

# FSM Testing and Checking Sequences

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- 1 Finite State Machine
  - Definitions
- 2 Finite state machine testing
  - Terminology
  - Formal FSM Testing
  - Example
  - Characterization Set Construction

# Outline

- 1 Finite State Machine
  - Definitions
- 2 Finite state machine testing
  - Terminology
  - Formal FSM Testing
  - Example
  - Characterization Set Construction

# Finite Machine in Applications [Bei95, HI98]

- a model for testing of applicaiton driven using menu
- a model of communication protocols
- a model used in object-oriented design

## Finite State Machine

- an abstract machine which the number of states and input symbols is finite and constant.
- consists of
  - states (nodes) ... future behavior is fully determined by a given state,
  - transitions (edges) ... behavioral rules,
  - input symbols (labels of edges) ... environmental stimuli, and
  - output symbols (labels of edges or nodes) ... external reactions.



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# Finite State Machine <sup>[HI98]</sup>

- Let *Input* be a finite alphabet.
- *Finite state machine* over *Input* consists of the following items:
  - 1 A finite set  $Q$  of elements called *states*.
  - 2 A subset  $I$  of the set  $Q$  containing *initial states*.
  - 3 A subset  $T$  of the set  $Q$  containing *end states*.
  - 4 A finite set of *transitions*, that returns a set of all possible next states for each state and each symbol of the input alphabet.

## Transition function

$$F : Q \times \text{Input} \rightarrow \mathcal{P}Q$$

- $F(q, \text{input})$  contains all possible states of the automaton, to which it is possible to make a transition if the input symbol *input* is accepted in state  $q$ .
- $\mathcal{P}Q$  denotes a set of all subsets of the set  $Q$   
(a *power set of the set  $Q$* , CZ *potenční množina množiny*).

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## Output function

$$G : Q \times \text{Input} \rightarrow \text{Output}$$

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# Finite State Machines Examples <sup>[HI98]</sup>

## A set *Input* of input symbols

- Actions or commands of the user entered through a keyboard,
- Mouse clicks or moves,
- Signals accepted by a sensor.

## A set *Q* of states

- Values of certain important variables of the system,
- A behavioral model of the system,
- A formular type visible on the monitor,
- Whether devices are active or not.

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# State Diagram <sup>[Bei95]</sup>

- **Nodes:** represent states (a state of the software application).
- **Edges:** represent transitions (a menu item selection).
- **Edge attributes (input symbols):** e.g. mouse actions, Alt+Key, function keys, keyboard keys of cursor movement.
- **Edge attributes (output symbols):** e.g. a menu presentation or a next window open.

## Space ship model *Enterprise*

- three modes of the impulse engine:  
move forward( $d$ ), neutral( $n$ ), and move backward( $r$ ).
- three possible state of movement:  
forward( $F$ ), stop( $S$ ), and backward( $B$ ).
- their combinations creates nine states:  
 $DF$ ,  $DS$ ,  $DB$ ,  $NF$ ,  $NS$ ,  $NB$ ,  $RF$ ,  $RS$ , and  $RB$ .
- possible inputs:  $d > d$ ,  $r > r$ ,  $n > n$ ,  $d > n$ ,  $n > d$ ,  $n > r$ ,  $r > n$ .

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## Enterprise State Space [Bei95]

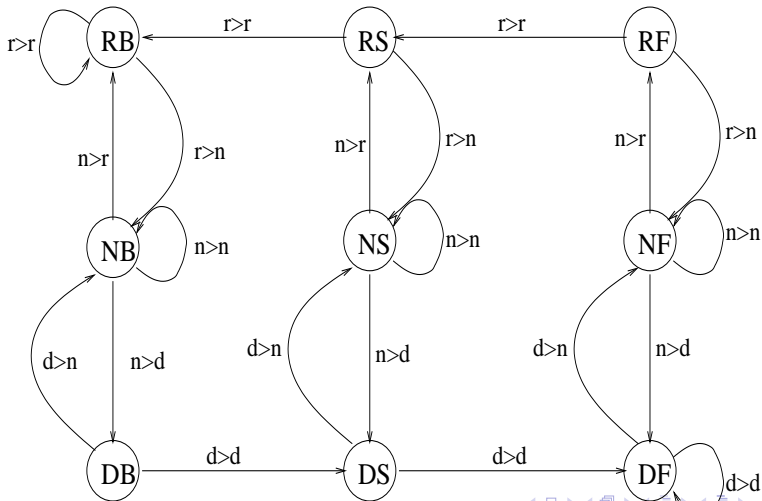
BACKWARD



STOPPED



FORWARD



# State Diagram Properties <sup>[Bei95]</sup>

## Properties

- A strong connected graph,
- State graphs grow very quickly,
- All possible and impossible inputs are considered in every state
  - the implementation of the system might be incorrect.
- Nice symmetry is a very rare case in real life.



# Transition Table <sup>[Bei95]</sup>

## A transition table

- has a row for each state
- has a column for each input.
- In fact, there are two tables with the same shape:
  - a transition table,
  - an output table.
- A value in the transition table represents the next state.
- A value in the output table is the output code for a given transition.
- **Hierachical (nested) automata** are the only way how huge tables can be avoided (e.g. statechart, starchart, etc.)





Enterprise Transition Table <sup>[Bei95]</sup>

## Enterprise

STATE	$r > r$	$r > n$	$n > n$	$n > r$	$n > d$	$d > d$	$d > n$	$r > d$	$d > r$
RB	RB	NB							
RS	RB	NS							
RF	RS	NF							
NB			NB	RB	DB				
NS			NS	RS	DS				
NF			NF	RF	DF				
DB						DS	NB		
DS						DF	NS		
DF						DF	NF		



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# State Reachability <sup>[Bei95]</sup>

- **Reachable state:** a state  $B$  is reachable from a state  $A$ , if there is a input sequence such that the system is transferred from the state  $A$  to the state  $B$ .
- **Unreachable state:** a state is unreachable if it is not reachable, especially from the initial state. Unreachable states implies typically a mistake.
- **Strong connectivity:** all state of the finite automaton are reachable from the initial state. Most practical models are strongly connected if they do not contain mistakes.
- **Isolated states:** a set of states that are not reachable from the initial state. If they exist, then they are very suspicious, mistaken states.
- **Reset:** a special input symbol/action causing the transition from any state to the initial state.



# State Categories <sup>[Bei95]</sup>

- **The set of the initial state:** If a transition leading from this set is performed, then there is no way back to this set (e.g. a boot of the system).
- **Working states:** When the set of the initial state is left, then the system works in a strongly connected set of states in which a majority of testing is performed.
- **The initial state of the working set:** a state of the working set which can be considered as the “initial state”.
- **The set of ending state:** If the system reaches this set, then there is not way back to the working set, e.g. a finalizing sequence, a shutdown.
- The system is **fully specified** if transitions and output symbols are defined for all combinations of input symbols and states.
- **A round trip of the state  $A$ :** a sequence of transitions going from the state  $A$  to a state  $B$  and back to the state  $A$ .



# Test Design <sup>[Bei95]</sup>

- Each state begins in the initial state.
- The system is transferred
  - from the initial state using the shortest path to the selected state,
  - the given transition is performed,
  - and the system is transferred using the shortest path back into the initial state,
  - i.e. we create a round trip.
- Each test is build upon the preceding simpler tests.
- The input symbol is determined for each transition of the round trip.
- The output symbol is determined for all associated transitions of the round trip.
- **We verify**
  - input codes,
  - output codes,
  - states,
  - each transition.
- **Are all end states reachable?**

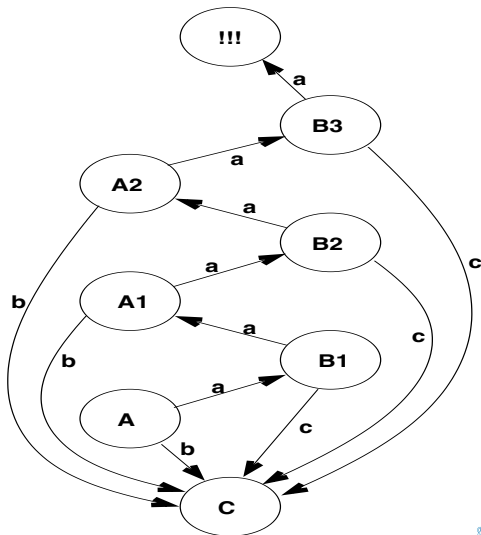
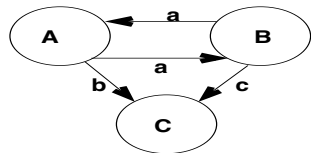


# Hidden States

- **Is the system in the initial state?**
  - A test cannot be started if there is no confirmation that the system is in the initial state.
  - Applications store their settings in a persistent way.
  - If a previous test fails, in what state is the application?
- **Hidden state:** an unknown state that is different from a given state but it has all transitions with the same input and output codes, i.e. it cannot be distinguish from the given state.
- **Has the implementation hidden states?**
  - During the software testing we might assume conditions that are not valid generally.
    - e.g. we know in which state the state is.
  - Often, we do not dealt with one or two hidden states, but the state space doubles and is multiplied in other way.



# Hidden States - Example



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# Finite State Machine Testing <sup>[HI98]</sup>

- Based on the isomorphism of finite state machines,

- $\mathcal{A} = (\text{Input}, Q, \mathbf{F}, q_0)$

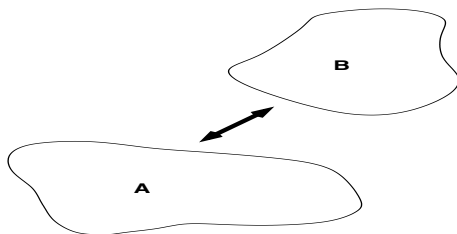
- $\mathcal{A}' = (\text{Input}, Q', \mathbf{F}', q_0')$

- $g : \mathcal{A} \rightarrow \mathcal{A}'$

- $g : Q \rightarrow Q'$

- 1  $g(q_0) = q_0'$

- 2  $\forall q \in Q, \text{input} \in \text{Input},$   
 $g(\mathbf{F}(q, \text{input})) = \mathbf{F}'(g(q), \text{input})$



# Test Set Construction [HI98, Cho78]

## Chow's $W$ method

- Let  $L$  be a set of input sequences and  $q, q'$  be two states.
- $L$  *distinguishes* (CZ rozliší) the state  $q$  from  $q'$  if there is a sequence  $k \in L$  such that the output sequence obtained by the application of  $k$  to the machine in the state  $q$  is different from the output sequence obtained by the application of  $k$  to the state  $q'$ .
- The machine is *minimal* if it does not contain redundant states.
- A set of input sequences  $W$  is called a *characterization set* if it can distinguish any two state of the machine.
- **A state cover** is a set  $L$  of input sequences such that it is possible to find an element of  $L$  using which we can reach the given state from the initial state  $q_0$ .
- **A transition cover** of the minimal machine is a set  $T$  of input sequences such that it is a state cover closed under the right composition with the input set  $Input$ .
  - $sequence \in T = L \bullet (Input^1 \cup \{\langle \rangle\})$



# Test Set Generation [HI98, Cho78]

- How many times are there more states than in the specification? ( $k$ )
- $Z = Input^k \bullet W \cup Input^{k-1} \bullet W \cup \dots \cup Input^1 \bullet W \cup W$ 
  - If  $A$  and  $B$  are two sets of sequences over the same alphabet, then  $A \bullet B$  denotes a set of sequences composed from the sequences of the set  $A$  followed by a sequence from  $B$ .
  - $k$  steps into an “unknown” space are performed followed by the verification of the state.

- Finite **test set**:

$$T \bullet Z$$

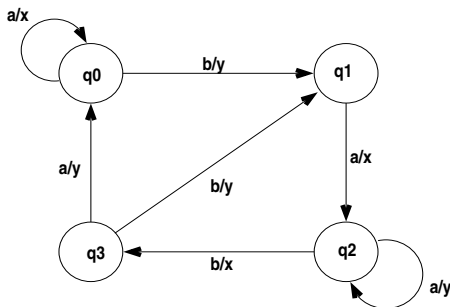
- Transition cover ensures
  - that all state and transition of the specification are implemented.
  - The set  $Z$  ensures that the implementation is in the same state as specified.
  - The parameter  $k$  ensures that all hidden states into the level  $k$  are tested.



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# A Simple Example <sup>[HI98]</sup>



- $Input = \{a, b\}$
- $L = \{\langle \rangle, b, b::a, b::a::b\}$ ,  $\langle \rangle \dots$  null input sequence
- $T = \{\langle \rangle, a, b, b::a, b::b, b::a::a, b::a::b, b::a::b::a, b::a::b::b\}$
- $W = \{a, b\}$  <sup>[Chy84]</sup>, pp. 31–34
  - $Z = Input \bullet W \cup W$
  - $= \{a, b\} \bullet \{a, b\} \cup \{a, b\}$
  - $= \{a, b, a::a, a::b, b::a, b::b\}$

# Test Set of the Example <sup>[HI98]</sup>

$$T \bullet Z =$$

$$= \{ \langle \rangle, a, b, b::a, b::b, b::a::a, b::a::b, b::a::b::a, b::a::b::b \}$$

$$\bullet \{ a, b, a::a, a::b, b::a, b::b \}$$

$$= \{ a, b, a::a, a::b, b::a, b::b,$$

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$$= \dots \text{simplifications}$$


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$$= \dots \text{simplifications}$$


# Applications <sup>[Bei95]</sup>

- Menu driven software,
- Object-oriented software,
- Protocols,
- Device drivers,
- Legacy hardware,
- Microcomputers of industrial and home devices,
- Software instalation,
- Archive and backup software,
- Safety software models,
- WEB applications.



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# Mealy Machine [Mea55, Mat13]

## Definition 1 (Mealy machine with a finite number of states is)

- 6-tuple  $M(X, Y, Q, q_0, \delta, \lambda)$ :
  - $X$  is a finite set of input symbols (the input alphabet),
  - $Y$  is a finite set of output symbols (the output alphabet)
  - $Q$  is a finite set of state,
  - $q_0 \in Q$  is the initial state,
  - $D \subseteq Q \times X$  is a specification domain,
  - $\delta : D \rightarrow Q$  is a state transition function,
  - $\lambda : D \rightarrow Y$  is an output function.
- If  $D = Q \times X$ , then  $M$  is a **complete** Mealy machine <sup>[SP10]</sup>.
  - A sequence  $\alpha = x_1 \dots x_k, \alpha \in I^*$  is a **defined input sequence** for a state  $q \in Q$  if there are  $q_1, \dots, q_{k+1} \in Q$ , where  $q_1 = q$  such that  $(q_i, x_i) \in D$  and  $\delta(q_i, x_i) = q_{i+1}$  for all  $1 \leq i \leq k$ .



# machine Minimality <sup>[SP10, Mat13]</sup>

Let  $M(X, Y, Q, q_0, \delta, \lambda)$  be a Mealy machine with a finite number of states.

- Extended transition and state functions applied to an input symbol  $x$  of a defined input sequence  $\alpha$  including the empty sequence  $\epsilon$ :
  - for  $q \in Q$ ,  $\delta(q, \epsilon) = q$  and  $\lambda(q, \epsilon) = \epsilon$
  - $\delta(q, \alpha x) = \delta(\delta(q, \alpha), x)$
  - $\lambda(q, \alpha x) = \lambda(\delta(q, \alpha), x)$
- $\Omega(q)$  is the set of all defined input sequences for state  $q \in Q$ .
- Two states  $q, q' \in Q$  are **distinguishable**, if there is  $\gamma \in \Omega(q) \cap \Omega(q')$  such that  $\lambda(q, \gamma) \neq \lambda(q', \gamma)$ . Then, we say that  $\gamma$  **distinguishes** the states  $q$  and  $q'$ .
- Two states  $q_1, q_2 \in Q$ ;  $q_1 \neq q_2$  are **state equivalent**, if they lead to the same of equivalent states after an application of any input sequence.
- $M$  is **minimal** if no its two states are equivalent <sup>[Ner58, Gil60]</sup>.



# $C$ -equivalence of States [SP10, Mat13]

Let  $M(X, Y, Q, q_0, \delta, \lambda)$  be a Mealy machine with a finite number of states.

- Let  $C \subseteq \Omega(q) \cap \Omega(q')$  be a set.
- The states  $q_1, q_2 \in Q$  are  **$C$ -equivalent**, if  $\lambda(q, \gamma) \neq \lambda(q', \gamma)$  for all  $\gamma \in C$ .

Two machines  $M_1(X, Y, Q_1, q_0^1, \delta_1, \lambda_1)$  and  $M_2(X, Y, Q_2, q_0^2, \delta_2, \lambda_2)$  are **equivalent**, if

- 1 for each state  $q \in M_1$  there is  $q' \in M_2$  such that  $q$  and  $q'$  are equivalent and
- 2 for each state  $q \in M_2$  there is  $q' \in M_1$  such that  $q$  and  $q'$  are equivalent.

## $k$ -equivalence

- Let  $M_1(X, Y, Q_1, q_0^1, \delta_1, \lambda_1)$  and  $M_2(X, Y, Q_2, q_0^2, \delta_2, \lambda_2)$  be two machines.
- The states  $q_i \in Q_1$  and  $q_j \in Q_2$  are considered to be  **$k$ -equivalent**, if they produce identical output sequences after excited with any input sequence of the length  $k$ .



# Characterization set $W$ [SP10, Mat13]

Let  $M(X, Y, Q, q_0, \delta, O)$  be a minimal and complete Mealy machine with a finite number of states.

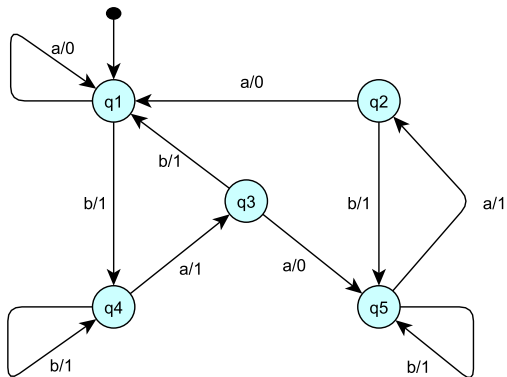
- $W$  is a finite set of input sequences that distinguishes any pair of different states  $q_i, q_j \in Q$ .
- Each input sequence  $\gamma \in W$  has a finite length.
- For each pair of different states  $q_i, q_j \in Q$  the set  $W$  contains at least one input sequence  $\gamma$  such that

$$\lambda(q_i, \gamma) \neq \lambda(q_j, \gamma)$$





# Characterization Set Example <sup>[HI98]</sup>



- $Input = \{a, b\}$
- $W = \{baaa, aa, aaa\}$
- $\lambda(q_1, baaa) = 1 \dots (1101)$
- $\lambda(q_2, baaa) = 0 \dots (1100)$
- $\lambda(q_1, baaa) \neq \lambda(q_2, baaa) \implies baaa$  distinguishes the states  $q_1$  a  $q_2$

# $k$ -equivalence Partition of States $Q$ <sup>[Mat13]</sup>

- $k$ -equivalence partition of states  $Q$ , denoted as  $P_k$ , is a collection of  $n$  finite sets  $\Sigma_{k,1}, \Sigma_{k,2}, \dots, \Sigma_{k,n}$  such that

$$\bigcup_{i=1}^n \Sigma_{k,i} = Q$$

- The states in  $\Sigma_{k,i}$  are  $k$ -equivalent.
- If states  $q_{\ell_1} \in \Sigma_{k,j}$  and  $q_{\ell_2} \in \Sigma_{k,i}$  for  $i \neq j$ , then  $q_{\ell_1}$  and  $q_{\ell_2}$  are  $k$ -distinguishable.



# W Set Construction <sup>[Mat13]</sup>

## The Algorithm

- 1 Create a sequence of  $k$ -equivalence partitions of states  $Q$  denoted as  $P_1, P_2, \dots, P_m, m > 0$
  - 2 Backward search  $k$ -equivalence partitions while constructing distinguishing sequences for each pair of the states.
- Algorithm convergence is guaranteed.
  - When the algorithm stops each class  $\Sigma_{K,j}$  of the finite partition  $P_K$  defines a class of equivalent states (1 for minimal machines).

### *Informally:*

- First, find what can be distinguished in one step,
- then in two steps,
- etc.



# W Set Construction <sup>[Mat13]</sup>

Tabular representation  $M$ .

0-equivalence partition  $P_0 = \{\Sigma_1 = \{q_1, q_2, q_3, q_4, q_5\}\}$

Current state	Output		Next state	
	a	b	a	b
$q_1$	0	1	$q_1$	$q_4$
$q_2$	0	1	$q_1$	$q_5$
$q_3$	0	1	$q_5$	$q_1$
$q_4$	1	1	$q_3$	$q_4$
$q_5$	1	1	$q_2$	$q_5$



# 1-equivalence Partition $P_1$ Construction <sup>[Mat13]</sup>

1-equivalence partition  $P_1 = \{\Sigma_1 = \{q_1, q_2, q_3\}, \Sigma_2 = \{q_4, q_5\}\}$  .

$\Sigma$	Current state	Output		Next state	
		a	b	a	b
<b>1</b>	$q_1$	0	1	$q_1$	$q_4$
	$q_2$	0	1	$q_1$	$q_5$
	$q_3$	0	1	$q_5$	$q_1$
<b>2</b>	$q_4$	1	1	$q_3$	$q_4$
	$q_5$	1	1	$q_2$	$q_5$



# 2-equivalence Partition Construction: $P_1$ Rewrite <sup>[Mat13]</sup>

Rewrite  $P_1$ , state  $q_i$  is replaced by  $q_{i,j}$  if  $q_i \in \Sigma_j$ .

$\Sigma$	Current state	Next state	
		a	b
<b>1</b>	$q_1$	$q_{1,1}$	$q_{4,2}$
	$q_2$	$q_{1,1}$	$q_{5,2}$
	$q_3$	$q_{5,2}$	$q_{1,1}$
<b>2</b>	$q_4$	$q_{3,1}$	$q_{4,2}$
	$q_5$	$q_{2,1}$	$q_{5,2}$



# 2-equivalence Partition Construction: $P_2$ Construction [Mat13]

Construct  $P_2$ . Divide  $\Sigma_{1,j}$  with regard to the groups of next states.

$\Sigma$	Current state	Next state	
		a	b
<b>1</b>	$q_1$	$q_{1,1}$	$q_{4,3}$
	$q_2$	$q_{1,1}$	$q_{5,3}$
<b>2</b>	$q_3$	$q_{5,3}$	$q_{1,1}$
<b>3</b>	$q_4$	$q_{3,2}$	$q_{4,3}$
	$q_5$	$q_{2,1}$	$q_{5,3}$



3-equivalence Partition Construction:  $P_3$  Construction [Mat13]

Construct  $P_3$ . Divide  $\Sigma_{2,j}$  with regard to the groups of next states.

$\Sigma$	Current state	Next state	
		a	b
<b>1</b>	$q_1$	$q_{1,1}$	$q_{4,3}$
	$q_2$	$q_{1,1}$	$q_{5,4}$
<b>2</b>	$q_3$	$q_{5,4}$	$q_{1,1}$
<b>3</b>	$q_4$	$q_{3,2}$	$q_{4,3}$
<b>4</b>	$q_5$	$q_{2,1}$	$q_{5,4}$





4-equivalence Partition Construction:  $P_4$  Construction [Mat13]

Construct  $P_4$ . Divide  $\Sigma_{3,j}$  with regard to the groups of next states.

$\Sigma$	Current state	Next state	
		a	b
<b>1</b>	$q_1$	$q_{1,1}$	$q_{4,4}$
<b>2</b>	$q_2$	$q_{1,1}$	$q_{5,5}$
<b>3</b>	$q_3$	$q_{5,5}$	$q_{1,1}$
<b>4</b>	$q_4$	$q_{3,3}$	$q_{4,4}$
<b>5</b>	$q_5$	$q_{2,2}$	$q_{5,5}$



Distinguishing Sequence Construction: Example <sup>[Mat13]</sup>

- ① Find a distinguishing sequence of the states  $q_1$  and  $q_2$ .
- ② Init the distinguishing sequence:  $z = \epsilon$ .
- ③ Find tables  $P_i$  and  $P_{i+1}$  such that  $(q_1, q_2)$  are in the same group in  $P_i$  and in different groups in  $P_{i+1}$ :
  - $P_3$  and  $P_4$  are obtained.
- ④ Find the input symbol distinguishing  $q_1$  and  $q_2$  in table  $P_3$ 
  - $b$  is the distinguishing symbol.
  - Update the distinguishing sequence:  $z := z.b = \epsilon.b = b$ .
- ⑤ Find the next states if the symbol  $b$  is applied to  $q_1$  and  $q_2$ ,
  - $q_4$  and  $q_5$  are obtained.
- ⑥ Find tables  $P_i$  and  $P_{i+1}$  such that  $(q_4, q_5)$  are in the same group in  $P_i$  and in different groups in  $P_{i+1}$ :
  - $P_2$  and  $P_3$  are obtained.
- ⑦  $(q_4, q_5) \rightarrow P_2, P_3 \rightarrow a \rightarrow z = ba$
- ⑧  $(q_3, q_2) \rightarrow P_1, P_2 \rightarrow a \rightarrow z = baa$
- ⑨  $(q_1, q_5) \rightarrow P_0, P_1 \rightarrow a \rightarrow z = baaa$
- ⑩ Repeat for each pair  $(q_i, q_j)$ :  $W = \{a, aa, aaa, baaa\}$



# Summary

- Finite state machines
- How to test finite state machines
- Test set construction using Chow's  $W$  method
- Characterization set construction

# Competencies

- Define finite state machine.
- Describe the concept of hidden states.
- Describe Chow's  $W$  method of test set construction.
- Define characterization set and describe its construction algorithm.



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