One dimensional searching

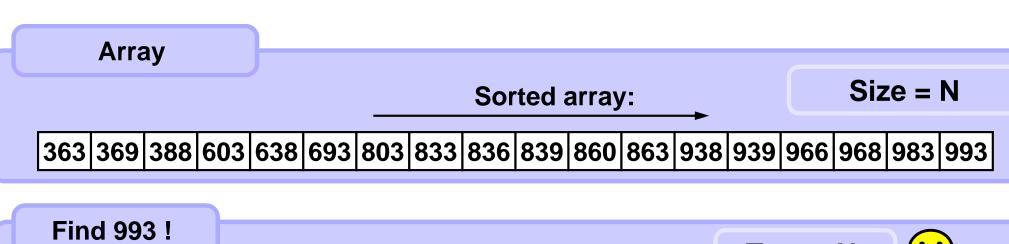
Searching in an array

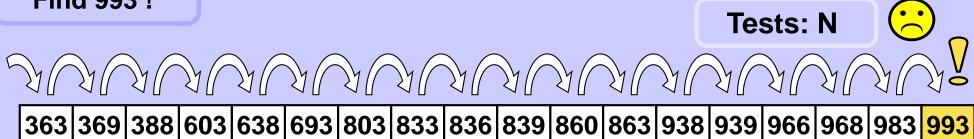
naive search, binary search, interpolation search

Binary search tree (BST)

operations Find, Insert, Delete

Naive search in a sorted array — linear, SLOW.





Find 363!



Tests: 1



363 369 388 603 638 693 803 833 836 839 860 863 938 939 966 968 983 993



Search in a sorted array — binary, FASTER



Find 863!







Search in a sorted array — binary, FASTER



Find q = 863!

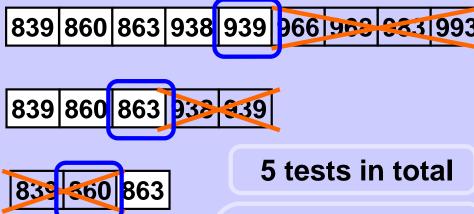


Typically, on average, the query value is *encountered* and/or found later in the search.

It takes too much time to test each value in the tree during the search descent to the leaf.

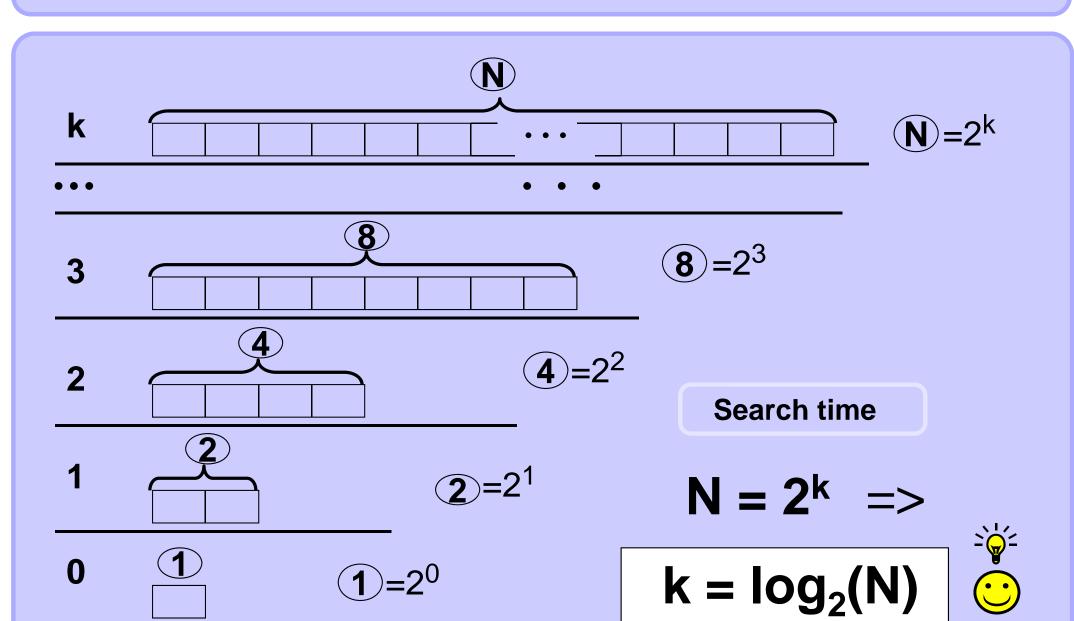
Therefore, the method first finds the exact place where the query value should be located and only then it checks if the value is really there.

During the search, the current segment is divided to two halves and the unpromissing half is discarded. The final test "Is q in the array?" is performed only once, when the current segment length is 1.



Though the query value 863 was encountered already in the 3rd check, its presence in the array was confirmed only after the 4th test.

Search in a sorted array — binary, FASTER

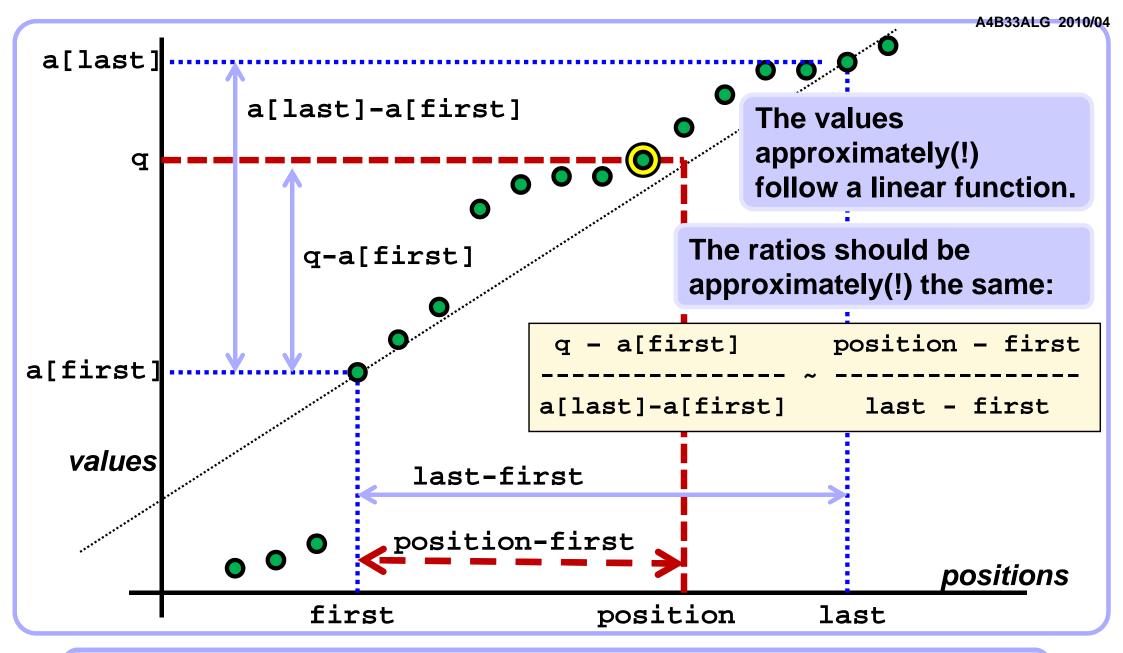


Binary search -- fast variant

Bug?: When low + high > INT_MAX in some languages overflow appears https://research.googleblog.com/2006/06/extra-extra-read-all-about-it-nearly.html

Array a[] Find
$$q = 939$$

When the values are expected to be more or less evenly distrubuted over the range then the interpolation search might help. The position of the element should roughly correspond to its value.



```
q - a[first]
position <-- first + ------ * (last - first)
a[last]-a[first]
```

If the query value is not found in the first attempt then continue the search recursively in the remaining part of the array which was not excluded from the search yet.

If the query value is not found in the next attempt then continue the search recursively in the remining part of the array which was not excluded from the search yet.

```
def interpolationSearch( arr, q ): # q is the query
    first = 0; last = len(arr)-1
    while True:
       # found?
        if first == last :
            if arr[first] == q: return pos
           else:
                                return -1
        # continue search
        pos = first + round( (q-arr[first])/
                        (arr[last]-arr[first]) * (last-first) )
        if arr[pos] == q: return pos
        if arr[pos] < q: first = pos+1 # check left side</pre>
                      last = pos-1 # check right side
        else:
```

Search in a sorted array — speed comparison

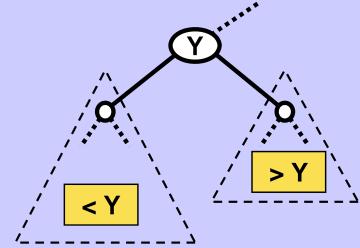
	Method		
Array	Linear search	Interpolation search	Binary search
size N	average case	average case	all cases
10	5.5	1.60	4
30	15.5	2.12	5
100	50.5	2.56	7
300	150.5	2.89	9
1 000	500.5	3.18	10
3 000	1 500.5	3.41	12
10 000	5 000.5	3.63	14
30 000	15 000.5	3.80	15
100 000	50 000.5	3.96	17
300 000	150 000.5	4.11	19
1 000 000	500 000.5	4.24	20
Asymptotic complexity	Obviously ⊕(n)	Random uniform distribution $log_2(log_2(N)) \in \Theta(log(log(N)))$	Due to the binary tree structure Θ(log(n))

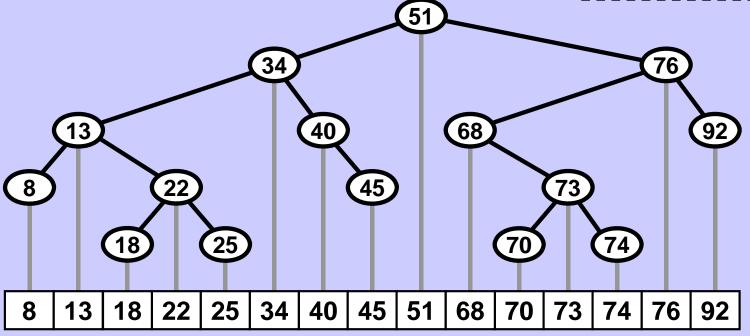
Binary search tree

For each node Y it holds:

Keys in the left subtree of Y are smaller than the key of Y.

Keys in the right subtree of Y are bigger than the key of Y.



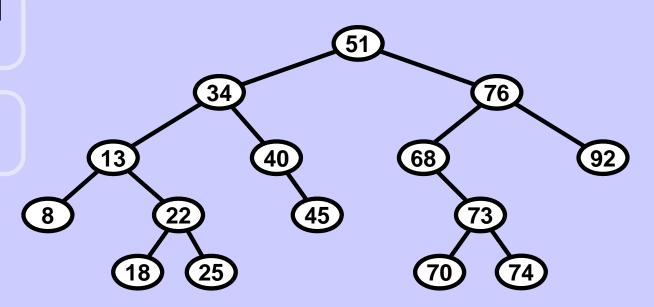


Binary search tree

BST may not be balanced and usually it is not.

BST may not be regular and usually it is not.

Apply the INORDER traversal to obtain sorted list of the keys of BST.

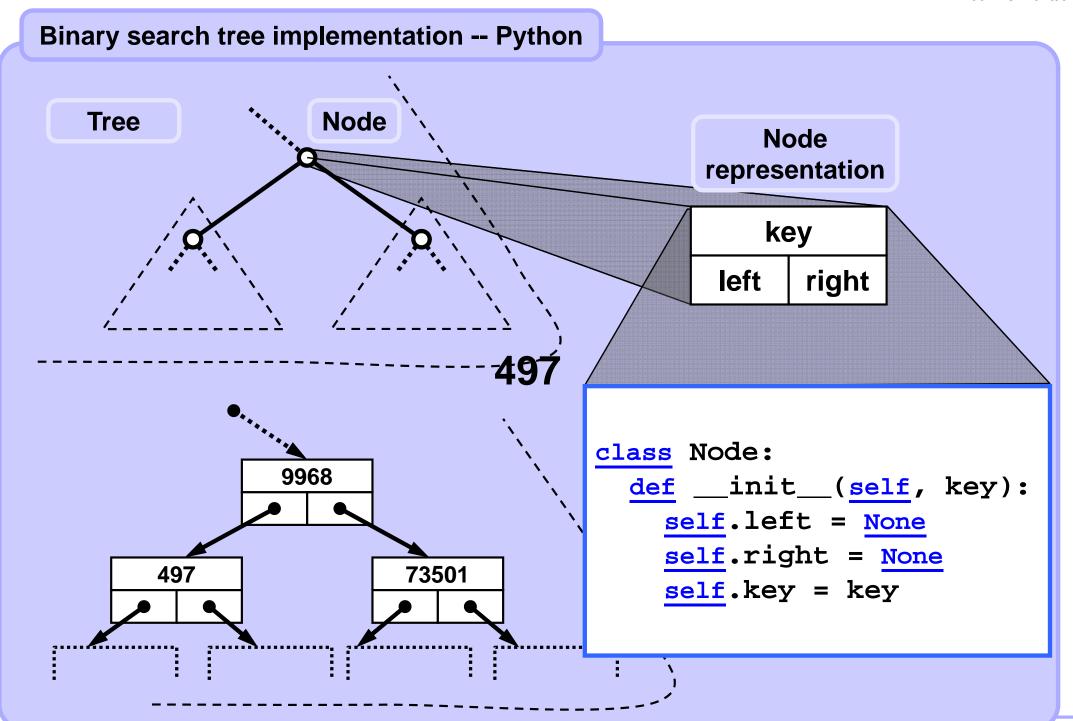


BST is flexible due to the operations:

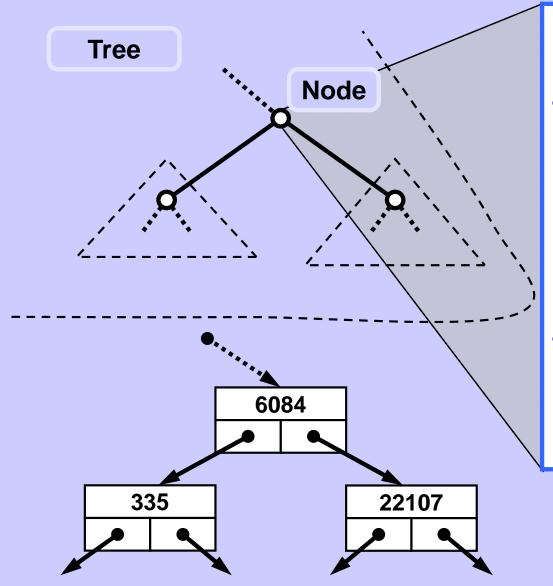
Find – return the pointer to the node with the given key (or null).

Insert – insert a node with the given key.

Delete – (find and) remove the node with the given key.



Binary search tree implementation -- Python



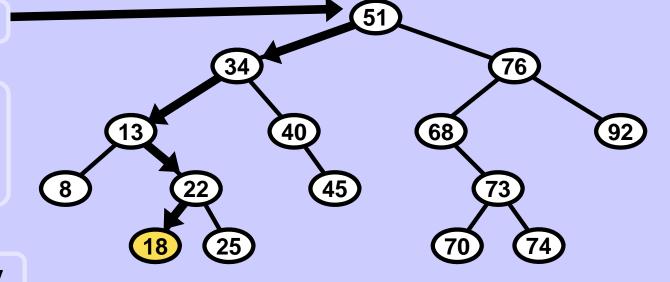
```
class Node:
    def __init__(self, key):
        self.left = None
        self.right = None
        self.key = key
```

```
class BinaryTree:
    def __init__(self):
        self.root = None
```

Operation Find in BST



Each BST operation starts in the root.



Iteratively

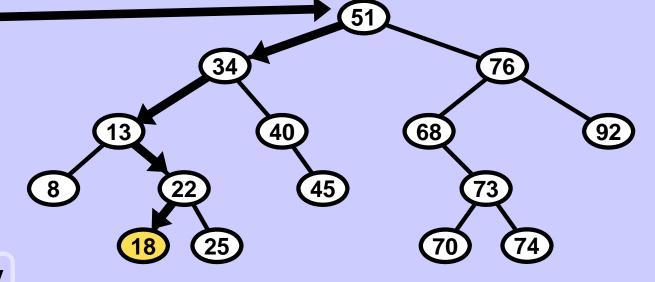
```
def FindIter(se key, node):
    while( True):
    if node == None : return None
    if key == node.key : return node
    if key < node.key : node = node.left
    else : node = node.right</pre>
```

FindIter(key, tree.root) # call

Operation Find in BST

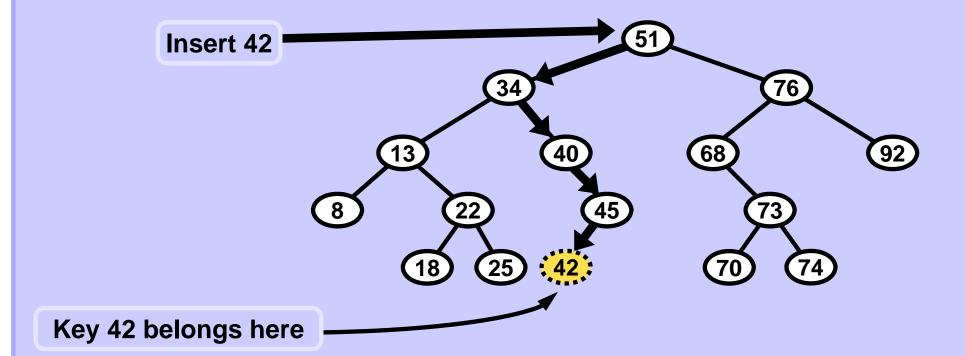


Each BST operation starts in the root.



Recursively

Operation Insert in BST



Insert

- 1. Find the place (like in Find) for the leaf where the key belongs.
- 2. Create this leaf and connect it to the tree.

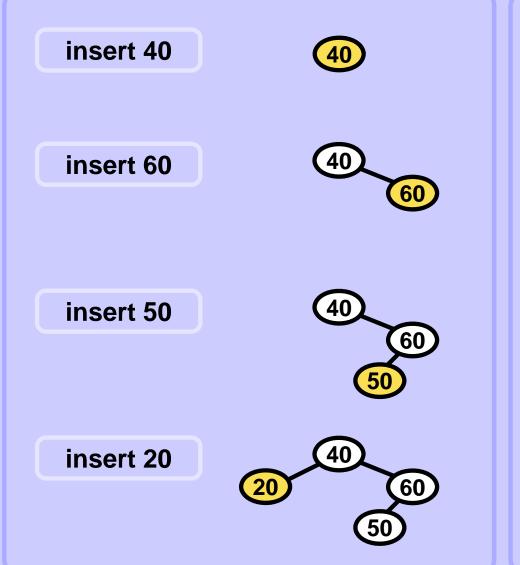
Operation Insert in BST iteratively

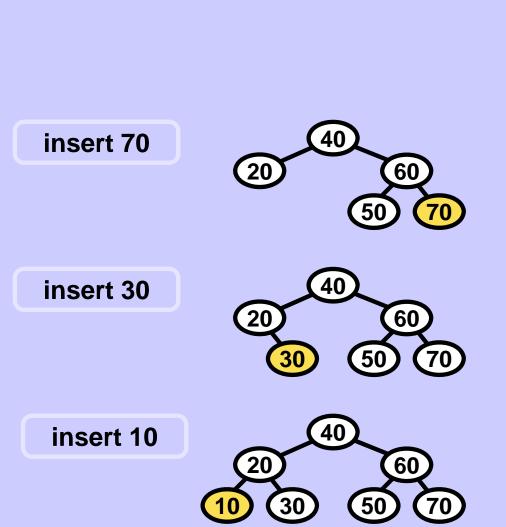
```
def InsertIter( self, key ):
                                        # empty tree
    if self.root == None:
        self.root = Node( key );
        return self.root
    node = self.root
    while True:
        if key == node.key: return None # no duplicates!
        if key < node.key:</pre>
            if node.left == None:
                node.left = Node( key )
                return node.left
            else: node = node.left
        else:
            if node.right == None:
                node.right = Node( key )
                return node.right
            else: node = node.right
```

Operation Insert in BST recursively

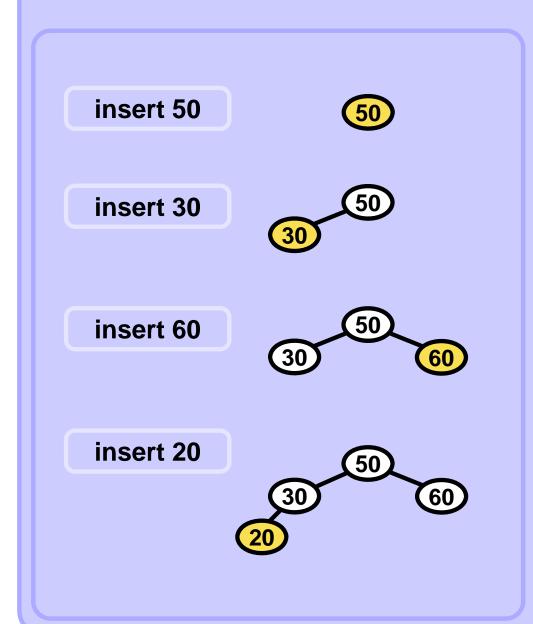
```
def Insert( self, key, node ):
    if key == node.key: return None # no duplicates
    if key < node.key:</pre>
        if node.left == None: node.left = Node( key )
        else:
                                self.Insert( key, node.left )
    else:
        if node.right == None: node.right = Node( key )
        else:
                                self.Insert( key, node.right )
# call
if self.root == None:
   self.root = Node( key )
else: Insert( key, self.root )
```

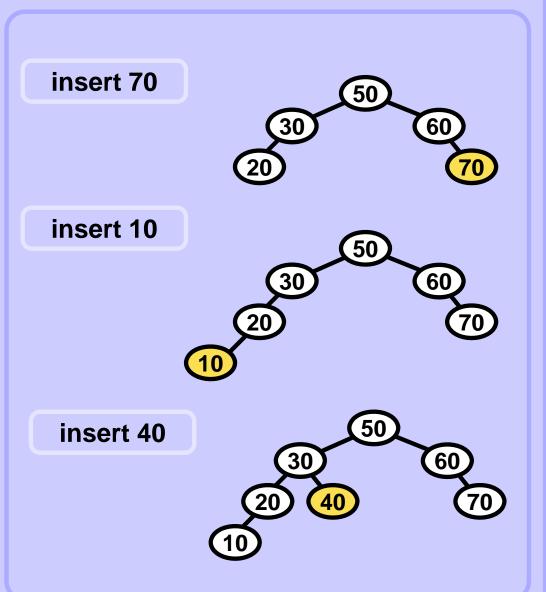
Building BST by repeated Insert



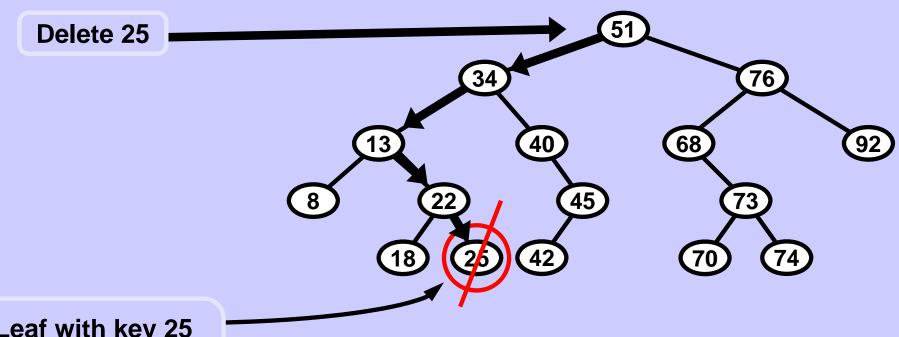


The shape of the BST depends on the order in which data are inserted.





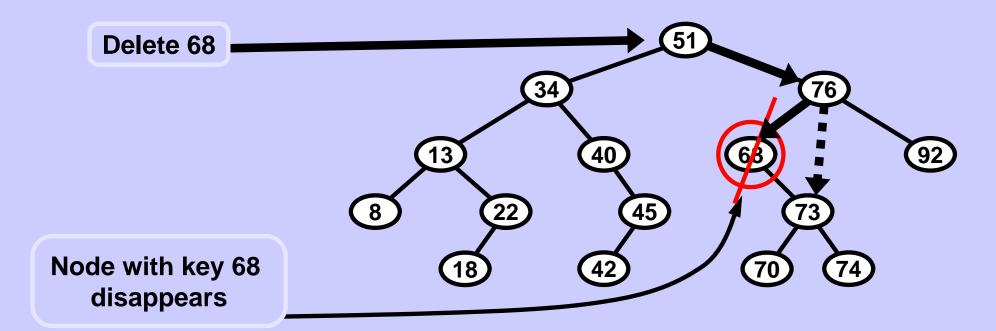
Delete the key in a node with 0 children (= leaf)



Leaf with key 25 disappears

Delete I. Find the node (like in Find operation) with the given key and set the reference to it from its parent to null (None).

Delete the key in a node with 1 child.

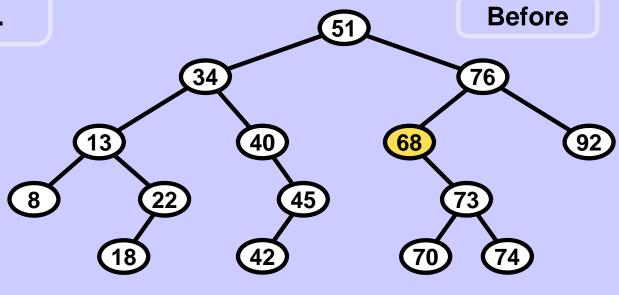


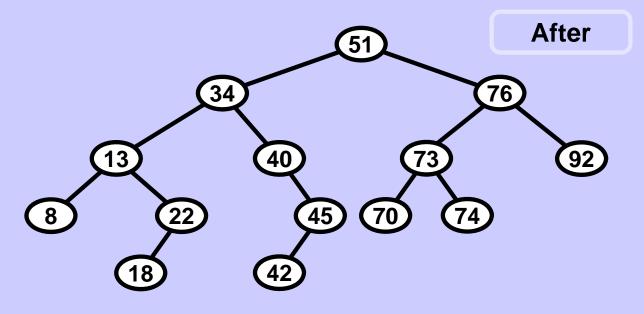
Change the 76 --> 68 reference to 76 --> 73 reference.

Delete II. Find the node (like in Find operation) with the given key and set the reference to it from its parent to its (single) child.

Delete a node with 1 child.

Delete 68

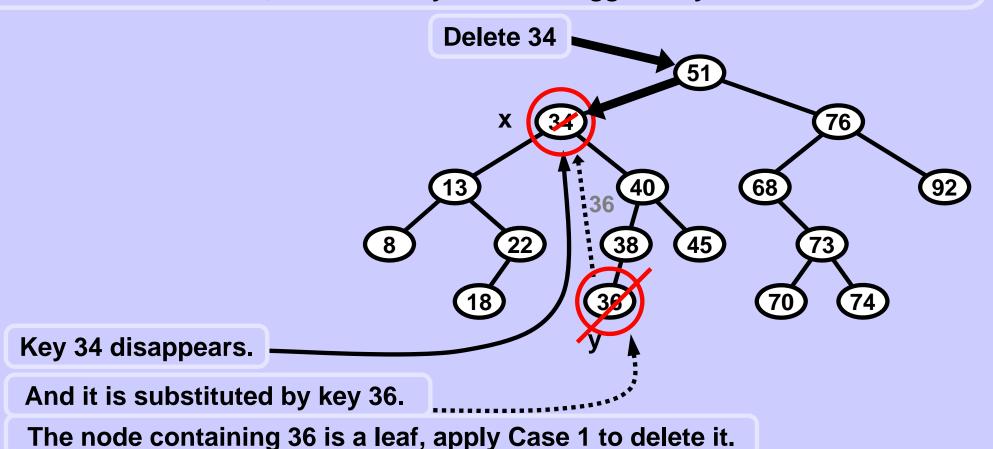




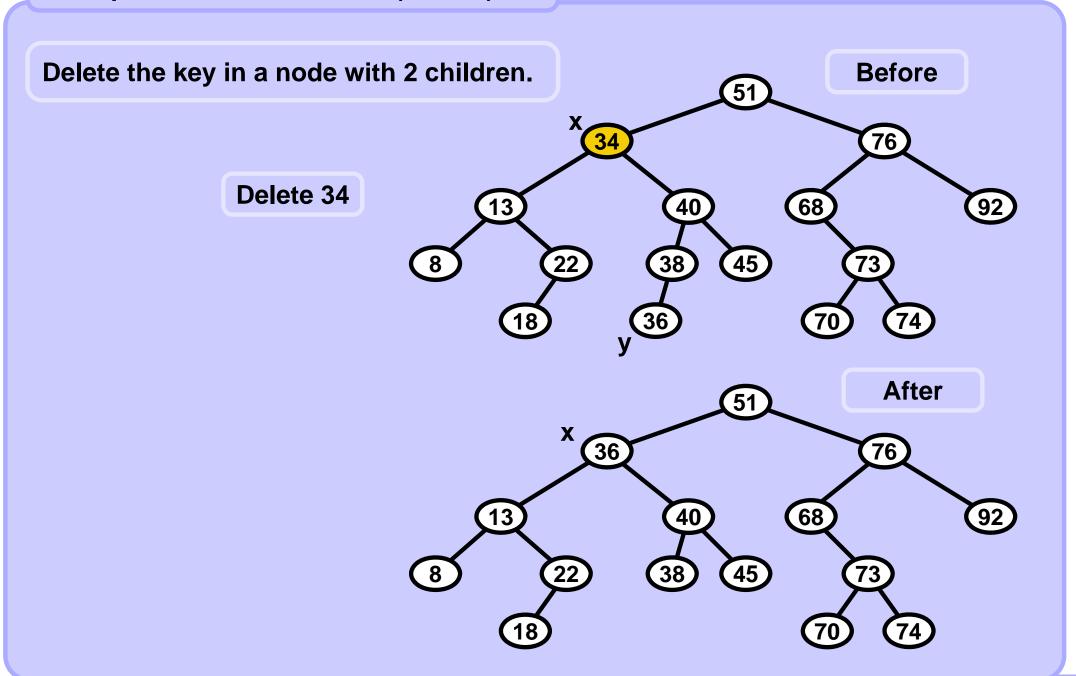
Delete the key in a node x with 2 children.

In the *right* subtree of x, locate node y with the *smallest* key. Node y has either 0 or 1 child. It *cannot* have 2 children.

Equivalently (see next example), the the algorithm may, in the *left* subtree of x, locate node y with the *biggest* key.



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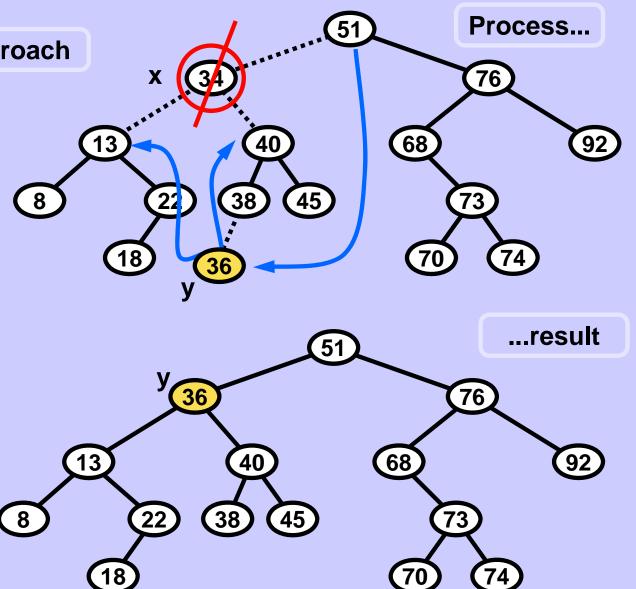


Delete 34 Alternative approach

previous

new

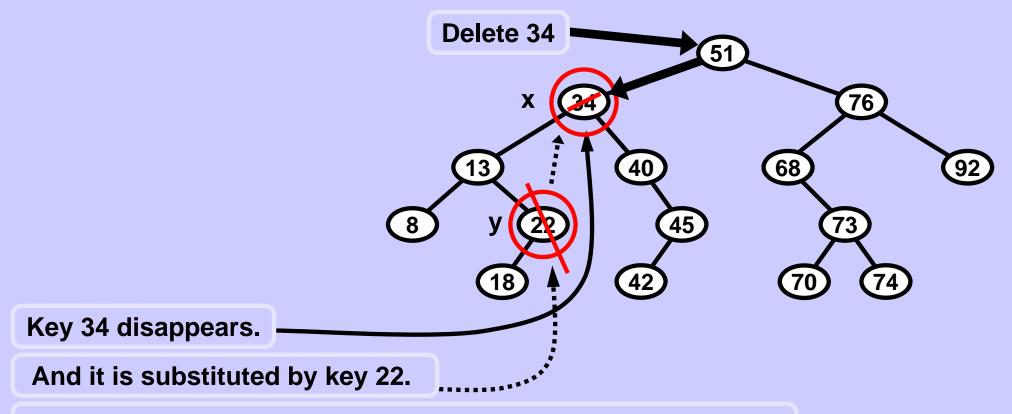
- 1. After finding the node *x* with the key to be deleted find the *leftmost* node *y* in the *right* subtree of *x*.
- 2. Point
 from y
 to the children of x,
 from the parent of y
 point to null (None),
 from the parent of x
 point to y.



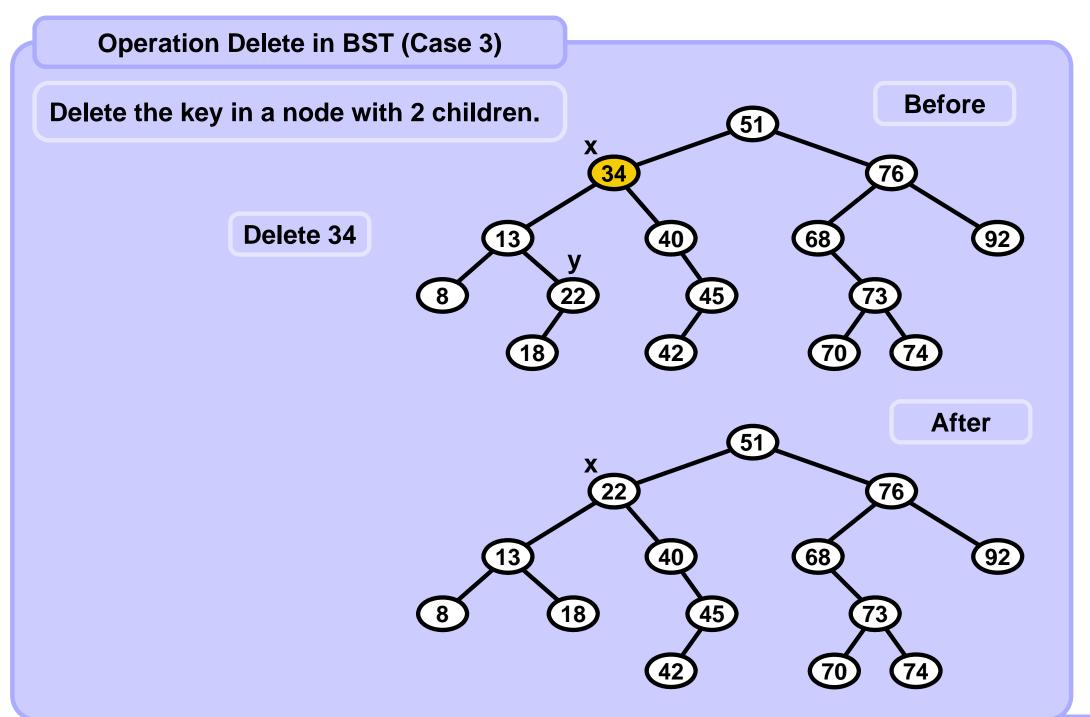
Delete the key in a node x with 2 children.

In the *right* subtree of x (see previous example), locate node y with the *smallest* key. Node y has either 0 or 1 child. It *cannot* have 2 children.

Equivalently (this example), in the *left* subtree of x, locate node y with the *biggest* key.



The node containing 22 has 1 child, apply Case 2 to delete it.



Delete 34 Alternative approach

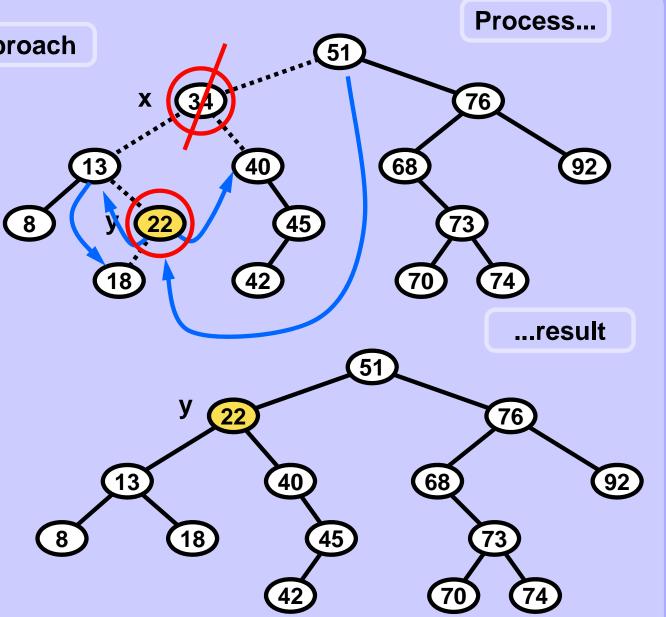
previous

new

1. After finding the node x with the key to be deleted find the <u>rightmost</u> node y in the <u>left</u> subtree of x.

2.

From y
point to the children of x,
from the parent of y
point to the child of y,
from the parent of x
point to y.



Operation Delete in BST -- recursively

```
def delete( self, node, parent, key ):
  # not found or search recursively in L or R subtree
  if node == None: return None
  if key < node.key: self.delete( node.left, node, key ); return</pre>
  if node.key < key: self.delete( node.right, node, key ); return</pre>
  # found in current node, delete the key/node
  if node.left != None and node.right != None:
    # both children
    rightMinNode, rightMinParent = self.findMin( node.right, node )
    node.key = rightMinNode.key
    self.delNodeWithAtMost1Child( rightMinNode, rightMinParent )
  else:
    # single child
    self.delNodeWithAtMost1Child( node, parent )
```

Operation Delete in BST -- support functions

```
def findMin( self, node, parent ):
    while node.left != None:
        parent = node; node = node.left
    return node, parent
def delNodeWithAtMost1Child( self, node, parent ):
    if node.left is None:
        if node.right == None:
            # leaf, no child
            if parent.left == node: parent.left = None
            else:
                                    parent.right = None
        else: # single R child
            if parent.left == node: parent.left = node.right
                                    parent.right = node.right
            else:
    else:
        if node.right == None:
            # single L child
            if parent.left == node: parent.left = node.left
                                    parent.right = node.left
            else:
```

Operation Delete in BST

Asymptotic complexities of operations Find, Insert, Delete in BST

	BST with n nodes		
Operation	Balanced Not guaranteed !! Must be induced by additional conditions.	Not balanced (expected general case)	
Find	O(log(n))	O(n)	
Insert	O(log(n))	O (n)	
Delete	O(log(n))	O(n)	

Additional Fact:

The expected height of a *randomly* built binary search tree on n distinct keys is O (log n).

source: [CLRS]

Randomly, in this case: Each of the n! permutations of the input keys is equally likely.

Uniformly random BST Experiment

```
def depth( self ):
   return self._depth( self.root )
def depth( self, node ):
   if node == None: return -1
   return 1 + max(self._depth(node.left),self._depth(node.right))
                                         Experiment results
def createRandomTree(self, Nkeys ):
   keys = list( range(0,Nkeys) )
                                         Uniformly Random BST
   random.shuffle ( keys )
                                         with N nodes
   for key in keys: self.insert( key )
                                         N = depth 2*log2(N)
for i in range( 1, 6 ):
                                                        6.6
                                         10
   tree = BinarySearchTree()
                                                  11 13.3
                                         100
   tree.createRandomTree( 10**i )
                                                  19 19.9
                                         1000
   print( tree.N, tree.depth() \
                                                  30 26.6
                                         10000
         "%4.1f"%(2*math.log2(tree.N)))
                                         100000 37 33.2
                                         1000000 48 39.9
```