

# Normalized Cuts

Shi & Malik, IEEE PAMI 2000

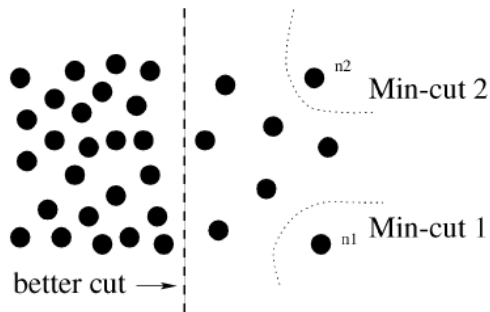
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# Unsupervised segmentation - graph partitioning

- ▶ Pixels = vertices
- ▶ Edges = neighbors
- ▶ Edge weights = similarities
- ▶ Segmentation = finding a cut (partitioning)
- ▶ Classes = graph components

# Minimum cut



$$\text{cut}(A, B) = \sum_{u \in A, v \in B} w(u, v).$$

## Normalized cut

Relative cost of the cut

$$Ncut(A, B) = \frac{cut(A, B)}{assoc(A, V)} + \frac{cut(A, B)}{assoc(B, V)},$$

$$assoc(A, V) = \sum_{u \in A, t \in V} w(u, t)$$

## Computing the normalized cut

Indicator  $x_i = 1$  if  $i \in A$ , otherwise  $x_i = -1$

Connection weight :  $d(i) = \sum_j w(i, j)$

$$\begin{aligned} Ncut(A, B) &= \frac{cut(A, B)}{assoc(A, V)} + \frac{cut(B, A)}{assoc(B, V)} \\ &= \frac{\sum_{(x_i > 0, x_j < 0)} -w_{ij} x_i x_j}{\sum_{x_i > 0} d_i} \\ &\quad + \frac{\sum_{(x_i < 0, x_j > 0)} -w_{ij} x_i x_j}{\sum_{x_i < 0} d_i}. \end{aligned}$$

## Rayleigh quotient

$$k = \frac{\sum_{x_i > 0} d_i}{\sum_i d_i} \quad b = \frac{k}{1-k}$$

$$\mathbf{y} = (\mathbf{1} + \mathbf{x}) - b(\mathbf{1} - \mathbf{x}),$$

$$\min_{\mathbf{x}} Ncut(\mathbf{x}) = \min_{\mathbf{y}} \frac{\mathbf{y}^T (\mathbf{D} - \mathbf{W}) \mathbf{y}}{\mathbf{y}^T \mathbf{D} \mathbf{y}}$$

$$\text{with } \mathbf{y}^T \mathbf{D} \mathbf{1} = 0 \text{ and } y(i) \in \{2, -2b\}$$

# Motivation

Solving

$$\min_{\mathbf{x}} Ncut(\mathbf{x}) = \min_{\mathbf{y}} \frac{\mathbf{y}^T (\mathbf{D} - \mathbf{W}) \mathbf{y}}{\mathbf{y}^T \mathbf{D} \mathbf{y}}$$

is equivalent to

$$\inf_{\mathbf{y}^T \mathbf{D} \mathbf{1} = 0} \frac{\sum_i \sum_j (\mathbf{y}(i) - \mathbf{y}(j))^2 w_{ij}}{\sum_i \mathbf{y}(i)^2 \mathbf{d}(i)}$$

spring analogy - oscillatory modes

## Eigenvalue solution

$$\min_{\mathbf{x}} Ncut(\mathbf{x}) = \min_{\mathbf{y}} \frac{\mathbf{y}^T (\mathbf{D} - \mathbf{W}) \mathbf{y}}{\mathbf{y}^T \mathbf{D} \mathbf{y}}$$

Relaxation solved by the generalized eigenvalue problem

$$(\mathbf{D} - \mathbf{W}) \mathbf{y} = \lambda \mathbf{D} \mathbf{y}.$$

$$\mathbf{D}^{-\frac{1}{2}} (\mathbf{D} - \mathbf{W}) \mathbf{D}^{-\frac{1}{2}} \mathbf{x} = \lambda \mathbf{x}$$

→

$\mathbf{y}_0 = \mathbf{1}$  is an eigenvector with  $\lambda = 0$ . 2<sup>nd</sup> largest eigenvalue →

eigenvector  $\mathbf{y}_1 =$  **solution** satisfying  $\mathbf{y}^T \mathbf{D} \mathbf{1} = 0$



# Graph construction

- ▶ Construct a weighted graph

$$w_{ij} = e^{-\frac{\|F(i) - F(j)\|_2^2}{\sigma_I^2}} * \begin{cases} e^{-\frac{\|X(i) - X(j)\|_2^2}{\sigma_X^2}} & \text{if } \|X(i) - X(j)\|_2 < r \\ 0 & \text{otherwise.} \end{cases}$$

- ▶ Solve  $(\mathbf{D} - \mathbf{W})\mathbf{y} = \lambda\mathbf{D}\mathbf{y}$ .

Complexity

$O(N)$  thanks to sparsity and low accuracy requirement

## Other pixel features

- $F(i) = I(i)$ , the intensity value, for segmenting brightness images,
- $F(i) = [v, v \cdot s \cdot \sin(h), v \cdot s \cdot \cos(h)](i)$ , where  $h, s, v$  are the HSV values, for color segmentation,
- $F(i) = [|I * f_1|, \dots, |I * f_n|](i)$ , where the  $f_i$  are DOOG filters at various scales and orientations as used in [16], in the case of texture segmentation.

Extended to spatiotemporal data, motion profiles

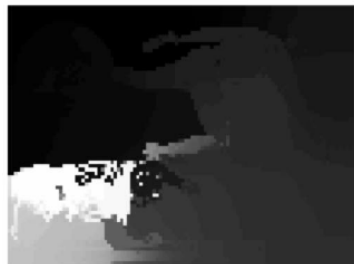
## Finalizing the segmentation

- ▶ Thresholding  $y_i$ - minimize  $Ncut$ ,  $l$  thresholds
- ▶ Partition recursively if desired
  - ▶ Stop if  $Ncut$  too high
  - ▶ Stop if eigenspectrum too smooth

## Example



## Example - eigenvectors



## Simultaneous $k$ -way cut

- ▶ Recursive 2-way cut computationally wasteful
- ▶ Use  $n$  top eigenvectors for further partitioning as labels
- ▶ Numerical inaccuracies  $\rightarrow$  use  **$k$ -means** to cluster pixel labels
- ▶ Postprocessing
  - ▶ Greedy pruning (merging)
  - ▶ Global cut at segment level - eigenvalue formulation or exhaustive
- ▶ *Not used in the presented experiments*

# Examples



## Example (2)





# Other eigenvalue formulations

Finding clumps

Finding splits



	Average association	Normalized Cut	Average cut
Discrete formulation	$\frac{\text{asso}(A,A)}{ A } + \frac{\text{asso}(B,B)}{ B }$	$\frac{\text{cut}(A,B)}{\text{asso}(A,V)} + \frac{\text{cut}(A,B)}{\text{asso}(B,V)}$ <p style="text-align: center;">or</p> $2 - \left( \frac{\text{asso}(A,A)}{\text{asso}(A,V)} + \frac{\text{asso}(B,B)}{\text{asso}(B,V)} \right)$	$\frac{\text{cut}(A,B)}{ A } + \frac{\text{cut}(A,B)}{ B }$
Continuous solution	$Wx = \bar{\lambda} x$	$(D-W)x = \bar{\lambda} D x$ <p style="text-align: center;">or</p> $Wx = (1 - \bar{\lambda})D x$	$(D-W)x = \bar{\lambda} x$

# Conclusions

- ▶ Unsupervised algorithm based on graph clustering
- ▶ Penalizes small classes
- ▶ Eigenvalue (spectral) formulation
- ▶ Lot of theory, short experimental evaluation