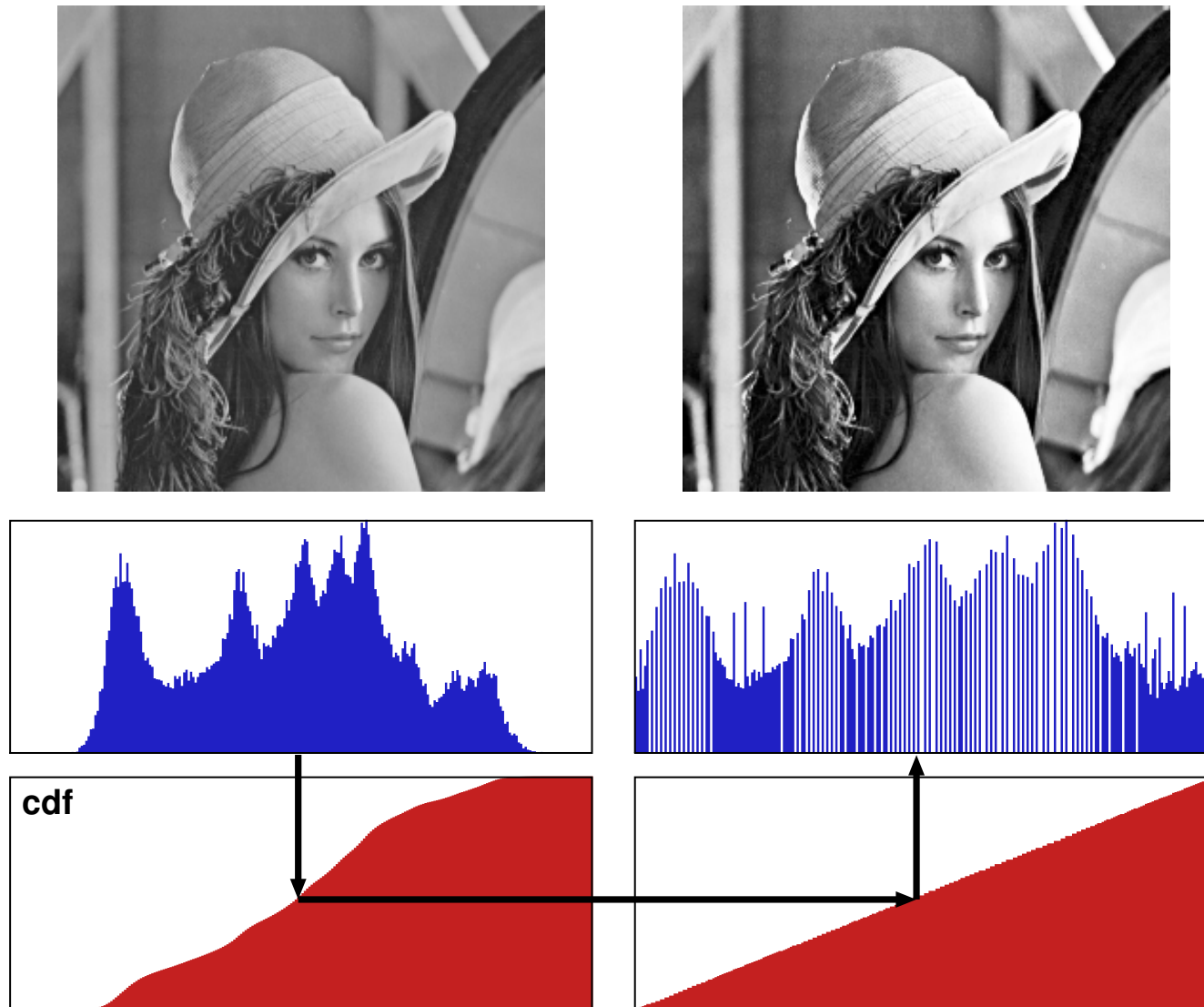


# Mid Term Recap

December 4, 2024

**Equalization:**  $T(l) = \text{cdf}(l) = \sum_{i=0}^l \text{pdf}(i)$



# Equalization

$I$



$I < T_{0.1}$   
 $I_{eq} < 0.1$



$I < T_{0.3}$   
 $I_{eq} < 0.3$



$I < T_{0.5}$   
 $I_{eq} < 0.5$



$I < T_{0.7}$   
 $I_{eq} < 0.7$



$I < T_{0.9}$   
 $I_{eq} < 0.9$



# Equalization

$I$



$I < 0.21$

$I_{eq} < 0.1$



$I < 0.39$

$I_{eq} < 0.3$



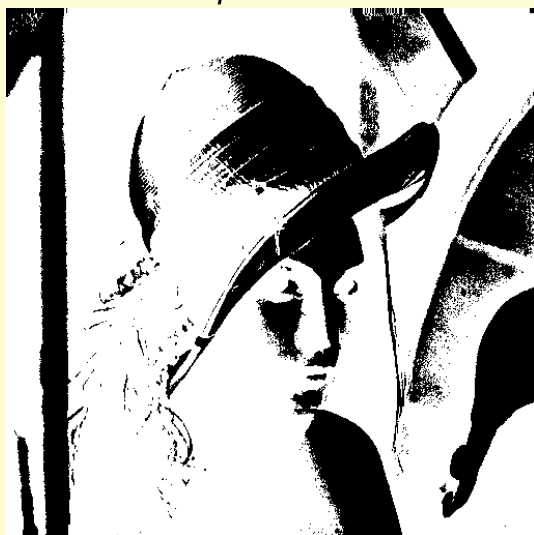
$I < 0.51$

$I_{eq} < 0.5$



$I < 0.60$

$I_{eq} < 0.7$

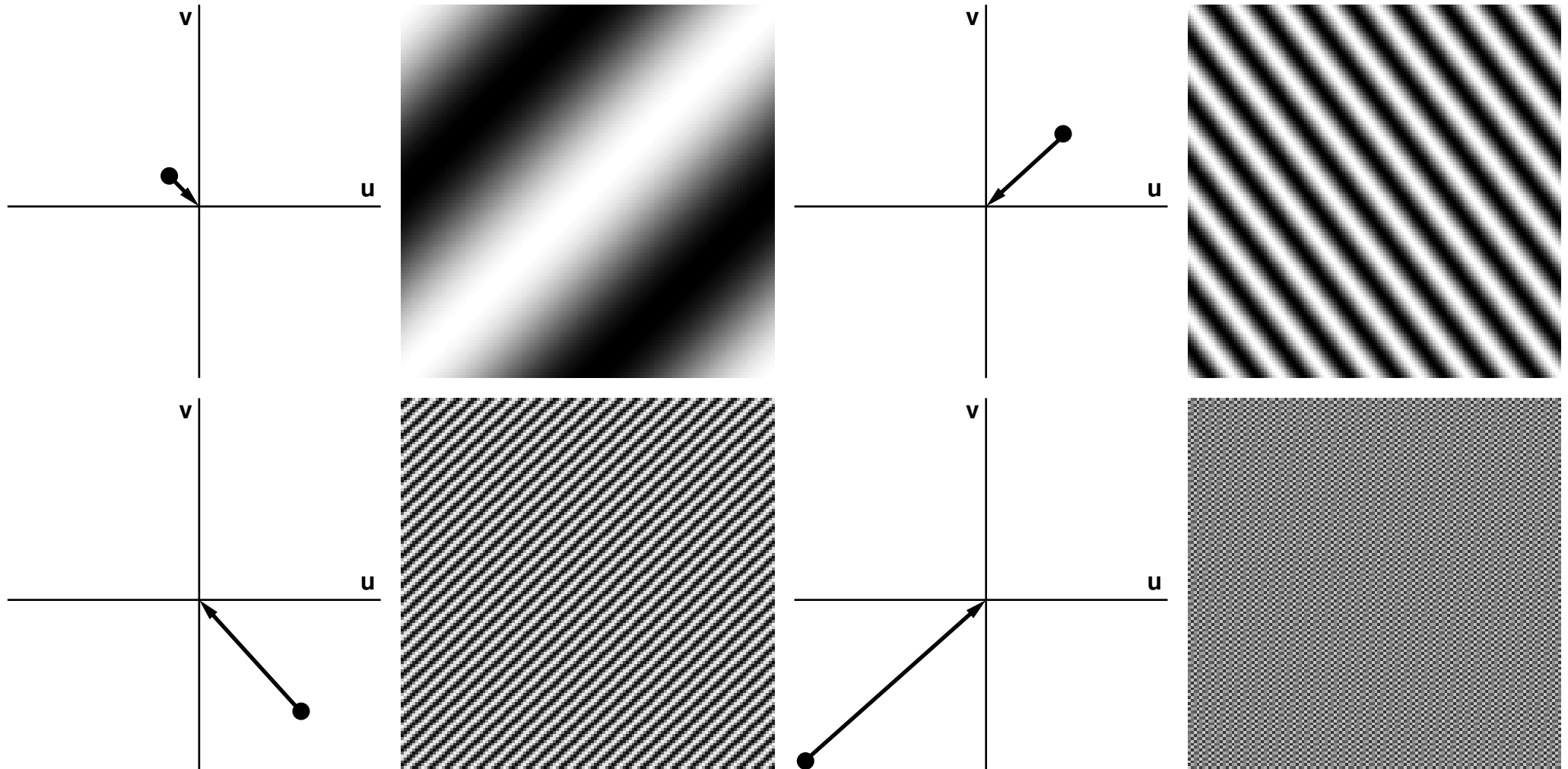


$I < 0.75$

$I_{eq} < 0.9$



basis functions:



# Fourier Basis (in 1D)

$$\phi_k[n] = e^{-i\frac{2\pi kn}{N}}, \quad n, k = 0, 1, \dots, N-1, \quad (1)$$

- ▶  $k$  is the frequency index,
- ▶  $n$  is the time sample index,
- ▶  $N$  is the total number of samples.

Dot product:

$$\langle \phi_k, \phi_m \rangle = \sum_{n=0}^{N-1} \phi_k[n] \phi_m^*[n] = \sum_{n=0}^{N-1} e^{-i\frac{2\pi kn}{N}} e^{i\frac{2\pi mn}{N}} \quad (2)$$

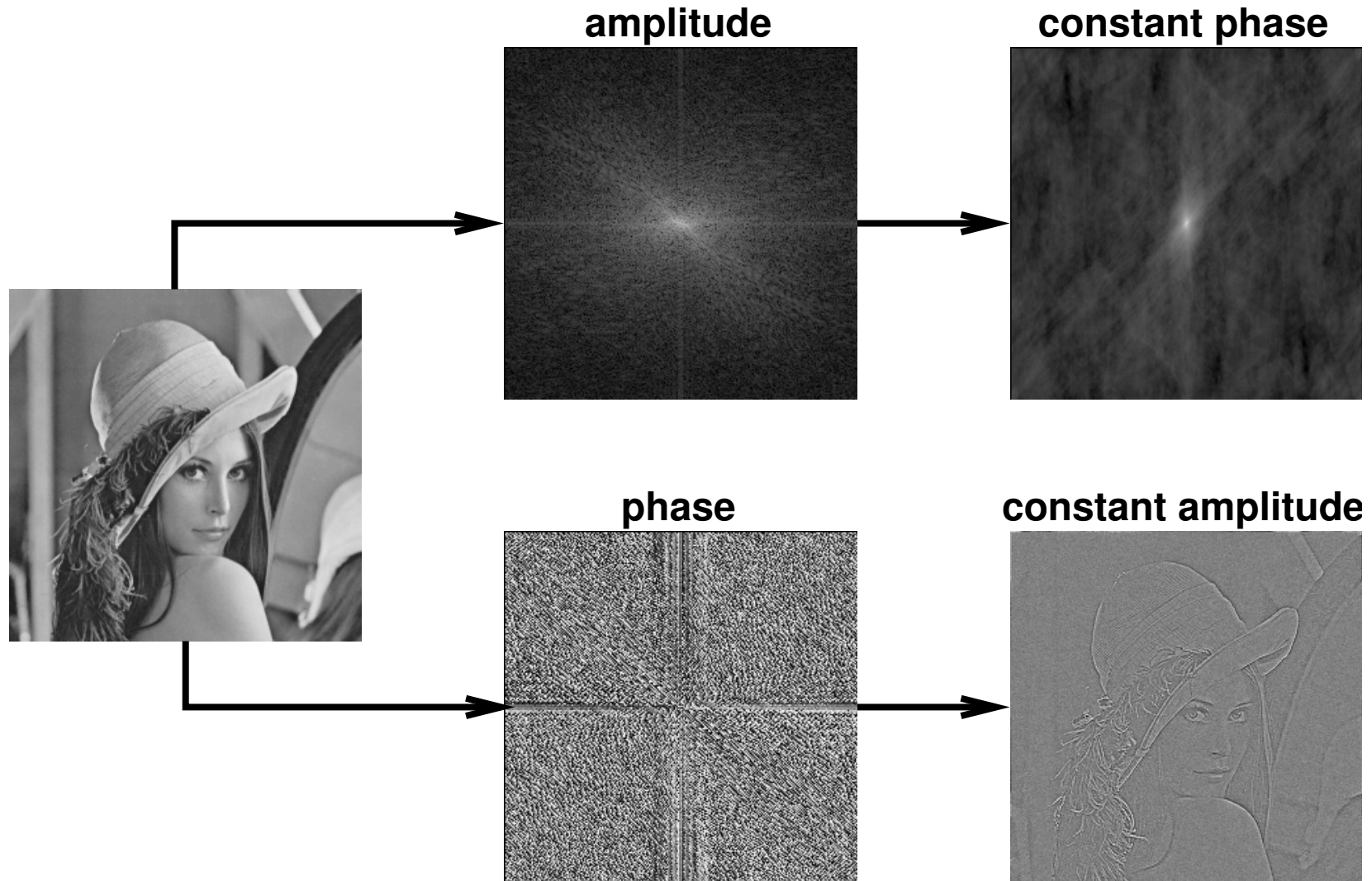
The Fourier Basis is orthogonal:

$$\langle \phi_k, \phi_m \rangle = \begin{cases} N, & \text{if } k = m, \\ 0, & \text{if } k \neq m. \end{cases} \quad (3)$$

Edges with orientation  $\arctan(v/u)$  and frequency  $\sqrt{u^2 + v^2}$ :

**Amplitude**  $\Rightarrow$  intensity

**Phase**  $\Rightarrow$  “location”



# Phase (only)

Let us keep the original phase only, and replace the amplitude by  $A = f^{-\beta}$ ,  $f = \sqrt{u^2 + v^2}$ :

$\beta = 0$



$\beta = 0.4$



$\beta = 0.8$



$\beta = 1$



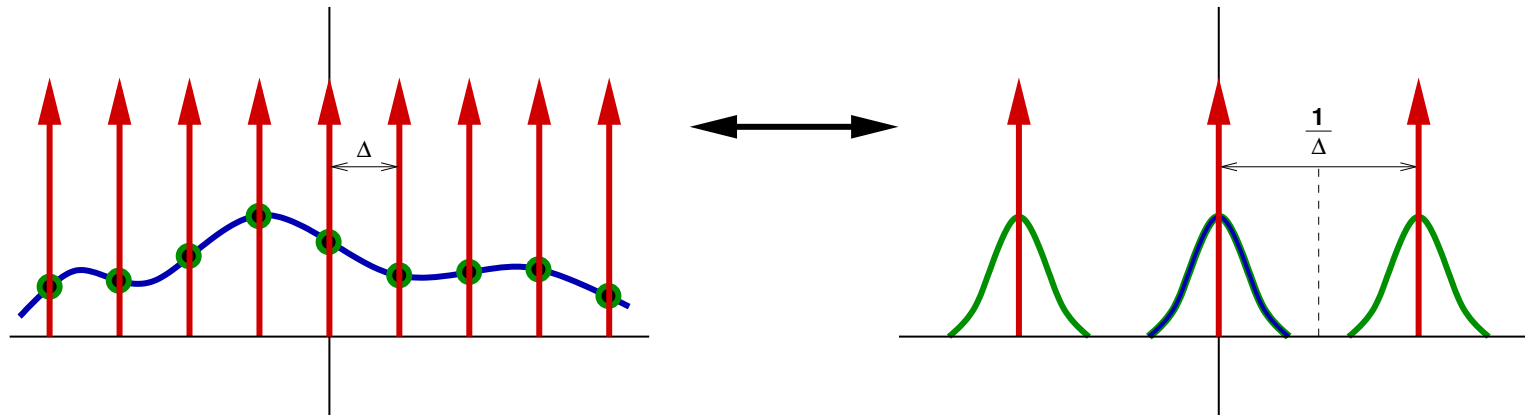
$\beta = 1.5$



$\beta = 2$

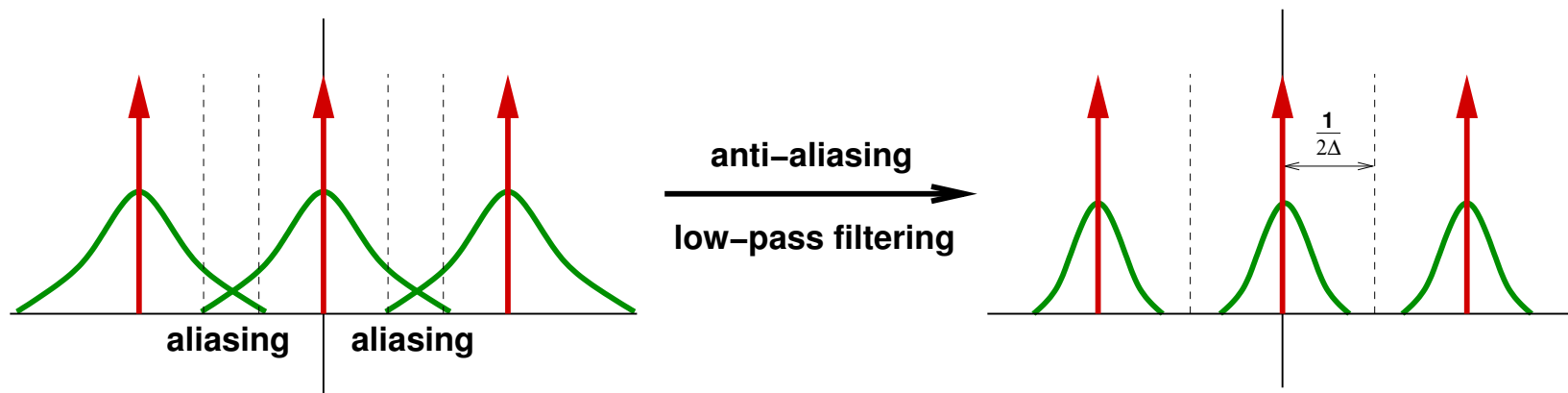


Nyquist frequency:  $f_{max} \leq \frac{1}{2\Delta}$



$$s(x) = \sum_k \delta(x - k\Delta) \iff S(u) = \sum_k \delta\left(u - \frac{k}{\Delta}\right)$$

$$d(x) = f(x) \cdot s(x) \iff D(u) = (F * S)(u)$$



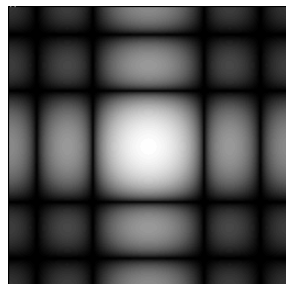
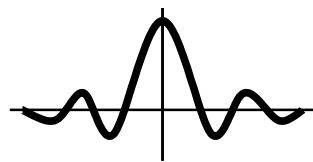
# Sampling theorem

- ▶ What can I do if sampling rate was too low?
- ▶ How about if I have a modulated signal? (e.g. FM radio)

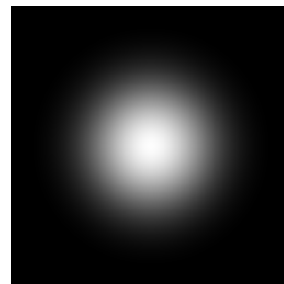
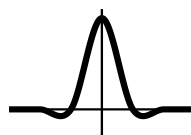
**Problem:** convolution with **sinc**  $\Rightarrow$  time consuming, ringing artifacts.

**Sinc** approximations with narrow support (bicubic, bilinear, box):

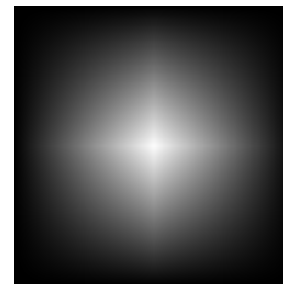
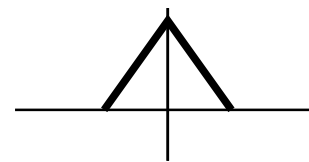
sinc



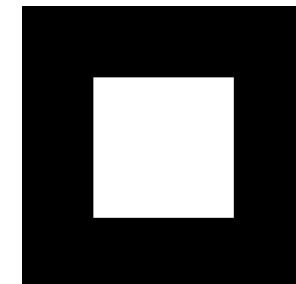
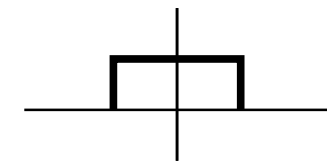
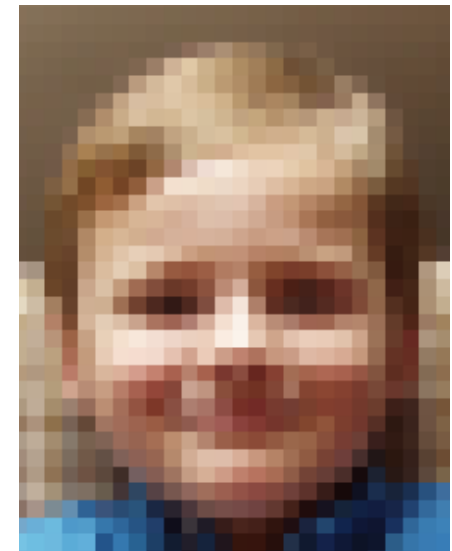
bicubic



bilinear



box

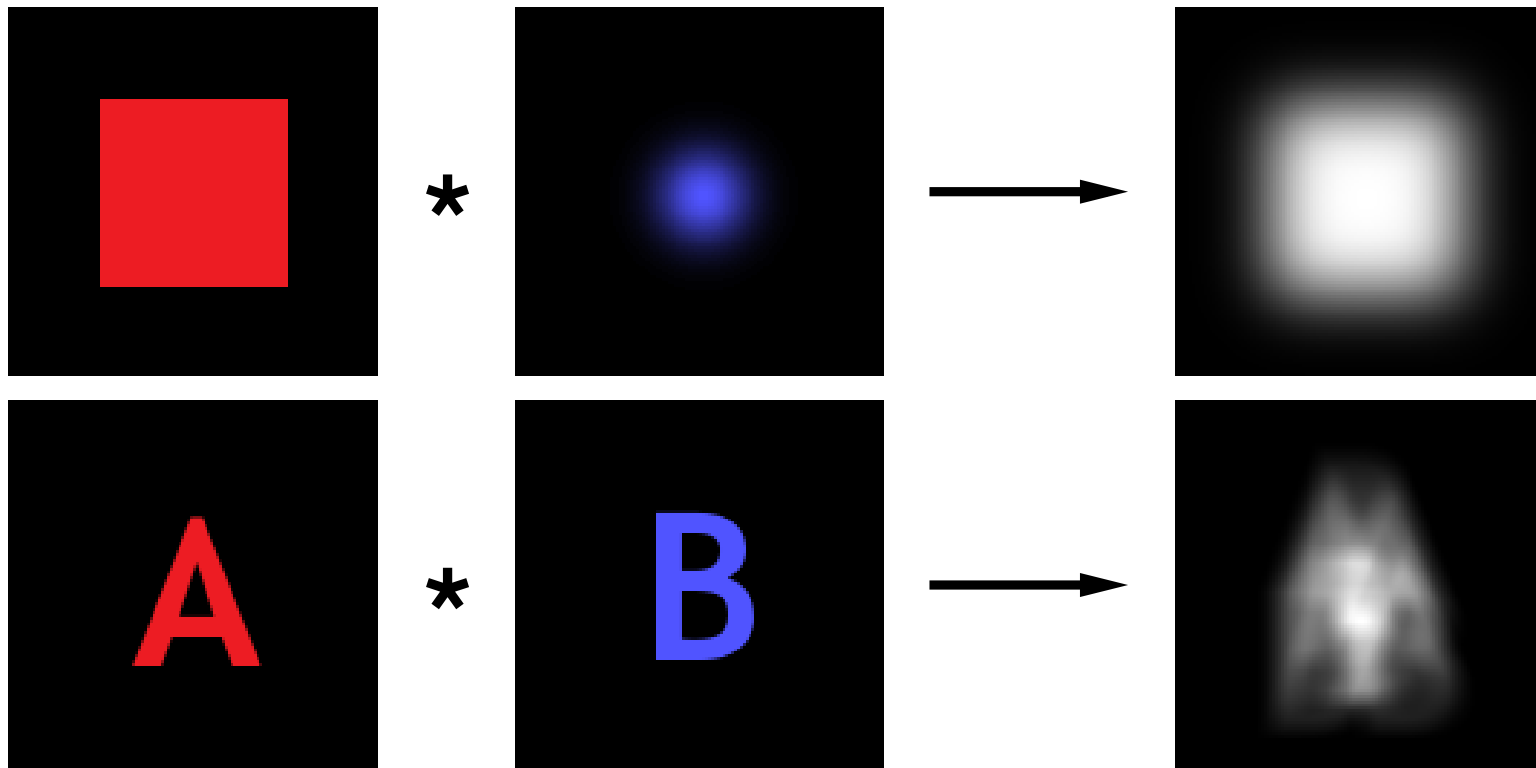


# Interpolation

- ▶ Does 2D nearest neighbor interpolation (box kernel) produce a result which is piecewise constant?
- ▶ Does (2D) bilinear interpolation (pyramid kernel) produce a result which is piecewise linear ( $r = ax + by + c$ )?

Extension of 1D case (image  $F$ , convolution kernel  $G$ ):

$$(F * G)(s, t) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(x, y) \cdot G(s - x, t - y) dx dy$$



# (Blackboard example – Computing convolution)

**Problem:** image  $f$  is also degraded by unknown additive noise  $n$ .

$$g = h * f + n \iff G = H \cdot F + N \Rightarrow F = (G - N)/H$$

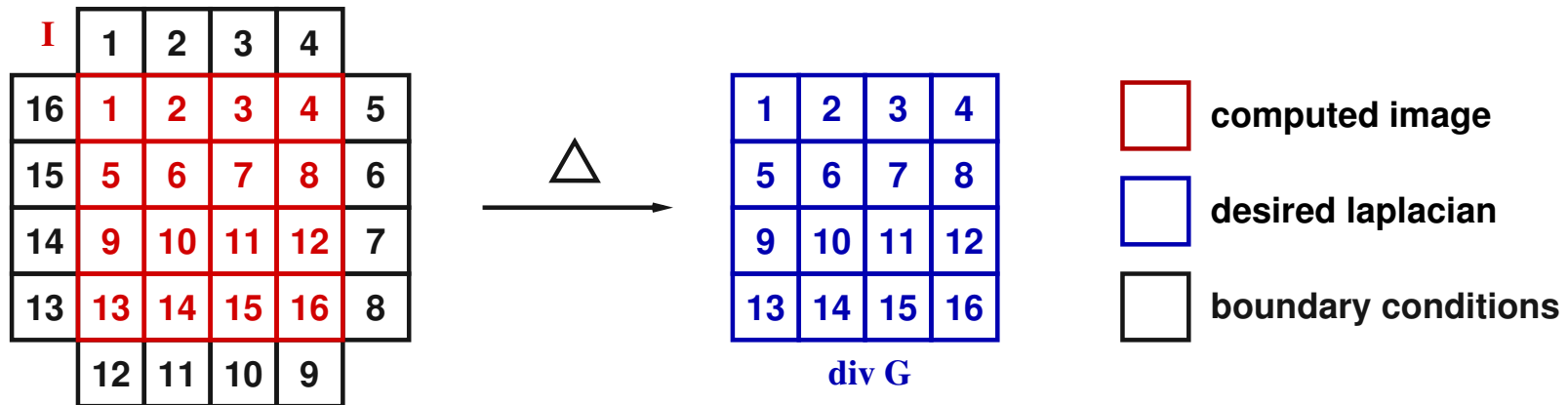
**Solution:** find an image  $\hat{f}$  such that  $\|f - \hat{f}\|^2$  is minimal.

$$\hat{F}(u, v) = \frac{H^*(u, v) \cdot G(u, v)}{\|H(u, v)\|^2 + \lambda} \quad \lambda = \text{SNR}^{-1} = \frac{\|N(u, v)\|^2}{\|F(u, v)\|^2}$$



(Matlab demo)

## Discretization of Poisson equation:



	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
--	---	---	---	---	---	---	---	---	---	----	----	----	----	----	----	----

-4	1			1												
1	-4	1			1											
	1	-4	1			1										
		1	-4				1									
1				-4	1			1								
	1			1	-4	1			1							
		1		1	-4	1				1						
			1		1	-4					1					

1	=	1	-	1	-	16
2	=	2	-	2		
3	=	3	-	3		
4	=	4	-	4	-	5
5	=	5	-	15		
6	=	6				
7	=	7				
8	=	8	-	6		

(Matlab demo and discussion)