



Humanoid Robots & Human-Robot Interaction

Doc. Mgr. Matěj Hoffmann, Ph.D.

Department of Cybernetics, Faculty of Electrical Engineering

Czech Technical University in Prague

matej.hoffmann@fel.cvut.cz

<https://sites.google.com/site/matejhof>

<https://cyber.felk.cvut.cz/research/groups-teams/humanoids/>



Overview

- Subject description:
 - [B3M33HRO Humanoidní roboti](#) / [BE3M33HRO Humanoid robots](#)
- Course website and rules of the game:
 - <https://cw.fel.cvut.cz/wiki/courses/hro/start>
- Literature and resources:
 - lectures and lecture slides
 - <https://cw.fel.cvut.cz/wiki/courses/hro/literature>
- Timetable:
 - <https://fel.cvut.cz/cz/education/rozvrhy-ng/public/html/predmety/66/52/p6652106.html>
 - <https://fel.cvut.cz/en/education/rozvrhy-ng/public/html/predmety/66/53/p6653806.html>

Team

Lectures

Matěj
Hoffmann



<https://cyber.felk.cvut.cz/research/groups-teams/humannoids/>

Labs

Lukáš Rustler



Shubhan Patni



Jason Khoury



Jakub Rozlivek



What is a robot?

any **automatically** operated machine that **replaces human effort**, though it **may not resemble human beings** in appearance or perform functions in a humanlike manner.

<https://www.britannica.com/technology/robot-technology>

a machine that **resembles a living creature** in being capable of moving independently (as by walking or rolling on wheels) and performing complex actions (such as grasping and moving objects)

often: such a machine built to **resemble a human being or animal in appearance and behavior**

<https://www.merriam-webster.com/dictionary/robot>

[M.H. added emphasis]

What Is a Robot?*

By Rodney Brooks

Shall I compare thee to creatures of God?
Thou art more simple and yet more remote.
You move about, but still today, a clod,
You sense and act but don't see or emote.

You make fast maps with laser light all spread,
Then compare shapes to object libraries,
And quickly plan a path, to move ahead,
Then roll and touch and grasp so clumsily.

You learn just the tiniest little bit,
And start to show some low intelligence,
But we, your makers, Gods not, we admit,
All pledge to quest for genuine sentience.

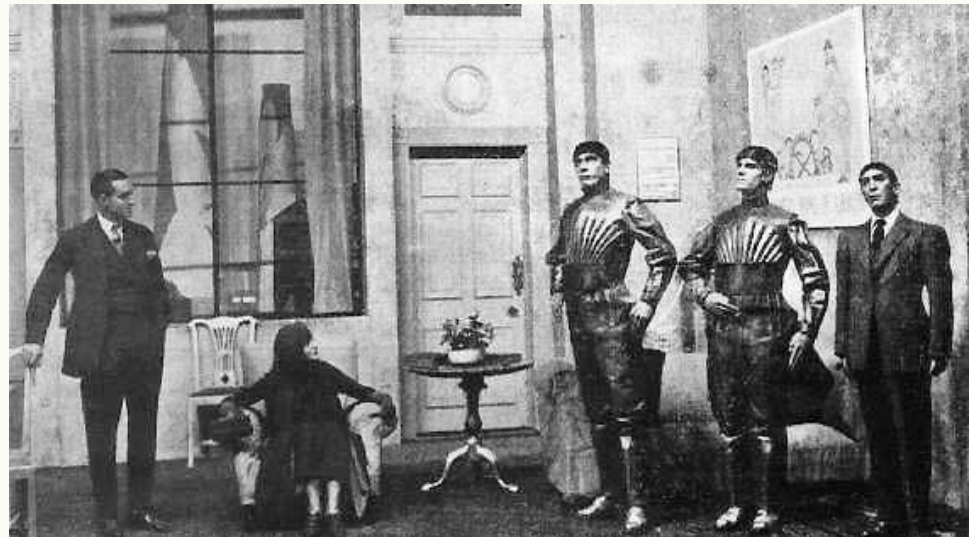
So long as mortals breathe, or eyes can see,
We shall endeavor to give life to thee.

* With thanks to William Shakespeare

History and etymology

The concept of artificial humans predates recorded history (see [automaton](#)), but the modern term *robot* derives from the Czech word *robota* ("forced labour" or "serf"), used in [Karel Čapek's](#) play [R.U.R.](#) (1920). The play's robots were manufactured humans, heartlessly exploited by factory owners until they revolted and ultimately destroyed humanity.

<https://www.britannica.com/technology/robot-technology>



Automata in history



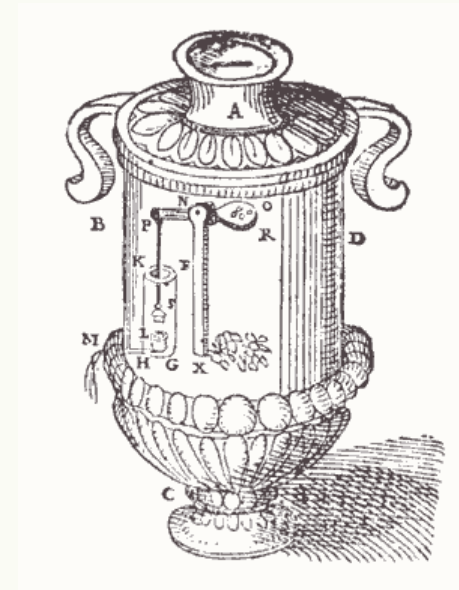
Talos (Τάλως)

Year	Invention
1000BC	Talos
100AD	Early automata
1500s	Leonardo da Vinci's Mechanical Lion
1580s	Rabbi Loew's Golem
1700s	Pierre Jaquet-Droz' Writing automaton
1738	Jacques de Vaucanson Mechanical Duck
1816	Mary Shelley
1833	Babbage's difference engines
1926	Metropolis: Maria
1961	George Devol's Unimate

From Greek mythology - a giant automaton made of bronze to protect Europa in Crete from pirates and invaders. He circled the island's shores three times daily.

Automata in history

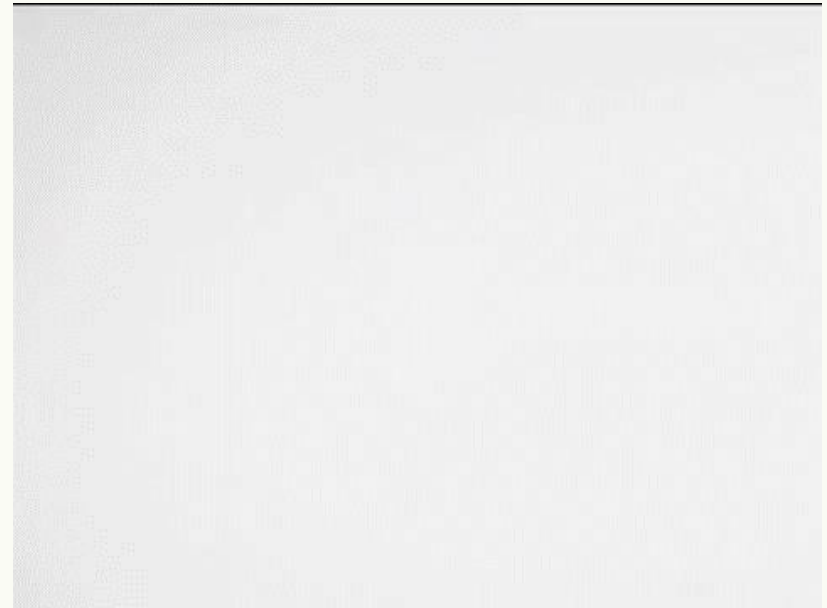
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Heron of Alexandria: the world's first vending machine dispensed holy water. Temple visitors would insert a coin into Heron's machine that would fall onto a lever which would open a valve and let water flow out

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“Robots” in History

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[Slide source – courtesy Alessandro Roncone]

The First Commercial Robot (Unimate, 1961)



Why humanoid robots?

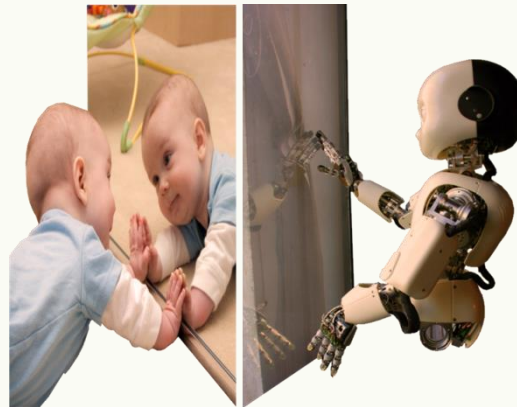
Humans are so good...
“Moreover, humans are generalists with the ability to perform a wide variety of distinct tasks. Roboticists would like to create robots with comparable versatility and skill.... Exactly what to borrow from the human example is controversial.”

“The pleasing mirror. Humans are humanity’s favorite subject.” “People are highly attuned to human characteristics.”

Human interaction.
Communication...



Fig. 56.1 The humanoid robot HRP-1S driving a backhoe (Courtesy of Kawasaki Heavy Industries, Tokyu Construction and AIST). The robot can be teleoperated by a human operator to control the backhoe remotely. The same robot could potentially interface with many different unmodified machines



Human environments.
Stairs, doors, tables, human tools...
Humanoids vs. specialized machines and drive-by-wire....

Test-bed for theories from psychology and neuroscience.
Understanding (human) intelligence by building.

Robots and humans

Robots and Humans

Front Matter

Pages 1789-1789

Humanoids

Paul Fitzpatrick, Kensuke Harada, Charles C. Kemp, Yoshio Matsumoto, Kazuhito Yokoi, Eiichi Yoshida
Pages 1789-1818

Human Motion Reconstruction

Katsu Yamane, Wataru Takano
Pages 1819-1834

Physical Human–Robot Interaction

Sami Haddadin, Elizabeth Croft
Pages 1835-1874

Human–Robot Augmentation

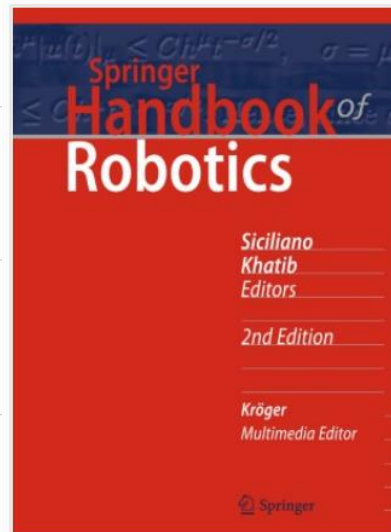
Massimo Bergamasco, Hugh Herr
Pages 1875-1906

Cognitive Human–Robot Interaction

Bilge Mutlu, Nicholas Roy, Selma Šabanović
Pages 1907-1934

Social Robotics

Cynthia Breazeal, Kerstin Dautenhahn, Takayuki Kanda
Pages 1935-1972



Socially Assistive Robotics

Maja J. Matarić, Brian Scassellati
Pages 1973-1994

Learning from Humans

Aude G. Billard, Sylvain Calinon, Rüdiger Dillmann
Pages 1995-2014

Biologically Inspired Robotics

Fumiya Iida, Auke Jan Ijspeert
Pages 2015-2034

Evolutionary Robotics

Stefano Nolfi, Josh Bongard, Phil Husbands, Dario Floreano
Pages 2035-2068

Neurorobotics: From Vision to Action

Patrick van der Smagt, Michael A. Arbib, Giorgio Metta
Pages 2069-2094

Perceptual Robotics

Heinrich Bülthoff, Christian Wallraven, Martin A. Giese
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Robotics for Education

David P. Miller, Illah Nourbakhsh
Pages 2115-2134

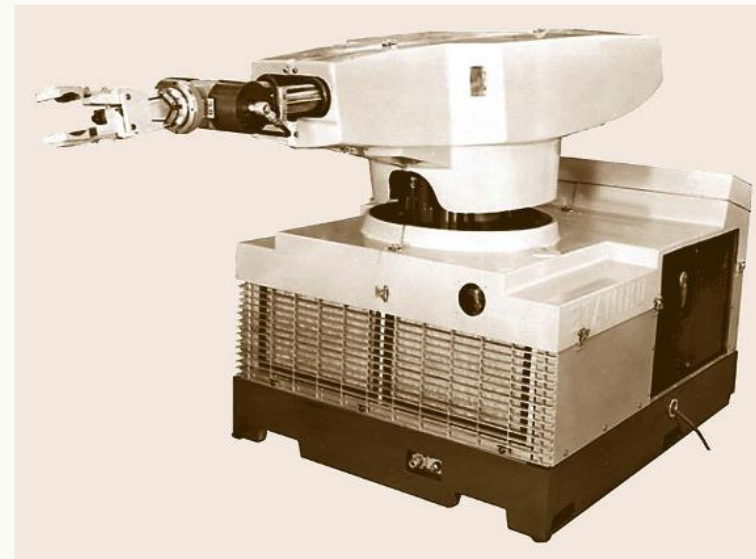
Roboethics: Social and Ethical Implications

Gianmarco Veruggio, Fiorella Operto, George Bekey
Pages 2135-2160

From robots replacing people...

D³ = Dull, Dirty, and
Dangerous tasks
[Gill Pratt]

Increase of automation
leads to increase of
productivity



...to **people helping** robots...

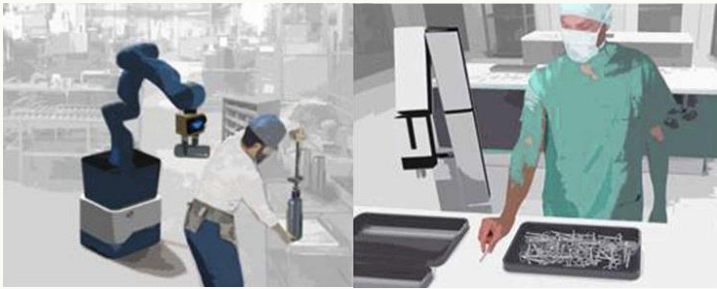


D³ = Dull, Dirty, and Dangerous tasks [Gill Pratt]

Increase of **collaboration** leads to increase of productivity



...or robots helping people



Humanoid robots – history – WABOT

- 1973 – WABOT-1 - Ichiro Kato et al. @ Waseda University

“The WABOT robots integrated functions that have been under constant elaboration since: visual object recognition, speech generation, speech recognition, bimanual object manipulation, and bipedal walking.”

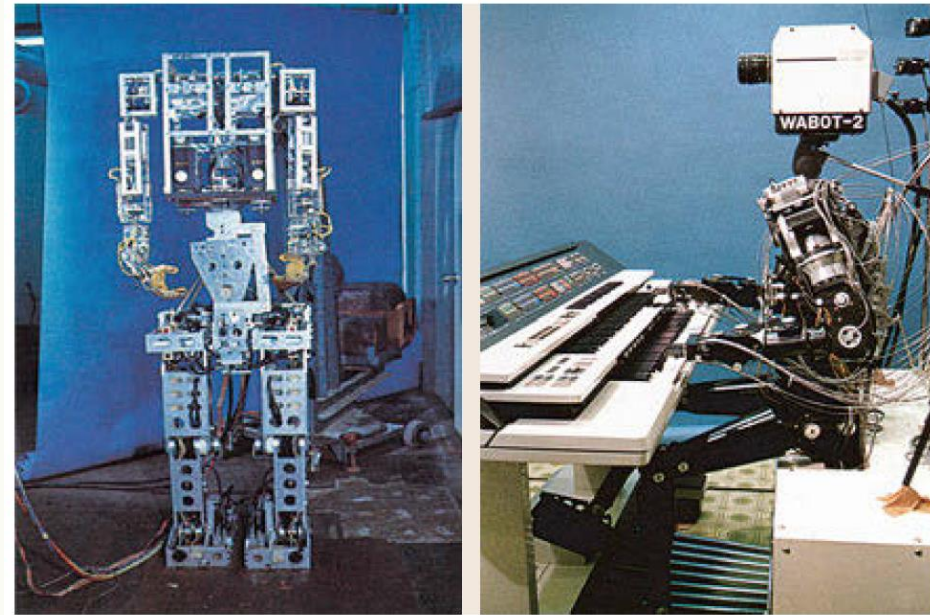
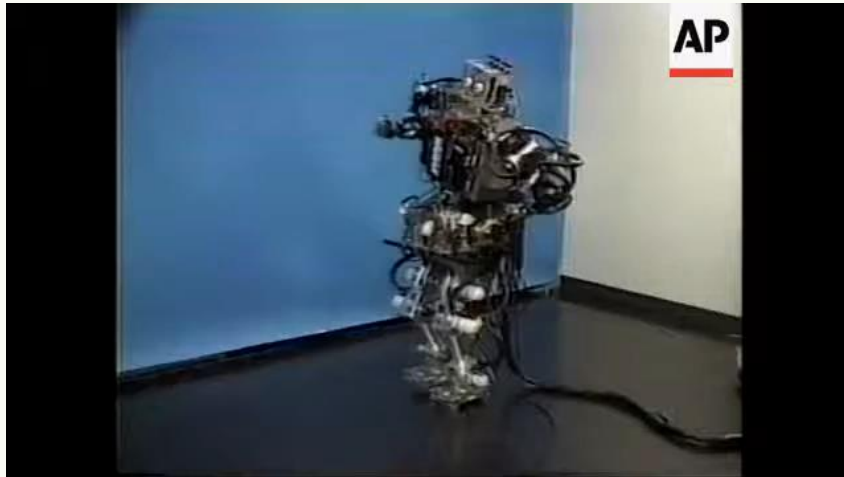


Fig. 67.8 (a) WABOT-1 (1973) and (b) WABOT-2 (1984; courtesy Humanoid Robotics Institute, Waseda University)



check also

<https://robots.ieee.org/robots/>

<https://youtu.be/E9PyANzjeoY>

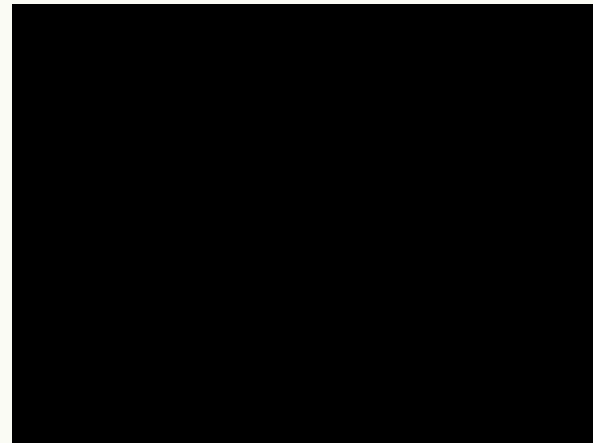
Humanoid robots – history – Honda ASIMO

- Honda project, i.e. not a university project
- Started in 1986 as a confidential project to create a humanoid biped.
- In 1996, Honda unveiled the Honda Humanoid P2
 - first full-scale humanoid capable of stable bipedal walking with onboard power and processing
- leap forward in sturdiness, using specially cast lightweight high-rigidity mechanical links, and harmonic drives with high torque capacity.



Fig. 67.9 (a) Honda P2 (180 cm tall, 210 kg), (b) P3 (160 cm, 130 kg), and (c) advanced step in innovative mobility (glossnoidx-ASIMO advanced step in innovative mobility) (120 cm, 43 kg) (after [67.31]; courtesy Honda)

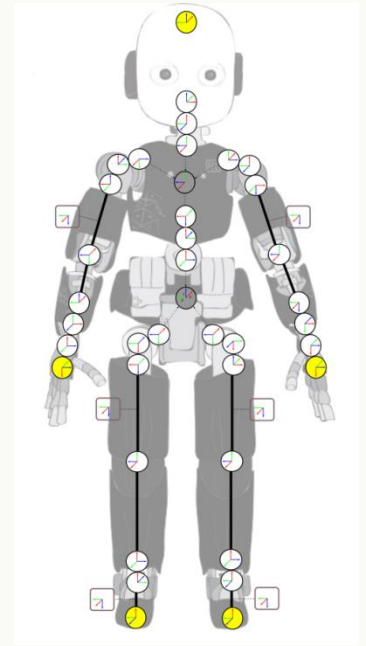
<https://youtu.be/NZngYDDdfW4>



Note:
anthropomorphization

The iCub humanoid (2004 – now)

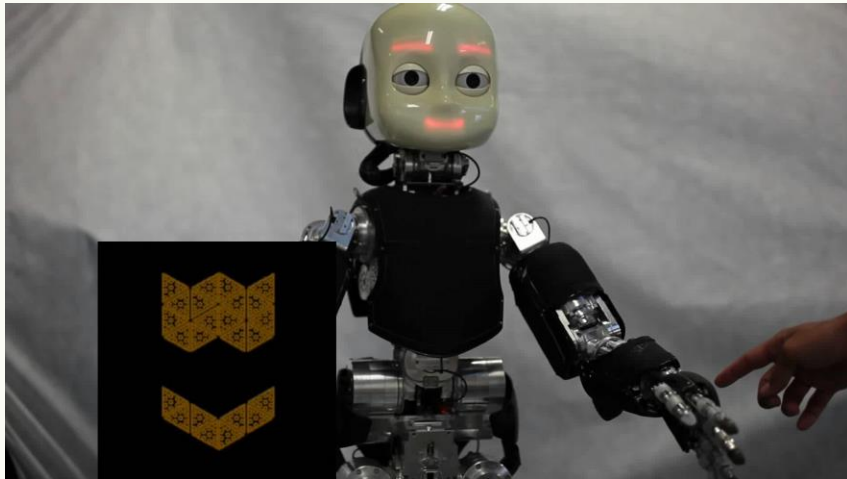
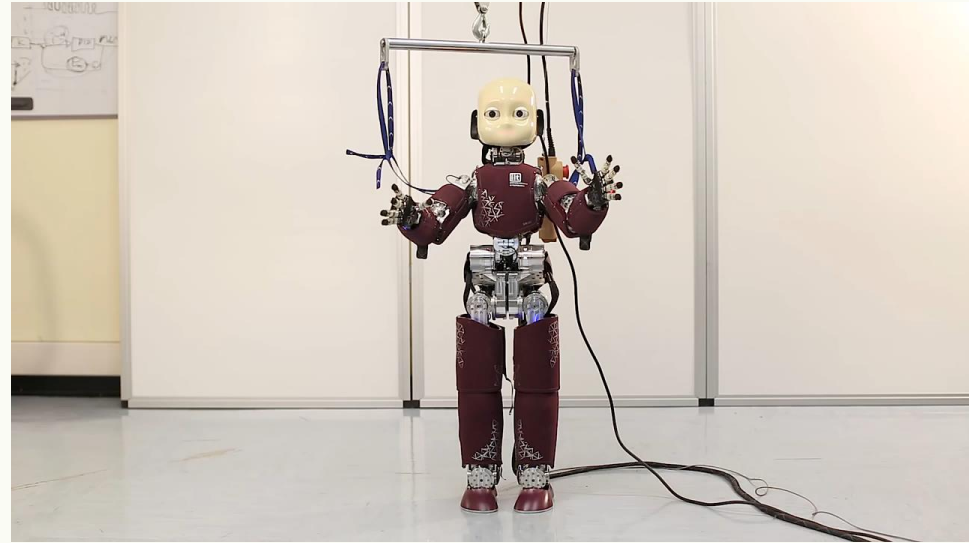
- Size of a 4 year old child
- Motor / proprioception (joint angles)
 - 53 DOF
- **Tactile information**
 - cca 4000 pressure-sensitive tactile elements (taxels) on the whole body
- Vision
 - 2 standard cameras in biomimetic DOF setup (pan, tilt, vergence)
- Force/torque sensors
- Inertial sensors
- Microphones...



iCub (videos)

iCub youtube channel: <https://www.youtube.com/channel/UCXBFWo4IQFkSJBfqdNrE1cA>

<https://youtu.be/UPQLcE1vwAQ>



<https://youtu.be/pfse424t5mQ>

Roncone, A.; Hoffmann, M.; Pattacini, U. & Metta, G. (2014), Automatic kinematic chain calibration using artificial skin: self-touch in the iCub humanoid robot, in 'Robotics and Automation (ICRA), 2014 IEEE International Conference on', pp. 2305-2312.

iCub at the center of this course

- Why?
 - it is a universal versatile platform – we can study kinematics, dynamics, reaching, grasping, walking, balancing, ...
 - it is a standard research platform – with 50 exemplars around the world (see <https://robot-bazaar.iit.it/robots>)
 - it is open source; large collection of modules and training materials available (<https://github.com/robotology>, <https://github.com/vvv-school>, <https://github.com/icub-training>)
 - it is available in our lab!

Nao robot (2008 – now)

- 2008, Aldebaran/Softbank
- Currently in V6
- Used as a unified platform for research, social HRI in particular
- Used also for robot football - Robocup
- Allows easy control via Choregraphe

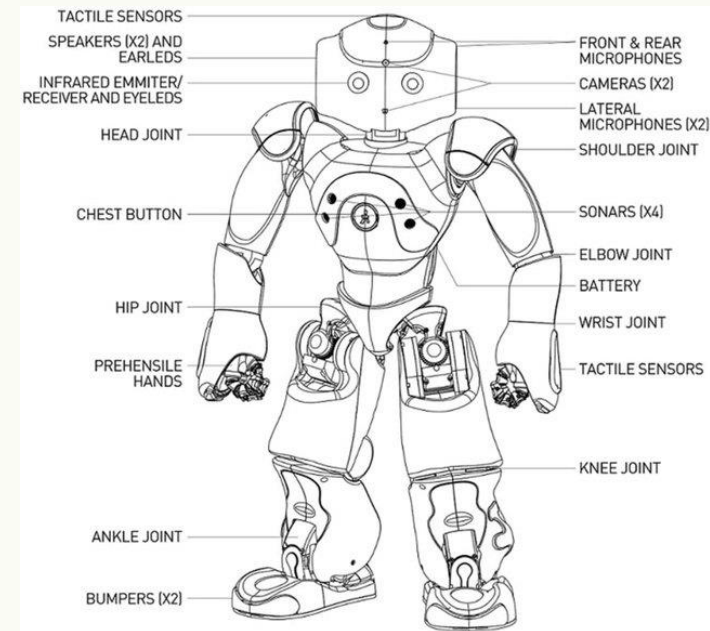
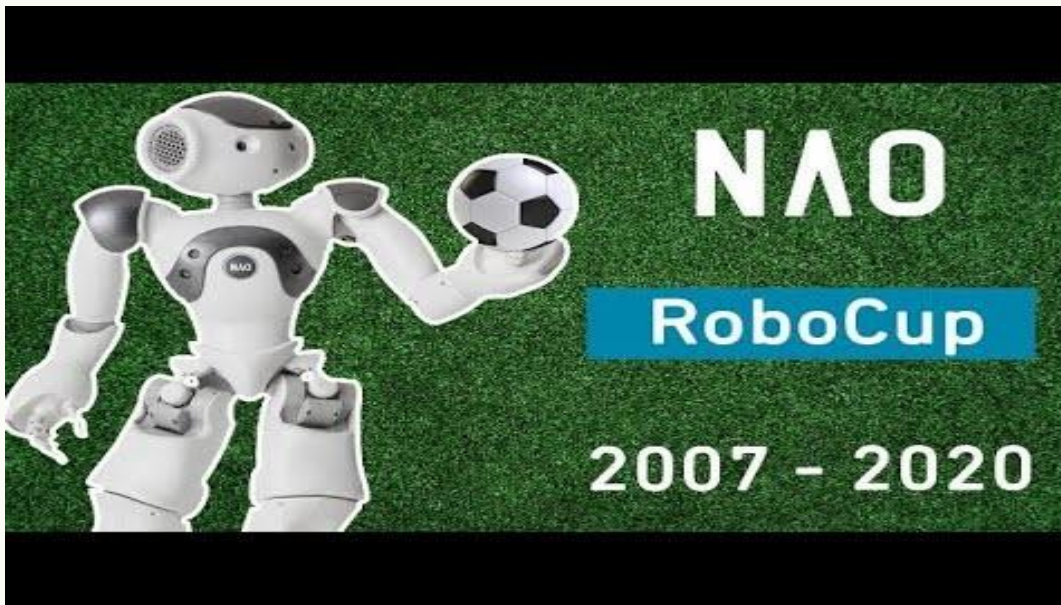


image courtesy of [Softbank robotics](https://www.softbankrobotics.com)

Pepper robot (2014 – now)

- Spiritual successor to Nao, 2014
- Humanoid robot aimed at social interaction
- More widely used in practice (e.g., stores)
- Similar basic design, equipment, and software

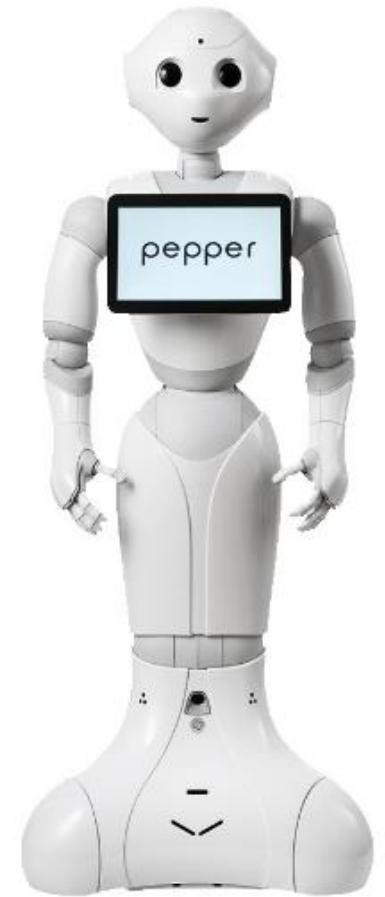
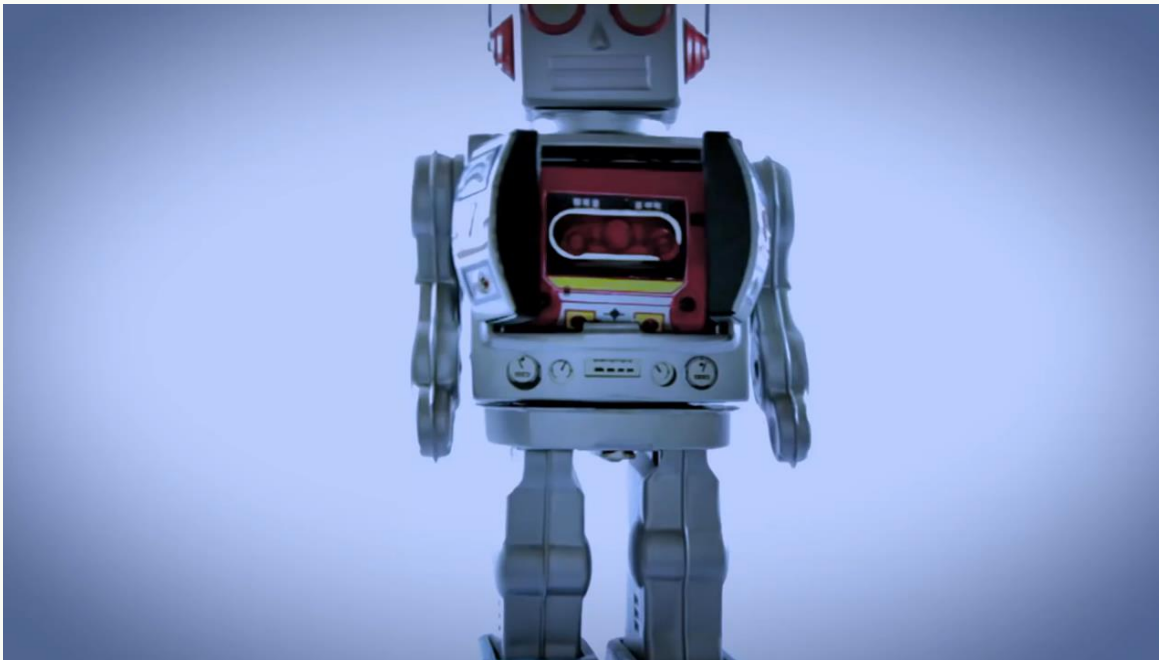


image courtesy of [IEEE robots](#)

<https://youtu.be/oDeQC1krLvc>

DARPA Robotics Challenge (DRC) (2012-2015)

- aimed to develop semi-autonomous ground robots that could do "complex tasks in dangerous, degraded, human-engineered environments"
- 7/18 teams with Atlas (Boston Dynamics)



<https://youtu.be/g0TaYhjp0fo>

Alternative designs



Winner: KAIST – DRC Hubo

<https://youtu.be/H3PptkxA5CU>

3rd – CHIMP CMU Tartan Rescue
<https://youtu.be/Wi2WsPUYDoY>

DARPA Robotics Challenge



Carnegie Mellon University
TARTAN RESCUE

PIs: Tony Stentz, Alonzo Kelly, Herman Herman, Eric Meyhofer
Systems Lead: David Stager

DARPA PM: Dr. Gill Pratt

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Resources

- Nenchev, D. N., Konno, A., & Tsujita, T. (2018). *Humanoid robots: Modeling and control*. Butterworth-Heinemann. [[LINK](#)]
- Fitzpatrick, P., Harada, K., Kemp, C. C., Matsumoto, Y., Yokoi, K., & Yoshida, E. (2016). Humanoids. In *Springer handbook of robotics* (pp. 1789-1818). Springer, Cham.
- Slides from Alessandro Roncone @ University of Colorado Boulder (Introduction to Robotics and Physical Human-Robot Interaction).