

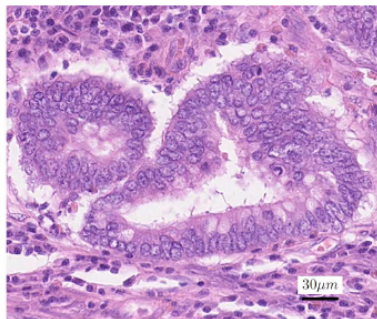
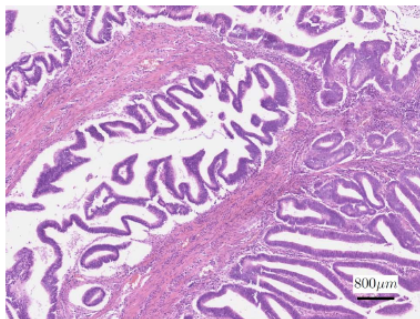
Detection and segmentation of cell nuclei

Al-Kofahi et al., IEEE TBME 2010

Jan Kybic

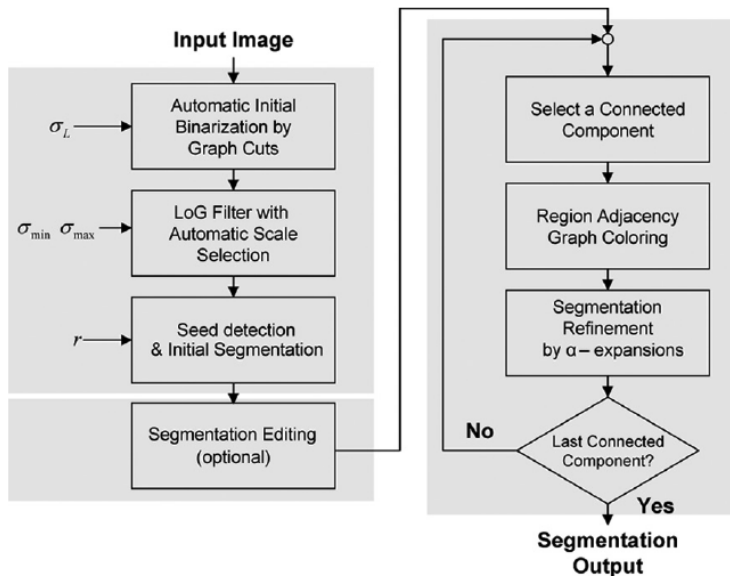
2020

Histology images



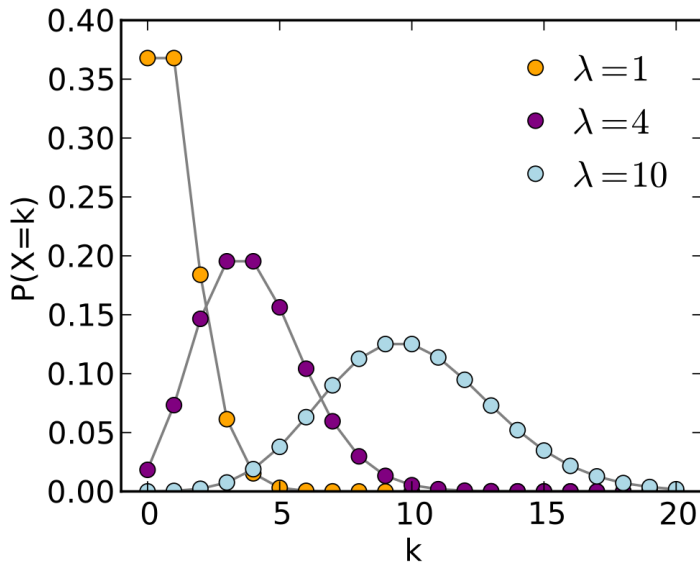
- ▶ Hematoxylin (nuclei, blue) & eosin (extracellular matrix and cytoplasm, pink)
- ▶ **Task:** find and segment cell nuclei → counting cells, diagnostics

Method



Poisson distribution

► $p(k) = \frac{\lambda^k e^{-\lambda}}{k!}$



Binarization - Poisson modeling

- ▶ Calculate histogram
- ▶ Model as a Poisson mixture ($\mu = \lambda$)

$$h(i) = P_0 \times p(i|0) + P_1 \times p(i|1)$$

- ▶ find threshold t minimizing KL divergence between model and histogram

$$t^* = \arg \min_t \{ \mu - P_0(t)(\ln P_0(t) + \mu_0(t) \ln \mu_0(t)) \\ - P_1(t)(\ln P_1(t) + \mu_1(t) \ln \mu_1(t)) \}$$

$$P_0(t) = \sum_{i=0}^t h(i), \quad \mu_0(t) = \frac{1}{P_0(t)} \sum_{i=0}^t i \times h(i)$$

$$P_1(t) = \sum_{i=t+1}^{I_{\max}} h(i), \quad \mu_1(t) = \frac{1}{P_1(t)} \sum_{i=t+1}^{I_{\max}} i \times h(i).$$

Binarization Graphcuts

$$E(L(x, y)) = \sum_{(x, y)} D(L(x, y); I_N(x, y)) \\ + \sum_{(x, y)} \sum_{(x', y') \in N(x, y)} V(L(x, y), L(x', y'))$$

- ▶ maximum log likelihood unary term

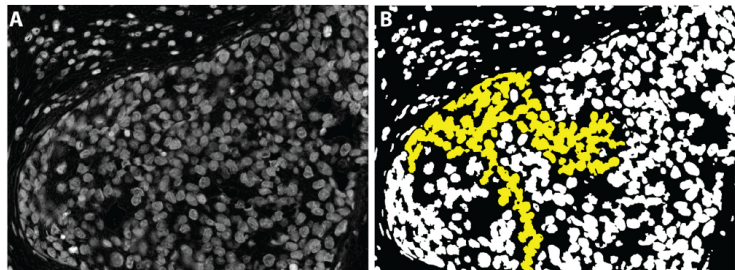
$$D(L(x, y); I_N(x, y)) = -\ln p(I_N(x, y) | j = \{0, 1\})$$

- ▶ edge term

$$V(L(x, y), L(x', y')) = \eta(L(x, y), L(x', y')) \\ \times \exp\left(-\frac{[I_N(x, y) - I_N(x', y')]}{2\sigma_L^2}\right)$$

with $\eta = \llbracket L(x, y) \neq L(x', y') \rrbracket$

Binarization results



Seed detection

- ▶ LoG filter $\text{LoG}_{\text{norm}}(x, y; \sigma) = \sigma^2 \text{LoG}(x, y; \sigma)$

$$\text{LoG}(x, y; \sigma) = \frac{\partial^2 G(x, y; \sigma)}{\partial x^2} + \frac{\partial^2 G(x, y; \sigma)}{\partial y^2}$$

- ▶ multiscale

$$R_N(x, y) = \arg \max_{\sigma \in [\sigma_{\min}, \sigma_{\text{MAX}}]} \{ \text{LoG}_{\text{norm}}(x, y; \sigma) * I_N(x, y) \}$$

where $\sigma_{\text{MAX}} = \max\{\sigma_{\min}, \min\{\sigma_{\text{max}}, 2 \times D_N(x, y)\}\}$.

D_N is a distance map

- ▶ seeds = local maxima, impose minimum size
- ▶ local-maximum clustering

Segmentation refinement

- ▶ Segment individual cells
- ▶ GraphCuts, α -expansion

$$V(L(x, y), L(x', y')) = \eta(L(x, y), L(x', y')) \\ \times \exp(-|I_N(x, y) - I_N(x', y')|)$$

where

$$\eta(L(x, y), L(x', y')) = \begin{cases} \text{Const,} & \text{if } L(x, y) \neq L(x', y') \\ 0, & \text{if } L(x, y) = L(x', y'). \end{cases}$$

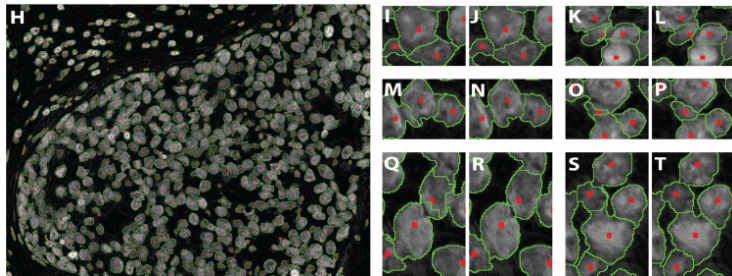
- ▶ Unary term - log likelihood for a Gaussian shape model

$$G(x, y; \mu_i, \Sigma_i)$$

(x, y) pixels with LoG weights

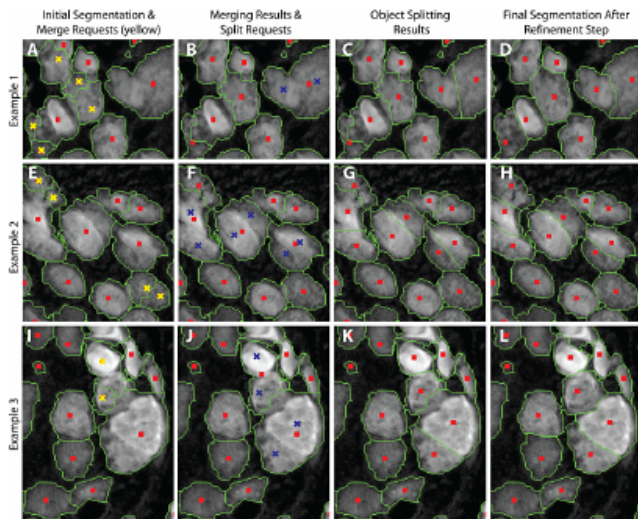
- ▶ to speed-up, group cells by graph colouring (e.g. 8 colors for 123 cells)
- ▶ iterate until convergence

Segmentation results

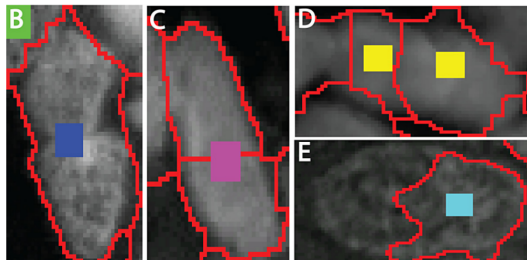
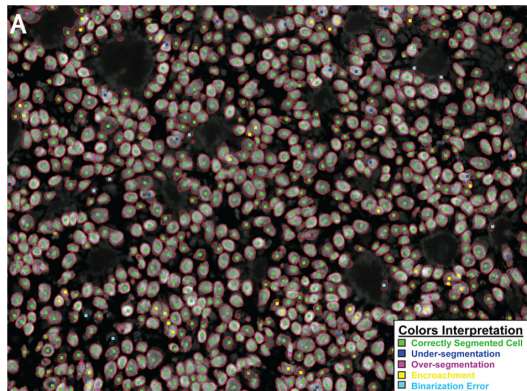


Computer-Assisted Editing

- ▶ merging, splitting, automatic refinement



Results



Results (2)

