

Learning for vision II

Neural networks

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Vision for Robotics and Autonomous Systems

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Center for Machine Perception

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Department for Cybernetics
Faculty of Electrical Engineering
Czech Technical University in Prague



Outline

- Neuron+ computational graph
- Fully connected neural network



Linear classifier and neuron

Labels


RGB images

+1



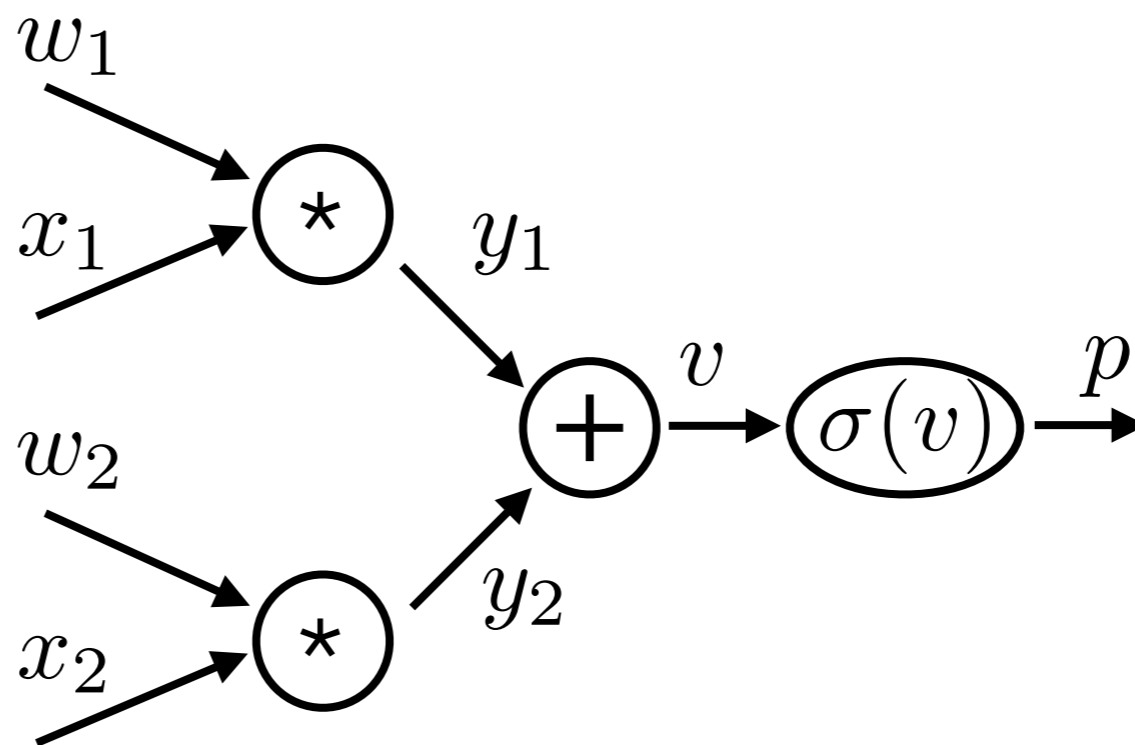
-1



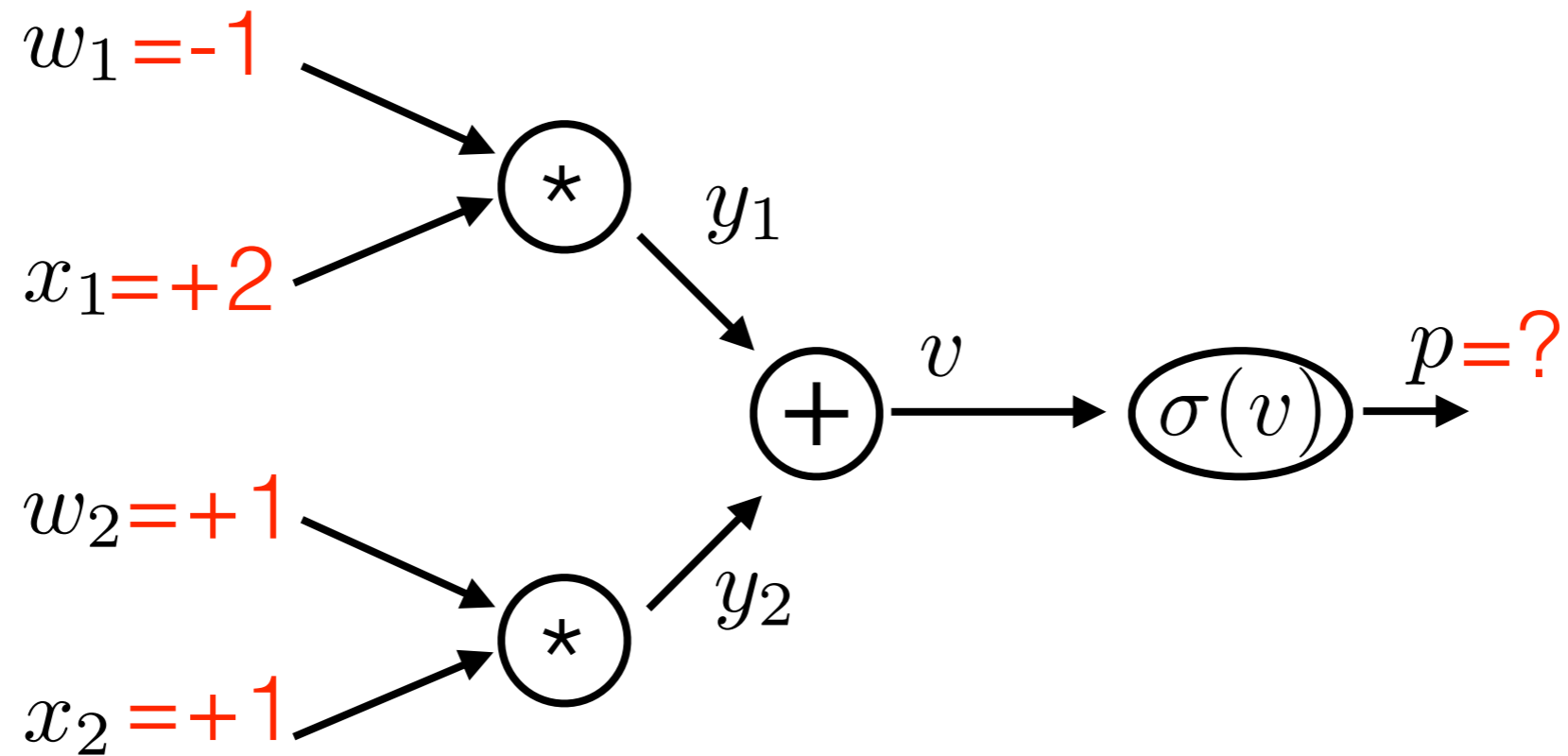
```
def classify(

Computational graph of linear classifier

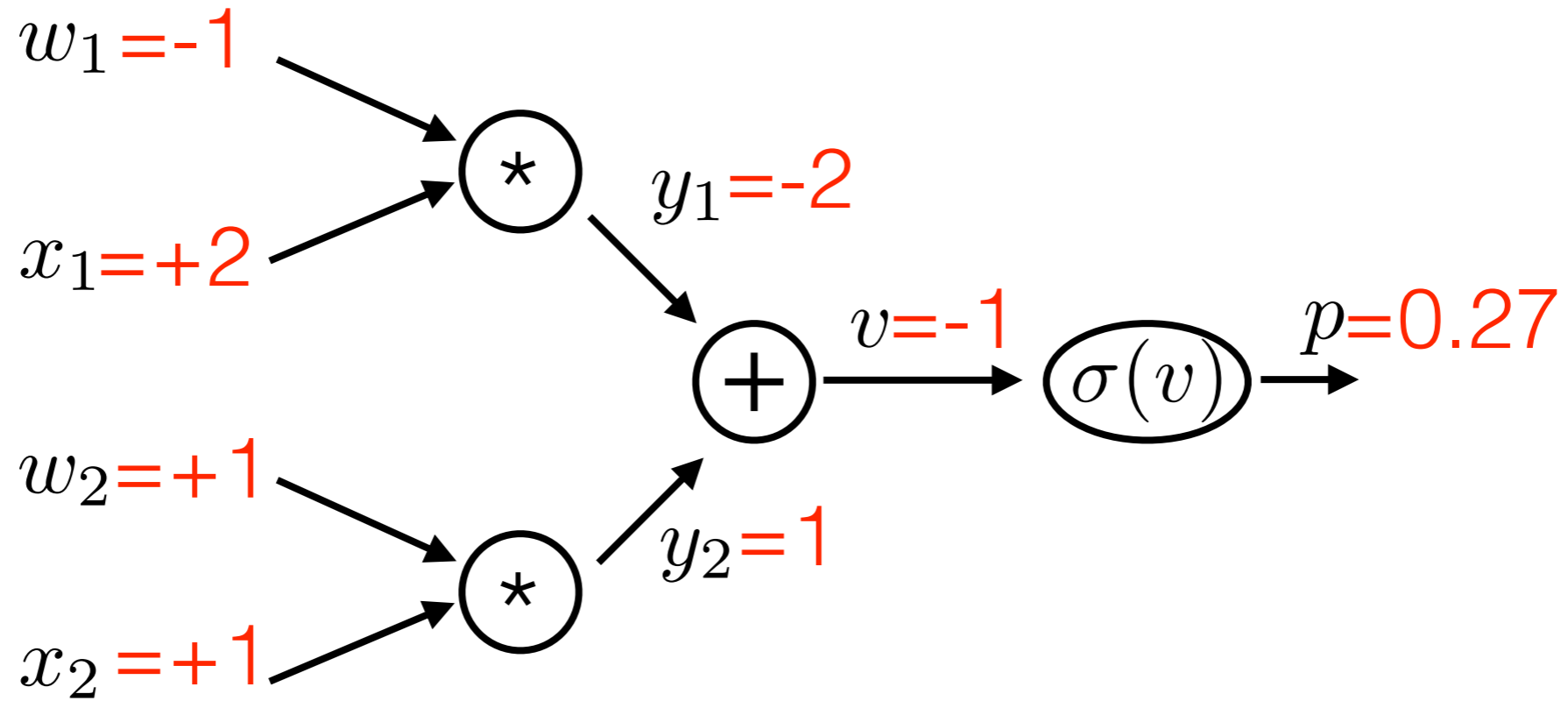

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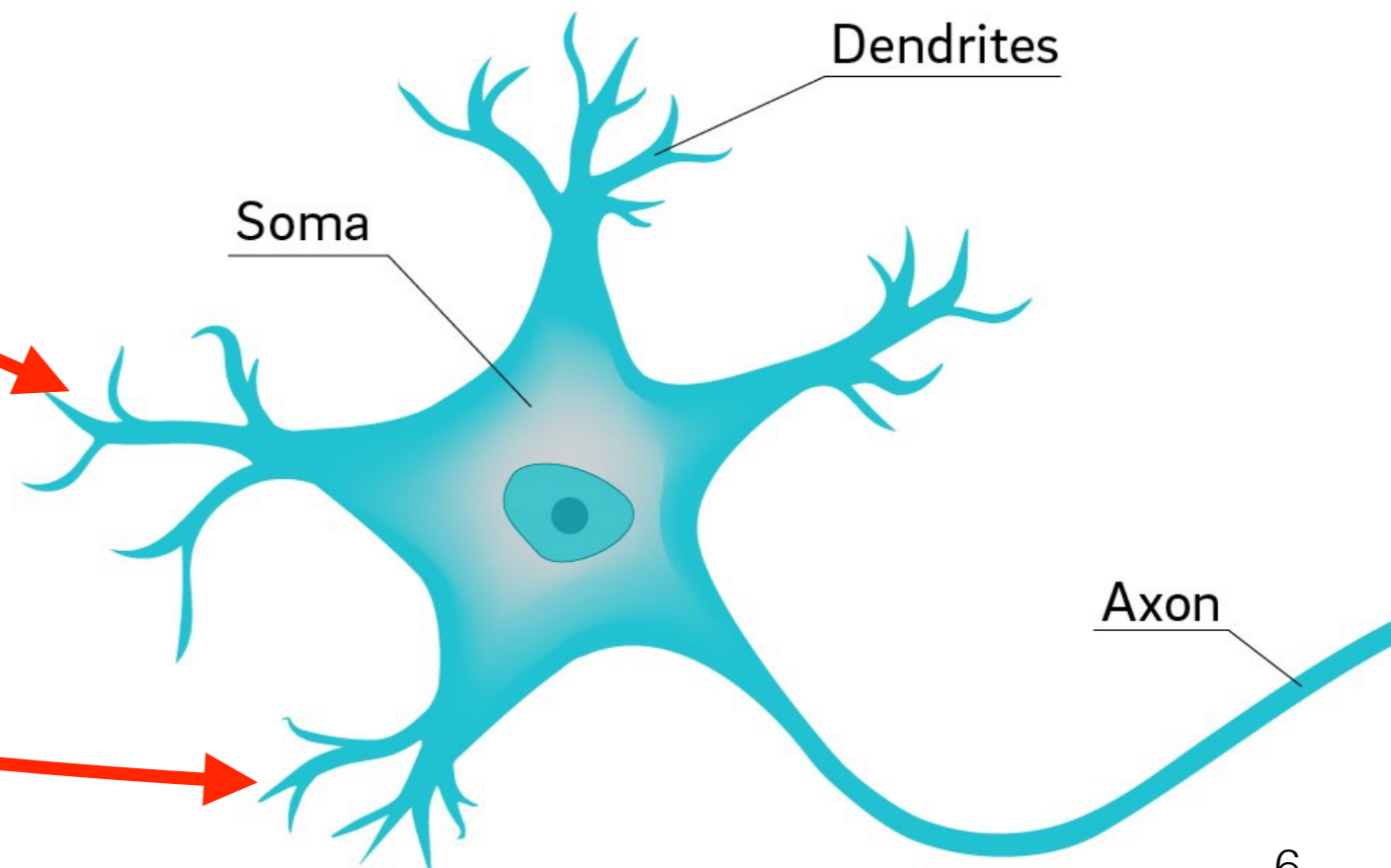
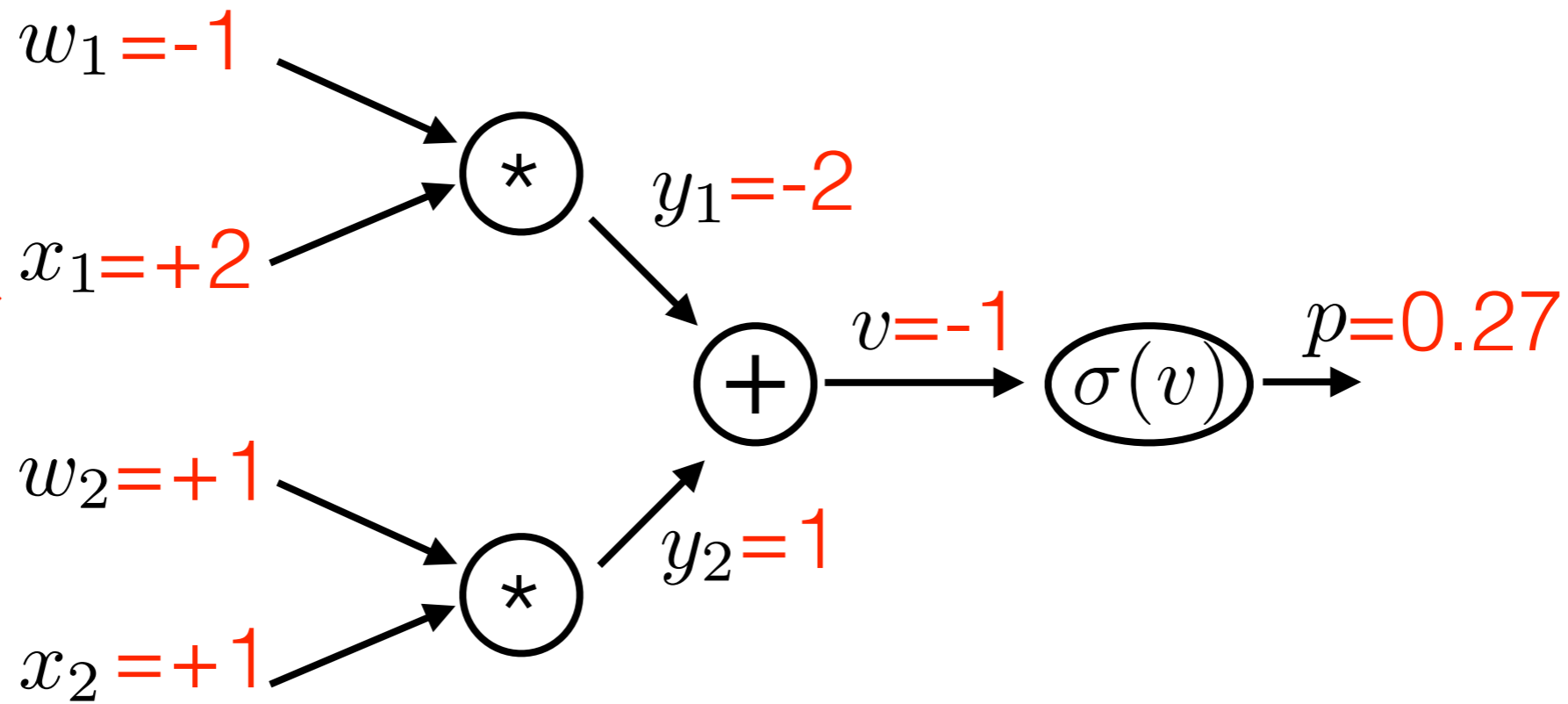
Example I: given trained neuron, and input, what is output?



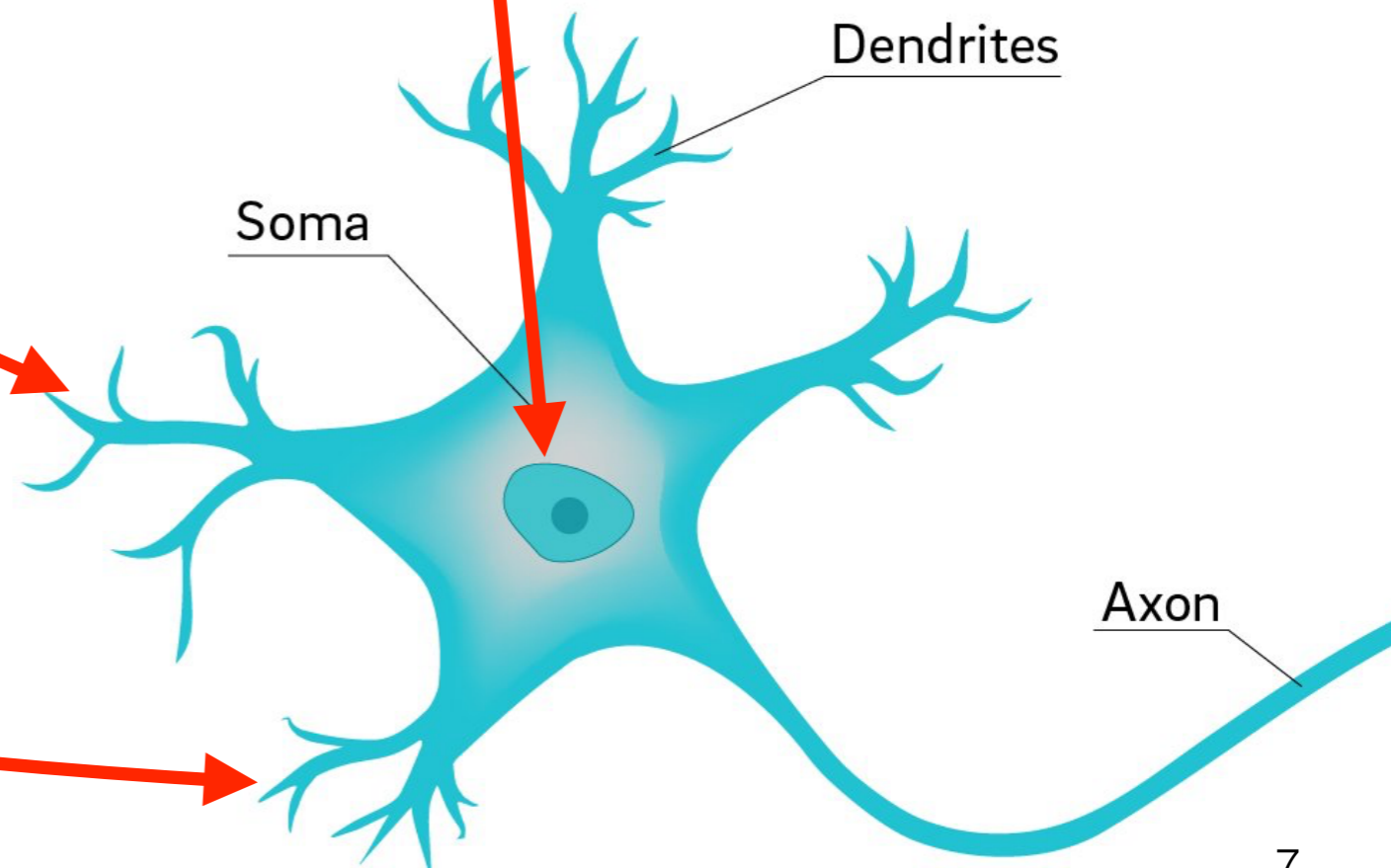
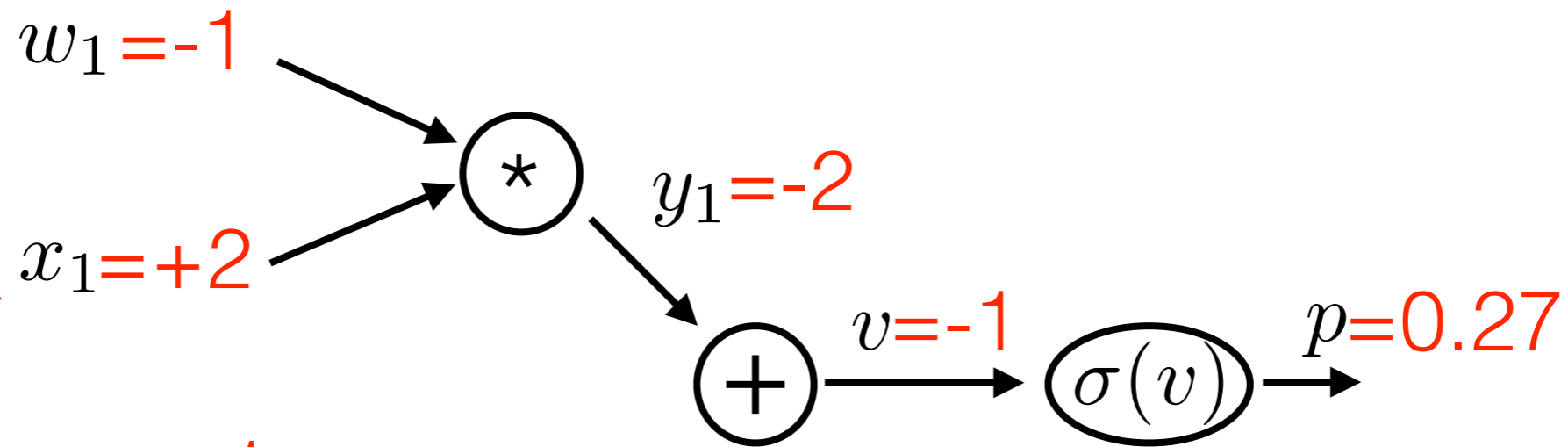
Example I: given trained classifier, and input, what is output?



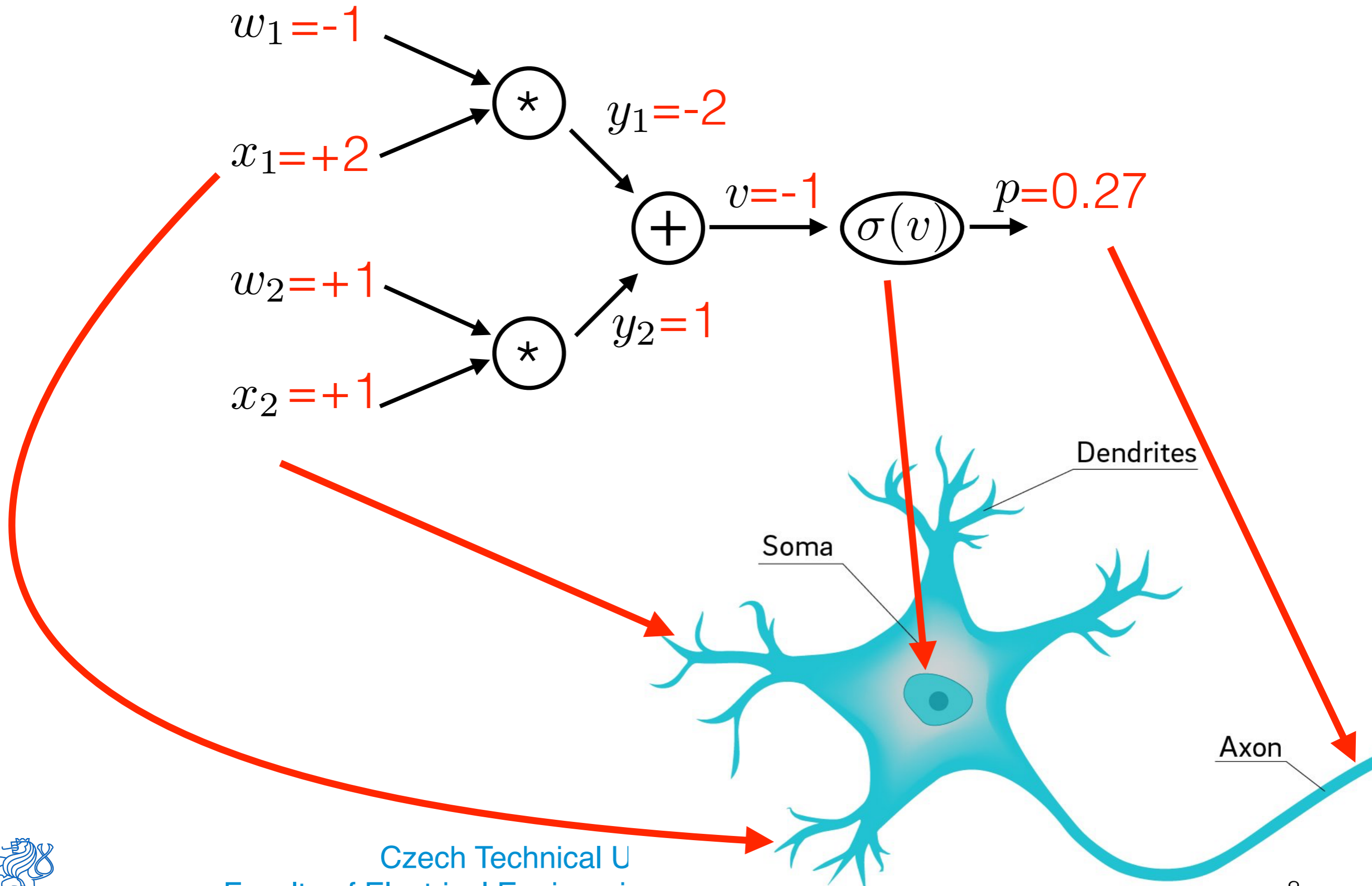
Relation to biological neuron



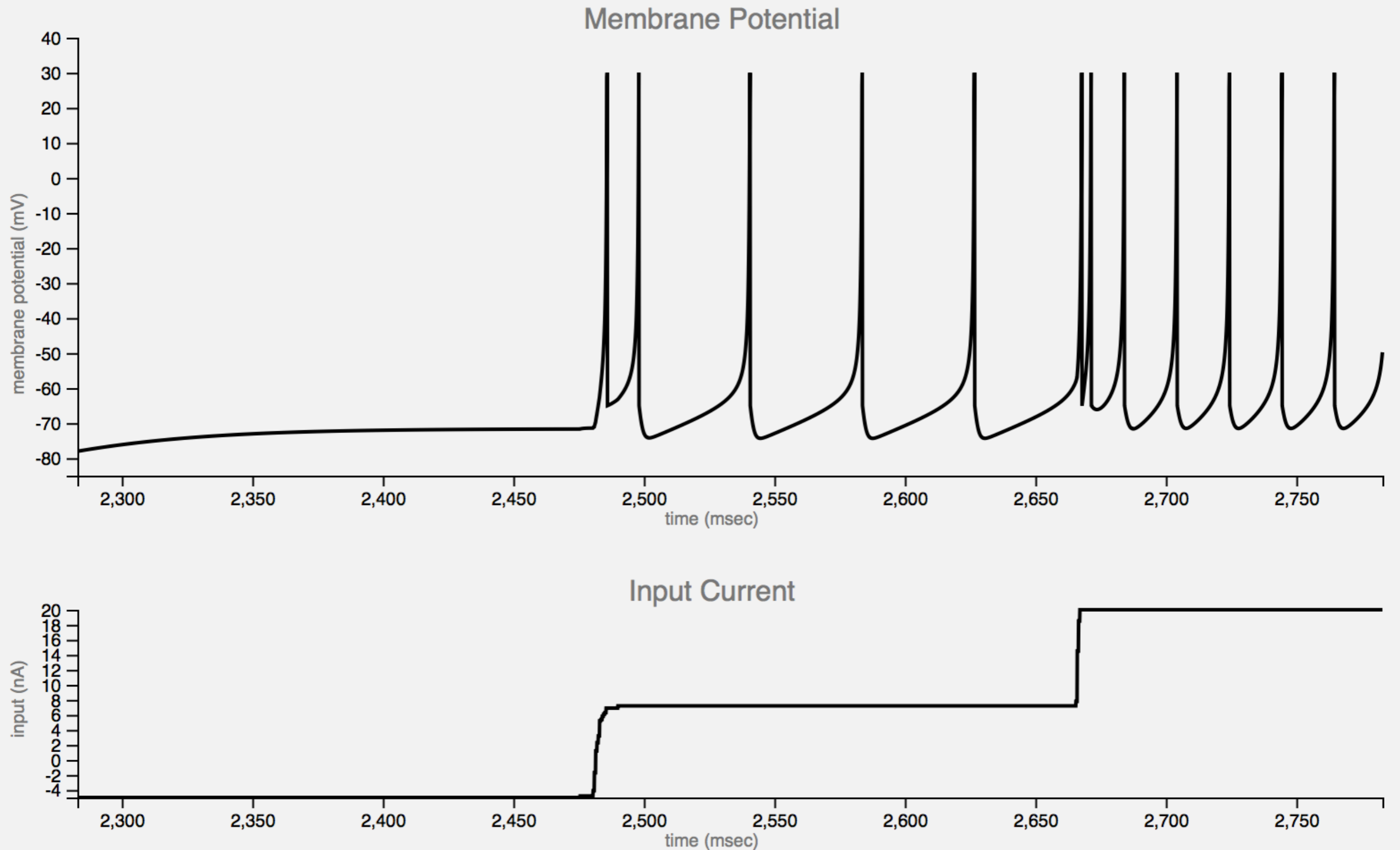
Relation to biological neuron



Relation to biological neuron



Modeling dynamic neuron behaviour



<http://jackterwilliger.com/biological-neural-networks-part-i-spiking-neurons/>

Linear classifier and neuron

Labels


RGB images

+1



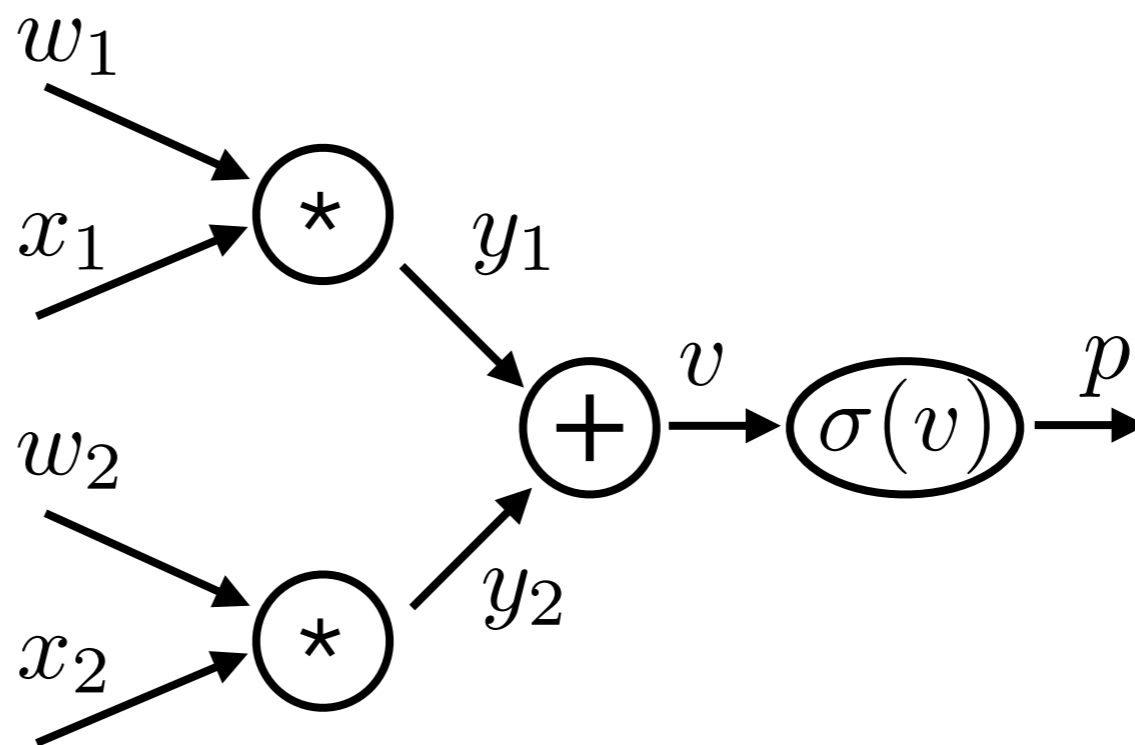
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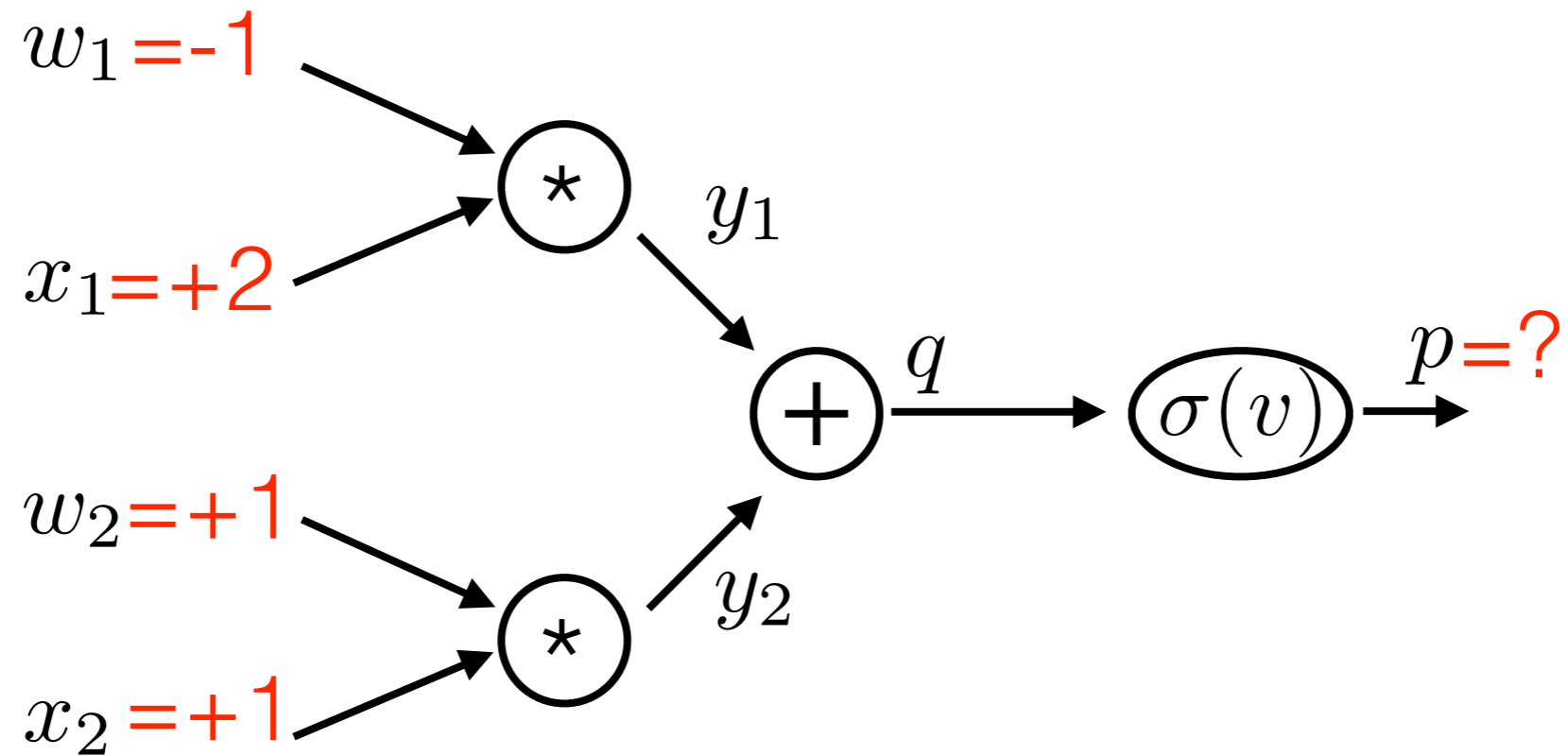
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Computational graph of linear classifier

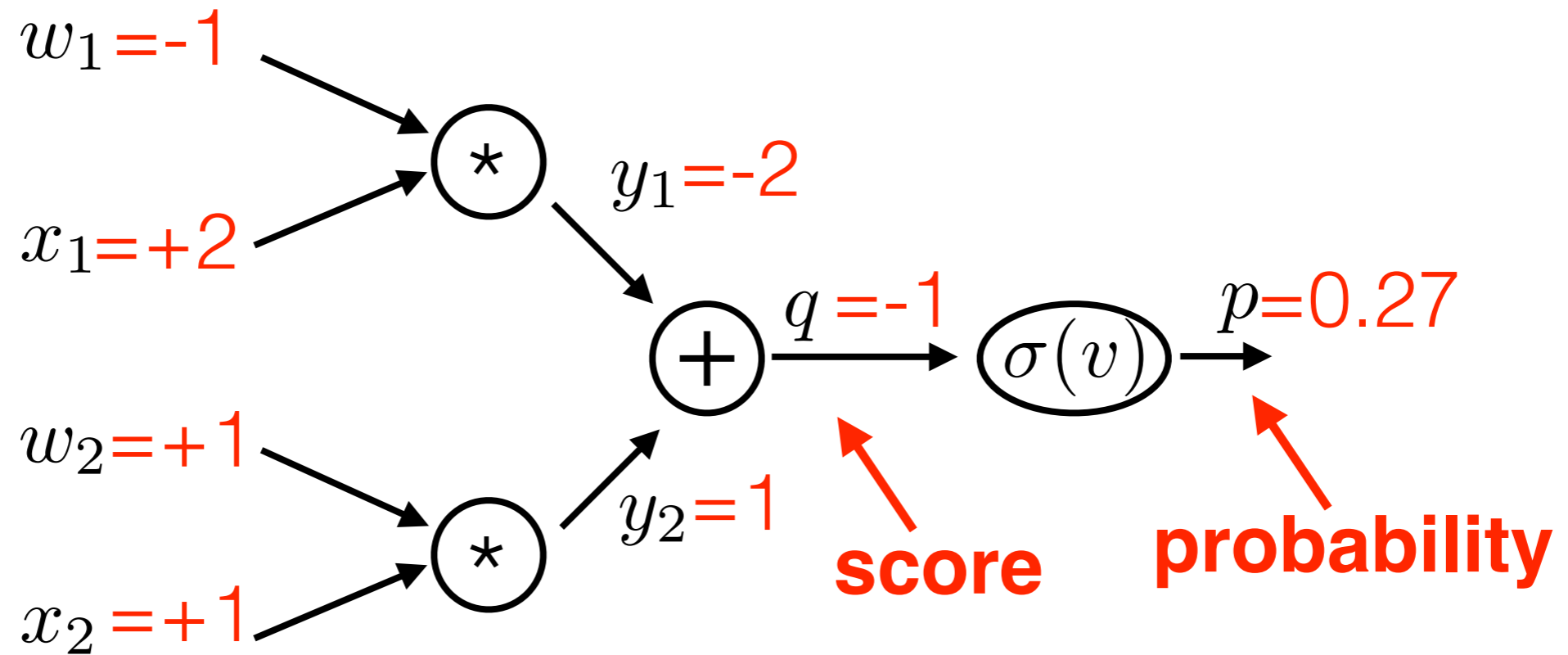

```



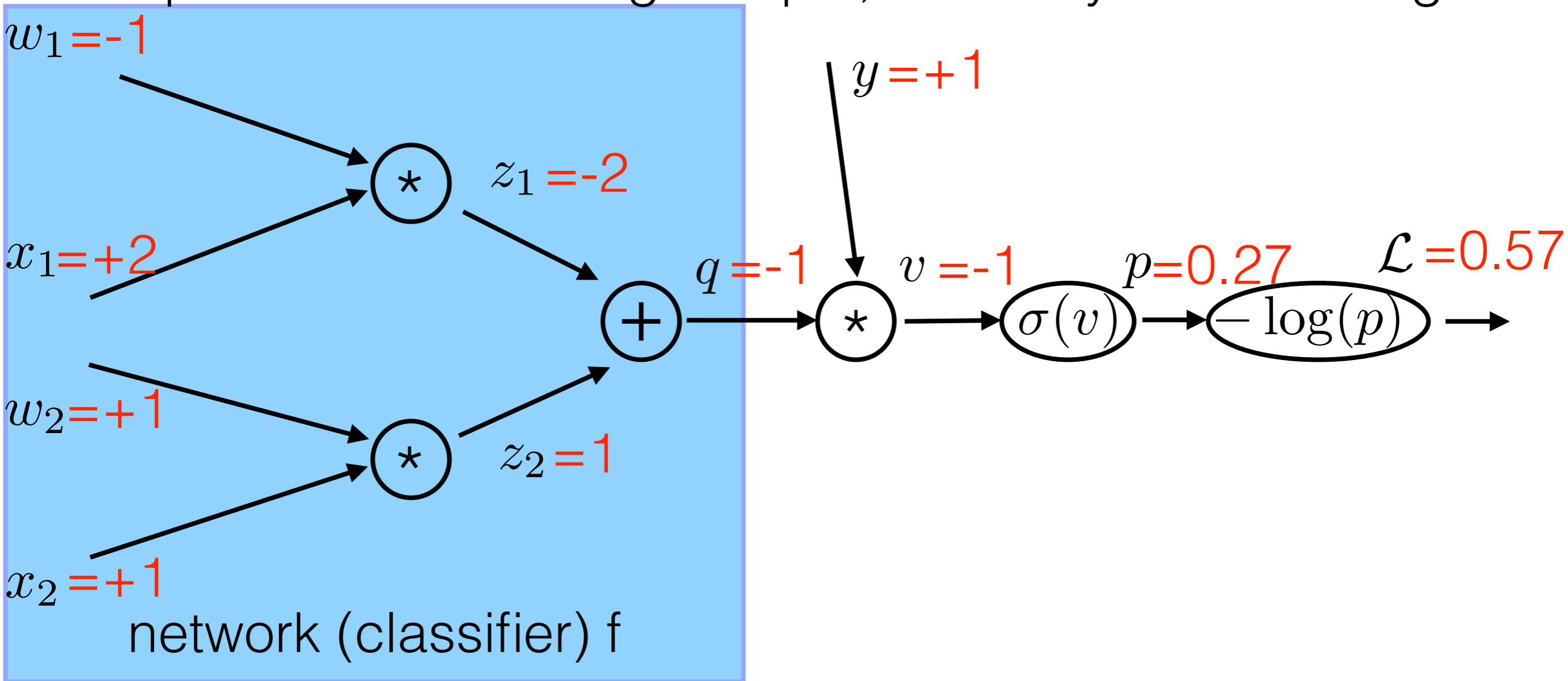
Example I: given trained neuron, and input, what is output?



Example I: given trained classifier, and input, what is output?



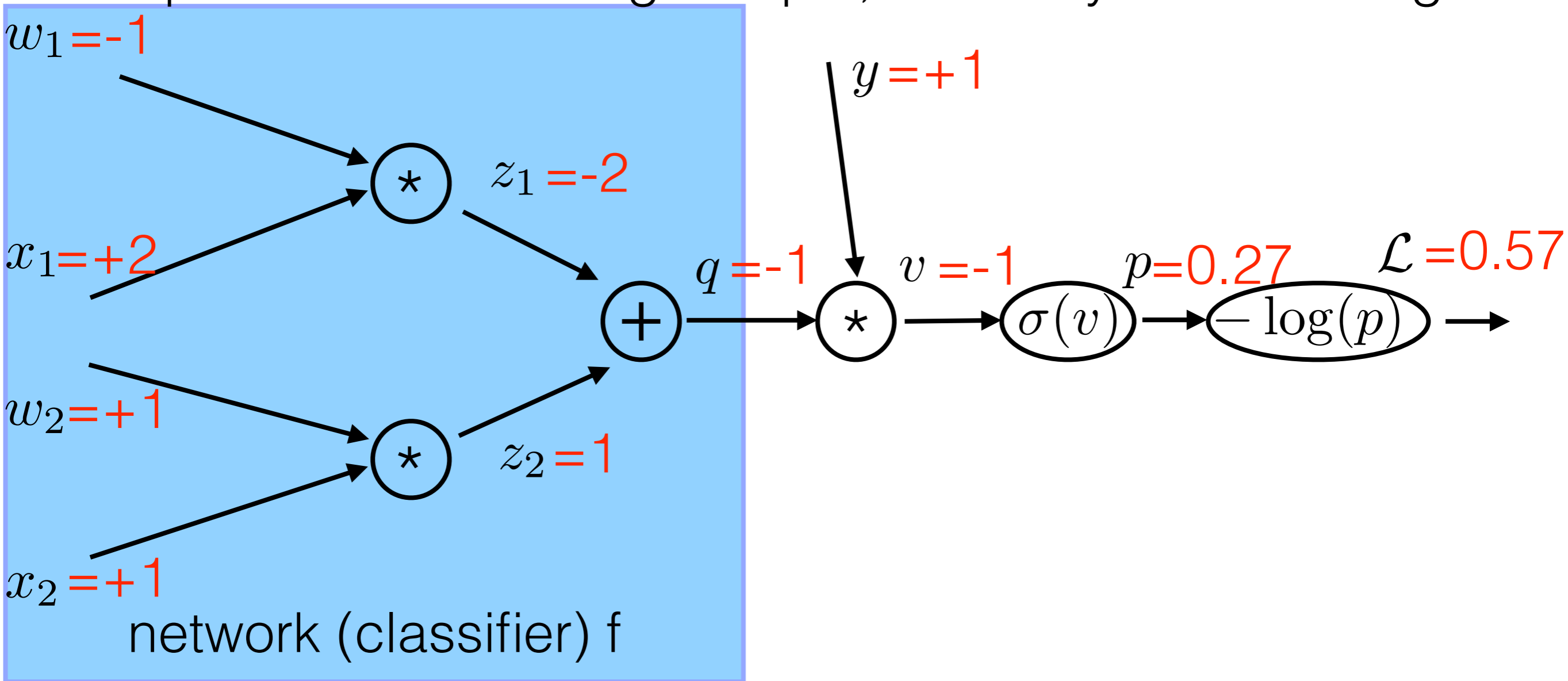
Example II: Given training sample, how do you learn weights?



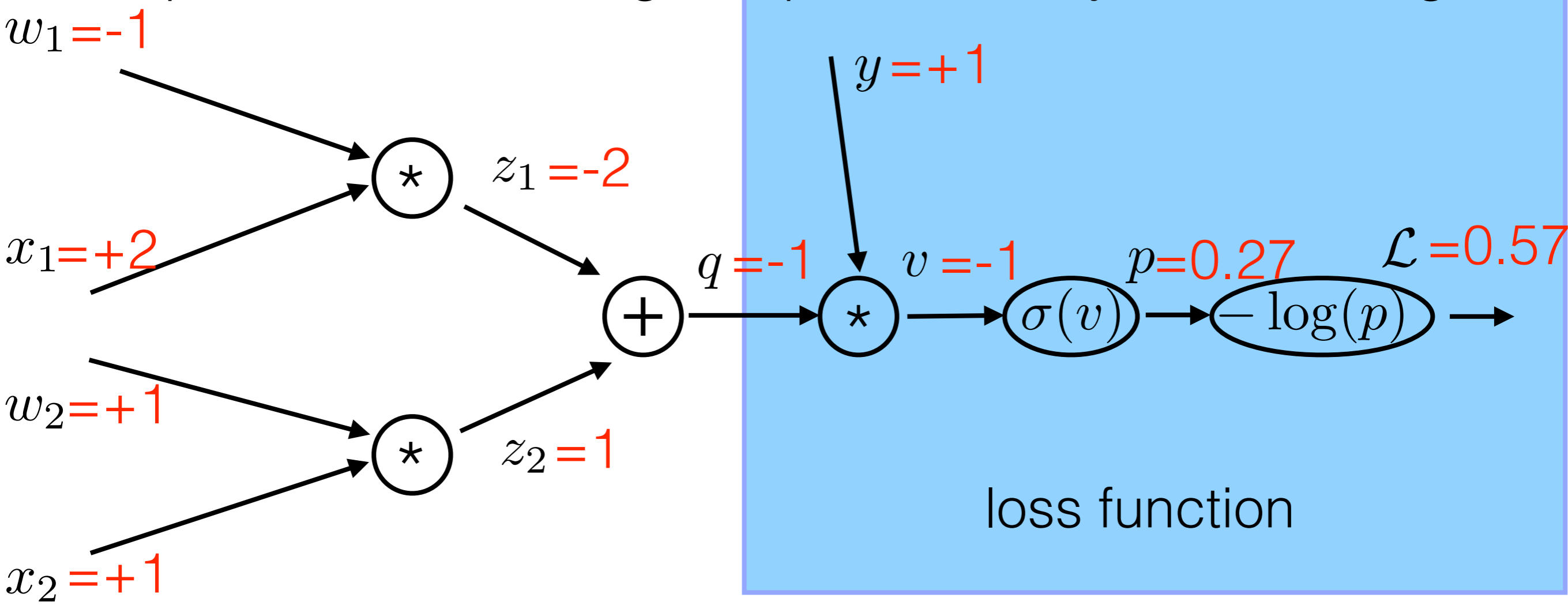
$$\arg \min_{\mathbf{w}} \left(-\log \left[\sigma \left(y_i f(\mathbf{x}_i, \mathbf{w}) \right) \right] \right)$$



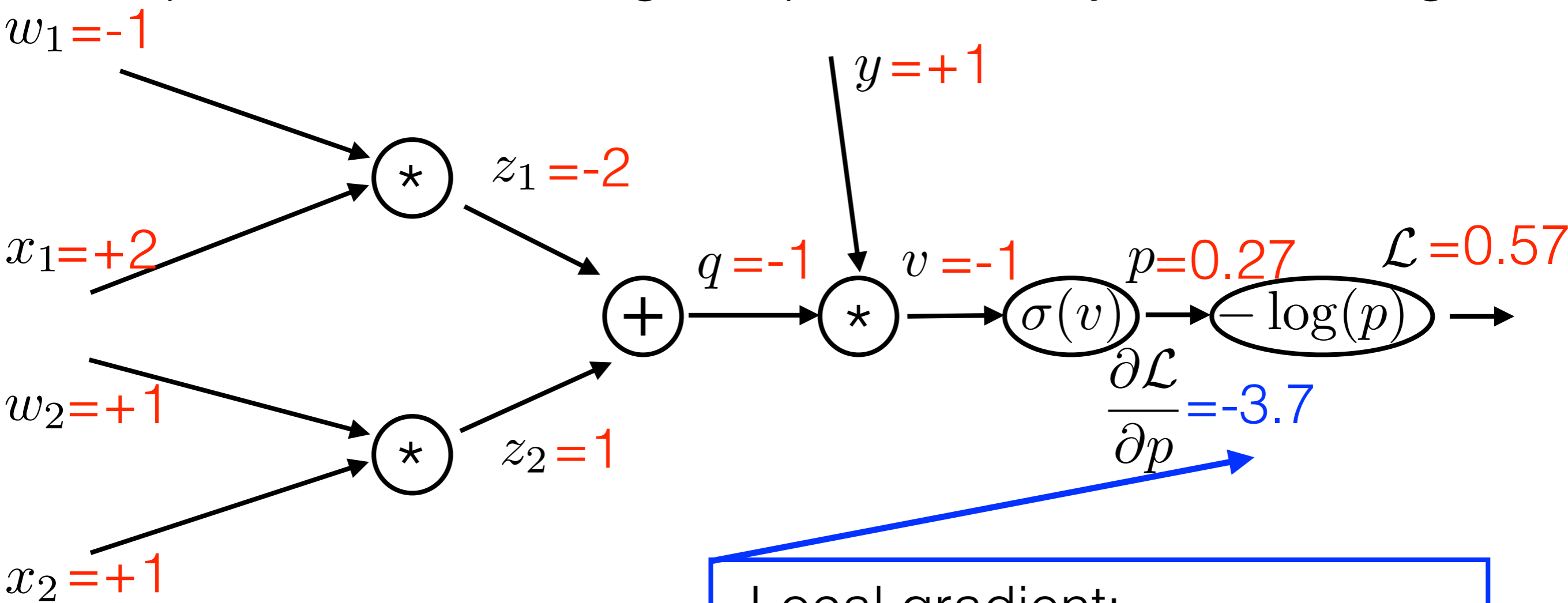
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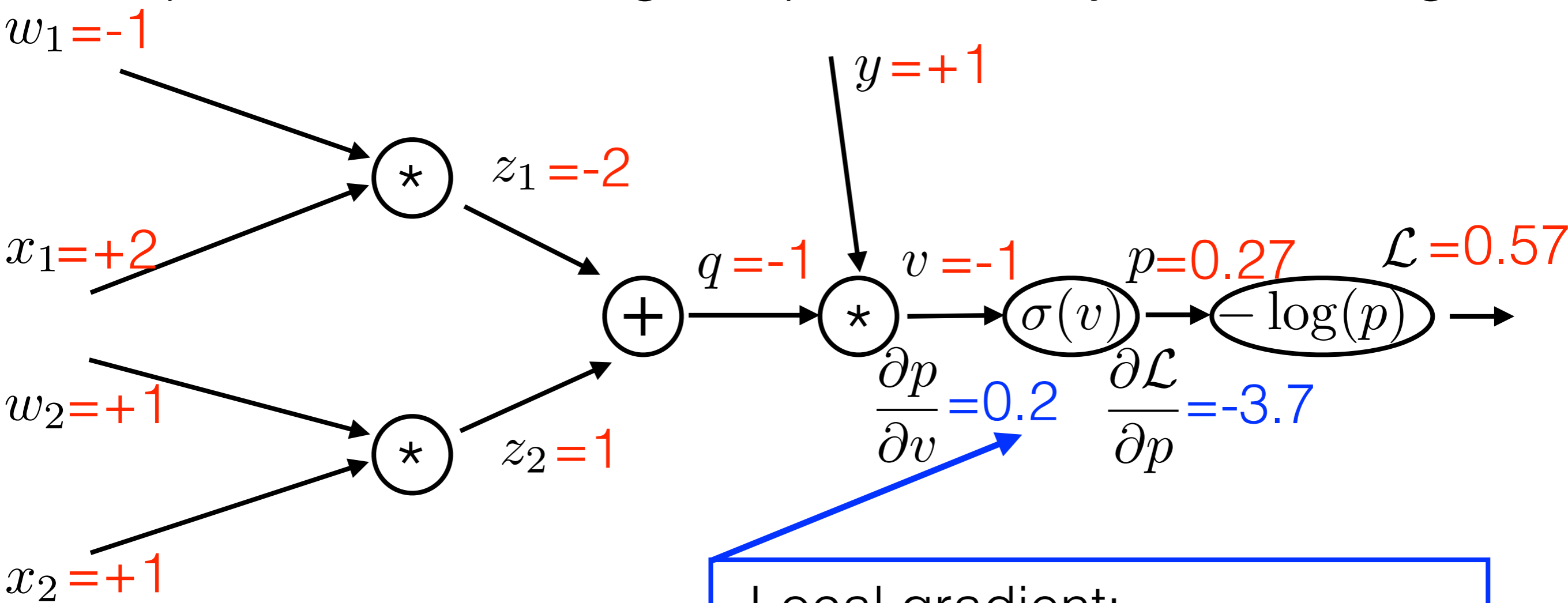


Local gradient:

$$\frac{\partial \mathcal{L}}{\partial p} = \frac{\partial(-\log(p))}{\partial p} = -\frac{1}{p}$$



Example II: Given training sample, how do you learn weights?

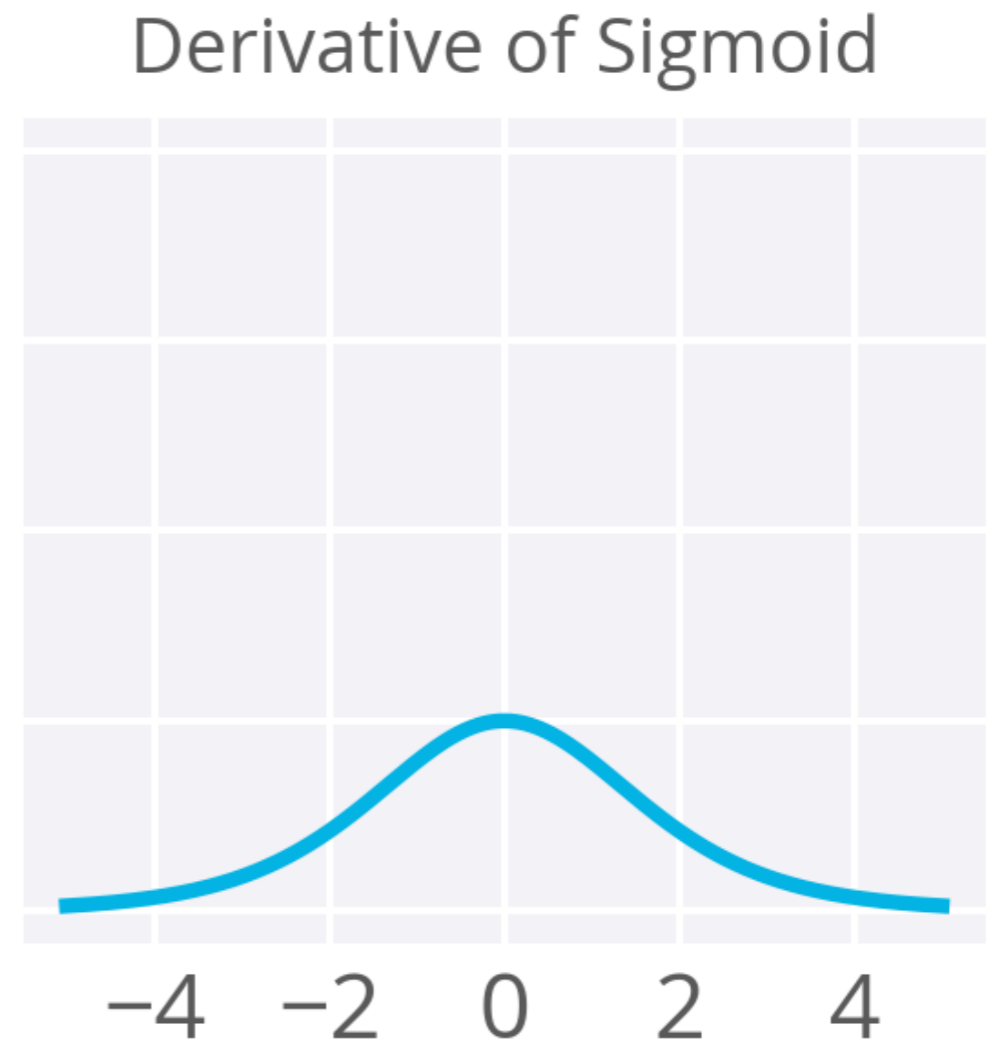
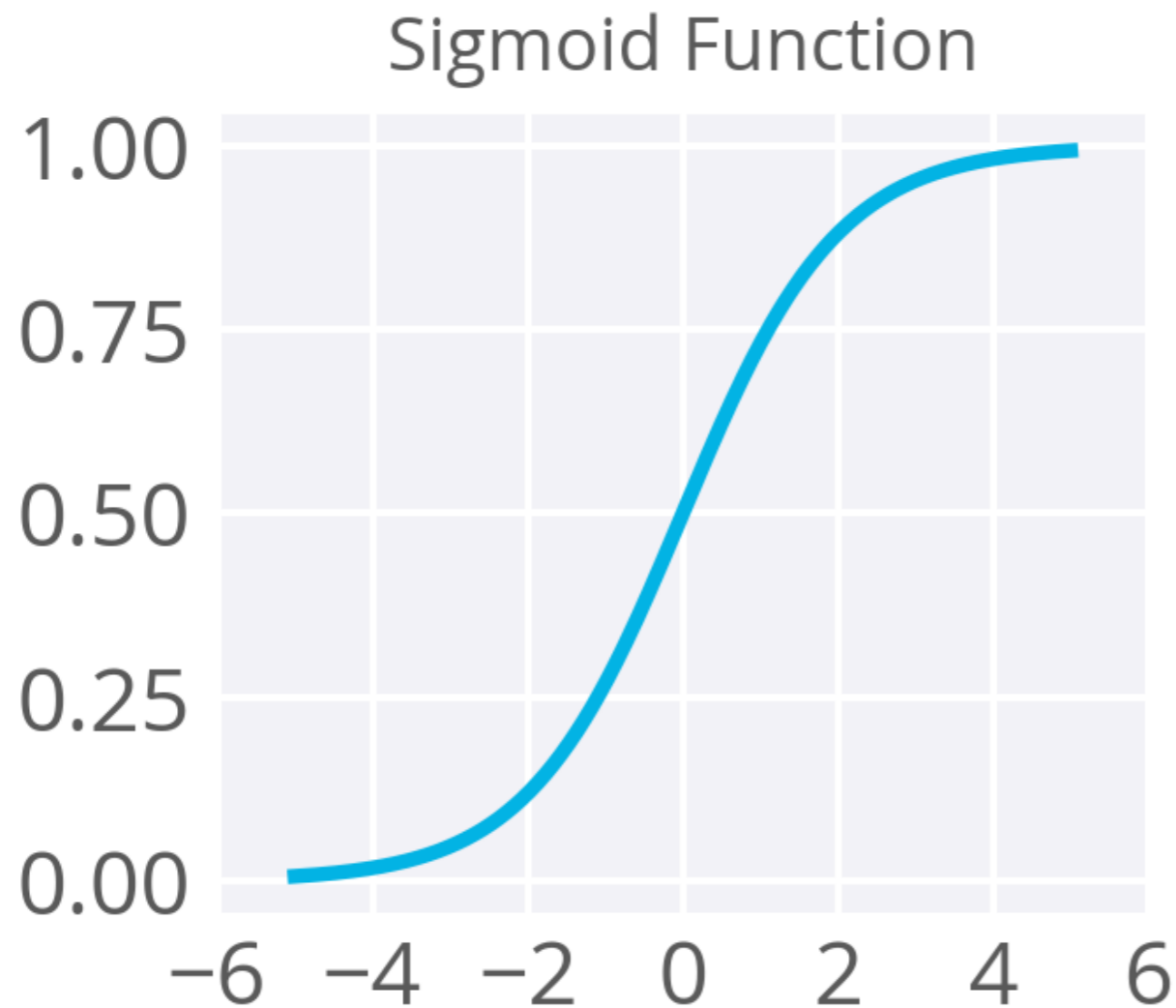


Local gradient:

$$\frac{\partial p}{\partial v} = \frac{\partial \sigma(v)}{\partial v} = \sigma(v)(1 - \sigma(v))$$



Example II: Given training sample, how do you learn weights?

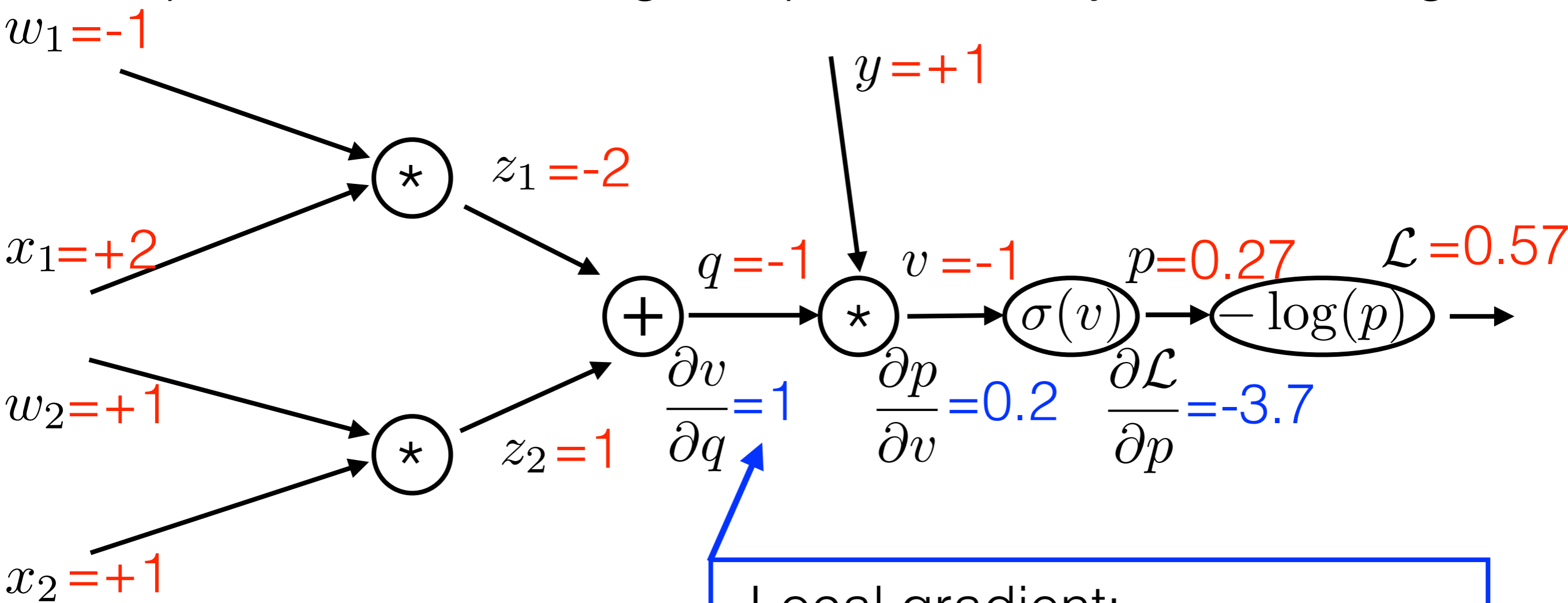


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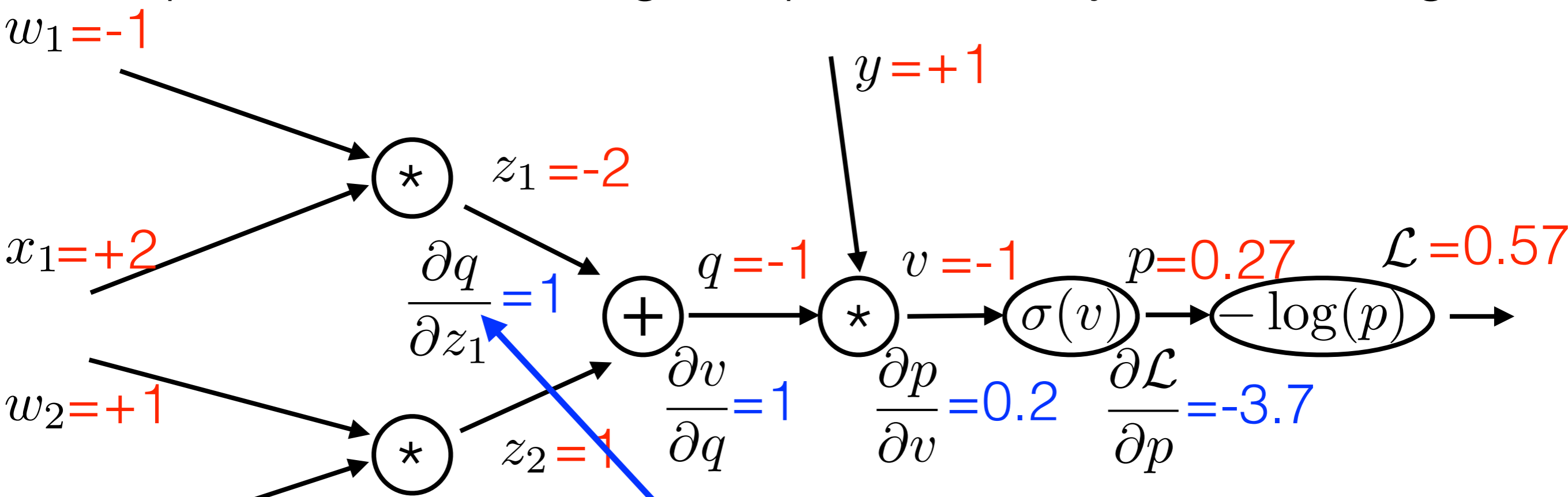


Local gradient:

$$\frac{\partial v}{\partial q} = \frac{\partial (yq)}{\partial q} = y$$



Example II: Given training sample, how do you learn weights?

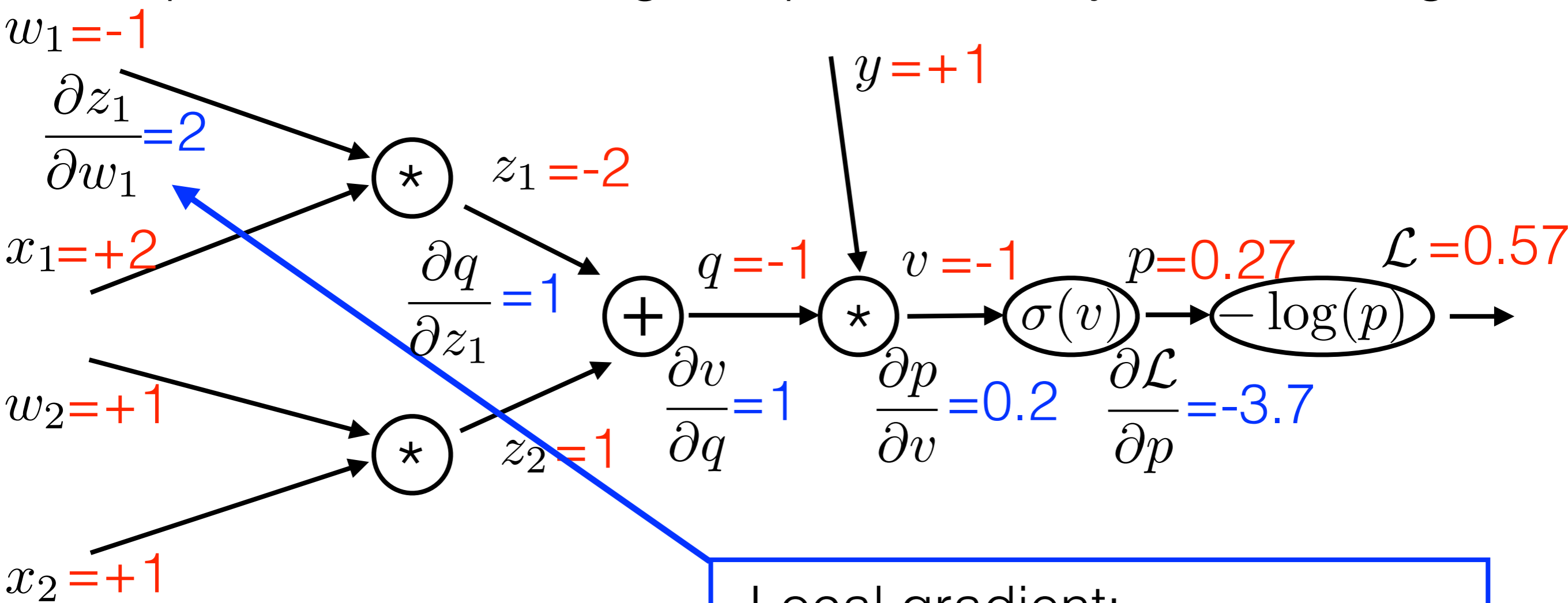


Local gradient:

$$\frac{\partial q}{\partial z_1} = \frac{\partial (z_1 + z_2)}{\partial z_1} = 1$$



Example II: Given training sample, how do you learn weights?

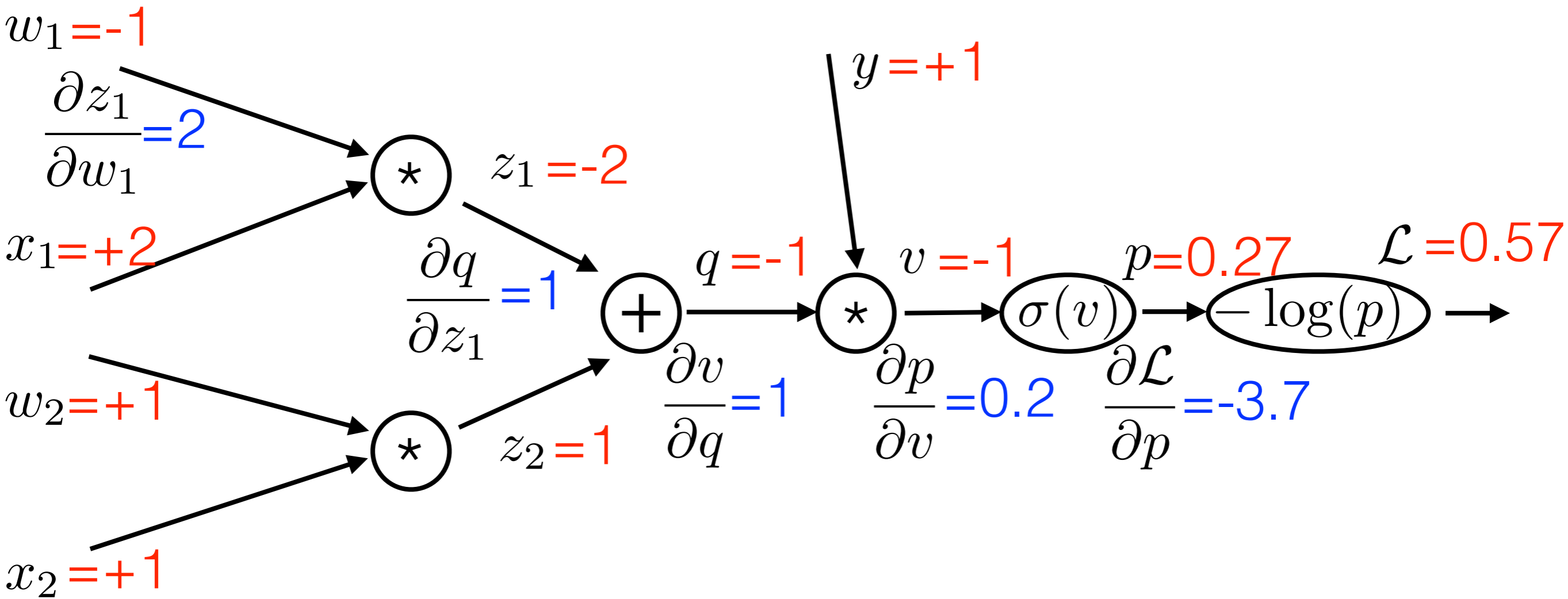


Local gradient:

$$\frac{\partial z_1}{\partial w_1} = \frac{\partial(w_1 x_1)}{\partial w_1} = x_1$$



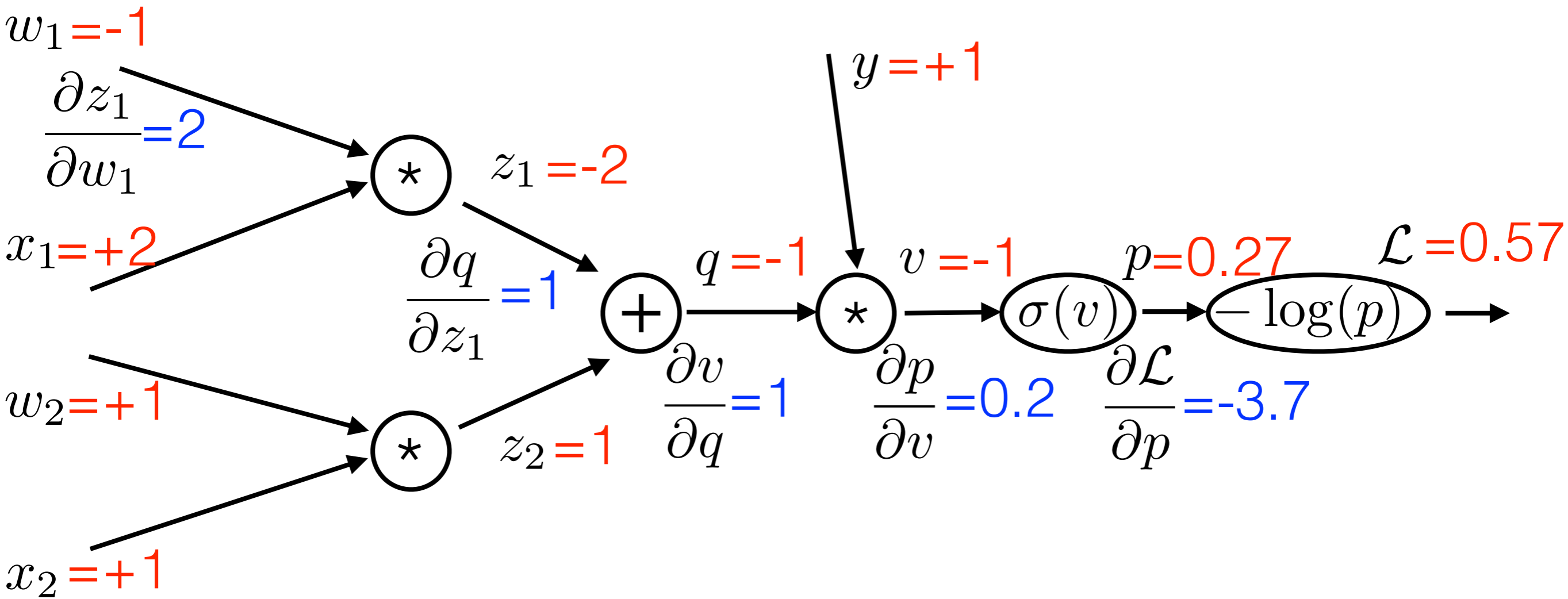
Example II: Given training sample, how do you learn weights?



$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \mathcal{L}}{\partial p} \frac{\partial p}{\partial v} \frac{\partial v}{\partial q} \frac{\partial q}{\partial z_1} \frac{\partial z_1}{\partial w_1} = -3.7 * 0.2 * 1 * 1 * 2 = -1.48$$



Example II: Given training sample, how do you learn weights?



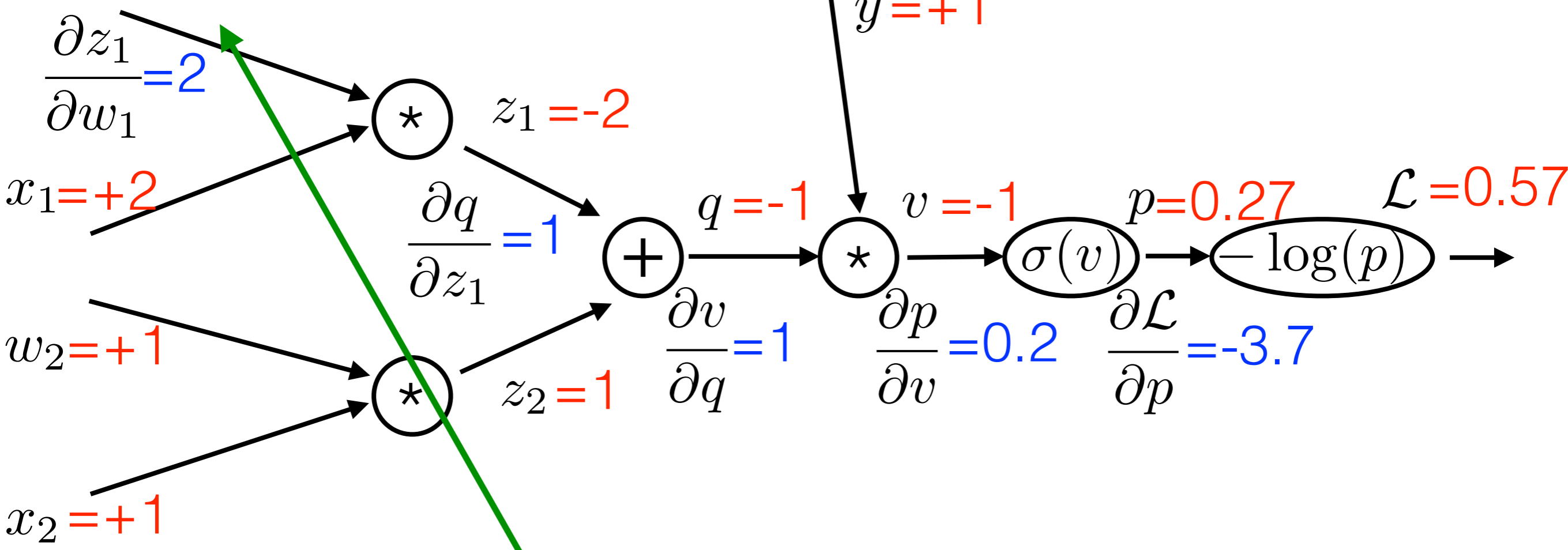
$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \mathcal{L}}{\partial p} \frac{\partial p}{\partial v} \frac{\partial v}{\partial q} \frac{\partial q}{\partial z_1} \frac{\partial z_1}{\partial w_1} = -3.7 * 0.2 * 1 * 1 * 2 = -1.48$$

$$w_1 = w_1 - \alpha \frac{\partial \mathcal{L}}{\partial w_1} = +0.48$$



Example II: Given training sample, how do you learn weights?

$w_1 = +0.48$



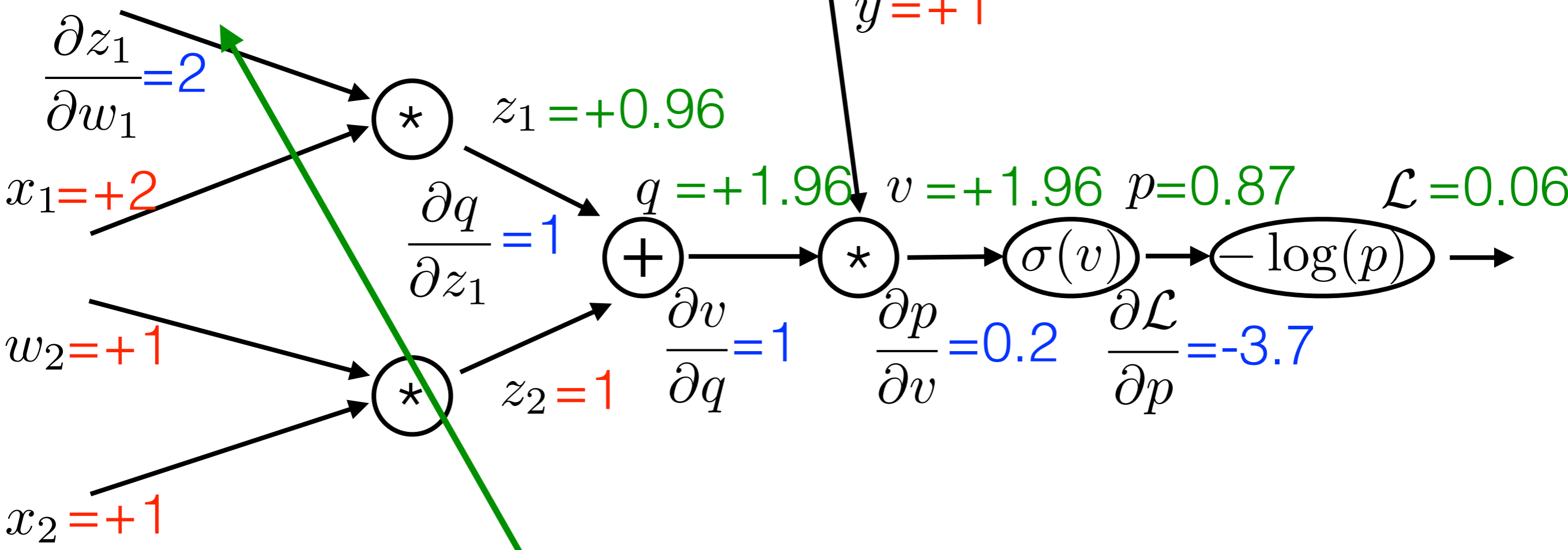
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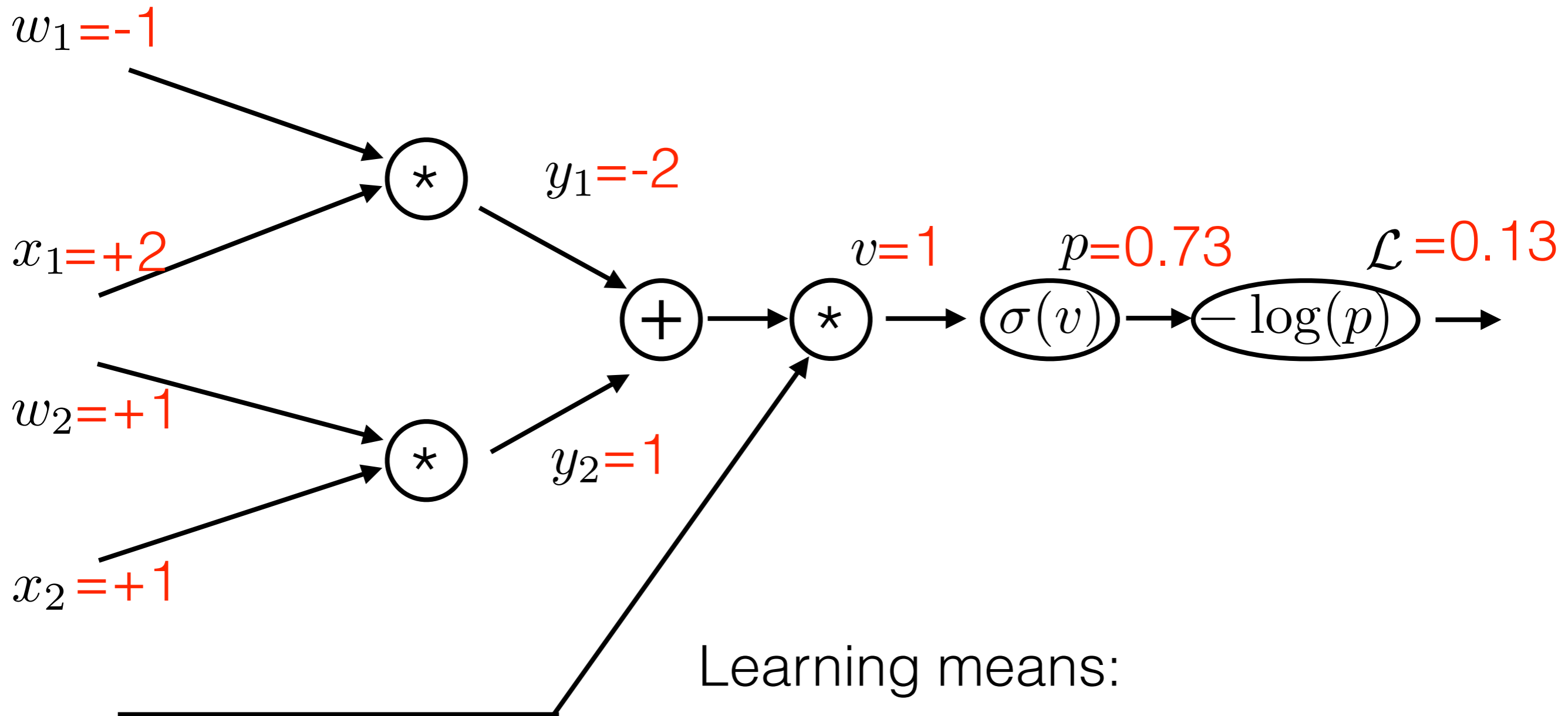


$$\frac{\partial \mathcal{L}}{\partial w_1} = \frac{\partial \mathcal{L}}{\partial p} \frac{\partial p}{\partial v} \frac{\partial v}{\partial q} \frac{\partial q}{\partial z_1} \frac{\partial z_1}{\partial w_1} = -3.7 * 0.2 * 1 * 1 * 2 = -1.48$$

$$w_1 = w_1 - \alpha \frac{\partial \mathcal{L}}{\partial w_1} = +0.48$$



Example III: vector representation

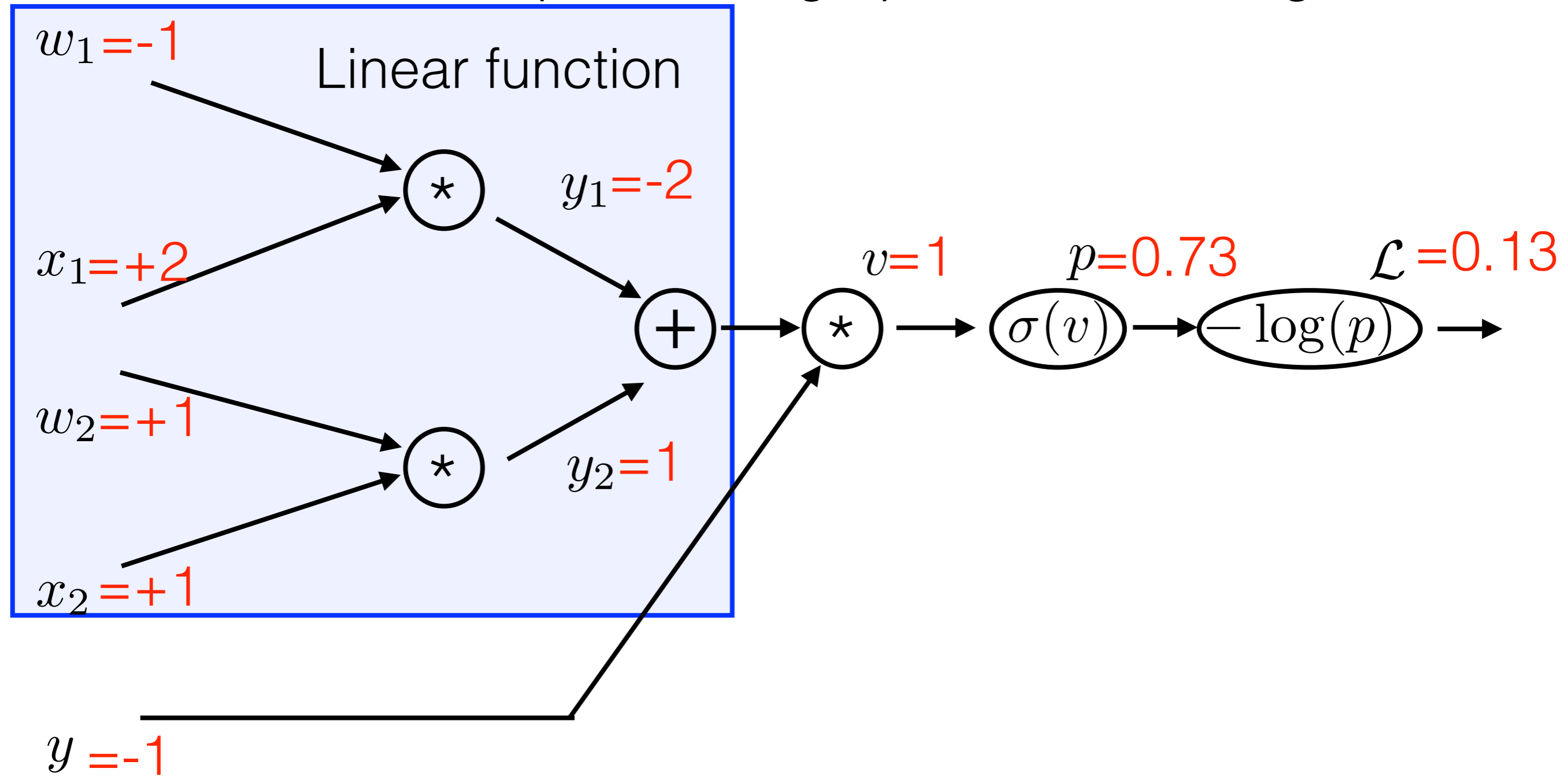


$y = -1$ Iteratively change all weights \mathbf{w} to minimize \mathcal{L}

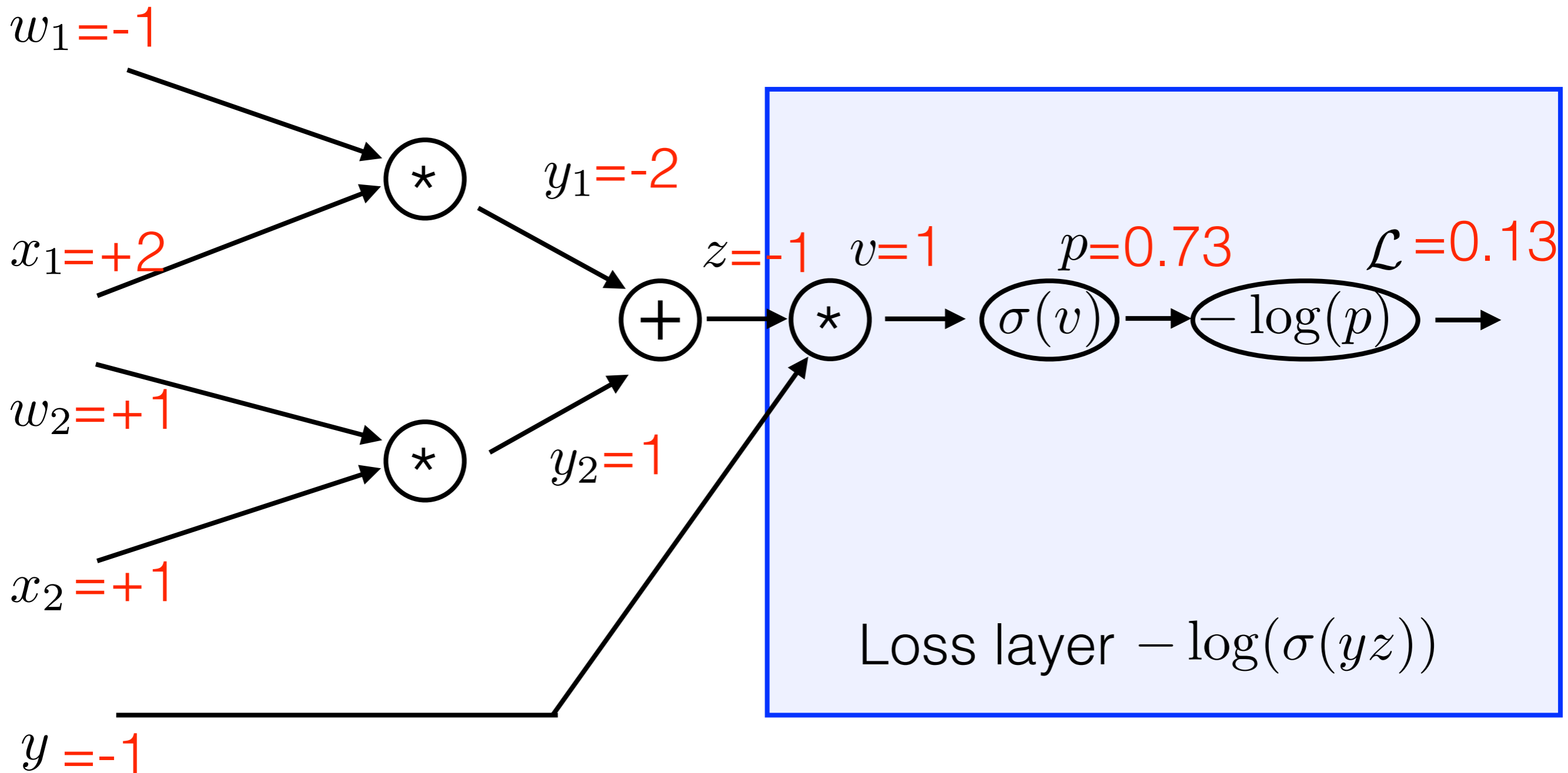
$$\mathbf{w} = \mathbf{w} - \alpha \left[\frac{\partial \mathcal{L}(\mathbf{w})}{\partial \mathbf{w}} \right]^\top \quad \text{where} \quad \frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \left[\frac{\partial \mathcal{L}}{\partial w_1}, \frac{\partial \mathcal{L}}{\partial w_2}, \dots \right]$$



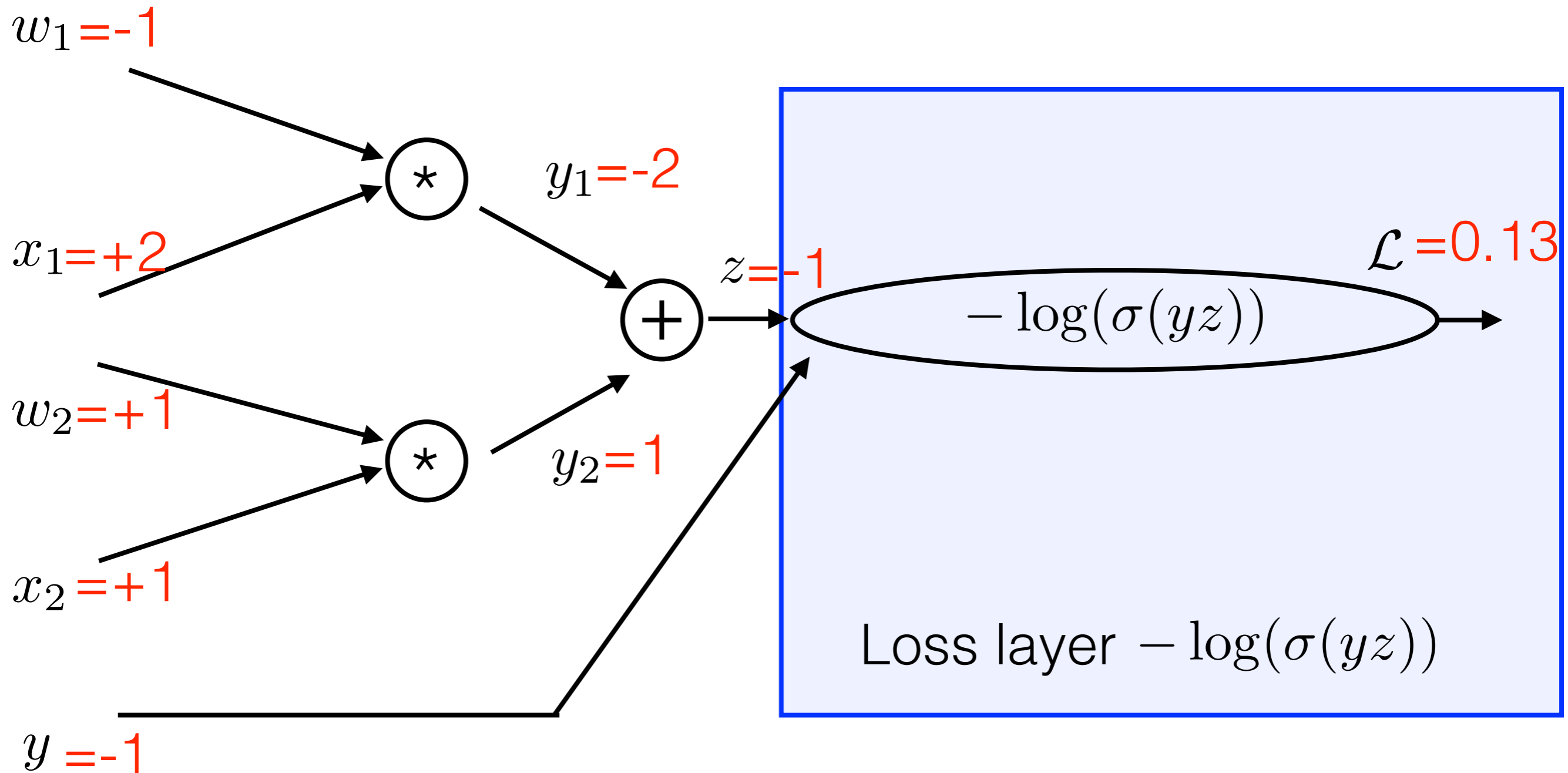
Computational graph of the learning



Computational graph of the learning



Backprop in vector representation

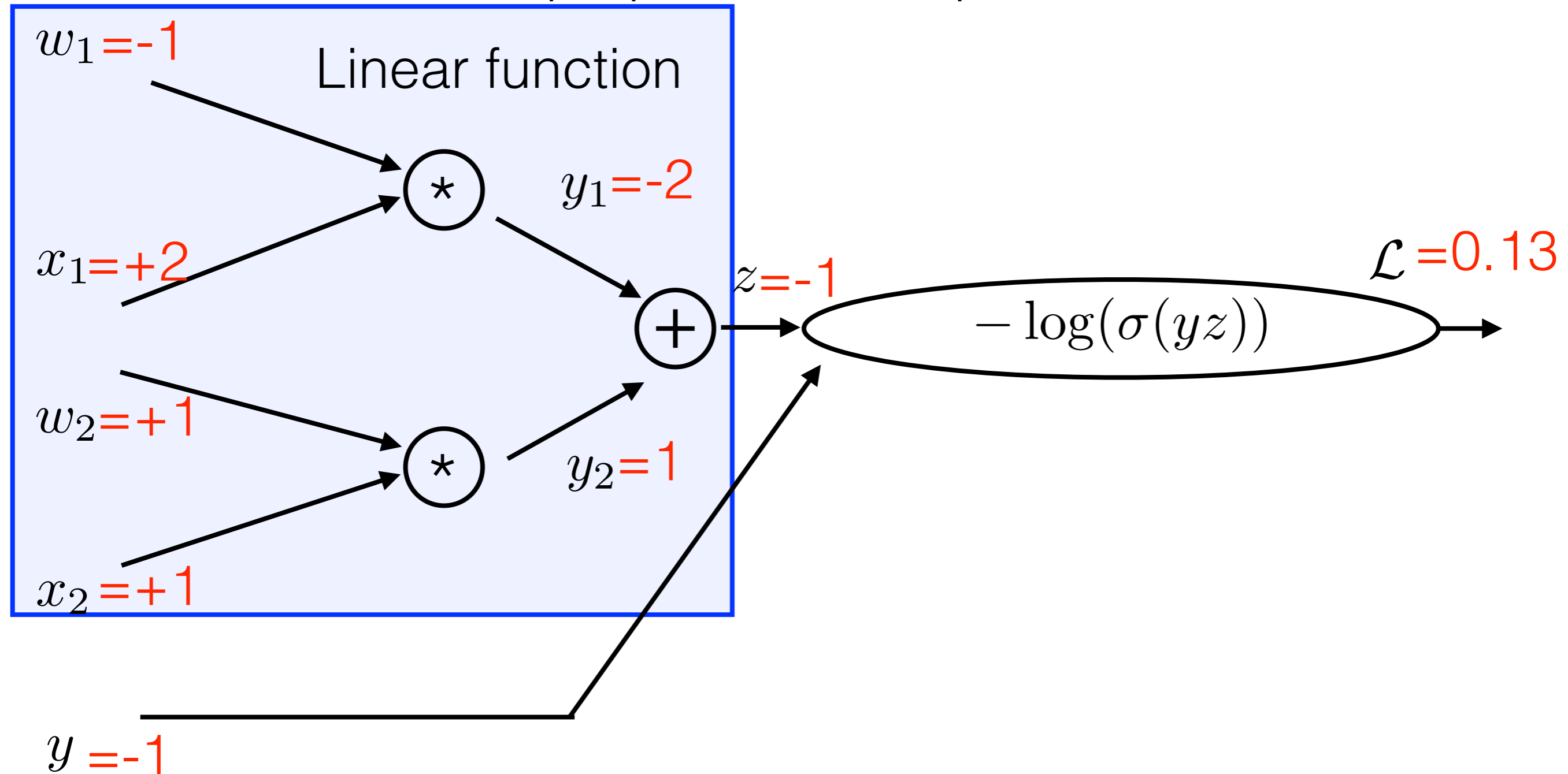


This is the logistic loss!

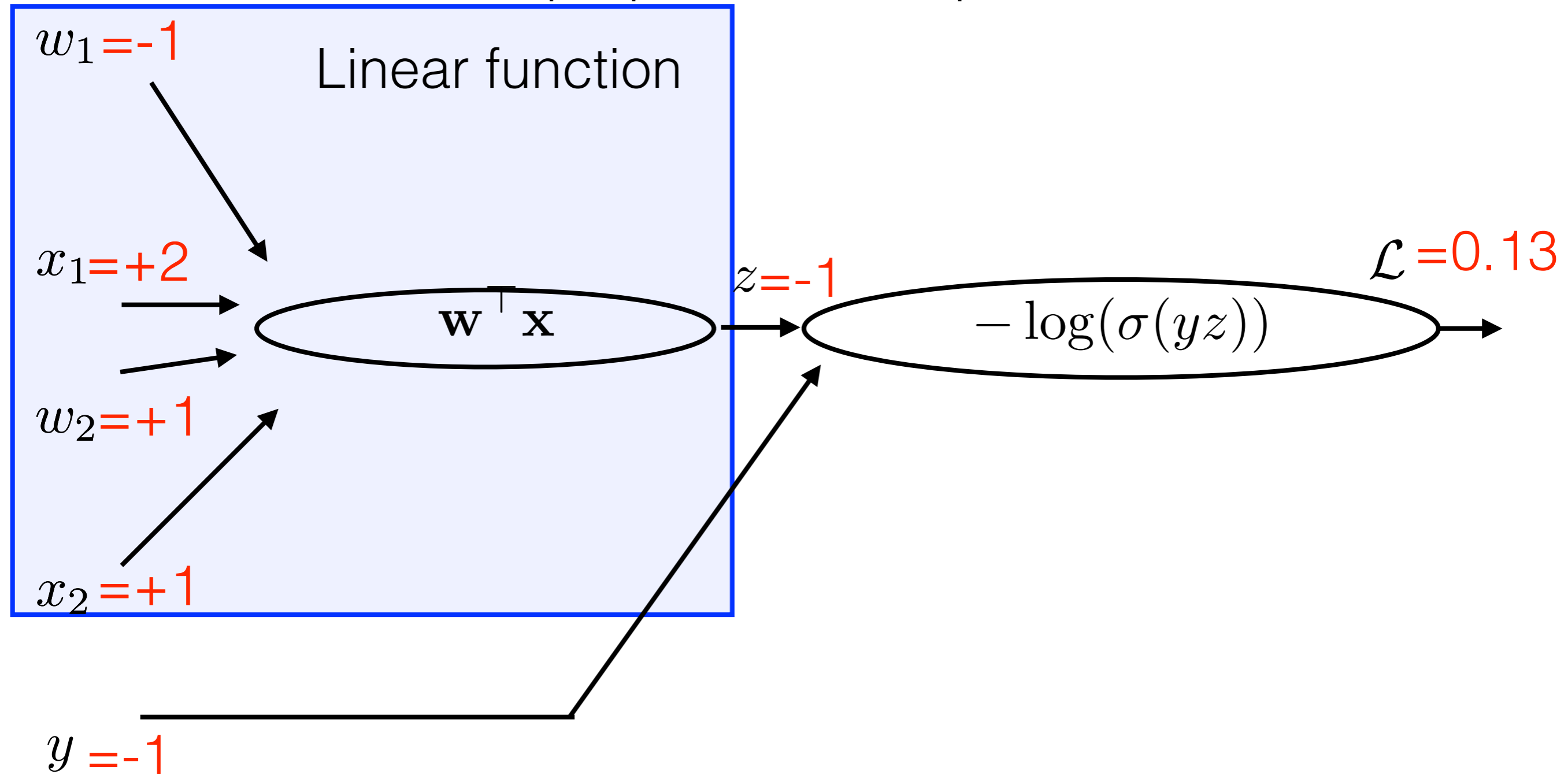
$$\mathcal{L}(y, z) = -\log(\sigma(yz)) = \log(1 + \exp(-yz))$$



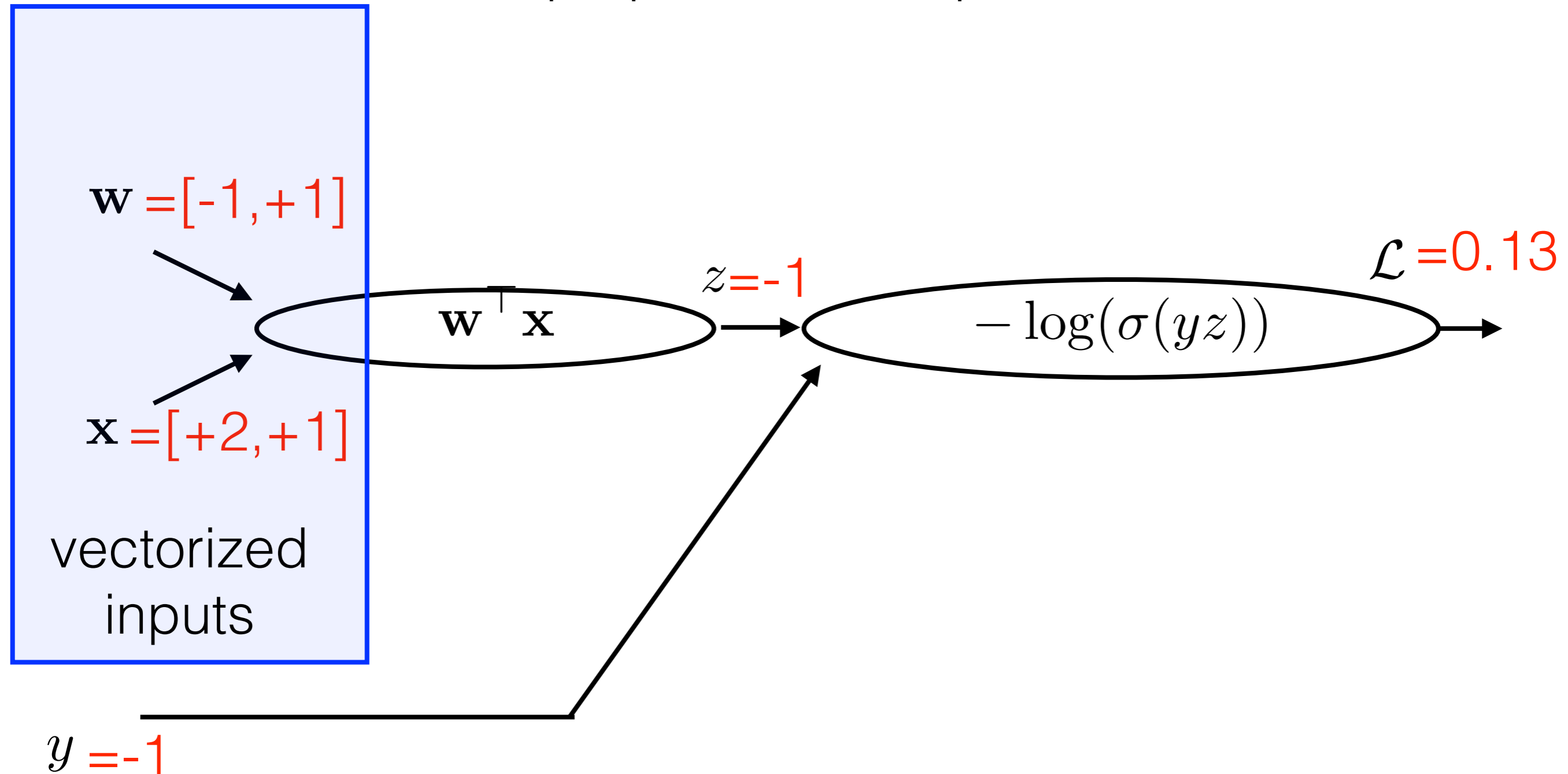
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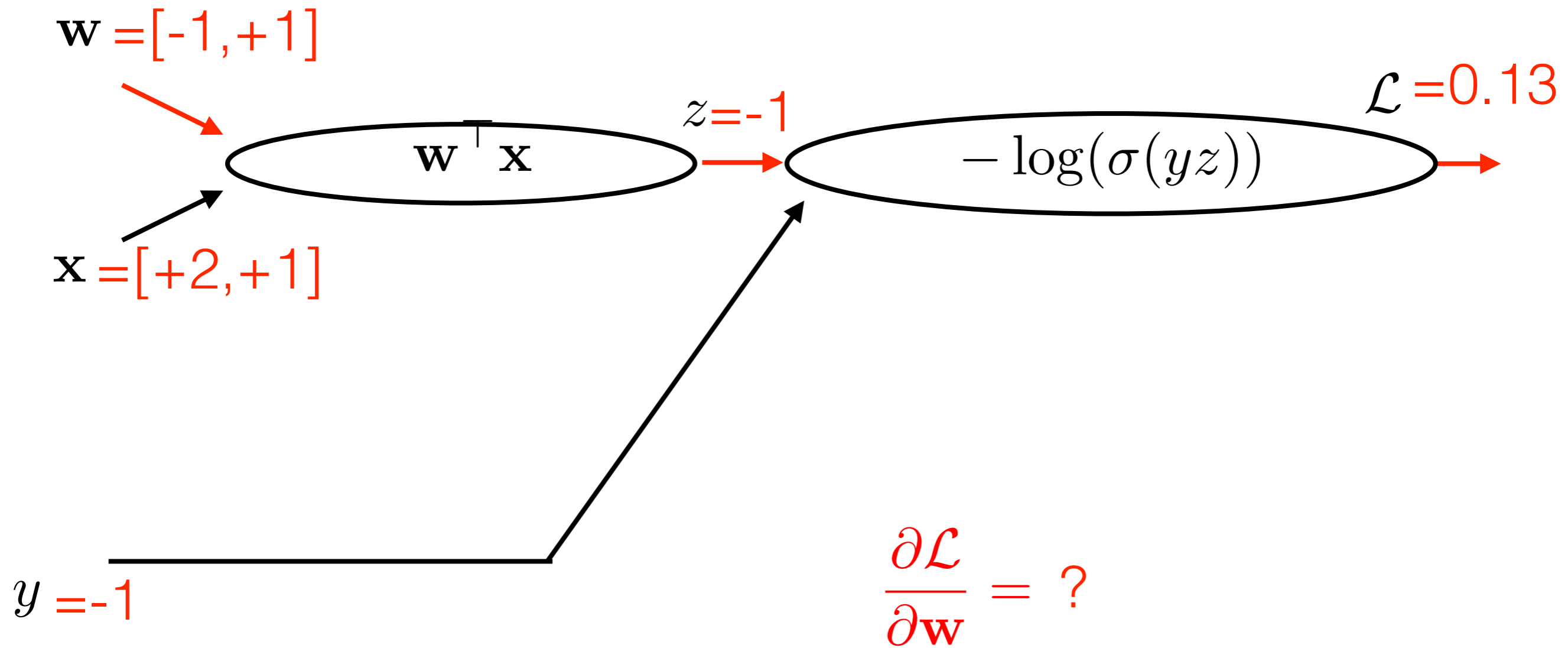
Backprop in vector representation



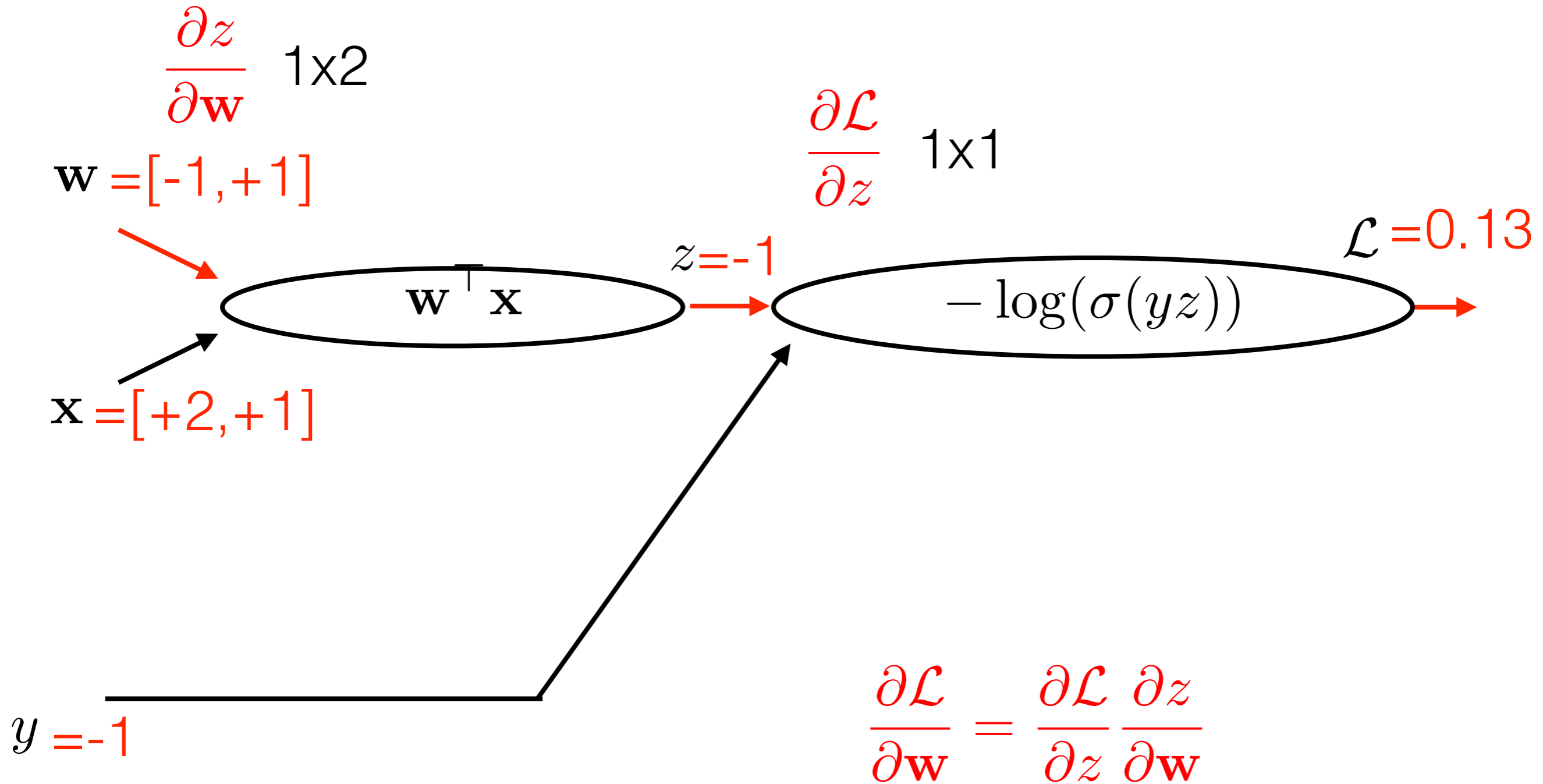
Backprop in vector representation



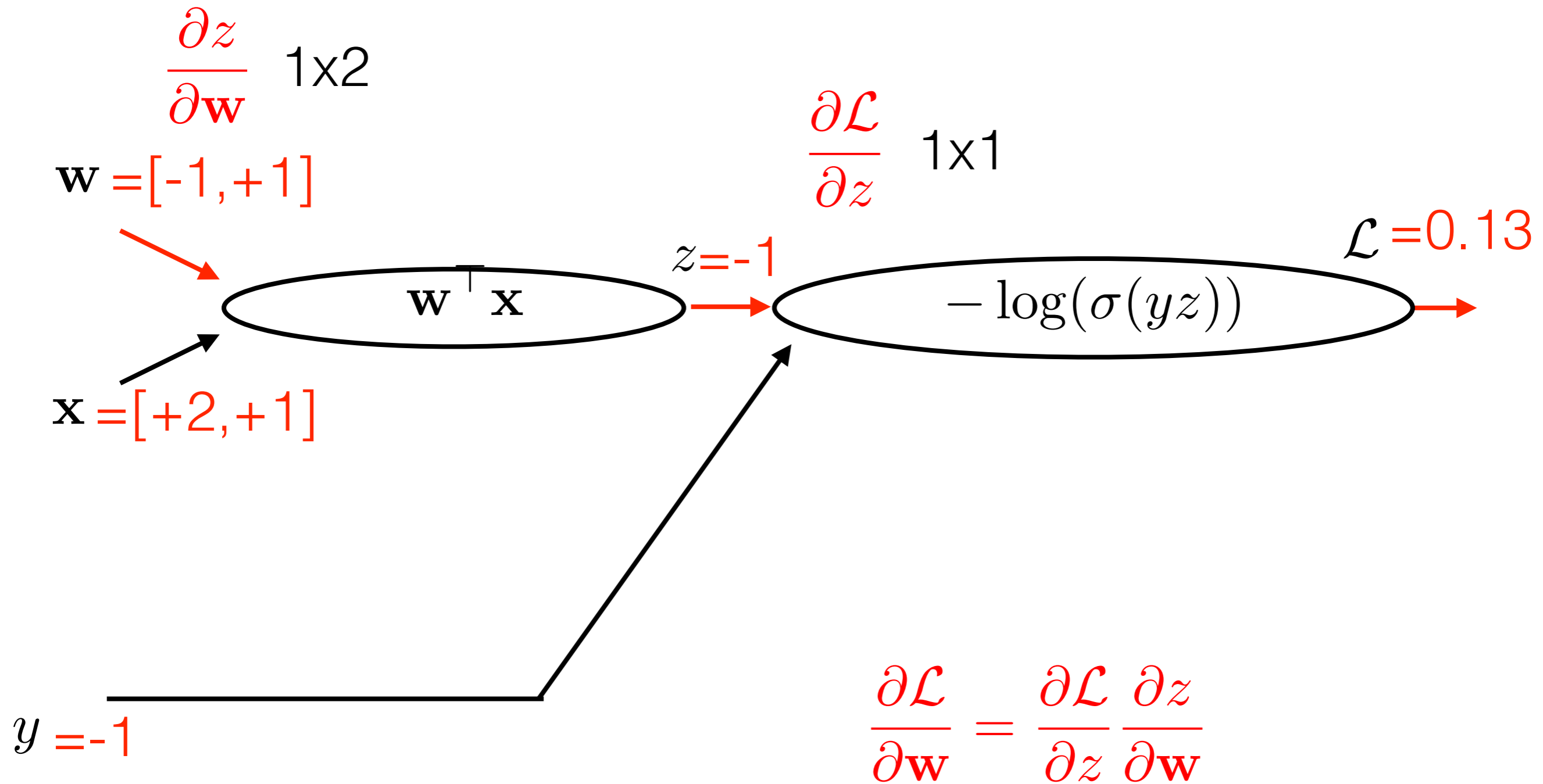
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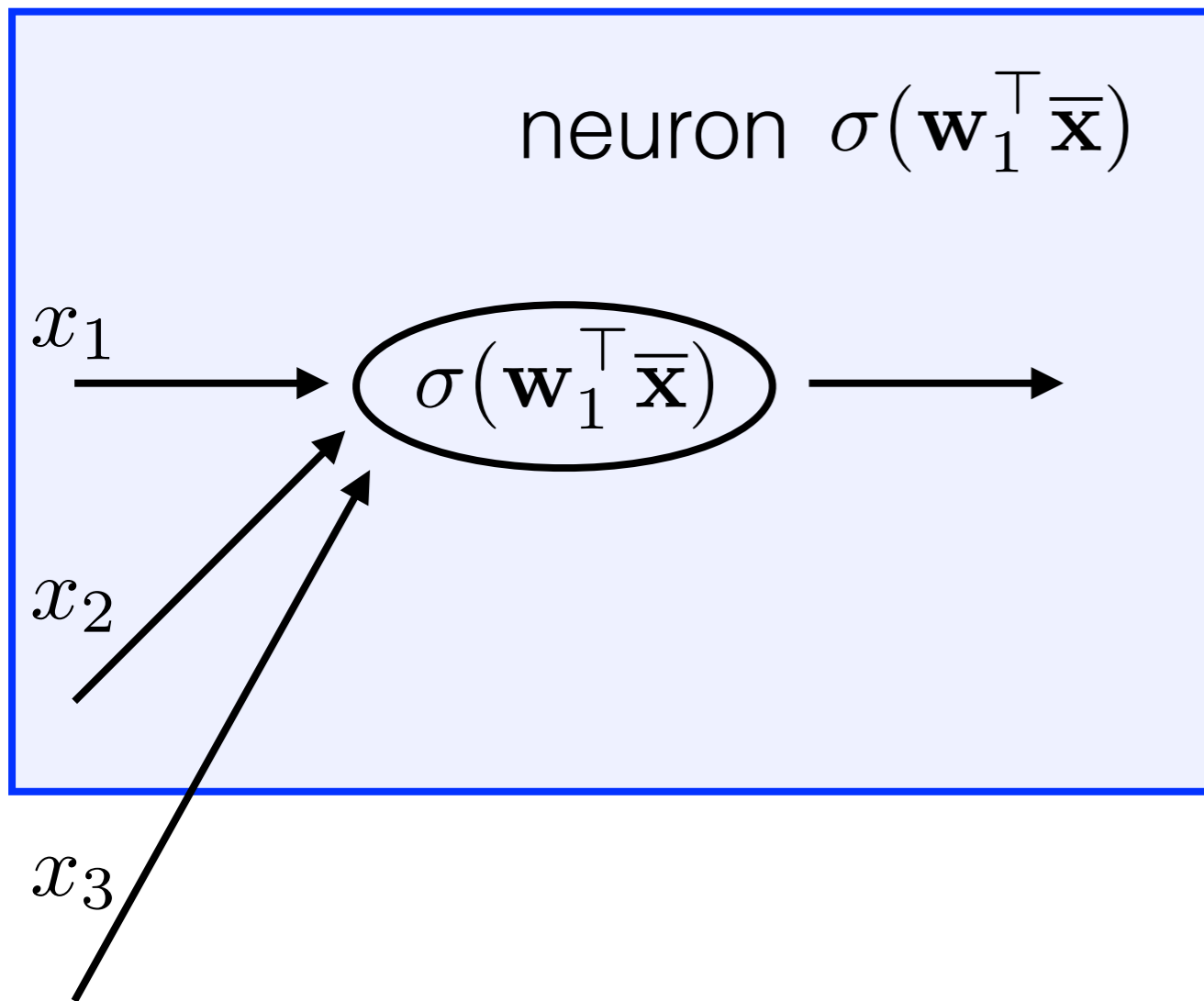
Backprop in vector representation



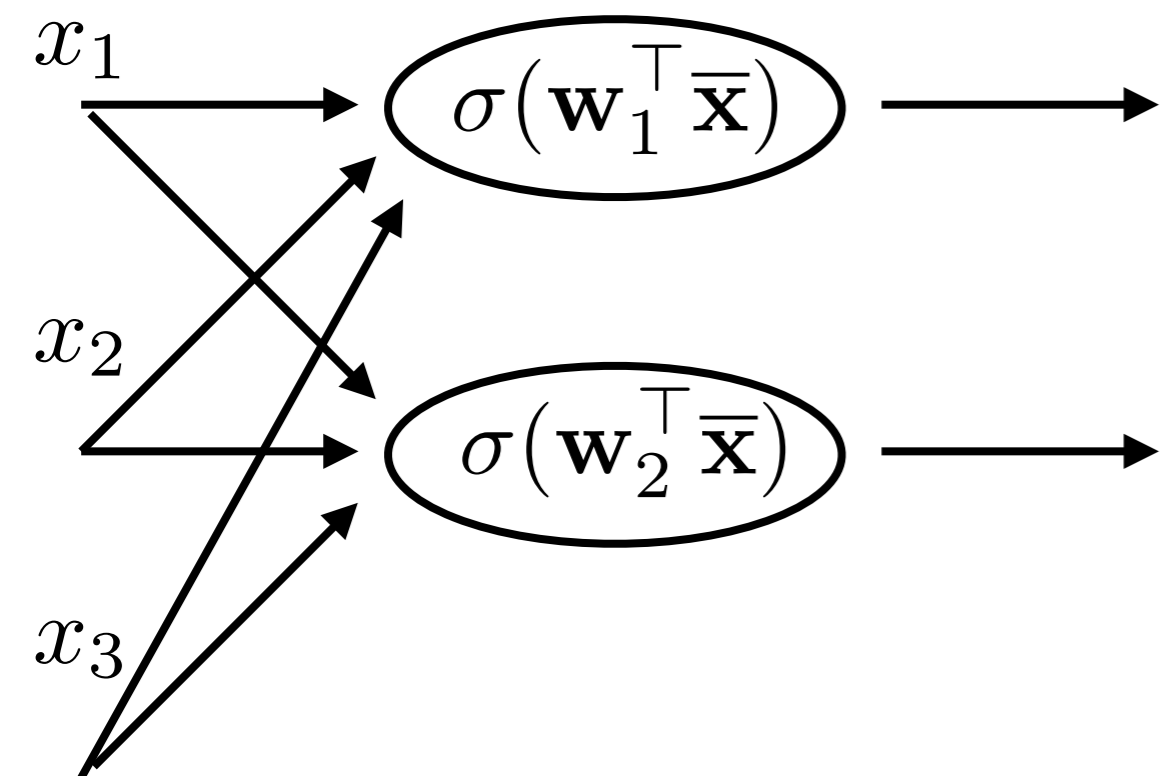
Learning from multiple training samples means summing up the gradient over all samples



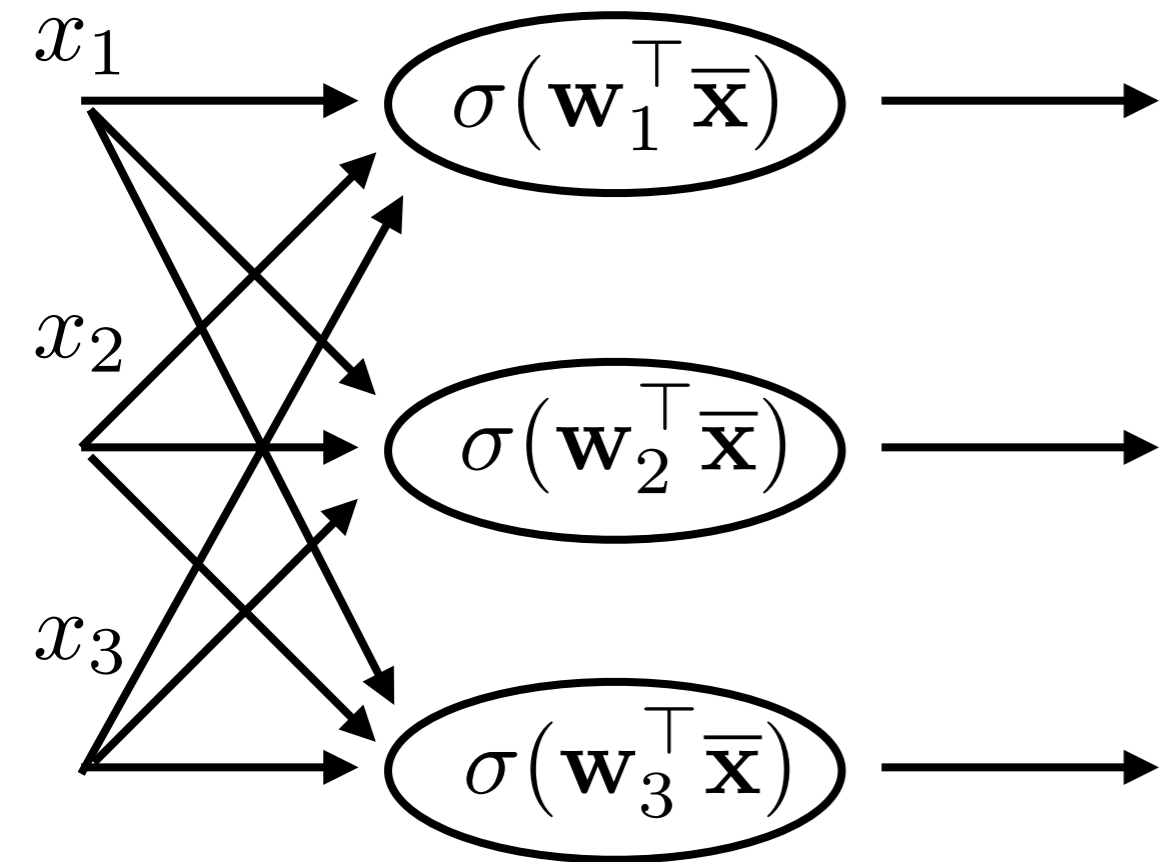
Fully connected neural network



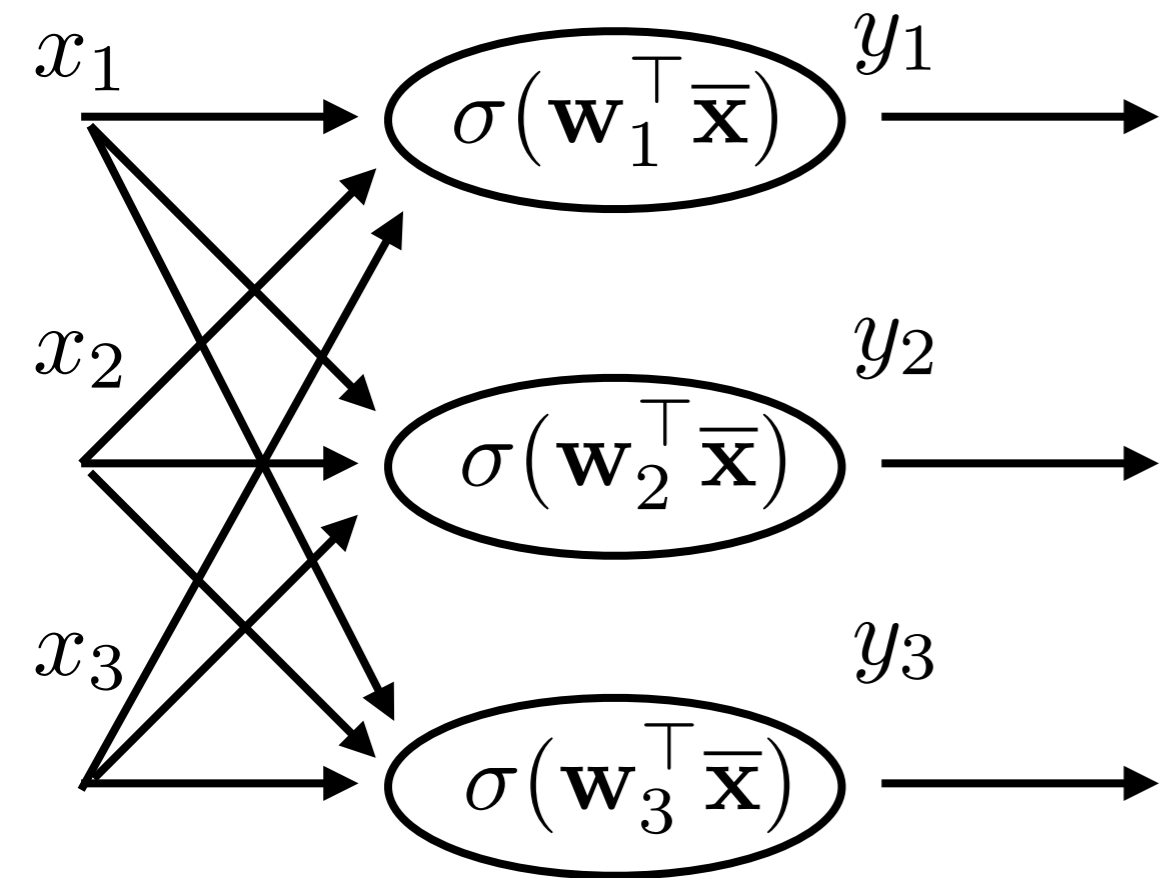
Fully connected neural network



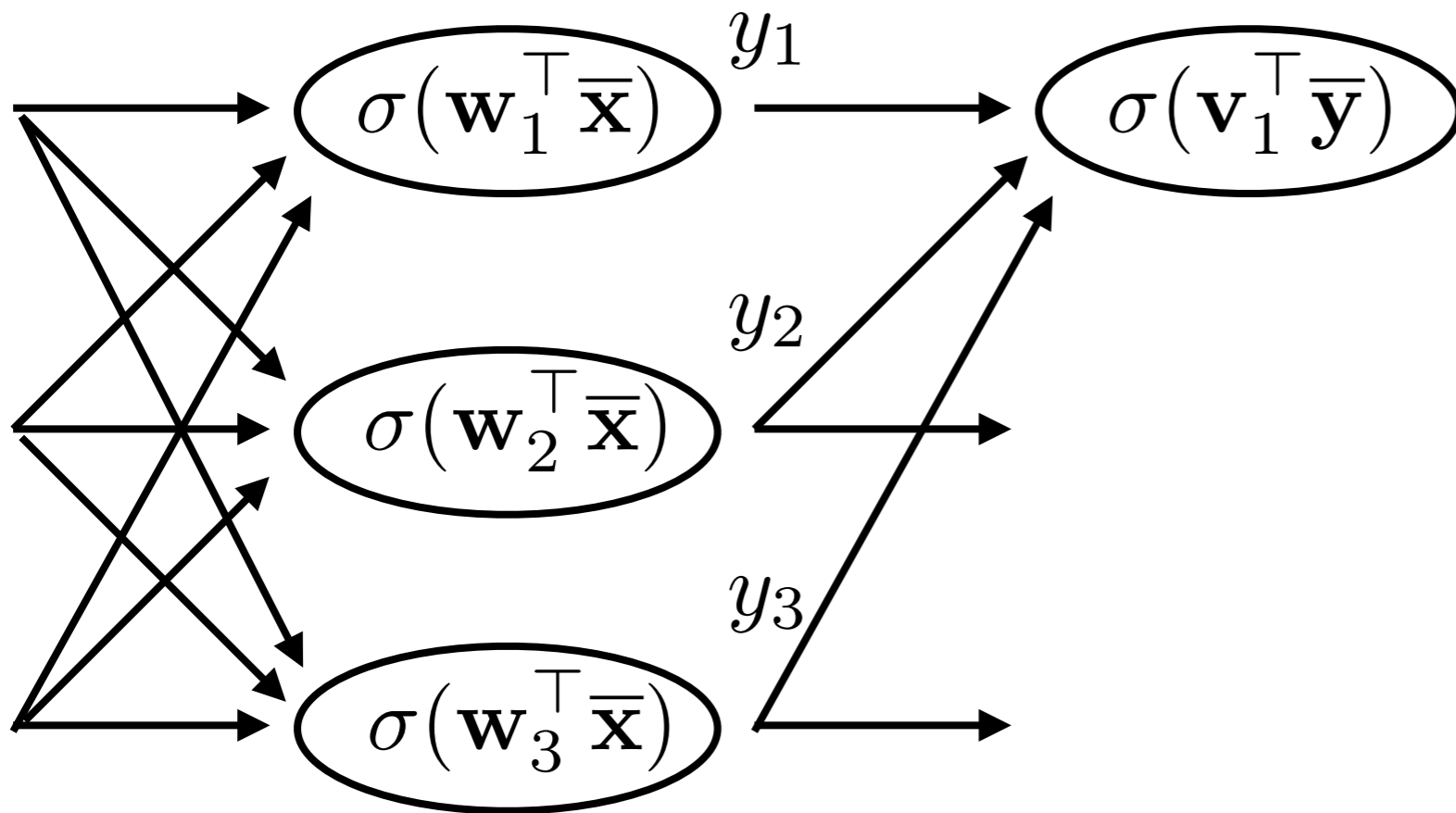
Fully connected neural network



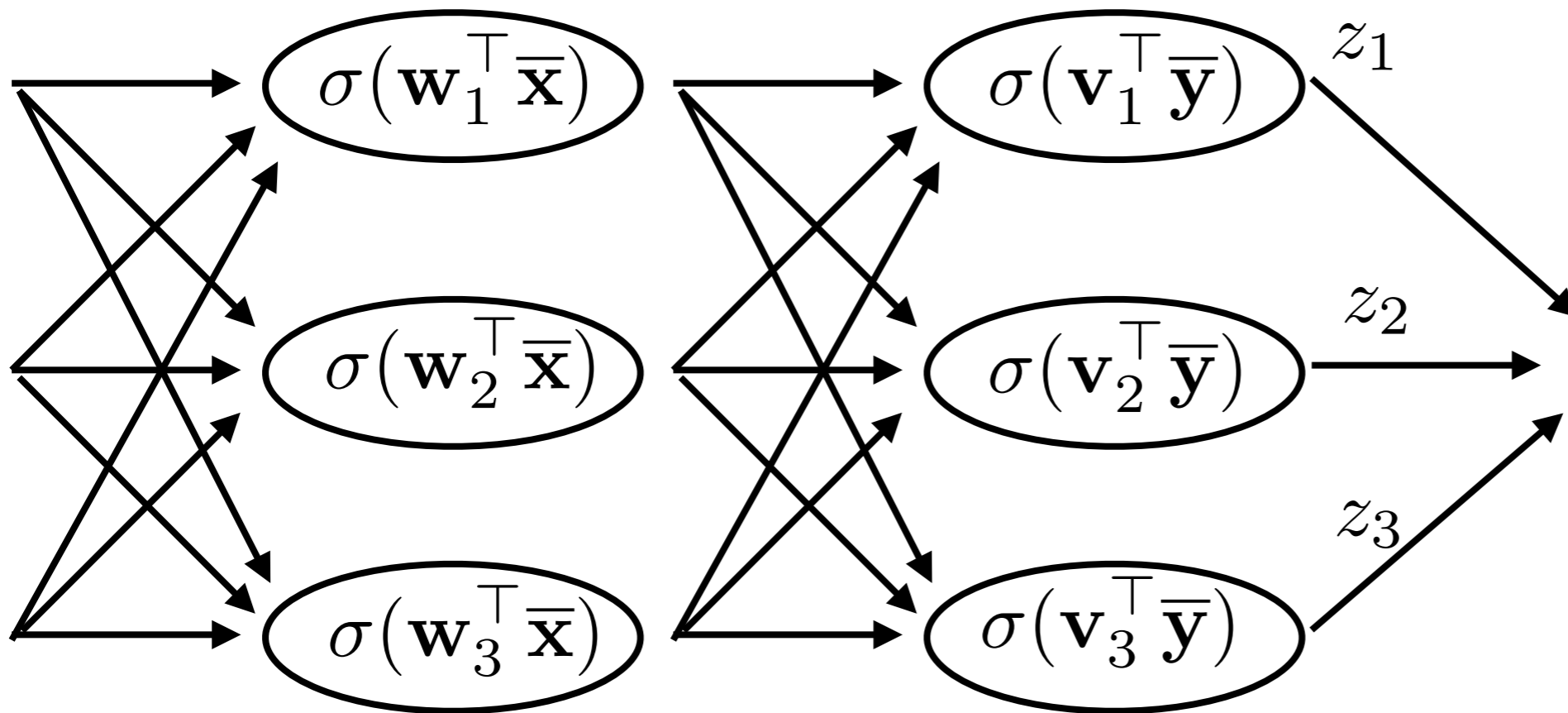
Fully connected neural network



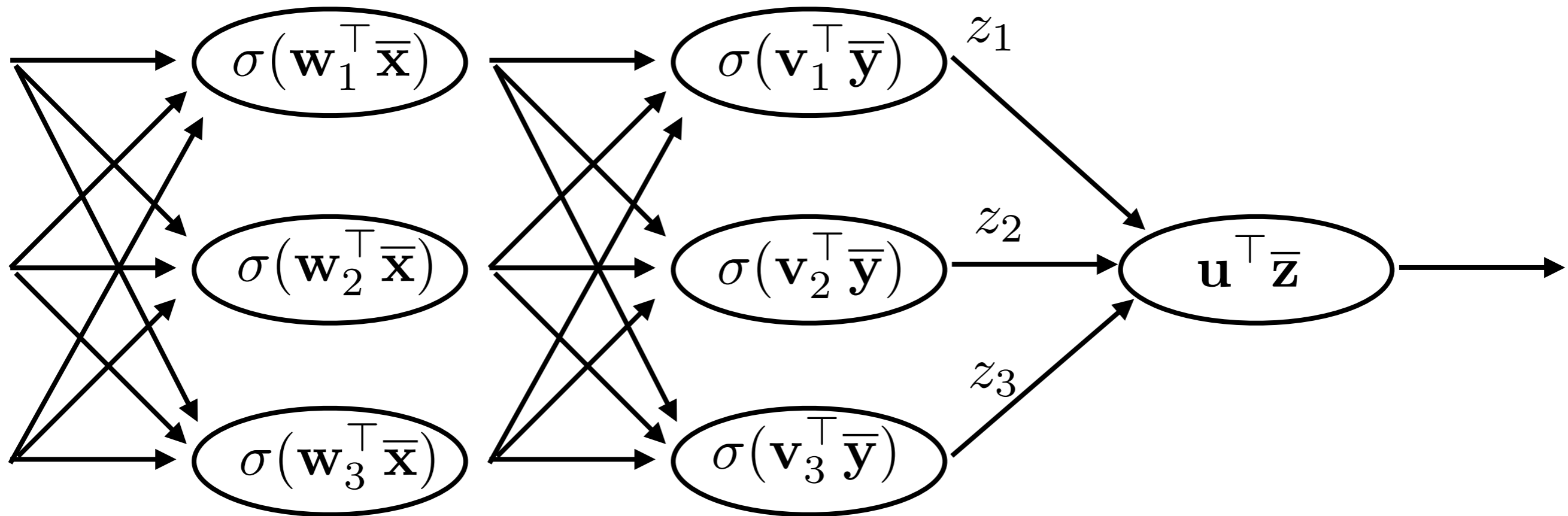
Fully connected neural network



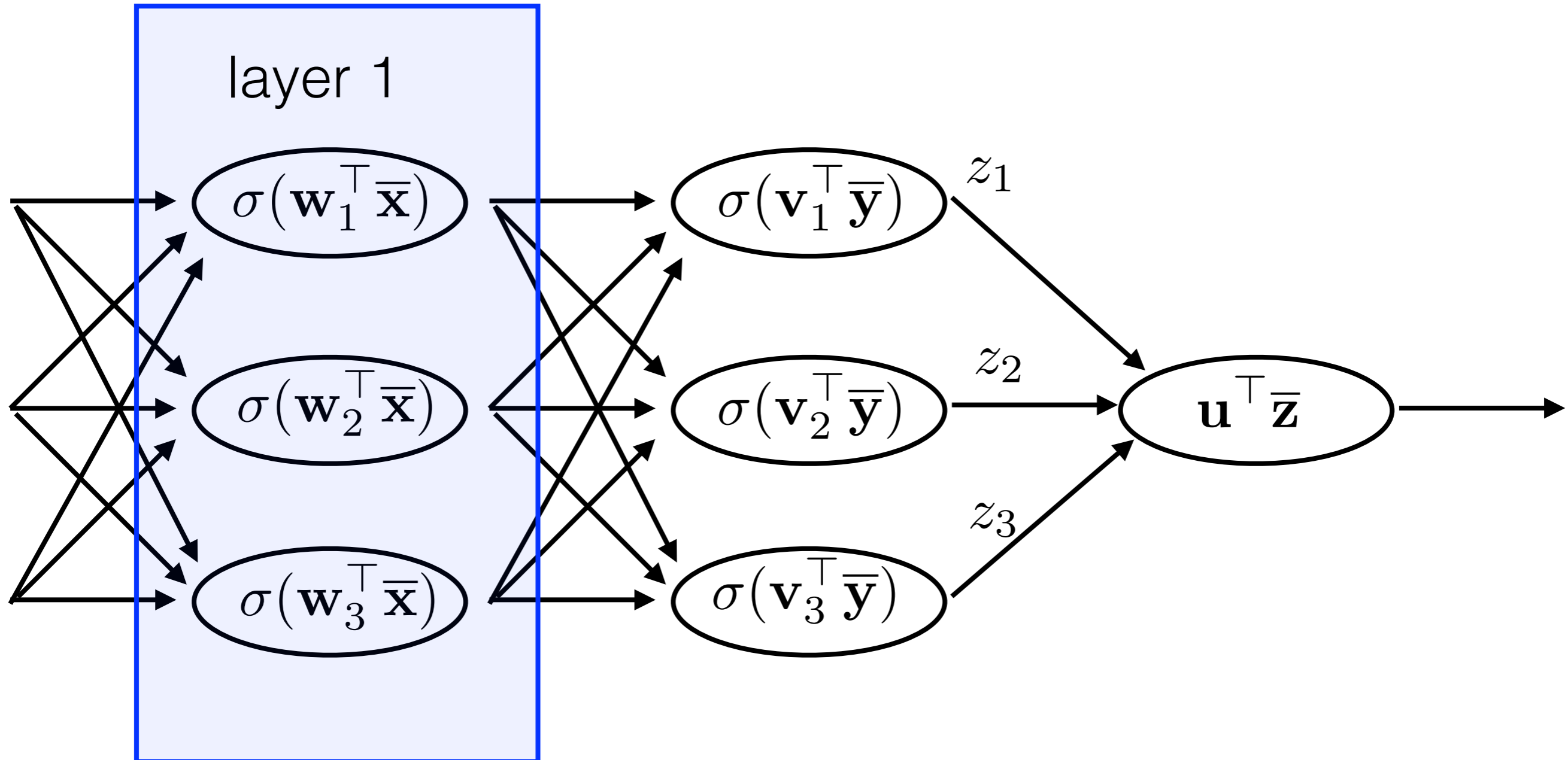
Fully connected neural network



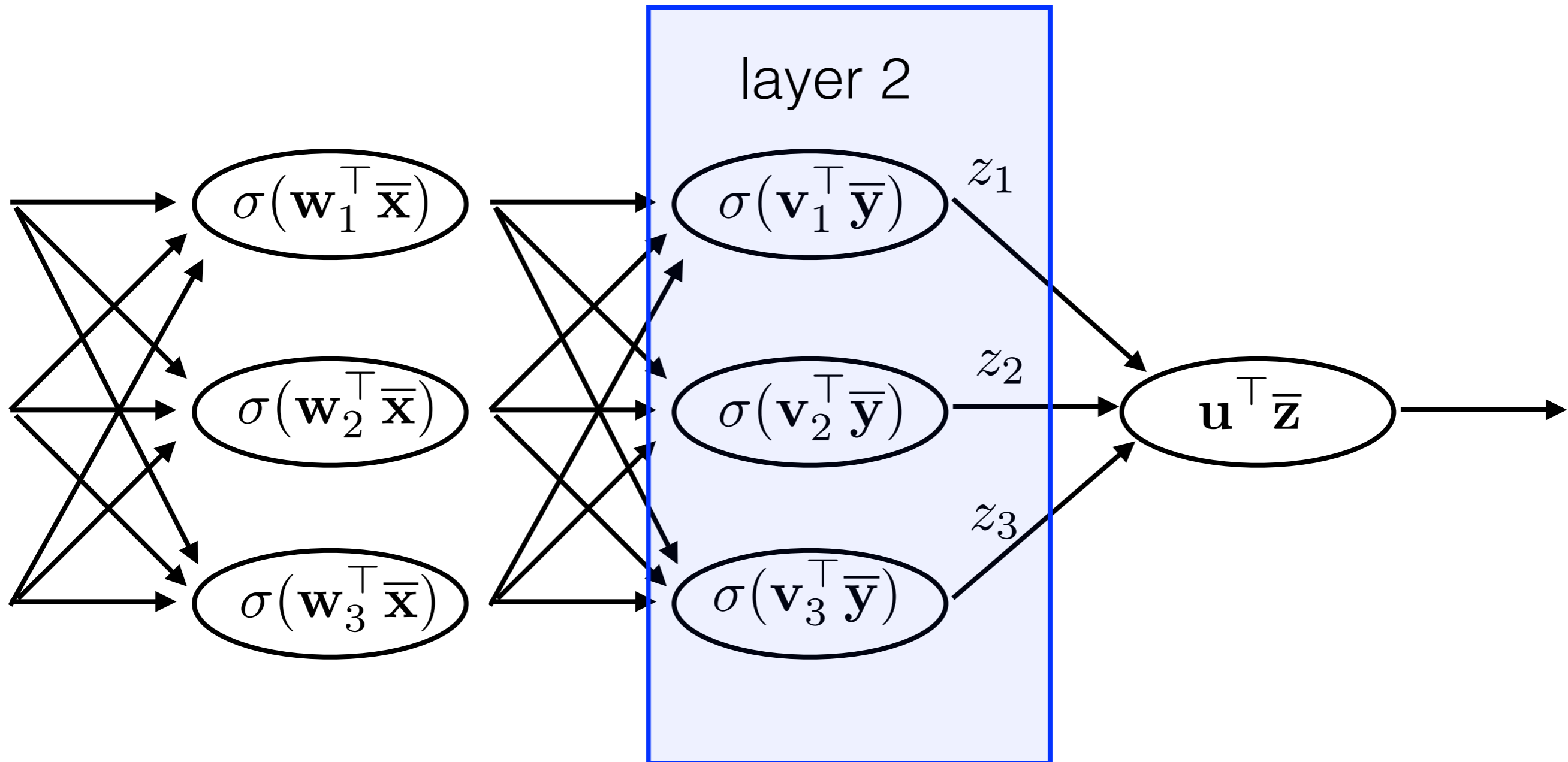
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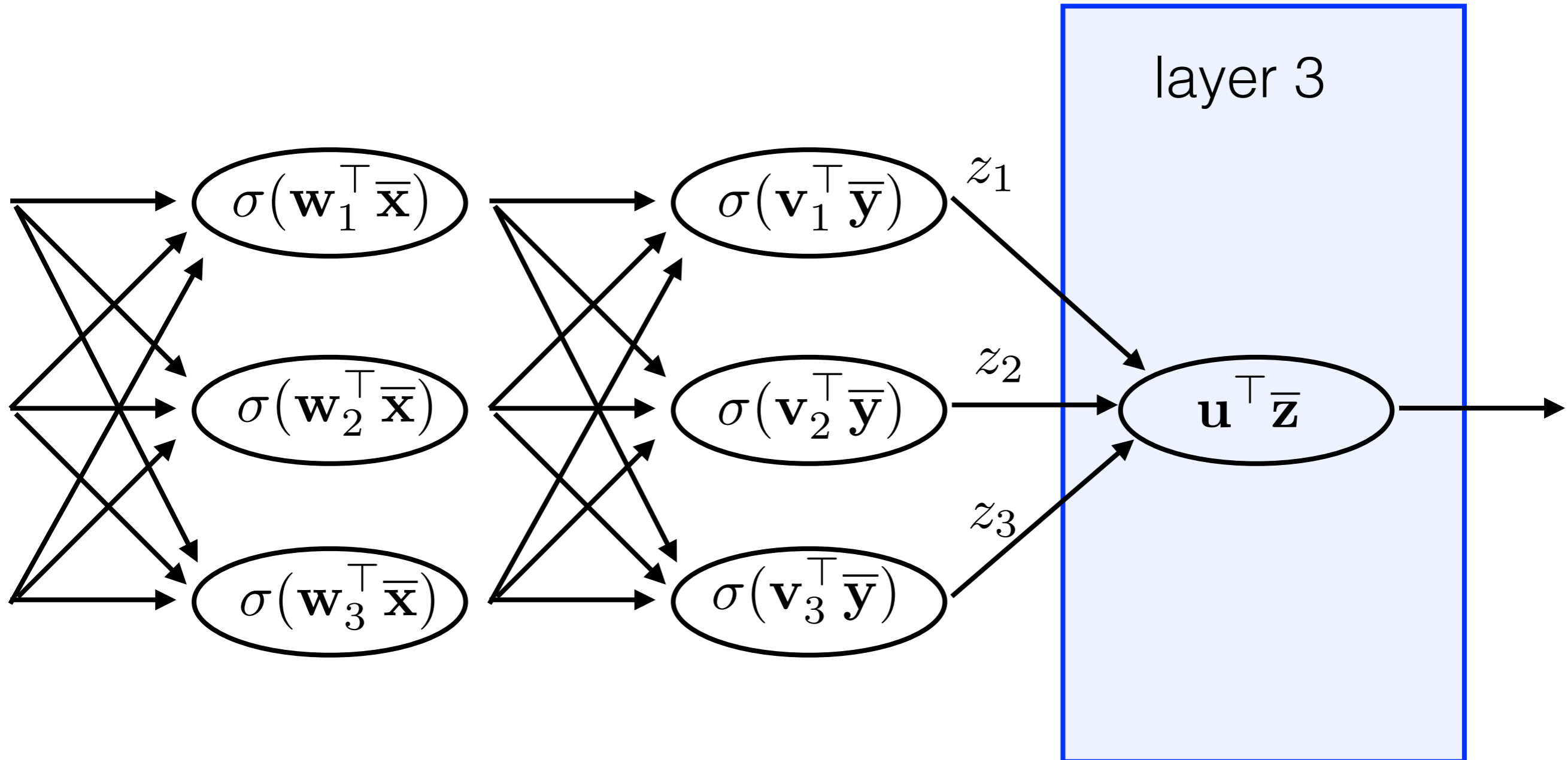
Fully connected neural network



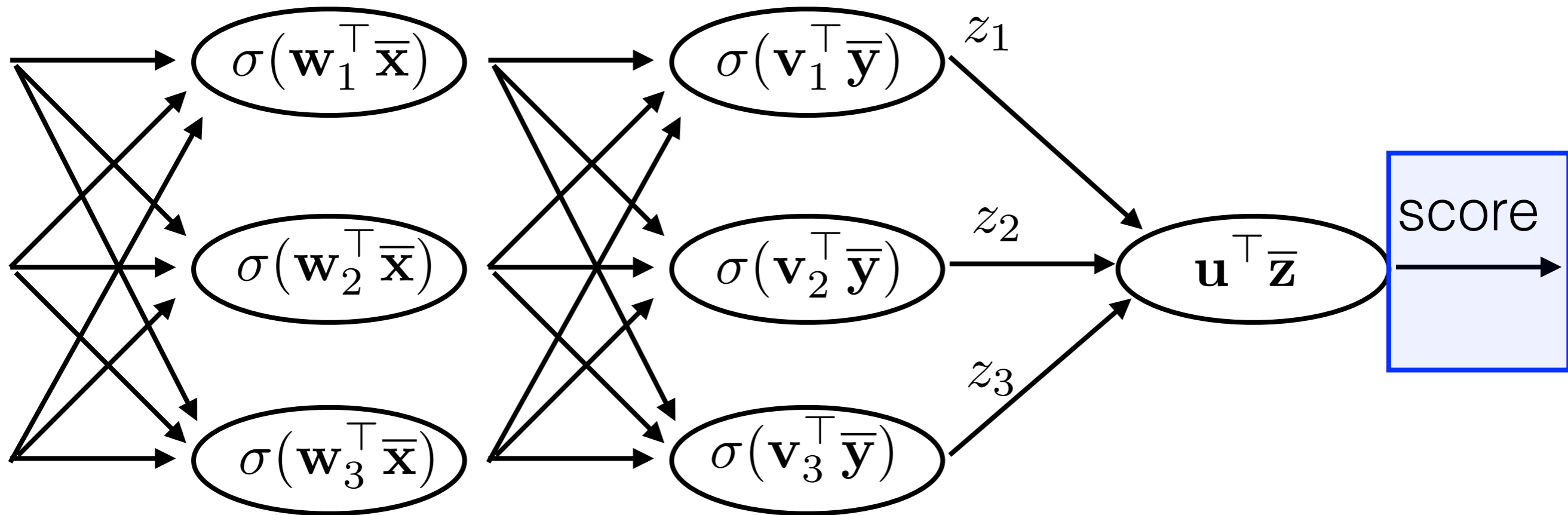
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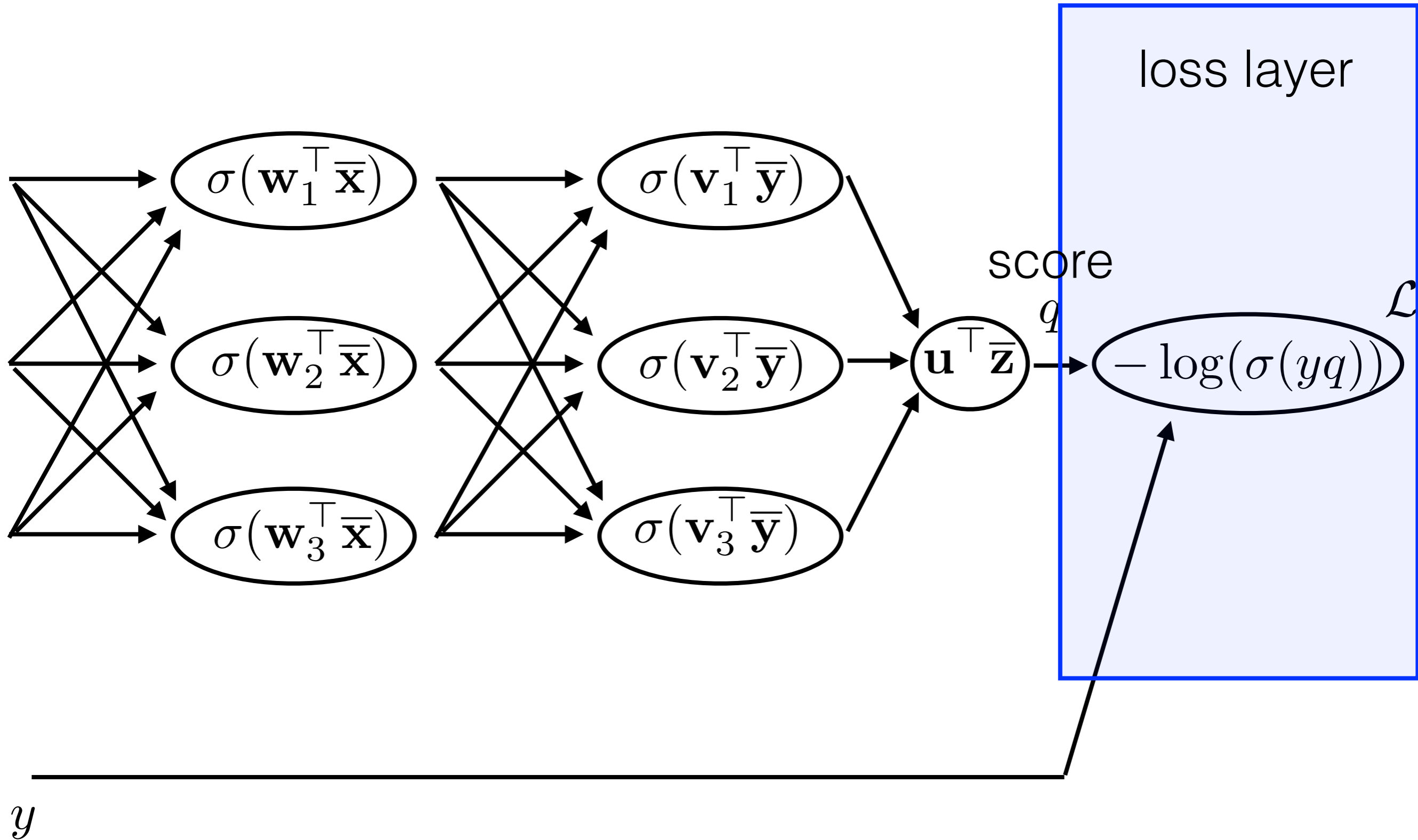
Fully connected neural network



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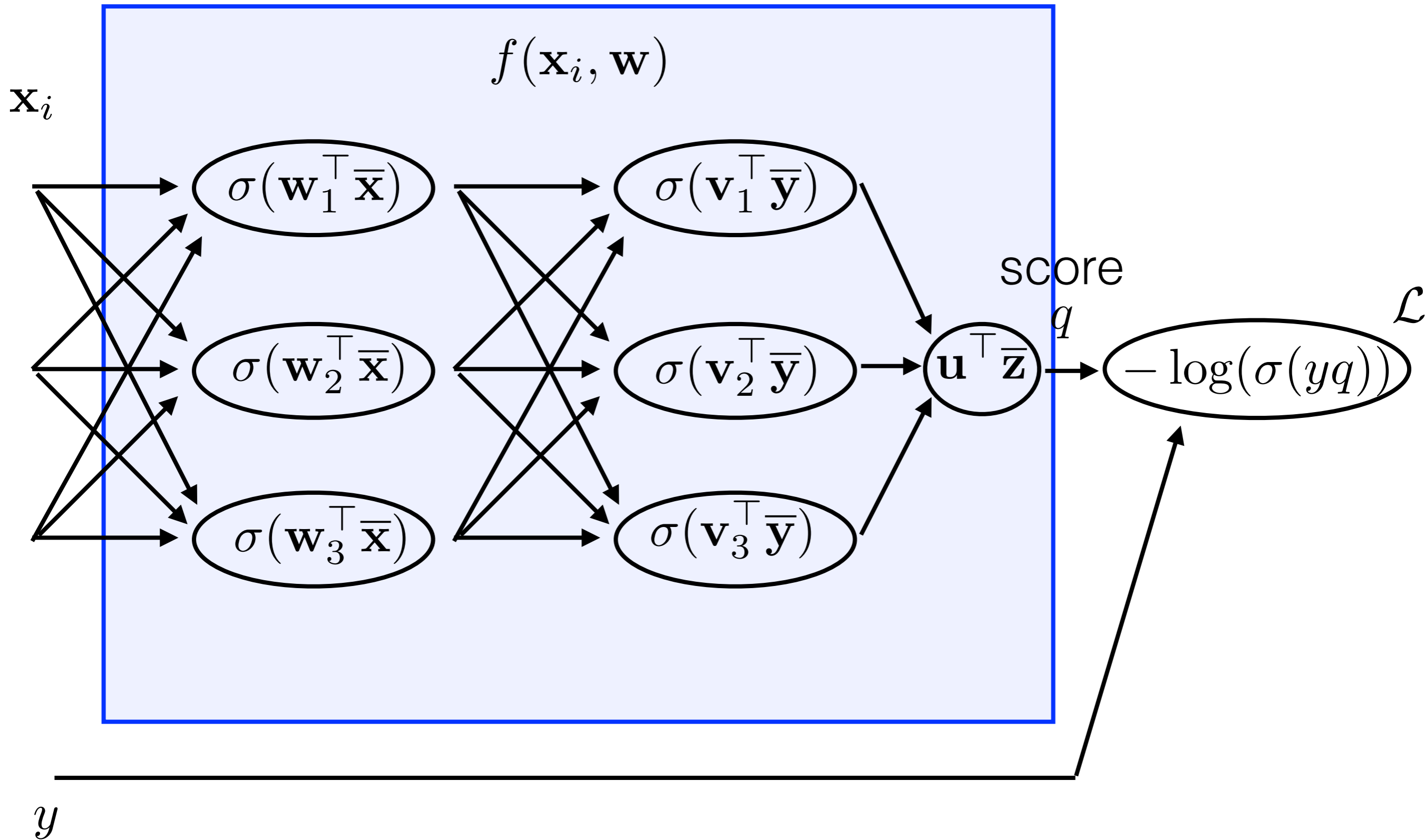
Fully connected neural network



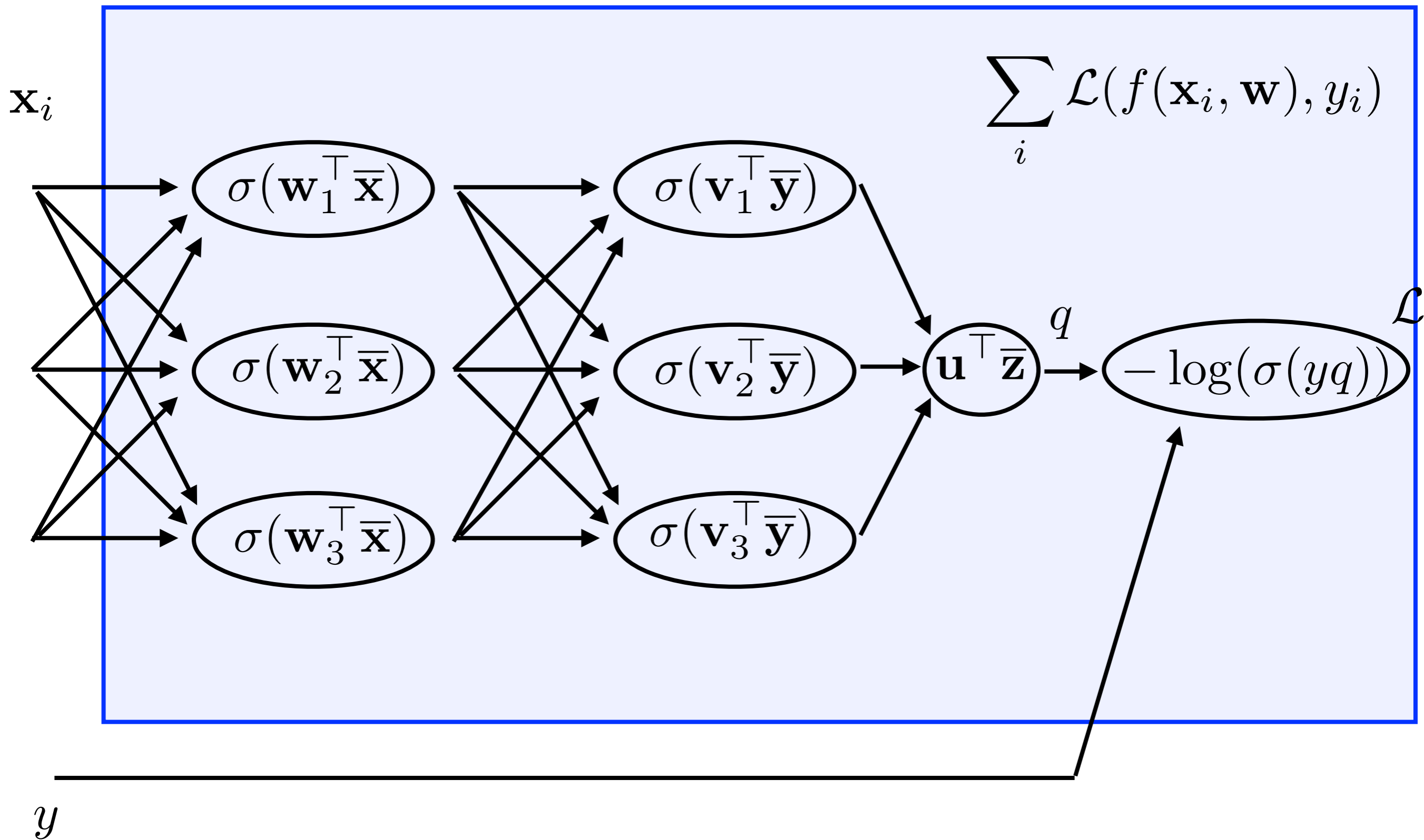
y



Fully connected neural network



Fully connected neural network



Learning of fully connected neural network

1. Estimate gradient

$$\sum_i \frac{\partial \mathcal{L}(f(\mathbf{x}_i, \mathbf{w}), y_i)}{\partial \mathbf{w}}$$

2. Update weights:

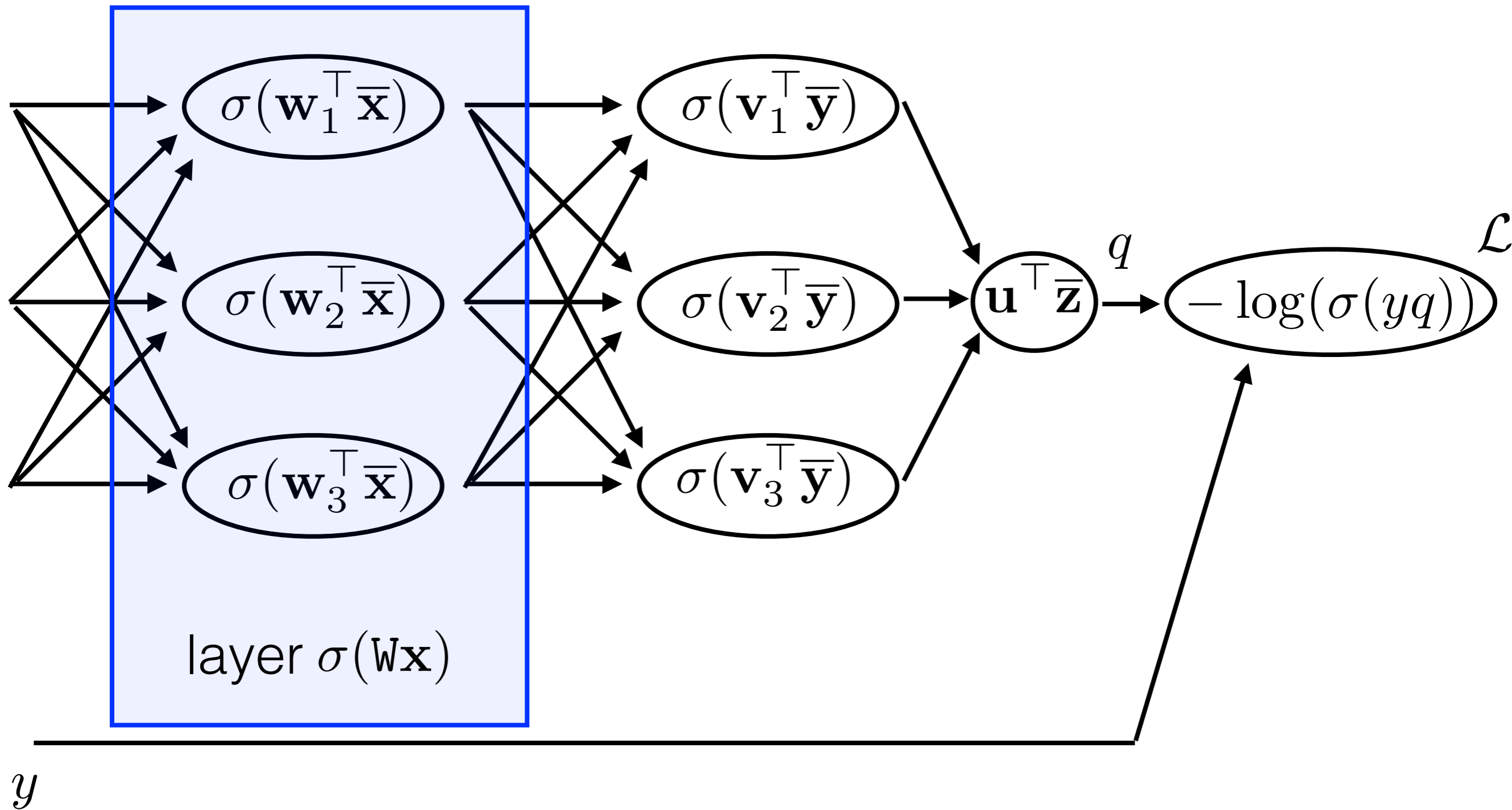
$$\mathbf{w} = \mathbf{w} - \alpha \sum_i \frac{\partial \mathcal{L}(f(\mathbf{x}_i, \mathbf{w}), y_i)}{\partial \mathbf{w}}$$

3. Optionally update learning rate α

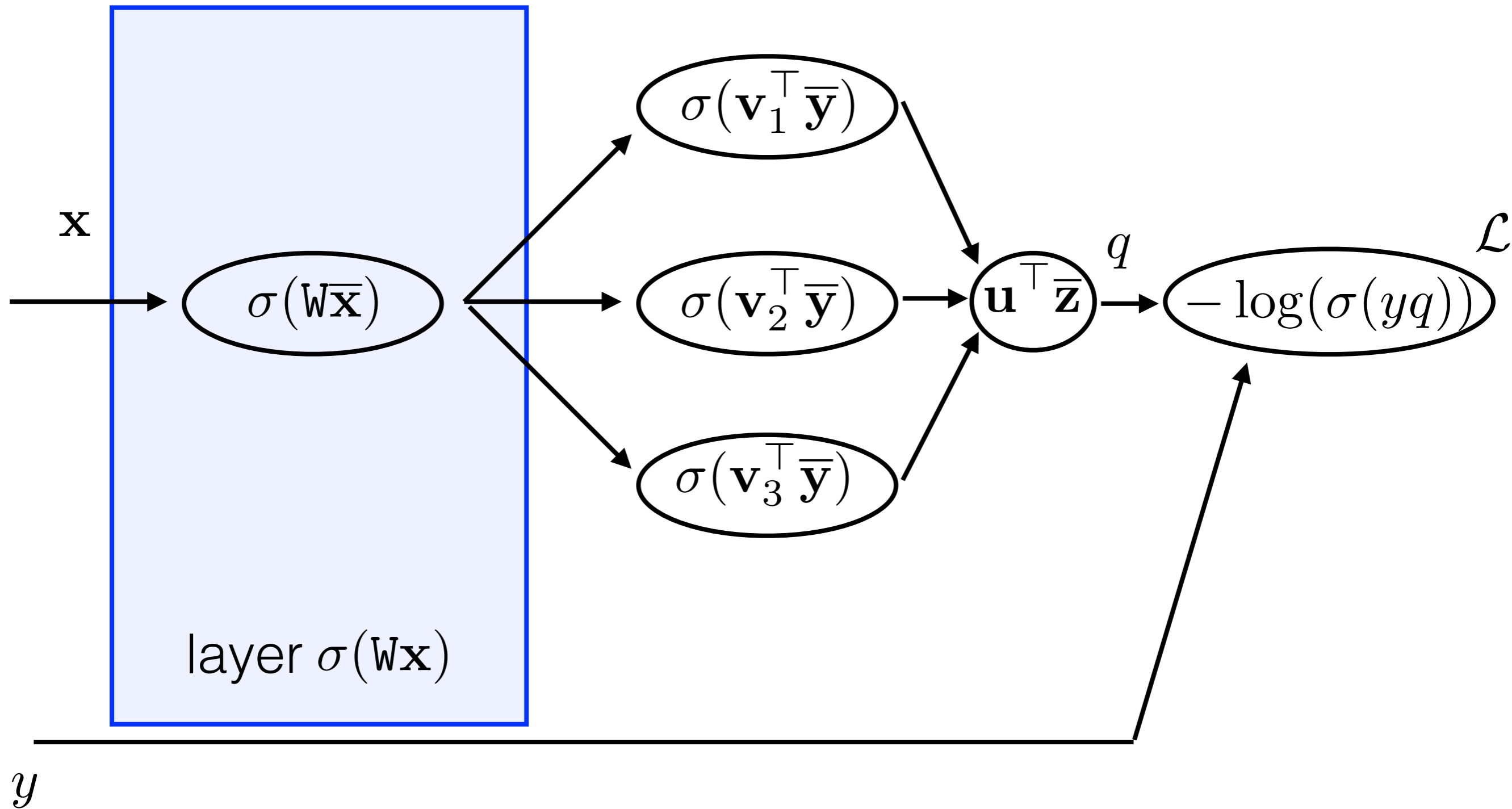
4. Repeat until convergence



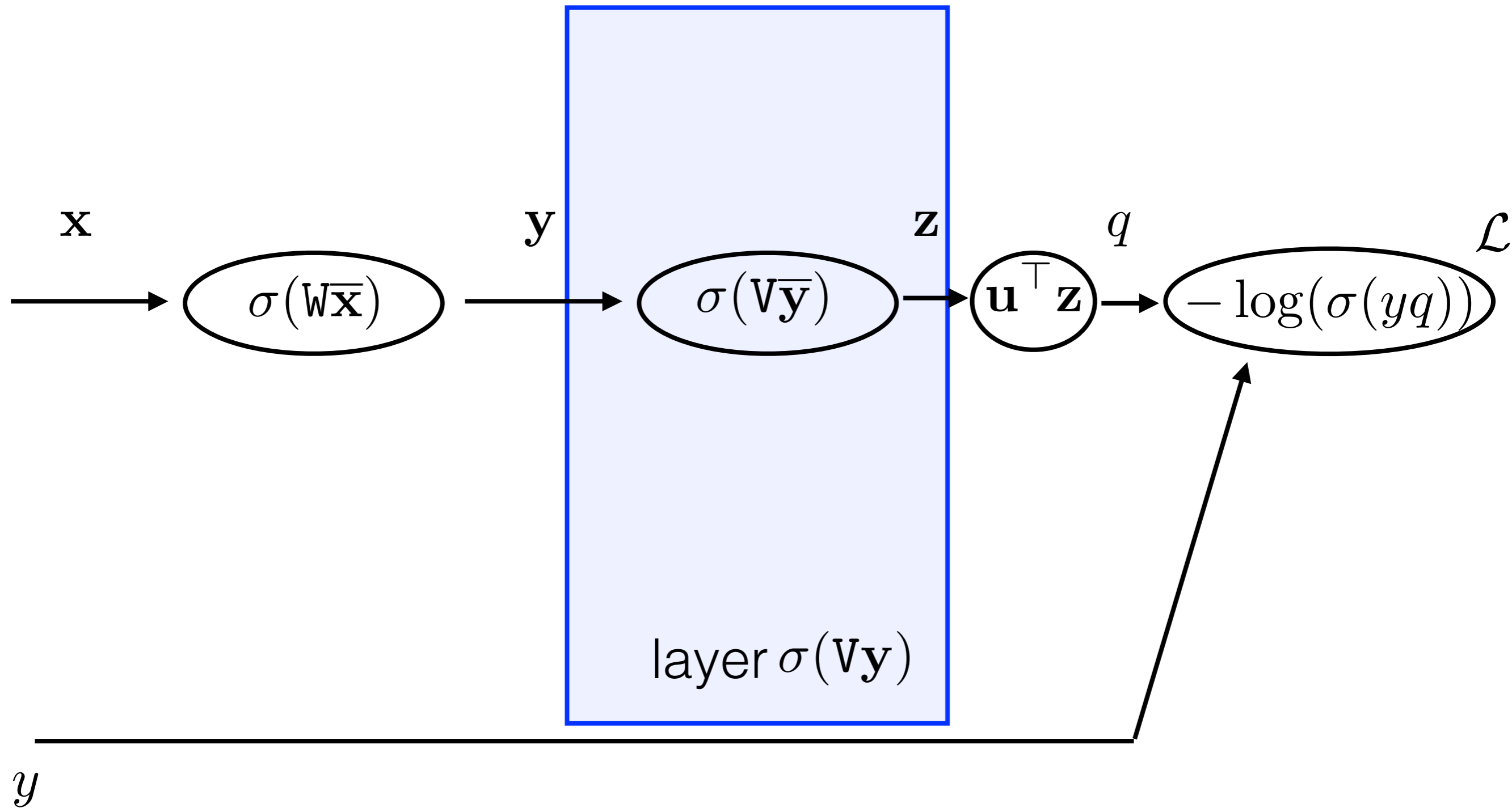
Learning of fully connected neural network



Learning of fully connected neural network



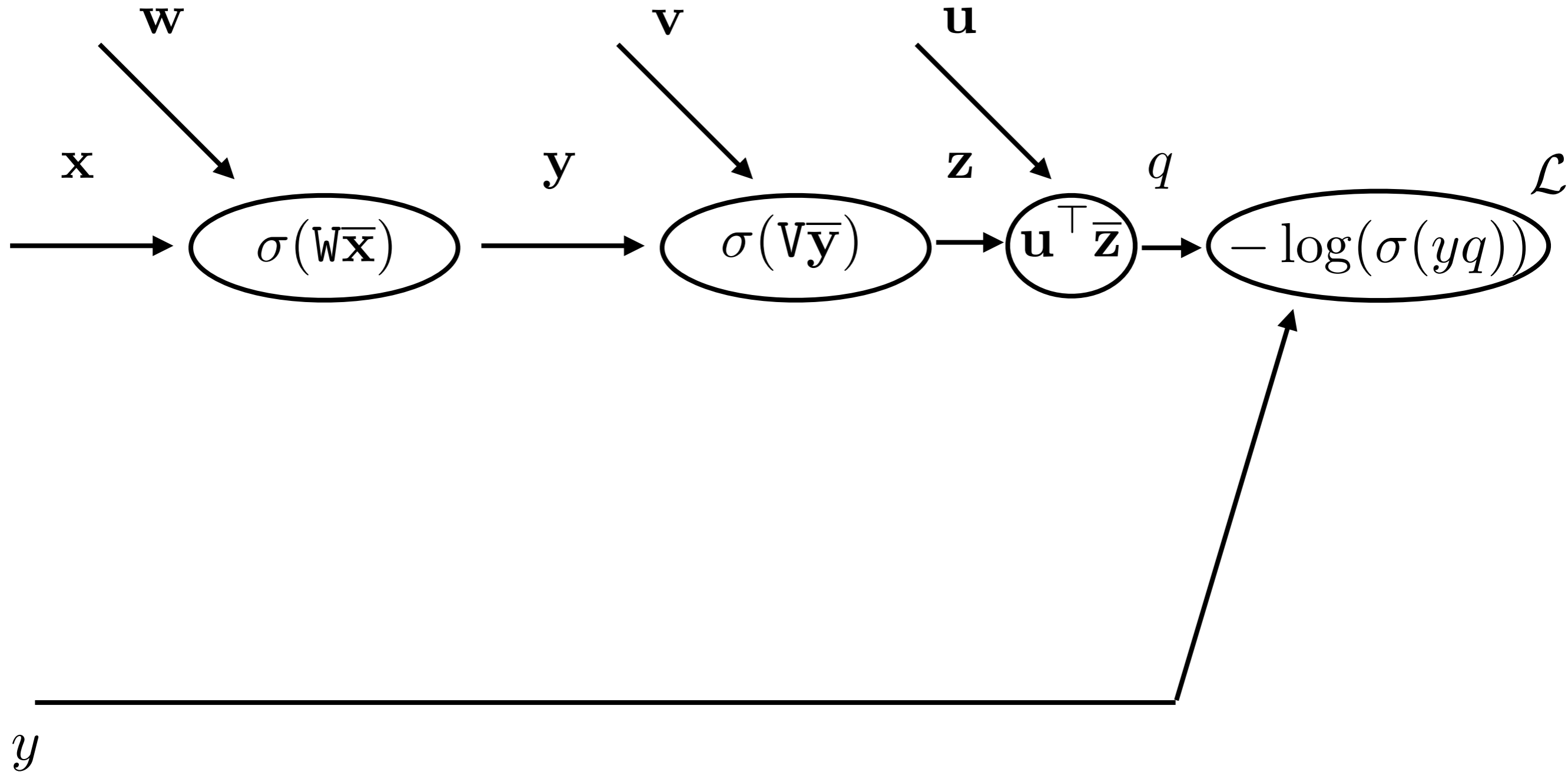
Learning of fully connected neural network



Learning of fully connected neural network

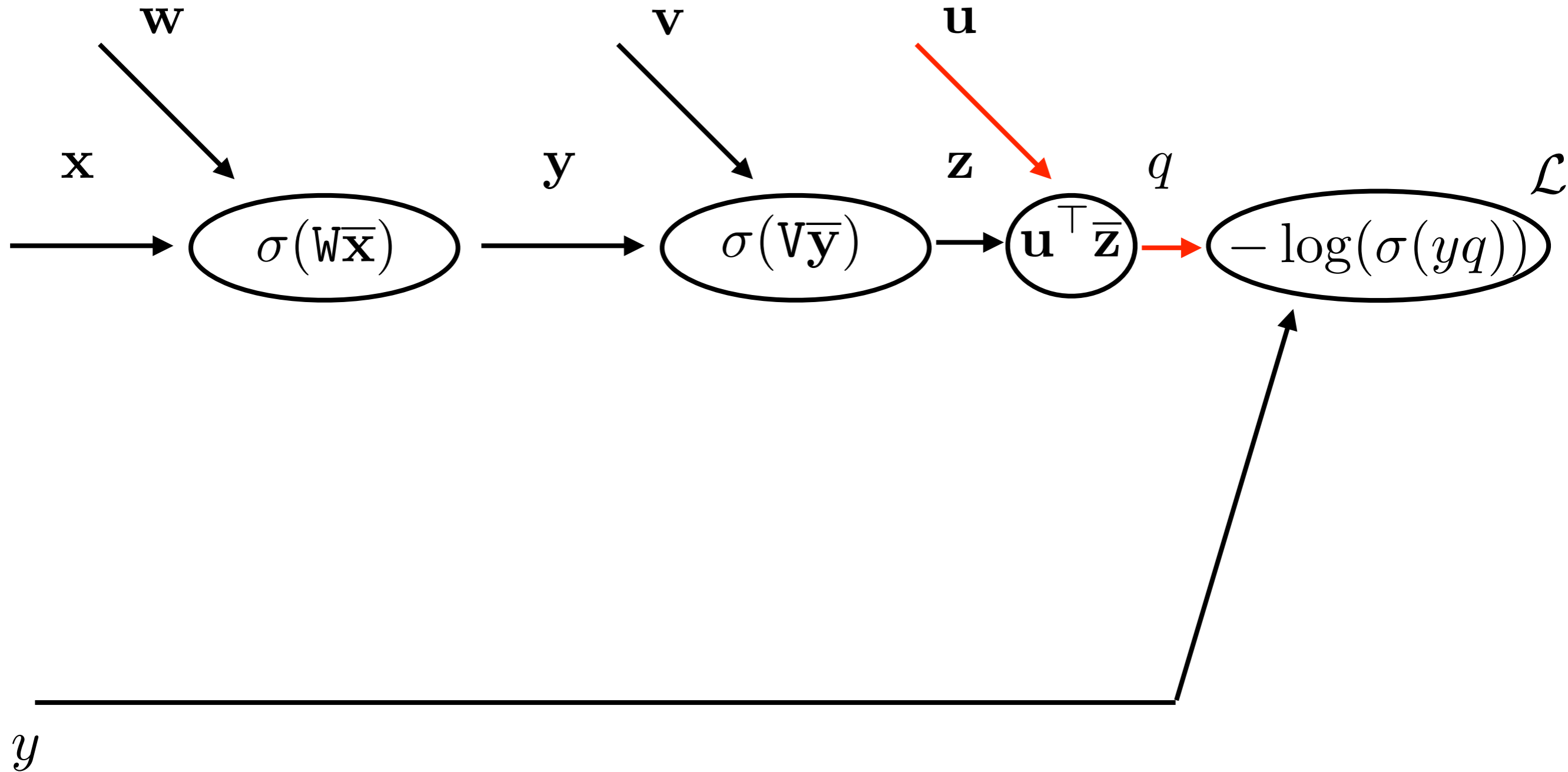
$$\mathbf{w} = \text{vec}(W)$$

$$\mathbf{v} = \text{vec}(V)$$



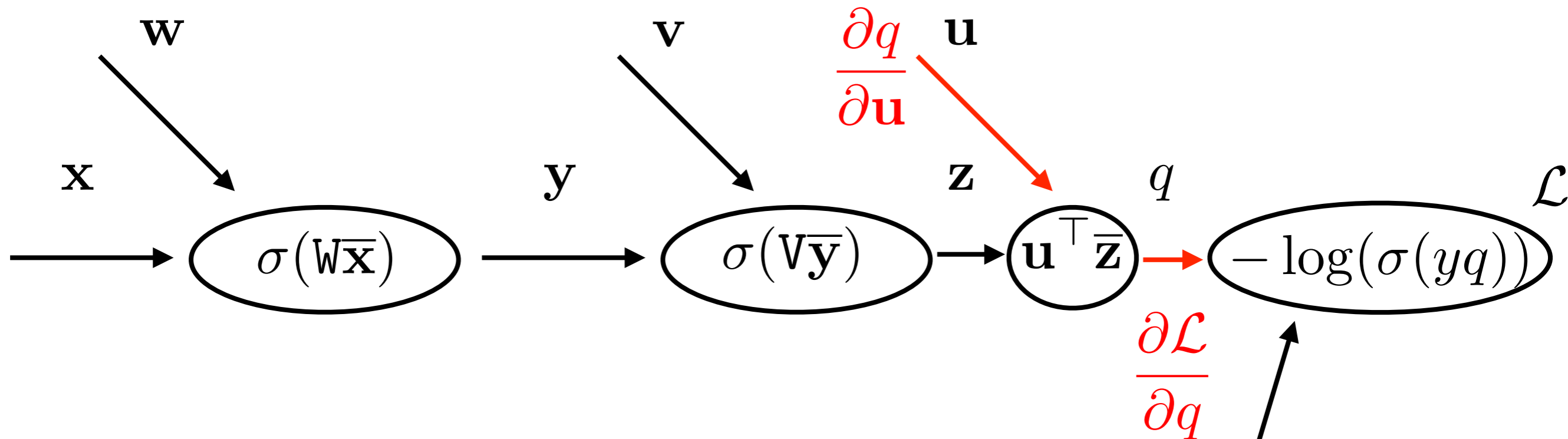
Learning of fully connected neural network

Derivative wrt \mathbf{u} : $\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = ?$



Learning of fully connected neural network

Derivative wrt \mathbf{u} : $\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{u}}$

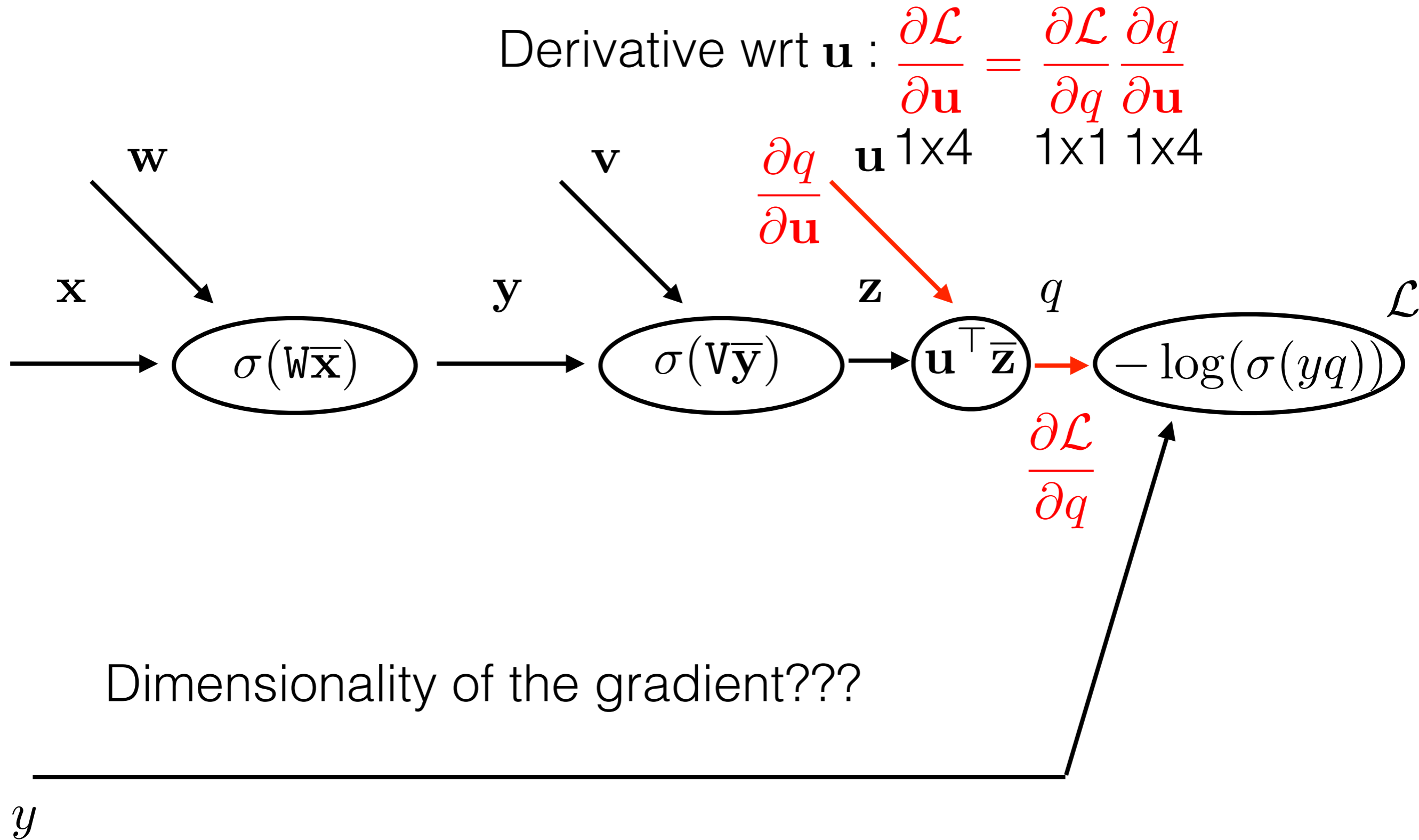


Dimensionality of the gradient???

y

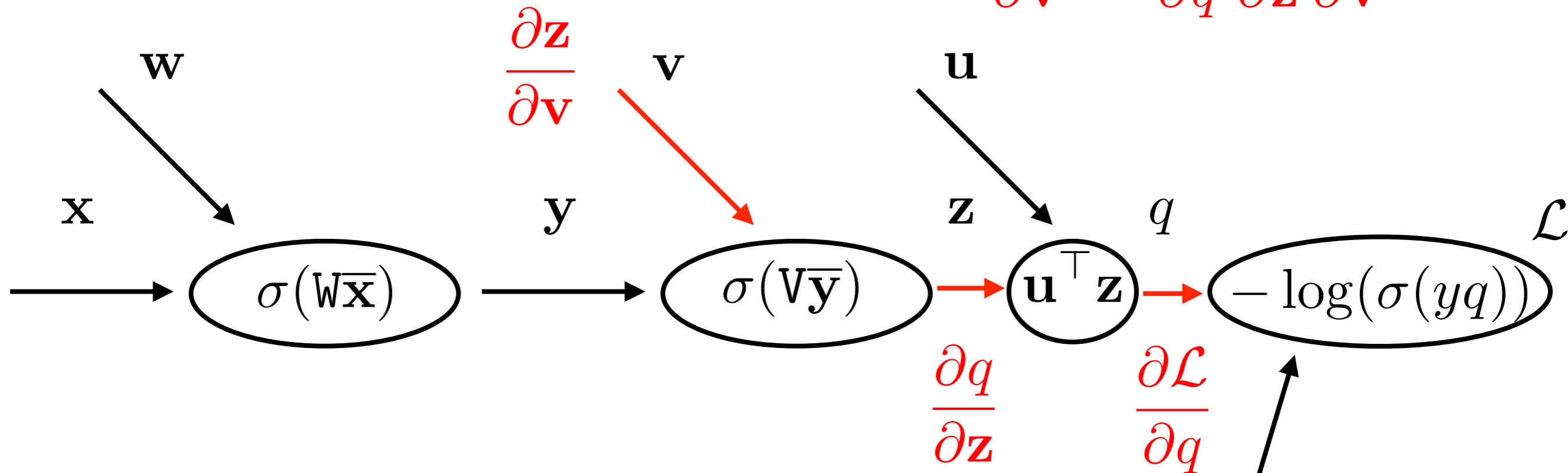


Learning of fully connected neural network



Learning of fully connected neural network

Derivative wrt \mathbf{v} : $\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}}$



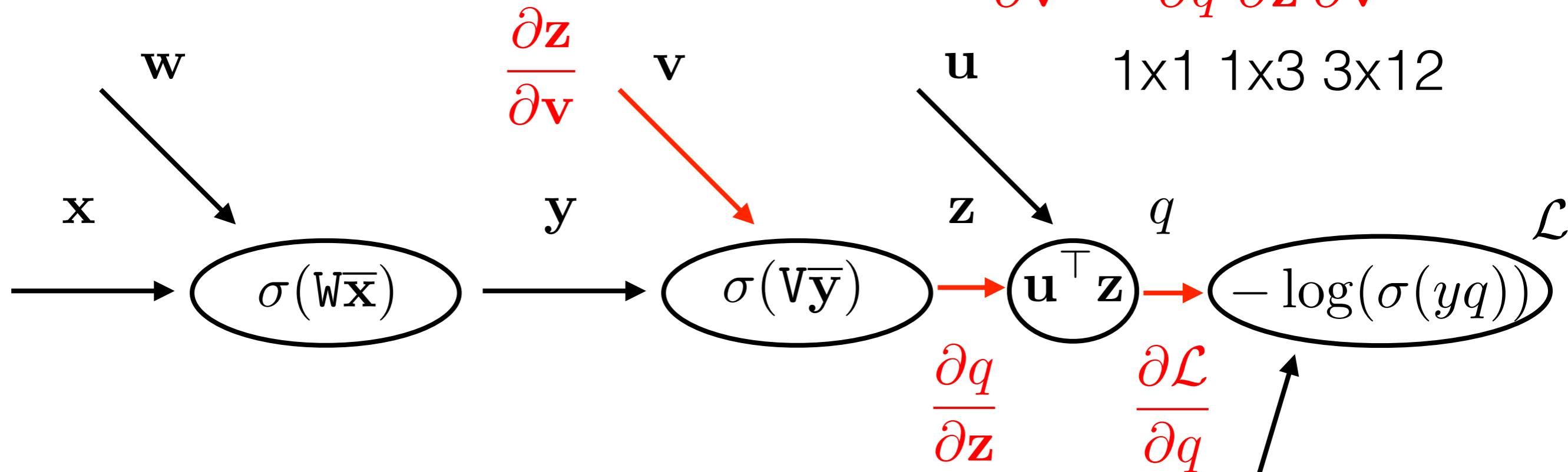
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Learning of fully connected neural network

Derivative wrt \mathbf{v} : $\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}}$



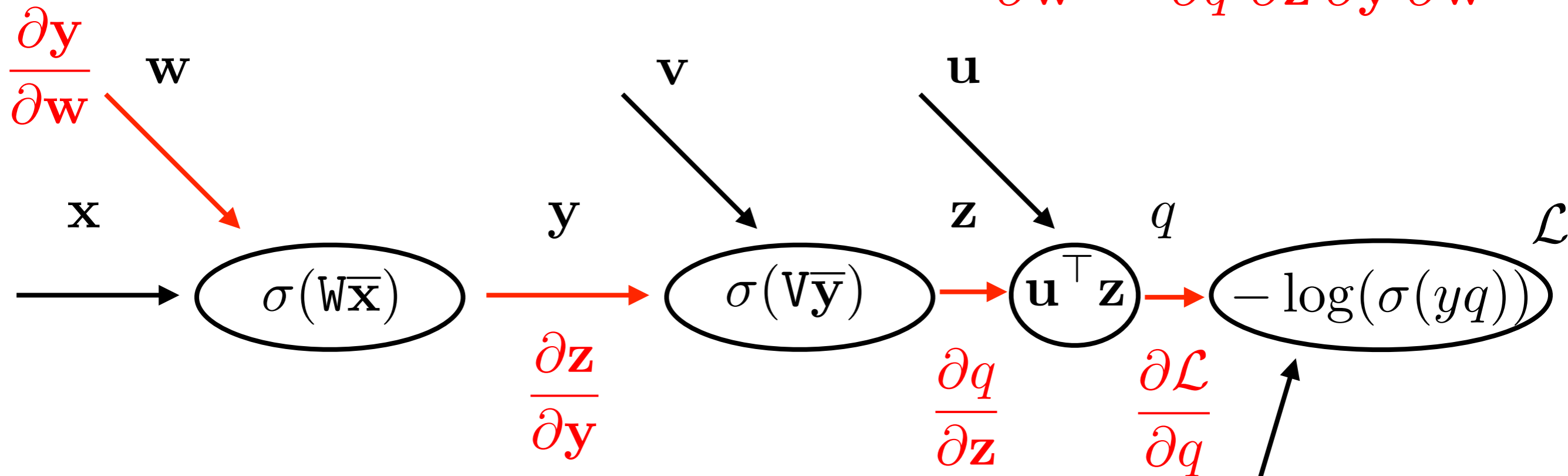
Dimensionality of the gradient???

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Learning of fully connected neural network

$$\text{Derivative wrt } \mathbf{w} : \frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}}$$



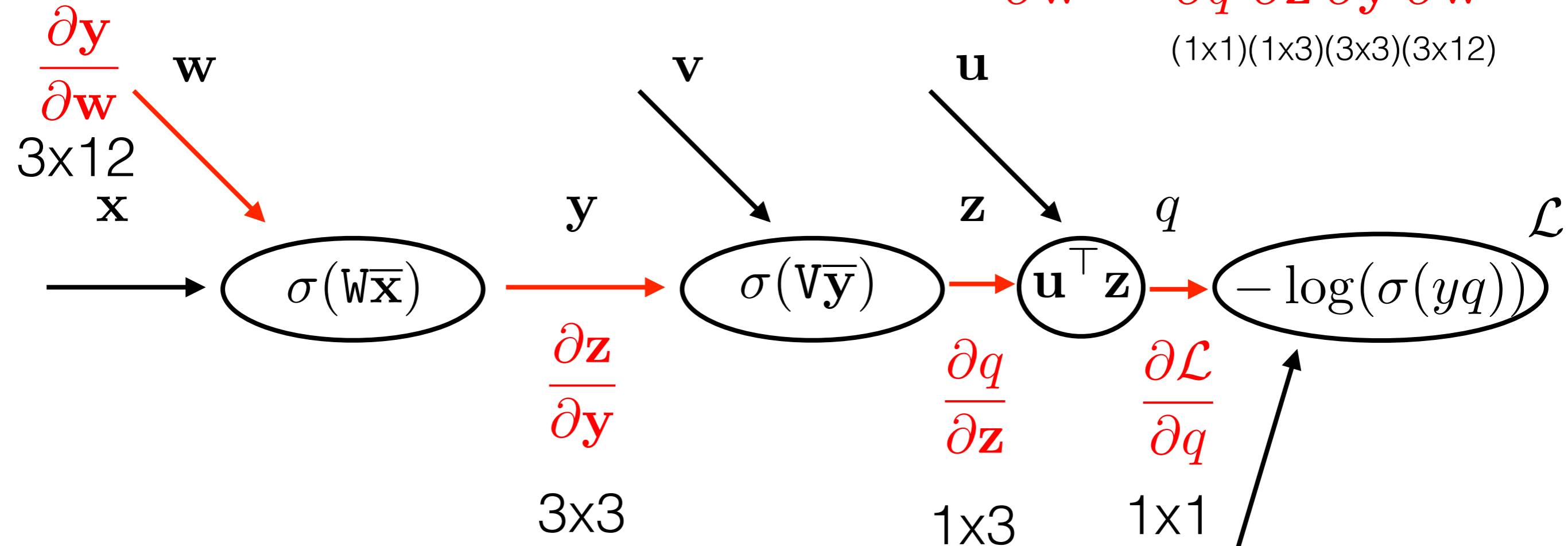
Dimensionality of the gradient???

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Learning of fully connected neural network

Derivative wrt \mathbf{w} : $\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}}$
 (1x1)(1x3)(3x3)(3x12)



Dimensionality of the gradient???

y



Learning of fully connected neural network

1. Estimate all required local gradients
2. Update weights:

$$\frac{\partial \mathcal{L}}{\partial \mathbf{u}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{u}} \quad \mathbf{u} = \mathbf{u} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{u}} \right]^\top$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{v}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{v}} \quad \mathbf{v} = \mathbf{v} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{v}} \right]^\top$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}} = \frac{\partial \mathcal{L}}{\partial q} \frac{\partial q}{\partial \mathbf{z}} \frac{\partial \mathbf{z}}{\partial \mathbf{y}} \frac{\partial \mathbf{y}}{\partial \mathbf{w}} \quad \mathbf{w} = \mathbf{w} - \alpha \left[\frac{\partial \mathcal{L}}{\partial \mathbf{w}} \right]^\top$$

3. Optionally update learning rate α
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Neural nets summary

- Neural net is a function created as concatenation of simpler functions (e.g. neurons or layers of neurons)
- Gradient optimization of the neural net is called backpropagation
- Neural net frameworks has many predefined layers
- **Spoiler alert:** It does not work (on images) at all - why?



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Linear classifier

NN

convNet

MNIST

<https://benchmarks.ai>

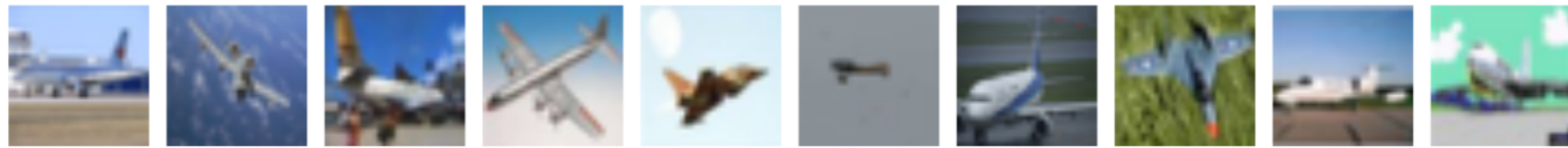
Czech Technical University in Prague

Faculty of Electrical Engineering, Department of Cybernetics



3	4	2	1	9	5	6	2	/
8	9	/	2	5	0	0	6	6
6	7	0	1	6	3	6	3	7
3	7	7	9	4	6	6	1	8
2	9	3	4	3	9	8	7	2
1	5	9	8	3	6	5	7	2
9	3	1	9	/	5	8	0	8

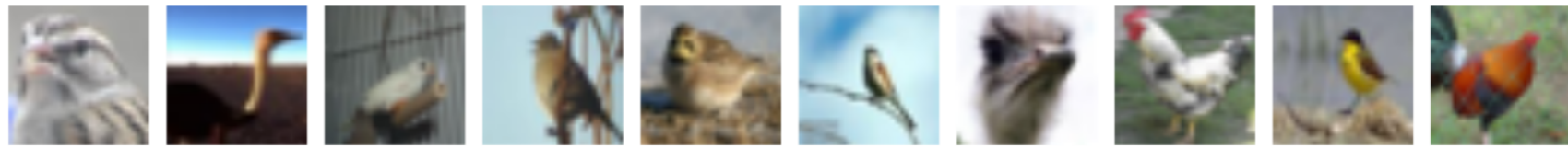
airplane



automobile



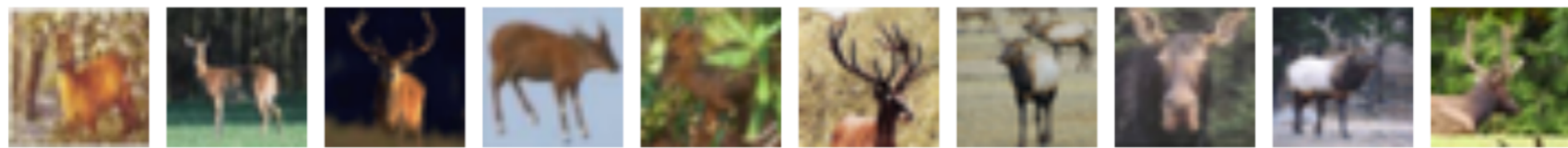
bird



cat



deer



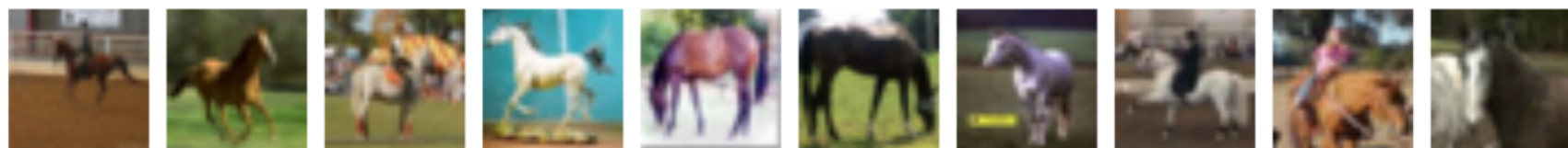
dog



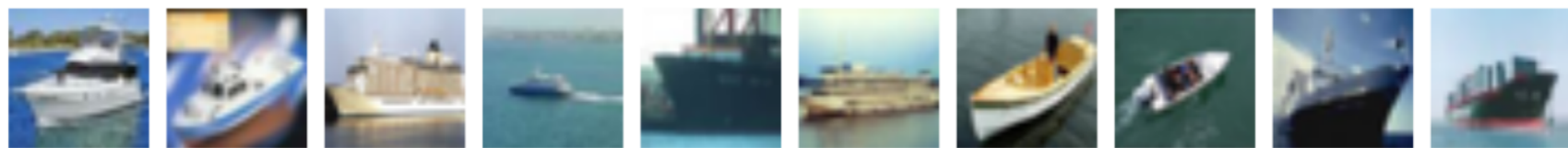
frog



horse



ship



truck



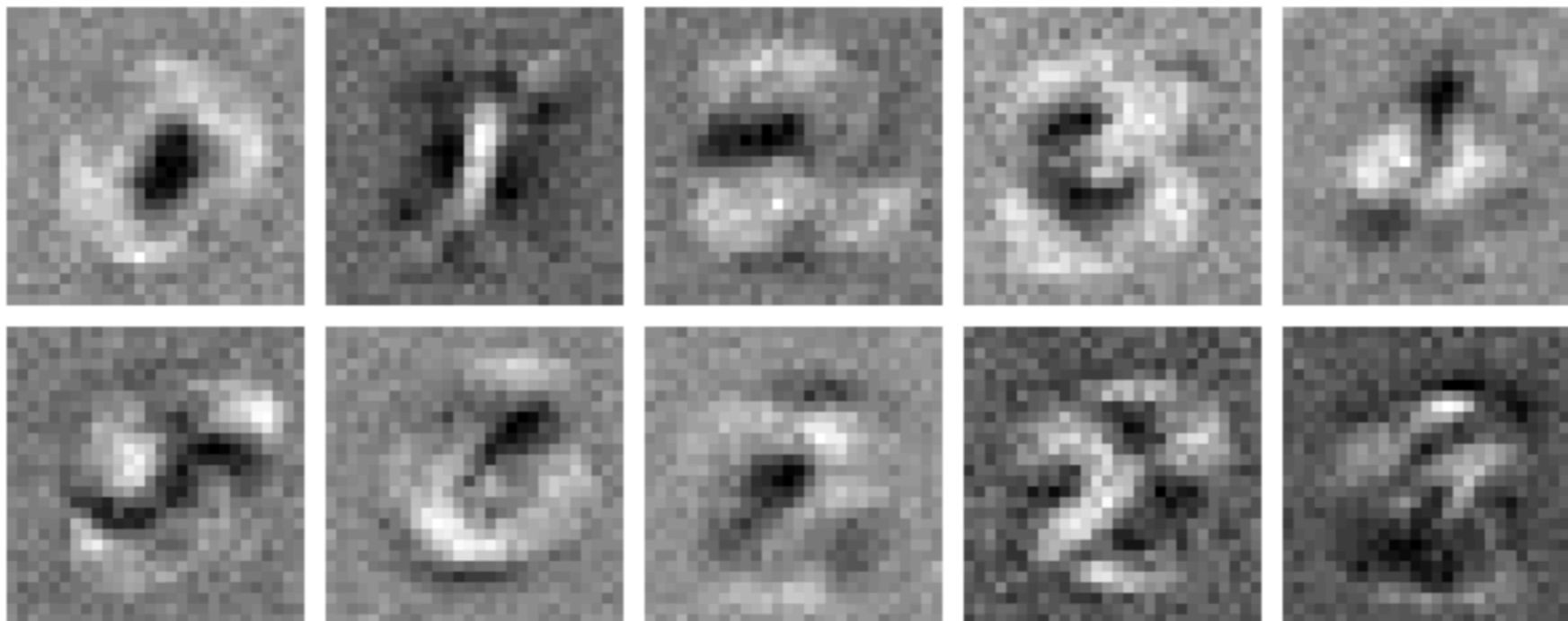
CIFAR-10: classify 32x32 RGB images into 10 categories
<https://www.cs.toronto.edu/~kriz/cifar.html>

Dataset

Learned weights of linear classifier

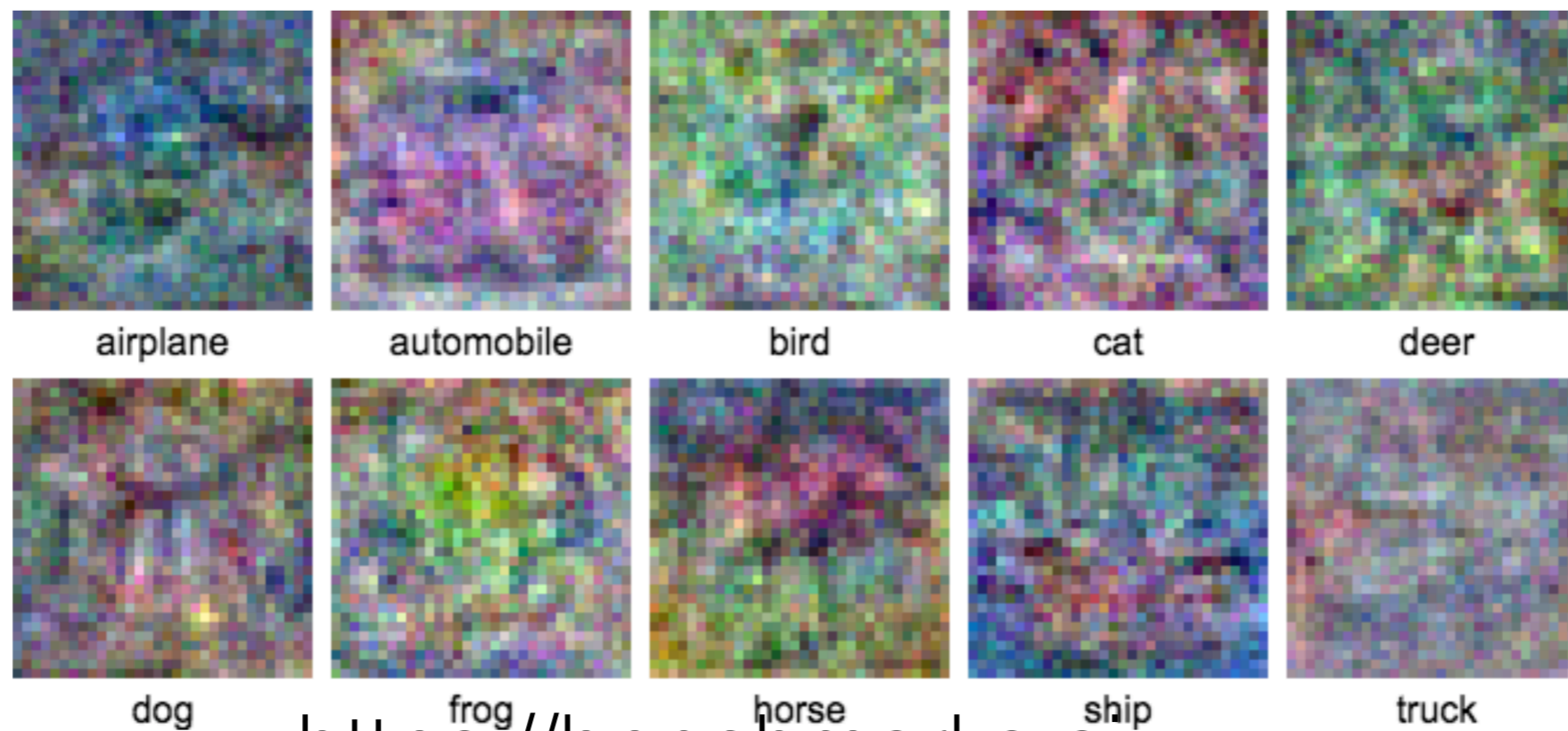
Error

MNIST



8%

CIFAR-10



63%

<https://benchmarks.ai>



Dataset

Error

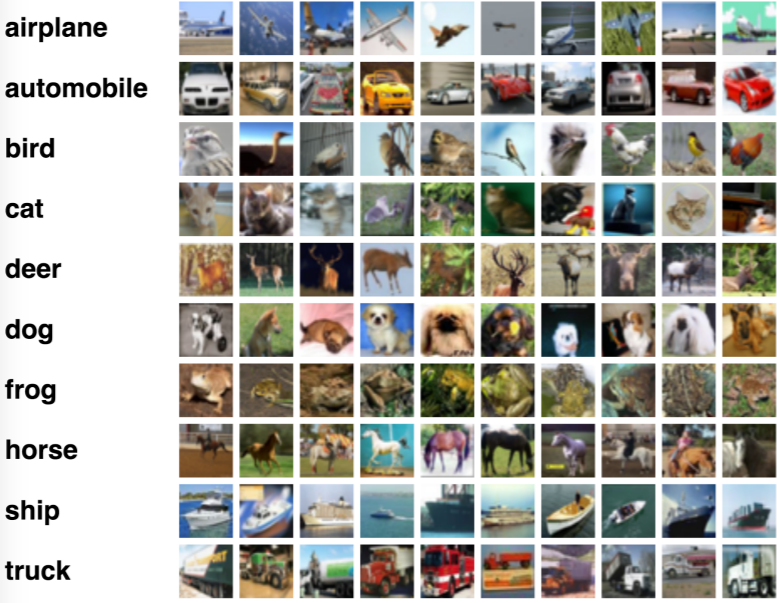
Linear

MNIST



8%

CIFAR-10



63%

<https://benchmarks.ai>

Czech Technical University in Prague

Faculty of Electrical Engineering, Department of Cybernetics



Dataset

Error

Linear

NN

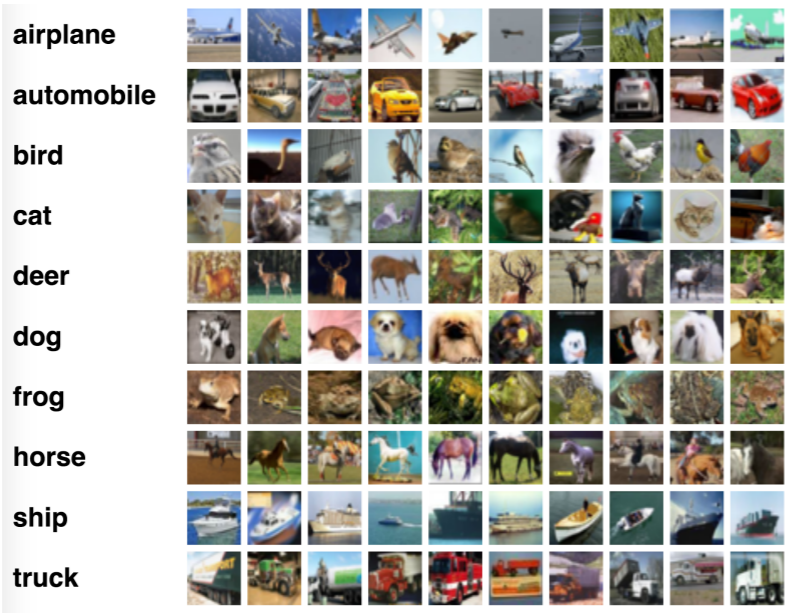
MNIST



8%

2%

CIFAR-10



63%

55%

<https://benchmarks.ai>



Dataset

Error

Linear

NN

ConvNet

MNIST



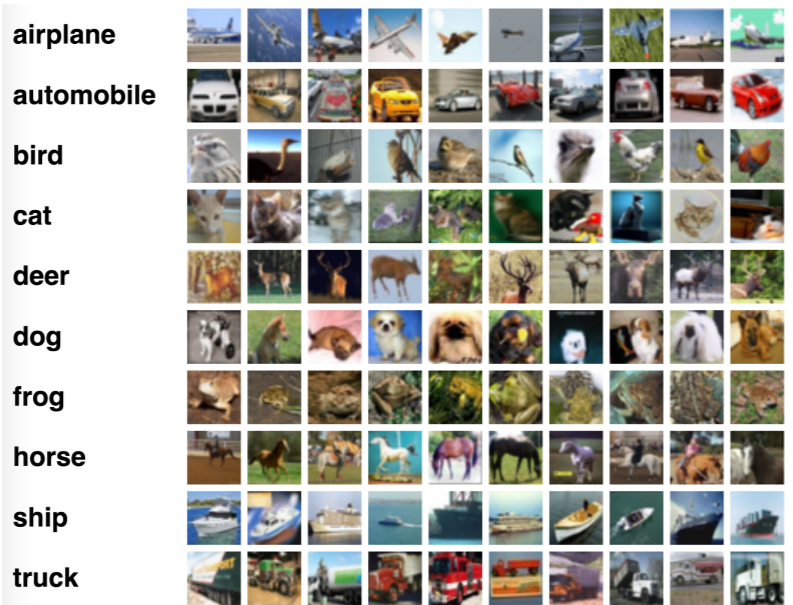
8%

2%

0.2%

[CVPR 2013]

CIFAR-10



63%

55%

1%

[EfficientNet, 2018]

<https://benchmarks.ai>

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Dataset

Error

Linear

NN

ConvNet

MNIST



8%

2%

0.2%

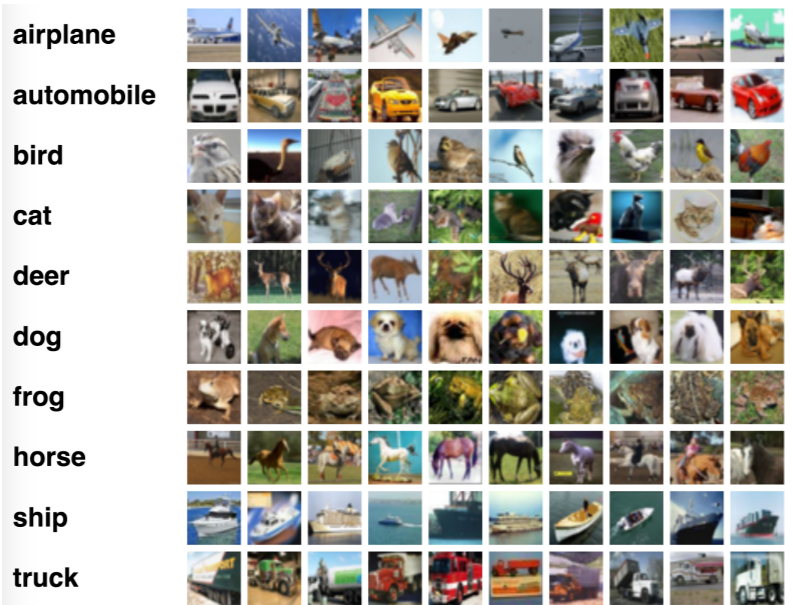
[CVPR 2013]

underfit

overfit

cortex inspired structure

CIFAR-10



63%

55%

1%

[EfficientNet, 2018]

<https://benchmarks.ai>

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Competencies required for the test T1

- Ability to draw a computational graph.
- Compute edge gradients/jacobians.
- Perform one step of backpropagation in a vectorized form
-



$$\mathbf{w}^* = \arg \min_{\mathbf{w}} \left(\sum_i -\log(p(y_i | \mathbf{x}_i, \mathbf{w})) \right) + (-\log p(\mathbf{w}))$$

loss function prior/regulariser

- Class of function represented by a NN is too general.
- Naive regulariser helps a bit, but dimensionality/wildness is huge => curse-of-dimensionality, overfitting,...
- What is number of weights between two 1000-neuron layers?
- **Next lecture:** study animal cortex to find a stronger prior on the class of suitable functions.
- **Spoiler alert 2:**
reduce very general class of functions "neuron layer" to very specific sub-class of functions "convolution layer"



Competencies required for the test T1

- Ability to draw a computational graph.
- Compute edge gradients/jacobians.
- Perform one step of backpropagation in a vectorized form

