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# X39RSO/A4M39RSO

## Sampling & Anti-aliasing

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Verze 2011

Prepared originally by Daniel Sýkora 2006

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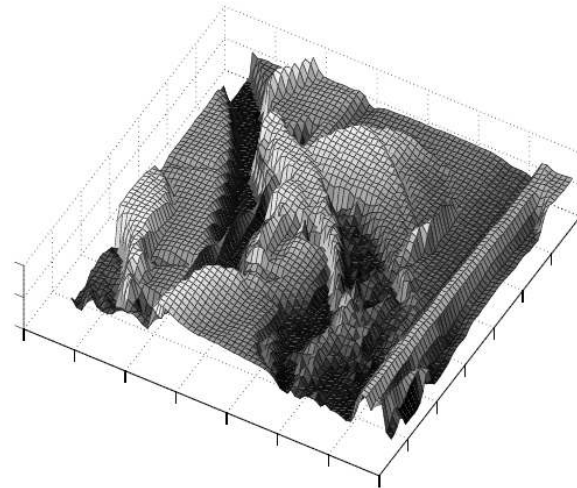
# Introduction

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# What Is an (Animated) Image?

- **Theory** - Continuous function of two/three variables:

$$I(x,y,t): \mathbf{R}^3 \rightarrow \mathbf{R}$$



- **Practice** – Time varying matrix of pixels
- One animation frame = equidistant samples of  $I(x,y,t_i)$ :

$$I[x,y,t]: \mathbf{N}^2 \rightarrow \mathbf{R}$$

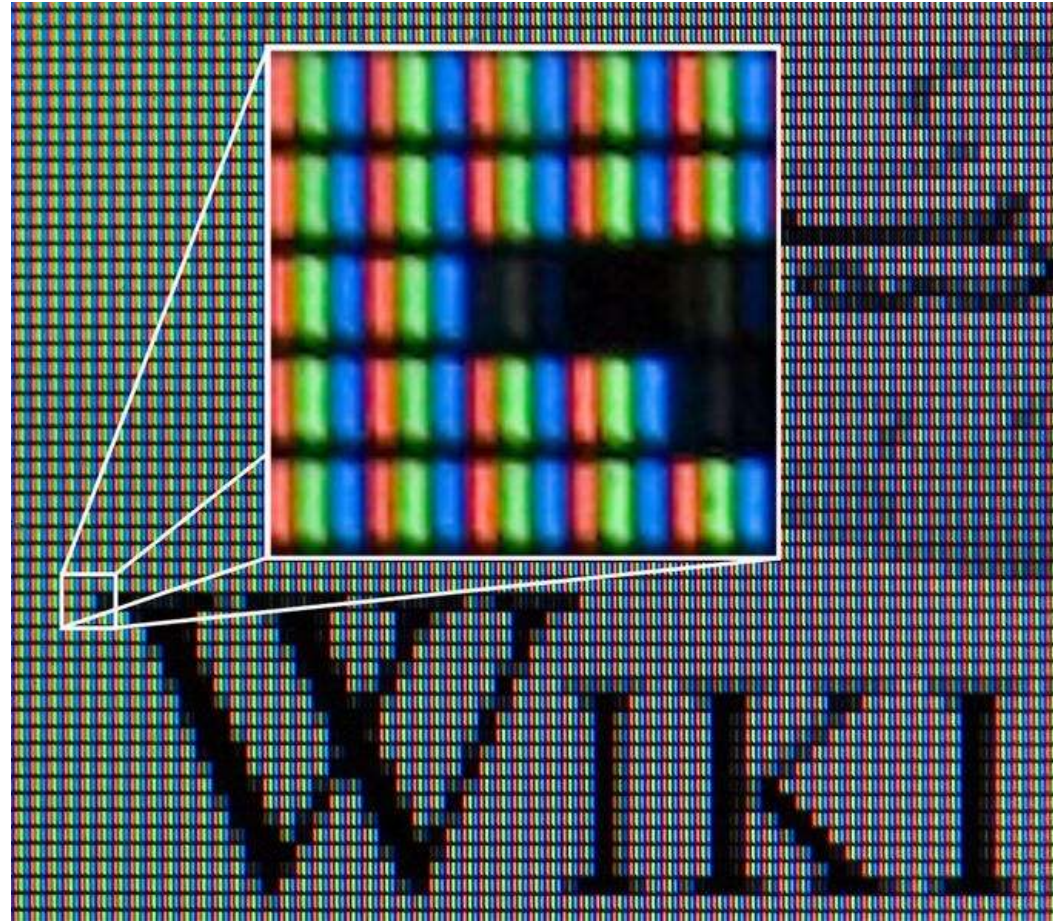
$I[x,y,t] \Rightarrow$  luminance, color RGB, etc.

# Imagers = Signal Sampling

- **Physical imagers** (imager = imaging device)
  - Integrate over sensor area and time
  - Integration: each photon hit => increase pixel value
  - Examples
    - Retina – rods / cones
    - CCD array
    - Film
- **Virtual imagers** – computer graphics cameras
  - Sample continuous image function at specific location and time instant
  - No integration takes place – has to be simulated

# Displays = Signal Reconstruction

- Take image samples
- Reconstruct continuous image (one pixel = small light)
- Examples
  - CRT
  - LCD



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# Image Sampling

- **Real devices**

- Sample = Integral over (small) area and (short) time

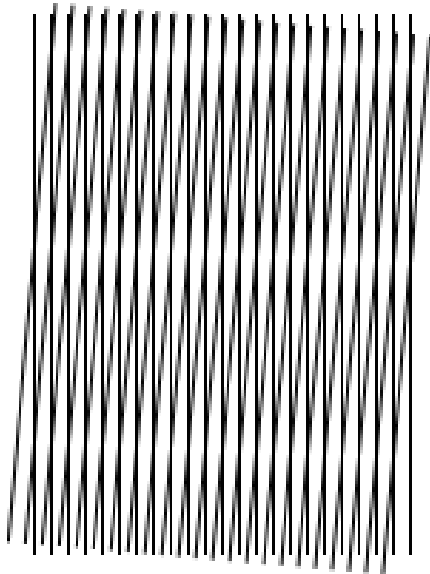
- **Rendering**

- Sample = Point sample
- Consequences – Aliasing
  - Jagged edges
  - Moire patterns
  - Flickering of small objects
  - Sparkling highlights
  - Temporal flickering
- Preventing aliasing – anti-aliasing

# Moire Patterns

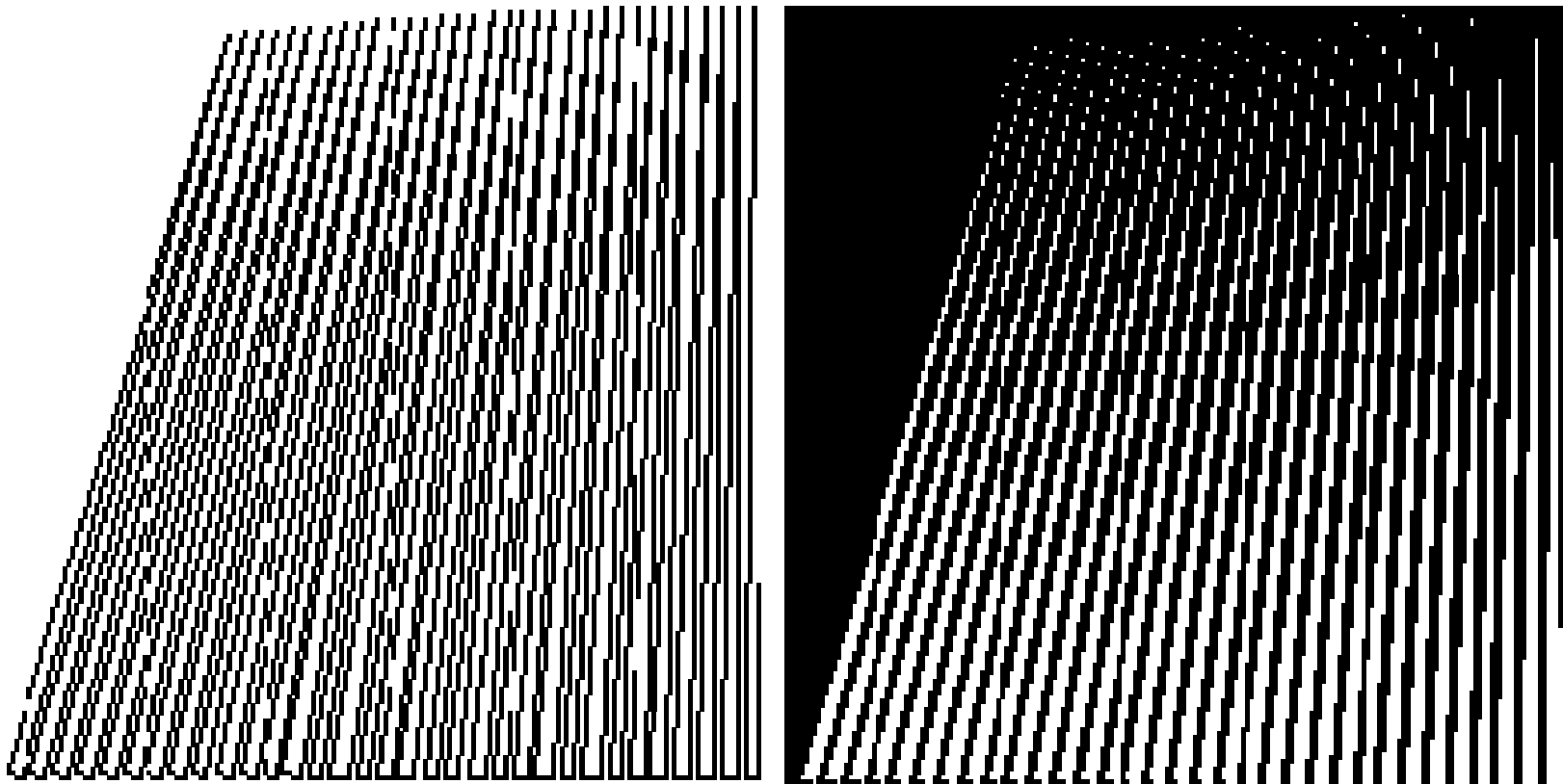
## ■ Definition from Wikipedia

A moiré pattern is an interference pattern created, for example, when two grids are overlaid at an angle, or when they have slightly different mesh sizes.



A moiré pattern, formed by two sets of parallel lines, one set inclined at an angle of  $5^\circ$  to the other.

# Another Moire Pattern (by Chris Cooksey)

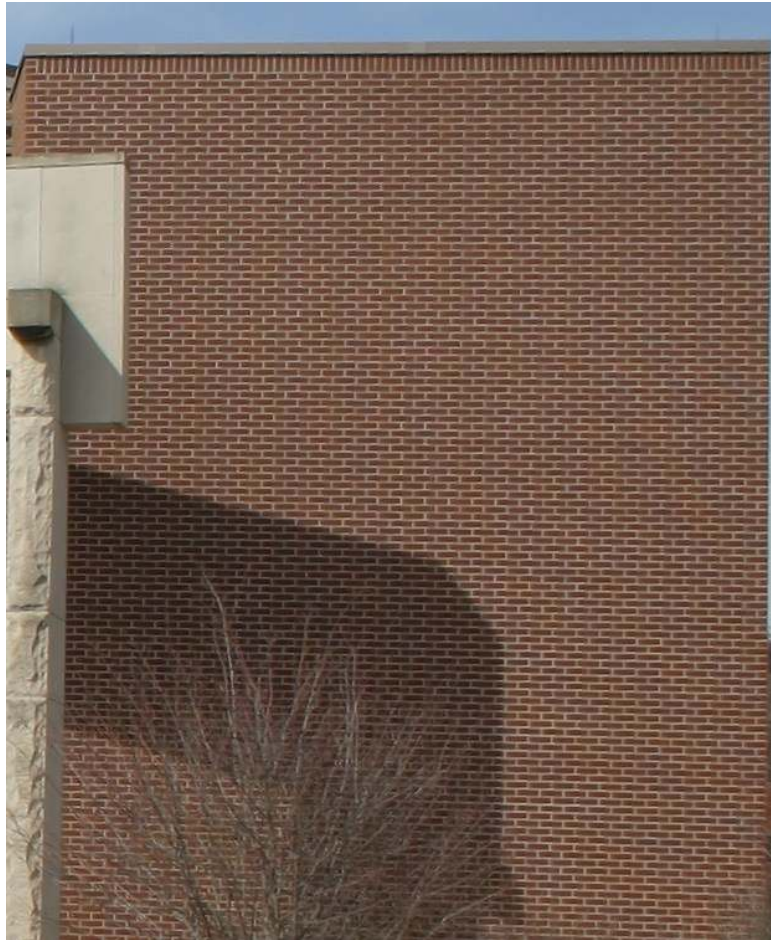




# Moire Patterns



# Moire Patterns

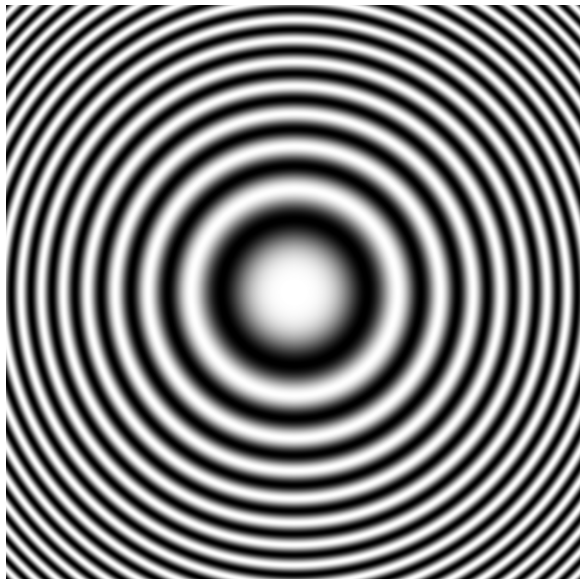


Original Image



Improperly  
subsamped  
image

# Moire Patterns



Continuous image  
("Zone plate")

$$\sin x^2 + y^2$$

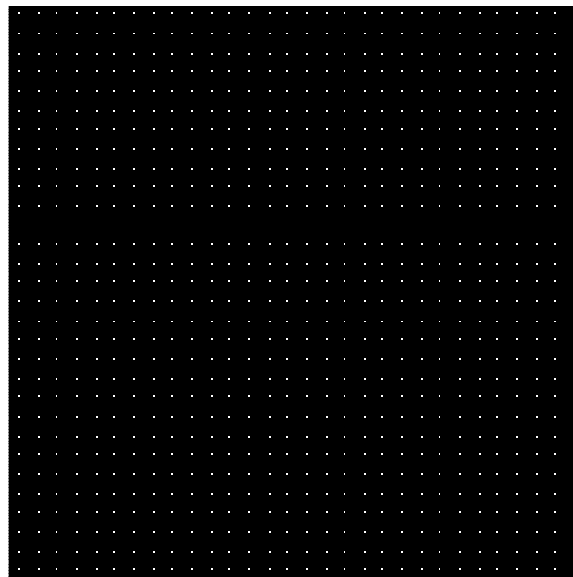
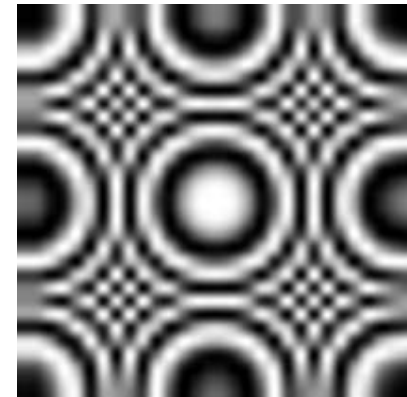


Image samples



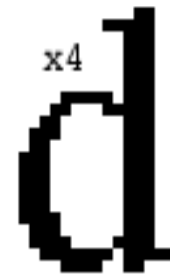
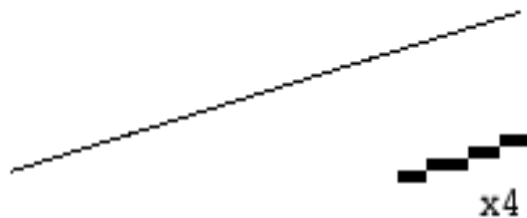
Reconstructed image

# Texture Aliasing



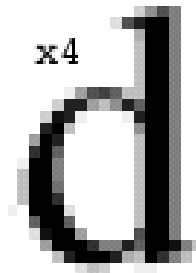
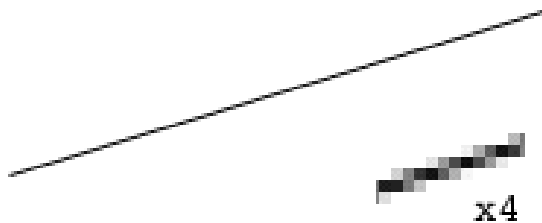
# Character antialiasing

This is not antialiased



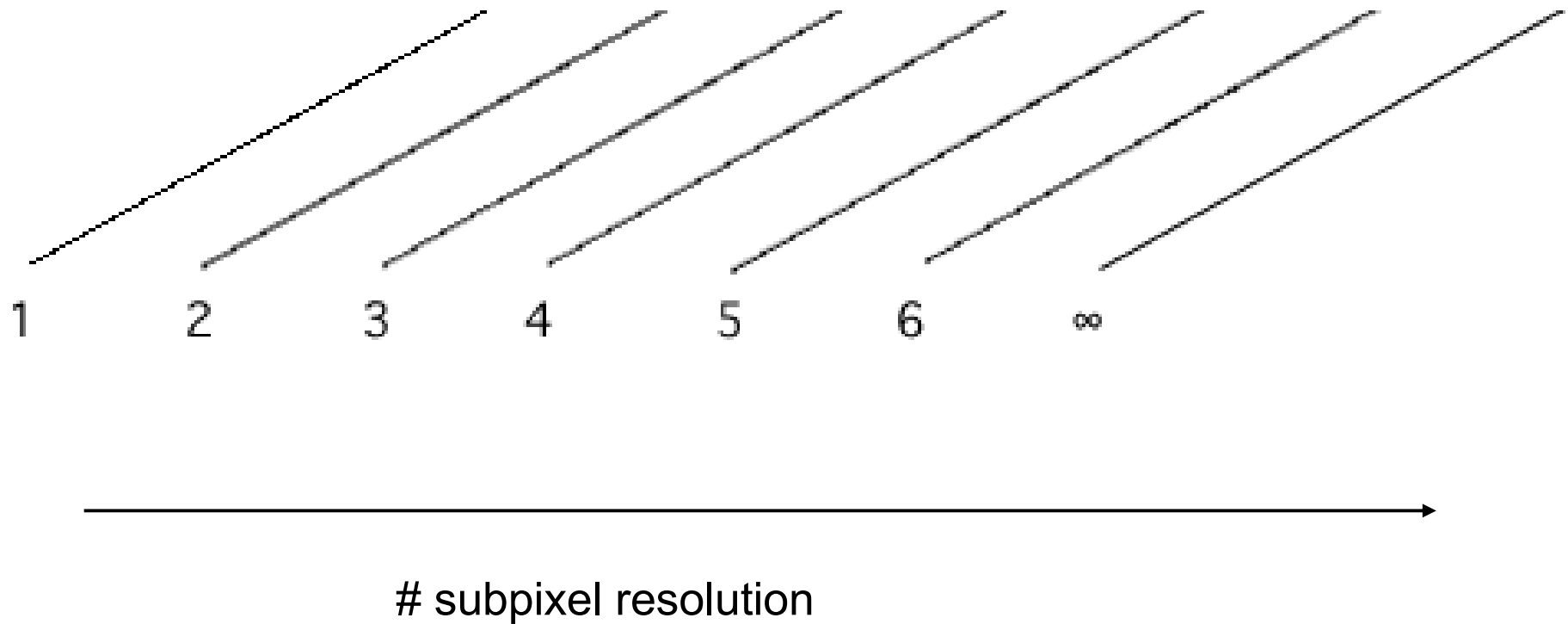
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This is antialiased



# Line antialiasing

- Subpixel sampling is not sufficient !



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# Fourier Transform & Convolution

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# Fourier Transform

- Any function = weighted sum of sines & cosines
- Fourier transform computes weights for sines / cosines of different frequencies (or sine + phase shift)
- Spectrum of  $f$  = Image of  $f$  after Fourier transform



# Fourier Transform

time  $\{x\}$   $\iff$  frequency  $\{u\}$

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forward:  $F(u) = \int_{-\infty}^{\infty} f(x) \cdot e^{-2\pi j u x} dx$

inverse:  $f(x) = \int_{-\infty}^{\infty} F(u) \cdot e^{+2\pi j u x} du$

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basis functions:  $e^{j\alpha} = \cos(\alpha) + j \sin(\alpha)$

cosine transform:  $\mathbf{Re}(F(u)) = \int_{-\infty}^{\infty} F(x) \cdot \mathbf{cos}(2\pi u x) dx$

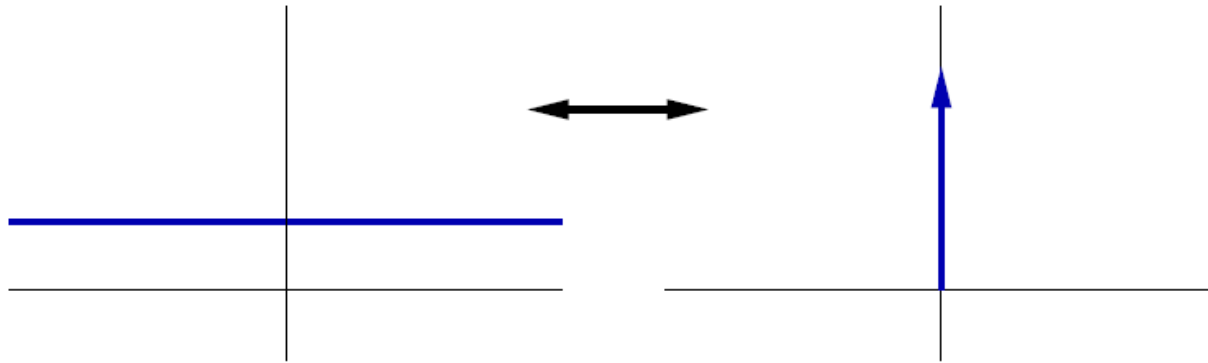
sine transform:  $\mathbf{Im}(F(u)) = - \int_{-\infty}^{\infty} F(x) \cdot \mathbf{sin}(2\pi u x) dx$

amplitude:  $|F(u)| = \sqrt{\mathbf{Re}(F(u))^2 + \mathbf{Im}(F(u))^2}$

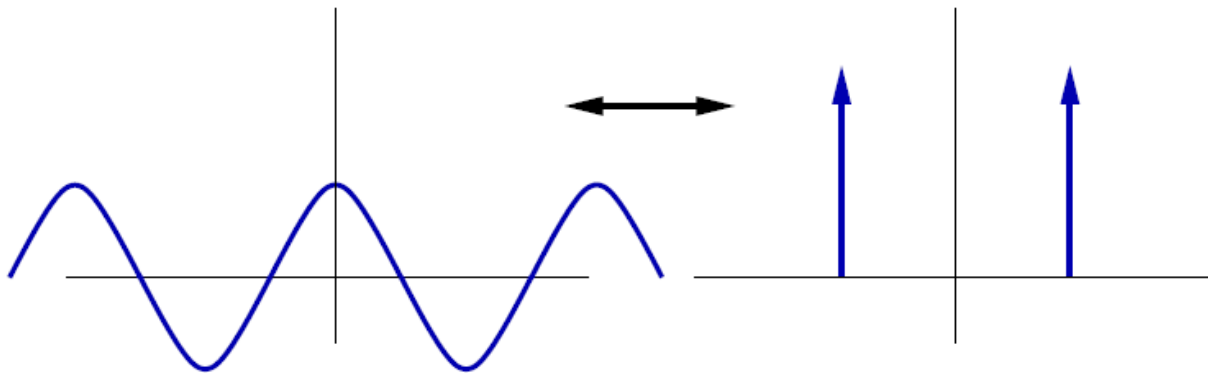
phase:  $\Phi(F(u)) = \tan^{-1} \left( \frac{\mathbf{Im}(F(u))}{\mathbf{Re}(F(u))} \right)$

# Fourier Transform Pairs (Examples)

$$1 \iff \delta(u)$$

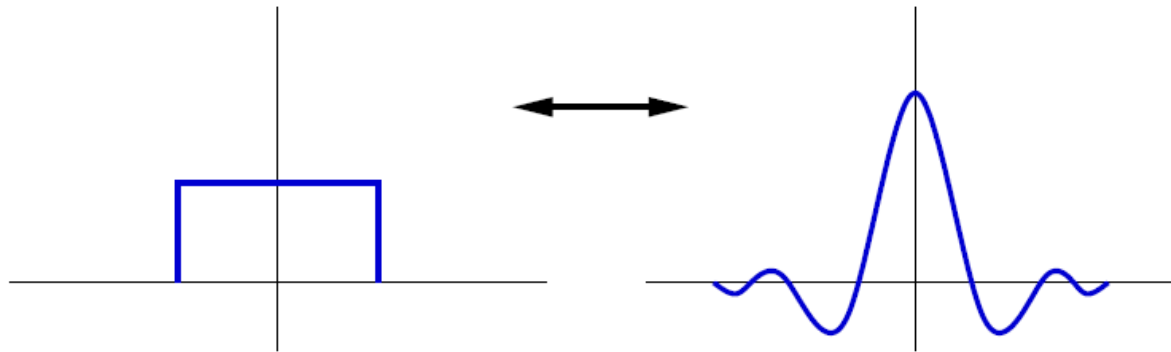


$$\cos(2\pi kx) \iff \frac{1}{2}(\delta(u+k) + \delta(u-k))$$

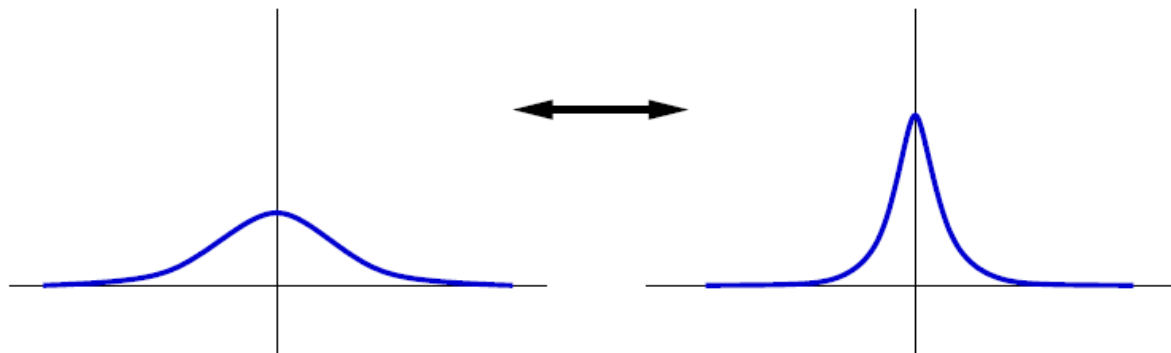


# Fourier Transform Pairs (Examples)

$$\mathbf{1}(x+k) - \mathbf{1}(x-k) \iff \frac{1}{\pi u} \sin(2\pi k u)$$



$$\exp(-kx^2) \iff \sqrt{\frac{\pi}{k}} \exp\left(-\frac{\pi^2}{k}u^2\right)$$

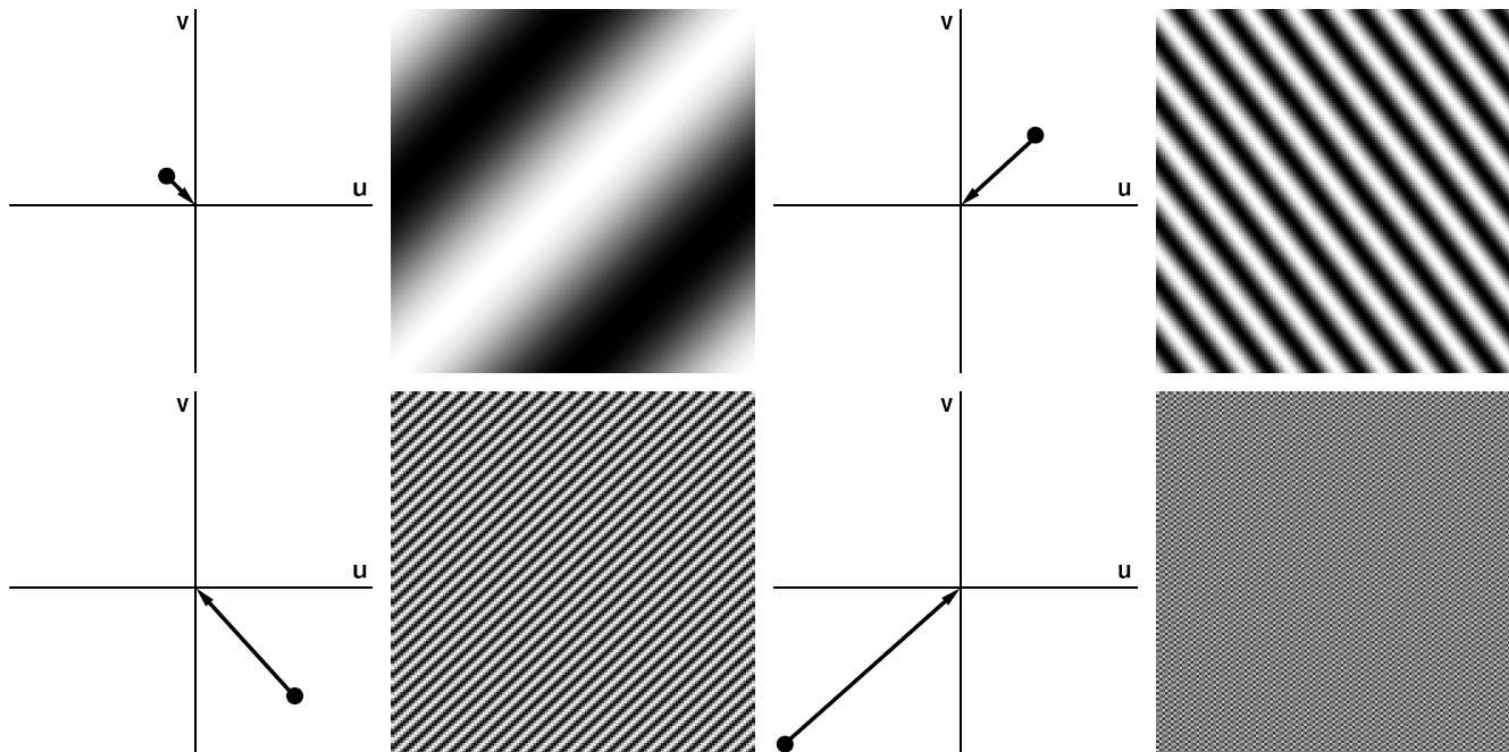


# Fourier Transform in 2D

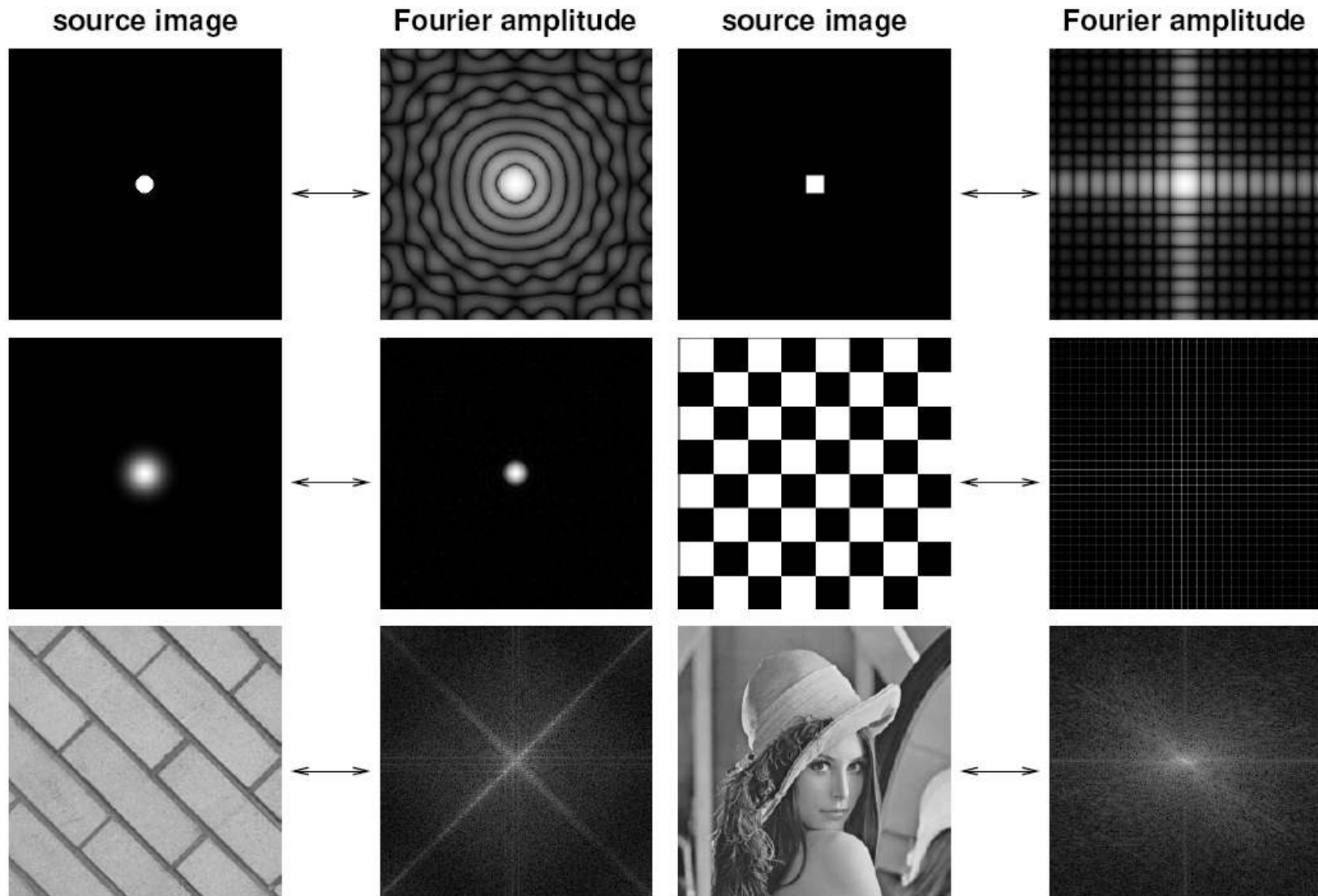
position  $\{x, y\}$   $\iff$  frequency & orientation  $\{u, v\}$

forward: 
$$F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) \cdot e^{-2\pi j(ux+vy)} dx dy$$

inverse: 
$$f(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(u, v) \cdot e^{+2\pi j(ux+vy)} du dv$$

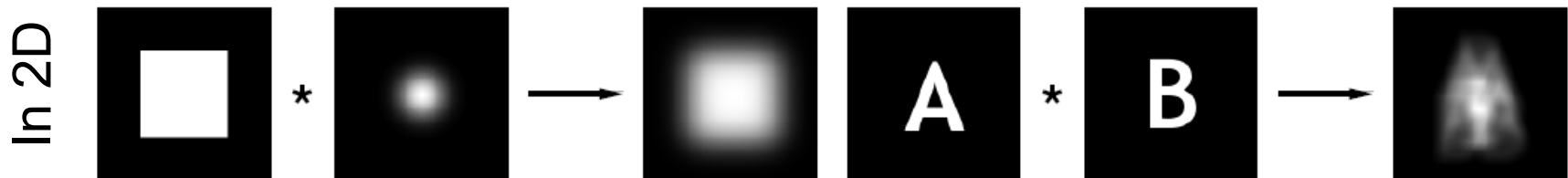
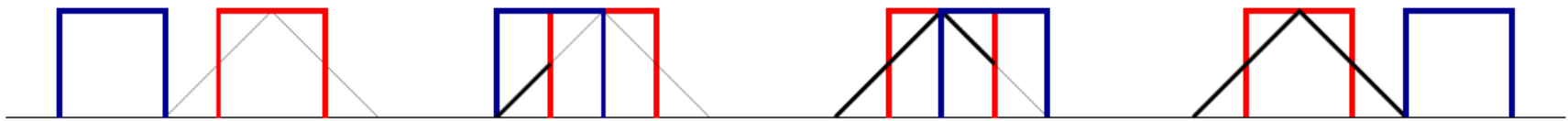
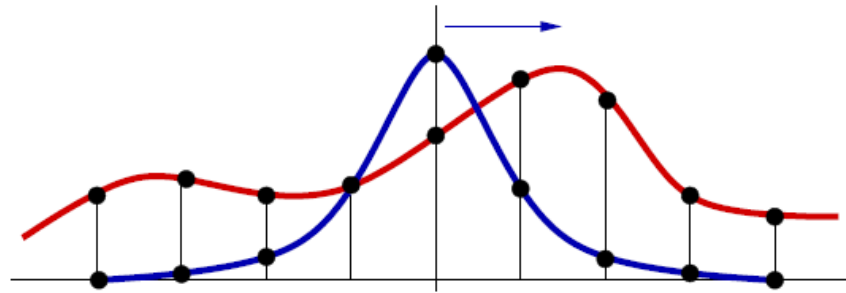


# Fourier Transform in 2D – Examples



# Convolution

$$h(x) = f \otimes g = \int f(x')g(x - x') dx'$$



# Convolution Theorem

- Multiplication in the frequency domain is equivalent to convolution in the space domain and vice versa.

$$f \otimes g \leftrightarrow F \times G$$

$$f \times g \leftrightarrow F \otimes G$$

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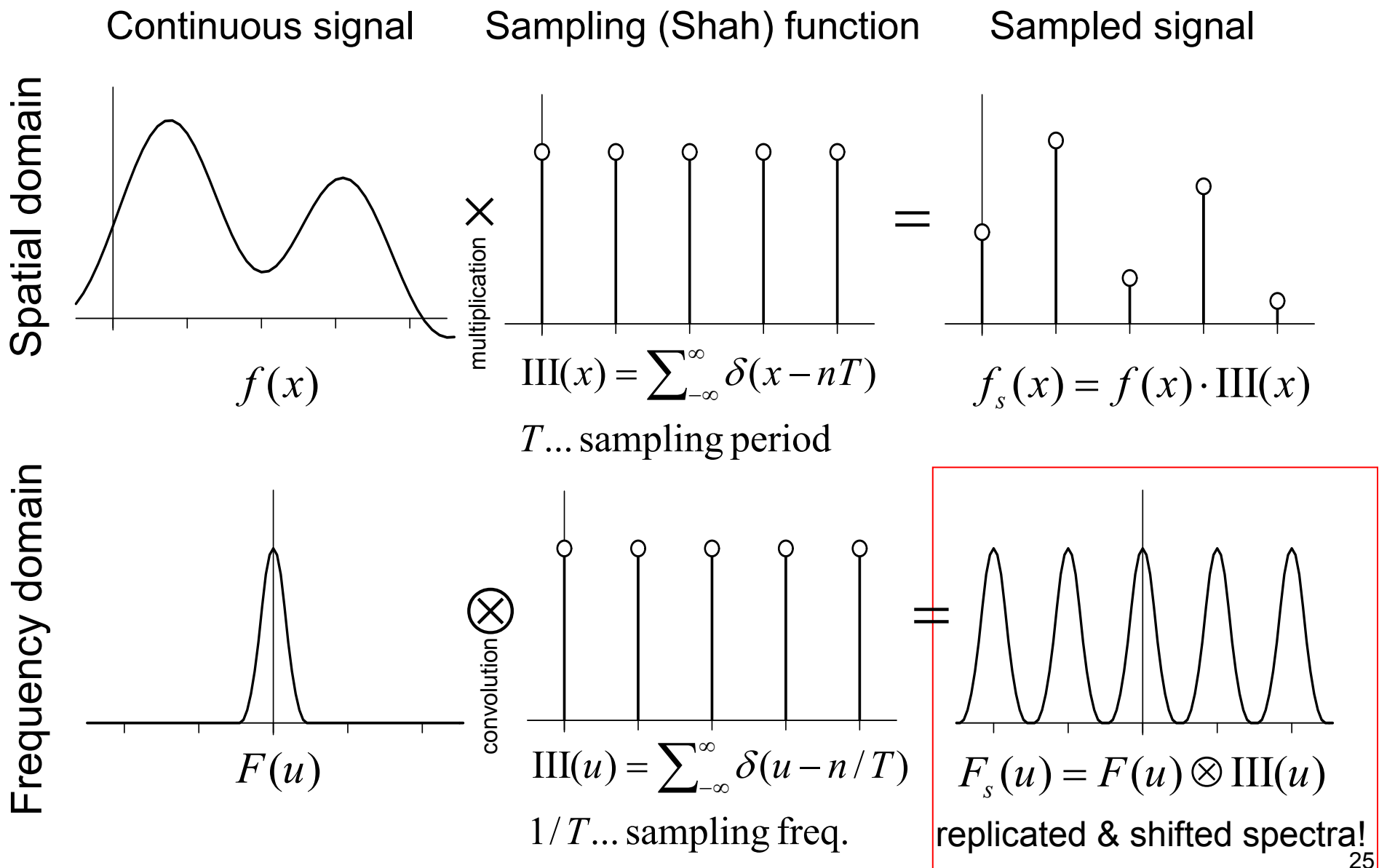
# **Sampling & Reconstruction**

## **The Sampling Theorem**

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# Sampling



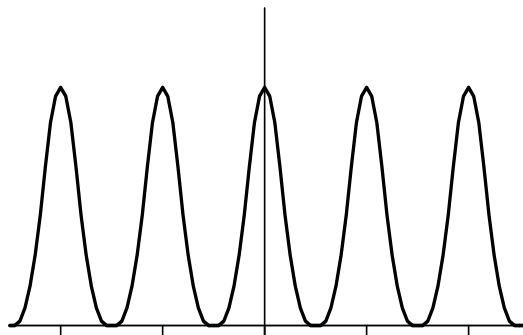
# Reconstruction

Sampled signal

(Ideal) Reconstruction filter

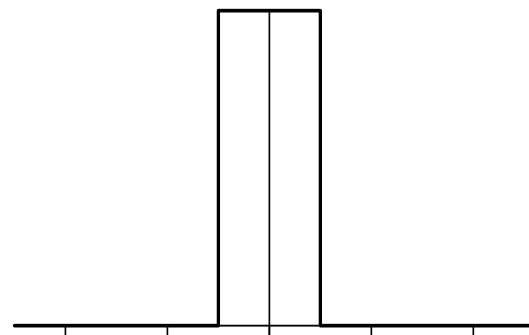
Reconstructed Continuous signal

Frequency domain



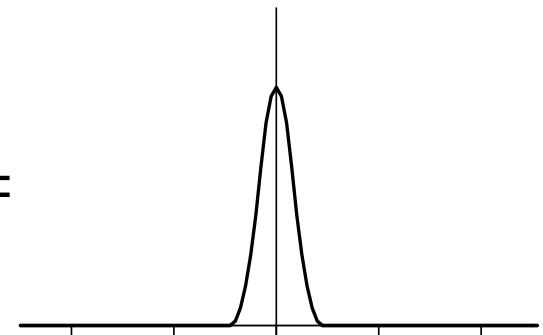
$$F_s(u)$$

multiplication  $\times$



$$\text{Box: } \Pi(u) = \begin{cases} 1 & |x| < 1/2T^{-1} \\ 0 & \text{otherwise} \end{cases}$$

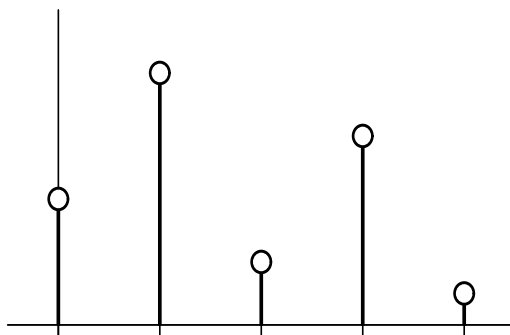
=



$$F'(u) = F_s(u) \cdot \Pi(u)$$

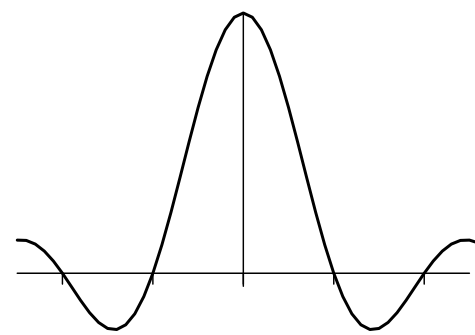
replicas cut off

Spatial domain



$$f_s(x)$$

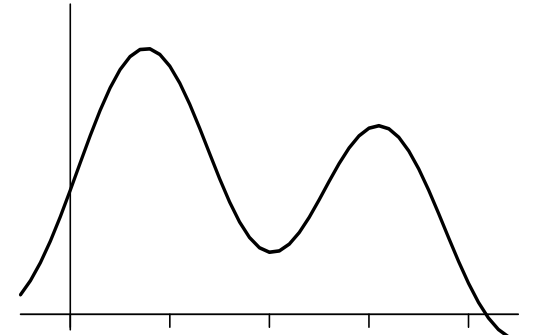
convolution  $\otimes$



$$\text{sinc}_T(x) = \sin(xT) / xT$$

$T$ ... sampling period

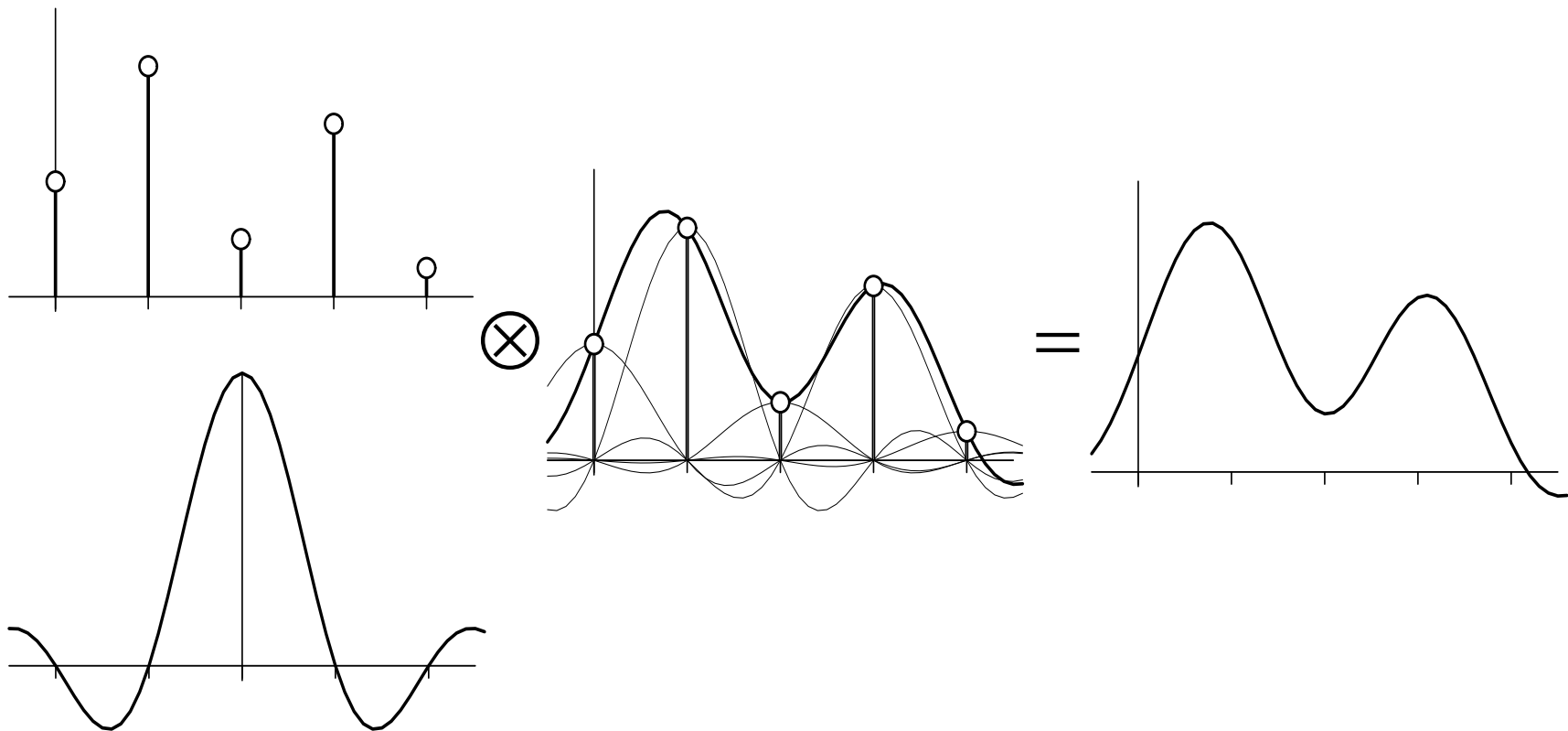
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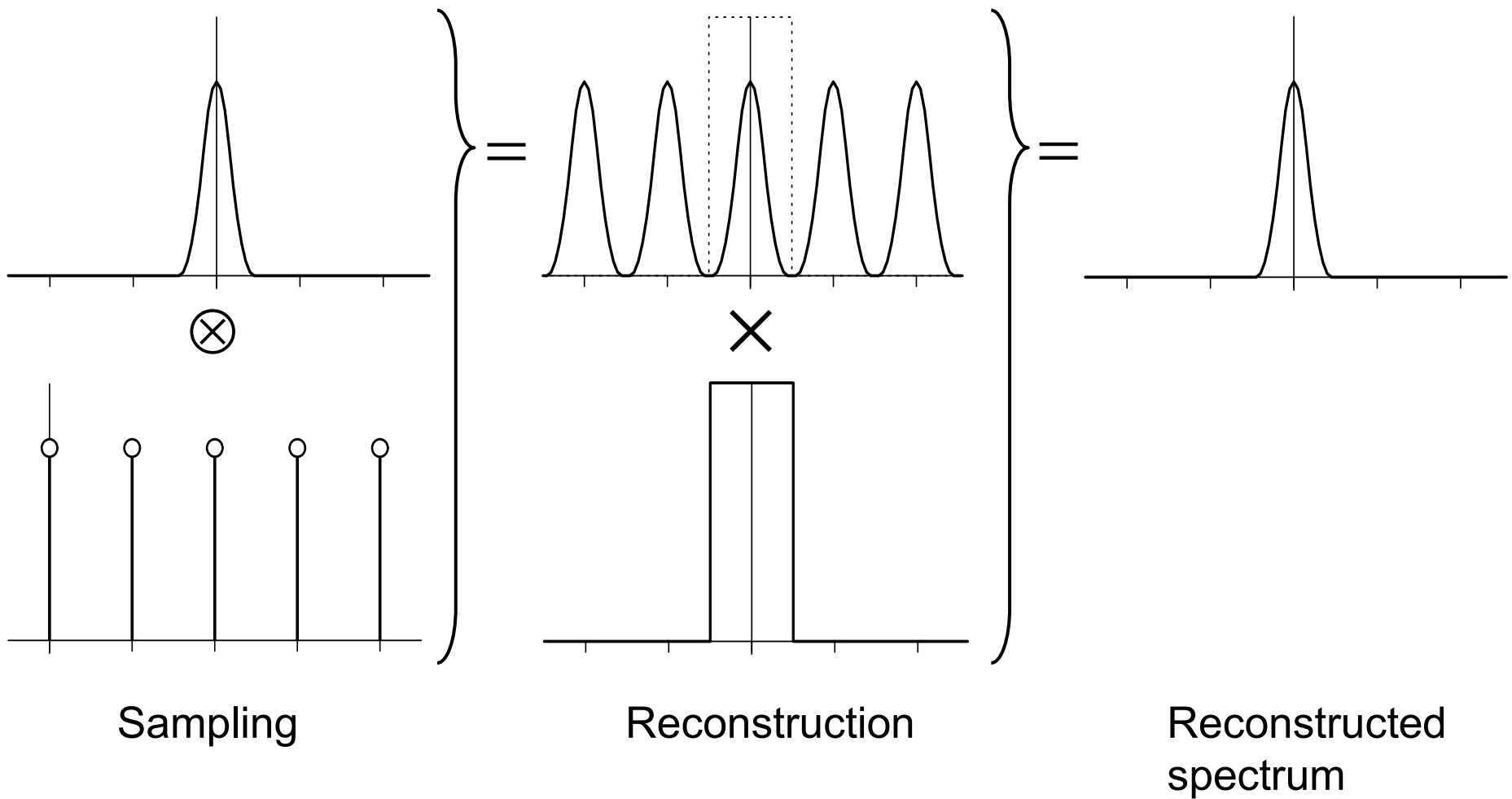
$$f'(x) = f_s(x) \otimes \text{III}(x)$$

# Reconstruction in Spatial Domain – Details

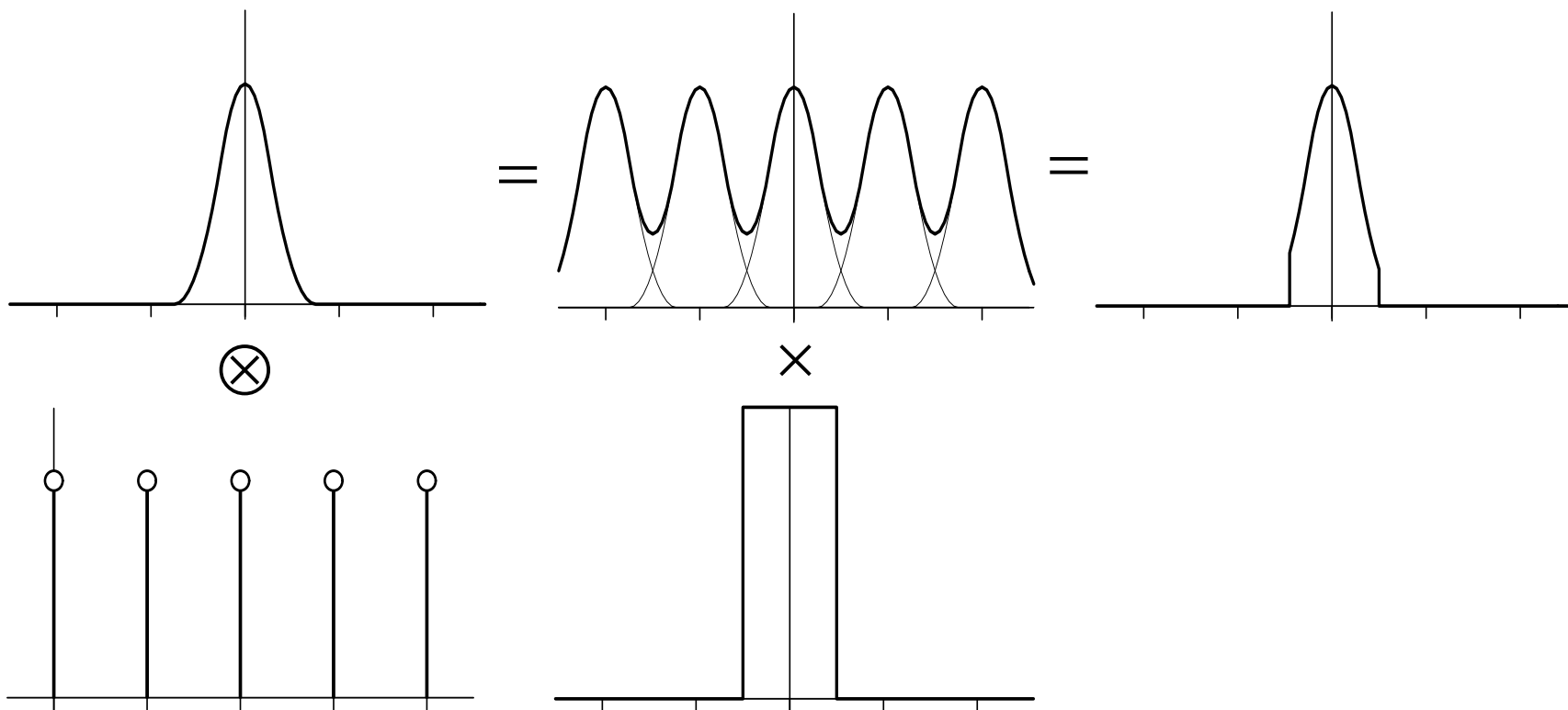
- **Convolution** with the sinc function
  - weighted sum of shifted sinc kernels



# Sampling and Reconstruction Summary – Frequency Domain



# Aliasing due to Undersampling



- If spectrum replicas overlap, impossible to reconstruct original signal

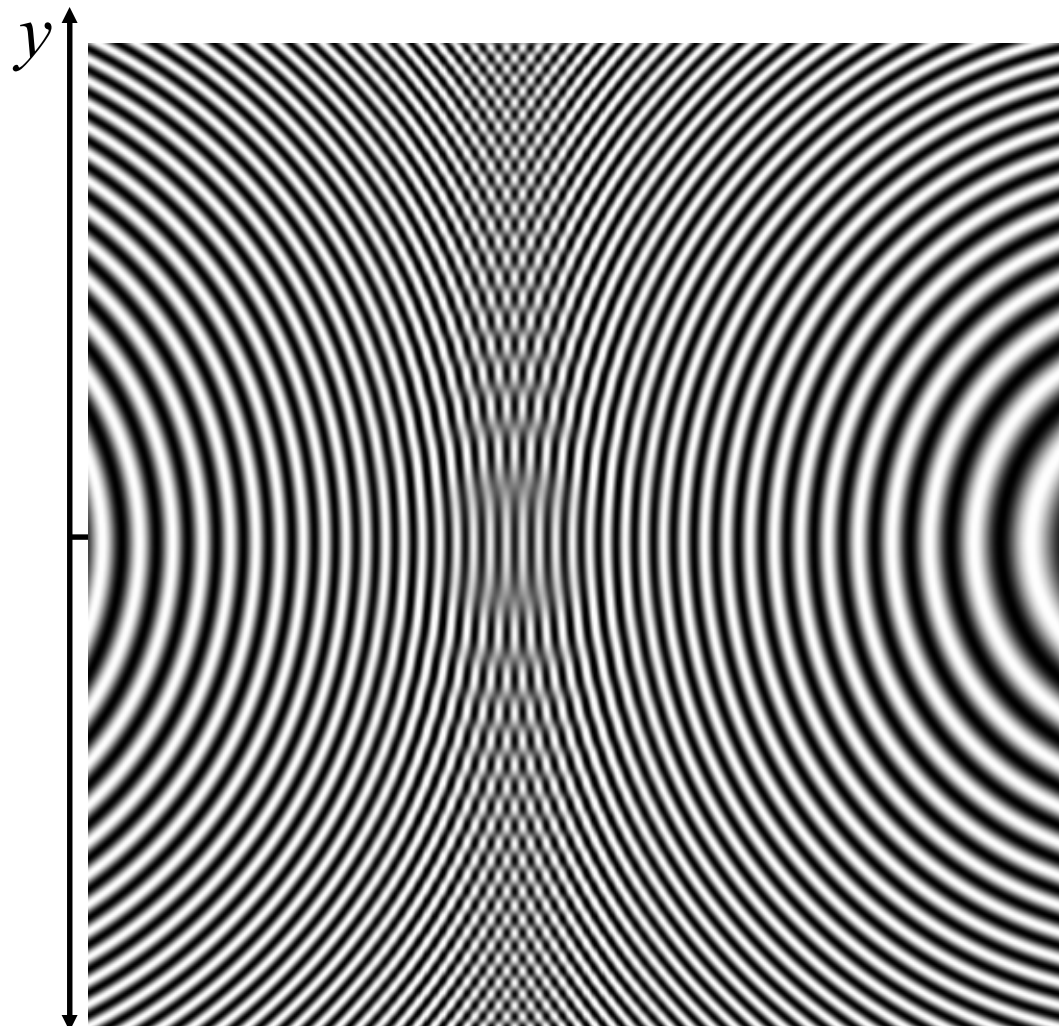
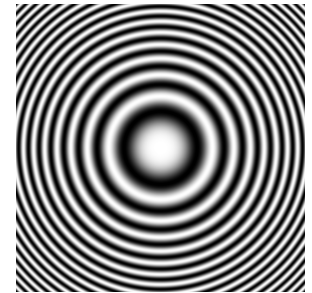
# Sampling Theorem

- Claude Shannon, 1949

**A signal can be reconstructed from its samples without loss of information, if the original signal has no frequencies above 1/2 the Sampling frequency.**

- DEF: Bandlimited function. There is some frequency  $u_{\max}$ , above which the spectrum is identically zero.
- For a given bandlimited function, the rate at which it must be sampled ( $2u_{\max}$ ) is called the Nyquist Frequency.

# Sampling a “Zone Plate”



**Zone plate:**  $\sin x^2 + y^2$

Sampled at 128x128

Reconstructed to 512x512  
using a 30-wide windowed  
sinc

$x$

**Left rings:** part of signal

**Right rings:** prealiasing

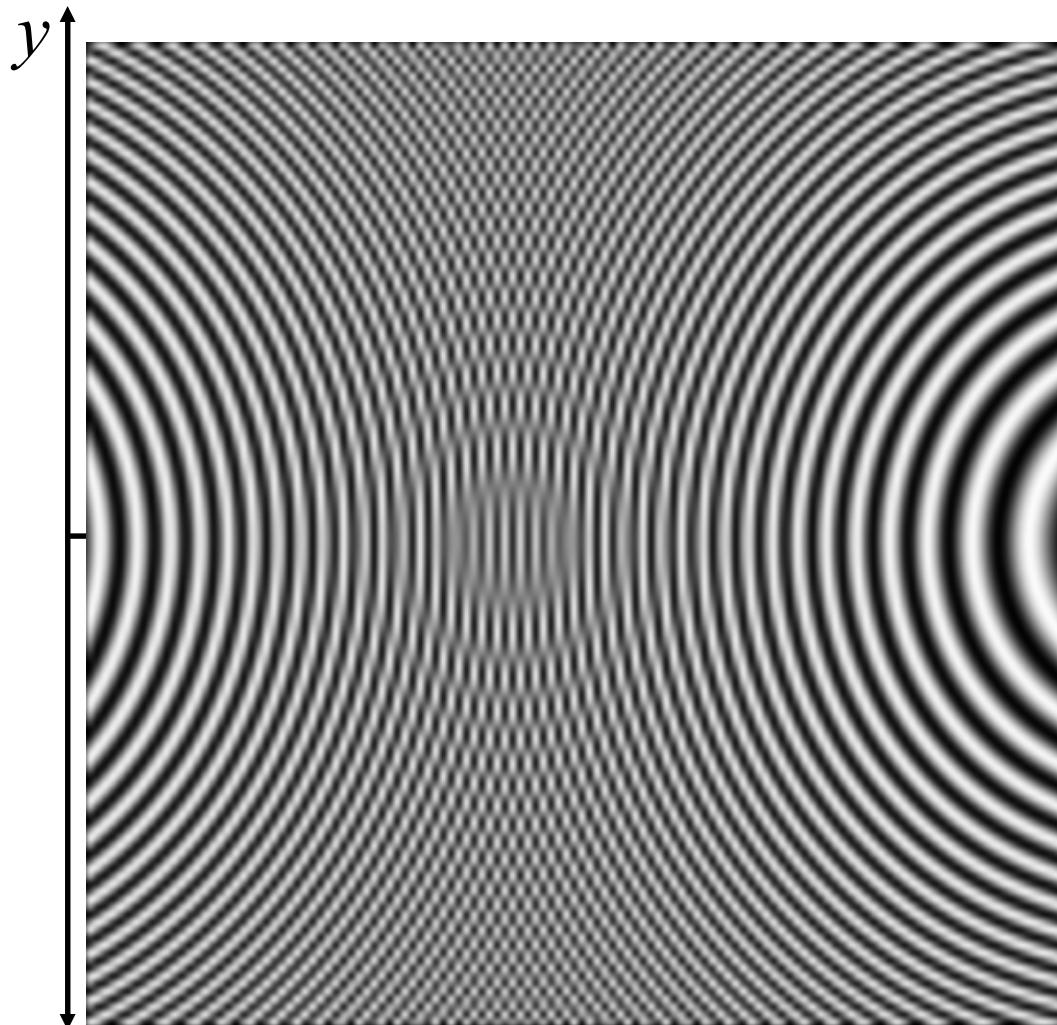
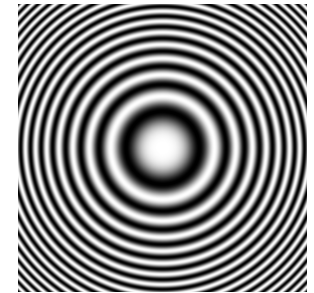
**Prealiasing:** due to  
inadequate sampling

# Ideal Reconstruction

- Ideally, use a perfect low-pass filter - the sinc function - to bandlimit the sampled signal and thus remove all copies of the spectra introduced by sampling
- Unfortunately,
  - The sinc has infinite extent and we must use simpler filters with finite extents. Physical processes in particular do not reconstruct with sincs
  - The sinc may introduce ringing which are perceptually objectionable



# Sampling a “Zone Plate”



**Zone plate:**  $\sin x^2 + y^2$

Sampled at 128x128

Reconstructed to 512x512

Using optimal cubic filter

**Left rings:** part of signal

**Right rings:** prealiasing

**Middle rings:** **postaliasing**

**Postaliasing:** due to  
inappropriate reconstruction

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# Antialiasing

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# Antialiasing Techniques

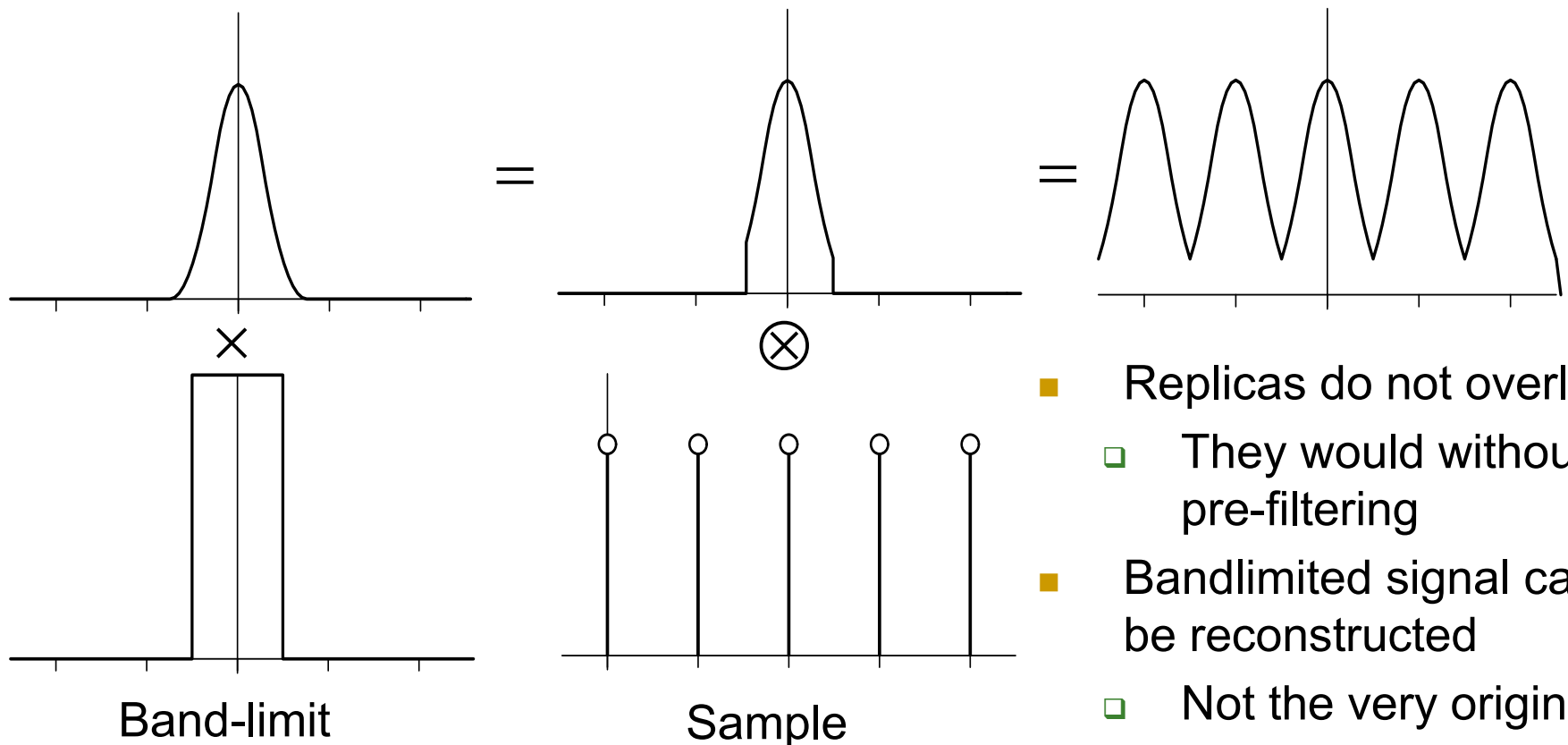
- Antialiasing = Preventing aliasing
- 1. Analytically prefilter the signal
  - Solvable for points, lines, polygons and **image textures**
  - Not solvable in general
    - e.g. procedurally defined geometry or textures
- 2. Uniform supersampling and resampling
- 3. Non-uniform or stochastic sampling

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- 1. **Analytically prefilter the signal**
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# Antialiasing by Prefiltering

1. First bandlimit the signal (cut off high frequencies = “blur”)
  2. Then sample
- Sampling process in **frequency domain**:



- Replicas do not overlap
- They would without pre-filtering
- Bandlimited signal can be reconstructed
- Not the very original

# Antialiasing by Prefiltering

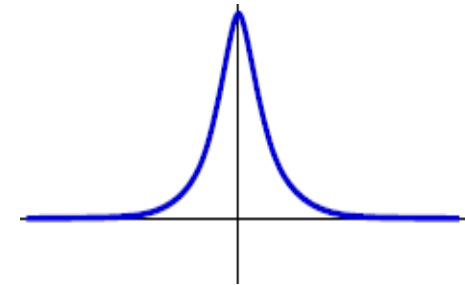
- Sampling process in **spatial domain**:

1. Convolve with ideal prefilter,  $h$  (ideally  $h = \text{sinc}$ )
2. Sample: multiply by  $\text{III}(x)$

$$f_s(x) = [f(x) \otimes h(x)] \times \text{III}(x)$$

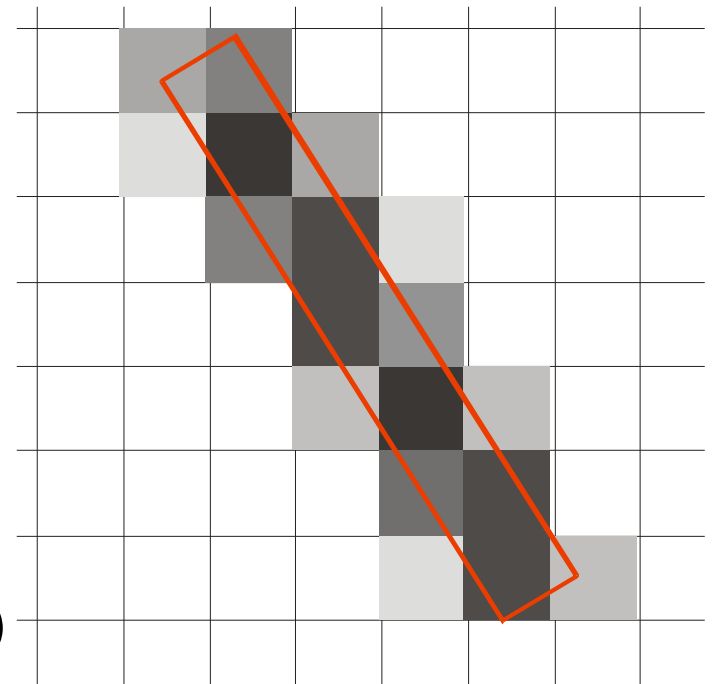
- In practice:

- sinc replaced by a locally supported filter, e.g. truncated Gaussian
- taking filtered samples
  - filter centered at the sample location



# Anti-aliased Lines With Pre-filtering

- Practice
  - Compute analytically the pixel area covered by the line
  - Assign a color based on this analytically computed coverage
- The same thing in terms of the signal theory
  1. Convolve with a box-shaped pre-filter (box=pixel)
  2. Sample at pixel centers
- Beware - box pre-filter is bad!
  - Spectrum is sinc – leaves a lot of high frequencies
  - So this method of line antialiasing is not optimal (but often sufficient)



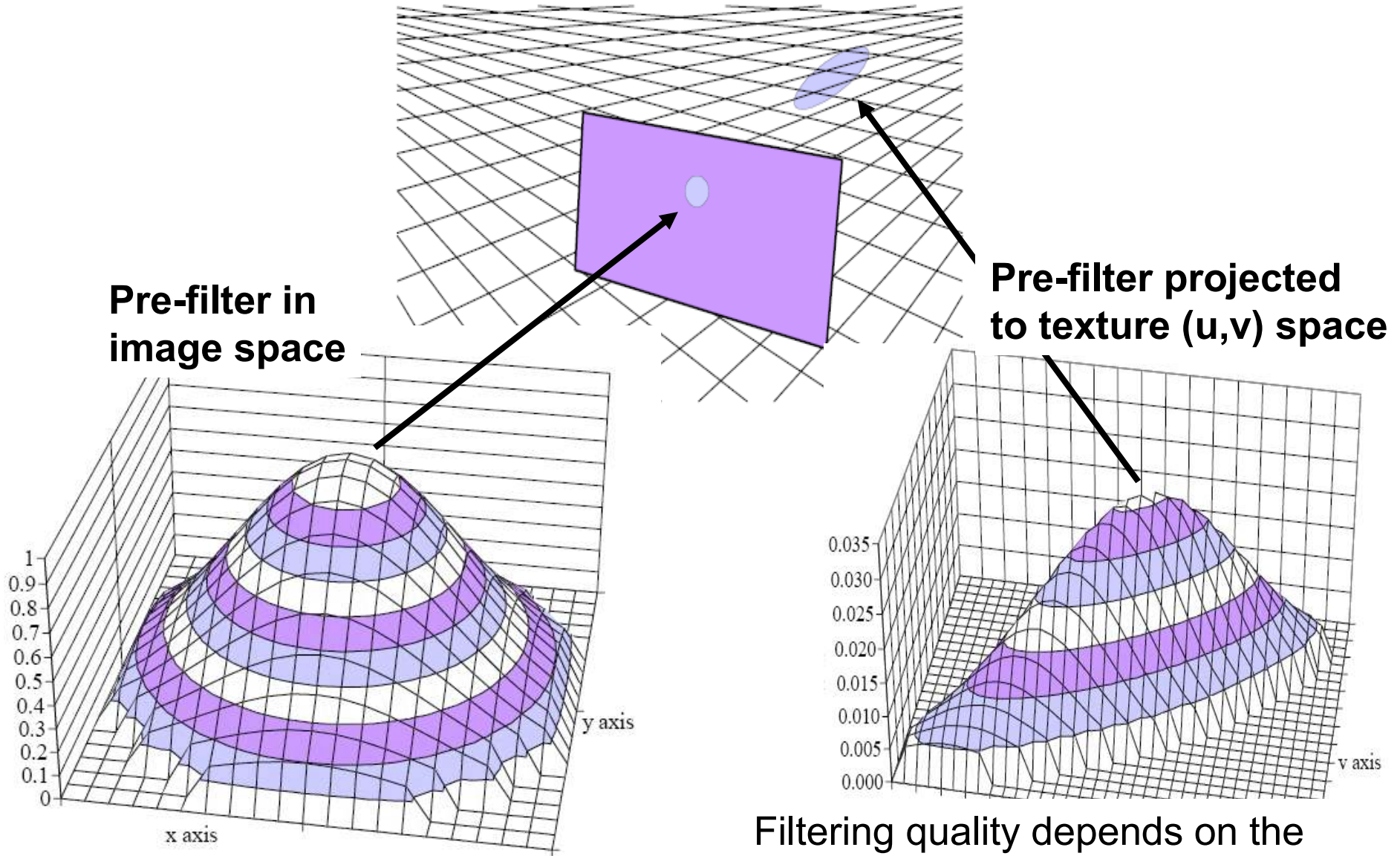
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# Texture Antialiasing by Prefiltering

- Pre-filter placed at the pixel
- Projected to texture space
- Convolution computed as a weighted sum of texels



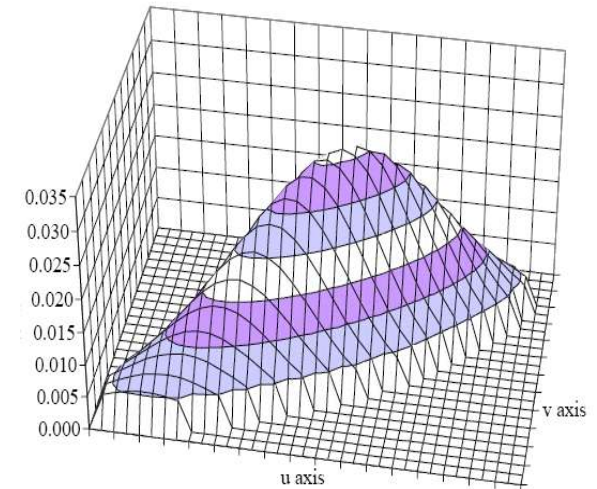
# Texture Antialiasing by Prefiltering



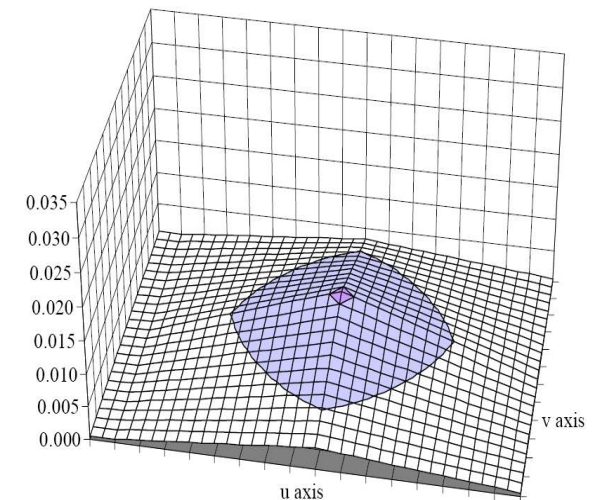
Filtering quality depends on the approximation of the projected filter.

# Trilinear Filtering

- Most commonly used in GPUs
  - 1. Choose a MIP-map level, so that the projected filter covers approximately 4 texels
  - 2. Bilinear texture interpolation in two adjacent MIP-map levels
  - 3. Linear interpolation between the two levels
- 
- Only isotropic filtering
  - Poor approximation of the projected prefilter

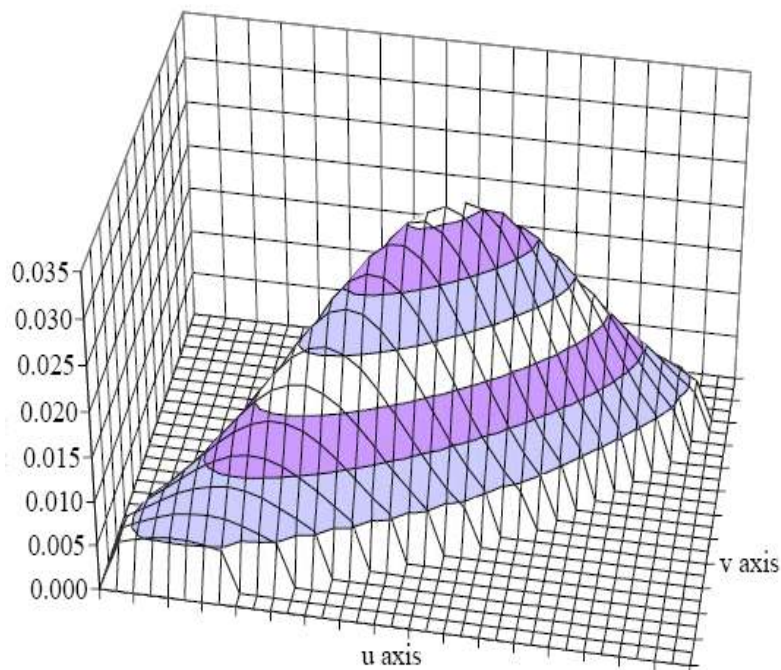


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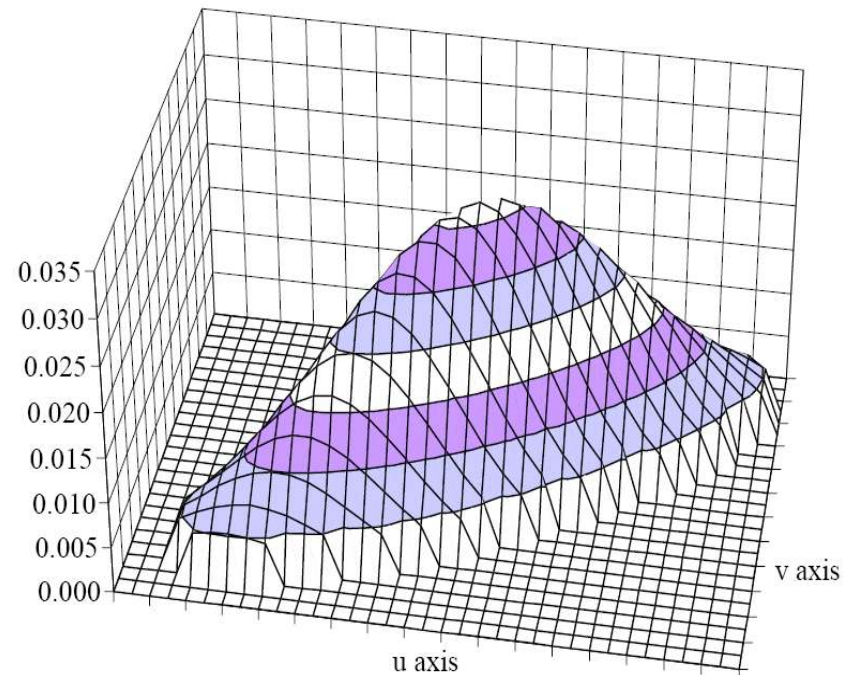


# EWA Texture Filtering

- EWA = Elliptical Weighted Average
- Approximated by an elliptical gaussian – close match
- Allows anisotropic filtering

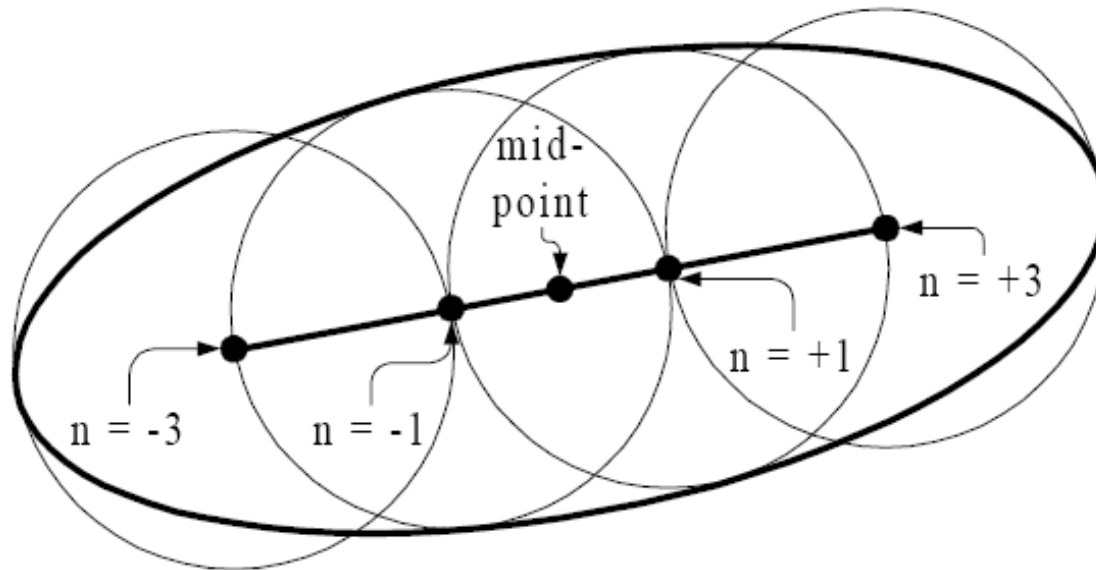


$\approx$



# Anisotropic Filtering on the GPU

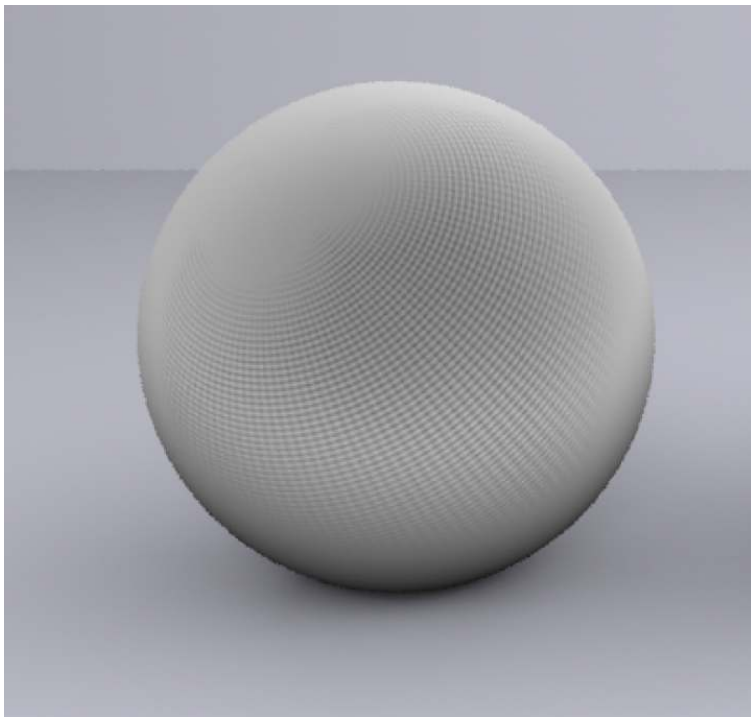
- Approximate projected pre-filter by a number of tri-linear look-ups
- E.g. 4 x aniso



# Texture Filtering Quality

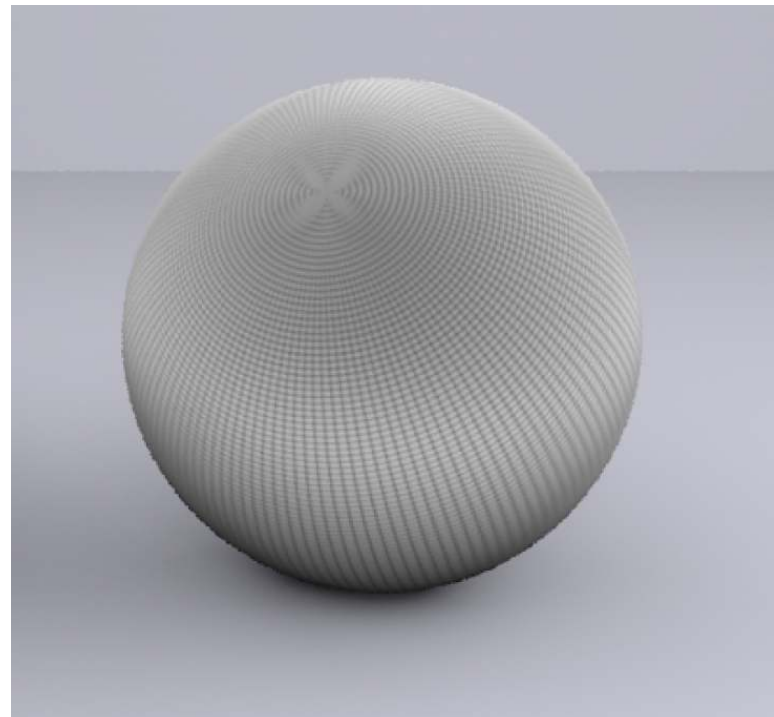
## Trilinear

- Bad overall quality - tent filter
- Blurs near silhouettes - Isotropic



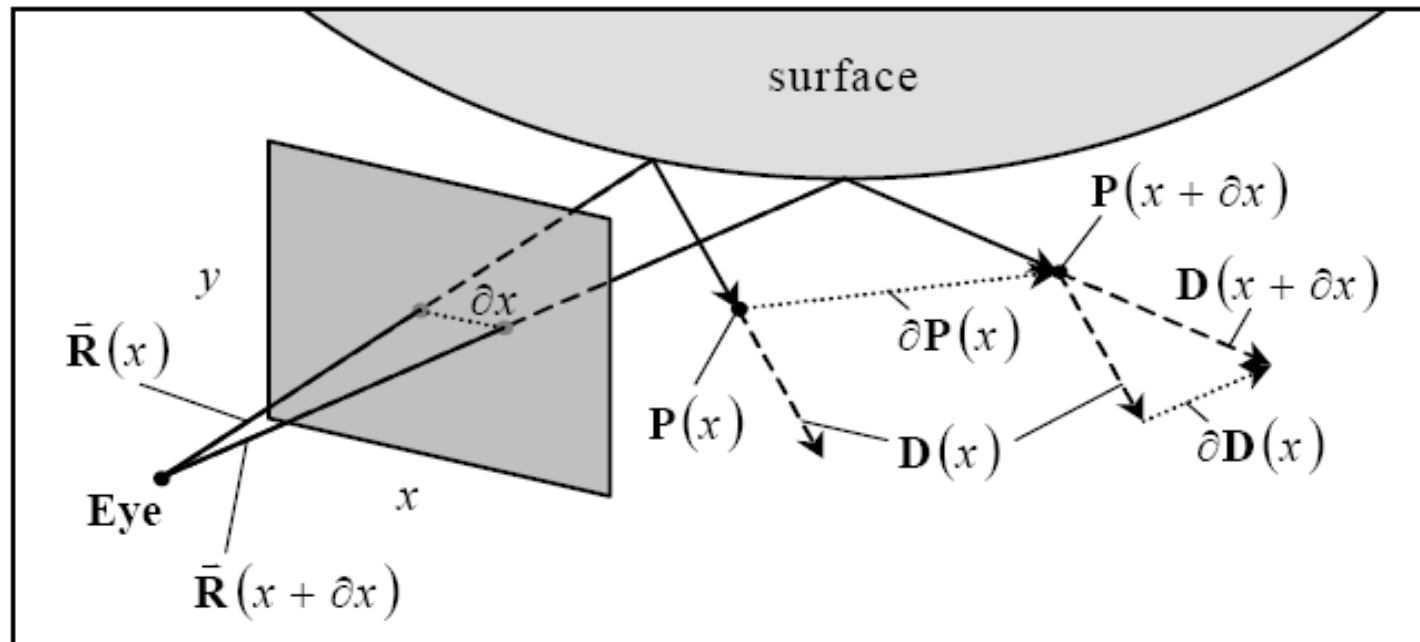
## EWA

- Better overall quality - Gauss filter
- Silhouettes preserved - Anisotropic



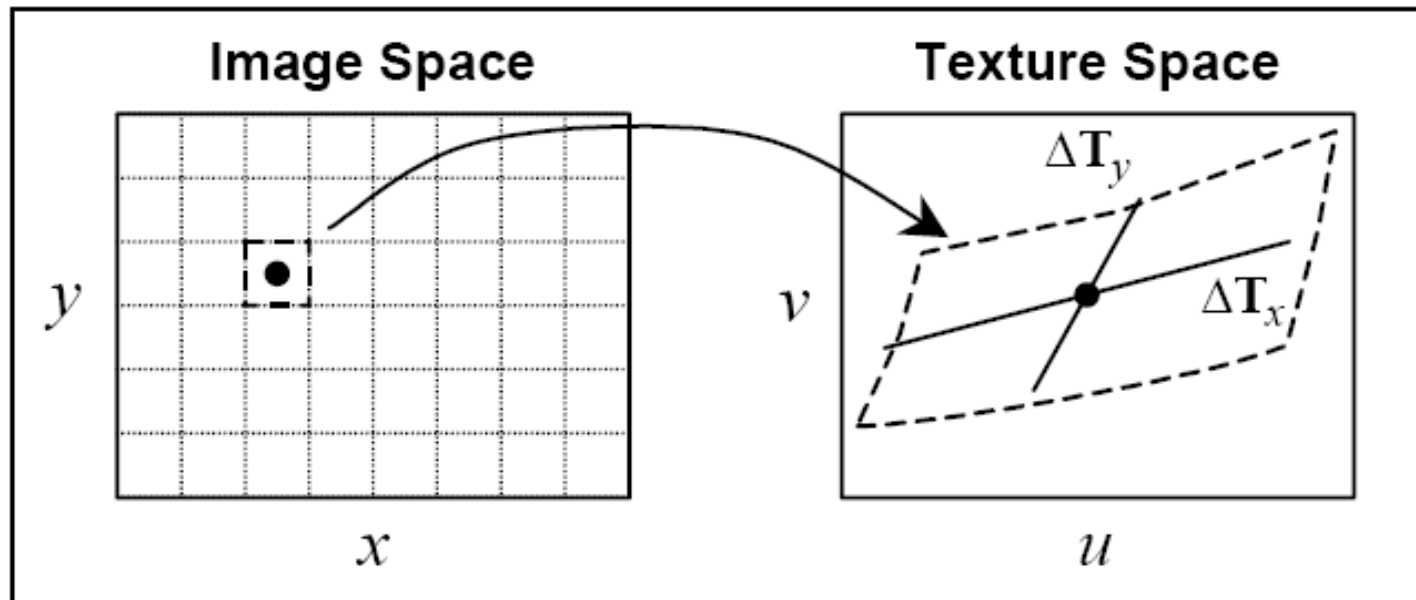
# Ray Differentials

- Texture filtering for reflected and refracted rays



**Figure 1:** A Ray Differential. The diagram above illustrates the positions and directions of a ray and a differentially offset ray after a reflection. The difference between these positions and directions represents a ray differential.

# Ray Differentials



**Figure 2:** Texture Filtering Kernel. A pixel's footprint in image space can map to an arbitrary region in texture space. This region can be estimated by a parallelogram formed by a first-order differential approximation of the ratios between rate of change in texture space and image space coordinates.

# Ray Differentials

Homan Igehy, **Tracing Ray Differentials**  
In *Proc. of SIGGRAPH '99*. 1999  
<http://graphics.stanford.edu/papers/trd/>



Sample Scene

Footprint based on distance



Bilinear  
base texture

Trilinear  
mip map

Footprint based ray differential



Trilinear  
mip map

Anisotropic  
mip map

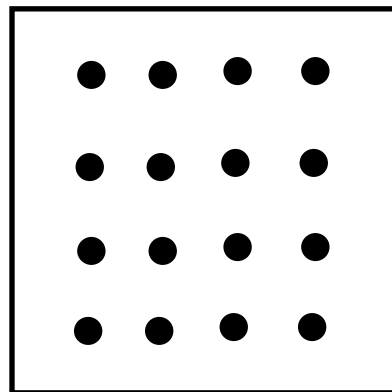


# Antialiasing Techniques

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e.g. procedurally defined geometry or textures
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# Uniform Supersampling

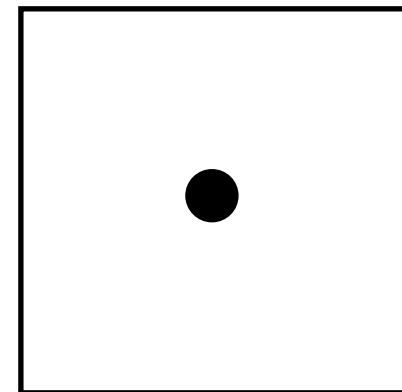
- Increasing the sampling rate moves each copy of the spectra further apart, potentially reducing the overlap and thus aliasing
- Resulting samples must be resampled (filtered) to image sampling rate



**Samples**

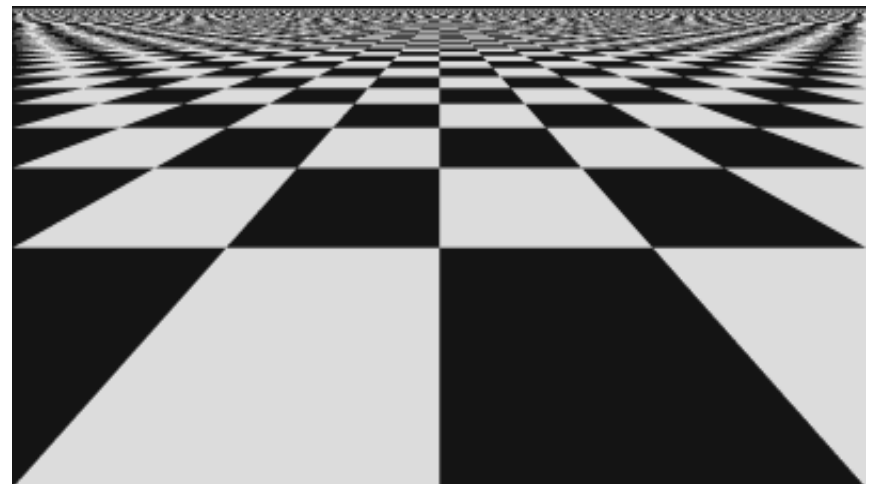
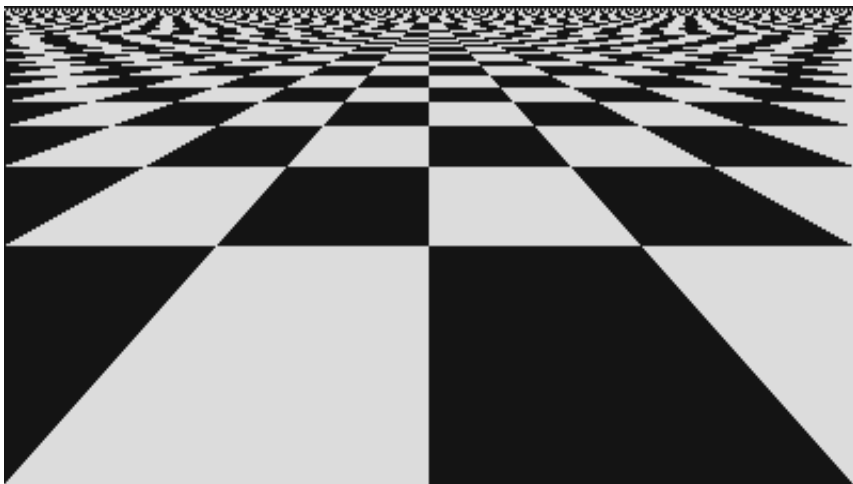
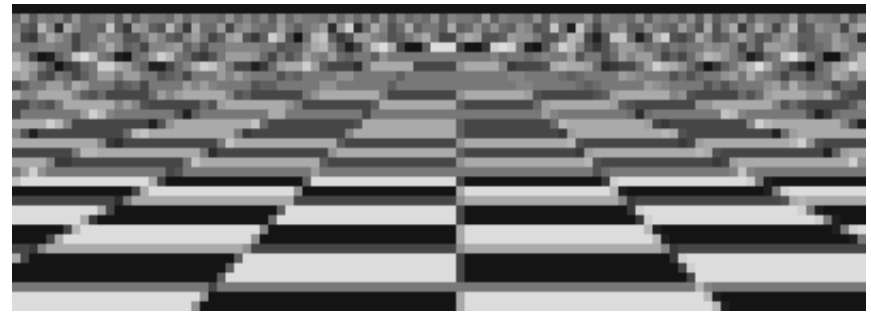
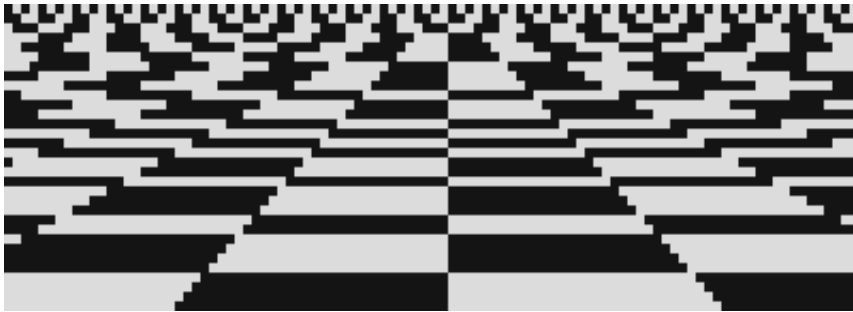
$$Pixel = \sum_s w_s \cdot Sample_s$$

resampling filter evaluated  
at the sample location



**Pixel**

# Point vs. Supersampled

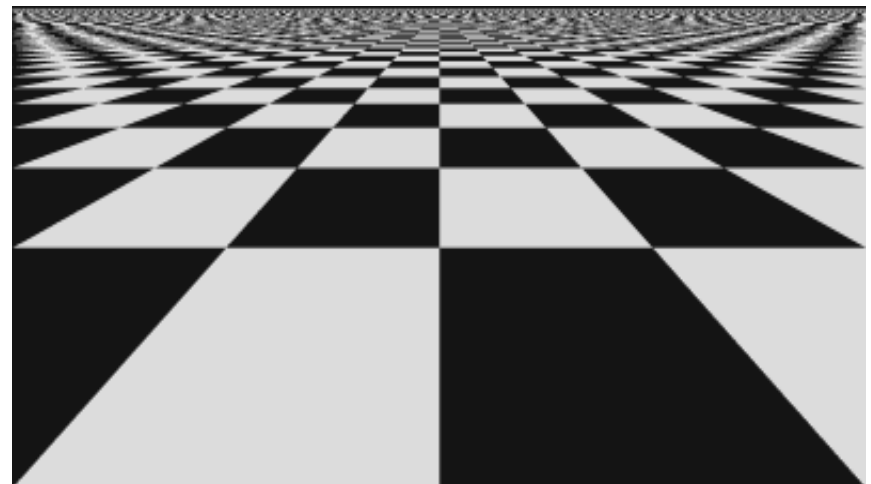
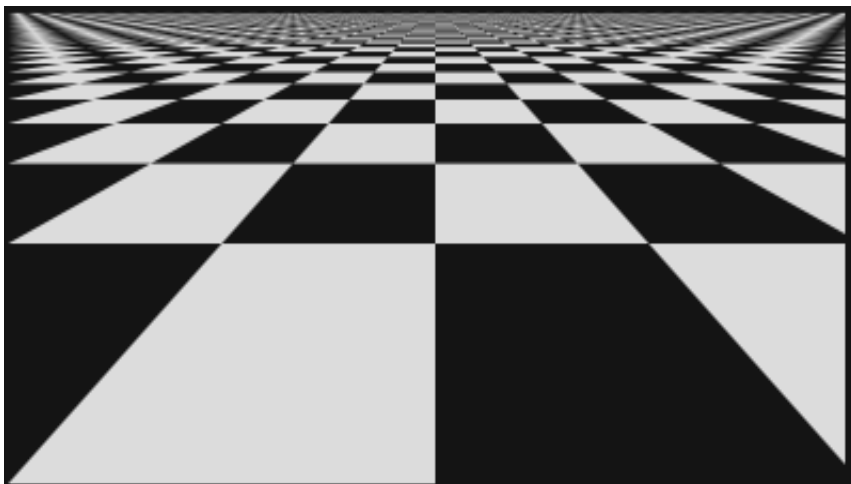
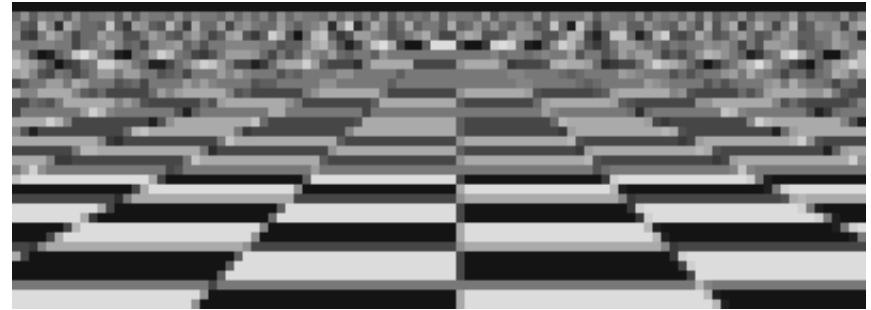
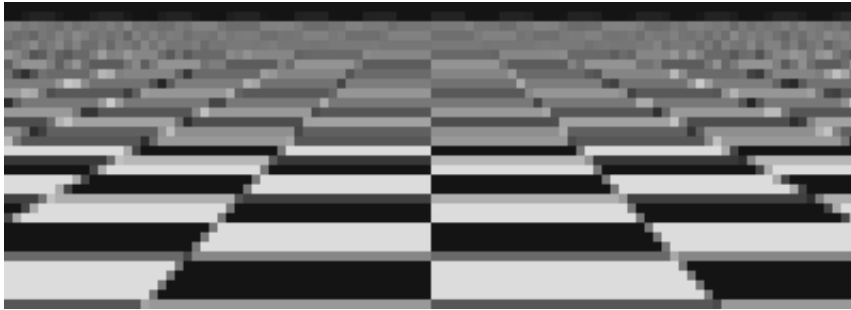


**Point**

**4x4 Supersampled**

Checkerboard sequence by Tom Duff

# Analytic vs. Supersampled



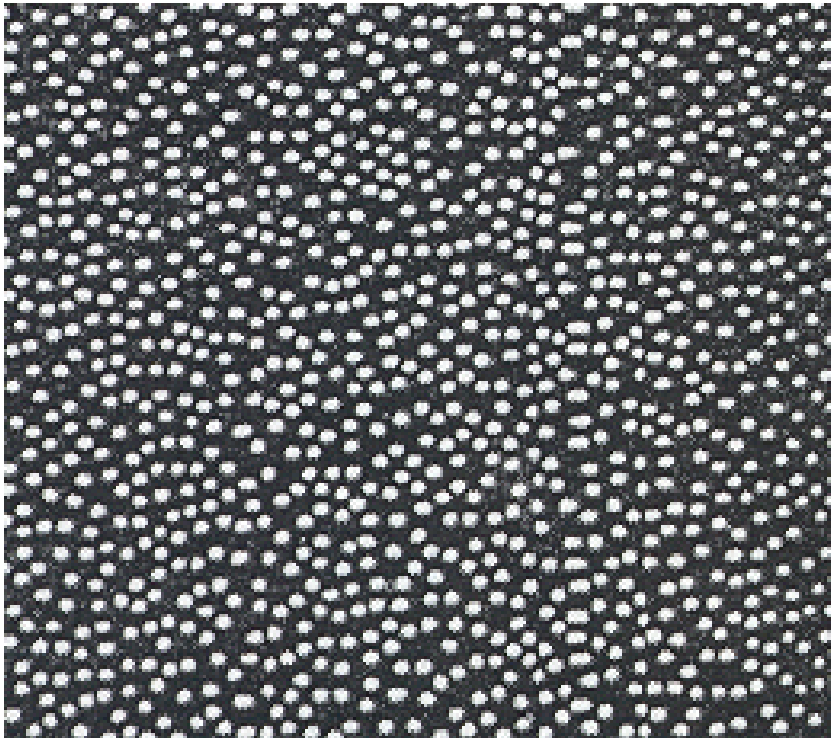
**Exact Area**

**4x4 Supersampled**

# Antialiasing Techniques

- Antialiasing = Preventing aliasing
- 1. Analytically prefilter the signal
  - Solvable for points, lines, polygons and **image textures**
  - Not solvable in general
    - e.g. procedurally defined geometry or textures
- 2. Uniform supersampling and resample
- 3. **Nonuniform or stochastic sampling**

# Distribution of Extrafoveal Cones



Monkey eye  
cone distribution

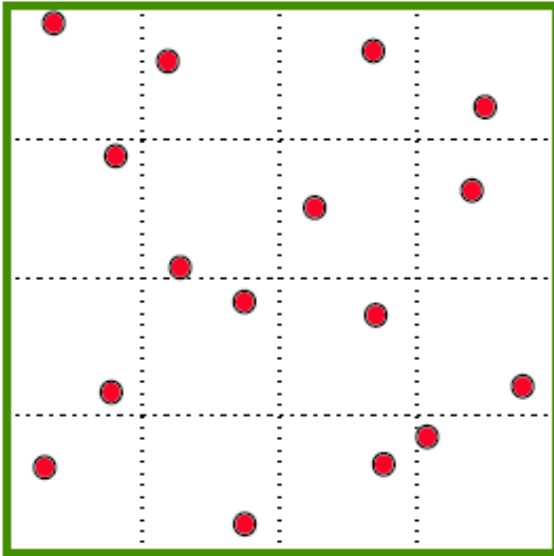


Fourier transform

## Yellot theory

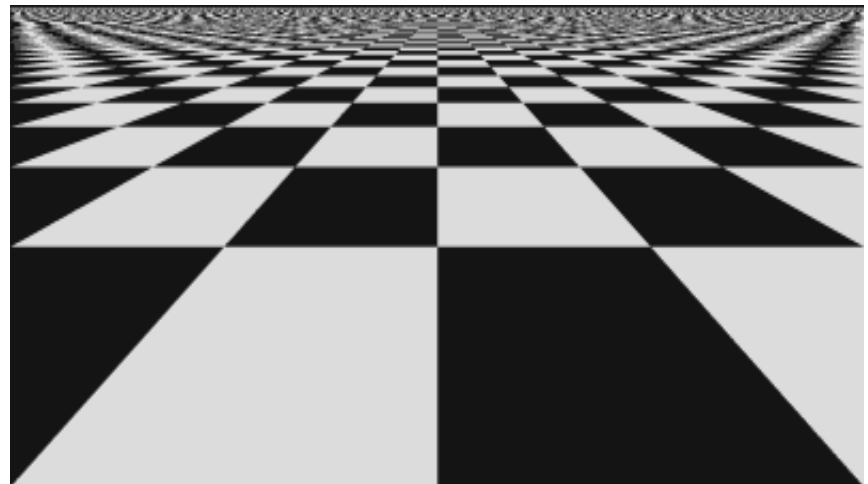
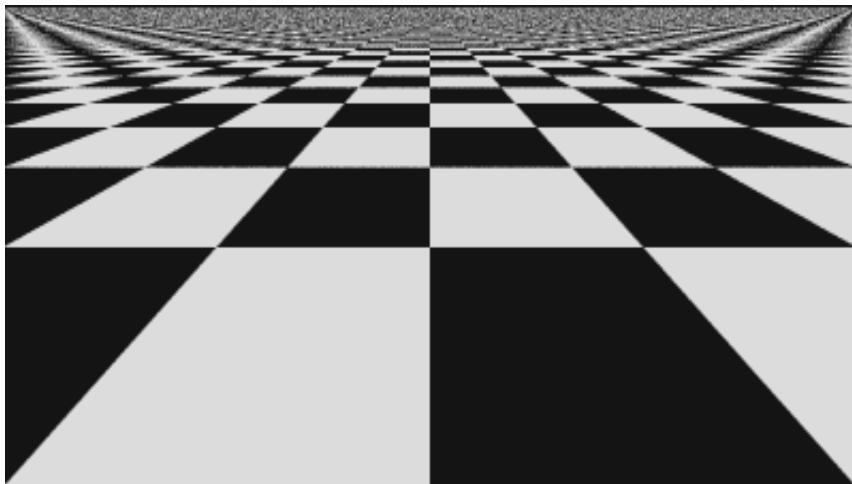
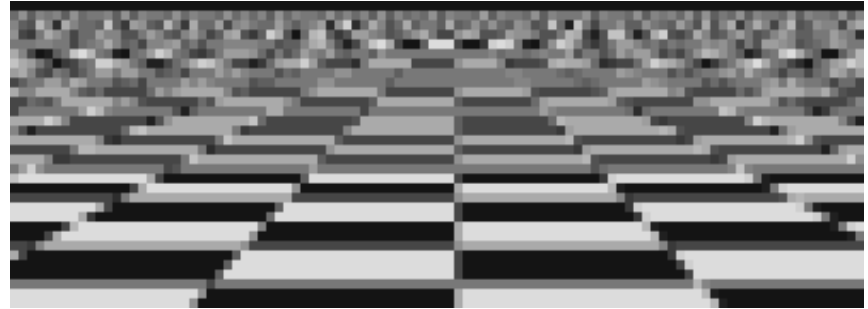
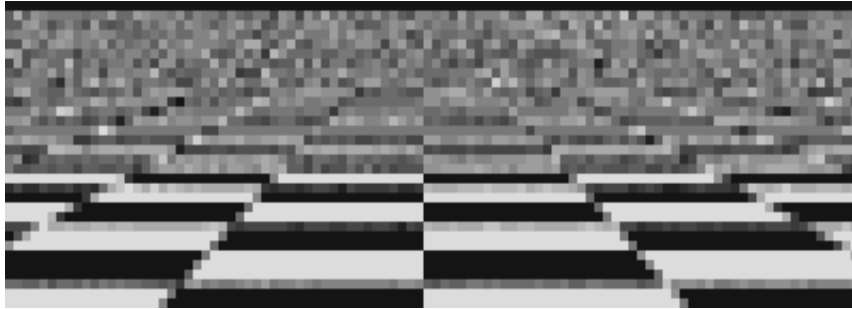
- Aliases replaced by noise
- Visual system less sensitive to high freq noise

# Jittering



- Jittering = stratified sampling on a grid
- Prevents clustering of random points
- Better sample distribution than pure random sampling
- However, clusters of up to four points can appear in 2D!

# Jittered vs. Uniform Supersampling

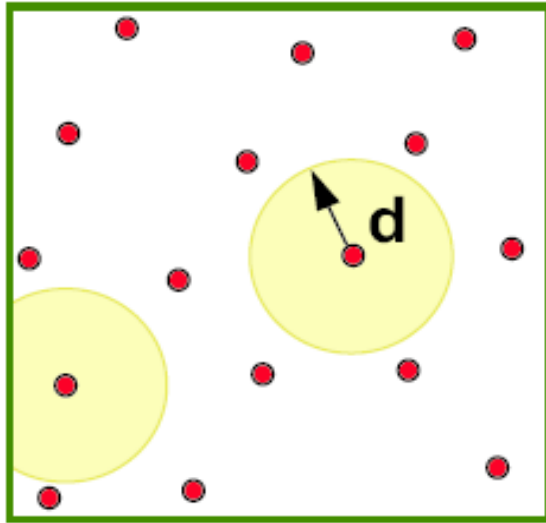


**4x4 Jittered Sampling**

**4x4 Uniform**



# Poisson Disk Sampling



- Gives by far the best quality for image sampling
- No sample closer to any other than a specified threshold  $d$
- Prevents sample clumping – better than jittering
- Efficient implementation did not exist for long time
- Common approach
  - Precompute pattern for a block of  $N \times N$  pixels
  - Reuse a randomly rotated version of the pattern

# Implementation of Poisson Disk Sampling

- Dart Throwing
  1. Create Candidates Randomly
  2. Discard if too close to an existing point
  - Extremely slow
  - Problem. How to set  $d$  for a desired number of points?
- Best Candidate Sampling (Mitchell)
  - Generates the pattern progressively
    1. Choose first sample randomly
    2. To generate  $(k+1)$ -th sample
      - generate  $k \cdot q$  independent candidates
      - choose one farthest from the  $k$  existing samples
  - Bigger  $q$   $\rightarrow$  better pattern quality

# Implementation of Poisson Disk Sampling – Recent Advances

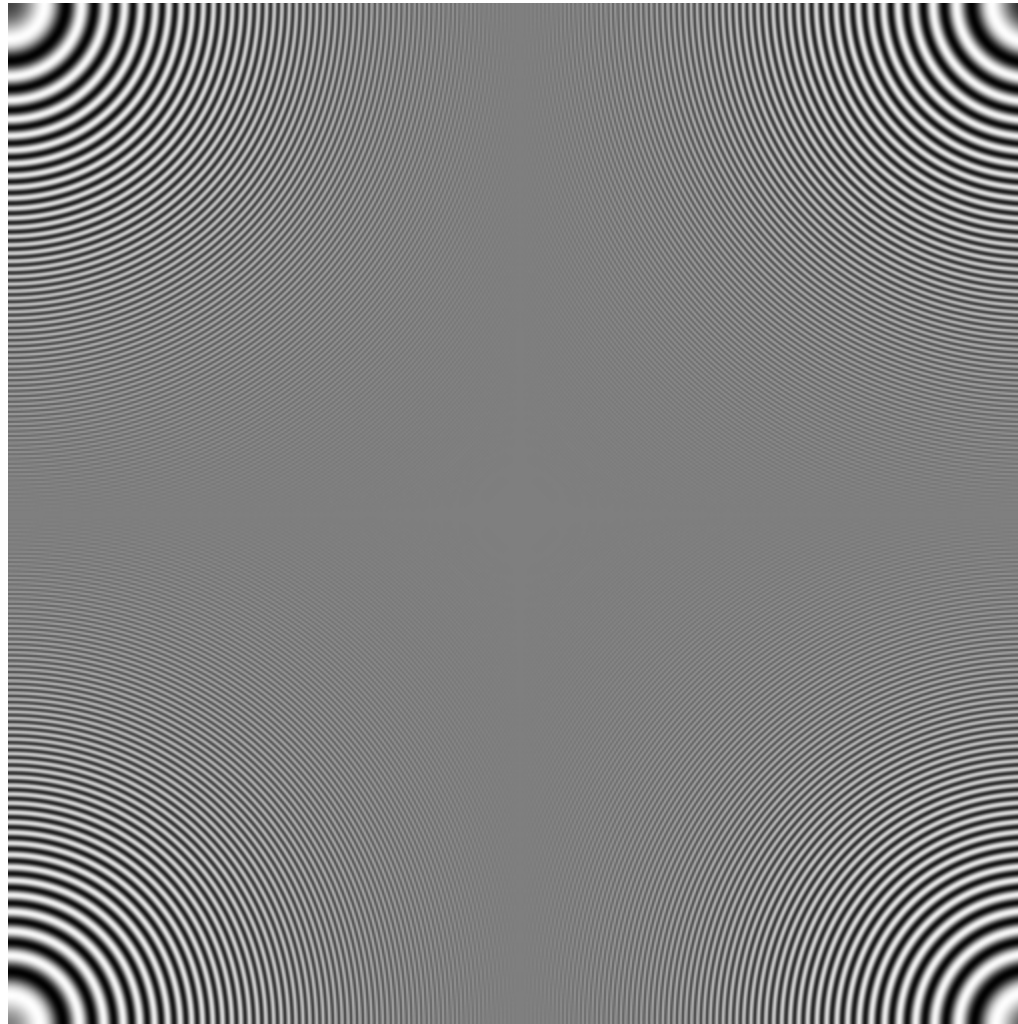
- Kopf et al. Recursive Wang Tiles for Real-Time Blue Noise, SIGGRAPH 2006.
- Dunbar and Humphreys. A spatial Data Structure for Fast Poisson-Disk Generation. SIGGRAPH 2006
- see videos at
  - [http://johanneskopf.de/publications/blue\\_noise/](http://johanneskopf.de/publications/blue_noise/)
  - <http://www.cs.virginia.edu/~gfx/pubs/antimony/>

# Various Sampling Patterns



Reference Image  
"Zone Plate"  
1,048,576 random samples/pixel

# Various Sampling Patterns

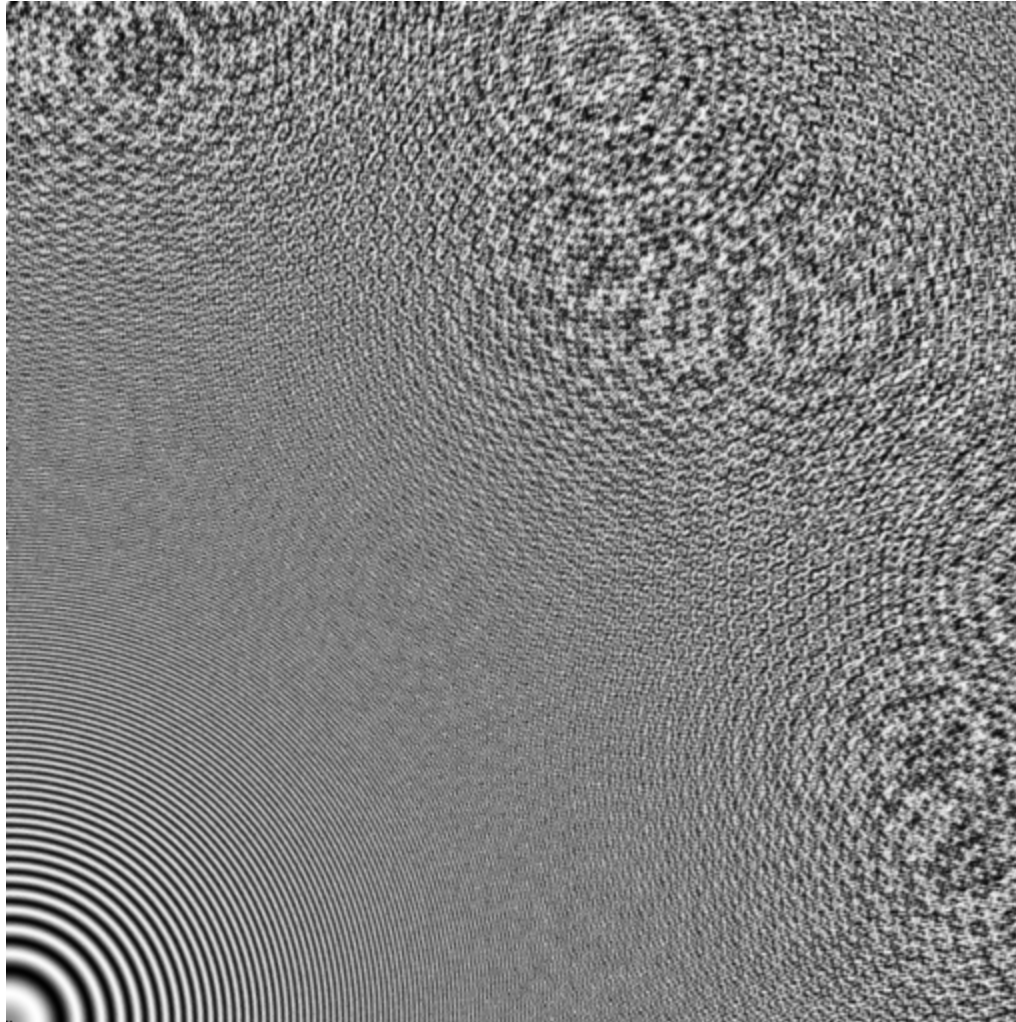


Rectilinear, 1 sample/pixel

RMS: -8.154799 dB

Pattern Generation: 17ms

# Various Sampling Patterns

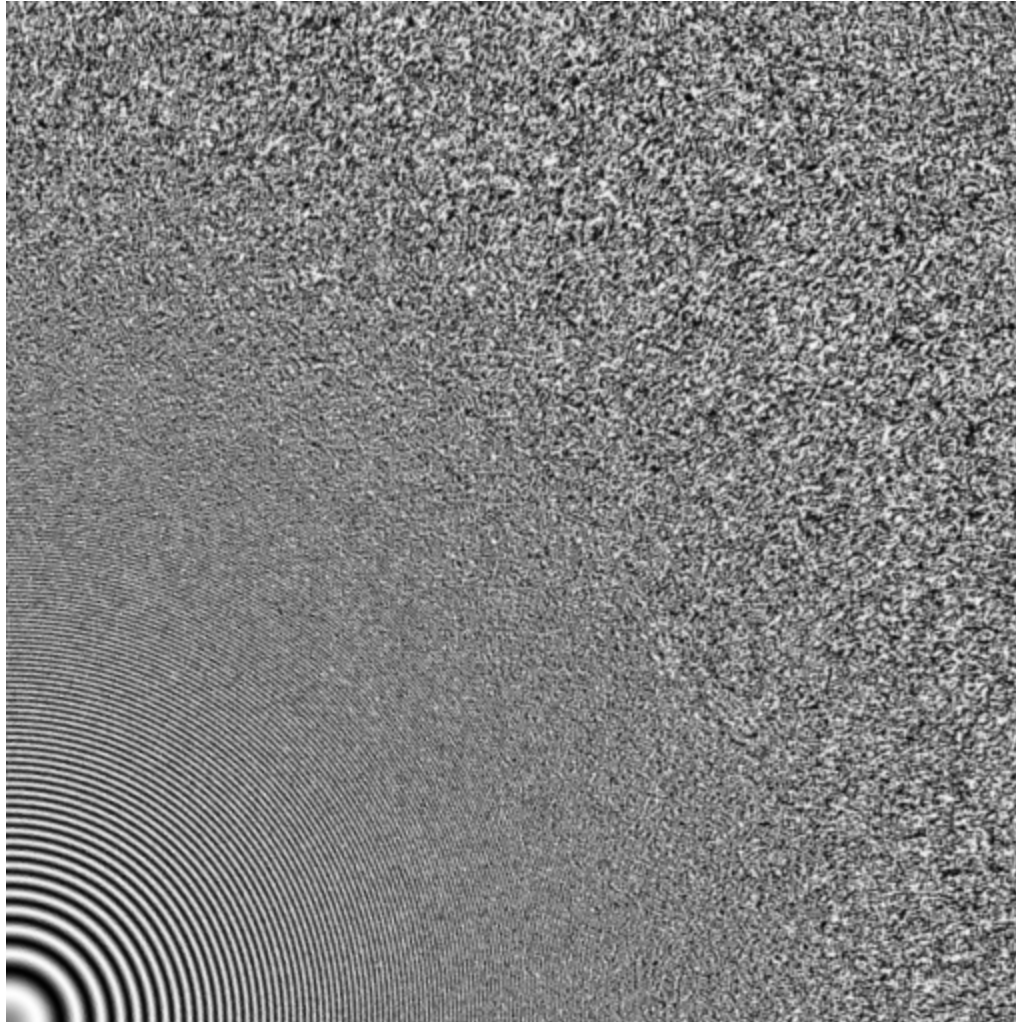


Jittered Grid, 1 sample/pixel

RMS: -8.121792 dB

Pattern Generation: 25ms

# Various Sampling Patterns



Kopf – Poisson disk, 1 sample/pixel  
RMS: -8.246348 dB  
Pattern Generation: 17ms

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# Conclusion

- Alias makes images ugly
- Rendering software **must** take care of antialiasing in order to produce compelling images without visible artifacts
- Signal analysis in Frequency domain explains aliasing and suggests antialiasing solutions
- Most common antialiasing techniques in graphics are
  - Pre-filtering
  - Supersampling (regular / stochastic)