

# Network Inference & Link Prediction

Network Application Diagnostics

B2M32DSA

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- 1 Preliminary Tools
  - Classification Evaluation
  - Network Terminology
- 2 Network Inference
  - Introduction
  - Network Inference Example - Viber
- 3 Link Prediction
  - Introduction
  - Scoring Functions

# Outline

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# Classification Predictions <sup>[Wik19a]</sup>

- **The expectation:** the terms *positive* and *negative* refer to the classifier's prediction.
- **The observation:** the terms *true* and *false* refer to whether that prediction corresponds to the external judgment.
- The confusion matrix (CZ kontingenční tabulka)

		Predicted / Classified	
		Negative	Positive
Actual	Negative	True Negative	False Positive
	Positive	False Negative	True Positive

- **TN / True Negative**

- the real case is negative
- and predicted negative

- **FP / False Positive**

- the real case is negative
- but predicted positive
- Type I error

- **TP / True Positive**

- the real case is positive
- and predicted as positive

- **FN / False Negative**

- the real case is positive
- but predicted negative
- Type II error



# Precision and Recall [Wik19a, ?]

## • Precision

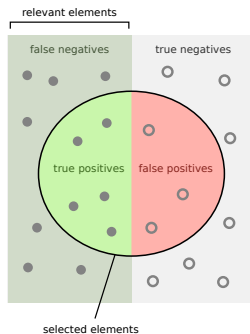
- the probability that a (randomly selected) retrieved document is relevant.
- the probability that a (randomly selected) object is correctly classified.

$$\text{Precision} = \frac{TP}{TP + FP}$$

## • Recall

- the probability that a (randomly selected) relevant document is retrieved in a search.
- the probability that a (randomly selected) class object is correctly classified.

$$\text{Recall} = \frac{TP}{TP + FN}$$



How many selected items are relevant?

$$\text{Precision} = \frac{\text{Green}}{\text{Green} + \text{Red}}$$

How many relevant items are selected?

$$\text{Recall} = \frac{\text{Green}}{\text{Green} + \text{White}}$$

# Accuracy and F1-Measure <sup>[Wik19a, ?]</sup>

## • Accuracy

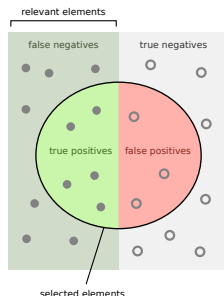
- the proportion of true results (both true positives and true negatives) among the total number of cases examined.

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN}$$

## • F1-Measure

- the harmonic mean of precision and recall.
- an  $F1$  score reaches its best value at 1 (perfect precision and recall) and worst at 0.

$$F1 = \left( \frac{\text{Precision}^{-1} + \text{Recall}^{-1}}{2} \right)^{-1} = \frac{2 \times \text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}}$$



How many selected items are relevant?

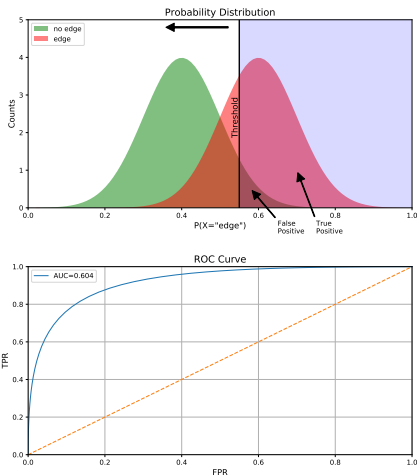
$$\text{Precision} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Positives}}$$

How many relevant items are selected?

$$\text{Recall} = \frac{\text{True Positives}}{\text{True Positives} + \text{False Negatives}}$$

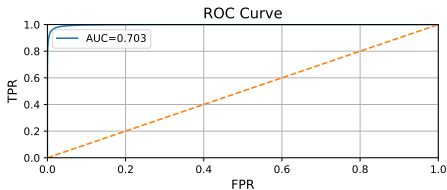
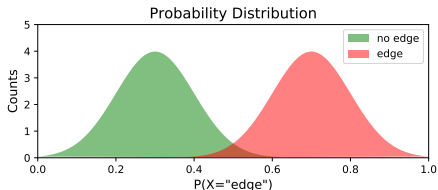
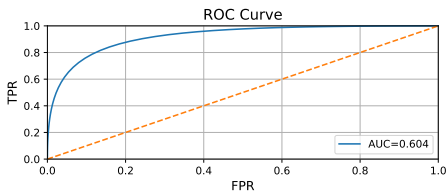
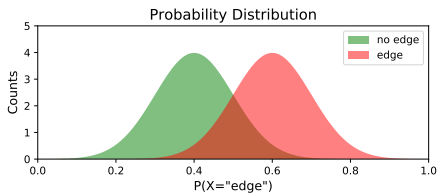
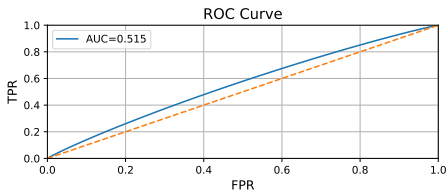
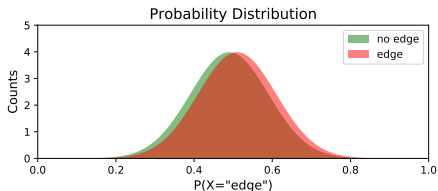
# ROC (Receiver Operating Characteristic) Curves <sup>[Wik19b]</sup>

- Plotting the true positive rate (TPR) against the false positive rate (FPR).
- Dealing with heavy class imbalance.
- The model performance is measured by the area under the ROC curve (AUC).
- The best possible AUC is 1.
- The worst AUC is 0.5 (the 45 degrees random line).
- If the AUC is below 0.5, do the exact opposite of what the model recommends.



$$TPR = \frac{TP}{TP + FN}, \quad FPR = \frac{FP}{FP + TN}$$

# ROC Performance Assessment [Wik19b]





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# Graph Notation <sup>[Kol09]</sup>

- Let  $G(V, E)$  be an undirected random network graph.
- $V^{(2)}$  is the set of distinct unordered pairs of vertices.
- $E$  is the set of edges in  $G$ .
- $N_v = |V|$  is the number of vertices.
- $N_e = |E|$  is the number of edges.
- $V^{(2)} \setminus E$  is the set of non-edges in  $G$ .
- $V_{obs}^{(2)}$  is the observed presence or absence of edges.
- $V_{miss}^{(2)} = V^{(2)} \setminus V_{obs}^{(2)}$  is the set of edges for which observations are missing.
- Sparse graph:  $|E| \ll |V|^2$
- The set  $\mathcal{N}(u)$  of neighbors of  $u \in V$  in  $G(V, E)$ :

$$\mathcal{N}(u) = \{v | v \in V, e = uv \in E\}$$



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# Network Topology Inference <sup>[Koi09]</sup>

- What should constitute a vertex and an edge is determined by user-specified decisions and rules.
- Such a network graph construction lacks an element of validation.
  - if the network representation is “accurate”,
    - i.e. capturing some well-defined but unobservable relational structure.
  - What accuracy can be expected given the available measurements?
  - Are there other similar representations with about the same accuracy?
  - How is the representation robust to changes in the measurements?
  - How is the representation useful for other purposes?

## Network Topology Inference Problem

- Given a set of measurements from a system of interest, e.g.
  - vertex attributes  $\mathbf{x} = (x_1, \dots, x_{N_V})$
  - binary indicators  $\mathbf{y} = [y_{ij}]$  of certain edges.
- and given a collection  $\mathcal{G}$  of potential graphs  $G$ ,
- select an appropriate member of  $\mathcal{G}$  that best captures the underlying state of the system.

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# Network Inference Problems <sup>[Koi09]</sup>

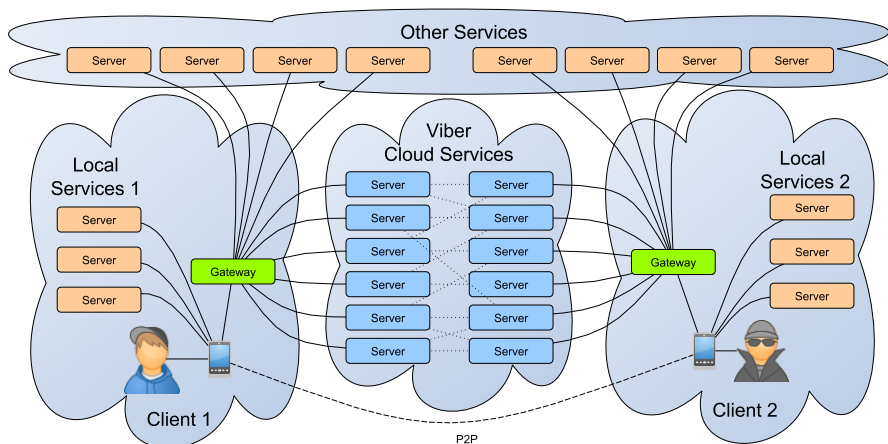
- **Link Prediction** . . . inferring whether or not a pair of vertices does or does not have an edge between them
  - using measurements that include a subset of vertex pairs whose edge/non-edge status is already observed.
  - knowledge of all of the vertices.
  - the status of some of the edges/non-edges
- **Association Graph Inference** . . . the relation defining edges is itself unobserved and must be inferred from measurements reflecting these characteristics.
  - no knowledge of edge status anywhere in the network graph,
  - relevant measurements at all of the vertices are assumed.
- **Tomographic Network Inference** . . . the measurements are available only at vertices that are somehow at the perimeter of the network.
  - measurements at only a particular subset of vertices are known.



# Outline

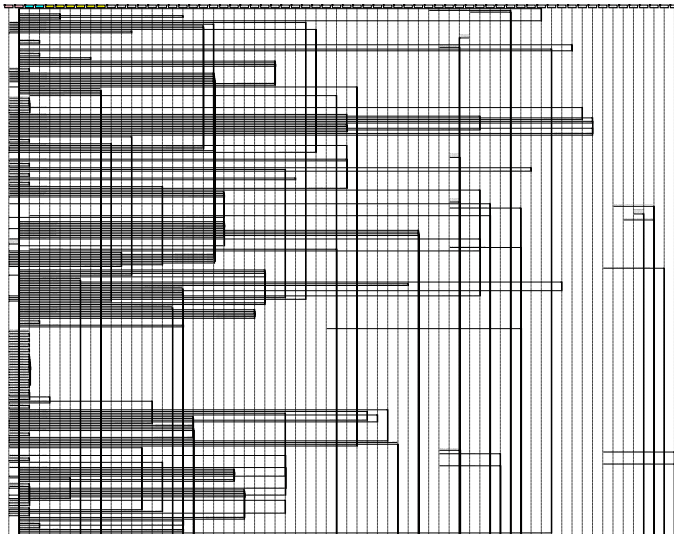
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# Exemplar (Viber) Environment <sup>[MBKK15]</sup>





# Example Capture Characteristics [MBKK15]



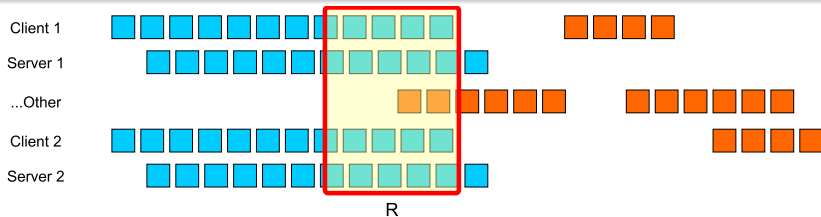
- 138882 PCAP blocks
- 1788 transport sessions
- 2 clients
- 22 viber.com servers
- 150 peers of 2 clients
- 5660 possible concurrent sessions
- **How to analyze?**



# Concurrent Communication Detection <sup>[MBKK15]</sup>

## Selection of IP nodes

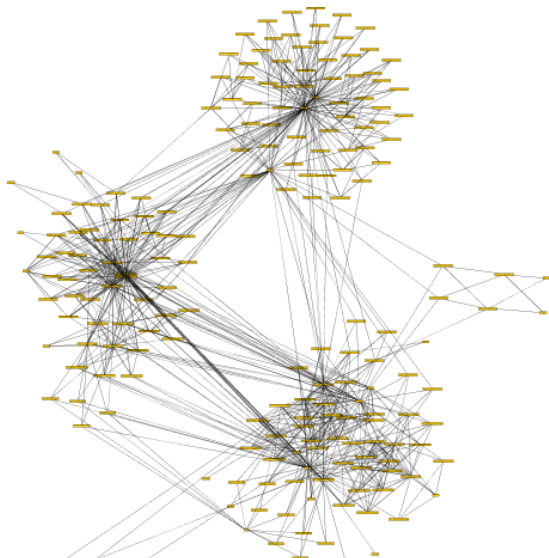
- *viber.com* servers → viber clients → other Viber servers
- classified based on entropy based characteristics of TCP/IP distributions



$$s(a, b) = \frac{\sum_{\forall i, j: t_a[i] - t_b[j] < R} R / (t_a[i] - t_b[j])}{\sum_{\forall i, j: t_a[i] - t_b[j] < R} 1}$$

In our experiments:  $R = 50ms$ ,  $s(a, b) > 0.001$

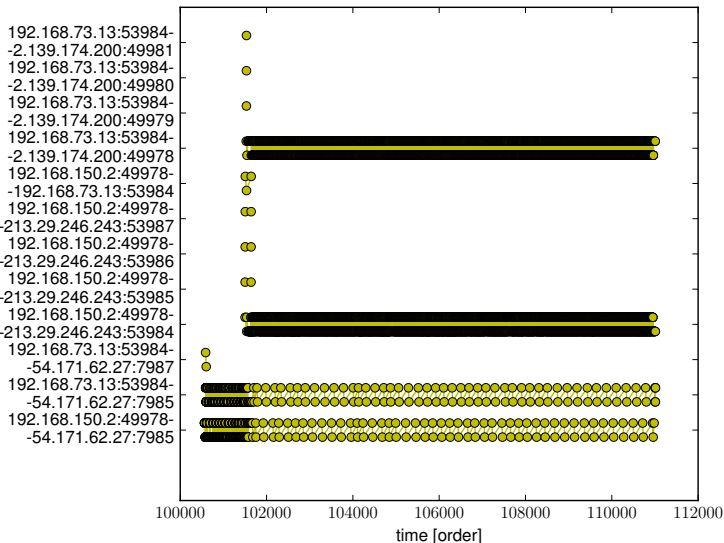
# UDP packet sequence concurrency as a complex network <sup>[MBKK15]</sup>



- captures with two clients
- "*communities*" of concurrent sessions
- some clusters related to only one client
- interesting clusters consist of nodes of both clients



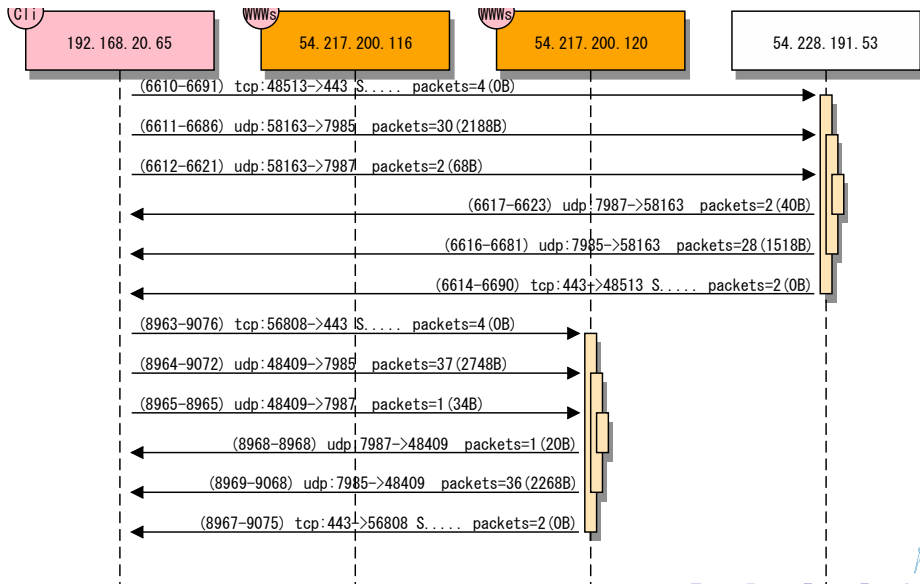
# UDP packet sequence concurrency - packet timing <sup>[MBKK15]</sup>



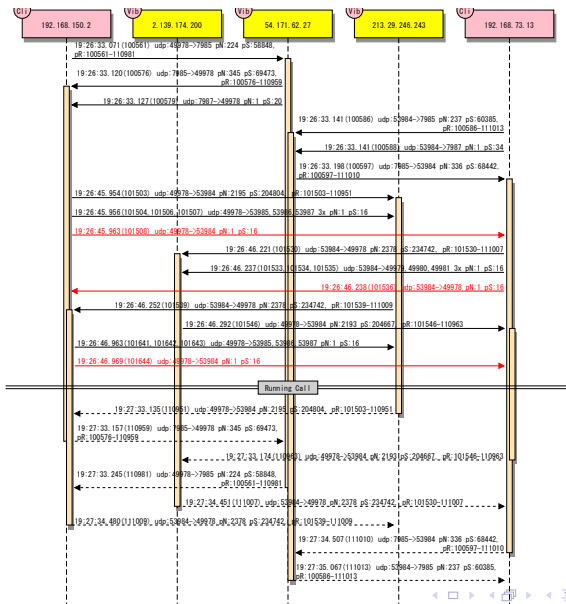
- signals
- calls
- keep-alive packets
- direct client to client packets



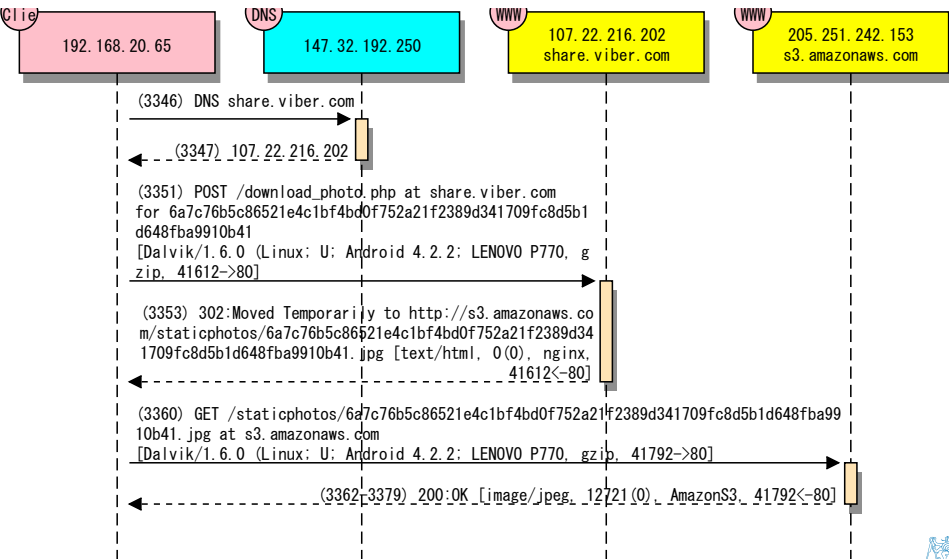
# Message Sending <sup>[MBKK15]</sup>



## Voice Call [MBKK15]



# Security/Privacy Assessment - Contact Picture Transfer





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# Link Prediction Motivation <sup>[LK03]</sup>

- Networks are highly dynamic objects
  - they grow and change . . . e.g. by adding new edges
- Network evolution models
  - To what extent can the evolution of a network be modeled using features *intrinsic to the network itself*?
  - A number of proximity measures lead to predictions that outperform a random prediction by factors 40 to 50.
  - The network topology might contain latent information from which one can infer future edges (interactions).
- Recovery of a hidden/latent informal network by observing the official observable network part.



# Link Prediction Definition <sup>[LK03, ?]</sup>

## ● Link Prediction

- A network is changing over time.
- Given a snapshot of a network at time  $t$ ,
- predict edges added in the interval  $(t, t')$

## ● Link Completion (missing links identification).

- Given a network,
- infer links that are consistent with the structure, but missing.
- *Find unobserved edges*

## ● Link Reliability

- Estimate the reliability of given links in the graph.

What can be predicted?

- Link existence,
- Link weight,
- Link type,
- Link cardinality.

# Link Prediction <sup>[LK03, ?]</sup>

- Given a graph  $G(V, E)$
- The number of *missing edges*:  $|V|(|V| - 1)/2 - |E|$
- Probability of a correct random guess  $O(\frac{1}{|v|^2})$ 
  - in sparse graphs ( $|E| \ll |V|^2$ )
- Each edge  $e \in E$  represents an interaction between its endpoints at a particular time  $t(e)$ .
- Multiple interactions are represented by parallel edges with different time-stamps.
- $G[t, t']$  is the subgraph of  $G$  restricted to edges with time-stamps between  $t$  and  $t'$ ,  $t < t'$ .

## Link prediction phases

- 1 **Learning:** *training* interval  $[t_0, t'_0] \dots G[t_0, t'_0]$
- 2 **Prediction:** *testing* interval  $[t_1, t'_1] \dots G[t_1, t'_1]$

# Link Prediction [LK03, ?]

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# Scoring Algorithm <sup>[LK03, ?]</sup>

- Proximity/Similarity score  $c(v_1, v_2)$  ... it is assumed that the higher the score the higher the probability that the vertexes  $v_1$  and  $v_2$  interact and they are linked by the edge.

## Link prediction by proximity scoring

- 1 Compute proximity/similarity score  $c(v_1, v_2)$  for each pair of nodes.
- 2 Sort all pairs by the decreasing score.
- 3 Select top pairs as new links
  - $n$  pairs
  - pairs above a treshold.



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# Scoring Functions - Neighborhood Based <sup>[LK03, ?]</sup>

Local neighborhoods of  $v_i$  and  $v_j$

- Number of **common neighbors**:

- based on the idea that links are formed between nodes who share many common neighbors

$$c^{CN}(v_i, v_j) = |\mathcal{N}(v_i) \cap \mathcal{N}(v_j)|$$

- **Jaccard's coefficient**:

- a measure of the likelihood that a neighbor of  $v_i$  is a neighbor of  $v_j$  and vice versa.

$$c^{JA}(v_i, v_j) = \frac{|\mathcal{N}(v_i) \cap \mathcal{N}(v_j)|}{|\mathcal{N}(v_i) \cup \mathcal{N}(v_j)|}$$

- **Adamic/Adar**:

- The larger weight is assigned to common neighbors  $v$  of  $v_i$  and  $v_j$  which themselves have few neighbors  $\log |\mathcal{N}(v)|$ ,
- i.e.  $v_i$  and  $v_j$  are “related” because of the rarer neighbor  $v$ .

$$c^{AA}(v_i, v_j) = \sum_{v \in \mathcal{N}(v_i) \cap \mathcal{N}(v_j)} \frac{1}{\log |\mathcal{N}(v)|}$$





# Scoring Functions - Neighborhood Based <sup>[LK03]</sup>

Preferential attachment:

- A new node is attached to a network node  $u$  that has a higher probability of fitness expressed as the size of its neighborhood  $|\mathcal{N}(u)|$ .

$$c(v_i, v_j) = |\mathcal{N}(v_i)| |\mathcal{N}(v_j)|$$



# Scoring Functions - Path Based <sup>[?]</sup>

Paths and ensembles of paths between  $v_i$  and  $v_j$

- Shortest path:

$$- \min_s \{path_{ij}^s > 0\}$$

- Katz score:

$$\sum_{\ell=1}^{\infty} \beta^{\ell} |paths^{(\ell)}(v_i, v_j)| = \sum_{\ell=1}^{\infty} (\beta \mathbf{A})_{ij}^{\ell} = (\mathbf{I} - \beta \mathbf{A})^{-1} - \mathbf{I}$$

- Personalized (rooted) PageRank:

$$PR = \alpha(\mathbf{D}^{-1} \mathbf{A})^T PR + (1 - \alpha)$$



# Scoring Functions - Path Based <sup>[?]</sup>

Local neighborhoods of  $v_i$  and  $v_j$

- Number of common neighbors

$$|\mathcal{N}(v_i) \cap \mathcal{N}(v_j)|$$

- Jaccard's coefficient

$$\frac{|\mathcal{N}(v_i) \cap \mathcal{N}(v_j)|}{|\mathcal{N}(v_i) \cup \mathcal{N}(v_j)|}$$

- Adamic/Adar:

$$\sum_{v \in \mathcal{N}(v_i) \cap \mathcal{N}(v_j)} \frac{1}{\log |\mathcal{N}(v)|}$$



# Summary

- Network inference problem
- Network inference case study
- Link prediction problem
- Link prediction scoring functions

# Competencies

- Define precision, recall, accuracy, and  $F1$ -measure used in classification evaluation.
- How ROC curves are used in classification problems?
- Define the network inference problem and its subproblems.
- How is it possible to detect packet sequence concurrency?
- Define the link prediction problem and its subproblems.
- Define typical scoring functions used in the link prediction problem.

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