STRUCTURED MODEL LEARNING EXAM SS2020 (25P)

Assignment 1. (14p) Consider a linear classifier $h: \mathcal{X} \times \mathcal{X} \to \mathcal{Y} \times \mathcal{Y}$ predicting a pair of labels $(y_1, y_2) \in \mathcal{Y} \times \mathcal{Y}$ from a pair of inputs $(x_1, x_2) \in \mathcal{X} \times \mathcal{X}$ based on the rule

$$h(x_1, x_2; \boldsymbol{\theta}) = \operatorname*{argmax}_{y_1 \in \mathcal{Y}, y_2 \in \mathcal{Y}} (\langle \boldsymbol{\phi}(x_1), \boldsymbol{w}_{y_1} \rangle + \langle \boldsymbol{\phi}(x_2), \boldsymbol{w}_{y_2} \rangle + g(y_1, y_2))$$
(1)

where $\phi: \mathcal{X} \to \mathbb{R}^n$ is a feature map, $w_y \in \mathbb{R}^n$, $y \in \mathcal{Y}$, are vectors and $g: \mathcal{Y} \times \mathcal{Y} \to \mathbb{R}$ is a function. The vector $\theta \in \mathbb{R}^{n|\mathcal{Y}|+|\mathcal{Y}|^2}$ encapsulates all parameters of the classifier, i.e. vectors $\{w_y \in \mathbb{R}^n \mid y \in \mathcal{Y}\}$ and function values $\{g(y, y') \in \mathbb{R} \mid y \in \mathcal{Y}, y' \in \mathcal{Y}\}$. Let $\mathcal{T}^m = \{(x_1^j, x_2^j, y_1^j, y_2^j) \in (\mathcal{X}^2 \times \mathcal{Y}^2) \mid j = 1, \dots, m\}$ and $\mathcal{S}^l = \{(x_1^j, x_2^j, y_1^j, y_2^j) \in (\mathcal{X}^2 \times \mathcal{Y}^2) \mid j = 1, \dots, m\}$ be a set of training and testing examples, respectively, both being drawn from i.i.d. random variables with a distribution $p(x_1, x_2, y_1, y_2)$. The goal is to use \mathcal{T}^m to learn a predictor h with small expected risk $R(h) = \mathbb{E}_{(x_1, x_2, y_1, y_2) \sim p} \ell(y_1, y_2, h_1(x_1), h_2(x_2))$, where the loss $\ell(y_1, y_2, \hat{y}_1, \hat{y}_2) = |y_1 + y_2 - \hat{y}_1 - \hat{y}_2|$ measures the absolute deviation between the sum of the correct and the predicted labels.

The Structured Output SVM can learn parameters $\boldsymbol{\theta} \in \mathbb{R}^d$ of a linear classifier

$$h'(x_1, x_2) \in \operatorname*{argmax}_{(y_1, y_2) \in \mathcal{Y}^2} \langle \boldsymbol{\theta}, \boldsymbol{\psi}(x_1, x_2, y_1, y_2) \rangle, \qquad (2)$$

by solving a convex problem $\theta^* = \operatorname{argmin}_{\theta \in \mathbb{R}^d} \left(\frac{\lambda}{2} \|\theta\|^2 + \hat{R}(\theta) \right)$ where $\lambda > 0$ is a regularization constant, $\psi \colon \mathcal{X}^2 \times \mathcal{Y}^2 \to \mathbb{R}^n$ is an input-output feature map, and

$$\hat{R}(\boldsymbol{\theta}) = \frac{1}{m} \sum_{i=1}^{m} \max_{(y_1, y_2) \in \mathcal{Y}^2} \left(\ell(y_1^i, y_2^i, y_1, y_2) + \langle \boldsymbol{\theta}, \boldsymbol{\psi}(x_1^i, x_2^i, y_1, y_2) - \boldsymbol{\psi}(x_1^i, x_2^i, y_1^i, y_2^i) \rangle \right).$$

a) (3p) Define ψ and θ such that (2) and (1) are equivalent.

b) (3**p**) Write a formula for computing the sub-gradient of $\hat{R}(\boldsymbol{\theta})$.

c) (4p) Describe a variant of the Perceptron algorithm learning parameters θ such that the classifier (1) predicts all examples from \mathcal{T}^m correctly provided such parameters exist.

d) (4p) Assume that we want to estimate the expected risk R(h) of the learned predictor h by computing the test risk $R_{S^l}(h) = \frac{1}{l} \sum_{j=1}^{l} \ell(y_1^j, y_2^j, h_1(x_1^j), h_2(x_2^j))$. What is the minimal number of the test examples l we need to collect in order to guarantee that R(h) is in the interval $(R_{S^l}(h) - \varepsilon, R_{S^l}(h) + \varepsilon)$ with probability δ at least? Write l as a function of ε and δ .

Assignment 2. (3p) Consider a binary valued Gibbs random field on a bipartite graph with n + m nodes. Its distribution is given by

$$p(x,y) = \frac{1}{Z} \exp\left[a^{\mathsf{T}}x + x^{\mathsf{T}}Wy + b^{\mathsf{T}}y\right],$$

where $x \in \mathcal{B}^n$ and $y \in \mathcal{B}^m$ are the label vectors of the two node sets and $\mathcal{B} = \{\pm 1\}$. The $n \times m$ matrix W and the vectors a, b are model parameters. Explain how to learn them from a training sample of pairs (x, y).

Assignment 3. (8p) Let $x \in \mathcal{B}^n$ denote *n*-dimensional binary vectors, where $\mathcal{B} = \{\pm 1\}$. Let W be a symmetric, real valued $n \times n$ matrix. Consider the following parallel sampler on \mathcal{B}^n .

$$T(x_{t+1} \mid x_t) = \frac{1}{Z(x_t)} \exp[x_{t+1}^{\mathsf{T}} W x_t]$$

a) Find a close form expression for the normalising factor Z(x). *Hint:* You may want to use the $\cosh(x) = \frac{1}{2}(e^x + e^{-x})$ function for this.

b) Prove that the sampler has a unique limiting distribution $p^*(x)$.

c) Show that the limiting distribution is

$$p^*(x) = \alpha \prod_{i=1}^n \cosh(w_i^\mathsf{T} x).$$

where w_i , i = 1, ..., n denote the row vectors of the matrix W.

d) Check whether the sampler has the detailed balance property.