

Recognizing and localizing objects, visual odometry

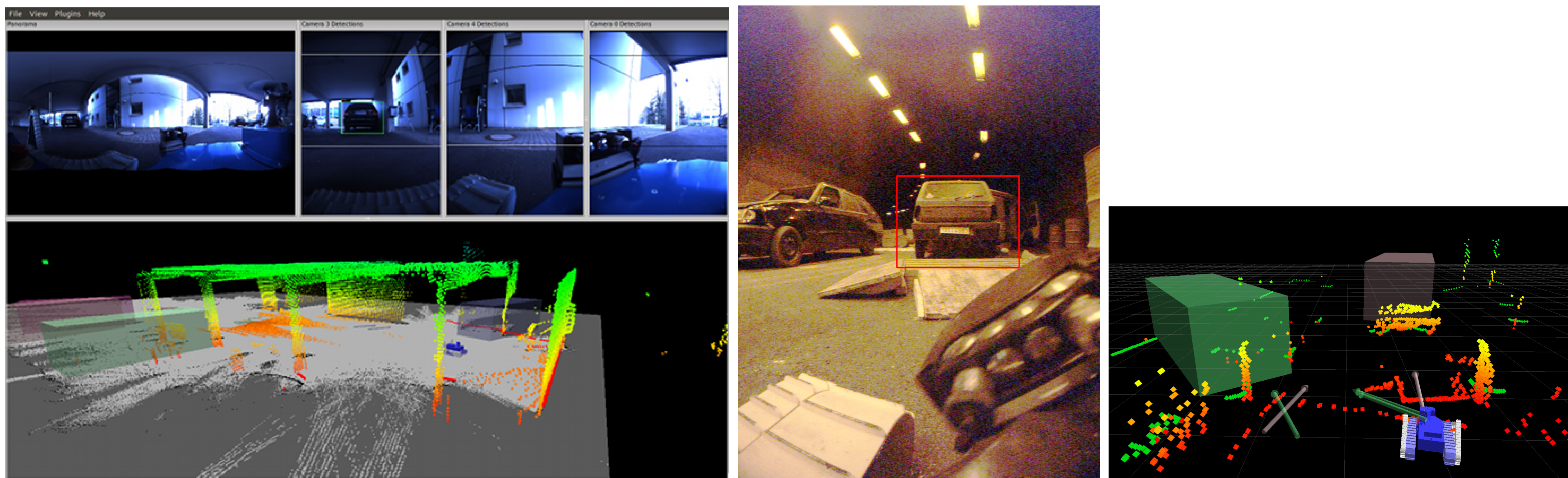
WP2: Visuo-conceptual modeling for situation awareness



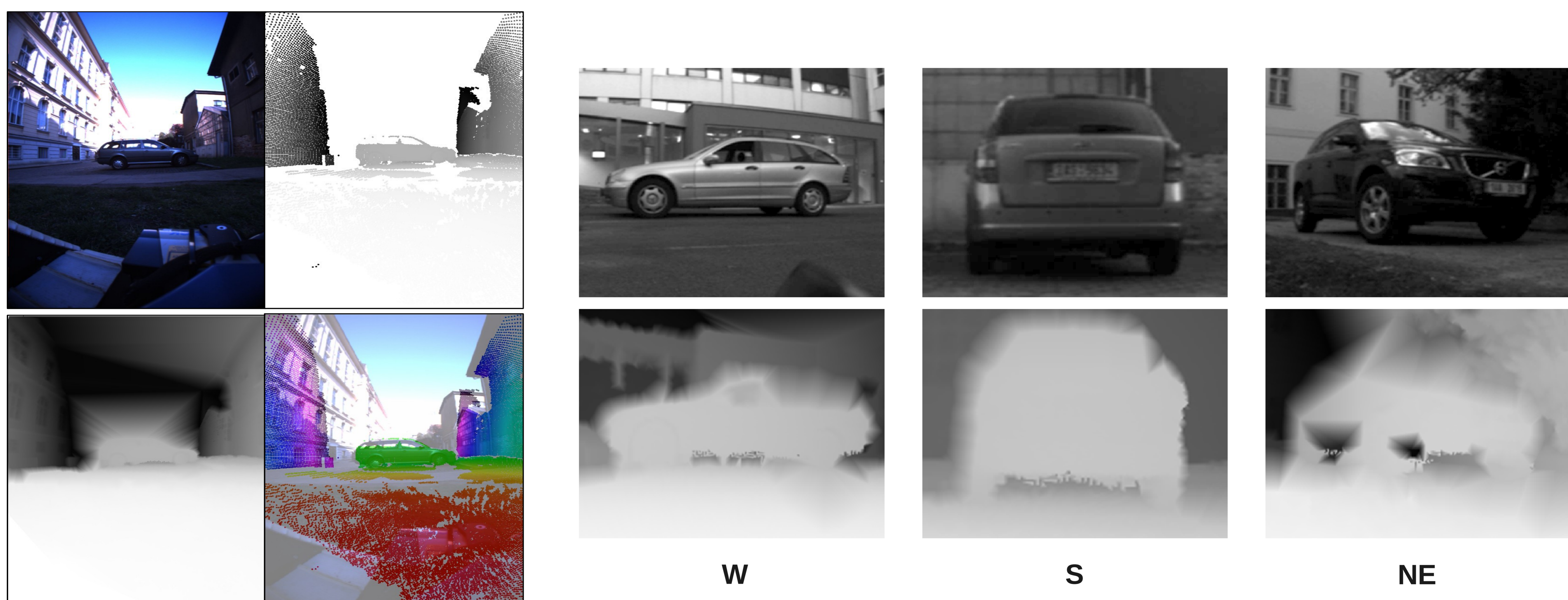
Natural Human-Robot
Cooperation in Dynamic
Environments

Project NIFTi, <http://www.nifti.eu>
CTU, FEE, Dept. of Cybernetics,
Center for Machine Perception
<http://cmp.felk.cvut.cz>

Detecting and locating cars visually



Finding cars by combining 3D and vision



Visual odometry

