

DCGI

KATEDRA POČÍTAČOVÉ GRAFIKY A INTERAKCE

Začneme brzy,
We will start soon,
at 16:15 today ...

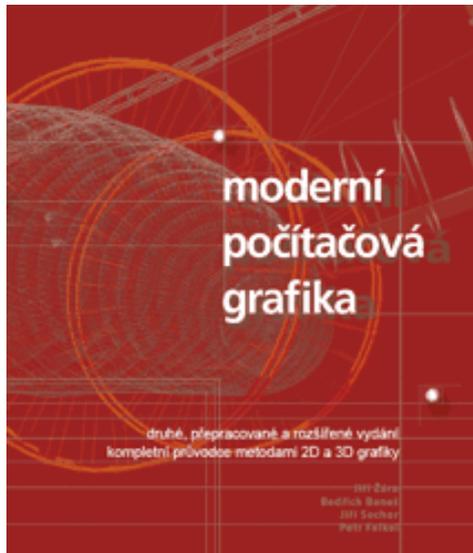
APG

Raster Graphics - Line

JIŘÍ ŽÁRA

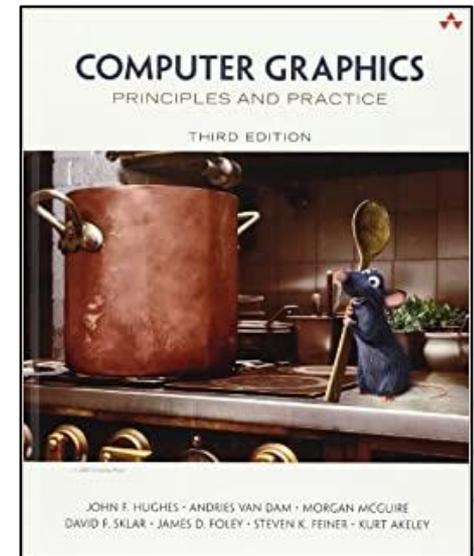
About this course

J. Žára a kol.:
Moderní počítačová grafika



← česky

J. Hughes et al.:
Computer Graphics: Principles and Practice



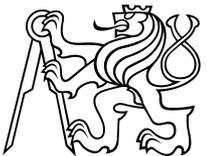
English →

- About 90% of knowledge given in Lectures
- About 10% of knowledge from literature (above)



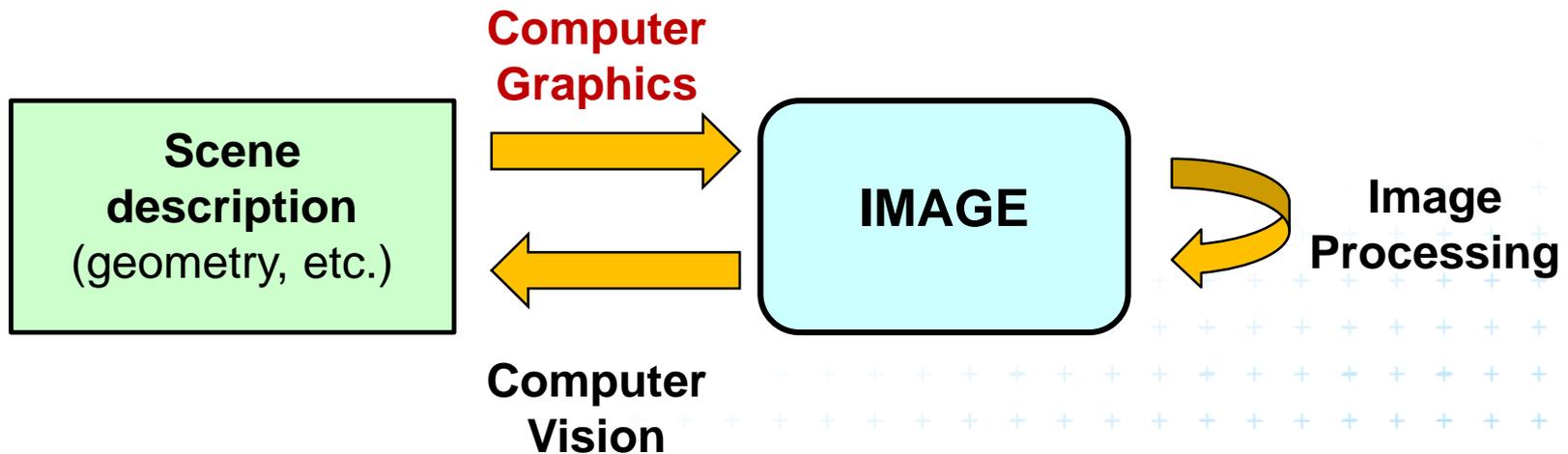
Contents

- About Computer Graphics
- Raster graphics
- **Line drawing**
 - DDA algorithm
 - Bresenham algorithm
- Dashed line
- Thick line
- Antialiasing

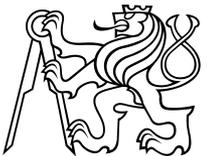


Computer Graphics

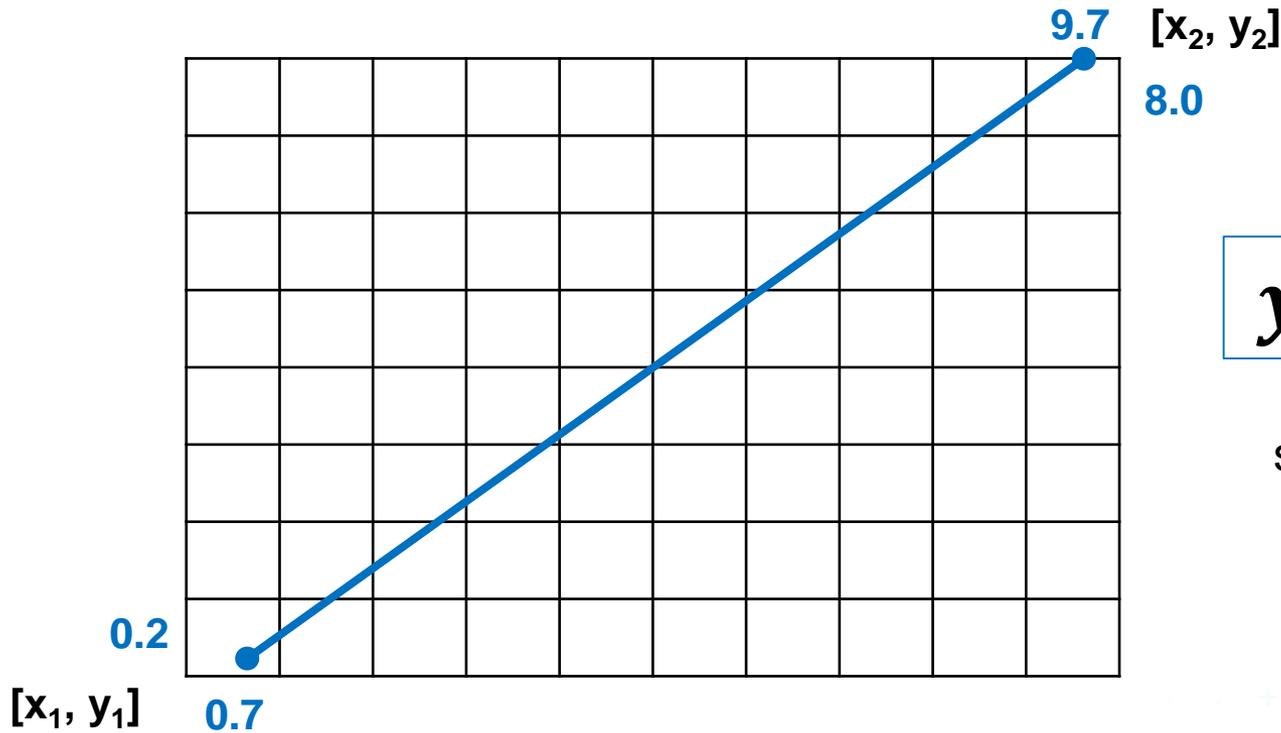
- Vector VERSUS Raster
- Conversion from abstract description into digital form (pixels) = **digitization** (2D), **rendering** (3D)



*Computer Graphics
Image Processing
Computer Vision*



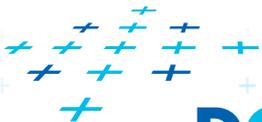
Raster



$$y = k \cdot x + b$$

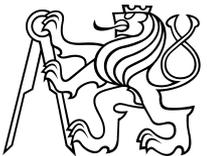
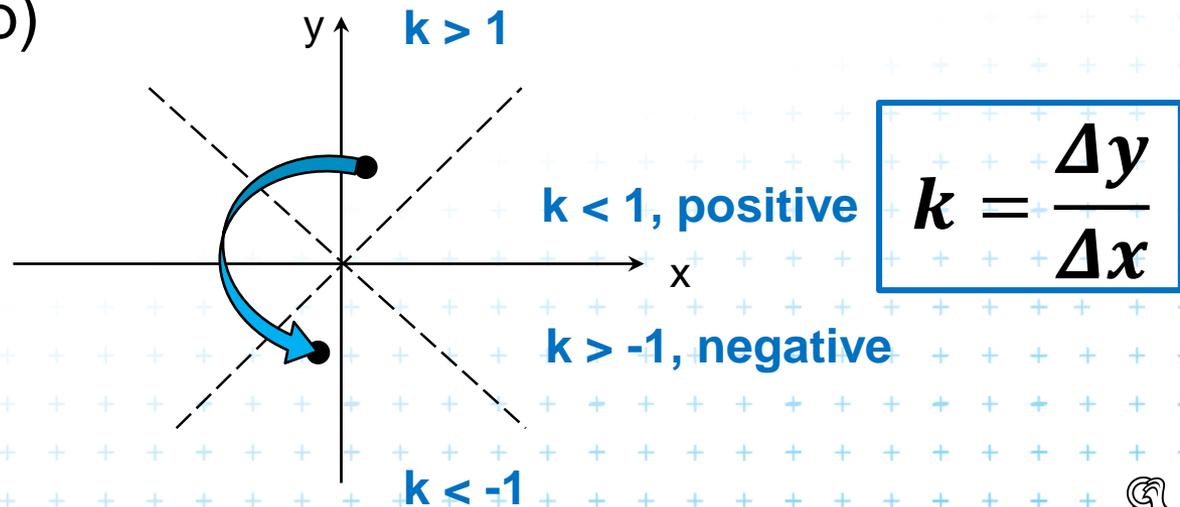
slope \uparrow
shift, intercept \uparrow

$$k = \frac{\Delta y}{\Delta x} = (y_2 - y_1) / (x_2 - x_1)$$

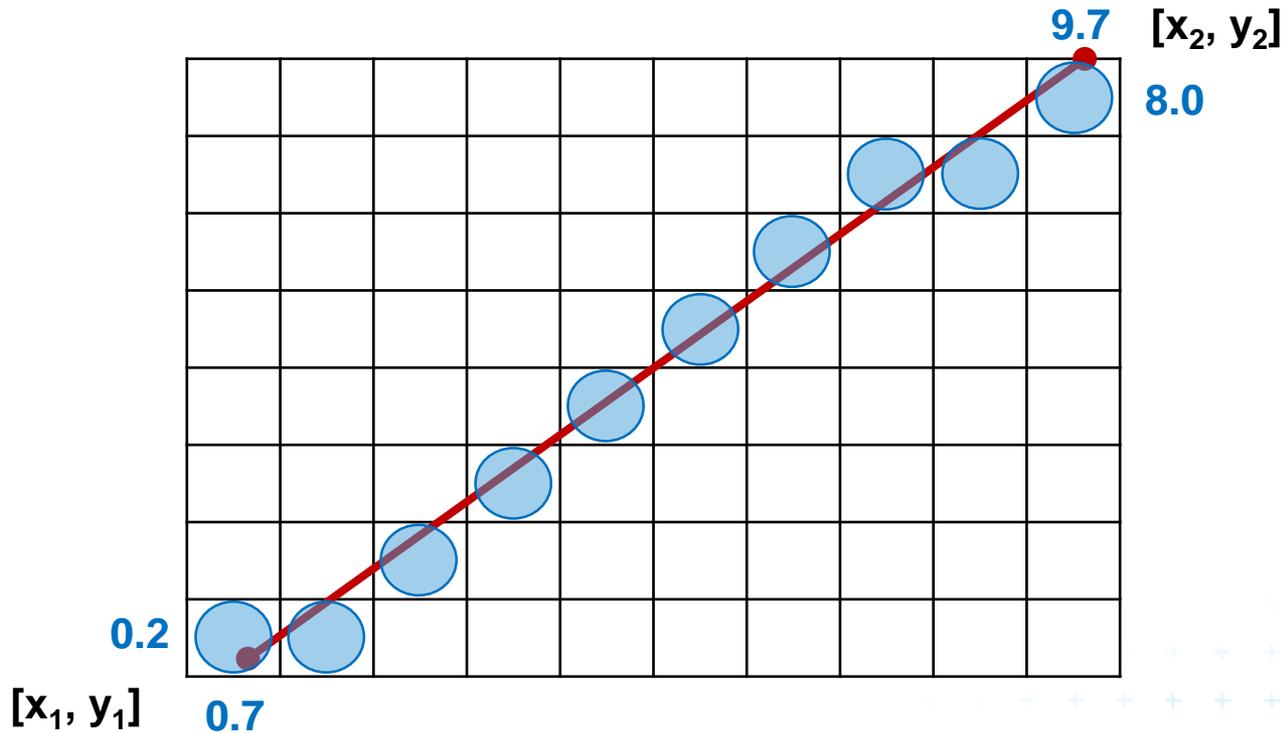


Line

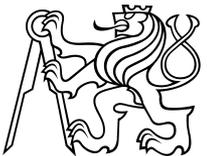
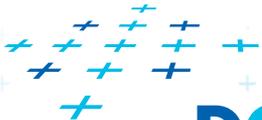
- Mathematics – infinitely thin line
- Computer Graphics
 - Sequence of neighboring pixels (*pixel, px, picture element*)
 - Digitization = sampling of a continuous function
- **Slope** defines a **driving/major axis** for sampling (by 1 pixel step)



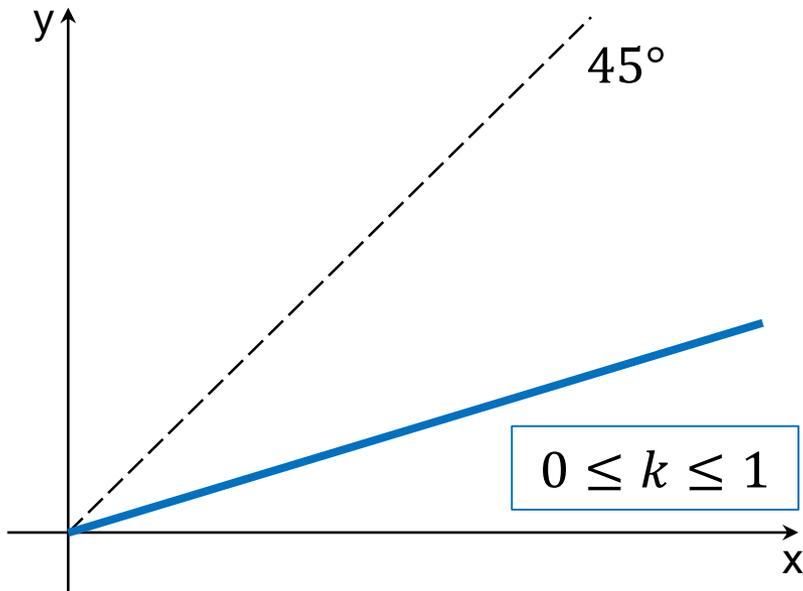
Line drawing methods



- DDA (Digital Differential Analyzer) [float]
- Bresenham algorithm [int]



DDA (Digital Differential Analyzer)



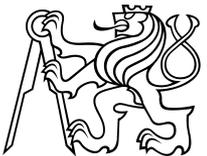
$$\text{step}X = 1$$

$$\text{step}Y = \frac{\Delta y}{\Delta x} = k$$

$$X_{i+1} = X_i + 1$$

$$Y_{i+1} = Y_i + k$$

Note: k is a real (float) number



DDA algorithm

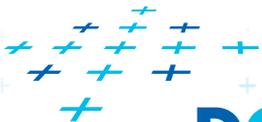
```
DDA (int x1, int y1, int x2, int y2) {  
    double k, Y;  
    k = (y2 - y1) / (x2 - x1);  
    setPixel (x1, y1);  
    Y = y1;  
    for (int i = x1+1; i<=x2; i++) {  
        Y += k;  
        setPixel (i, round(Y));  
    }  
}
```

$$k \in \langle 0, 1 \rangle$$

$$x1 < x2$$

Endpoints preprocessing:

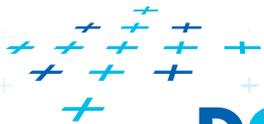
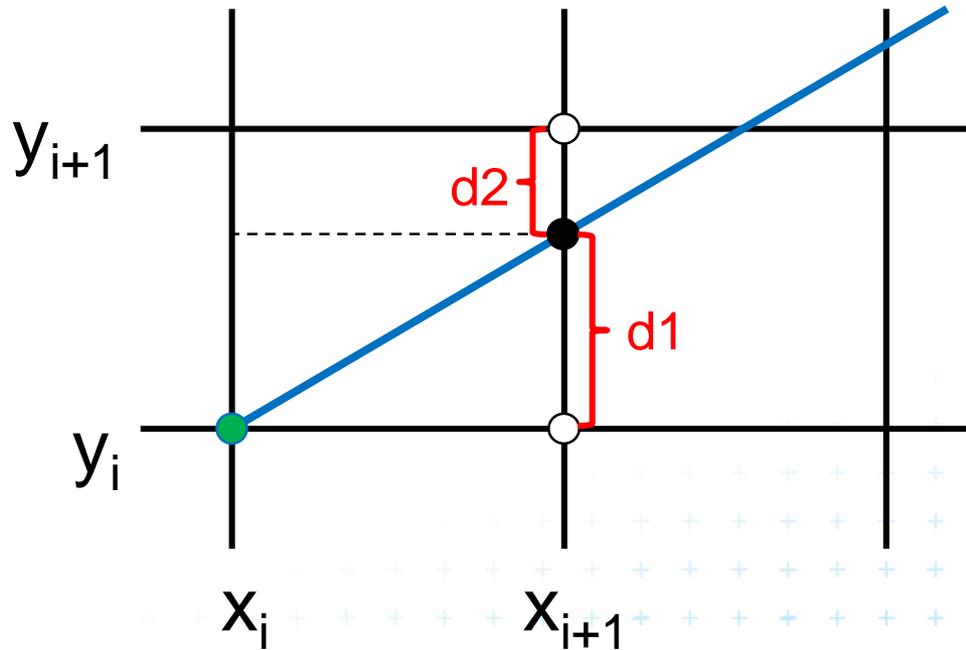
- Coordinate rounding (to int)
- Driving axis determination
- Orientation (from left/bottom)



Jack Elton Bresenham, *1937

Integer only algorithm

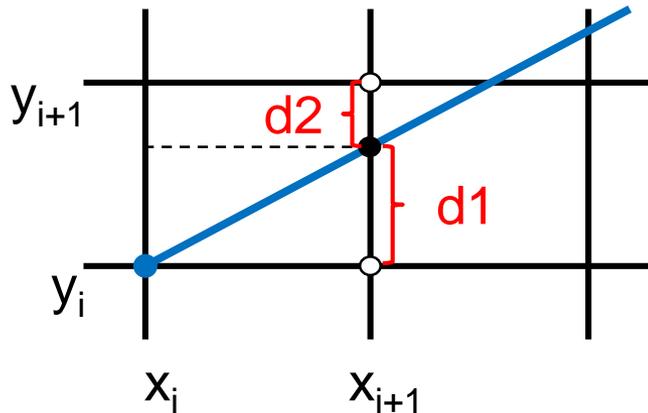
- IBM, developed in 1962, published in 1965



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Bresenham algorithm (1/2)



$$y_{\text{real}} = k(x_i + 1) + b$$

$$d_1 = y_{\text{real}} - y_i$$

$$d_2 = y_i + 1 - y_{\text{real}}$$

$$d = d_1 - d_2 = 2k \cdot (x_i + 1) - 2y_i + 2b - 1$$

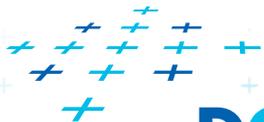
$$p_i = \Delta x \cdot (d_1 - d_2)$$

$$= 2\Delta y \cdot x_i - 2\Delta x \cdot y_i + \underbrace{2\Delta y + \Delta x \cdot (2b - 1)}_{\text{Const.}}$$

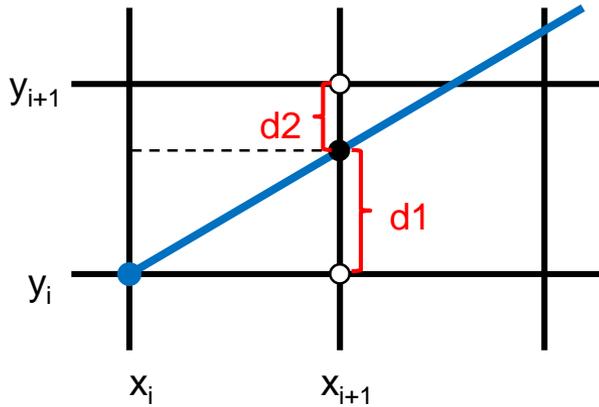
$$k = \frac{\Delta y}{\Delta x}$$

$$p_{i+1} = p_i + 2\Delta y - 2\Delta x (y_{i+1} - y_i)$$

prediction



Bresenham algorithm (2/2)



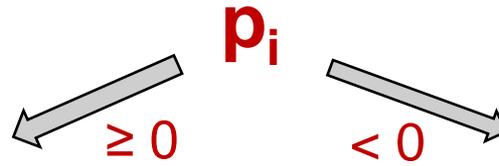
$$[x_i, y_i, p_i] \rightarrow [x_{i+1}, y_{i+1}, p_{i+1}]$$

$$x_{i+1} = x_i + 1$$

$$p_{i+1} = p_i + 2\Delta y - 2\Delta x (y_{i+1} - y_i)$$

$$y_{i+1} = y_i + 1$$

$$p_{i+1} = p_i + 2\Delta y - 2\Delta x$$



$$y_{i+1} = y_i$$

$$p_{i+1} = p_i + 2\Delta y$$

Note: $p_0 = 2\Delta y - \Delta x$
 from $p_i = \dots$, where $x_0 = y_0 = b = 0$



Bresenham algorithm – code

```
Bresenham (int x1, int y1, int x2, int y2) {
```

```
    int c0, c1, p;
```

```
    init (c0, c1, p);
```

```
    setPixel (x1, y1);
```

```
    for (int i = x1 + 1; i <= x2; i++) {
```

```
        if (p < 0) {
```

```
            p += c0;
```

```
        } else {
```

```
            p += c1;
```

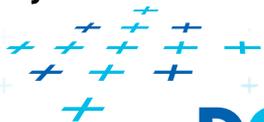
```
            y1++;
```

```
        }
```

```
        setPixel (i, y1);
```

```
    }
```

```
}
```



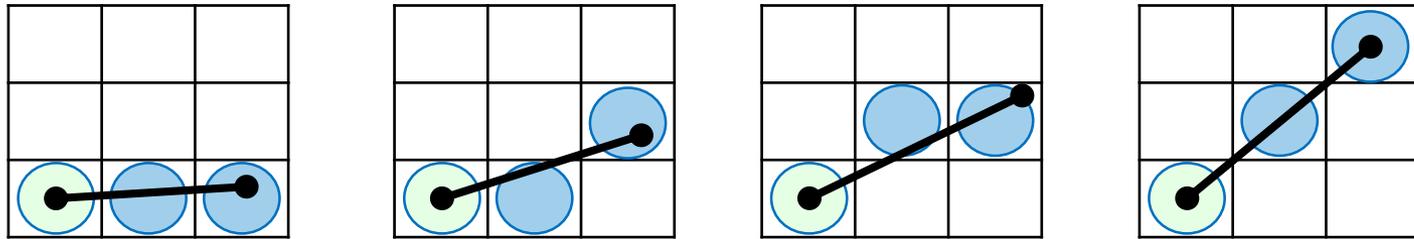
```
init (int c0, int c1, int p) {  
    c0 = 2 * (y2 - y1);  
    c1 = c0 - 2 * (x2 - x1);  
    p = c0 - (x2 - x1);  
}
```

$k \in \langle 0, 1 \rangle$
 $x1 < x2$

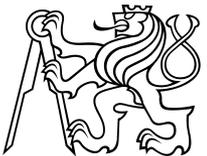
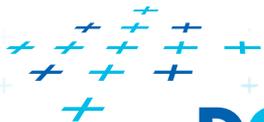
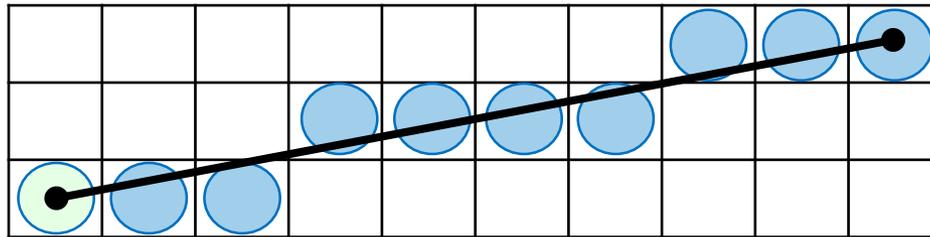


Multi-step methods – interesting research

- Pairs/triplets of pixel



- Computing distance to minor axis change



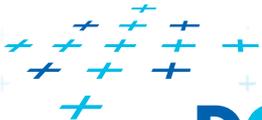
Dashed line



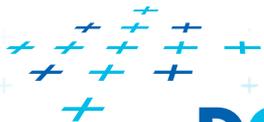
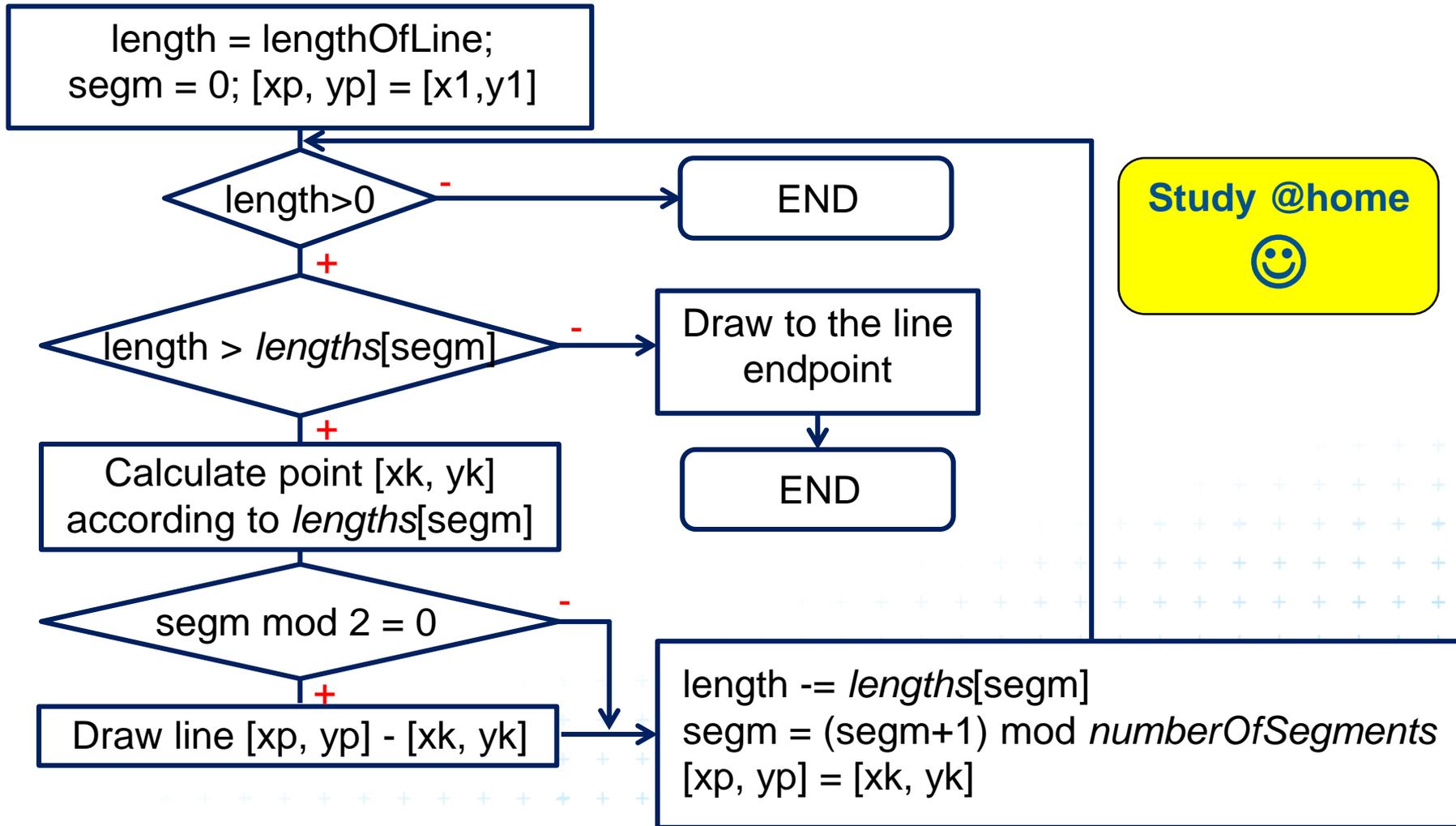
- Line appearance defined in a length segment array
- Odd segment drawn, even skipped

```
class DashedLine {  
    int numberOfSegments;    // e.g. 6  
    int [ ] lengths;  
}
```

- Two possible approaches:
 1. By individual segments
 2. The whole line at once (modified Bresenham alg.)

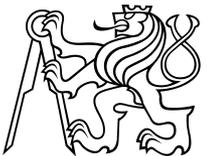


1. Drawing by segments



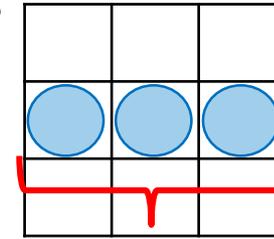
2. Drawing the whole line at once

- Bresenham algorithm modification
- Blocking setPixel() according to odd/even segment:
 - a) `int segm; int segmLength;`
 - b) `segm mod 2` \longrightarrow enable/disable setPixel()
 - c) decrement segmLength, when 0 \longrightarrow prepare for next segment

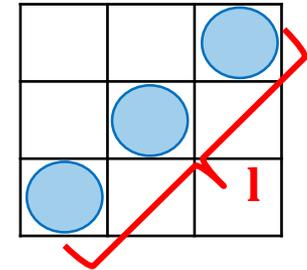


Problems with raster metric

- length VERSUS Nr. of pixels
- Oblique lines appear thinner

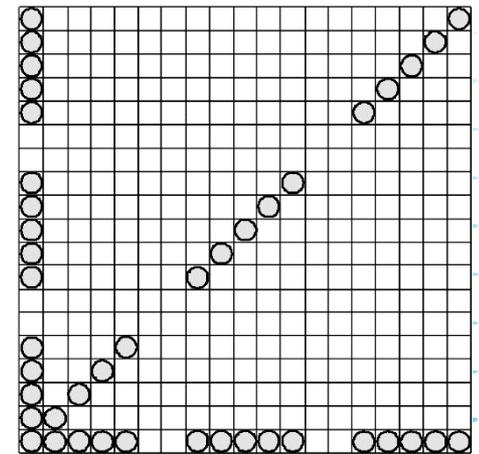


3 pixels
 $l = 3$



3 pixels
 $l = 3 \cdot \sqrt{2}$

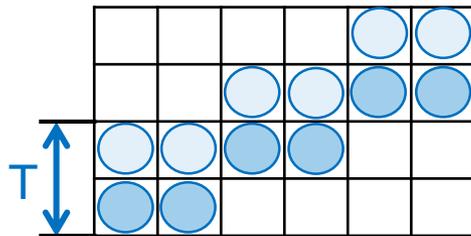
- Modified Bresenham = bad approach
- By segments = good technique



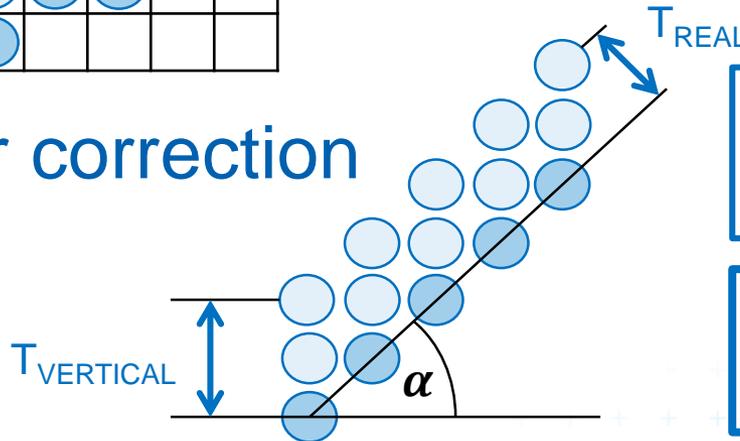
Thick line

a) Trivial solution – Bresenham modified

setPixel \longrightarrow $T \times$ setPixel (in a proper direction)



b) Angular correction

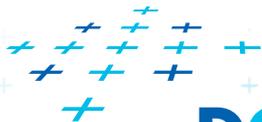


$$\begin{aligned} T &= T_{REAL} \\ &= T_{VERTICAL} \cdot \cos \alpha \end{aligned}$$

$$T_{VERTICAL} = \frac{T}{\cos \alpha}$$

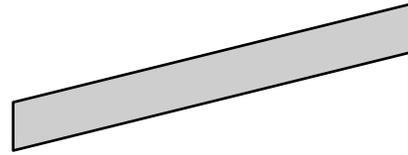
c) Filling boundary line (outline) = correct solution

Outline computation + polygon filling (see next lectures)

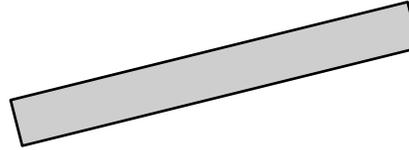


Thick lines ending

- a) Bresenham



- b) Fill area

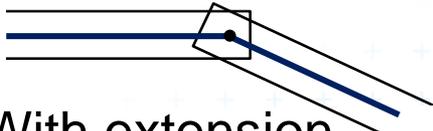


- Ending types:

1) No extension



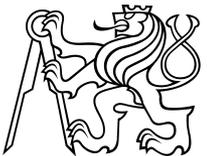
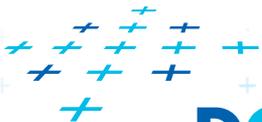
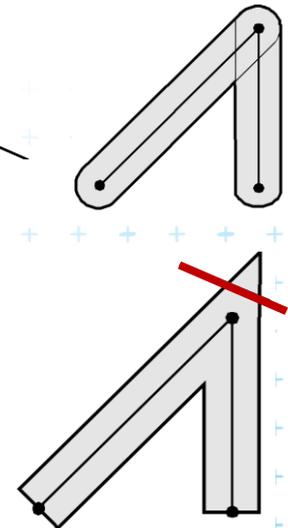
2) With extension



3) Circular extension

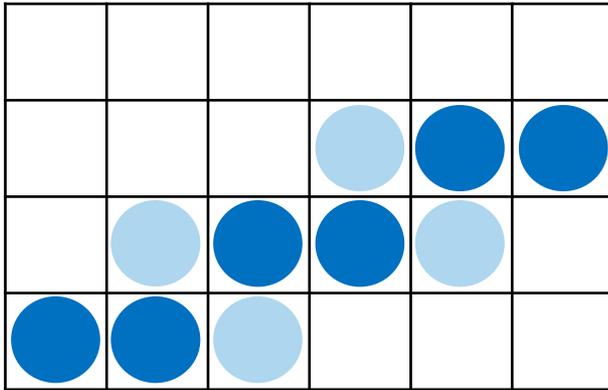


4) General outline



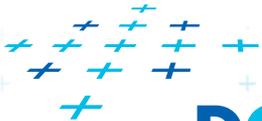
Aliasing & Antialiasing of lines

- Aliasing = causes jaggy lines (result of **subsampling**)
- Antialiasing = smoothing (via pixel **intensities**)



Aliasing

Antialiasing



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Antialiasing

- **Local (Line) antialiasing**
 - when individual line is drawn
- **Global (Full screen) antialiasing**
 - after the whole image/screen is generated
 - image processing technique (filtering)



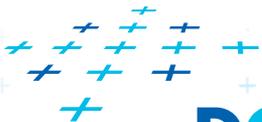
Global antialiasing

- Input = image memory
- Final pixel intensity influenced by neighboring intensities

Filter function H (kernel)

$$I'(x, y) = H(i, j) \cdot I(x + i, y + j)$$

$$H(i, j) = \begin{matrix} i/j & -1 & 0 & 1 \\ -1 & \left[\begin{array}{ccc} \frac{1}{16} & \frac{2}{16} & \frac{1}{16} \\ \frac{2}{16} & \frac{4}{16} & \frac{2}{16} \\ \frac{1}{16} & \frac{2}{16} & \frac{1}{16} \end{array} \right] \\ 0 & & & \\ 1 & & & \end{matrix}$$



Thank you for your attention

Jiří Žára, 23.09.2020

... and study “**Circle Digitizing**” methods @home

