# Lecture 2: Vectors \& Matrices 

BE0B17MTB - Matlab

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September 30, 2020
Winter semester 2020/21

## Outline

1. Matlab Editor
2. Matrix Creation
3. Operations with Matrices
4. Excercises


## Matlab Editor

- It is often required to evaluate certain sequence of commands repeatedly $\Rightarrow$ utilization of Matlab scripts (plain ASCII coding).
- The best option is to use Matlab Editor,
- which can be opened using the following command:


## >> edit

- A script is a sequence of statements what we have been up to now typing in the command line.
- All the statements are executed one by one upon the launch of the script.
- The script operates over Matlab base workspace data.
- Scripts are suitable for quick analysis and solving problems involving multiple statements.
- There are specific naming conventions for scripts (and also for functions as we will see later).


## MatLab Editor, R2019



## Script Execution, m-files

- To execute script:
- F5 function key in Matlab Editor,
- Current folder $\rightarrow$ select script $\rightarrow$ context menu $\rightarrow$ Run,
- Current folder $\rightarrow$ select script $\rightarrow$ F9,
- from the command line:
>> script_name
- Scripts are stored as so called m-files, .m
- Caution: If you have Mathematica installed, the .m files may be launched by Mathematica.


## Data in Scripts

- Scripts can use data located in Workspace.
- Variables remain in the Workspace even after the calculation is finished.
- Operations on data in scripts are performed in the base Workspace.
- Matlab carries out commands sequentially.


## Useful Functions for Script Generation I.

- Function disp displays value of a variable in Command Window.
- Without displaying variable's name and the equation sign " $=$ ".
- Can be combined with a text (more on that later).
- Often it is advantageous to use more complicated but robust function sprintf.

```
a = 2^13 - 1;
b}=[\begin{array}{ll}{8*a}&{16*a}\end{array}
b
```

```
a}=\mp@subsup{2}{}{\wedge}13-1
b}=[8*a 16*a]
disp(b);
```


## Useful Functions for Script Generation II.

- Function input is used to enter variables.
- If the function it terminated unexpectedly, the input request is repeated A = input ('Enter parameter A: ');
- It is possible to enter strings as well:

```
str = input('Enter String str', 's');
```


## Script Commenting

- MAKE COMMENTS!!
- Important/complicated parts of code.
- Description of functionality, ideas, change of implementation.
- Typical single-line comment:

```
% create matrix, sum all members
matX = [1, 2, 3, 4, 5];
sumX = sum(matX); % sum of matrix
```

- Multiple-line comment:

```
% {
This is a multiple-line comment.
Mostly, it is more appropriate to use
more single-line comments.
%}
```

- Cell mode enables to separate script into more blocks.

```
matX = [1, 2, 3, 4, 5];
%% CELL mode (must be enabled in Editor)
sumX = sum(matX);
```


## Cell Mode in Matlab Editor

- Cells enable to separate the code into smaller, logically compacted parts.
- Separator $\% \%$.
- The separation is visual only, but it is possible to execute a single cell - shortcut CTRL+ENTER.



## Entering Matrices Using ":" I.

- Large vectors and matrices with regularly increasing elements can be typed in using colon operator.
- a is the smallest element ("from"), x is increment, b is the largest element ("to")

```
>> A = 1:4:13
A =
    1 5 9 13
```

$A=a: x: b$

- b doesn't have to be element of the series.
- Last element $N \cdot x$ then follows the inequality:

```
>> A = 1:4:10
A =
    1 5
```

$$
|a+N \cdot x| \leq|b|
$$

- If x is ommited, the increment is set equal to 1 .

$$
A=a: x: b
$$

## Entering Matrices Using ": " II.

- Using the colon operator ":" create:
- Following vectors

$$
\begin{array}{r}
\mathbf{u}=\left[\begin{array}{llll}
1 & 3 & \ldots & 99
\end{array}\right] \\
\mathbf{v}
\end{array}=\left[\begin{array}{lllll}
25 & 20 & \ldots & -5
\end{array}\right]^{\mathrm{T}}
$$

- Matrix
- Caution, the third column can't be created using colon operator ":" only,

$$
\mathbf{T}=\left[\begin{array}{ccc}
-4 & 1 & \frac{\pi}{2} \\
-5 & 2 & \frac{\pi}{4} \\
-6 & 3 & \frac{\pi}{6}
\end{array}\right]
$$

but can be created using "." and dot operator "." (we will see later).

## Entering Matrices Using linspace, logspace I.

- Colon operator defines vector with evenly spaced points.
- In the case when fixed number of elements of a vector is required, use linspace:

```
A = linspace(a, b, N);
```

```
>>A = linspace(0, 2, 5)
A =
    0 0.5000 1.0000 1.5000 2.000
```

- When the N parameter is left out, the vector with 100 elements is generated:

A = linspace ( $\mathrm{a}, \mathrm{b}$ );

- The function logspace works analogically, except that logaritmic scale is used $\mathrm{A}=\operatorname{logspace}(\mathrm{a}, \mathrm{b}, \mathrm{N})$;


## Entering Matrices Using linspace, logspace II.

- Create a vector of 100 evenly spaced points in the interval $[-1.15,75.4]$
- Create a vector of 201 evenly spaced points in the interval [ $-100,100]$ sorted in descending order.
- Create a vector with spacing of -10 in the interval $[-100,100]$ sorted in descending order.
- try both options using linspace and colon ":"


## Entering Matrices Using Functions I.

- Special types of matrices of given sizes are needed quite often.
- Matlab offers a number of functions to serve the purpose.
- Example: matrix filled with zeros
- Will be used frequently.

```
zeros(m)
    % matrix of size [m x m]
zeros(m, n) % matrix of size [m x n]
zeros(m, n, p, ..) % matrix of size [m x n x p x ..]
zeros([m,n]) % matrix of size [mxn]
B = zeros(m, 'single') % matrix of size [mxn], of type 'single'
% see documentation for other options
```


## Entering Matrices Using Functions II.

- Following useful functions analogical to the zeros function are available

| ones | matrix filled with ones |
| :---: | :--- |
| eye | identity matrix |
| NaN, Inf | matrix filled with NaN, matrix filled with Inf |
| magic | matrix suitable for MATLAB experiments, notice its properties |
| rand, randn, randi | matrix filled with random numbers coming from uniform and normal |
|  | distribution, matrix filled with uniformly distributed random integers |
| randperm | returns vector containing random permutation of numbers |
| diag | creates diagonal matrix or returns diagonal of a matrix |
| blkdiag | construct block diagonal matrix from input arguments |
| cat | groups several matrices into one |
| true, false | creates a matrix of logical ones and zeros |

- For further functions see Matlab $\rightarrow$ Mathematics $\rightarrow$ Elementary Mathematics $\rightarrow$ Constants and Test Matrices.


## Entering Matrices Using Functions III.

- Create following matrices
- use Matlab functions
- begin with matrices you find easy to cope with.

$$
\begin{aligned}
& \mathbf{M}_{1}=\left[\begin{array}{ll}
\mathrm{NaN} & \mathrm{NaN} \\
\mathrm{NaN} & \mathrm{NaN}
\end{array}\right] \\
& \mathbf{M}_{2}=\left[\begin{array}{llll}
1 & 1 & 1 & 1
\end{array}\right] \\
& \mathbf{M}_{3}=\left[\begin{array}{lll}
2 & 0 & 0 \\
0 & 3 & 0 \\
0 & 0 & -5
\end{array}\right] \\
& \mathbf{M}_{4}=\left[\begin{array}{llll}
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0
\end{array}\right]
\end{aligned}
$$

## Entering Matrices Using Functions IV.

- Try to create an empty three-dimensional array of type double.
- Can you find another option?
- empty is hidden (but public) method of all non-abstract classes in Matlab.


## Dealing with Sparse Matrices

- Matlab provides support for working with sparse matrices.
- Most of the elements of sparse matrices are zeros and it pays off to store them in a more efficient manner.
- To create a sparse matrix $S$ out of matrix A:

```
S = sparse (A)
```

- Conversion of a sparse matrix to a full matrix:

B = full (S)

- In the case of need see Help for other functions.


## Entering Matrices

- Quite often, there are several options how to create a given matrix.
- It is possible to use an output of one function as an input of another function in Matlab:
- Consider:
- clarity,

```
plot(diag(randn(10, 1), 1))
```

- simplicity,
- speed,
- convention.
E.g. band matrix with " 1 " on main diagonal and with " 2 " and " 3 " on secondary diagonals. N = 10; diag(ones (N, 1)) + diag(2 * ones (N - 1, 1), 1) + diag(3 * ones (N - 1, 1), -1)
- Can be done using for cycle as well (see later in semester), might be faster ...
- Some other idea?


## Transpose and Matrix Conjugate

- Pay attention to situations where the matrix is complex, $\mathbf{A} \in \mathbb{C}^{M \times N}$.
- Theere are two operations:

| transpose | $\mathbf{A}^{\mathrm{T}}=\left[A_{i j}\right]^{\mathrm{T}}=\left[A_{j i}\right]$ | transpose (A) $<-$ don't use | A. ' |
| :---: | :---: | :--- | :---: | :---: |
| transpose + conjugate | $\mathbf{A}^{\mathrm{H}}=\left[A_{i j}\right]^{\mathrm{H}}=\left[\mathbf{A}^{*}\right]^{\mathrm{T}}$ | ctranspose(A) $<-$ don't use | $\mathrm{A}^{\prime}$ |

```
>> A = magic(2) + 1j * magic(2)'
```

```
|>>A.'' }\begin{array}{ll}{\hline\multicolumn{y}{l}}\\{\mathrm{ ans =}}\\{1.0000+1.0000i}&{4.0000+3.0000i}\\{3.0000+4.0000i}&{2.0000+2.0000i}\\{\hline}
```

```
>> A'
ans =
    1.0000-1.0000i 4.0000-3.0000i
    3.0000-4.0000i 2.0000-2.0000i
```


## Matrix Operations I.

- There are other useful functions apart from transpose (transpose) and matrix diagonal (diag):

```
P = magic(4)
```

- upper triangular matrix,

$$
\mathrm{U}=\operatorname{triu}(\mathrm{P})
$$

- lower triangular matrix,

$$
\mathrm{L}=\operatorname{tril}(\mathrm{P})
$$

- a matrix can be modified taking into account secondary diagonals as well

```
V = triu(P, -1)
```

$$
\begin{aligned}
& \mathbf{P}=\left[\begin{array}{cccc}
16 & 2 & 3 & 13 \\
5 & 11 & 10 & 8 \\
9 & 7 & 6 & 12 \\
4 & 14 & 15 & 1
\end{array}\right] \mathbf{U}=\left[\begin{array}{cccc}
\hline 16 & 2 & 3 & 13 \\
0 & 11 & 10 & 8 \\
0 & 0 & 6 & 12 \\
0 & 0 & 0 & 1
\end{array}\right] \\
& \mathbf{L}=\left[\begin{array}{cccc}
16 & 0 & 0 & 0 \\
5 & 11 & 0 & 0 \\
9 & 7 & 6 & 0 \\
4 & 14 & 15 & 1
\end{array}\right] \quad \mathbf{V}=\left[\begin{array}{cccc}
\begin{array}{ccc}
16 & 2 & 3 \\
5 & 11 & 10
\end{array} \\
\begin{array}{ccc}
8 \\
0 & 7 & 6 \\
0 & 0 & 12
\end{array} & 1
\end{array}\right]
\end{aligned}
$$

## Matrix Operations II.

- Function repmat is used to copy (part of) a matrix.

```
\(B=\operatorname{repmat}(A, m, n)\)
\[
\mathbf{A}=\left[\begin{array}{lll}
A_{11} & A_{12} & A_{13}
\end{array}\right]
\]
```

```
B = repmat (A, 1, 2)
```

B = repmat (A, 1, 2)
C = repmat (A, [2 1])
C = repmat (A, [2 1])

$$
\begin{gathered}
\mathbf{B}=\left[\begin{array}{lll}
\begin{array}{lll}
A_{11} & A_{12} & A_{13}
\end{array} \begin{array}{ll}
A_{11} & A_{12}
\end{array} A_{13}
\end{array}\right] \\
\mathbf{C}=\left[\begin{array}{lll}
\begin{array}{lll}
A_{11} & A_{12} & A_{13} \\
\left.\begin{array}{lll}
A_{11} & A_{12} & A_{13}
\end{array}\right]
\end{array}
\end{array} .\right.
\end{gathered}
$$

```
- repmat is a very fast function.
- Comparison of execution time of creation a \(10^{4} \times 10^{4}\) matrix filled with pi (HW, SW and Matlab version dependent):
```

X = ones(1e4) % computed in 0.71s
Y = repmat (1, 1e4, 1e4) % computed in 0.4s, BUT... don't use it

```
- It is for you to consider the way of matrix creation...

\section*{Matrix Operations III.}
- Function reshape is used to rearrange a matrix
\(\mathrm{B}=\operatorname{reshape}(\mathrm{A}, \mathrm{m}, \mathrm{n})\)
- e.g.
\[
\mathbf{A}=\left[\begin{array}{ll}
A_{11} & A_{12} \\
A_{21} & A_{22}
\end{array}\right]
\]
\[
\begin{aligned}
& \mathrm{C}=\text { reshape }(\mathrm{A},[4,1]) \\
& \mathrm{D}=\text { reshape }(\mathrm{A}, ~ 1,4) \\
& \mathrm{D}=\text { reshape }(\mathrm{A},[], 4)
\end{aligned}
\]
\[
\begin{gathered}
\mathbf{C}=\left[\begin{array}{l}
A_{11} \\
A_{21} \\
A_{12} \\
A_{22}
\end{array}\right] \\
\mathbf{D}=\left[\begin{array}{llll}
A_{11} & A_{21} & A_{12} & A_{22}
\end{array}\right]
\end{gathered}
\]

\section*{Matrix Operations IV.}
- Following functions are used to swap the order of
- columns: fliplr, B = fliplr (A)
- rows: flipud, C = flipud (A)
- row-wise or column-wise: flip.
\[
\begin{aligned}
& \mathrm{B}=\operatorname{flip}(\mathrm{A}, 1) \\
& \mathrm{C}=\operatorname{flip}(\mathrm{A}, 2) \\
& \hline
\end{aligned}
\]
\[
\begin{aligned}
& \mathbf{A}=\left[\begin{array}{lll}
A_{11} & A_{12} & A_{13} \\
A_{21} & A_{22} & A_{23}
\end{array}\right] \\
& \mathbf{B}=\left[\begin{array}{lll}
A_{13} & A_{12} & A_{11} \\
A_{23} & A_{22} & A_{21}
\end{array}\right] \\
& \mathbf{C}=\left[\begin{array}{lll}
A_{21} & A_{22} & A_{23} \\
A_{11} & A_{12} & A_{13}
\end{array}\right]
\end{aligned}
\]
- The same result is obtained using indexing (later in the course).

\section*{Matrix Operations V.}
- Circular shift is also available.
- Can be carried out along an arbitrary dimension (row-wise/column-wise).
- Can be carried out in both directions (back/forth).
- Consider the difference between flip and circshift.
```

B = circshift (A, -2)
C = circshift(A, [-2 1])

```
\[
\mathbf{B}=\left[\begin{array}{lll}
A_{31} & A_{32} & A_{33} \\
A_{11} & A_{12} & A_{13} \\
A_{21} & A_{22} & A_{23}
\end{array}\right]
\]
\[
\begin{aligned}
& \mathbf{A}=\left[\begin{array}{lll}
A_{11} & A_{12} & A_{13} \\
A_{21} & A_{22} & A_{23} \\
A_{31} & A_{32} & A_{33}
\end{array}\right] \\
& \mathbf{C}=\left[\begin{array}{lll}
A_{33} & A_{31} & A_{32} \\
A_{13} & A_{11} & A_{12} \\
A_{23} & A_{21} & A_{22}
\end{array}\right]
\end{aligned}
\]

\section*{Matrix Operations VI.}
- Convert matrix \(\mathbf{A}\) into the form of matrices \(\mathbf{A}_{1}\) to \(\mathbf{A}_{4}\).
\[
A=[1 \mathrm{pi} ; \exp (1)-1 i]
\]
\[
\mathbf{A}=\left[\begin{array}{cc}
1 & \pi \\
\mathrm{e} & -\mathrm{i}
\end{array}\right]
\]
- Use repmat, reshape, triu, tril and conj.
\[
\left.\left.\begin{array}{c}
\mathbf{A}_{1}=\left[\begin{array}{cccccc}
1 & \pi & 1 & \pi & 1 & \pi \\
\mathrm{e} & -\mathrm{i} & \mathrm{e} & -\mathrm{i} & \mathrm{e} & -\mathrm{i}
\end{array}\right] \quad \mathbf{A}_{3}=\left[\begin{array}{cc}
1 & \pi \\
\mathrm{e} & +\mathrm{i} \\
1 & \pi \\
\mathrm{e} & +\mathrm{i} \\
1 & \pi \\
\mathrm{e} & +\mathrm{i}
\end{array}\right] \quad \mathbf{A}_{4}=\left[\begin{array}{cccc}
1 & \pi & 0 & 0 \\
0 & 0 & 0 \\
\mathrm{e} & -\mathrm{i} & \mathrm{e} & 0 \\
0 & 0 & 0 \\
0 & \pi & 1 & \pi \\
0 & 0 & \mathrm{e} & -\mathrm{i} \\
\mathrm{e} & 0 \\
0 & \pi & \mathrm{e} & -\mathrm{i}
\end{array}\right] \quad 0 \\
\mathbf{A}_{2}
\end{array}\right] \quad \begin{array}{lllll}
0 & \pi & 1 & \pi \\
0 & 0 & 0 & 0 & \mathrm{e} \\
\hline
\end{array}\right]
\]

\section*{Matrix Operations VII.}
- Create the following matrix (use advanced techniques)
\[
\mathbf{A}=\left[\begin{array}{llllll}
1 & 2 & 3 & 1 & 2 & 3 \\
0 & 2 & 4 & 0 & 2 & 4 \\
0 & 0 & 5 & 0 & 0 & 5
\end{array}\right]
\]
- Create matrix \(\mathbf{B}\) by swapping columns in matrix \(\mathbf{A}\).

- Create matrix \(\mathbf{C}\) by swapping rows in matrix \(\mathbf{B}\).


\section*{Matrix Operations VIII.}
- Compare and interpret following commands.
```

x = (1:5).' % entering vector
x = repmat (x, [1 10]); % 1. option
X = x(:, ones(10, 1)); % 2. option

```
- repmat is powerful, but not always the most time-efficient function.

\section*{Vector and Matrix Operations}
- Remember that matrix multiplication is not commutative, i.e. \(\mathbf{A B} \neq \mathbf{B A}\).
- Remember that vector \(\times\) vector product results in
\begin{tabular}{|c|c|}
\cline { 2 - 3 } \multicolumn{1}{c|}{} & \(u_{11}\)
\end{tabular}\(u_{12}\).
\[
\underset{\substack{\text { v. }}}{\mathbf{v}_{1, M}} \mathbf{u}_{M, 1}=\mathbf{w}_{1,1}
\]
\begin{tabular}{|cc|}
\hline\(v_{11}\) & \(v_{12}\) \\
\(u_{11}\) \\
\(u_{21}\) \\
\(u_{31}\) \\
\hline
\end{tabular}\(w_{11}\)\begin{tabular}{l}
\(w_{13}\) \\
\hline
\end{tabular}
... pay attention to the dimensions of matrices!

\section*{Element-by-element Vector Product}
- It is possible to multiply arrays of the same size in the element-by-element manner in Matlab.
- Result of the operation is an array.
- Size of all arrays are the same, e.g. in the case of \(1 \times 3\) vectors:
\[
\mathbf{a}=\left[\begin{array}{lll}
a_{1} & a_{2} & a_{3}
\end{array}\right] \quad \mathbf{b}=\left[\begin{array}{lll}
b_{1} & b_{2} & b_{3}
\end{array}\right]
\]
```

|alll}$$
\begin{array}{lll}{\mp@subsup{a}{1}{}}&{\mp@subsup{a}{2}{}}&{\mp@subsup{a}{3}{}}\\{*}&{\begin{array}{lll}{\mp@subsup{b}{1}{}}&{\mp@subsup{b}{2}{}}&{\mp@subsup{b}{3}{}}\end{array}
$$->\quad\mathrm{ (Inner matrix dimensions must agree.)}}

```
>> a.*b
\[
\begin{array}{|lll}
\hline a_{1} & a_{2} & a_{3} \\
\hline
\end{array} * \begin{array}{|lll}
b_{1} & b_{2} & b_{3} \\
\hline
\end{array} \rightarrow \begin{array}{|lll}
a_{1} b_{1} & a_{2} b_{2} & a_{3} b_{3} \\
\hline
\end{array}=\left[a_{i} b_{i}\right]
\]

\section*{Element-by-element Matrix Product}
- If element-by-element multiplication of two matrices of the same size is needed, use the .* operator.
- It is so called Hadamard product/element-wise product/Schur product: A \(\circ \mathbf{B}\).
- These two cases of multiplication are distinguished:

\[
\begin{array}{ll}
A_{11} & A_{12} \\
A_{21} & A_{22}
\end{array} \quad \star \begin{array}{|ll}
B_{11} & B_{12} \\
B_{21} & B_{22}
\end{array} \rightarrow \begin{array}{|ll|}
A_{11} B_{11}+A_{12} B_{21} & A_{11} B_{12}+A_{12} B_{22} \\
A_{21} B_{11}+A_{22} B_{21} & A_{21} B_{12}+A_{22} B_{22} \\
\hline
\end{array}
\]
```

>> A.*B

```
\begin{tabular}{ll}
\(A_{11}\) & \(A_{12}\) \\
\(A_{21}\) & \(A_{22}\)
\end{tabular}\(\cdot *\)\begin{tabular}{|cc|}
\(B_{11}\) & \(B_{12}\) \\
\(B_{21}\) & \(B_{22}\)
\end{tabular}\(\rightarrow\)\begin{tabular}{l}
\(A_{11} B_{11}\) \\
\(A_{12} B_{12}\) \\
\(A_{21} B_{21}\)
\end{tabular}\(A_{22} B_{22}\)

\section*{Compatible Array Size}
- Since Matlab version R2016b most two-input (binary) operators support arrays that have compatible sizes.
- Variables have compatible sizes if their sizes are either the same or one of them is 1 (for all dimensions).
- Examples:
- \(\circ\) represents arbitrary two-input element-wise operator (+, \(-, \ldots, . /, \&,<,==, \ldots\) ).

\[
[3 \times 1] \quad[1 \times 2] \quad[3 \times 2]
\]

\([2 \times 2] \quad[2 \times 1] \quad[2 \times 2]\)
\([2 \times 2] \quad[1 \times 1] \quad[2 \times 2]\)

\[
[4 \times 3 \times 1]
\]
\[
[1 \times 3 \times 3]
\]
\[
[4 \times 3 \times 3]
\]


\section*{Element-wise Operations I.}
- Elements-wise operations can be applied to vectors as well in Matlab. Element-wise operations can be usefully combined with vector functions.
- It is possible, quite often, to eliminate 1 or even 2 for-loops!!!
- These operations are exceptionally efficient \(\rightarrow\) allow use of so called vectorization (see later).

\[
f(x)=\frac{10}{(x+1)} \tan (x), \quad x \in\left[-\frac{\pi}{4}, \frac{\pi}{4}\right]
\]
```

x = -pi/4:pi/100:pi/4;
fx = 10 ./ (1 + x) .* tan(x);
plot(x, fx)
grid on

```

\section*{Element-wise Operations II.}
- Evaluate functions of the variable
\[
x \in[0,2 \pi]:
\]
\[
\begin{aligned}
& f_{1}(x)=\sin (x) \\
& f_{2}(x)=\cos ^{2}(x) \\
& f_{3}(x)=f_{1}(x)+f_{2}(x)
\end{aligned}
\]
- Evaluate the functions in evenly spaced points of the interval, the spacing is \(\Delta x=\pi / 20\).
- For verification use:
\[
\operatorname{plot}(x, f 1, x, f 2, x, f 3)
\]


\section*{Element-wise Operations III.}
- Depict graphically following functional dependency in the interval \(x \in[0,5 \pi]\).
- Plot the result using the following function:
\[
f_{4}(x)=\frac{-\cos (3 x)}{\cos (x) \sin \left(x-\frac{\pi}{5}\right)-\pi}
\]
```

plot(x, f4)

```
- Explain the difference in the way of multiplication of matrices of the same size.
\(\square\)
\(\square\) >> \(A^{\prime} . * B\)


\section*{Element-wise Operation IV.}
- Evaluate the function \(f(x, y)=x y, \quad x, y \in[0,2]\), use 101 evenly spaced points in both \(x\) and \(y\).
- The evaluation can be carried out either using vectors, matrix element-wise vectorization or using two for loops.
- Plot the result using \(\operatorname{surf}(\mathrm{x}, \mathrm{y}, \mathrm{f})\).
- When ready, try also \(f(x, y)=x^{0.5} y^{2}\) on the same interval.


\section*{Matrix Operations}
- Contruct block diagonal matrix: blkdiag.
```

A = 1;
B = [2 3; -4 -5];
C = blkdiag(B, A);

```
\[
\mathbf{A}=\begin{aligned}
& A_{11} \\
& \left.\mathbf{B}=\begin{array}{ll}
B_{11} & B_{12} \\
B_{21} & B_{22}
\end{array}\right]
\end{aligned}
\]
\[
\left.\mathbf{C}=\begin{array}{|cc|}
\hline B_{11} & B_{12} \\
B_{21} & B_{22}
\end{array}\right) 0
\]
- Arranging two matrices of the same size: cat.
\[
\begin{aligned}
& \mathrm{C}=\operatorname{cat}(2, \mathrm{~A}, \mathrm{~B}) \\
& \mathrm{C}=\operatorname{cat}(1, \mathrm{~A}, \mathrm{~B}) \\
& \mathrm{C}=\operatorname{cat}(3, \mathrm{~A}, \mathrm{~B})
\end{aligned}
\]



\section*{Size of Matrices and Other Structures I.}
- It is often needed to know sizes of matrices and arrays.
- Function size returns vector giving the size of a matrix/array.
\[
\begin{aligned}
& A=\operatorname{randn}(3,5) ; \\
& d=\operatorname{size}(A) \% d=[35]
\end{aligned}
\]
- Function length returns largest dimension of an array.
\[
\text { length(A) }=\max (\operatorname{size}(A))
\]
\[
\begin{aligned}
& A=\operatorname{randn}(3,5,8) ; \\
& e=\operatorname{length}(A) \% e=8
\end{aligned}
\]
- Function ndims returns number of dimensions of a matrix/array.
\[
\operatorname{ndims}(A)=\operatorname{length}(\operatorname{size}(A)) \quad m=\operatorname{ndims}(A) \div m=3
\]
- Function numel returns number of elements of a matrix/array.
\[
\text { numel }\{\mathrm{A}\}=\operatorname{prod}(\operatorname{size}(\mathrm{A}))
\]
\[
\mathrm{n}=\text { numel }(\mathrm{A}) \quad \% \mathrm{n}=120
\]

\section*{Size of Matrices and Other Structures II.}
- Create an arbitrary 3D array.
- You can make use of the following commands:
```

A = rand(2 + randi(10), 3 + randi(5));
A = cat(3, A, flipud(fliplr(A)))

```
- And now:
- Find out the size of A.
- Find out the number of elements of A.
- Find out the number of elements of \(A\) in the "longest" dimension.
- Find out the number of dimensions of A.

\section*{Squeeze}
- Function squeeze removes dimension of an array with length 1.
- If the input is scalar, vector or array without any dimension of the length 1 , the output is identical to the input.



\section*{Function gallery}
- Function enabling to create a vast set of matrices that can be used for Matlab code testing.
- Most of the matrices are special-purpose.
- Function gallery offers significant coding time reduction for advanced Matlab users.
- See: help gallery or doc gallery
- Try for instance:
```

gallery('pei', 5, 4)
gallery('leslie', 10)
gallery('clement', 8)

```

\section*{Exercises}

\section*{Exercise I.}
- Create matrix M of size size (M) = [lllllland containing random numbers coming from uniform distribution on the interval \([-0.5,7.5]\).
\[
I(x)=\left(I_{\max }-I_{\min }\right) \operatorname{rand}(\ldots)+I_{\min }
\]


\section*{Exercise II.}
- Consider the operation a1^a2. Is this operation applicable to the following cases?
\[
\begin{array}{ll}
\text { a1 - matrix } & \text { a2 - scalar } \\
\text { a1 - matrix } & \text { a2- matrix } \\
\text { a1 - matrix } & \text { a2- vector } \\
\text { a1- scalar } & \text { a2- scalar } \\
\text { a1 - scalar } & \text { a2- matrix } \\
\text { a1, a } 2 \text { matrix } & \text { a1.^a2 }
\end{array}
\]

You can always create the matrices a1, a2 and make a test ...

\section*{Exercise III.}
- Make corrections to the following piece of code to get values of the function \(f(x)\) for 200 points on the interval \([0,1]\) :
\[
f(x)=\frac{x^{2} \cos (\pi x)}{\left(x^{3}+1\right)(x+2)}
\]
- Find out the value of the function for \(x=1\) by direct accessing the vector.
- What is the value of the function for \(x=2\) ?
- To check, plot the graph of the function \(f(x)\).


\section*{Exercise IV.}
- Create a random matrix \(\mathbf{M}\) of size \(N \times N\) containing only 0 and 1 elements.
- Compute the percentage of 0 elements in matrix.
- Compute number of 1 elements on the matrix main diagonal.

\section*{Exercise V.a}
- A proton, carrying a charge of \(Q=1.602 \cdot 10^{-19} \mathrm{C}\) with a mass of \(m=1.673 \cdot 10^{-31} \mathrm{~kg}\) enters a homogeneous magnetic and electric field in the direction of the \(z\) axis in the way that the proton follows a helical path; the initial velocity of the proton is \(v_{0}=1 \cdot 10^{7} \mathrm{~ms}^{-1}\). The intensity of the magnetic field is \(B=0.1 \mathrm{~T}\), the intensity of the electric field is \(E=1 \cdot 10^{5} \mathrm{Vm}^{-1}\)
- Velocity of the proton among the \(z\) axis is \(v=\frac{Q E}{m} t+v_{0}\),
- where \(t\) is time, traveled distance along the \(z\) axis is \(z=\frac{1}{2} \frac{Q E}{m} t^{2}+v_{0} t\),
- radius of the helix is \(r=\frac{v m}{B Q}\),
- frequency of orbiting the helix is \(f=\frac{v}{2 \pi r}\),
- the \(x\) and \(y\) coordinates of the proton are \(x=r \cos (2 \pi f t), y=r \sin (2 \pi f t)\).

\section*{Exercise V.b}
- Plot the path of the proton in space in the time interval from 0 ns to 1 ns in 1001 points using function comet \(3(x, y, z)\).
```

clear; clc; close all;

```
```

comet3(x, y, z);

```


\title{
Questions?
}

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}

September 30, 2020
Winter semester 2020/21

This document has been created as a part of BE0B17MTB course.
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Acknowledgement: Filip Kozak, Pavel Valtr.```

