## STATISTICAL MACHINE LEARNING (WS2023/24) SEMINAR 2

Assignment 1. Let  $\mathcal{X} = [a, b] \subset \mathbb{R}$ ,  $\mathcal{Y} = \{+1, -1\}$ ,  $\ell(y, y') = [[y \neq y']]$ ,  $p(x \mid y = +1) = p(x \mid y = -1)$  be uniform distributions on  $\mathcal{X}$  and p(y = +1) = 0.8. Consider the learning algorithm which for a given training set  $\mathcal{T}^m = \{(x^1, y^1), \dots, (x^m, y^m)\}$  returns the strategy

$$h_m(x) = \begin{cases} y^j & \text{if } x = x^j \text{ for some } j \in \{1, \dots, m\} \\ -1 & \text{otherwise} \end{cases}$$

a) Show that the empirical risk  $R_{\mathcal{T}^m}(h_m) = \frac{1}{m} \sum_{i=1}^m \ell(y^i, h_m(x^i))$  equals 0 with probability 1 for any finite m.

**b**) Show that the expected risk  $R(h_m) = \mathbb{E}_{(x,y)\sim p}(\ell(y, h_m(x)))$  equals 0.8 with probability 1 for any finite m.

Assignment 2. The ULLN for finite hypothesis space  $\mathcal{H} = \{h_1, \dots, h_K\}$  ensures that for every  $\varepsilon > 0$  we have that

$$\mathbb{P}\left(\max_{h\in\mathcal{H}}|R_{\mathcal{T}^m}(h) - R(h)| \ge \varepsilon\right) \le 2|\mathcal{H}|e^{-\frac{2m\varepsilon^2}{(\ell_{\max} - \ell_{\min})^2}},\tag{1}$$

where  $\mathcal{T}^m$  is a training set i.i.d. generated from an arbitrary p(x, y). Use (1) to prove validity of the generalization bound which states that for every  $\delta \in [0, 1]$  the upper bound

$$R(h) \le R_{\mathcal{T}^m}(h) + (\ell_{\max} - \ell_{\min}) \sqrt{\frac{\log 2|\mathcal{H}| + \log \frac{1}{\delta}}{2m}}$$

holds true for all  $h \in \mathcal{H}$  simultaneously with probability  $1 - \delta$  at least.

Assignment 3. Assume we train a Convolution Neural Network (CNN) classifier  $h: \mathcal{X} \to \mathcal{Y}$  to predict a digit  $y \in \mathcal{Y} = \{0, 1, \dots, 9\}$  from an image  $x \in \mathcal{X}$ . We train the CNN by the Stochastic Gradient Descent (SGD) algorithm using 100 epochs. After each epoch we save the current weights so that at the end of training we have a set  $\mathcal{H} = \{h_t: \mathcal{X} \to \mathcal{Y} \mid i = 1, \dots, 100\}$  containing 100 different CNN classifiers. We select the best CNN classifier  $\hat{h}$  out of  $\mathcal{H}$  based on the validation error  $R_{\mathcal{V}^m}(h)$ , i.e.  $\hat{h} = \arg \min_{h \in \mathcal{H}} R_{\mathcal{V}^m}(h)$ , where

$$R_{\mathcal{V}^m}(h) = \frac{1}{m} \sum_{i=1}^m \llbracket y^j \neq h(x^j) \rrbracket,$$

is computed from the validation set  $\mathcal{V}^m = \{(x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, ..., m\}$  i.i.d. drawn from p(x, y). The validation set  $\mathcal{V}^m$  has not been used by SGD for training. We

are left with no additional examples for testing and hence we use the validation error  $R_{\mathcal{V}^m}(\hat{h})$  also as an estimate of the generalization error  $R(\hat{h}) = \mathbb{E}[\ell(y, \hat{h}(x))]$ .

**a**) Can you quantify how well the validation error  $R_{\mathcal{V}^m}(\hat{h})$  estimates the generalization error  $R(\hat{h})$ ?

**b**) What is the minimum number of examples in the validation set  $\mathcal{V}^m$  required to confidently assert, with a 99% probability, that the generalization error  $R(\hat{h})$  exceeds the validation error  $R_{\mathcal{V}^m}(\hat{h})$  by no more than 1% ?