

Statistical Machine Learning (BE4M33SSU)

Lecture 7: Generative learning, EM-Algorithm

Czech Technical University in Prague

- ◆ Generative vs. Discriminative Learning
- ◆ Maximum Likelihood Estimator, consistency
- ◆ Expectation Maximisation Algorithm

1. Generative vs. Discriminative Learning

Generative learning:

- ◆ Model the **joint** probability distribution $p_{\theta}(x, y)$ for features $x \in \mathcal{X}$ and hidden states $y \in \mathcal{Y}$ up to unknown parameter(s) $\theta \in \Theta$.
- ◆ Optimal prediction strategy (if true parameter θ_0 is known):

$$h(x) \in \arg \min_{y \in \mathcal{Y}} \sum_{y' \in \mathcal{Y}} p_{\theta_0}(y' | x) \ell(y', y)$$

- ◆ Learning: if $\theta_0 \in \Theta$ is not known, estimate it from training data $\mathcal{T}^m = \{(x^j, y^j) \in \mathcal{X} \times \mathcal{Y} \mid j = 1, \dots, m\}$ e.g. by maximum likelihood estimator (MLE)

$$\theta^* \in \arg \max_{\theta \in \Theta} \sum_{i=1}^m \log p_{\theta}(x^i, y^i)$$

1. Generative vs. Discriminative Learning

Discriminative learning(1):

- ◆ Model only the **conditional** distributions $p_{\theta}(y | x)$, $\theta \in \Theta$.
- ◆ Optimal prediction strategy (if true parameter θ_0 is known): as above
- ◆ Learning: if $\theta_0 \in \Theta$ is not known, estimate it by maximising the conditional likelihood of the training data \mathcal{T}^m .

$$\theta^* \in \arg \max_{\theta \in \Theta} \sum_{i=1}^m \log p_{\theta}(y^i | x^i)$$

Discriminative learning(2):

- ◆ Model the class of prediction strategies $h \in \mathcal{H}$.
- ◆ Optimal prediction strategy (if $p(x, y)$ is known):

$$h_0(x) = \arg \min_{y' \in \mathcal{Y}} \sum_{y' \in \mathcal{Y}} p(y' | x) \ell(y', y)$$

- ◆ Estimate the optimal strategy $h^* \in \mathcal{H}$ by minimising the empirical risk on the training data

$$h^* \in \arg \min_{h \in \mathcal{H}} \frac{1}{m} \sum_{j=1}^m \ell(y^j, h(x^j))$$

1. Generative vs. Discriminative Learning

Example (Gaussian Discriminative Analysis, Logistic Regression, Linear Classifier)

$x \in \mathbb{R}^n$, $y \in \{0, 1\}$ with $y \sim \text{Bern}(\alpha)$ and $x | y \sim \mathcal{N}(\mu_y, V)$, i.e.

$$p(y) = \alpha^y (1 - \alpha)^{1-y}$$

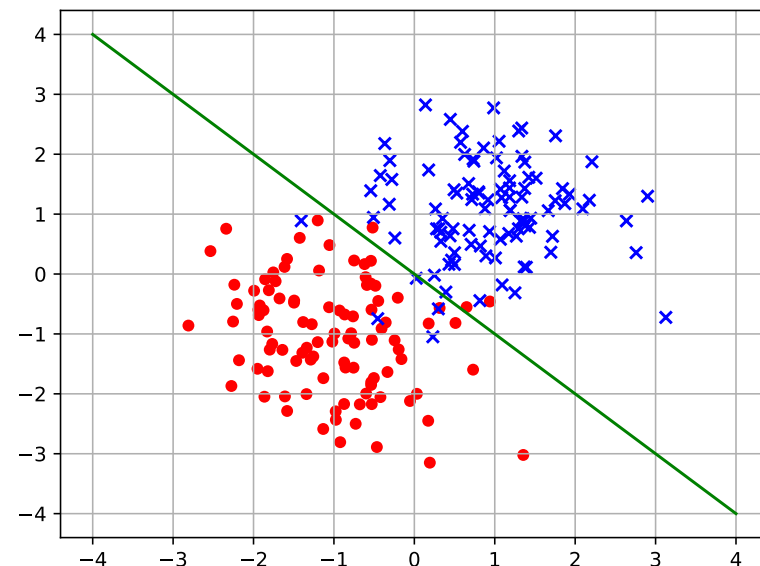
$$p(x | y) = \frac{1}{(2\pi)^{n/2} |V|^{1/2}} \exp \left[-\frac{1}{2} (x - \mu_y) \cdot V^{-1} \cdot (x - \mu_y) \right]$$

Generative learning: Denote $I_1 = \{j | y^j = 1\}$ and I_0 correspondingly. ML estimator for training data $\mathcal{T}^m = \{(x^j, y^j) | j = 1, \dots, m\}$ gives

$$\alpha^* = \frac{1}{m} |I_1|$$

$$\mu_0^* = \frac{1}{|I_0|} \sum_{j \in I_0} x^j, \quad \mu_1^* = \frac{1}{|I_1|} \sum_{j \in I_1} x^j$$

$$V^* = \frac{1}{m} \sum_{j=1}^m (x^j - \mu_{y^j}) \otimes (x^j - \mu_{y^j})$$



1. Generative vs. Discriminative Learning

Discriminative learning(1): Notice that the posterior conditional probabilities can be expressed as

$$p(y | x) = \frac{\exp[y(\langle w, x \rangle + b)]}{1 + \exp[\langle w, x \rangle + b]},$$

i.e. a logistic regression, where w and b are some functions of α , μ_0 , μ_1 and V .

Estimate w and b by maximising the conditional likelihood on training data

$$(w^*, b^*) \in \arg \max_{w, b} \left\{ \sum_{j \in I_1} (\langle w, x^j \rangle + b) - \sum_{i=1}^m \log(1 + \exp(\langle w, x^j \rangle + b)) \right\}$$

The objective is concave in w and b . Its global optimum can be found by gradient ascent.

Discriminative learning(2): The optimal inference rule is a linear classifier. Learn it by minimising the empirical risk. \Rightarrow SVM

1. Generative vs. Discriminative Learning

Question: The three methods will provide different decision boundaries when trained on the same dataset. Which one is better?

General answer:

- ◆ Generative learning makes stronger assumptions and is more data efficient when the assumptions are (nearly) correct.
- ◆ Discriminative learning makes weaker assumptions and is less data efficient but significantly more robust to deviations from model assumptions.

2. Consistency of the Maximum Likelihood estimator

Let $\mathcal{T}^m = \{z^j \mid j = 1, \dots, m\}$ be i.i.d. generated from $p_{\theta_0}(z)$, with $\theta_0 \in \Theta$ unknown.

Which conditions ensure consistency of the MLE $\theta^* = \arg \max_{\theta \in \Theta} \log p_{\theta}(\mathcal{T}^m)$?

$$\mathbb{P}_{\theta_0}(\|\theta_0 - \theta^*(\mathcal{T}^m)\| > \epsilon) \xrightarrow{m \rightarrow \infty} 0$$

Denote log-likelihood of training data $L(\theta, \mathcal{T}^m) = \frac{1}{m} \sum_{i=1}^m \log p_{\theta}(z^i)$

and expected log-likelihood $L(\theta) = \mathbb{E}_{\theta_0}(L(\theta, \mathcal{T}^m)) = \sum_{z \in \mathcal{Z}} p_{\theta_0}(z) \log p_{\theta}(z)$

Consider $L(\theta, \mathcal{T}^m) = L(\theta) + [L(\theta, \mathcal{T}^m) - L(\theta)]$

- ◆ The model should be identifiable, i.e. $\theta_0 = \arg \max_{\theta \in \Theta} L(\theta)$
- ◆ Ensure that the Uniform Law of Large Numbers (ULLN) holds, i.e.

$$\mathbb{P}_{\theta_0}(\sup_{\theta \in \Theta} |L(\theta, \mathcal{T}^m) - L(\theta)| > \epsilon) \xrightarrow{m \rightarrow \infty} 0$$

for any $\epsilon > 0$.

2. Consistency of the Maximum Likelihood estimator

Identifiability of the model θ_0 is easy to prove if $p_{\theta_0}(z) \neq p_{\theta}(z)$ holds $\forall \theta \neq \theta_0$.

Let $p(z), q(z)$ be two probability distributions s.t. $p \neq q$. Then

$$\sum_{z \in \mathcal{Z}} p(z) \log p(z) > \sum_{z \in \mathcal{Z}} p(z) \log q(z)$$

follows from strict concavity of the function $\log(x)$:

$$-D_{KL}(p \parallel q) = \sum_{z \in \mathcal{Z}} p(z) \log \frac{q(z)}{p(z)} < \log \sum_{z \in \mathcal{Z}} \frac{q(z)p(z)}{p(z)} = \log 1 = 0$$

ULLN can be ensured e.g. by requiring that

- ◆ $L(\theta, z)$ is continuous in θ and $\Theta \subset \mathbb{R}^k$ is compact.
- ◆ $L(\theta, z)$ can be upper bounded: $\log p_{\theta}(z) \leq d(z) \forall \theta$ with $\mathbb{E}_{\theta_0} d(z) < \infty$.

3. The Expectation Maximisation Algorithm

Unsupervised generative learning:

- ◆ The joint p.d. $p_\theta(x, y)$, $\theta \in \Theta$ is known up to the parameter $\theta \in \Theta$,
- ◆ given training data $\mathcal{T}^m = \{x^j \in \mathcal{X} \mid i = 1, 2, \dots, m\}$ i.i.d. generated from p_{θ_0} .

How shall we implement the MLE

$$\theta^*(\mathcal{T}^m) = \arg \max_{\theta \in \Theta} \frac{1}{m} \sum_{x \in \mathcal{T}^m} \log p_\theta(x) = \arg \max_{\theta \in \Theta} \frac{1}{m} \sum_{x \in \mathcal{T}^m} \log \sum_{y \in \mathcal{Y}} p_\theta(x, y)$$

- ◆ If θ is a single parameter or a vector of homogeneous parameters \Rightarrow maximise the log-likelihood directly.
- ◆ If θ is a collection of heterogeneous parameters \Rightarrow apply the **Expectation Maximisation Algorithm** (Schlesinger, 1968, Sundberg, 1974, Dempster, Laird, and Rubin, 1977)

3. The Expectation Maximisation Algorithm

EM approach:

- ◆ Introduce auxiliary variables $\alpha_x(y) \geq 0$, for each $x \in \mathcal{T}^m$, s.t. $\sum_{y \in \mathcal{Y}} \alpha_x(y) = 1$
- ◆ Construct a lower bound of the log-likelihood $L(\theta, \mathcal{T}^m) \geq L_B(\theta, \alpha, \mathcal{T}^m)$
- ◆ Maximise this lower bound by block-wise coordinate ascent.

Construct the bound:

$$L(\theta, \mathcal{T}^m) = \frac{1}{m} \sum_{x \in \mathcal{T}^m} \log \sum_{y \in \mathcal{Y}} p_\theta(x, y) = \frac{1}{m} \sum_{x \in \mathcal{T}^m} \log \sum_{y \in \mathcal{Y}} \frac{\alpha_x(y)}{\alpha_x(y)} p_\theta(x, y) \geq$$
$$L_B(\theta, \alpha, \mathcal{T}^m) = \frac{1}{m} \sum_{x \in \mathcal{T}^m} \sum_{y \in \mathcal{Y}} \alpha_x(y) \log p_\theta(x, y) - \frac{1}{m} \sum_{x \in \mathcal{T}^m} \sum_{y \in \mathcal{Y}} \alpha_x(y) \log \alpha_x(y)$$

3. The Expectation Maximisation Algorithm

Maximise $L_B(\theta, \alpha, \mathcal{T}^m)$ by block-coordinate ascent:

Start with some $\theta^{(0)}$ and iterate

E-step Fix the current $\theta^{(t)}$, maximise $L_B(\theta^{(t)}, \alpha, \mathcal{T}^m)$ w.r.t. α -s. This gives

$$\alpha_x^{(t)}(y) = p_{\theta^{(t)}}(y | x).$$

M-step Fix the current $\alpha^{(t)}$ and maximise $L_B(\theta, \alpha^{(t)}, \mathcal{T}^m)$ w.r.t. θ .

$$\theta^{(t+1)} = \arg \max_{\theta \in \Theta} \frac{1}{m} \sum_{x \in \mathcal{T}^m} \sum_{y \in \mathcal{Y}} \alpha_x^{(t)}(y) \log p_{\theta}(x, y)$$

This is equivalent to solving the MLE for annotated training data.

Claims:

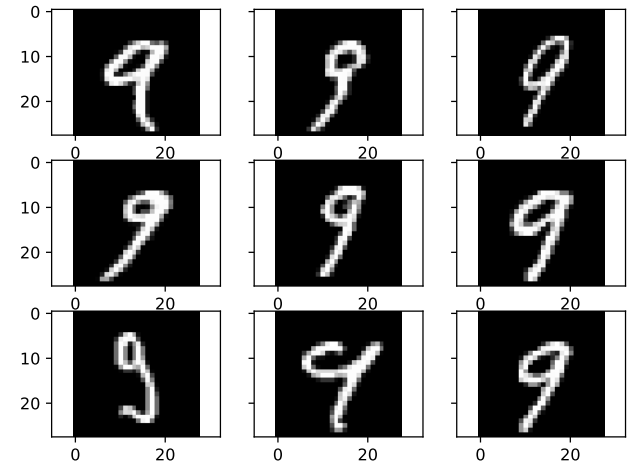
- ◆ The bound is tight if $\alpha_x(y) = p_{\theta}(y | x)$,
- ◆ The sequence of likelihood values $L(\theta^{(t)}, \mathcal{T}^m)$, $t = 1, 2, \dots$ is increasing, and the sequence $\alpha^{(t)}$, $t = 1, 2, \dots$ is convergent (under mild assumptions).

3. The Expectation Maximisation Algorithm

Example: Latent mode model (mixture) for images of digits

- ◆ $x = \{x_i \mid i \in D\}$ image on the pixel domain $D \in \mathbb{Z}^2$,
- ◆ $x_i \in \mathcal{B} = \{0, 1, 2, \dots, 255\}$
- ◆ $k \in K$ latent variable (mode indicator),
- ◆ joint distribution - Naive Bayes model

$$p(x, k) = p(k) \prod_{i \in D} p(x_i \mid k)$$



Learning problem: Given i.i.d. training data $\mathcal{T}^m = \{x^j \mid j = 1, 2, \dots, m\}$, estimate the mode probabilities $p(k)$ and the conditional probabilities $p(x_i \mid k)$, $\forall x_i \in \mathcal{B}$, $k \in K$ and $i \in D$.

3. The Expectation Maximisation Algorithm

Applying the EM algorithm: Start with some model $p^{(0)}(k)$, $p^{(0)}(x_i | k)$ and iterate the following steps until convergence.

E-step Given the current model estimate $p^{(t)}(k)$, $p^{(t)}(x_i | k)$, compute the posterior mode probabilities for each image x in the training data \mathcal{T}^m

$$\alpha_x^{(t)}(k) = p^{(t)}(k | x) = \frac{p^{(t)}(k) \prod_{i \in D} p^{(t)}(x_i | k)}{\sum_{k'} p^{(t)}(k') \prod_{i \in D} p^{(t)}(x_i | k')}.$$

M-step Re-estimate the model by solving

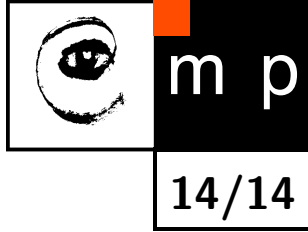
$$\sum_{x \in \mathcal{T}^m} \sum_{k \in K} \alpha_x^{(t)}(k) \left[\log p(k) + \sum_{i \in D} \log p(x_i | k) \right] \rightarrow \max_p$$

This gives

$$p^{(t+1)}(k) = \frac{1}{m} \sum_{x \in \mathcal{T}^m} \alpha_x^{(t)}(k)$$

$$p^{(t+1)}(x_i = b | k) = \frac{\sum_{x \in \mathcal{T}^m: x_i=b} \alpha_x^{(t)}(k)}{\sum_{x \in \mathcal{T}^m} \alpha_x^{(t)}(k)}$$

3. The Expectation Maximisation Algorithm



Additional reading:

Schlesinger, Hlavac, Ten Lectures on Statistical and Structural Pattern Recognition, Chapter 6, Kluwer 2002 (also available in Czech)

Thomas P. Minka, Expectation-Maximization as lower bound maximization, 1998 (short tutorial, available on the internet)