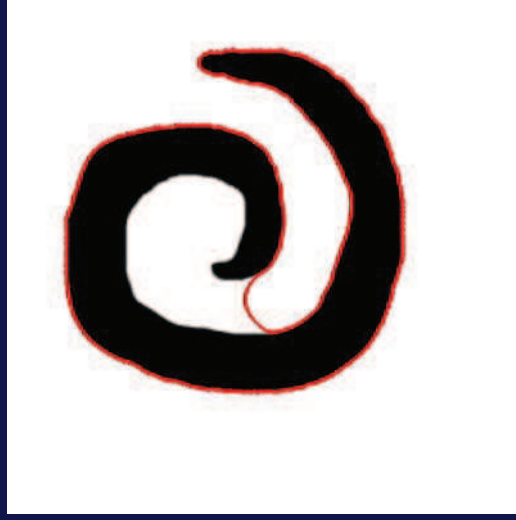


Evolution of Explicit Boundaries



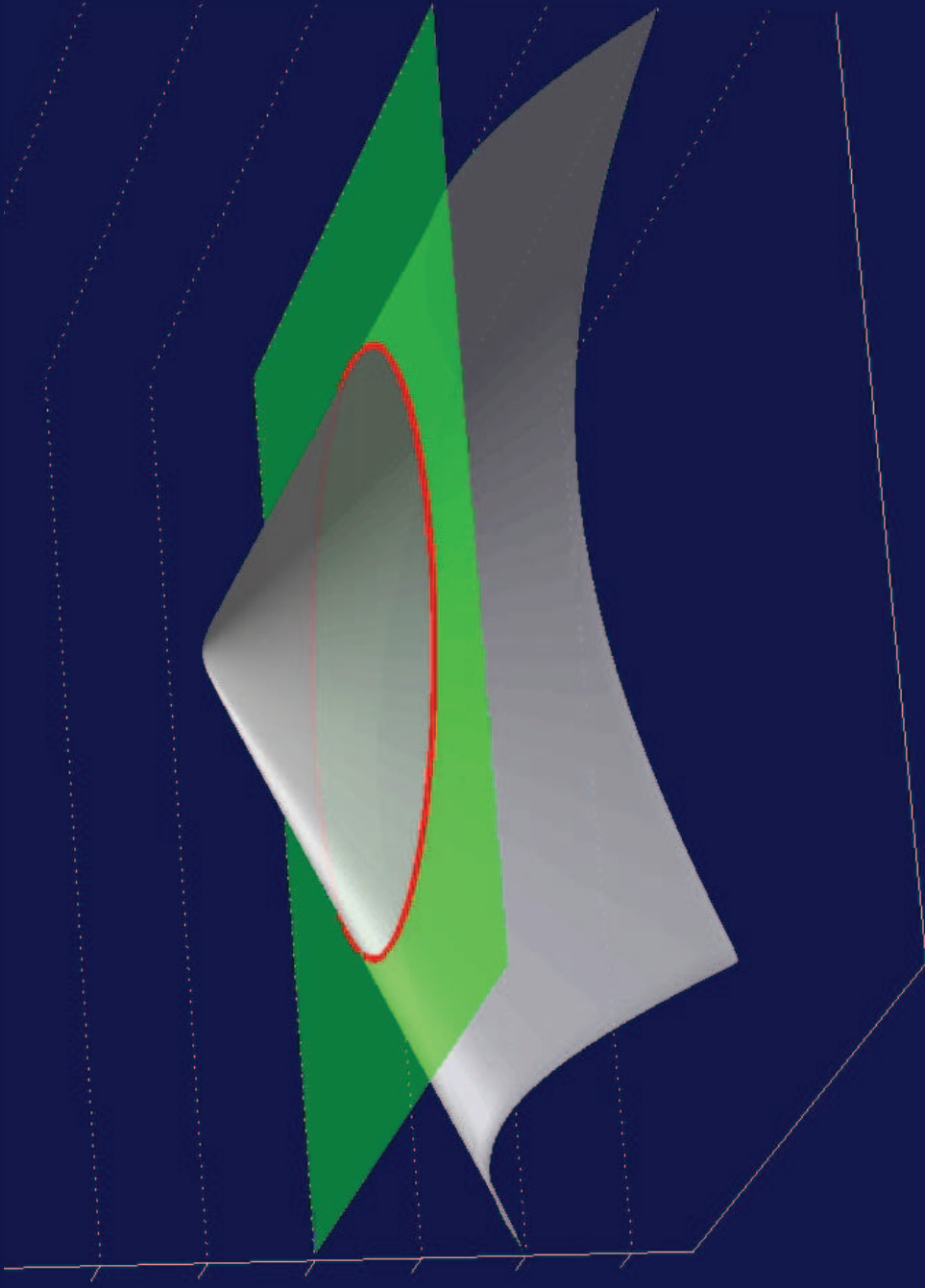
Cremers, Tischhäuser, Weickert, Schnörr, "Diffusion Snakes", IJCV '02

Evolution of Explicit Boundaries



Cremers, Tischhäuser, Weickert, Schnörr, "Diffusion Snakes", IJCV '02

The Level Set Method



$$C = \{x \in \Omega \mid \phi(x) = 0\}, \quad \phi : \Omega \subset \mathbb{R}^n \rightarrow \mathbb{R}$$

Osher, Sethian, J. of Comp. Phys. '88

Dervieux, Thomasset, '79, '81

The Level Set Method

Assume the interface evolves according to: $\frac{dC}{dt} = F \vec{n}$

At all times the interface is the zero level of ϕ :

$$\phi(C(t), t) = 0 \quad \forall t.$$

Then the total time derivative of must vanish:

$$0 = \frac{d}{dt} \phi(C(t), t) = \nabla \phi \frac{dC}{dt} + \partial_t \phi.$$

We obtain an evolution equation for ϕ : $\partial_t \phi = -\nabla \phi \frac{dC}{dt} = -\nabla \phi F \vec{n}$.

Using $\vec{n} = \frac{\nabla \phi}{|\nabla \phi|}$, we obtain the level set equation:

$$\partial_t \phi = -F |\nabla \phi|.$$

Image Segmentation: Edge-based

Kass, Witkin, Terzopoulos, "Snakes" '88:

$$E(C) = \underbrace{- \int |\nabla I(C)|^2 ds}_{\text{external energy}} + \underbrace{\int \{ \nu_1 |C_s|^2 + \nu_2 |C_{ss}|^2 \}}_{\text{internal energy}} ds$$

Image $I : \Omega \rightarrow \mathbb{R}$, parametric contour $C : [0, 1] \rightarrow \Omega$

Caselles et al. '93, Caselles et al. '95, Kichenassamy et al. '95:

$$E(C) = \int g(C(s)) ds \quad g(x) = \frac{1}{1 + |\nabla I_\sigma(x)|^2}$$



 edge indicator function smoothed image

geodesic active contours:

$$\frac{\partial \phi}{\partial t} = |\nabla \phi| \operatorname{div} \left(g(x) \frac{\nabla \phi}{|\nabla \phi|} \right)$$

Image Segmentation: Edge-based



Goldenberg, Kimmel, Rivlin, Rudzsky, IEEE TIP '01

Image Segmentation: Region-based

$$E(u, K) = \int_{\Omega} (I - u)^2 dx + \lambda \int_{\Omega \setminus K} |\nabla u|^2 dx + \nu_o \mathcal{H}^1(K)$$

$$\Omega \subset \mathbb{R}^2$$

Image domain

Mumford, Shah '85, '89
Blake, Zisserman '87

$$I : \Omega \rightarrow \mathbb{R}$$

Input image

$$u : \Omega \rightarrow \mathbb{R}$$

Segmented image

$$K \subset \Omega$$

Discontinuity set

$\lambda \rightarrow \infty$: piecewise constant model

$$E(u, K) = \sum_i \int_{R_i} (I(x) - u_i)^2 dx + \nu |K|$$

Mumford, Shah '89
spatially discrete: Blake '83

Image Segmentation: Region-based

$$E(u, K) = \sum_i \int_{R_i} (I(x) - u_i)^2 dx + \nu |K|$$

piecewise constant model

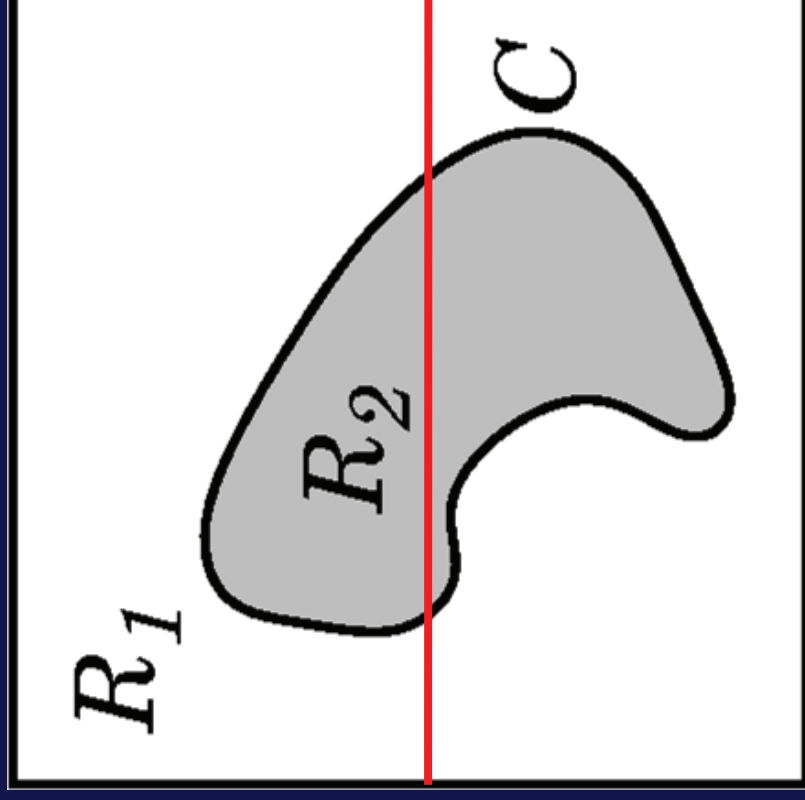
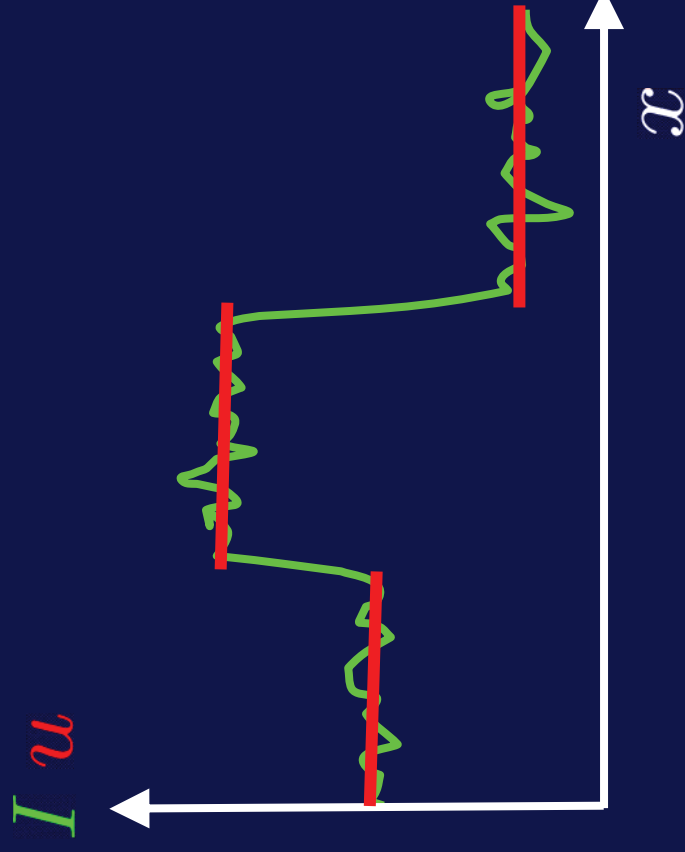


Image Segmentation: Region-based

$$E(u, K) = \sum_i \int_{R_i} (I(x) - u_i)^2 dx + \nu |K|$$

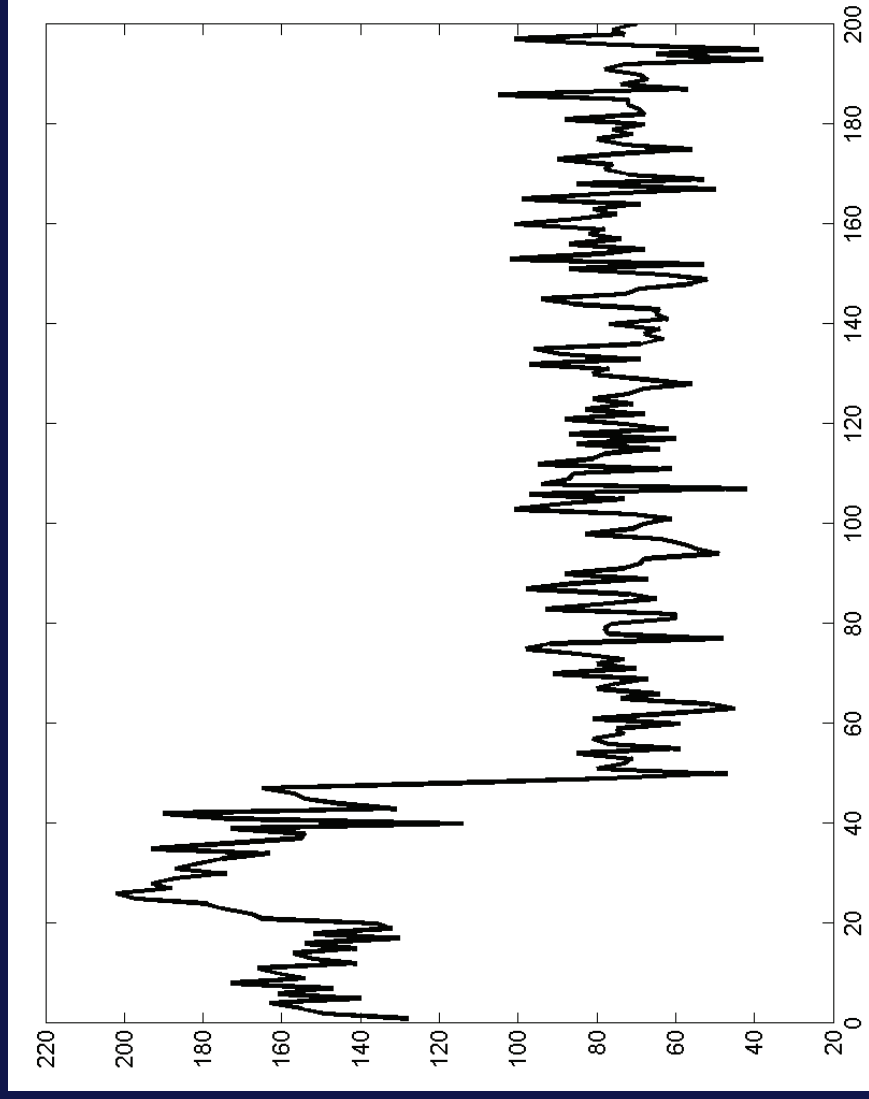
piecewise constant model



Quantitative Comparison on 1-D



Input image



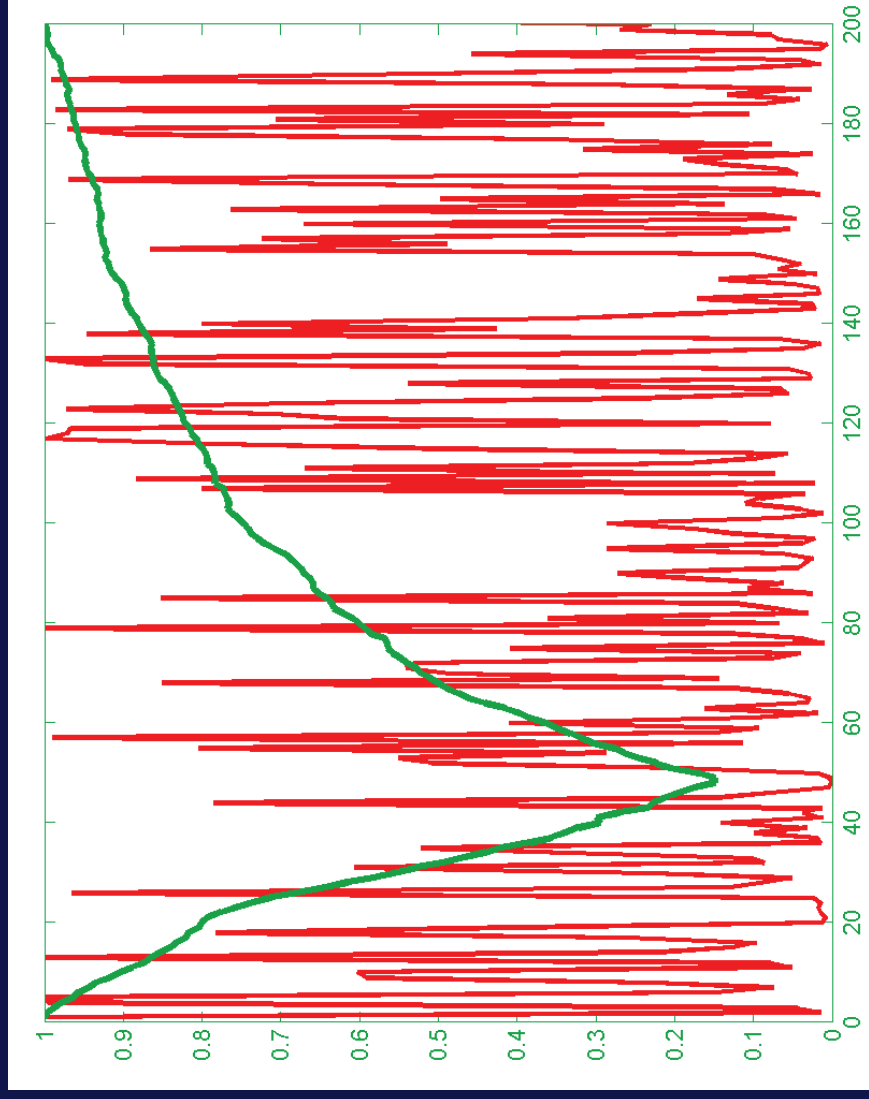
Intensity along 1D slice

Cremers, Rousson, Deriche, IJCV '06

Quantitative Comparison on 1-D



Input image



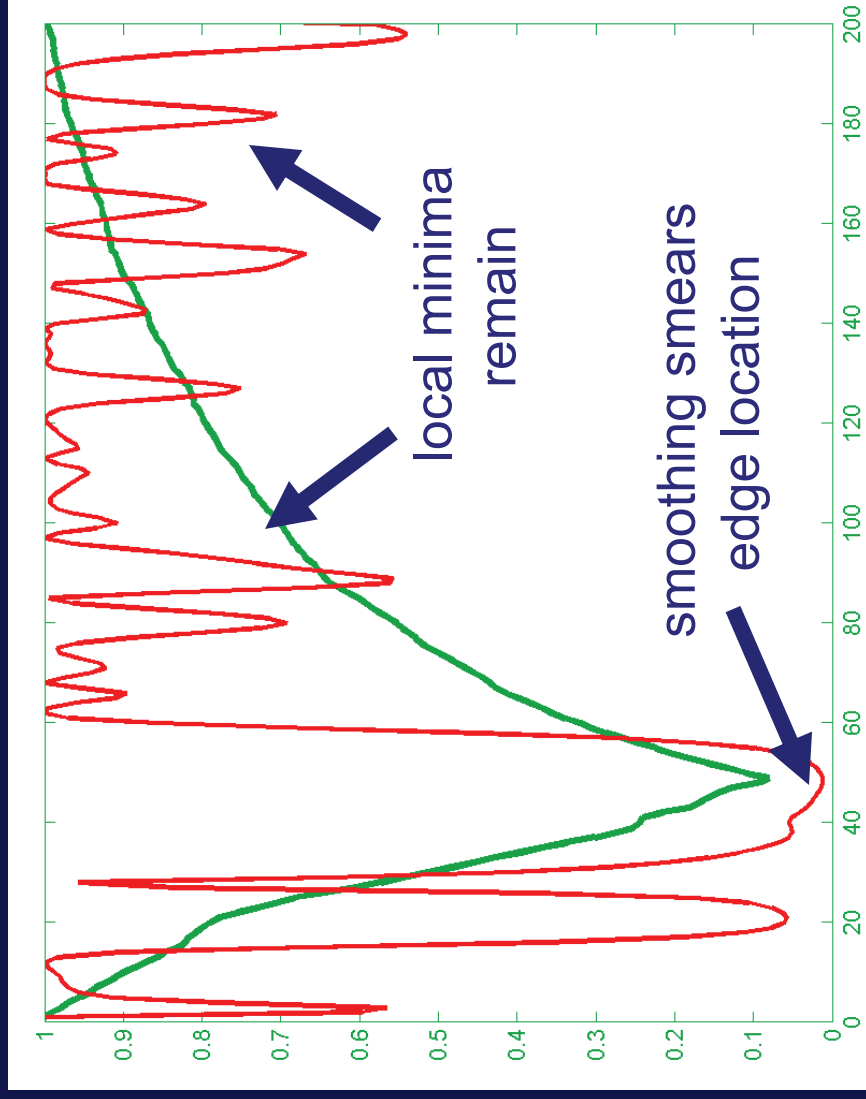
Energy of 1D segmentation for
edge-based and region-based energies

Cremers, Rousson, Deriche, IJCV '06

Quantitative Comparison on 1-D



Input image



Energy for **region-based** and **edge-based after smoothing**

Cremers, Rousson, Deriche, IJCV '06

Level Set Formulation of Mumford-Shah

Chan, Vese '99, Tsai et al. '00

$$E(u, C) = \sum_i \int_{R_i} (I(x) - u_i)^2 dx + \nu |C|$$



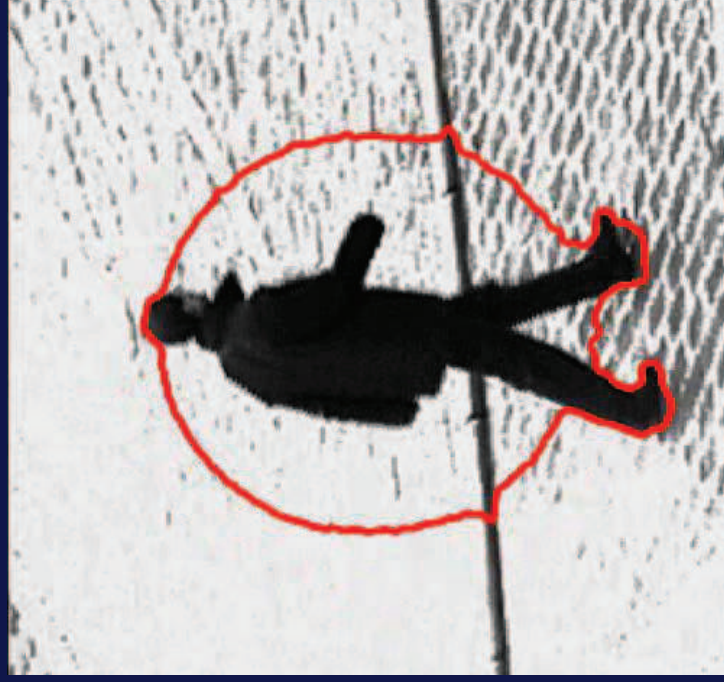
$$H\phi \equiv H(\phi) = \begin{cases} 1, & \text{if } \phi > 0 \\ 0, & \text{else} \end{cases}$$

Use smoothed step function

$$E(\phi, u) = \int_{\Omega} (I - u_1)^2 H\phi + (I - u_2)^2 (1 - H\phi) dx + \nu \int_{\Omega} |\nabla H\phi| dx$$

$$\frac{\partial \phi}{\partial t} = - \frac{\partial E}{\partial \phi} = \delta(\phi) \left(\nu \operatorname{div} \left(\frac{\nabla \phi}{|\nabla \phi|} \right) + (I - u_2)^2 - (I - u_1)^2 \right)$$

Level Set Formulation of Mumford-Shah



Chan & Vese '99, Implementation: D. Cremers

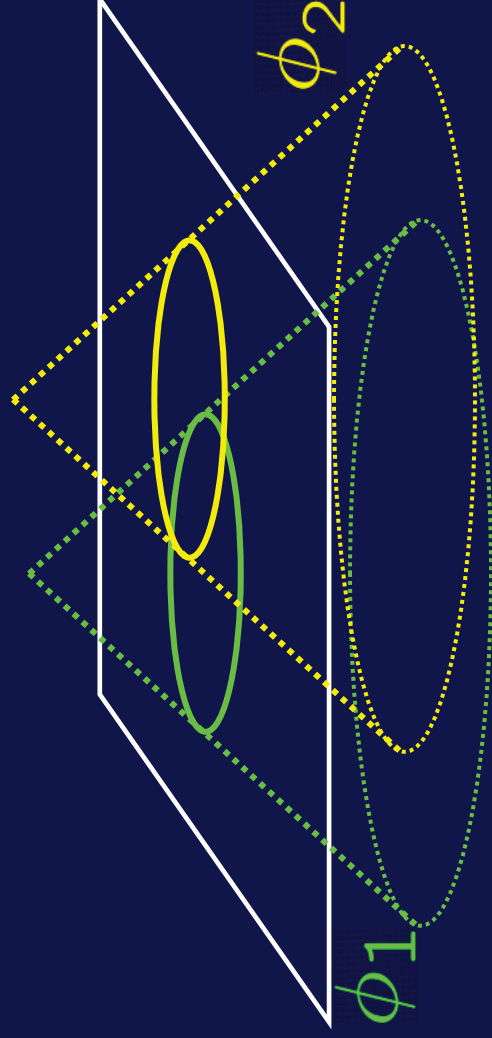
Level Set Formulation of Mumford-Shah



Chan & Vese '99, Implementation: D. Cremers

Multiphase Level Set Formulation

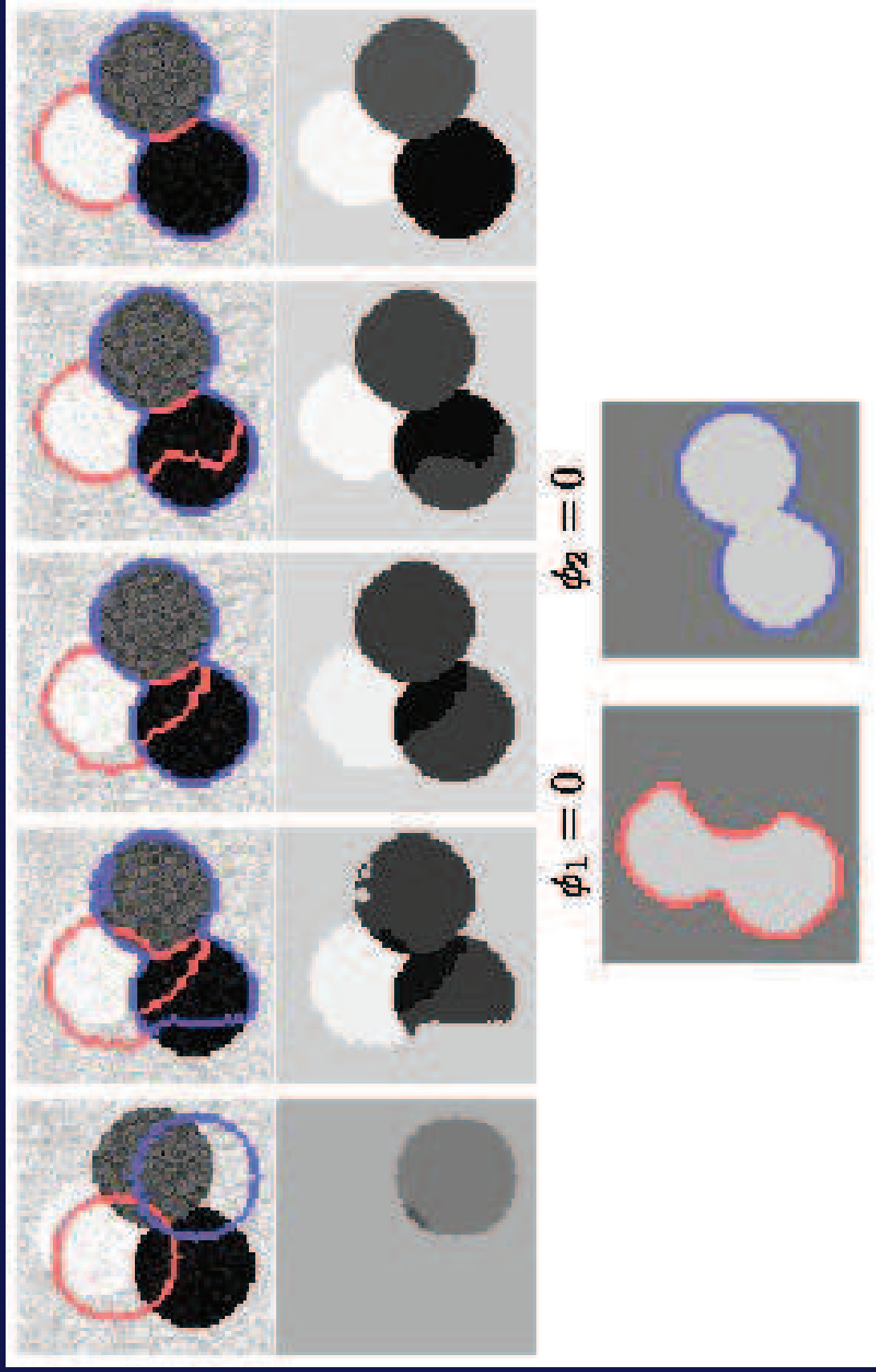
Vese, Chan '02



	$\phi_1 \geq 0$	$\phi_1 < 0$
$\phi_2 \geq 0$	Ω_1	Ω_2
$\phi_2 < 0$	Ω_3	Ω_4

$$\begin{aligned}
 E(\phi_1, \phi_2, u) = & \int_{\Omega} (I - u_1)^2 H\phi_1 H\phi_2 + (I - u_2)^2 (1 - H\phi_1) H\phi_2 \, dx \\
 & + \int_{\Omega} (I - u_3)^2 H\phi_1 (1 - H\phi_2) + (I - u_4)^2 (1 - H\phi_1) (1 - H\phi_2) \, dx \\
 & + \nu \sum_i \int_{\Omega} |\nabla H\phi_i| \, dx \\
 \frac{\partial \vec{\phi}}{\partial t} = & - \frac{dE}{d\vec{\phi}}
 \end{aligned}$$

Multiphase Level Set Formulation

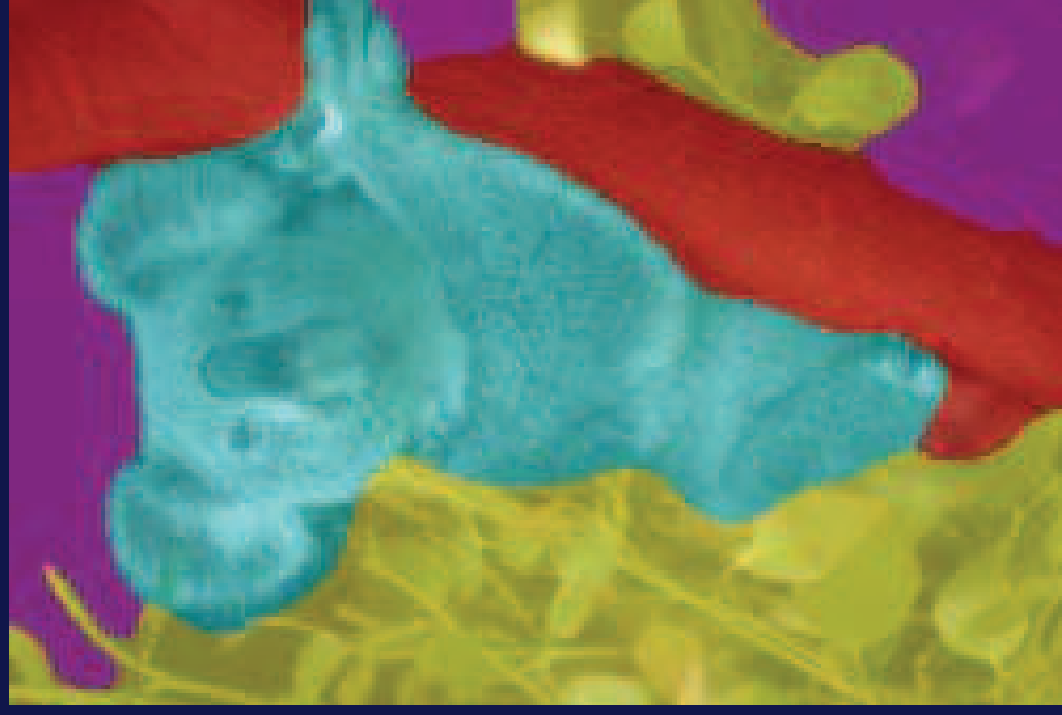


Chan, Vese '01

Efficient Multiphase Formulation



2-phase solution



multiphase solution

Brox, Weickert '04, '06

Efficient Multiphase Formulation



Brox, Weickert '04, '06