## Electromagnetic Field Theory 1 <br> (fundamental relations and definitions)

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## Fundamental Question of Classical Electrodynamics

A specified distribution of elementary charges is in a state of arbitrary (but known) motion. At certain time we pick one of them and ask what is the force acting on it.

Rather difficult question - will not be fully answered

## Elementary Charge



As far as we know, all charges in nature have values $\quad \pm N e, N \in \mathbb{Z}$

## Charge conservation

Amount of charge is conserved in every frame (even non-inertial).

Neutrality of atoms has been verified to 20 digits

## Continuous approximation of charge distribution



Continuous approximation allows for using powerful mathematics

## Fundamental Question of Electrostatics

There exist a specified distribution of static elementary charges. We pick one of them and ask what is the force acting on it.

This will be answered in full details

## Coulomb('s) Law



## Coulomb('s) Law + Superposition Principle

$$
\boldsymbol{F}(\boldsymbol{r})=\frac{q}{4 \pi \varepsilon_{0}} \sum_{n} \frac{q_{n}^{\prime}\left(\boldsymbol{r}-\boldsymbol{r}_{n}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}_{n}^{\prime}\right|^{3}}
$$

Entire electrostatics can be deduced from this formula

## Electric Field

$$
\boldsymbol{F}(\boldsymbol{r})=q \boldsymbol{E}(\boldsymbol{r}) \quad \boldsymbol{E}(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \sum_{n} \frac{q_{n}^{\prime}\left(\boldsymbol{r}-\boldsymbol{r}_{n}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}_{n}^{\prime}\right|^{3}}
$$

Force is represented by field - entity generated by charges and permeating the space

## Continuous Distribution of Charge

$$
\boldsymbol{E}(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \sum_{n} \frac{q_{n}^{\prime}\left(\boldsymbol{r}-\boldsymbol{r}_{n}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}_{n}^{\prime}\right|^{3}} \quad \boldsymbol{E}(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \int_{V^{\prime}} \frac{\rho\left(\boldsymbol{r}^{\prime}\right)\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} \mathrm{~d} V^{\prime}
$$

Continuous description of charge allows for using powerful mathematics

## Continuous Description of a Point Charge



## Gauss(') Law



## Rotation of Electric Field

$\nabla \times \boldsymbol{E}=0$


Differential law (local)
$\oint_{l} \boldsymbol{E} \cdot \mathrm{~d} \boldsymbol{l}=0$


Integral law (global)

## Various Views on Electrostatics

Integral laws of electrostatics
 electrostatics

Coulomb's law


$$
\begin{array}{ll}
\oint_{S} \boldsymbol{E} \cdot \mathrm{~d} \boldsymbol{S}=\frac{Q}{\varepsilon_{0}}
\end{array} \Longleftrightarrow \begin{aligned}
& \nabla \cdot \boldsymbol{E}(\boldsymbol{r})=\frac{\rho(\boldsymbol{r})}{\varepsilon_{0}} \\
& \oint_{l} \boldsymbol{E} \cdot \mathrm{~d} \boldsymbol{l}=0
\end{aligned} \Longleftrightarrow \boldsymbol{E}(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \int_{V^{\prime}} \frac{\rho\left(\boldsymbol{r}^{\prime}\right)\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} \mathrm{~d} V^{\prime}
$$

The physics content is the same, the formalism is different.

## Electric potential

$$
\nabla \times \boldsymbol{E}=0 \quad 2 \boldsymbol{E}(\boldsymbol{r})=-\nabla \varphi(\boldsymbol{r}) \quad \longrightarrow \quad \varphi(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \int_{V^{\prime}} \frac{\rho\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \mathrm{d} V^{\prime}+K
$$

Scalar description of electrostatic field

## Voltage



Voltage represents connection of abstract field theory with experiments

## Electrostatic Energy



## Electrostatic Energy vs Force

$$
\begin{aligned}
& \begin{array}{l}
\text { Energy of a } \\
\text { system of point } \\
\text { charges }
\end{array} \\
& W=\frac{1}{8 \pi \varepsilon_{0}} \sum_{\substack{i, j \\
j \neq i}} \frac{q_{i} q_{j}}{\left|\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right|} \quad \text { Coulomb's law }
\end{aligned}
$$

Electrostatic forces are always acting so as to minimize energy of the system

## Electric Stress Tensor

Total electric
force acting in
a volume
Stress tensor


$$
\boldsymbol{F}=\int_{V} \rho(\boldsymbol{r}) \boldsymbol{E}(\boldsymbol{r}) \mathrm{d} V=\varepsilon_{0} \oint_{S} \overline{\overline{\boldsymbol{T}}} \cdot \mathrm{~d} \boldsymbol{S} \quad \boldsymbol{\overline { \boldsymbol { T } }}=\boldsymbol{E} \boldsymbol{E}-\frac{1}{2} \overline{\overline{\boldsymbol{I}}}|\boldsymbol{E}|^{2}
$$

All the information on the volumetric Coulomb's force is contained at the boundary

## Ideal Conductor - classical description

Ideal conductor contains unlimited amount of free charges which under action of external electric field rearrange so as to annihilate electric field inside the conductor.

In 3D, the free charge always resides on the external bounding surface of the conductor.

```
In 1D and 2D
```

                    it is not so
    Generally, free charges in conductors move so as to minimize the energy

## Ideal Conductor - quantum description

In an ideal conductor, wave functions of electrons in outer shells perceive flat potential background. In reaction to an external electric field, these wave functions are slightly modified so as to provide zero average charge density inside the conductor. Due to flat potential background, there is no counter interaction.

Long-range transport of charge does not truly happen in a solid conductor

## Boundary Conditions on Ideal Conductor

- Inside conductor

$$
\text { - } \boldsymbol{E}(\boldsymbol{r})=0 \Leftrightarrow \varphi(\boldsymbol{r})=\text { const. }
$$

- Just outside conductor
- $\boldsymbol{n}(\boldsymbol{r}) \times \boldsymbol{E}(\boldsymbol{r})=0 \Leftrightarrow \varphi(\boldsymbol{r})=$ const.

Potential is
continuous
across the
boundary

Surface charge residing on the outer surface of the conductor

Outward normal to the conductor

## Capacitance of a System of $N$ conductors



Electrostatic system is fully characterized by capacitances (we know the energy)

## Capacitance of a System of two conductors



## Poisson('s) equation

$$
\Delta x(t)=\frac{-(t)}{5}
$$

The solution to Poisson's equation is unique in a given volume once the potential is known on its bounding surface and the charge density is known throughout the volume.

## Laplace('s) equation

$$
\Delta \varphi(\boldsymbol{r})=0
$$

The solution to Laplace's equation is unique in a given volume once the potential is known on its bounding surface.

## Mean Value Theorem



The solution to Laplace's equation posses neither maxima nor minima inside the solved volume.

## Earnshaw('s) Theorem

Consequence of mean value theorem

A charged particle cannot be held in stable equilibrium by electrostatic forces alone.

Mind that the solution to Laplace's equation posses neither maxima nor minima inside the solved volume. This means that charged particle will always travel towards the boundary.

## Image Method

When solving field generated by charges in the presence of conductors, it is sometimes possible to remove the conductor and mimic its boundary conditions by adding extra charges to the exterior of the solution volume. The uniqueness theorem claims that this is a correct solution.

Image method always works with planes and spheres.

## Separation of Variables

$$
\begin{gathered}
\begin{array}{c}
\text { Constants } \\
\text { determined by } \\
\text { boundary conditions }
\end{array} \\
\Delta \varphi(\boldsymbol{r})=0 \quad \varphi_{i j k}(\boldsymbol{r})=X_{i}(x) Y_{j}(y) Z_{k}(z) \quad \Longleftrightarrow
\end{gathered}
$$

Semi-analytical method for canonical problems

## Finite Differences

$$
\begin{aligned}
& \varphi(x+h, y, z) \rightarrow \varphi_{(i+1) j k} \\
& \Delta \varphi(\boldsymbol{r}) \approx \frac{\varphi_{(i+1) j k}-2 \varphi_{i j k}+\varphi_{(i-1) j k}}{h^{2}}+\frac{\varphi_{i(j+1) k}-2 \varphi_{i j k}+\varphi_{i(j-1) k}}{h^{2}}+\frac{\varphi_{i j(k+1)}-2 \varphi_{i j k}+\varphi_{i j(k-1)}}{h^{2}}
\end{aligned}
$$



Powerful numerical method for closed problems

## Integral Equation \& Method of Moments

Assumed to be known in volume where the charge resides

Distribution of charge is unknown

$$
\varphi(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \int_{V^{\prime}} \frac{\rho\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \mathrm{d} V^{\prime}
$$

Simple functions for
which the potential integral can be easily evaluated

$$
\rho(\boldsymbol{r}) \approx \sum_{n} \alpha_{n} \rho_{n}(\boldsymbol{r})
$$

$$
\int_{V} \rho_{m}(\boldsymbol{r}) \varphi(\boldsymbol{r}) \mathrm{d} V=\sum_{n} \alpha_{n} \frac{1}{4 \pi \varepsilon_{0}} \int_{V} \int_{V^{\prime}} \frac{\rho_{m}(\boldsymbol{r}) \rho_{n}\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \mathrm{d} V^{\prime} \mathrm{d} V
$$

Powerful numerical method for open problems

## Dielectrics

- Material in which charges cannot move freely
- Charges are forming clusters (atoms, molecules)
- Under influence of electric field the clusters change shape or rotate
- Electric field induces electric dipoles with density $\boldsymbol{P}(\boldsymbol{r}) \quad\left[\mathrm{C} \cdot \mathrm{m}^{-2}\right]$


## Electric Field of a Dipole

Two opposite charges
very close to each other

$$
\left|\boldsymbol{r}-\boldsymbol{r}_{\text {center }}\right| \gg\left|\boldsymbol{r}_{1}-\boldsymbol{r}_{2}\right|
$$

$$
\varphi(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \frac{q}{\left|\boldsymbol{r}-\boldsymbol{r}_{1}\right|}-\frac{1}{4 \pi \varepsilon_{0}} \frac{q}{\left|\boldsymbol{r}-\boldsymbol{r}_{2}\right|} \approx \frac{1}{4 \pi \varepsilon_{0}} \frac{\boldsymbol{p} \cdot\left(\boldsymbol{r}-\boldsymbol{r}_{\text {center }}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}_{\text {center }}\right|^{3}}
$$



## Field Produced by Polarized Matter

$$
\varphi(\boldsymbol{r})=\frac{1}{4 \pi \varepsilon_{0}} \int_{V^{\prime}} \frac{\boldsymbol{P}\left(\boldsymbol{r}^{\prime}\right) \cdot\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} \mathrm{~d} V^{\prime}=\frac{1}{4 \pi \varepsilon_{0}} \oint_{S^{\prime}} \frac{\boldsymbol{P}\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \cdot \mathrm{d} \boldsymbol{S}^{\prime}-\frac{1}{4 \pi \varepsilon_{0}} \int_{V^{\prime}} \frac{\nabla^{\prime} \cdot \boldsymbol{P}\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \mathrm{d} V^{\prime}
$$

This formula holds very well outside the matter and, curiously, it also well approximates the field inside

## Electric Displacement

Electric displacement $\left[\mathrm{C} \cdot \mathrm{m}^{-2}\right]$

$$
\nabla \cdot \boldsymbol{D}(\boldsymbol{r})=\rho(\boldsymbol{r})
$$

$\boldsymbol{D}(\boldsymbol{r})=\varepsilon_{0} \boldsymbol{E}(\boldsymbol{r})+\boldsymbol{P}(\boldsymbol{r})$


$$
\oint_{S} \boldsymbol{D} \cdot \mathrm{~d} \boldsymbol{S}=\int_{V} \rho(\boldsymbol{r}) \mathrm{d} V=Q
$$

Only free charge
(compare to divergence of electric field)

## Linear Isotropic Dielectrics



All the complicated structure of matter reduces to a simple scalar quantity

## Fields in Presence of Dielectrics 1/2

Analogy with electric field in vacuum can only be used when entire space is homogeneously filled with dielectric.

$$
\nabla \times \boldsymbol{D}(\boldsymbol{r})=\nabla \times[\varepsilon(\boldsymbol{r}) \boldsymbol{E}(\boldsymbol{r})] \neq 0
$$

Analogy with vacuum can only be used when space is homogeneously filled with dielectric

Fields in Presence of Dielectrics 2/2

$$
\nabla \times \boldsymbol{E}(\boldsymbol{r})=0 \Leftrightarrow \boldsymbol{E}(\boldsymbol{r})=-\nabla \varphi(\boldsymbol{r}) \quad \Rightarrow \quad \nabla \cdot[\varepsilon(\boldsymbol{r}) \nabla \varphi(\boldsymbol{r})]=-\rho(\boldsymbol{r})
$$

$$
\Delta \varphi(\boldsymbol{r})=-\frac{\rho(\boldsymbol{r})}{\varepsilon}
$$

Poisson's equation holds only when permittivity does not depend on coordinates

## Dielectric Boundaries

$$
\begin{aligned}
& \qquad \boldsymbol{n}(\boldsymbol{r}) \times\left[\boldsymbol{E}_{1}(\boldsymbol{r})-\boldsymbol{E}_{2}(\boldsymbol{r})\right]=0 \quad \Leftrightarrow \quad \varphi_{1}(\boldsymbol{r})-\varphi_{2}(\boldsymbol{r})=0 \\
& \boldsymbol{n}(\boldsymbol{r}) \cdot\left[\varepsilon_{1} \boldsymbol{E}_{1}(\boldsymbol{r})-\varepsilon_{2} \boldsymbol{E}_{2}(\boldsymbol{r})\right]=\sigma(\boldsymbol{r}) \quad \Leftrightarrow \quad \varepsilon_{1} \frac{\partial \varphi_{1}(\boldsymbol{r})}{\partial n}-\varepsilon_{2} \frac{\partial \varphi_{2}(\boldsymbol{r})}{\partial n}=-\sigma(\boldsymbol{r}) \\
& \text { Normal } \\
& \text { pointing to } \\
& \text { region (1) }
\end{aligned}
$$

Both conditions are needed for unique solution

## Electrostatic Energy in Dielectrics

$$
W=\frac{1}{2} \varepsilon_{0} \int_{V}|\boldsymbol{E}(\boldsymbol{r})|^{2} \mathrm{~d} V \quad \quad \quad \quad \quad W=\frac{1}{2} \int_{V} \boldsymbol{E}(\boldsymbol{r}) \cdot \boldsymbol{D}(\boldsymbol{r}) \mathrm{d} V
$$

## Forces on Dielectrics

This only holds when charge is held constant

$$
\begin{aligned}
W & =\frac{1}{2} C U^{2}=\frac{1}{2} \frac{Q^{2}}{C} \\
W & =\frac{1}{2} \int_{V} \boldsymbol{E}(\boldsymbol{r}) \cdot \boldsymbol{D}(\boldsymbol{r}) \mathrm{d} V
\end{aligned}
$$

## Electric Current



Charges in motion are represented by current density

## Local Charge Conservation

$$
\nabla \cdot \boldsymbol{J}(\boldsymbol{r}, t)=-\frac{\partial}{\partial t} \sum_{k=1}^{N} q_{k} \delta\left(\boldsymbol{r}-\boldsymbol{r}_{k}(t)\right)=-\frac{\partial \rho(\boldsymbol{r}, t)}{\partial t}
$$

Charge is conserved locally at every space-time point

## Global Charge Conservation

When charge leaves a given volume, it is always accompanied by a current through the bounding envelope

$$
\oint_{S} \boldsymbol{J}(\boldsymbol{r}, t) \cdot d \boldsymbol{S}=-\frac{\partial Q(t)}{\partial t}
$$

Charge can neither be created nor destroyed. It can only be displaced.
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## Stationary Current

When charge enters a volume, another must leave it without any delay

$$
\nabla \cdot \boldsymbol{J}(\boldsymbol{r})=0
$$

$$
\oint_{S} \boldsymbol{J}(\boldsymbol{r}) \cdot d \boldsymbol{S}=0
$$

There is no charge accumulation in stationary flow

## Ohm('s) Law

Conductivity
$\left[\mathrm{S} \cdot \mathrm{m}^{-1}\right]$

$$
\boldsymbol{J}(\boldsymbol{r})=\sigma(\boldsymbol{r}) \boldsymbol{E}(\boldsymbol{r})
$$

This simple linear relation holds for enormous interval of electric field strengths

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## Electromotive Force

Stationary flow of charges cannot be caused by electrostatic field. The motion forces are non-conservative, are called electromotive forces, and are commonly of chemical, magnetic or photoelectric origin.


For curves passing through sources of electromotive force


For curves not crossing sources of electromotive force

## Boundary Conditions for Stationary Current

$$
\begin{aligned}
\boldsymbol{n}(\boldsymbol{r}) \times\left[\boldsymbol{E}_{1}(\boldsymbol{r})-\boldsymbol{E}_{2}(\boldsymbol{r})\right]=0 & \Leftrightarrow \varphi_{1}(\boldsymbol{r})-\varphi_{2}(\boldsymbol{r})=0 \\
\boldsymbol{n}(\boldsymbol{r}) \cdot\left[\varepsilon_{1} \boldsymbol{E}_{1}(\boldsymbol{r})-\varepsilon_{2} \boldsymbol{E}_{2}(\boldsymbol{r})\right]=\sigma(\boldsymbol{r}) & \Leftrightarrow \varepsilon_{1} \frac{\partial \varphi_{1}(\boldsymbol{r})}{\partial n}-\varepsilon_{2} \frac{\partial \varphi_{2}(\boldsymbol{r})}{\partial n}=-\sigma(\boldsymbol{r}) \\
\boldsymbol{n}(\boldsymbol{r}) \cdot\left[\sigma_{1} \boldsymbol{E}_{1}(\boldsymbol{r})-\sigma_{2} \boldsymbol{E}_{2}(\boldsymbol{r})\right]=0 & \Leftrightarrow \sigma_{1} \frac{\partial \varphi_{1}(\boldsymbol{r})}{\partial n}-\sigma_{2} \frac{\partial \varphi_{2}(\boldsymbol{r})}{\partial n}=0
\end{aligned}
$$

Charge conservation forces the continuity of current across the boundary

## Electric Current




## Resistance (Conductance)



## Resistive Circuits and Kirchhoff('s) Laws



Kirchhoff's laws are a consequence of electrostatics and law's of stationary current flow

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## Joule('s) Heat



Electric field within conducting material produces heat

## Fundamental Question of Magnetostatics

There exist a specified distribution of stationary current. We pick a differential volume of it and ask what is the force acting on it.

## Biot-Savart('s) Law



## Biot-Savart('s) Law + Superposition Principle

$$
\boldsymbol{F}(\boldsymbol{r})=\boldsymbol{J}(\boldsymbol{r}) \mathrm{d} V \times \frac{\mu_{0}}{4 \pi} \int_{V^{\prime}} \frac{\boldsymbol{J}\left(\boldsymbol{r}^{\prime}\right) \times\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} \mathrm{~d} V^{\prime}
$$

Entire magnetostatics can be deduced from this formula

## Magnetic Field

$$
\boldsymbol{F}(\boldsymbol{r})=\boldsymbol{J}(\boldsymbol{r}) \mathrm{d} V \times \boldsymbol{B}(\boldsymbol{r}) \quad \boldsymbol{B}(\boldsymbol{r})=\frac{\mu_{0}}{4 \pi} \int_{V^{\prime}} \frac{\boldsymbol{J}\left(\boldsymbol{r}^{\prime}\right) \times\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} \mathrm{~d} V^{\prime}
$$

Magnetic field
(Magnetic induction)

## Divergence of Magnetic Field

$$
\nabla \cdot \boldsymbol{B}(\boldsymbol{r})=0 \quad \oint_{S} \boldsymbol{B}(\boldsymbol{r}) \cdot \mathrm{d} \boldsymbol{S}=0
$$

There are no point sources of magnetostatic field

## Curl of Magnetic Field - Ampere('s) Law

$$
\nabla \times \boldsymbol{B}(\boldsymbol{r})=\mu_{0} \boldsymbol{J}(\boldsymbol{r})
$$


$\oint_{l} \boldsymbol{B}(\boldsymbol{r}) \cdot \mathrm{d} \boldsymbol{l}=\mu_{0} I$
Total current captured within the curve

## Magnetic Vector Potential

$$
\begin{gathered}
\text { Magnetic vector } \\
\text { potential }
\end{gathered} \begin{gathered}
\begin{array}{c}
\text { Defined up to } \\
\text { arbitrary scalar } \\
\text { function }
\end{array} \\
\nabla \cdot \boldsymbol{B}=0 \longmapsto \boldsymbol{B}(\boldsymbol{r})=\nabla \times \boldsymbol{A}(\boldsymbol{r}) \Longrightarrow \boldsymbol{A}(\boldsymbol{r})=\frac{\mu_{0}}{4 \pi} \int_{V^{\prime}} \frac{\boldsymbol{J}\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \mathrm{d} V^{\prime}+\nabla \psi(\boldsymbol{r}),
\end{gathered}
$$

Reduced description of magnetostatic field

## Poisson('s) equation

$$
\Delta A(r)=-\mu_{0} J(r)
$$

The solution to Poisson's equation is unique in a given volume once the potential is known on its bounding surface and the current density is known through out the volume.

## Boundary Conditions

$$
\begin{gathered}
n(\boldsymbol{r}) \cdot\left[\boldsymbol{B}_{1}(\boldsymbol{r})-\boldsymbol{B}_{2}(\boldsymbol{r})\right]=0 \\
\boldsymbol{A}_{1}(\boldsymbol{r})-\boldsymbol{A}_{2}(\boldsymbol{r})=0
\end{gathered}
$$

## Magnetostatic Energy

$$
W=\frac{1}{2} \int_{V} \boldsymbol{A}(\boldsymbol{r}) \cdot \boldsymbol{J}(\boldsymbol{r}) \mathrm{d} V \quad \quad \quad \quad \quad \int_{V}=\frac{1}{2 \mu_{0}} \int_{V}|\boldsymbol{B}(\boldsymbol{r})|^{2} \mathrm{~d} V
$$

For now it is just a formula that works - it must be derived with the help of time varying fields

## Magnetostatic Energy - Current Circuits

$$
\begin{aligned}
M_{i j}=M_{j i}= & \frac{\mu_{0}}{4 \pi I_{i} I_{j}} \int_{V_{j}} \int_{V_{i}^{\prime}} \frac{\boldsymbol{J}_{j}\left(\boldsymbol{r}_{j}\right) \cdot \boldsymbol{J}_{i}\left(\boldsymbol{r}_{i}^{\prime}\right)}{\left|\boldsymbol{r}_{j}-\boldsymbol{r}_{i}^{\prime}\right|} \mathrm{d} V_{i}^{\prime} \mathrm{d} V_{j} \\
& \text { Mutual-Inductance }[\mathrm{H}]
\end{aligned}
$$



## Mutual Inductance - Thin Current Loop



## Magnetic Materials

- Material response is due to magnetic dipole moments
- Magnetic moment comes from spin or orbital motion of an electron
- Magnetic field tends to align magnetic moments
- Magnetic field induces magnetic dipoles with density $M(r) \quad\left[\mathrm{A} \cdot \mathrm{m}^{-1}\right]$

Number of dipoles
in unitary volume

## Magnetic Field of a Dipole



Magnetic dipole approximates infinitesimally small current loop

## Field Produced by Magnetized Matter

$$
\boldsymbol{A}(\boldsymbol{r})=\frac{\mu_{0}}{4 \pi} \int_{V^{\prime}} \frac{\boldsymbol{M}\left(\boldsymbol{r}^{\prime}\right) \times\left(\boldsymbol{r}-\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|^{3}} \mathrm{~d} V^{\prime}=\frac{\mu_{0}}{4 \pi} \oint_{S^{\prime}} \frac{\boldsymbol{M}\left(\boldsymbol{r}^{\prime}\right) \times \mathrm{d} \boldsymbol{S}^{\prime}}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|}+\frac{\mu_{0}}{4 \pi} \int_{V^{\prime}} \frac{\nabla^{\prime} \times \boldsymbol{M}\left(\boldsymbol{r}^{\prime}\right)}{\left|\boldsymbol{r}-\boldsymbol{r}^{\prime}\right|} \mathrm{d} V^{\prime}
$$

This formula holds very well outside the matter and, curiously, it also well approximates the field inside

## Magnetic Intensity



## Linear Isotropic Magnetic Materials



All the complicated structure of matter reduces to a simple scalar quantity

## Fields in Presence of Magnetic Material

$$
\nabla \cdot \boldsymbol{B}(\boldsymbol{r})=0 \Leftrightarrow \boldsymbol{B}(\boldsymbol{r})=\nabla \times \boldsymbol{A}(\boldsymbol{r}) \quad \boldsymbol{\nabla} \times\left[\frac{1}{\mu(\boldsymbol{r})} \nabla \times \boldsymbol{A}(\boldsymbol{r})\right]=\boldsymbol{J}(\boldsymbol{r})
$$



Poisson's equation holds only when permittivity does not depend on coordinates

## Magnetic Material Boundaries

$$
\begin{aligned}
& \boldsymbol{n}(\boldsymbol{r}) \times\left[\boldsymbol{H}_{1}(\boldsymbol{r})-\boldsymbol{H}_{2}(\boldsymbol{r})\right]=\boldsymbol{K}(\boldsymbol{r}) \\
& \boldsymbol{n}(\boldsymbol{r}) \cdot\left[\mu_{1} \boldsymbol{H}_{1}(\boldsymbol{r})-\mu_{2} \boldsymbol{H}_{2}(\boldsymbol{r})\right]=0
\end{aligned}
$$

Normal
pointing to region (1)

Both conditions are needed for unique solution

## Magnetostatic Energy in Magnetic Material

$$
W=\frac{1}{2 \mu_{0}} \int_{V}|\boldsymbol{B}(\boldsymbol{r})|^{2} \mathrm{~d} V \quad \quad \quad \quad \quad \quad=\frac{1}{2} \int_{V} \boldsymbol{H}(\boldsymbol{r}) \cdot \boldsymbol{B}(\boldsymbol{r}) \mathrm{d} V
$$

## Magnetic Materials

- Paramagnetic - small positive susceptibility (small attraction - linear)
- Diamagnetic - small negative susceptibility (small repulsion - linear)
- Ferromagnetic - "large positive susceptibility" (large attraction - nonlinear)


## Ferromagnetic Materials

- Spins are ordered within domains
- Magnetization is a non-linear function of field intensity
- Magnetization curve - Hysteresis, Remanence
- Susceptibility can only be defined as local approximation
- Above Curie('s) temperature ferromagnetism disappears

Exact calculations are very difficult - use simplified models (soft material, permanent magnet)

## Faraday('s) Law



Time variation in magnetic field produces electric field that tries to counter the change in magnetic flux (electromotive force)

## Lenz('s) Law

The current created by time variation of magnetic flux is directed so as to oppose the flux creating it.

## Time Varying RL Circuits



## Time Varying Potentials

$$
\begin{gathered}
\begin{array}{c}
\text { Potential } \\
\text { calibration }
\end{array} \\
\nabla \cdot \boldsymbol{A}(\boldsymbol{r}, t)=-\sigma \mu \varphi(\boldsymbol{r}, t) \\
\boldsymbol{B}(\boldsymbol{r}, t)=\nabla \times \boldsymbol{A}(\boldsymbol{r}, t) \\
\boldsymbol{E}(\boldsymbol{r}, t)=-\nabla \varphi(\boldsymbol{r}, t)-\frac{\partial \boldsymbol{A}(\boldsymbol{r}, t)}{\partial t}
\end{gathered}
$$

In time varying fields scalar potential becomes redundant

## Source and Induced Currents

Those are fixed, not reacting to fields

$$
\nabla \times \boldsymbol{H}(\boldsymbol{r}, t)=\boldsymbol{J}_{\text {source }}(\boldsymbol{r}, t)+\boldsymbol{J}_{\text {inducued }}(\boldsymbol{r}, t)=\boldsymbol{J}_{\text {sourre }}(\boldsymbol{r}, t)+\sigma \boldsymbol{E}(\boldsymbol{r}, t)
$$

## Diffusion Equation

$$
\begin{aligned}
& \Delta \boldsymbol{A}(\boldsymbol{r}, t)-\sigma \mu \frac{\partial \boldsymbol{A}(\boldsymbol{r}, t)}{\partial t}=-\mu \boldsymbol{J}_{\text {source }}(\boldsymbol{r}, t) \\
& \Delta \boldsymbol{H}(\boldsymbol{r}, t)-\sigma \mu \frac{\partial \boldsymbol{H}(\boldsymbol{r}, t)}{\partial t}=-\nabla \times \boldsymbol{J}_{\text {source }}(\boldsymbol{r}, t) \\
& \Delta \boldsymbol{E}(\boldsymbol{r}, t)-\sigma \mu \frac{\partial \boldsymbol{E}(\boldsymbol{r}, t)}{\partial t}=\frac{1}{\varepsilon} \nabla \rho_{\text {source }}(\boldsymbol{r}, t)+\mu \frac{\partial \boldsymbol{J}_{\text {source }}(\boldsymbol{r}, t)}{\partial t} \\
& \begin{array}{c}
\text { Material parameters are assumed } \\
\text { independent of coordinates }
\end{array}
\end{aligned}
$$

## Maxwell('s)-Lorentz('s) Equations

$$
\begin{aligned}
& \nabla \times \boldsymbol{H}(\boldsymbol{r}, t)=\boldsymbol{J}(\boldsymbol{r}, t)+\frac{\partial \boldsymbol{D}(\boldsymbol{r}, t)}{\partial t} \\
& \nabla \times \boldsymbol{E}(\boldsymbol{r}, t)=-\frac{\partial \boldsymbol{B}(\boldsymbol{r}, t)}{\partial t} \\
& \nabla \cdot \boldsymbol{B}(\boldsymbol{r}, t)=0 \\
& \nabla \cdot \boldsymbol{D}(\boldsymbol{r}, t)=\rho(\boldsymbol{r}, t)
\end{aligned}
$$

Equations of motion for fields

$$
\boldsymbol{f}(\boldsymbol{r}, t)=\rho(\boldsymbol{r}, t) \boldsymbol{E}(\boldsymbol{r}, t)+\boldsymbol{J}(\boldsymbol{r}, t) \times \boldsymbol{B}(\boldsymbol{r}, t)
$$

Interaction with materials


Absolute majority of things happening around you is described by these equations

## Boundary Conditions

$$
\begin{gathered}
\boldsymbol{n}(\boldsymbol{r}) \times\left[\boldsymbol{E}_{1}(\boldsymbol{r}, t)-\boldsymbol{E}_{2}(\boldsymbol{r}, t)\right]=0 \\
\boldsymbol{n}(\boldsymbol{r}) \times\left[\boldsymbol{H}_{1}(\boldsymbol{r}, t)-\boldsymbol{H}_{2}(\boldsymbol{r}, t)\right]=\boldsymbol{K}(\boldsymbol{r}, t) \\
\boldsymbol{n}(\boldsymbol{r}) \cdot\left[\boldsymbol{B}_{1}(\boldsymbol{r}, t)-\boldsymbol{B}_{2}(\boldsymbol{r}, t)\right]=0 \\
\boldsymbol{n}(\boldsymbol{r}) \cdot\left[\boldsymbol{D}_{1}(\boldsymbol{r}, t)-\boldsymbol{D}_{2}(\boldsymbol{r}, t)\right]=\sigma(\boldsymbol{r}, t)
\end{gathered}
$$

Normal pointing to region (1)

## Electromagnetic Potentials

$$
\begin{gathered}
\nabla \cdot \boldsymbol{A}(\boldsymbol{r}, t)=-\sigma \mu \varphi(\boldsymbol{r}, t)-\varepsilon \mu \frac{\begin{array}{c}
\text { Lorentz('s) } \\
\text { calibration }
\end{array}}{\partial t} \\
\boldsymbol{B}(\boldsymbol{r}, t)=\nabla \times \boldsymbol{A}(\boldsymbol{r}, t) \\
\boldsymbol{E}(\boldsymbol{r}, t)=-\nabla \varphi(\boldsymbol{r}, t)-\frac{\partial \boldsymbol{A}(\boldsymbol{r}, t)}{\partial t}
\end{gathered}
$$

## Wave Equation

$$
\Delta \boldsymbol{A}(\boldsymbol{r}, t)-\sigma \mu \frac{\partial \boldsymbol{A}(\boldsymbol{r}, t)}{\partial t}-\varepsilon \mu \frac{\partial^{2} \boldsymbol{A}(\boldsymbol{r}, t)}{\partial t^{2}}=-\mu \boldsymbol{J}_{\text {source }}(\boldsymbol{r}, t)
$$

Material parameters are assumed
independent of coordinates

## Poynting('s)-Umov('s) Theorem



Energy balance in an electromagnetic system

## Linear Momentum Carried by Fields

Volume integration considerably change the meaning of Poynting('s) vector


This formula is only valid in vacuum. In material media things are more tricky.

## Angular Momentum Carried by Fields

$$
\boldsymbol{L}=\frac{1}{c_{0}^{2}} \int_{V} \boldsymbol{r} \times(\boldsymbol{E} \times \boldsymbol{H}) \mathrm{d} V
$$

This formula is only valid in vacuum. In material media things are more tricky.

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## Frequency Domain



$$
\begin{aligned}
& \frac{\partial \boldsymbol{F}(\boldsymbol{r}, t)}{\partial t} \leftrightarrow j \omega \hat{\boldsymbol{F}}(\boldsymbol{r}, \omega) \\
& \text { es reduce to } \\
& \text { Itiplication }
\end{aligned} \frac{\partial \boldsymbol{F}(\boldsymbol{r}, t)}{\partial r_{\xi}} \leftrightarrow \frac{\partial \hat{\boldsymbol{F}}(\boldsymbol{r}, \omega)}{\partial r_{\xi}}
$$

Time derivatives reduce to algebraic multiplication

Spatial derivatives are untouched

Frequency domain helps us to remove explicit time derivatives

## Phasors

$$
\hat{\boldsymbol{F}}(\boldsymbol{r},-\omega)=\hat{\boldsymbol{F}}^{*}(\boldsymbol{r}, \omega) \quad \boldsymbol{F}(\boldsymbol{r}, t)=\frac{1}{\pi} \int_{0}^{\infty} \operatorname{Re}\left[\hat{\boldsymbol{F}}(\boldsymbol{r}, \omega) \mathrm{e}^{\mathrm{j} \omega t}\right] d \omega
$$

Reduced frequency domain representation

## Maxwell('s) Equations - Frequency Domain

$$
\begin{aligned}
& \nabla \times \hat{\boldsymbol{H}}(\boldsymbol{r}, \omega)=\hat{\boldsymbol{J}}(\boldsymbol{r}, \omega)+\mathrm{j} \omega \varepsilon \hat{\boldsymbol{E}}(\boldsymbol{r}, \omega) \\
& \nabla \times \hat{\boldsymbol{E}}(\boldsymbol{r}, \omega)=-\mathrm{j} \omega \mu \hat{\boldsymbol{H}}(\boldsymbol{r}, \omega) \\
& \nabla \cdot \hat{\boldsymbol{H}}(\boldsymbol{r}, \omega)=0 \\
& \nabla \cdot \hat{\boldsymbol{E}}(\boldsymbol{r}, \omega)=\frac{\hat{\rho}(\boldsymbol{r}, \omega)}{\varepsilon}
\end{aligned}
$$

We assume linearity of material relations

## Wave Equation - Frequency Domain

$$
\Delta \hat{\boldsymbol{A}}(\boldsymbol{r}, \omega)-\mathrm{j} \omega \mu(\sigma+\mathrm{j} \omega \varepsilon) \hat{\boldsymbol{A}}(\boldsymbol{r}, \omega)=-\mu \hat{\boldsymbol{J}}_{\text {sourre }}(\boldsymbol{r}, \omega)
$$

Helmholtz('s) equation

## Heat Balance in Time-Harmonic Steady State

$$
\begin{aligned}
& \text { Valid for general periodic steady state } \\
& \left.-\int_{V}\left\langle\boldsymbol{E} \cdot \boldsymbol{J}_{\text {source }}\right\rangle \mathrm{d} V=\oint_{S}\langle\boldsymbol{E} \times \boldsymbol{H}\rangle \cdot \mathrm{d} \boldsymbol{S}+\left.\int_{V}\langle\sigma| \boldsymbol{E}\right|^{2}\right\rangle \mathrm{d} V \\
& -\frac{1}{2} \int_{V} \operatorname{Re}\left[\hat{\boldsymbol{E}} \cdot \hat{\boldsymbol{J}}_{\text {source }}^{*}\right] \mathrm{d} V=\frac{1}{2} \oint_{S} \operatorname{Re}\left[\hat{\boldsymbol{E}} \times \hat{\boldsymbol{H}}^{*}\right] \cdot \mathrm{d} \boldsymbol{S}+\frac{1}{2} \int_{V} \sigma|\hat{\boldsymbol{E}}|^{2} \mathrm{~d} V \\
& \text { Valid for time mean } \\
& \text { Charmonic steady state }
\end{aligned}
$$

## Plane Wave

Electric and magnetic fields
are orthogonal to propagation direction

$$
\hat{\boldsymbol{H}}(\boldsymbol{r}, \omega)=\frac{k}{\omega \mu}\left[\boldsymbol{n} \times \boldsymbol{E}_{0}(\omega)\right] \mathrm{e}^{-\mathrm{j} k n \cdot \boldsymbol{r}}
$$

$$
\boldsymbol{n} \cdot \boldsymbol{E}_{0}(\omega)=0
$$

$$
\boldsymbol{n} \cdot \boldsymbol{H}_{0}(\omega)=0
$$

$$
k^{2}=-\mathrm{j} \omega \mu(\sigma+\mathrm{j} \omega \varepsilon)
$$

Wave-number

Unitary vector representing the direction of propagation

Electric and magnetic fields are mutually orthogonal

The simplest wave solution of Maxwell('s) equations

## Plane Wave Characteristics

$$
\begin{aligned}
& k=\sqrt{-\mathrm{j} \omega \mu(\sigma+\mathrm{j} \omega \varepsilon)} \\
& \operatorname{Re}[k]>0 ; \operatorname{Im}[k]<0 \\
& \lambda=\frac{2 \pi}{\operatorname{Re}[k]} \\
& v_{\mathrm{f}}=\frac{\omega}{\operatorname{Re}[k]} \\
& Z=\frac{\omega \mu}{k} \\
& \delta=-\frac{1}{\operatorname{Im}[k]}
\end{aligned}
$$

Vacuum

$$
k=\frac{\omega}{c_{0}}
$$

$$
\operatorname{Re}[k]>0 ; \operatorname{Im}[k]=0
$$

$$
\lambda=\frac{c_{0}}{f}
$$

 material

$$
v_{\mathrm{f}}=c_{0}
$$

$$
Z=c_{0} \mu_{0}=\sqrt{\frac{\mu_{0}}{\varepsilon_{0}}} \approx 377 \Omega
$$

$$
\delta \rightarrow \infty
$$

## Cycle Mean Power Density of a Plane Wave

Power propagation coincides with phase propagation

$$
\langle\boldsymbol{E}(\boldsymbol{r}, t) \times \boldsymbol{H}(\boldsymbol{r}, t)\rangle=\frac{1}{2} \frac{\operatorname{Re}[k]}{\omega \mu}\left|\boldsymbol{E}_{0}(\omega)\right|^{2} \mathrm{e}^{2 \operatorname{II}[k] n \cdot \boldsymbol{r}} \boldsymbol{n}
$$

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