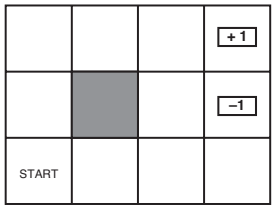
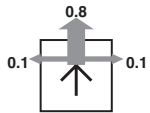
Value/Policy iteration

J. Kostlivá, Z. Straka, P. Švarný, F. Gama





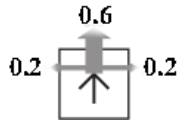
-10	*B*	30
-10	*A*	20

We have:

- States: S, Actions: A
- Transition model: $T(s, a, s') \equiv P(s'|s, a)$, we are in state s, take action a and get to state s'
- Reward: $r(s)$, immediate reward
- State value: $V(s)$, Expected sum of rewards when performing optimal actions
- Policy: π, robot/agent behaviour strategy

Example

-40	30	-50
-40	A	-50
-40	B	-50



- Square environment, numbers are rewards
- Red states are terminal
- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- Immediate reward $r(A) = r(B) = -1$
- Transition model: see picture
- Forgetting/discount factor: $\gamma = 0.9$

Example

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-40	$r(A) = -1$	-50
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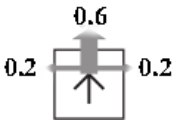

- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$

Task: find optimal policies and values of states A, B

A: $\pi(A) = \uparrow, \pi(B) = \leftarrow$

B: $\pi(A) = \rightarrow, \pi(B) = \leftarrow$

C: $\pi(A) = \leftarrow, \pi(B) = \uparrow$

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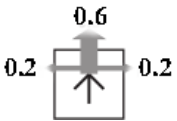

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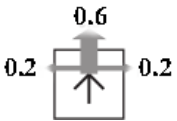

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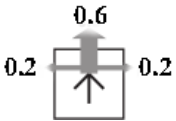

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How to do?

1. Calculate the state value V(s):
   - A: $V(s) = \sum_{s'} p(s'|s,a)[r(s,a,s') + \gamma V(s')]$
   - B: $V(s) = \sum_{s'} \gamma V(s')$
   - C: $V(s) = \max_a \sum_{s'} p(s'|s,a)[r(s,a,s') + \gamma V(s')]$
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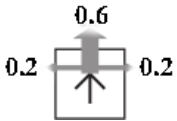

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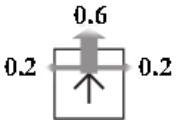

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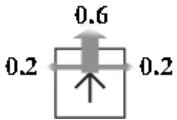

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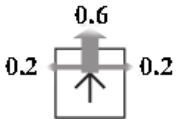

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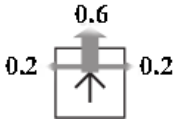

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We have two methods:

- Value iteration
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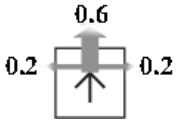

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Different variants of rewards

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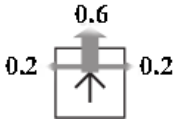

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What if we had another variant of MDP? Let's $r(s)$ be instead $r(s,a,s')$. Then, $V(s) = \max_a \sum_{s'} p(s'|s,a)[r(s,a,s') + \gamma V(s')]$ changes to:

A: $V(s) = \sum_{s'}[V(s') + \gamma r(s')]$

B: $V(s) = r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V(s')$

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D: $V(s) = \max_{a \in A(s)} \sum_{s'} \gamma(V(s') + r(s'))$

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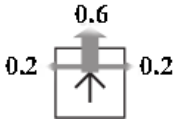

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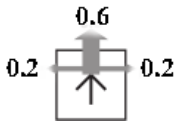

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Use Bellman update $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Iterate until the change of state value $V(s)$ between two iterations is lower than ϵ

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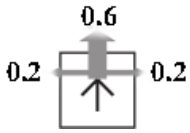

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- $\gamma = 0.9$
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$t = 0: \quad V(A) = 0, V(B) = 0$

$$t = 1: \quad V(A) = -1 + 0.9 \cdot \max \begin{cases} (\rightarrow) & 0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot 0 = -24 \\ (\leftarrow) & 0.6 \cdot (-40) + 0.2 \cdot 30 + 0.2 \cdot 0 = -18 \\ (\uparrow) & 0.6 \cdot 30 + 0.2 \cdot (-40) + 0.2 \cdot (-50) = 0 \\ (\downarrow) & 0.6 \cdot 0 + 0.2 \cdot (-50) + 0.2 \cdot (-40) = -18 \end{cases} = -1 \quad (\uparrow)$$

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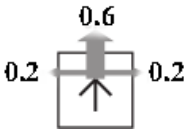

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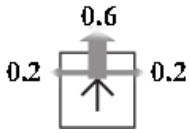

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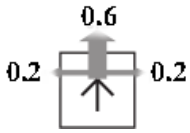

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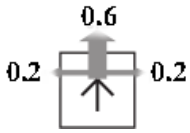

- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

$t = 0: \quad V(A) = 0, V(B) = 0$

$$t = 1: \quad V(A) = -1 + 0.9 \cdot \max \begin{cases} (\rightarrow) & 0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot 0 = -24 \\ (\leftarrow) & 0.6 \cdot (-40) + 0.2 \cdot 30 + 0.2 \cdot 0 = -18 \\ (\uparrow) & 0.6 \cdot 30 + 0.2 \cdot (-40) + 0.2 \cdot (-50) = 0 \\ (\downarrow) & 0.6 \cdot 0 + 0.2 \cdot (-50) + 0.2 \cdot (-40) = -18 \end{cases} = -1 \quad (\uparrow)$$

$$V(B) = -1 + 0.9 \cdot \max \begin{cases} (\rightarrow) & 0.6 \cdot (-50) + 0.2 \cdot 0 + 0.2 \cdot 0 = -30 \\ (\leftarrow) & 0.6 \cdot (-40) + 0.2 \cdot 0 + 0.2 \cdot 0 = -24 \\ (\uparrow) & 0.6 \cdot 0 + 0.2 \cdot (-40) + 0.2 \cdot (-50) = -18 \\ (\downarrow) & 0.6 \cdot 0 + 0.2 \cdot (-50) + 0.2 \cdot (-40) = -18 \end{cases} = -17.2 \quad (\uparrow)/(\downarrow)$$

Example - Value Iteration

-40	30	-50
-40	$r(A) = -1$	-50
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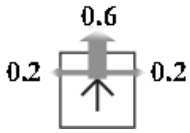

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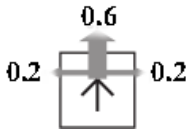

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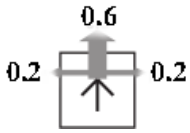

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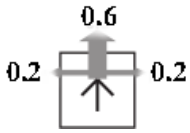

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Example - Value Iteration

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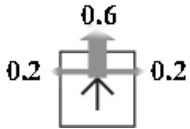

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$$V(B) = -1 + 0.9 \cdot \max \begin{cases} (\rightarrow) & 0.6 \cdot (-50) + 0.2 \cdot (-1) + 0.2 \cdot (-17.2) = -33.64 \\ (\leftarrow) & 0.6 \cdot (-40) + 0.2 \cdot (-1) + 0.2 \cdot (-17.2) = -27.64 \\ (\uparrow) & 0.6 \cdot (-1) + 0.2 \cdot (-40) + 0.2 \cdot (-50) = -18.6 \\ (\downarrow) & 0.6 \cdot (-17.2) + 0.2 \cdot (-50) + 0.2 \cdot (-40) = -28.32 \end{cases} = -17.74 \ (\uparrow)$$

$$t = 3: \quad V(A) = -1 + 0.9 \cdot \max \begin{cases} (\rightarrow) & 0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot (-17.74) = -27.548 \\ (\leftarrow) & 0.6 \cdot (-40) + 0.2 \cdot 30 + 0.2 \cdot (-17.74) = -21.548 \\ (\uparrow) & 0.6 \cdot 30 + 0.2 \cdot (-40) + 0.2 \cdot (-50) = 0 \\ (\downarrow) & 0.6 \cdot (-17.74) + 0.2 \cdot (-50) + 0.2 \cdot (-40) = -28.64 \end{cases} = -1 \ (\uparrow)$$

$$V(B) = -1 + 0.9 \cdot \max \begin{cases} (\rightarrow) & 0.6 \cdot (-50) + 0.2 \cdot (-1) + 0.2 \cdot (-17.74) = -33.748 \\ (\leftarrow) & 0.6 \cdot (-40) + 0.2 \cdot (-1) + 0.2 \cdot (-17.74) = -27.748 \\ (\uparrow) & 0.6 \cdot (-1) + 0.2 \cdot (-40) + 0.2 \cdot (-50) = -18.6 \\ (\downarrow) & 0.6 \cdot (-17.74) + 0.2 \cdot (-50) + 0.2 \cdot (-40) = -28.64 \end{cases} = -17.74 \ (\uparrow)$$

Example - Value Iteration

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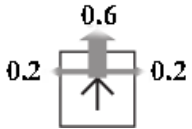

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Example - Value Iteration

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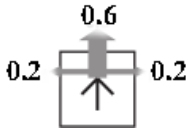

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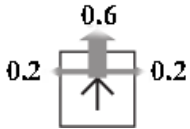

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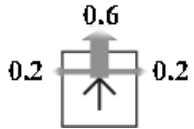

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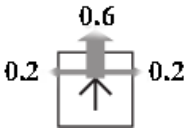

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Policy iteration - 1 iteration:

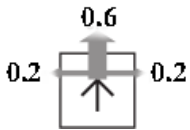
A: 1 step

B: 2 steps

C: 3 steps

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Policy iteration - 1 iteration:

A: 1 step

B: 2 steps

C: 3 steps

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
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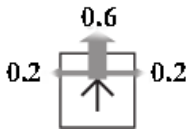

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Policy iteration - 1 iteration:

A: 1 step

B: 2 steps

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Example - Policy Iteration

-40	30	-50
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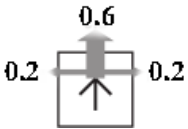


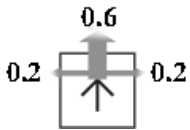
- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Policy iteration - 1 iteration: 2 steps

1. Policy Evaluation:
   - A: Calculate policies
   - B: Calculate state values
   - C: Calculate both

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Policy iteration - 1 iteration: 2 steps

1. Policy Evaluation:
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Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
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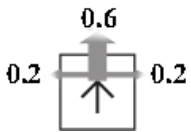

- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Policy iteration - 1 iteration: 2 steps

1. Policy Evaluation:
   - A: Calculate policies
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Example - Policy Iteration

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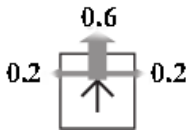


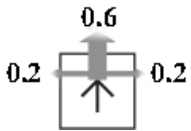
- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Policy iteration - 2 steps:

1. Policy evaluation:
   - $V_{k+1}^{\pi_i}(s) \leftarrow \sum_{s'} p(s'|s, \pi_i(s))[r(s, \pi_i(s), s') + \gamma V_k^{\pi_i}(s')]$
   - Iteratively or analytically
2. Policy refinement:
   - A: Calculate policies
   - B: Calculate state values
   - C: Calculate both

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Policy iteration - 2 steps:

1. Policy evaluation:
   - $V_{k+1}^{\pi_i}(s) \leftarrow \sum_{s'} p(s'|s, \pi_i(s))[r(s, \pi_i(s), s') + \gamma V_k^{\pi_i}(s')]$
   - Iteratively or analytically
2. Policy refinement:

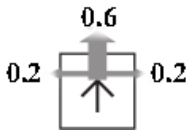
   A: Calculate policies

   B: Calculate state values

   C: Calculate both

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

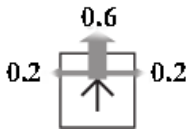
Policy iteration - 2 steps:

1. Policy evaluation:
   - $V_{k+1}^{\pi_i}(s) \leftarrow \sum_{s'} p(s'|s, \pi_i(s))[r(s, \pi_i(s), s') + \gamma V_k^{\pi_i}(s')]$
   - Iteratively or analytically
2. Policy refinement:

A: Calculate policies
B: Calculate state values
C: Calculate both

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

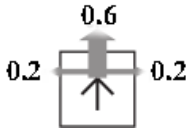
Policy iteration - 2 steps:

1. Policy evaluation:
   - $V_{k+1}^{\pi_i}(s) \leftarrow \sum_{s'} p(s'|s, \pi_i(s))[r(s, \pi_i(s), s') + \gamma V_k^{\pi_i}(s')]$
   - Iteratively or analytically
2. Policy refinement:

$$\pi_{i+1}(s) = \arg\max_a \sum_{s'} p(s'|s,a)[r(s,a,s') + \gamma V_k^{\pi_i}(s')]$$

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

$t = 0: \quad \pi(A) = \rightarrow, \pi(B) = \leftarrow$

$t = 1: \quad PE:$

$$\begin{aligned} V(A) &= -1 + 0.9 \cdot \{0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot V(B)\} \\ V(B) &= -1 + 0.9 \cdot \{0.6 \cdot (-40) + 0.2 \cdot V(A) + 0.2 \cdot V(B)\} \end{aligned}$$

$$\begin{aligned} V(A) &= -22.6 + 0.18 \cdot V(B) \\ V(B) &= -1 + 0.9 \cdot \{-24 + 0.2 \cdot (-22.6 + 0.18 \cdot V(B)) + 0.2 \cdot V(B)\} = \\ &= -26.668 + 0.2124 \cdot V(B) \\ V(B) &= \frac{-26.668}{0.7876} = -33.86 \\ V(A) &= -28.69 \end{aligned}$$

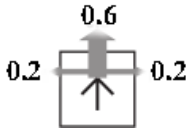
$PR:$

$$\pi(A) = \arg\max_a \begin{cases} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (30) + 0.2 \cdot \{-33.86)\} = -28.69 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (30) + 0.2 \cdot \{-33.86)\} = -23.29 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (30) + 0.2 \cdot (-40) + 0.2 \cdot \{-50)\} = -1 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48 \end{cases} = (\uparrow)$$

$$\pi(B) = \arg\max_a \begin{cases} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -39.26 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -33.86 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (-28.69) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -32.69 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48 \end{cases} = (\uparrow)$$

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

$t = 0:$ $\pi(A) = \rightarrow, \pi(B) = \leftarrow$

$t = 1:$ $PE:$

$$V(A) = -1 + 0.9 \cdot \{0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot V(B)\}$$
$$V(B) = -1 + 0.9 \cdot \{0.6 \cdot (-40) + 0.2 \cdot V(A) + 0.2 \cdot V(B)\}$$

$$V(A) = -22.6 + 0.18 \cdot V(B)$$
$$V(B) = -1 + 0.9 \cdot \{-24 + 0.2 \cdot (-22.6 + 0.18 \cdot V(B)) + 0.2 \cdot V(B)\} =$$
$$= -26.668 + 0.2124 \cdot V(B)$$
$$V(B) = \frac{-26.668}{0.7876} = -33.86$$
$$V(A) = -28.69$$

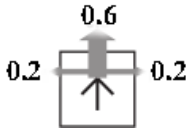
$PR:$

$$\pi(A) = \arg\max_a \begin{cases} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (30) + 0.2 \cdot \{-33.86)\} = -28.69 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (30) + 0.2 \cdot \{-33.86)\} = -23.29 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (30) + 0.2 \cdot (-40) + 0.2 \cdot \{-50)\} = -1 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48 \end{cases} = (\uparrow)$$

$$\pi(B) = \arg\max_a \begin{cases} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -39.26 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -33.86 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (-28.69) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -32.69 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48 \end{cases} = (\uparrow)$$

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

$t = 0:$ $\pi(A) = \rightarrow, \pi(B) = \leftarrow$

$t = 1:$ $PE:$

$$
\begin{aligned}
V(A) &= -1 + 0.9 \cdot \{0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot V(B)\} \\
V(B) &= -1 + 0.9 \cdot \{0.6 \cdot (-40) + 0.2 \cdot V(A) + 0.2 \cdot V(B)\}
\end{aligned}
$$

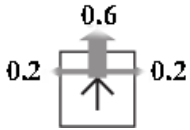
$$
\begin{aligned}
V(A) &= -22.6 + 0.18 \cdot V(B) \\
V(B) &= -1 + 0.9 \cdot \{-24 + 0.2 \cdot (-22.6 + 0.18 \cdot V(B)) + 0.2 \cdot V(B)\} = \\
&= -26.668 + 0.2124 \cdot V(B) \\
V(B) &= \tfrac{-26.668}{0.7876} = -33.86 \\
V(A) &= -28.69
\end{aligned}
$$

$$
PR: \quad \pi(A) = \arg\max_a \left\{ \begin{array}{ll} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (30) + 0.2 \cdot \{-33.86)\} = -28.69 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (30) + 0.2 \cdot \{-33.86)\} = -23.29 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (30) + 0.2 \cdot (-40) + 0.2 \cdot \{-50)\} = -1 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48 \end{array} \right\} = (\uparrow)
$$

$$
\pi(B) = \arg\max_a \left\{ \begin{array}{ll} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -39.26 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -33.86 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (-28.69) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -32.69 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48 \end{array} \right\} = (\uparrow)
$$

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

$t = 0:$ $\pi(A) = \rightarrow, \pi(B) = \leftarrow$

$t = 1:$ $PE:$

$$
\begin{aligned}
V(A) &= -1 + 0.9 \cdot \{0.6 \cdot (-50) + 0.2 \cdot 30 + 0.2 \cdot V(B)\} \\
V(B) &= -1 + 0.9 \cdot \{0.6 \cdot (-40) + 0.2 \cdot V(A) + 0.2 \cdot V(B)\}
\end{aligned}
$$

$$
\begin{aligned}
V(A) &= -22.6 + 0.18 \cdot V(B) \\
V(B) &= -1 + 0.9 \cdot \{-24 + 0.2 \cdot (-22.6 + 0.18 \cdot V(B)) + 0.2 \cdot V(B)\} = \\
&= -26.668 + 0.2124 \cdot V(B) \\
V(B) &= \tfrac{-26.668}{0.7876} = -33.86 \\
V(A) &= -28.69
\end{aligned}
$$

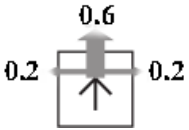
$PR:$

$$
\pi(A) = \arg\max_a \left\{ \begin{array}{ll}
(\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (30) + 0.2 \cdot (-33.86)\} = -28.69 \\
(\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (30) + 0.2 \cdot (-33.86)\} = -23.29 \\
(\uparrow) & -1 + 0.9\{0.6 \cdot (30) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -1 \\
(\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48
\end{array} \right\} = (\uparrow)
$$

$$
\pi(B) = \arg\max_a \left\{ \begin{array}{ll}
(\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -39.26 \\
(\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (-28.69) + 0.2 \cdot (-33.86)\} = -33.86 \\
(\uparrow) & -1 + 0.9\{0.6 \cdot (-28.69) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -32.69 \\
(\downarrow) & -1 + 0.9\{0.6 \cdot (-33.86) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -35.48
\end{array} \right\} = (\uparrow)
$$

Example - Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- Actions: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

$t = 2$: PE:

$$\begin{aligned} V(A) &= -1 + 0.9 \cdot \{0.6 \cdot (30) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} \\ V(B) &= -1 + 0.9 \cdot \{0.6 \cdot V(A) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} \end{aligned}$$

$$\begin{aligned} V(A) &= -1 \\ V(B) &= -1 + 0.9 \cdot \{-0.6 - 18\} = -17.74 \end{aligned}$$

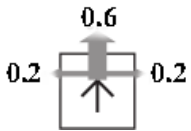
PR:

$$\pi(A) = \arg\max_a \left\{ \begin{array}{ll} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (30) + 0.2 \cdot (-17.74)\} = -25.79 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (30) + 0.2 \cdot (-17.74)\} = -20.39 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (30) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -1 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-17.74) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -26.78 \end{array} \right\} = (\uparrow)$$

$$\pi(B) = \arg\max_a \left\{ \begin{array}{ll} (\rightarrow) & -1 + 0.9\{0.6 \cdot (-50) + 0.2 \cdot (-1) + 0.2 \cdot (-17.74)\} = -31.37 \\ (\leftarrow) & -1 + 0.9\{0.6 \cdot (-40) + 0.2 \cdot (-1) + 0.2 \cdot (-17.74)\} = -25.97 \\ (\uparrow) & -1 + 0.9\{0.6 \cdot (-1) + 0.2 \cdot (-40) + 0.2 \cdot (-50)\} = -17.74 \\ (\downarrow) & -1 + 0.9\{0.6 \cdot (-17.74) + 0.2 \cdot (-50) + 0.2 \cdot (-40)\} = -26.78 \end{array} \right\} = (\uparrow)$$

Example - Comparison Value/Policy Iteration

-40	30	-50
-40	$r(A) = -1$	-50
-40	$r(B) = -1$	-50



- akce: $\{\leftarrow, \rightarrow, \uparrow, \downarrow\}$
- $\gamma = 0.9$
- $V_{k+1}(s) \leftarrow r(s) + \gamma \max_{a \in A(s)} \sum_{s'} p(s'|s,a) V_k(s')$

Final policy:

A: It may be different

B: It must be the same

C: It shouldn't be different