# Rational decisions under uncertainty 

## Jiří Kléma

Department of Computer Science, Czech Technical University in Prague


http://cw.felk.cvut.cz/doku.php/courses/a4b33zui/start

## Outline

- Artificial agents with deliberate and effective decision making = rational
- how to define them,
- how to cope with uncertain action results,
- decision theory + utility theory,
- concepts: prize, lottery, utility function, preference,
- rational and deliberate human decision making
- do we behave rationally when making decisions?
- money as an example of ordinal utility measure,
- multiattribute utility
- each and every state cannot be separately assessed,
- preference and utility derived from its attributes,
- value of information
- when does it pay off to make an effort to obtain a piece of information?


## Task formalization, basic terms

- agent chooses among possible states of the world $\left\{s_{1}, \ldots, s_{n}\right\}$,
- every state can be assigned a prize $\{A, B, \ldots\}$,
- agent reaches states by performing actions $\left\{a_{1}, \ldots, a_{m}\right\}$
- actions are stochastic, the outcome=state is not certain,
- action $a$ leading with prob $p$ to state $s_{1}$ with prize $A$ and with prob $p-1$ to state $s_{2}$ with prize $B$ can be defined as lottery $L_{a}=[p, A ;(1-p), B]$,
- a deterministic lottery (no random element) is equal to a prize,
- rationality: the agent's goal is to apply action resulting in the highest prize.



## Preferences

- How can we define prizes?
- in general, they do not have to be numerical,
- it suffices to define symbolic prizes with preference relations
$A \succ B \ldots A$ preferred to $B$,
$A \sim B \ldots A$ and $B$ indifferent,
$A \succeq B \ldots B$ not preferred to $A$,
- a rational agent has to implement preferences with certain constraints
- orderability: $(A \succ B) \vee(B \succ A) \vee(A \sim B)$,
- transitivity: $(A \succ B) \wedge(B \succ C) \Rightarrow(A \succ C)$,
- continuity: $A \succ B \succ C \Rightarrow \exists p[p, A ; 1-p, C] \sim B$,
- substitutability: $A \sim B \Rightarrow[p, A ; 1-p, C] \sim[p, B ; 1-p, C]$,
- monotonicity: $A \succ B \Rightarrow(p>q \Leftrightarrow[p, A ; 1-p, B] \succ[q, A ; 1-q, B])$,
- decomposability: $[p, A ; 1-p,[q, B ; 1-q, C]] \sim[p, A ;(1-p) q, B ;(1-$ $p)(1-q), C]$.


## Transitivity as necessary condition of rationality

- Violating the constraints leads to irrationality,
- example: intransitive agent can give away all his money
- assume an agent with preferences $A \succ B, B \succ C, C \succ A$,
- it is willing to pay (say) 1 cent to exchange its $C$ for somebody else's $B$,
- consequently, it pays 1 cent to exchange its $B$ for somebody else's $A$,
- finally, it exchanges $A$ for $C$ and pays 1 extra cent again,
- it owns $C$ again, but has got 3 cents less.



## Maximizing expected utility

- von Neumann-Morgenstern theorem
- given constrained preferences there exists a real-valued function $U$ s.t.

$$
U(A) \geq U(B) \Leftrightarrow A \succeq B
$$

(we keep the preferences in prizes),
$U\left(\left[p_{1}, S_{1} ; \ldots ; p_{n}, S_{n}\right]\right)=\sum_{i} p_{i} U\left(S_{i}\right)$
(lottery utility computed as expected utility of the individual outcomes),

- maximizing expected utility, the principle
- take an action (corresponding lottery) that maximizes expected utility,
- introduction of (explicit) utility is not a necessary condition of rationality
- ex.: agent has its strategy in the form of look-up table.



## From preferences towards utility function

- utility function maps prizes (and thus states) on real numbers
- the linear ordering given by preferences must be preserved,
- there is an infinite number of functions with the identical behavior of agent,
- in deterministic environments (without lotteries) it is the only condition $A \prec B \sim C \preceq D$ agrees both with $U_{1}$ and $U_{2}$, the behavior of agent does not change.

|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| $U_{1}$ | 1 | 2 | 2 | 3 |
| $U_{2}$ | -1 | 2 | 2 | 1000 |

## From preferences towards utility function

- with lotteries there is one more condition,
- behavior does not change with linear utility function transformations only,

$$
\forall k_{1}>0 \quad U_{2}(x)=k_{1} U_{1}(x)+k_{2}
$$

|  | A | B | C | D |
| :---: | :---: | :---: | :---: | :---: |
| $U_{1}$ | 1 | 2 | 2 | 3 |
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$-U_{1}$ and $U_{2}$ interchange preferences in lotteries $[0.5, A ; 0.5, B]$ and $[0.9, A ; 0.1, D]$,

- standardize by normalized utility
- best possible prize $u_{\top}=1.0$, worst possible catastrophe $u_{\perp}=0.0$,
- any intermediate prize $A$ matches $p$ set such that

$$
A \sim\left[p, u_{\top} ;(1-p), u_{\perp}\right] .
$$

## People as "rational" money-driven agents

- St. Petersburg paradox (Bernoulli, 1738)
- how much would you pay as an entry fee for the following game?
* adversary repeatedly tosses a (standard) coin until the first head, * the number of coin tosses $n \rightarrow$ your gain $2^{n}$ Kč $\rightarrow$ game over,


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* the number of coin tosses $n \rightarrow$ your gain $2^{n}$ Kč $\rightarrow$ game over,
- provided that money directly represent utility function, you shall be willing to pay an arbitrary finite fee
* let us apply von Neumann-Morgenstern theorem

$$
\begin{aligned}
U(p b g h) & =U\left(\left[p\left(h_{1}\right), U\left(h_{1}\right) ; p\left(h_{2}\right), U\left(h_{2}\right) ; \ldots\right]\right)= \\
& =\sum_{i=1}^{\infty} \frac{1}{2^{i}} 2^{i}=1+1+\cdots=\infty
\end{aligned}
$$

- this conclusion does not seem to be truly rational
* Bernoulli solved the paradox by log transform of money utility

$$
\begin{aligned}
& U(k)=\log _{2} k \\
& U(p b g h)=\sum_{i=1}^{\infty} \frac{1}{2^{i}} \log _{2} 2^{i}=\frac{1}{2}+\frac{2}{4}+\frac{3}{8}+\cdots=2
\end{aligned}
$$

* reverse transformation gives the real game fee: $2=\log _{2} k \Rightarrow k=4$ Kč.


## People as "rational" money-driven agents

- Tversky and Kahneman experiment (1982)
- choose one of the lotteries $L_{1}$ and $L_{2}$, then one of the lotteries $L_{3}$ and $L_{4}$

| Choice 1 | Choice 2 |
| :--- | :--- |
| $L_{1}=[0.8,80000 K c ; 0.2,0]$ | $L_{3}=[0.2,80000 K c ; 0.8,0]$ |
| $L_{2}=[1,60000 K c]$ | $L_{4}=[0.25,60000 K c ; 0.75,0]$ |

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- most people prefer lottery $L_{2}$ to $L_{1}$ and $L_{3}$ to $L_{4}$
* does not seem rational, provided that $U(0 K c)=0$ it holds choice 1: $0.8 U(80000 K c)<U(60000 K c)$, choice 2: $0.8 U(80000 K c)>U(60000 K c)$,
* there is no utility function consistent with both choices,
- possible explanations
* people are irrational,
* the analysis disregards regret when loosing a very likely reward ad $L_{2}$,
* that is why people avoid/take risk in probable/unlikely events.


## People as "rational" money-driven agents

- money is not the direct utility function
- people often do not maximize monetary expected utility,

$$
U\left(\left[p_{1}, S_{1} ; \ldots ; p_{n}, S_{n}\right]\right) \neq \sum_{i} p_{i} U\left(S_{i}\right)
$$

- and tend to avoid the risk, i.e., lotteries,

$$
U\left(\left[p_{1}, S_{1} ; \ldots ; p_{n}, S_{n}\right]\right)<\sum_{i} p_{i} U\left(S_{i}\right)
$$

- utility curve non-linearly transforms money to utility
- we search for probability $p$, for which a given person does not distinguish prize $x$ and lottery $[p, \$ M ;(1-p), \$ 0], \$ M$ is large




## Multiattribute utility functions

- Often we cannot assign a prize to every state
- too many states or infinite state space,
- states usually described by features (airport locality selection - safety, noise level, land prize),
- utility function has several parameters then
$-U\left(X_{1}, \ldots, X_{n}\right)$ (parameters resp. attributes instead of state),
$-n$ attributes with $m$ distinct values define $m^{n}$ states,
- utility function can be simplified by assumption of preference regularity
* preference monotonicity when changing single attribute

$$
x \geq y \Rightarrow U\left(X_{1}, \ldots, X_{i}=x, \ldots, X_{n}\right) \geq U\left(X_{1}, \ldots, X_{i}=y, \ldots, X_{n}\right)
$$

* relationships of independence among attributes wrt preferences state defs: $A \sim\left(x_{1}, y_{1}\right), B \sim\left(x_{2}, y_{1}\right), C \sim\left(x_{1}, y_{2}\right), D \sim\left(x_{2}, y_{2}\right)$ preference independence: $(A \succ B \Rightarrow C \succ D) \wedge(A \succ C \Rightarrow B \succ D)$
- preference regularities correspond to a simplified utility function $* U\left(x_{1}, \ldots, x_{n}\right)=f\left[f_{1}\left(x_{1}\right), \ldots, f_{n}\left(x_{n}\right)\right], f$ is simple, e.g., addition.


## Strict dominance

- assumption: $U$ monotonously increasing in all attributes,
- choice $B$ strictly dominates choice $A$ iff
$-\forall i X_{i}(B) \geq X_{i}(A) \Rightarrow f_{i}\left(X_{i}(B)\right) \geq f_{i}\left(X_{i}(A)\right) \Rightarrow U(B) \geq U(A)$
- one airport location safer, less noisy with cheaper land than others,
- rarely applicable in practice
- utility further decreased by uncertainty in estimation of attribute values.


Deterministic attributes


Uncertain attributes

## Stochastic dominance

- do not compare the worst possible attribute value in the first state with the best possible in the second,
- rather compare cumulative distribution functions of the attributes,
- distribution $p_{1}$ stochastically dominates distribution $p_{2}$ if

$$
-\forall t \int_{-\infty}^{t} p_{1}(x) d x \leq \int_{-\infty}^{t} p_{2}(x) d x
$$

- for $U$ monotonously increasing with $x$ it necessarily holds

$$
-\int_{-\infty}^{\infty} p_{1}(x) U(x) d x \geq \int_{-\infty}^{\infty} p_{2}(x) U(x) d x
$$

- for multiple attributes require stochastic dominance of a state in all attributes,


## Stochastic dominance - example

- S1: the airport cost at location $13.7 \pm 0.4 \mathrm{mld}$,
- S2: the airport cost at location $24.0 \pm 0.35 \mathrm{ml}$,
- choose S1.




## Value of information

- Agent rarely has complete information at its disposal
- what questions shall it ask?
- question $\rightarrow$ information with both value and costs (for test, time of an expert, etc.),
- agent sorts questions by the difference between value and costs,
- negatively valued questions not asked, actions taken based on the current information,
- agent typically myopic - greedy decisions, disregards interactions between questions.
- How to compute the value of information?
- has the given piece of information potential to change the current plan?
- can be a modified plan significantly better than the current one?


## Value of information - qualitative distinctions

- 3 examples: actions $A_{1}$ and $A_{2}$, their expected utility $U_{1}$ and $U_{2}$,
- the utility distributions known a priori, $E_{j}$ will bring the precise action utility,
(a) choice is obvious, information worth little,
(b) choice is unclear, information worth a lot,
(c) choice is unclear, information worth little.



## Value of information - general description

- current evidence $E$, current best action $\alpha$ possible outcomes of the action $S_{i}$, possible future observation $E_{j}$
- expected utility without knowing the value of $E_{j}$ :
$E U(\alpha \mid E)=\max _{a} \sum_{i} U\left(S_{i}\right) P\left(S_{i} \mid E, a\right)$
- if we knew that $E_{j}=e_{j k}$, then we would choose a different action $\alpha_{e_{j k}}$
- expected utility when knowing the value of $E_{j}$ :

$$
E U\left(\alpha_{e_{j k}} \mid E, E_{j}=e_{j k}\right)=\max _{a} \sum_{i} U\left(S_{i}\right) P\left(S_{i} \mid E, a, E_{j}=e_{j k}\right)
$$

- when assessing the value of information, the value of $E_{j}$ is unknown expected utility must aggregate over all possible values of $E_{j}$ $V P I_{E}\left(E_{j}\right)=\left(\sum_{k} P\left(E_{j}=e_{j k} \mid E\right) E U\left(\alpha_{e_{j k}} \mid E, E_{j}=e_{j k}\right)\right)-E U(\alpha \mid E)$
- $\mathrm{VPI}=$ value of perfect information
- exact evidence about $E_{j}$ can be obtained.


## Value of information - characteristics

- VPI is always non-negative

$$
\forall j, E \quad V P I_{E}\left(E_{j}\right) \geq 0
$$

- even though it can lead into a state with a lower utility eventually,
- VPI is not additive

$$
V P I_{E}\left(E_{j}, E_{k}\right) \neq V P I_{E}\left(E_{j}\right)+V P I_{E}\left(E_{k}\right)
$$

- VPI is order-independent

$$
V P I_{E}\left(E_{j}, E_{k}\right)=V P I_{E}\left(E_{j}\right)+V P I_{E, E_{j}}\left(E_{k}\right)=V P I_{E}\left(E_{k}\right)+V P I_{E, E_{k}}\left(E_{j}\right)
$$

- the agent inquires information if: $\exists E_{j} V P I_{E}\left(E_{j}\right)>\operatorname{Cost}\left(E_{j}\right)$,
- consequence
- evidence gathering becomes a sequential decision problem.


## Value of information - investment example

:: There are three types of investment opportunity (I): stocks (s), funds (f) and state bonds (b). Investment profit depends on whether markets (M) grow ( $\uparrow$ ), stay at the same level (resp. grow with inflation, $\rightarrow$ ) or fall down $(\downarrow)$. Based on the values in table below compute the value of information about future market change.

| $M$ | $\operatorname{Pr}(M)$ | $\mathrm{U}(\mathrm{s}, \mathrm{M})$ | $\mathrm{U}(\mathrm{f}, \mathrm{M})$ | $\mathrm{U}(\mathrm{b}, \mathrm{M})$ |
| :---: | :---: | :---: | :---: | :---: |
| $\uparrow$ | 0.5 | 1500 | 900 | 500 |
| $\rightarrow$ | 0.3 | 300 | 600 | 500 |
| $\downarrow$ | 0.2 | -800 | -200 | 500 |

## Value of information - investment example

$$
\begin{aligned}
& E U(\alpha \mid\{ \})= \max _{I \in\{s, f, b\}} \sum_{M \in\{\uparrow, \rightarrow, \downarrow\}} U(I, M) \operatorname{Pr}(M)= \\
&= \max (.5 \times 1500+.3 \times 300-0.2 \times 800, \\
&=.5 \times 900+.3 \times 600-0.2 \times 200,500)= \\
&=\max (680,590,500)=680
\end{aligned}
$$

$$
E U\left(\alpha_{\uparrow} \mid\{\uparrow\}\right)=\max _{I \in\{s, f, b\}} U(I, \uparrow)=1500\left(E U\left(\alpha_{\rightarrow} \mid\{\rightarrow\}\right)=600, E U\left(\alpha_{\downarrow} \mid\{\downarrow\}\right)=500\right)
$$

$$
V P I_{\{ \}}(M)=\left[\sum_{M \in\{\uparrow, \rightarrow, \downarrow\}} \operatorname{Pr}(M) E U\left(\alpha_{M} \mid M\right)\right]-E U(\alpha \mid\{ \})=
$$

$$
=.5 \times 1500+.3 \times 600+0.2 \times 500-680=1030-680=350
$$

## Summary

- rational agent takes action leading to the best expected result,
- its decisions can be based on three types of theory
- probability - how to cope with observations in uncertain world,
- utility - how to describe what to strive for, how to formulate goal,
- decision making - actions to take based on stochastic model and goals,
- how to define utility function, what it is good for
- complex worlds, states defined by attribute vectors, dominance decisions,
- pieces of information to prefer, when to ask for them,
- people are just "approximately" rational
- in complex worlds we must employ instincts and heuristics * automatic system that decides quickly, but imprecisely, * reflexive human system approaches the ideal view of rationality,
- AI - both ideally rational agents and agents behaving like people.


## Recommended reading, lecture resources

:: Reading

- Russell, Norvig: AI: A Modern Approach, Rational Decisions
- chapter 16, http://aima.eecs.berkeley.edu/slides-pdf/chapter16.pdf
- book online on Google books (limited access): http://books.google.com/books?id=8jZBksh-bUMC.


## Experimental ZUI utility curve

- For each $x$ adjust $p$ such that
- half the students chooses lottery $[p, 200000 K c ; 1-p, 0]$, half prefers $x$,
- what is the relationship between the curve and risk taking?



## Utility and insurance

- On the concave curve the rational motivation for insurance can be shown.

> room for insurance company profit


