Statistical Machine Learning (BE4M33SSU) Lecture 2: Predictor evaluation and learning via using empirical risk

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Definition of the prediction problem

- igle $\mathcal X$ is a set of input observations/features
- \mathcal{Y} is a set of hidden states/labels
- $(x,y) \in \mathcal{X} \times \mathcal{Y}$ samples randomly drawn from r.v. with p.d.f. p(x,y)
- $h: \mathcal{X} \to \mathcal{Y}$ is a prediction strategy/hypothesis
- $\ell \colon \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$ is a loss function
- Task: find a strategy with the minimal true risk (expected loss)

$$R(h) = \int \sum_{y \in \mathcal{Y}} \ell(y, h(x)) \ p(x, y) \ \mathrm{d}x = \mathbb{E}_{(x, y) \sim p} \Big(\ell(y, h(x)) \Big)$$

• Optimal solution: Bayes predictor h^* attaining the minimal risk

$$R(h^*) = \inf_{h \in \mathcal{Y}^{\mathcal{X}}} R(h)$$

Example of a prediction problem

The statistical model is known:

•
$$\mathcal{X} = \mathbb{R}$$
, $\mathcal{Y} = \{+1, -1\}$, $\ell(y, y') = \begin{cases} 0 & \text{if } y = y' \\ 1 & \text{if } y \neq y' \end{cases}$

•
$$p(x,y) = p(y) \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{1}{2\sigma^2}(x-\mu_y)^2}, \quad y \in \mathcal{Y}.$$





Predictor evaluation and learning based on examples

• Assumption: The true risk $R(h) = \mathbb{E}_{(x,y)\sim p}(\ell(y,h(x)))$ is unknow due to unknown p(x,y), however, we assume to have examples

$$(x^1, y^1), (x^2, y^2), \dots, (x^n, y^n)$$

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drawn from i.i.d. r.v. distributed according to p(x, y).

- We will analyze two problems:
 - 1. Evaluation: given $h: \mathcal{X} \to \mathcal{Y}$, estimate its R(h) using test set

$$\mathcal{S}^{l} = \{ (x^{i}, y^{i}) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, l \}$$
 drawn i.i.d. from $p(x, y)$

2. Learning: find $h: \mathcal{X} \to \mathcal{Y}$ with small R(h) using training set

$$\mathcal{T}^m = \{(x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m\}$$
 drawn i.i.d. from $p(x, y)$

Predictor evaluation via empirical risk



Given a predictor $h: \mathcal{X} \to \mathcal{Y}$ and a test set \mathcal{S}^l draw i.i.d. from p(x, y), compute the empirical risk

$$R_{\mathcal{S}^l}(h) = \frac{1}{l} \left(\ell(y^1, h(x^1)) + \dots + \ell(y^l, h(x^l)) \right) = \frac{1}{l} \sum_{i=1}^l \ell(y^i, h(x^i))$$

and use it as an estimate of the true risk $R(h) = \mathbb{E}_{(x,y)\sim p}(\ell(y,h(x)))$.

• $R_{S^l}(h)$ is a random number with an unknown distribution.

We will construct a confidence interval such that

 $R(h) \in (R_{\mathcal{S}^{l}(h)} - \varepsilon, R_{\mathcal{S}^{l}(h)} + \varepsilon)$ with probability (confidence) $\gamma \in (0, 1)$

where ε is a deviation.

Law of large numbers

 Sample mean (arithmetic average) of the results of random trials gets closer to the expected value as more trials are performed. р

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Example: The expected value of a single roll of a fair die is



Counting frequency of bad estimates



a = 1, b = 6

m p

Hoeffding inequality

Theorem: Let $\{z^1, \ldots, z^l\}$ be a sample from independent r.v. from [a, b] with expected value μ . Let $\hat{\mu} = \frac{1}{l} \sum_{i=1}^{l} z^i$. Then for any $\varepsilon > 0$ it holds that

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$$\mathbb{P}\Big(|\hat{\mu} - \mu| \ge \varepsilon\Big) \le 2e^{-\frac{2l\varepsilon^2}{(b-a)^2}}$$

Properties:

- Conservative: the bound may not be tight.
- General: the bound holds for any distribution.
- Cheap: The bound is simple and easy to compute.

$\begin{array}{c} \text{Confidence intervals} \\ (l,\gamma) \rightarrow \varepsilon \end{array}$



• Find ε such that $\mu \in (\hat{\mu} - \varepsilon, \hat{\mu} + \varepsilon)$ with probability at least γ .

Using the Hoeffding inequality we can write

$$\mathbb{P}\Big(|\hat{\mu}-\mu|<\varepsilon\Big) = 1 - \mathbb{P}\Big(|\hat{\mu}-\mu|\geq\varepsilon\Big) \geq 1 - 2e^{-\frac{2l\varepsilon^2}{(b-a)^2}} = \gamma$$

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and solving the last equation for ε yields

$$\varepsilon = |b - a| \sqrt{\frac{\log(2) - \log(1 - \gamma)}{2l}}$$

Confidence intervals $(\varepsilon, \gamma) \rightarrow l$



• Let $\hat{\mu} = \frac{1}{l} \sum_{i=1}^{l} z^i$ be the sample mean computed from $\{z^1, \ldots, z^l\} \in [a, b]^l$ sampled from r.v. with expected value μ .

• Given a fixed $\varepsilon > 0$ and $\gamma \in (0, 1)$, what is the minimal number of examples l such that $\mu \in (\hat{\mu} - \varepsilon, \hat{\mu} + \varepsilon)$ with probability γ at least ?

Starting from

$$\mathbb{P}\Big(|\hat{\mu}-\mu|<\varepsilon\Big) = 1 - \mathbb{P}\Big(|\hat{\mu}-\mu|\geq\varepsilon\Big) \geq 1 - 2e^{-\frac{2l\varepsilon^2}{(b-a)^2}} = \gamma$$

and solving for l yields

$$l = \frac{\log(2) - \log(1 - \gamma)}{2\varepsilon^2} (b - a)^2$$

Back to the problem: Estimation of the true risk by using confidence intervals

• Given $h: \mathcal{X} \to \mathcal{Y}$ estimate the true risk $R(h) = \mathbb{E}_{(x,y)\sim p}(\ell(y,h(x)))$ by the empirical risk $R_{\mathcal{S}^l}(h) = \frac{1}{l} \sum_{i=1}^l \ell(y^i,h(x^i))$ using the test set \mathcal{S}^l .

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• Confidence interval:

$$R(h) \in \left(R_{\mathcal{S}^l}(h) - \varepsilon, R_{\mathcal{S}^l}(h) + \varepsilon \right) \quad \text{with probability} \quad \gamma \in (0, 1)$$

For fixed l and $\gamma \in (0,1)$ compute interval width

$$\varepsilon = (\ell_{\max} - \ell_{\min}) \sqrt{\frac{\log(2) - \log(1 - \gamma)}{2l}}$$

• For fixed ε and $\gamma \in (0,1)$ compute number of test examples

$$l = \frac{\log(2) - \log(1 - \gamma)}{2\varepsilon^2} \left(\ell_{\max} - \ell_{\min}\right)^2$$

Learning: the definition



• The goal: Find a strategy $h: \mathcal{X} \to \mathcal{Y}$ minimizing R(h) using the training set of examples

$$\mathcal{T}^m = \{ (x^i, y^i) \in (\mathcal{X} \times \mathcal{Y}) \mid i = 1, \dots, m \}$$

drawn from i.i.d. rv. with unknown p(x, y).

• Hypothesis class (space):

$$\mathcal{H} \subseteq \mathcal{Y}^{\mathcal{X}} = \{h \colon \mathcal{X} \to \mathcal{Y}\}$$

Learning algorithm: a function

$$A\colon \cup_{m=1}^{\infty} (\mathcal{X} \times \mathcal{Y})^m \to \mathcal{H}$$

which returns a strategy $h_m = A(\mathcal{T}^m)$ for a training set \mathcal{T}^m

Learning: Empirical Risk Minimization approach

• The expected risk R(h), i.e. the true but unknown objective, is replaced by the empirical risk computed from the training examples \mathcal{T}^m ,

$$R_{\mathcal{T}^m}(h) = \frac{1}{m} \sum_{i=1}^m \ell(y^i, h(x^i))$$

• The ERM based algorithm returns h_m such that

$$h_m \in \operatorname{Argmin}_{h \in \mathcal{H}} R_{\mathcal{T}^m}(h) \tag{1}$$

 Depending on the choince of H and l and algorithm solving (1) we get individual instances e.g. Support Vector Machines, Linear Regression, Logistic Regression, Neural Networks learned by back-propagation, AdaBoost, Gradient Boosted Trees, ...



Example of ERM failure



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- The optimal strategy is h(x) = +1 with the Bayes risk $R^* = 0.2$.
- Consider learning algorithm which for a given training set $\mathcal{T}^m = \{(x^1, y^1), \dots, (x^m, y^m)\}$ returns memorizing strategy

$$h_m(x) = \begin{cases} y^j & \text{if } x = x^j \text{ for some } j \in \{1, \dots, m\} \\ -1 & \text{otherwise} \end{cases}$$

- The empirical risk is $R_{\mathcal{T}^m}(h_m) = 0$ with probability 1 for any m.
- The expected risk is $R(h_m) = 0.8$ for any m.