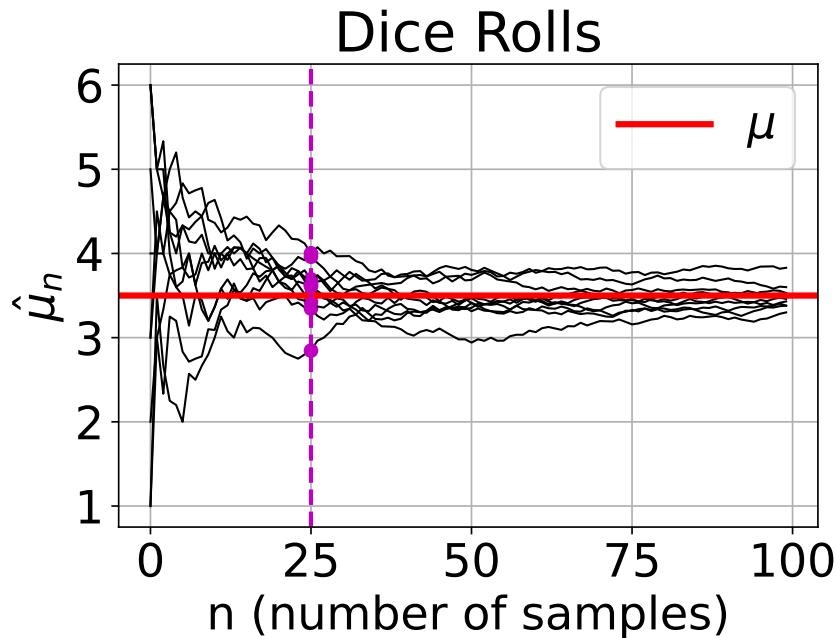
Law of Large Numbers

- ◆ The sample mean $\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n z_i$ of i.i.d. sample $Z_n = (z_1, z_2, \dots, z_n)$ generated from $q(z)$ gets closer to the expected value $\mu = \mathbb{E}_{z \sim q}[z]$ as the sample size n increases.
- ◆ Example: The expected value of a single roll of a fair die is

$$\mu = \mathbb{E}_{z \sim q}[z] = \sum_{z=1}^6 z q(z) = \frac{1 + 2 + 3 + 4 + 5 + 6}{6} = 3.5$$



Law of large numbers

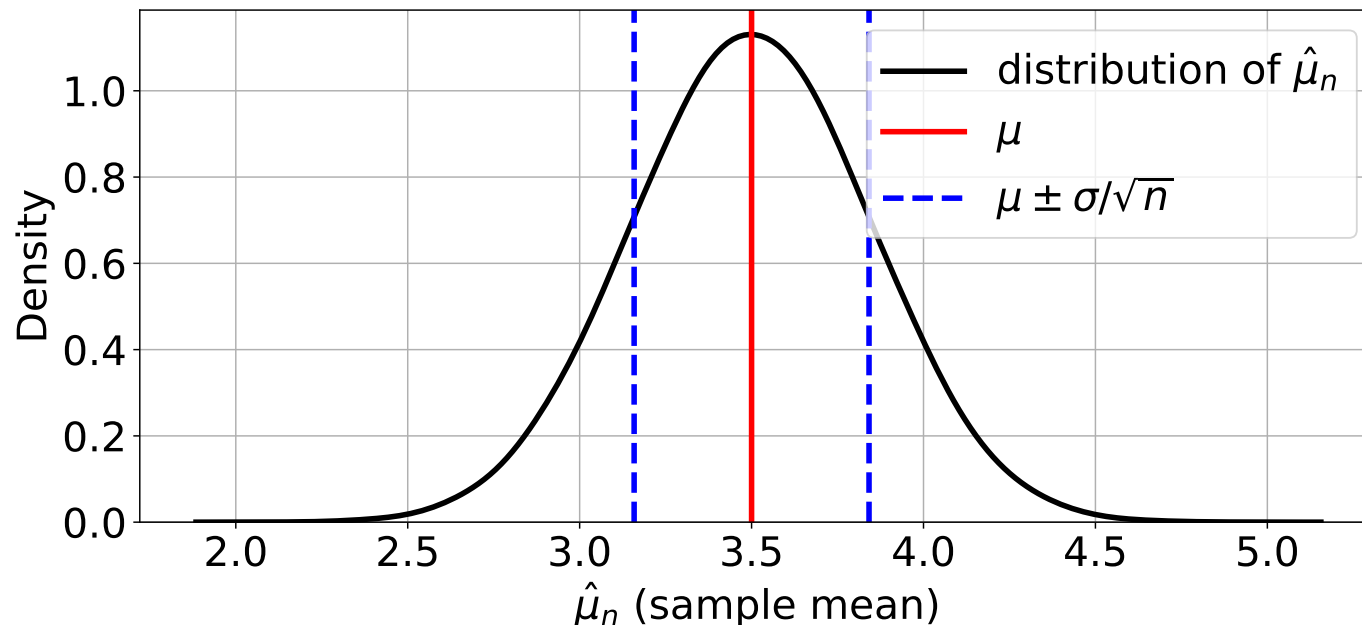


$$\mu = \mathbb{E}_{z \sim q}[z] = \frac{1+2+3+4+5+6}{6} = 3.5$$

$$\sigma^2 = \mathbb{V}_{z \sim q}[z] = \frac{(1-3.5)^2 + \dots + (6-3.5)^2}{6} \approx 2.917$$

The sample mean $\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n z_i$ is an unbiased estimator of the expected value μ :

$$\mathbb{E}_{(z_1, \dots, z_n) \sim q^n}[\hat{\mu}_n] = \mu$$

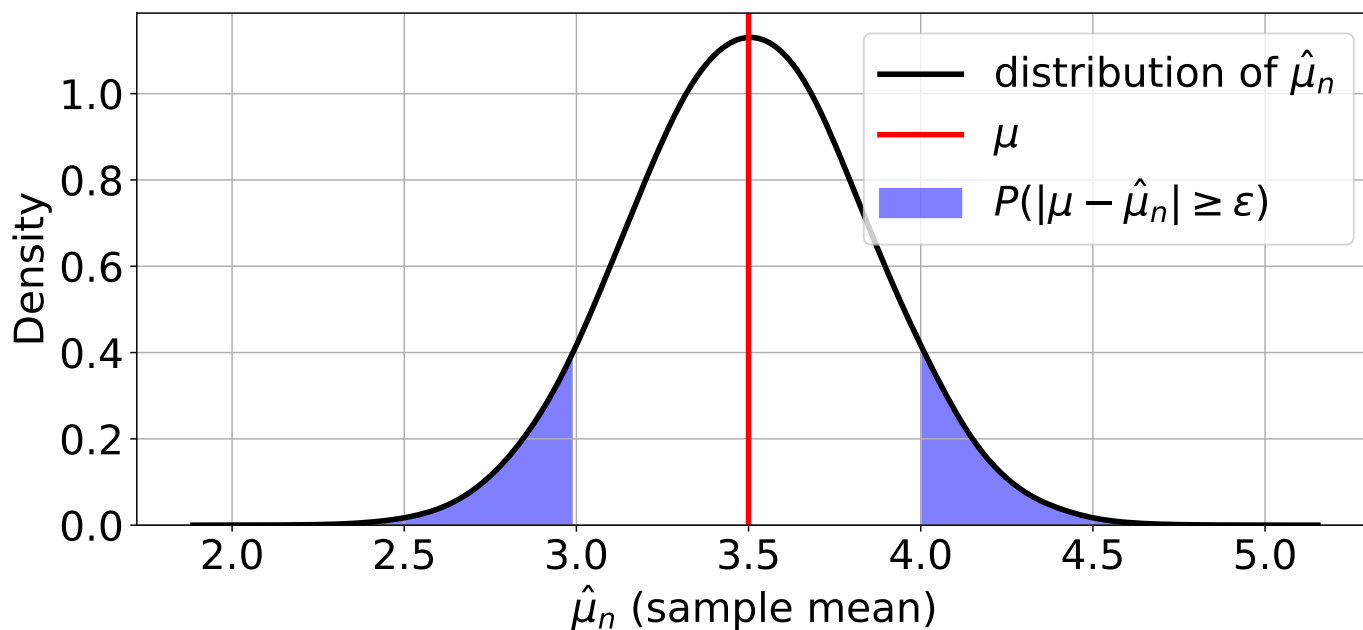
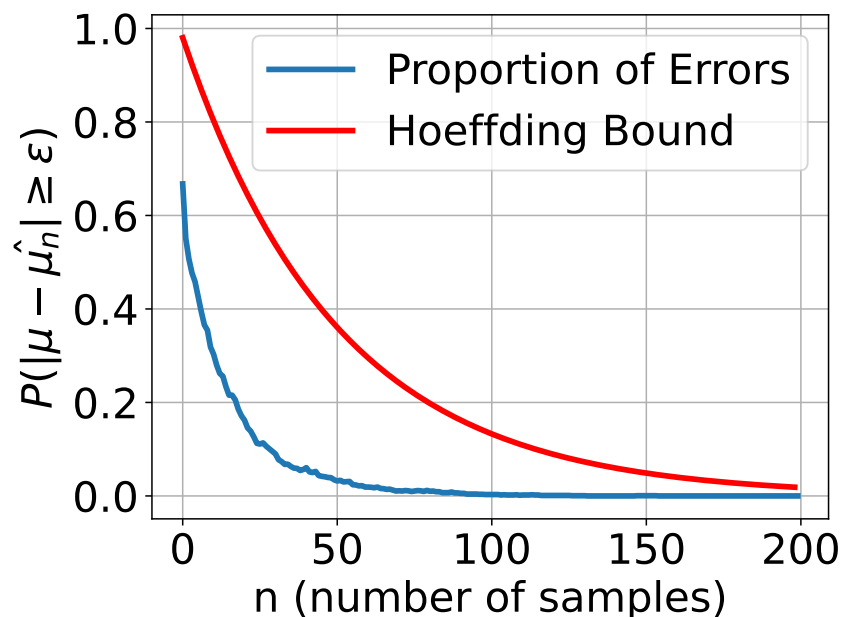
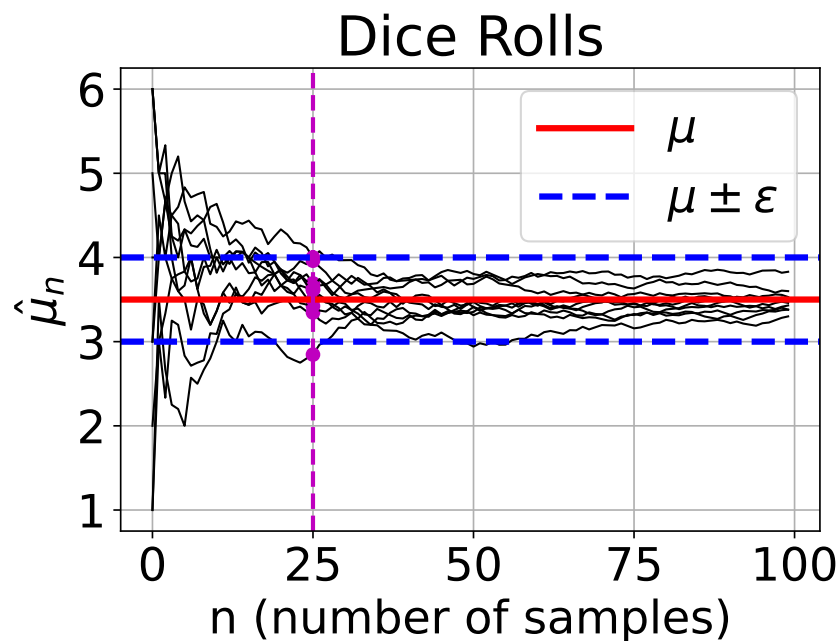


The variance of $\hat{\mu}_n$ decays with $\frac{1}{n}$:

$$\mathbb{V}_{(z_1, \dots, z_n) \sim q^n}[\hat{\mu}_n] = \frac{\sigma^2}{n}$$

$$n = 25 \rightarrow \frac{\sigma^2}{n} = 0.116$$

Hoeffding inequality



Hoeffding inequality:

$$\mathbb{P}(|\mu - \hat{\mu}_n| \geq \varepsilon) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}}$$

$$a = 1, b = 6, \varepsilon = 0.5$$

Hoeffding inequality

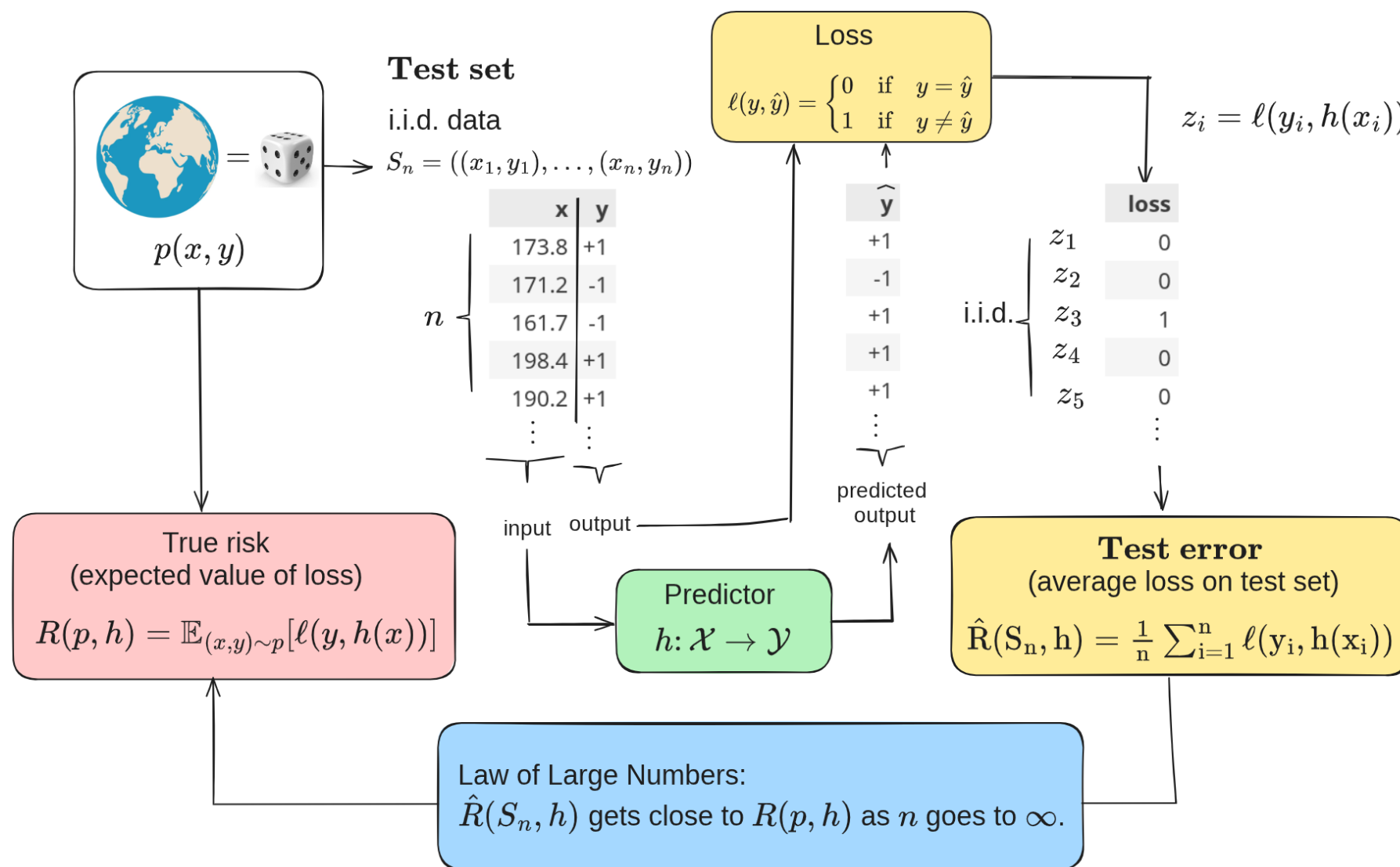
- ◆ **Theorem:** Let $Z_n = (z_1, \dots, z_n)$ be i.i.d. sample generated from r.v. with distribution $q(z)$. Let the random variables attain values from an interval $[a, b]$. Let the expected value of the r.v. be $\mu = \mathbb{E}_{z \sim q}[z]$. Let $\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n z_i$. Then, for any $\varepsilon > 0$:

$$\mathbb{P}_{Z_n \sim q^n} \left(|\hat{\mu}_n - \mu| \geq \varepsilon \right) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}}$$

◆ **Key Properties:**

- (+) **General:** the bound holds for any bounded i.i.d. random variables.
- (-) **Conservative:** the bound is typically not tight.
- (+) **Vanishing:** the bound $\rightarrow 0$ as $n \rightarrow \infty$.
- (+) **Cheap:** the bound is simple and easy to compute.

Predictor evaluation



Application of the Hoeffding inequality:

$$\mathbb{P}_{Z_n \sim q^n} \left(|\hat{\mu}_n - \mu| \geq \varepsilon \right) \leq 2e^{-\frac{2n\varepsilon^2}{(b-a)^2}} \Rightarrow \mathbb{P}_{S_n \sim p^n} \left(|\hat{R}(S_n, h) - R(p, h)| \geq \varepsilon \right) \leq 2e^{-\frac{2n\varepsilon^2}{(\ell_{\max} - \ell_{\min})^2}}$$

Confidence interval

- ◆ **Goal:** Characterize the deviation between the true risk $R(p, h) = \mathbb{E}_{(x,y) \sim p}[\ell(y, h(x))]$ and the test error $\hat{R}(S_n, h) = \frac{1}{n} \sum_{i=1}^n \ell(y^i, h(x^i))$ computed on i.i.d. data $S_n \sim p^n$.
- ◆ **Hoeffding inequality:** provides a probabilistic bound on the deviation between the true risk $R(p, h)$ and the test error $\hat{R}(S_n, h)$:

$$\mathbb{P}_{S_n \sim p^n} \left(|R(p, h) - \hat{R}(S_n, h)| \geq \varepsilon \right) \leq 2e^{-\frac{2n\varepsilon^2}{(\ell_{\max} - \ell_{\min})^2}} \quad \forall \varepsilon > 0$$

- ◆ **(1- δ)-Confidence interval:** (derived from the Hoeffding inequality)

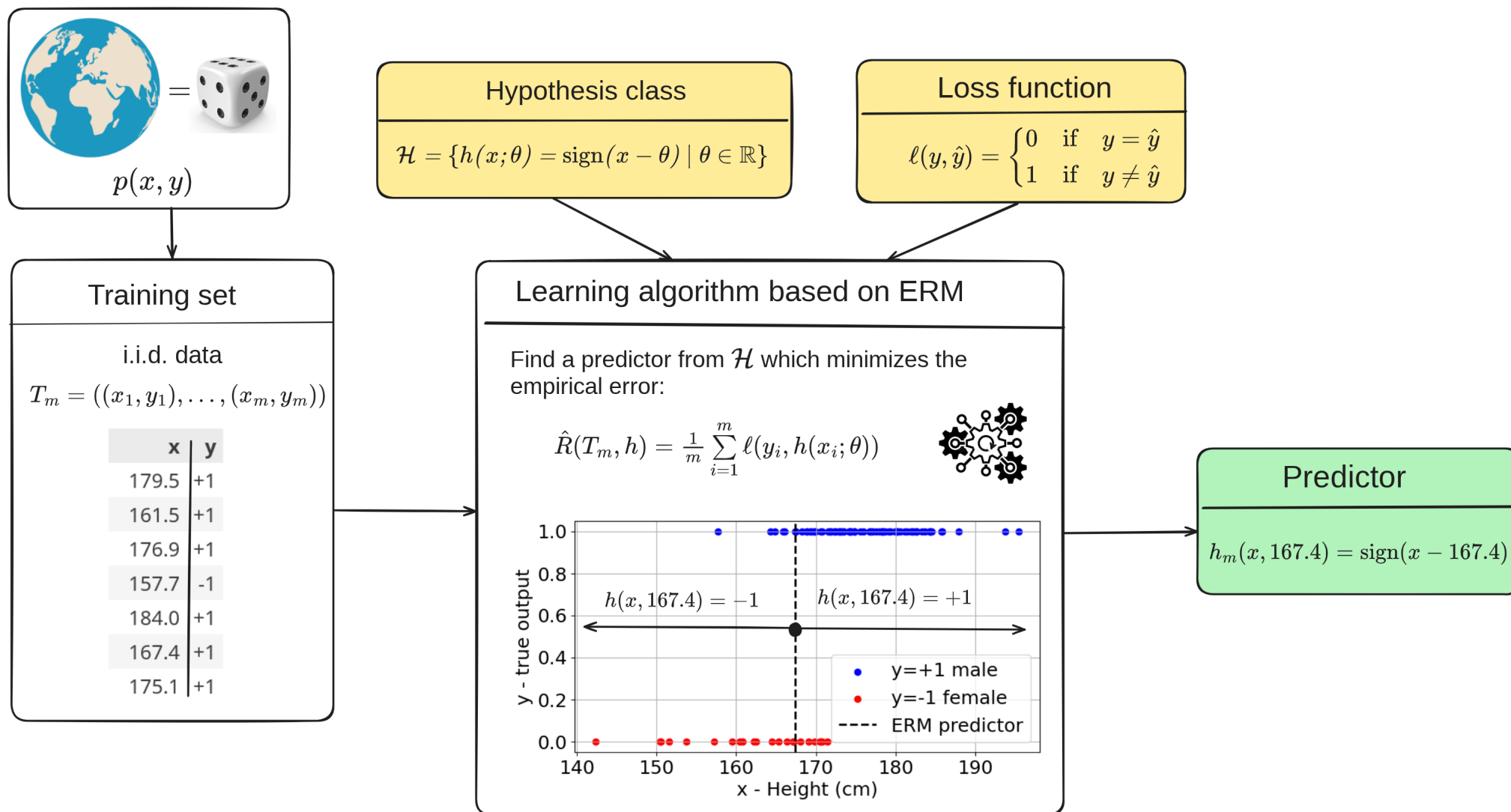
$R(p, h) \in (\hat{R}(S_n, h) - \varepsilon, \hat{R}(S_n, h) + \varepsilon)$ holds with probability $1 - \delta$ at least,

where $1 - \delta$ is called the confidence level.

- For fixed n and $\delta \in [0, 1]$, compute $\varepsilon = (\ell_{\max} - \ell_{\min}) \sqrt{\frac{\log(2) - \log(\delta)}{2n}}$
- For fixed ε and $\delta \in [0, 1]$, compute $n = \frac{\log(2) - \log(\delta)}{2\varepsilon^2} (\ell_{\max} - \ell_{\min})^2$

Empirical Risk Minimization

ERM: a principle to construct algorithms learning predictors from data.



Instances: Linear regression, Logistic Regression, Neural Networks learn by back-propagation, Gradient Boosted Trees, ...

Empirical Risk Minimization

- ◆ **Goal:** Given a training set $T_m = ((x_1, y_1), \dots, (x_m, y_m)) \sim p^m$, learn a predictor $h: \mathcal{X} \rightarrow \mathcal{Y}$ minimizing the expected risk $R(p, h) = \mathbb{E}_{(x,y) \sim p}[\ell(y, h(x))]$.

- ◆ **Hypothesis class (space):** is fixed before learning based on prior knowledge

$$\mathcal{H} \subseteq \mathcal{Y}^{\mathcal{X}} = \{h: \mathcal{X} \rightarrow \mathcal{Y}\}$$

- ◆ **Learning algorithm:** is a function

$$A: \cup_{m=1}^{\infty} (\mathcal{X} \times \mathcal{Y})^m \rightarrow \mathcal{H}$$

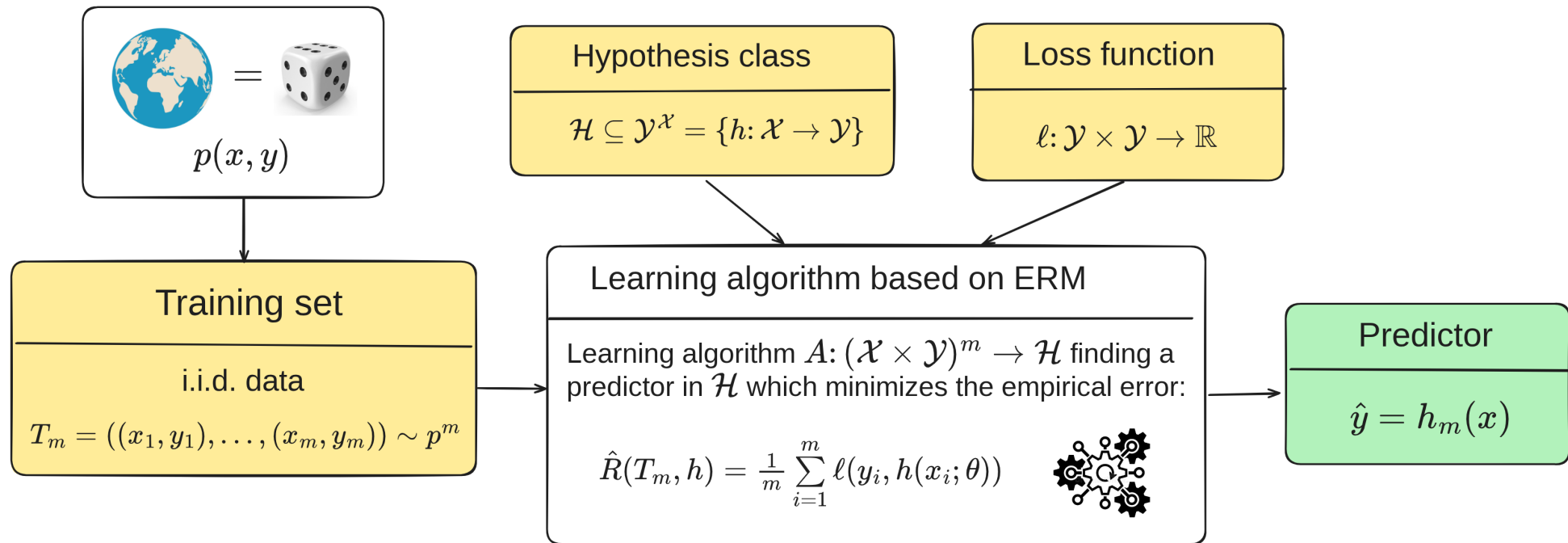
- ◆ **Empirical risk** evaluated on T_m (a.k.a training error):

$$\hat{R}(T_m, h) = \frac{1}{m} \sum_{i=1}^m \ell(y_i, h(x_i))$$

- ◆ **ERM based learning algorithm:**

$$h_m = A(T_m) = \underset{h \in \mathcal{H}}{\text{Argmin}} \hat{R}(T_m, h)$$

When does ERM work?



Plan for the next lectures:

PAC learning Successful PAC learner = with a high probability it finds close approximation of the best predictor in $\mathcal{H}$.	"Too complex" hypothesis space $h: \mathcal{X} \rightarrow \mathcal{Y}$ ERM is not PAC learner	Finite hypothesis space $\mathcal{H} = \{h_1, h_2, \dots, h_{\mathcal{H}}\}$ ERM is PAC learner	VC dimension $\text{VCdim}: \{-1, +1\}^{\mathcal{X}} \rightarrow \mathbb{N}$ $\text{VCdim}(\mathcal{H}) < \infty$ $\iff$ ERM is PAC learner
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ERM can fail when the hypothesis class is too complex

- ◆ Setup: $\mathcal{X} = [a, b] \subset \mathbb{R}$, $\mathcal{Y} = \{+1, -1\}$, $\ell(y, y') = \mathbb{I}[y \neq y']$, $p(x \mid y = +1)$ and $p(x \mid y = -1)$ uniform on $\mathcal{X}$, with $p(y = +1) = 0.8$.
- ◆ Optimal predictor: $h^*(x) = +1$ with true risk $R(p, h^*) = 0.2$.
- ◆ “Memorizer” learning rule: for training set $T_m = ((x_1, y_1), \dots, (x_m, y_m))$, define

$$h_m(x) = \begin{cases} y_j & \text{if } x = x_j \text{ for some } j \in \{1, \dots, m\}, \\ -1 & \text{otherwise.} \end{cases}$$

- Implements ERM: $\mathbb{P}(\hat{R}(T_m, h_m) = 0) = 1$.
- Performs poorly: $\mathbb{P}(R(p, h_m) = 0.8) = 1$ for any finite m .
- ◆ **Overfitting:** occurs when $h_m = A(T_m)$ achieves low empirical risk $\hat{R}(T_m, h_m)$ while the true risk $R(p, h_m)$ is high.

Summary of Key Concepts

◆ Law of Large Numbers

- The sample mean converges to the expected value as the number of samples increases.
- Hoeffding's inequality: bounds the probability of deviation between the sample mean and the expected value.

◆ Predictor Evaluation

- For a fixed $h: \mathcal{X} \rightarrow \mathcal{Y}$, the losses $\ell(y_i, h(x_i))$ on an i.i.d. sample S_n are themselves i.i.d. random variables.
- Confidence intervals provide bounds on the estimation error.

◆ Empirical Risk Minimization (ERM)

- ERM selects a predictor that minimizes empirical error on the training set.
- ERM may fail if the hypothesis class $\mathcal{H}$ is too complex.