

Digital Image

(B4M33DZO, Summer 2024)

Lecture 8:

Image Registration 1

<https://cw.fel.cvut.cz/wiki/courses/b4m33dzo/start>

Daniel Sýkora & Ondřej Drbohlav

Department of Cybernetics

Faculty of Electrical Engineering

Czech Technical University in Prague

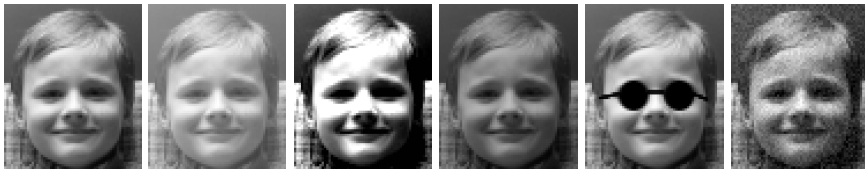
© Daniel Sýkora & Ondřej Drbohlav, 2024





Sum of absolute differences (SAD):

$$\sum_x \sum_y |\mathbf{A}[x, y] - \mathbf{B}[x, y]|$$



Sum of absolute differences (SAD): $\sum_x \sum_y |\mathbf{A}[x, y] - \mathbf{B}[x, y]|$

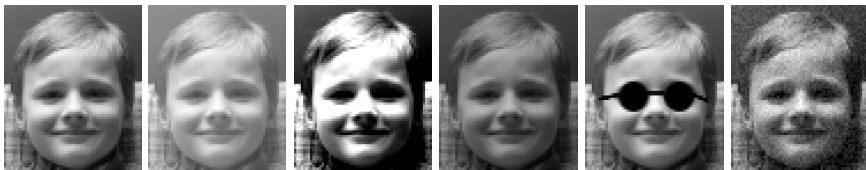
Sum of squared differences (SSD): $\sum_x \sum_y (\mathbf{A}[x, y] - \mathbf{B}[x, y])^2$



Sum of absolute differences (SAD): $\sum_x \sum_y |\mathbf{A}[x, y] - \mathbf{B}[x, y]|$

Sum of squared differences (SSD): $\sum_x \sum_y (\mathbf{A}[x, y] - \mathbf{B}[x, y])^2$

$$\sum_x \sum_y \mathbf{A}[x, y]^2 - 2 \cdot \mathbf{A}[x, y] \cdot \mathbf{B}[x, y] + \mathbf{B}[x, y]^2$$



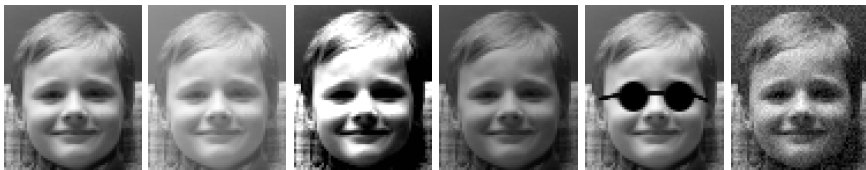
Sum of absolute differences (SAD):
$$\sum_x \sum_y |\mathbf{A}[x, y] - \mathbf{B}[x, y]|$$

Sum of squared differences (SSD):
$$\sum_x \sum_y (\mathbf{A}[x, y] - \mathbf{B}[x, y])^2$$

$$\sum_x \sum_y \mathbf{A}[x, y]^2 - 2 \cdot \underbrace{\mathbf{A}[x, y] \cdot \mathbf{B}[x, y]} + \mathbf{B}[x, y]^2$$

Cross-correlation:

$$\sum_x \sum_y \mathbf{A}(x, y) \cdot \mathbf{B}(x, y)$$



Sum of absolute differences (SAD):
$$\sum_x \sum_y |\mathbf{A}[x, y] - \mathbf{B}[x, y]|$$

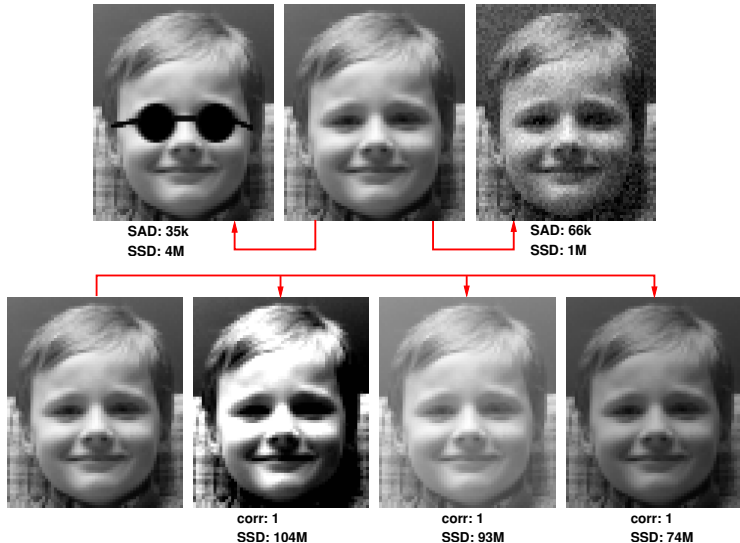
Sum of squared differences (SSD):
$$\sum_x \sum_y (\mathbf{A}[x, y] - \mathbf{B}[x, y])^2$$

$$\sum_x \sum_y \mathbf{A}[x, y]^2 - 2 \cdot \mathbf{A}[x, y] \cdot \mathbf{B}[x, y] + \mathbf{B}[x, y]^2$$

Normalized cross-correlation:

$$\frac{1}{\sigma_{\mathbf{A}} \sigma_{\mathbf{B}}} \sum_x \sum_y \left(\mathbf{A}(x, y) - \hat{\mathbf{A}} \right) \cdot \left(\mathbf{B}(x, y) - \hat{\mathbf{B}} \right)$$

(invariant to brightness & contrast changes)

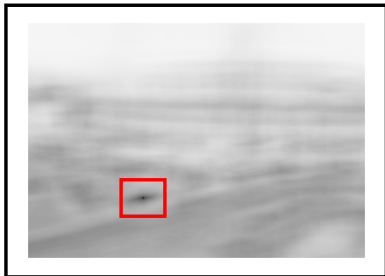
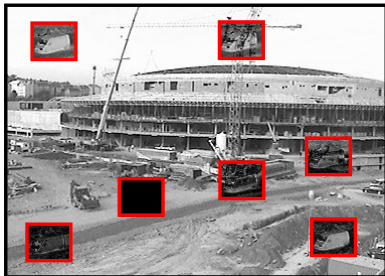


Minimize similarity metric \circ over all possible shifts:

$$\arg \min_{[s,t]} \sum_x \sum_y \mathbf{A}[x + s, y + t] \circ \mathbf{B}[x, y]$$

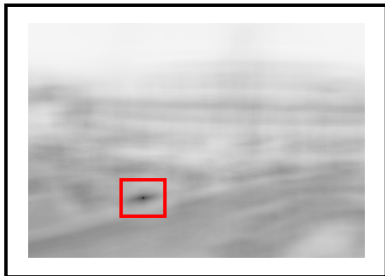
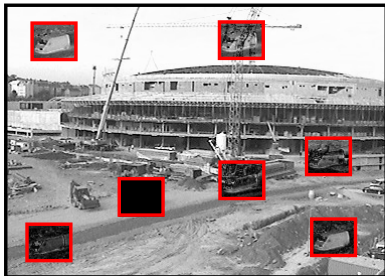
Minimize similarity metric \circ over all possible shifts:

$$\arg \min_{[s,t]} \sum_x \sum_y A[x+s, y+t] \circ B[x, y]$$



Minimize similarity metric \circ over all possible shifts:

$$\arg \min_{[s,t]} \sum_x \sum_y \mathbf{A}[x + s, y + t] \circ \mathbf{B}[x, y]$$



Problem: complexity of block matching is $\mathcal{O}(|\mathbf{A}| \cdot |\mathbf{B}|)$.

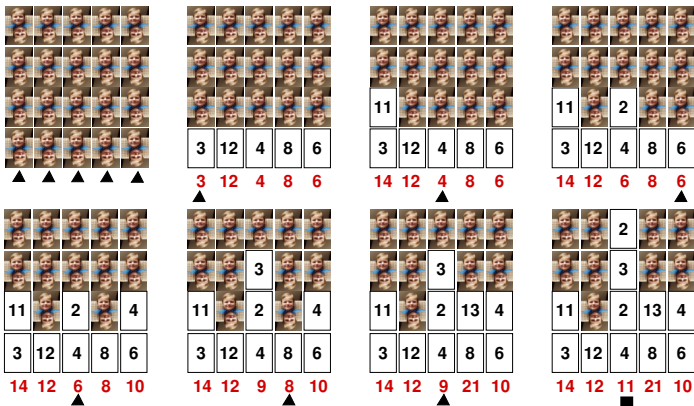
1. **Early termination** ($\mathcal{O}(|\mathbf{A}| \cdot |\mathbf{B}|)$, global minimum):

Compare current summation with the last best value.

1. Early termination ($\mathcal{O}(|\mathbf{A}| \cdot |\mathbf{B}|)$, global minimum):

Compare current summation with the last best value.

2. Winner-update strategy ($\mathcal{O}(|\mathbf{A}| \cdot |\mathbf{B}|)$, global minimum):

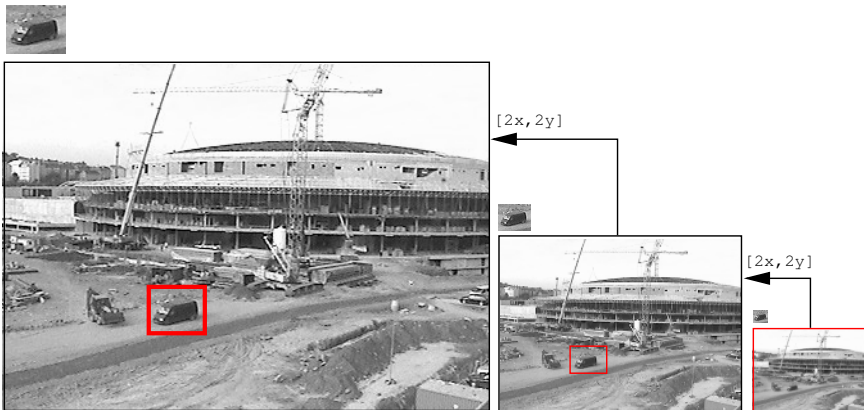


3. Hierarchical approach ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, local minimum):

Use reduced resolution to compute initial solution and refine.

3. Hierarchical approach ($\mathcal{O}(|A| \cdot \log |A|)$, local minimum):

Use reduced resolution to compute initial solution and refine.



4. SSD decomposition ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, global minimum):

$$\arg \min_{[s,t]} \sum_{x=0}^w \sum_{y=0}^h (\mathbf{A}[x+s, y+t] - \mathbf{B}[x, y])^2 =$$

4. SSD decomposition ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, global minimum):

$$\arg \min_{[s,t]} \sum_{x=0}^w \sum_{y=0}^h (\mathbf{A}[x+s, y+t] - \mathbf{B}[x, y])^2 =$$

$$\arg \min_{[s,t]} \left(\sum_{x=s}^{s+w} \sum_{y=t}^{t+h} \mathbf{A}[x, y]^2 - 2 \sum_{x=0}^w \sum_{y=0}^h \mathbf{A}[x+s, y+t] \cdot \mathbf{B}[x, y] \right)$$

4. SSD decomposition ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, global minimum):

$$\arg \min_{[s,t]} \sum_{x=0}^w \sum_{y=0}^h (\mathbf{A}[x+s, y+t] - \mathbf{B}[x, y])^2 =$$

$$\arg \min_{[s,t]} \left(\sum_{x=s}^{s+w} \sum_{y=t}^{t+h} \mathbf{A}[x, y]^2 - 2 \sum_{x=0}^w \sum_{y=0}^h \mathbf{A}[x+s, y+t] \cdot \mathbf{B}[x, y] \right)$$

Summed area table:

$$\sum_{x=s}^{s+w} \sum_{y=t}^{t+h} \mathbf{A}[x, y]^2 = \Sigma[s, t] - \Sigma[s+w, t] - \Sigma[s, t+h] + \Sigma[s+w, t+h]$$

4. SSD decomposition ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, global minimum):

$$\arg \min_{[s,t]} \sum_{x=0}^w \sum_{y=0}^h (\mathbf{A}[x+s, y+t] - \mathbf{B}[x, y])^2 =$$

$$\arg \min_{[s,t]} \left(\sum_{x=s}^{s+w} \sum_{y=t}^{t+h} \mathbf{A}[x, y]^2 - 2 \sum_{x=0}^w \sum_{y=0}^h \mathbf{A}[x+s, y+t] \cdot \mathbf{B}[x, y] \right)$$

Summed area table:

$$\sum_{x=s}^{s+w} \sum_{y=t}^{t+h} \mathbf{A}[x, y]^2 = \Sigma[s, t] - \Sigma[s+w, t] - \Sigma[s, t+h] + \Sigma[s+w, t+h]$$

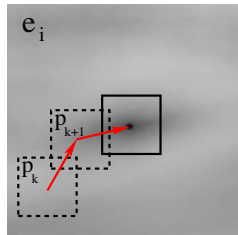
Fourier convolution theorem:

$$\sum_{x=0}^w \sum_{y=0}^h \mathbf{A}[x+s, y+t] \cdot \mathbf{B}[x, y] = \mathcal{F}^{-1} \{ \mathcal{F}\{\mathbf{A}\} \cdot \mathcal{F}\{\mathbf{B}^+\} \} [s, t]$$

5. Gradient descent ($\mathcal{O}(|\mathbf{B}|)$, local minimum):

We want to minimize:

$$E = \sum_i (\mathbf{A}[\mathbf{x}_i + \mathbf{t}] - \mathbf{B}[\mathbf{x}_i])^2 \Rightarrow E' = 0$$



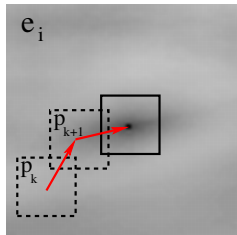
5. Gradient descent ($\mathcal{O}(|\mathbf{B}|)$, local minimum):

We want to minimize:

$$E = \sum_i (\mathbf{A}[\mathbf{x}_i + \mathbf{t}] - \mathbf{B}[\mathbf{x}_i])^2 \Rightarrow E' = 0$$

Using linear approximation:

$$\mathbf{A}[\mathbf{x}_i + \mathbf{t}] \approx \mathbf{A}[\mathbf{x}_i] + \frac{\partial}{\partial \mathbf{x}} \mathbf{A}[\mathbf{x}_i] \cdot \mathbf{t}$$



5. Gradient descent ($\mathcal{O}(|\mathbf{B}|)$, local minimum):

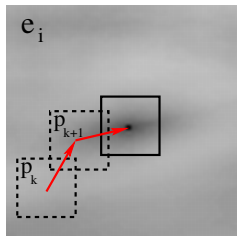
We want to minimize:

$$E = \sum_i (\mathbf{A}[\mathbf{x}_i + \mathbf{t}] - \mathbf{B}[\mathbf{x}_i])^2 \Rightarrow E' = 0$$

Using linear approximation:

$$\mathbf{A}[\mathbf{x}_i + \mathbf{t}] \approx \mathbf{A}[\mathbf{x}_i] + \frac{\partial}{\partial \mathbf{x}} \mathbf{A}[\mathbf{x}_i] \cdot \mathbf{t}$$

$$\mathbf{A}[\mathbf{x}_i] \rightarrow \mathbf{A}_i \quad \mathbf{B}[\mathbf{x}_i] \rightarrow \mathbf{B}_i \quad \frac{\partial}{\partial \mathbf{x}} \mathbf{A}_i \rightarrow \mathbf{A}'_i \quad \frac{\partial E}{\partial \mathbf{t}} \rightarrow E'$$



5. Gradient descent ($\mathcal{O}(|\mathbf{B}|)$, local minimum):

We want to minimize:

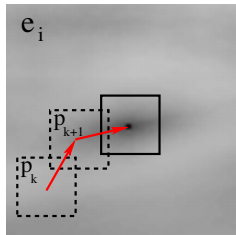
$$E = \sum_i (\mathbf{A}[\mathbf{x}_i + \mathbf{t}] - \mathbf{B}[\mathbf{x}_i])^2 \Rightarrow E' = 0$$

Using linear approximation:

$$\mathbf{A}[\mathbf{x}_i + \mathbf{t}] \approx \mathbf{A}[\mathbf{x}_i] + \frac{\partial}{\partial \mathbf{x}} \mathbf{A}[\mathbf{x}_i] \cdot \mathbf{t}$$

$$\mathbf{A}[\mathbf{x}_i] \rightarrow \mathbf{A}_i \quad \mathbf{B}[\mathbf{x}_i] \rightarrow \mathbf{B}_i \quad \frac{\partial}{\partial \mathbf{x}} \mathbf{A}_i \rightarrow \mathbf{A}'_i \quad \frac{\partial E}{\partial \mathbf{t}} \rightarrow E'$$

$$E' \approx \frac{\partial}{\partial \mathbf{t}} \sum_i (\mathbf{A}_i + \mathbf{A}'_i \mathbf{t} - \mathbf{B}_i)^2 = 2 \sum_i (\mathbf{A}'_i)^T (\mathbf{A}_i + \mathbf{A}'_i \mathbf{t} - \mathbf{B}_i) = 0$$



5. Gradient descent ($\mathcal{O}(|\mathbf{B}|)$, local minimum):

We want to minimize:

$$E = \sum_i (\mathbf{A}[\mathbf{x}_i + \mathbf{t}] - \mathbf{B}[\mathbf{x}_i])^2 \Rightarrow E' = 0$$

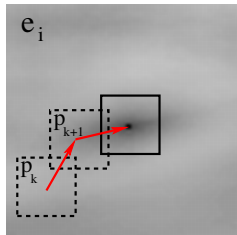
Using linear approximation:

$$\mathbf{A}[\mathbf{x}_i + \mathbf{t}] \approx \mathbf{A}[\mathbf{x}_i] + \frac{\partial}{\partial \mathbf{x}} \mathbf{A}[\mathbf{x}_i] \cdot \mathbf{t}$$

$$\mathbf{A}[\mathbf{x}_i] \rightarrow \mathbf{A}_i \quad \mathbf{B}[\mathbf{x}_i] \rightarrow \mathbf{B}_i \quad \frac{\partial}{\partial \mathbf{x}} \mathbf{A}_i \rightarrow \mathbf{A}'_i \quad \frac{\partial E}{\partial \mathbf{t}} \rightarrow E'$$

$$E' \approx \frac{\partial}{\partial \mathbf{t}} \sum_i (\mathbf{A}_i + \mathbf{A}'_i \mathbf{t} - \mathbf{B}_i)^2 = 2 \sum_i (\mathbf{A}'_i)^T (\mathbf{A}_i + \mathbf{A}'_i \mathbf{t} - \mathbf{B}_i) = 0$$

$$\mathbf{t} = \left(\sum_i (\mathbf{A}'_i)^T (\mathbf{A}'_i) \right)^{-1} \left(\sum_i (\mathbf{A}'_i)^T (\mathbf{B}_i - \mathbf{A}_i) \right)$$



Phase correlation ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, local minimum):

$$\mathbf{A}[x, y] * \delta(s, t) = \mathbf{B}[x, y] \iff \mathcal{A}[u, v] \cdot e^{2\pi i(us+vt)} = \mathcal{B}[u, v]$$

Phase correlation ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, local minimum):

$$\mathbf{A}[x, y] * \delta(s, t) = \mathbf{B}[x, y] \iff \mathcal{A}[u, v] \cdot e^{2\pi i(us+vt)} = \mathcal{B}[u, v]$$

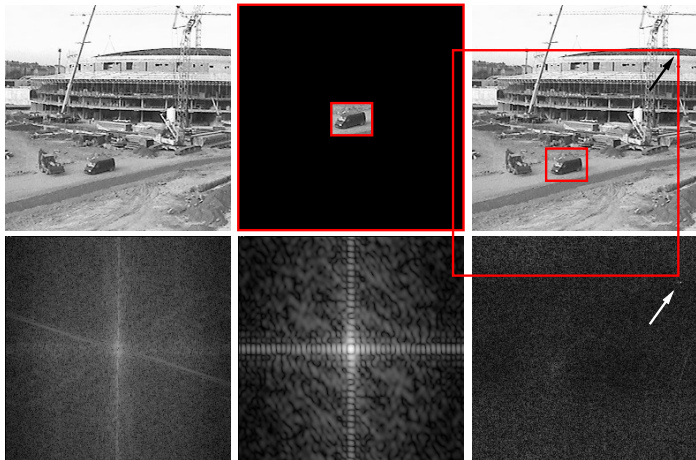
$$\frac{\mathcal{A}^*[u, v] \cdot \mathcal{B}[u, v]}{|\mathcal{A}[u, v]|^2} = e^{2\pi i(us+vt)} \implies \delta(s, t)$$

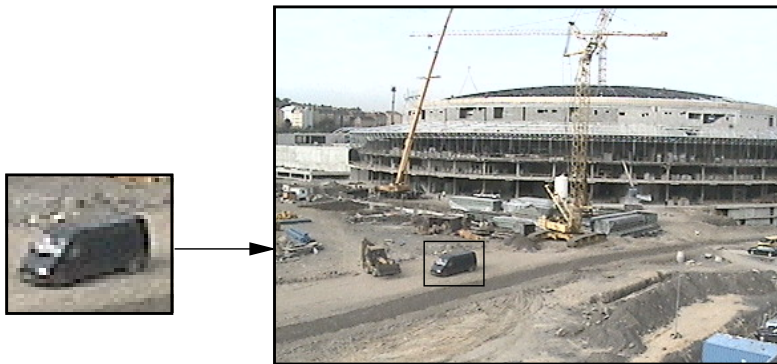
Phase correlation ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, local minimum):

$$\mathbf{A}[x, y] * \delta(s, t) = \mathbf{B}[x, y] \iff \mathcal{A}[u, v] \cdot e^{2\pi i(us+vt)} = \mathcal{B}[u, v]$$

$$\frac{\mathcal{A}^*[u, v] \cdot \mathcal{B}[u, v]}{|\mathcal{A}[u, v] \cdot \mathcal{B}[u, v]|} = e^{2\pi i(us+vt)} \implies \delta(s, t)$$

Phase correlation ($\mathcal{O}(|\mathbf{A}| \cdot \log |\mathbf{A}|)$, local minimum):



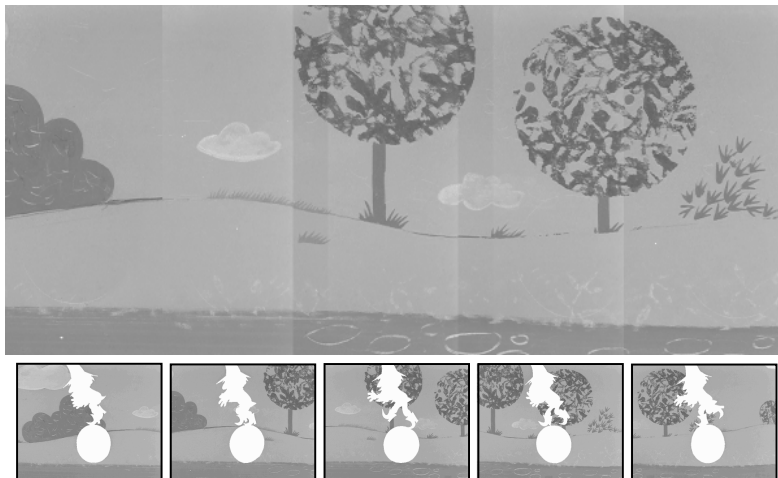


template matching, motion estimation, video compression, ...



stitching, stabilization, restoration, retrieval, . . .

Recovering background from occluded observations:



hole filling & texture synthesis

