#### Volumetric Texture Segmentation Reyes-Aldasoro 2007

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#### Overview

- ▶ medical, 3D
- Fourier subband descriptors
- Bhattacharyya space/distance
- oct tree in feature space
- boundary refinement

## Fourier tesselation (2D)





# Filtering



### Orientation pyramid



Amplitude only. Real signal  $\rightarrow$  FT symmetry  $\rightarrow$  half space needed

#### Feature selection

Bhattacharyya distance

 $D_B(p,q) = -\ln(BC(p,q)), \quad BC(p,q) = \int_{x \in X} \sqrt{p(x)q(x)}$ 

Bhattacharyya distance from variance and mean

$$D_B(k_1, k_2) = \frac{1}{4} \ln \left( \frac{1}{4} \left( \frac{\sigma_{k_1}^2}{\sigma_{k_2}^2} + \frac{\sigma_{k_2}^2}{\sigma_{k_1}^2} + 2 \right) \right) + \frac{1}{4} \left( \frac{(\mu_{k_1} - \mu_{k_2})^2}{\sigma_{k_1}^2 + \sigma_{k_2}^2} \right)$$

Sum D<sub>B</sub>over class pairs p

$$B_I(i) = \sum_{p=1}^{N_p} B(i,p) = \sum_{p=1}^{N_p} D_B\left(S_{k_1}^i, S_{k_2}^i\right),$$

• consider features in the ordered of decreasing  $B_I(i)$ 

#### Feature selection experiment



## Multiresolution classification

- build a multiresolution pyramid by quad tree/oct tree
- segment/classify at the lowest resolution
- (suboptimal classifier) calculate class means and then do NN clustering
- refine progresively at finer levels using "butterfly filters" (anisotropic filtering)

#### Orientation pyramid features



## Segmentation



## Knee segmentation



#### Cartilage segmentation

#### extracted heuristically from the bone boundaries



