

14. Computing marginal probabilities for GRFs

Consider a GRF for pairs (x, s) on a graph (V, E) , where $x: V \rightarrow \mathcal{F}$ is a field of features and $s: V \rightarrow \mathcal{K}$ is a field of hidden variables

$$p_u(x, s) = \frac{1}{Z(u)} \exp \left[\sum_{i \in V} u_i(x_i, s_i) + \sum_{ij \in E} u_{ij}(s_i, s_j) \right].$$

Its partition function is

$$Z(u) = \sum_{x \in \mathcal{F}^V} \sum_{s \in \mathcal{K}^V} \exp \left[\sum_{i \in V} u_i(x_i, s_i) + \sum_{ij \in E} u_{ij}(s_i, s_j) \right]$$

Computing its marginal probabilities on vertices and edges like

$$p_u(s_i), p_u(s_i | x), p_u(s_i, s_j), p_u(s_i, s_j | x)$$

for $i, j \in V$, $ij \in E$ is needed for

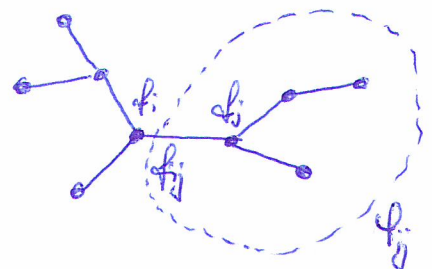
- (1) Inference with locally additive loss functions (e.g. Hamming distance) \Rightarrow optimal decision is based on $p(s_i | x)$
- (2) Learning model parameters u_i, u_{ij} . This requires to compute node and edge marginals from u -s and vice versa (see next section)

Computing the partition function and marginal prob's for general GRFs is NP-hard. We have to rely on approximation algorithms.

A. Belief propagation

Recall Sec. 10, computing marginals of a Markov model on a tree:

$$\begin{aligned} p(s) &= \frac{1}{Z} \prod_{i \in V} \phi_i(s_i) \prod_{ij \in E} \phi_{ij}(s_i, s_j) \stackrel{!}{=} \\ &= \prod_{i \in V} p(s_i) \prod_{ij \in E} \frac{p(s_i, s_j)}{p(s_i)p(s_j)} \end{aligned}$$



Hence,

$$p(s_i) \propto f_i(s_i) \prod_{j \in \mathcal{N}_i} \psi_{ij}(s_i)$$

$$p(s_i, s_j) \propto f_i(s_i) f_{ij}(s_i, s_j) f_j(s_j) \prod_{l \in \mathcal{N}_i \setminus j} \psi_{il}(s_i) \prod_{m \in \mathcal{N}_j \setminus i} \psi_{jm}(s_j)$$

from which follows that

$$\frac{p(s_i, s_j)}{p(s_i)p(s_j)} = \frac{f_{ij}(s_i, s_j)}{\psi_{ij}(s_i) \psi_{ji}(s_j)}$$

- recall that ψ -s are defined on oriented edges
- the above formula is an equivalent transformation in the $(+, x)$ -domain

The recursive definition of the ψ -s is

$$\psi_{ij}(s_i) = \sum_{s_j \in \mathcal{K}} f_{ij}(s_i, s_j) f_j(s_j) \prod_{l \in \mathcal{N}_j \setminus i} \psi_{jl}(s_j)$$

Belief propagation for random fields on general graphs (aka message passing):

- (1) repeatedly recompute ψ -s according ~~the~~ to the formula above until (hopefully) a fixpoint ψ^* is reached

- (2) estimate marginals from

$$p(s_i) \propto f_i(s_i) \prod_{j \in \mathcal{N}_i} \psi_{ij}^*(s_i)$$

$$p(s_i, s_j) \propto f_{ij}(s_i, s_j) \frac{p(s_i)p(s_j)}{\psi_{ij}^*(s_i) \psi_{ji}^*(s_j)}$$

Remarks 1

- (1) Quite often BP gives reasonable estimates for unary marginals. However, it inherently fails to estimate pairwise marginals
- (2) In the log-domain (replacing $(+, \times)$ by $(\min, +)$) this gives an approximation algorithm for solving $(\min, +)$ -problems

B. Sampling

Let $S = \{S_i \mid i \in V\}$ be a K -valued random field with joint p.d. $p(s)$ and let $F: K^V \rightarrow \mathbb{R}$ be a random variable. How can we estimate its expectation

$$\mathbb{E}_p(F) = \sum_{s \in K^V} p(s) F(s)$$

by sampling?

- generate an i.i.d. sample $\{s^j \in K^V \mid j=1, \dots, \ell\}$ of realisations from $p(s)$
- estimate the expectation by

$$\mathbb{E}_p(F) \approx \frac{1}{\ell} \sum_{j=1}^{\ell} F(s^j)$$

How to sample from $p(s)$? Theorem 1, Sec. 1 \Rightarrow design a homogeneous Markov chain with transition probability matrix $T(s|s')$, $s, s' \in K^V$ s.t.

- (a) the chain is irreducible and a-periodic
- (b) its stationary p.d. is $p(s)$

In practice:

- Design a set of simple (sparse) transition prob. matrices B_m , $m \in M$ s.t. $p(s)$ is stationary for all of them
- Compose T by

$$T = \prod_{m \in M} B_m \quad \text{or} \quad T = \sum_{m \in M} d_m B_m \quad (d_m \geq 0, \sum_{m \in M} d_m = 1)$$

- prove that T is irreducible and a-periodic.

Gibbs sampler (for GRFs)

Design B_i , $i \in V$ by

$$B_i(s|s') = \begin{cases} 0 & \text{if } s_{V \setminus i} \neq s'_{V \setminus i} \\ p(s_i | s'_{V \setminus i}) \stackrel{!}{=} p(s_i | s'_{V \setminus i}) & \text{otherwise} \end{cases}$$

Stationarity of $p(s)$

$$\begin{aligned} \sum_{s' \in K^V} B_i(s|s') p(s') &= \sum_{k \in K} p(s_i | s_{V \setminus i} = k) p(s'_{V \setminus i} = k) \\ &= p(s_i | s_{V \setminus i}) p(s_{V \setminus i}) = p(s) \end{aligned}$$

It is easy to see that $T = \prod_{i \in V} B_i$ and $T = \sum_{i \in V} d_i B_i$

are irreducible and a-periodic if $p(s)$ is strictly positive.

Remarks 2

- Gibbs sampler is easy to implement
- Gibbs samplers are very slow: long "burn-in time" and "slow mixing".

C. Mean field approximation

If only unary marginals needed \Rightarrow approximate $p(s)$ by an independent distribution

$$q(s) = \prod_{i \in V} q_i(s_i)$$

with smallest KL-divergence from p

$$D_{KL}(q||p) = \sum_{s \in K^V} q(s) \log \frac{q(s)}{p(s)} \rightarrow \min_q$$

For a GRF on a graph this reads

$$\begin{aligned} & \sum_{i \in V} \sum_{s_i \in K} q_i(s_i) \log q_i(s_i) - \sum_{i \in V} \sum_{s_i \in K} q_i(s_i) u_i(s_i) - \\ & - \sum_{j \in E} \sum_{s_i, s_j \in K} q_i(s_i) q_j(s_j) u_{ij}(s_i, s_j) \rightarrow \min_{q \geq 0} \end{aligned}$$

$$\text{s.t. } \sum_{s_i} q_i(s_i) = 1 \quad \forall i \in V$$

This can be solved approximately by block-coordinate descent.