Lecture 2: Complex Numbers, Editor, Matrix Creation A8B17CAS

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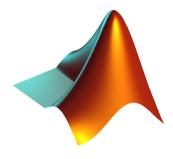
October 3 Winter semester 2023/24



Outline



- 1. Complex Numbers
- 2. Matlab Editor
- 3. System of Linear Equations
- 4. Vector and Matrix Creation



Warm Up: Adding Forces (Superposition)

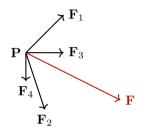


ightharpoonup Following forces were localized at point **P** in xy plane:

$$\mathbf{F}_1 = [2, 2]$$
 $\mathbf{F}_3 = [2, 0]$ $\mathbf{F}_2 = [1, -3]$ $\mathbf{F}_4 = [2, -1.5]$

- ▶ What is the direction of the resultant force **F**?
- ▶ Normalize the resulting vector.

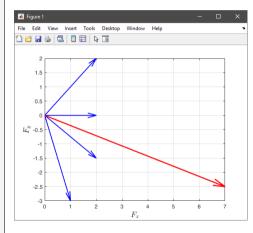
$$\mathbf{n}_{\mathrm{F}} = \frac{\mathbf{F}}{|\mathbf{F}|} = \frac{\mathbf{F}}{\sqrt{F_x^2 + F_y^2 + F_z^2}}$$







```
clear:
clc:
% User input
Fs = [2 2; 1 - 3; 2 0; 2 - 1.5];
F = sum(Fs, 1) % resulting force
%% Graphical output
Z = zeros(size(Fs. 1), 1):
figure ('color', 'w');
quiver(Z, Z, Fs(:,1), Fs(:,2), 0, ...
   'LineWidth', 1.5, 'Color', 'b');
hold on; % allows to have more graphs in a figure
quiver(0, 0, F(1), F(2), 0, ...
   'LineWidth', 2, 'Color', 'r');
grid on; % enable grid
% add labels (LaTeX interpreter possible)
option = {'Interpreter', 'LaTeX', 'FontSize', 14};
xlabel('$F x$', option{:});
ylabel('$F_y$', option{:});
```



Complex Numbers I.

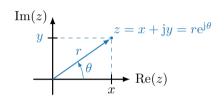


► Cartesian complex plane (real and imaginary parts)

$$z = x + jy$$

▶ Polar complex plane (modulus and argument)

$$z = |z| e^{j\phi}$$



Complex Numbers II.



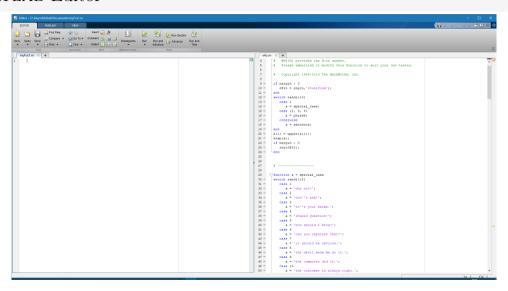
$$z = x + jy = |z| e^{j\phi}$$

\blacktriangleright Frequently used functions:

x, y	real, imag	real and imaginary parts of a complex number
z^*	conj	complex conjugate
z	abs	absolute value of a complex number
ϕ	angle	angle in complex plane [rad]
$x, y \to z$	complex	constructs complex number from real and imaginary parts
	isreal	checks if the input is a complex number (more on that later)
j	i, j	complex unit
	cplxpair	sort complex numbers into complex conjugate pairs

MATLAB Editor





Script Execution, m-files



- ► To execute a script:
 - ► F5 function key in MATLAB Editor,
 - ightharpoonup Current folder ightharpoonup select script ightharpoonup context menu ightharpoonup Run,
 - ightharpoonup Current folder \rightarrow select script \rightarrow F9,
 - ▶ from the command line:

>> script_name

- ▶ Scripts are stored as so called m-files, .m
- ► Caution: If you have MATHEMATICA installed, the .m files may be launched by MATHEMATICA.

Useful Shortcuts



F5 F9	run a script run selected code
$^{\%\%}_{\text{CTRL+SHIFT}}$	add cell run actual cell of code
$\begin{array}{c} \text{CTRL+R} \\ \text{CTRL+T} \end{array}$	comment selected code uncomment selected code

Script Commenting



- ► MAKE COMMENTS!!
 - ▶ Important/complicated parts of code.
 - ▶ Description of functionality, ideas, change of implementation.
- ► Typical single-line comment:

```
% create matrix, sum all members
matX = [1, 2, 3, 4, 5];
sumX = sum(matX); % sum of matrix
```

▶ Cell mode enables to separate script into more blocks:

```
matX = [1, 2, 3, 4, 5];
%% CELL mode (must be enabled in Editor)
sumX = sum(matX);
```

Cell Mode in MATLAB Editor



- ▶ Cells enable to separate the code into smaller, logically compacted parts.
 - ► Separator %%.
 - ► The separation is visual only, but it is possible to execute a single cell: shortcuts CTRL+ENTER and CTRL+SHIFT+ENTER.



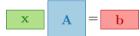
Solving System of Linear Equations in MATLAB



- ► Two cases are distinguished:
 - ▶ left division (\ mldivide),
 - ▶ right division (/ mrdivide).
- ▶ Solution of a linear system of equations:
 - ▶ A is an invertible (regular) matrix,
 - ▶ **b** is a column (row) vector.

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$
$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$$

$$\mathbf{x} = \mathbf{A} \cdot \mathbf{b}$$



$$xA = b$$

$$\mathbf{x} = \mathbf{b} \mathbf{A}^{-1}$$

Linear Equations



- ► Find the sum of diagonal elements (trace of a matrix) of the matrix **T** with elements coming from normal distribution with mean equal to 10 and standard deviation equal to 4.
- ► Find determinant of matrix **U**.

$$\mathbf{U} = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & 0 \\ 0 & -2 & -1 \end{bmatrix}$$

► Solve the linear system of equations:

$$x_1 + 2x_2 + 3x_3 = 6$$
 $\mathbf{A}\mathbf{x} = \mathbf{b}$
 $4x_1 + 5x_2 + 6x_3 = 15$ $\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$
 $7x_1 + 8x_2 + x_3 = 16$

$$>> T = 10 + 4*randn(7, 7);$$

Predefined Values in MATLAB



- ► Matlab contains several predefined values:
 - ▶ eps precision of single/double numbers (Determines the shortest distance between two single/double numbers).
 - ightharpoonup ans -answer-most recent answer.
 - ▶ NaN not a number (every expression containing NaN is NaN)
 - ▶ NaN can be used advantageously in some cases.
 - ightharpoonup Inf infinite number (variable Inf can be used in calculation)
 - ▶ Pay attention to Inf propagation throughout your code (use allowed operations only).
 - ▶ i, j complex unit.
 - ▶ They are all basically functions (without input parameter).
 - ► Check results of the following expressions:

```
>> t1 = 10/0 % t1 = Inf

>> t2 = 0/0 % t2 = NaN

>> t3 = t1*5 % t3 = Inf

>> t4 = t1 + t2 % t4 = NaN
```

Format of Command Line Output



Matlab offers number of other formatting options

- ▶ Use >> format style.
- ▶ Output format does not change neither the computation accuracy (single/double) nor the accuracy of stored results (eps, realmax, realmin, ...still apply).

style	format description	
short	fixed 4 decimal points are displayed	
long	15 decimal points for double precision, 7 decimal points for single precision	
shortE	floating-point format (scientific notation)	
longE	_//_	
compact	suppressed the display of blank lines	
and others	check >> doc format	

► Omitting style parameter restores default setup!

Format of Command Line Output



- ► Try following output format settings:
 - ► Each format is suitable for different type of problems.

```
>> clc;
>> s = [-5, 1/2, 1/3, 10*pi, sqrt(2), cos(pi/2)];
>> format compact
>> format long; s
>> format longE; s
>> format short; s
>> format shortE; s
>> format +; s
>> format; s
```

► Later, we will learn how to use formatted conversion into strings (commands sprintf and fprintf).

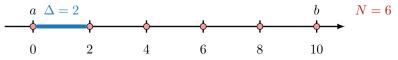
Entering Matrices Using ":" (Colon) Operator and linspace



Large vectors and matrices require automated input.

► For equidistantly spaced values from a to b with an increment x:

- ▶ b doesn't have to be an element of the series.
- \triangleright increment x can be negative.
- ► For N equidistantly spaced valued from a to b:



Entering Matrices I.



- ▶ Using the colon operator ":" create
 - ▶ the following vector

$$\mathbf{v} = [25 \ 20 \ \dots \ -5]^{\mathrm{T}}$$

- ▶ the following matrix
 - ► Caution, the third column can't be created using colon operator ":" only.

$$\mathbf{T} = \begin{bmatrix} -4 & 1 & \frac{\pi}{2} \\ -5 & 2 & \frac{\pi}{4} \\ -6 & 3 & \frac{\pi}{6} \end{bmatrix}$$

Entering Matrices II.



- \blacktriangleright Create a vector of 100 evenly spaced points in the interval [-1.15, 75.4].
- ▶ Create a vector of 201 evenly spaced points in the interval [-100, 100] sorted in descending order.
- ▶ Create a vector with spacing of -10 in the interval [100, -100] sorted in descending order.
 - ▶ Try both options using linspace and colon ":".

Entering Matrices Using Functions I.



- ▶ Special types of matrices of given sizes are needed quite often.
 - ► MATLAB offers a number of functions to serve the purpose., e.g., zeros, ones, NaN, inf, eye, rand, randn, randi, true, false.
- ► Example: matrix filled with zeros
 - ▶ Will be used frequently.

Entering Matrices Using Functions III.



- ► Create following matrices
 - ▶ use Matlab functions
 - ▶ begin with matrices you find easy to cope with.

$$\mathbf{M}_1 = \left[egin{array}{ccc} \mathrm{NaN} & \mathrm{NaN} \ \mathrm{NaN} & \mathrm{NaN} \end{array}
ight]$$

$$\mathbf{M}_2 = \left[\begin{array}{ccccc} 1 & 1 & 1 & 1 \end{array} \right]$$

$$\mathbf{M}_3 = \left[\begin{array}{ccc} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -5 \end{array} \right]$$

$$\mathbf{M}_4 = \left[\begin{array}{cccc} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Entering Matrices



- ▶ Quite often, there are several options how to create a given matrix.
 - ▶ It is possible to use an output of one function as an input of another function in MATLAB:
- ► Consider:
 - ▶ clarity,
 - ► simplicity,
 - ► speed,
 - ▶ convention.
- ▶ e.g. band matrix with "1" on main diagonal and with "2" and "3" on secondary diagonals.

```
N = 10; A = diag(ones(N, 1)) + diag(2 * ones(N - 1, 1), 1) + diag(3 * ones(N - 1, 1), -1)
```

- ▶ Can be done using for cycle as well (see later in the semester).
- ► Some other idea?

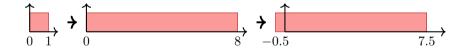
plot(diag(randn(10, 1), 1))

Generation of a Random Matrix



▶ Create matrix \mathbf{M} of size $size(M) = [3\ 4\ 2]$ containing random numbers coming from uniform distribution on the interval [-0.5, 7.5].

$$I(x) = (I_{\text{max}} - I_{\text{min}}) \operatorname{rand}(...) + I_{\text{min}}$$



Transpose and Matrix Conjugate



- ▶ Pay attention to situations where the matrix is complex, $\mathbf{A} \in \mathbb{C}^{M \times N}$.
- ► There are two operations:

$$\begin{array}{ll} \text{transpose} & \mathbf{A}^{\text{T}} = [A_{ij}]^{\text{T}} = [A_{ji}] & \text{transpose} \, (\texttt{A}) & \texttt{A.'} \\ \text{transpose} + \text{conjugate} & \mathbf{A}^{\text{H}} = [A_{ij}]^{\text{H}} = [\mathbf{A}^*]^{\text{T}} & \text{ctranspose} \, (\texttt{A}) & \texttt{A'} \end{array}$$

Matrix Operations I.



There are other useful functions apart from transpose (transpose), e.g.,

- ▶ vector to a diagonal matrix, matrix diagonal to a vector (diag),
- ▶ upper/lower triagular matrix (triu, tril),
- ► array replication (repmat),
- ► array reshape (reshape),
- ► array flip (flip),
- ► array rotation (rot90),
- ► circular shift (circshift),
- ▶ block-diagonal matrix from individual matrices (blkdiag),
- ▶ arranging two (or more) matrices side by side (cat),
- ▶ and many others...

Always check the documentation (» doc ...).

Matrix Operations II.



 \blacktriangleright Convert matrix **A** into the form of matrices \mathbf{A}_1 to \mathbf{A}_4 .

$$A = [1 pi; exp(1) -1i]$$

Use repmat, reshape, triu, tril and conj.

$$\mathbf{A}_{1} = \begin{bmatrix} 1 & \pi & 1 & \pi & 1 & \pi \\ e & -i & e & -i & e & -i \end{bmatrix}$$

$$\mathbf{A}_{2} = \begin{bmatrix} 1 & \pi & 0 & 0 & 0 & 0 \\ 1 & \pi & e & -i & e & -i \end{bmatrix}$$

$$\mathbf{A}_{3} = \begin{bmatrix} 1 & \pi & 0 & 0 & 0 & 0 \\ e & +i & \pi & e & -i \\ 1 & \pi & e & +i \\ 1 & \pi & e & +i \end{bmatrix}$$

$$\mathbf{A}_{4} = \begin{bmatrix} 1 & \pi & 0 & 0 & 0 & 0 \\ e & -i & e & 0 & 0 & 0 \\ 0 & \pi & 1 & \pi & 0 & 0 \\ 0 & 0 & e & -i & e & 0 \\ 0 & 0 & 0 & \pi & 1 & \pi \\ 0 & 0 & 0 & 0 & e & -i \end{bmatrix}$$

$$\mathbf{A} = \left[\begin{array}{cc} 1 & \pi \\ e & -i \end{array} \right]$$

$$\mathbf{A}_4 = \begin{bmatrix} 1 & \pi & 0 & 0 & 0 & 0 \\ e & -i & e & 0 & 0 & 0 \\ 0 & \pi & 1 & \pi & 0 & 0 \\ 0 & 0 & e & -i & e & 0 \\ 0 & 0 & 0 & \pi & 1 & \pi \\ 0 & 0 & 0 & 0 & e & -i \end{bmatrix}$$

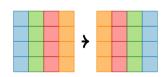
Matrix Operations III.



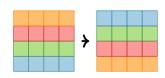
► Create the following matrix (use advanced techniques)

$$\mathbf{A} = \left[\begin{array}{cccccc} 1 & 2 & 3 & 1 & 2 & 3 \\ 0 & 2 & 4 & 0 & 2 & 4 \\ 0 & 0 & 5 & 0 & 0 & 5 \end{array} \right]$$

ightharpoonup Create matrix **B** by swapping columns in matrix **A**.



► Create matrix **C** by swapping rows in matrix **B**.



Matrix Operations IV. - Tensor Products



Kronecker tensor product

$$K = kron(A, B)$$

 Convolution kernel A is applied to a mask B.

Example:

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \otimes \frac{1}{2} \begin{bmatrix} 1 & -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 0 & 0 & 1 & -1 \\ 1 & -1 & 0 & 0 \end{bmatrix}$$

Tensor product

► Inner product

$$\sum_{n} \cdots \sum_{k} \sum_{j} A_{jk\cdots n} B_{jk\cdots n} = c$$

► Outer product

$$[A_{jk\cdots n}][B_{pq\cdots t}] = [C_{jk\cdots npq\cdots t}]$$

► Tensor product

$$\sum_{j} \cdots \sum_{p} \sum_{j} A_{jk\cdots n} B_{pq\cdots t} = [C_{k\cdots nq\cdots t}]$$

Size of Matrices and Other Structures I.



- ▶ It is often needed to know sizes of matrices and arrays.
- ► Function size returns vector giving the size of a matrix/array.

► Function length returns largest dimension of an array.

$$length(A) = max(size(A))$$

$$A = randn(3, 5, 8);$$

 $e = length(A) % e = 8$

▶ Function ndims returns number of dimensions of a matrix/array.

$$ndims(A) = length(size(A))$$

$$m = ndims(A) % m = 3$$

► Function numel returns number of elements of a matrix/array.

$$numel(A) = prod(size(A))$$

► Functions height and width return number of rows and columns, respectively.

Size of Matrices and Other Structures II.



- ► Create an arbitrary 3D array.
 - ▶ You can make use of the following commands:

```
A = rand(2 + randi(10), 3 + randi(5));

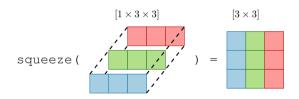
A = cat(3, A, rot90(A, 2))
```

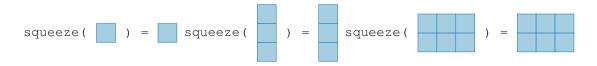
- ► And now:
 - ► Find out the size of A.
 - ► Find the number of elements of A.
 - ▶ Find out the number of elements of A in the "longest" dimension.
 - ▶ Find out the number of dimensions of A.

Squeeze



- ▶ Function squeeze removes dimension of an array with length 1.
 - ▶ If the input is scalar, vector or array without any dimension of the length 1, the output is identical to the input.





Function gallery



- ► Function enabling to create a vast set of matrices that can be used for MATLAB code testing.
- ▶ Most of the matrices are special-purpose.
 - ► Function gallery offers significant coding time reduction for advanced MATLAB users.
- ► See: doc gallery
- ► Try for instance:

```
gallery('pei', 5, 4)
gallery('leslie', 10)
gallery('clement', 8)
```

Questions?

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