Statistical Machine Learning (BE4M33SSU) Lecture 7: Generative learning, EM-Algorithm

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Generative vs. Discriminative Learning

Maximum Likelihood Estimator, consistency

Expectation Maximisation Algorithm

Generative learning:

- Model the **joint** probability distribution p(x,y) for features $x \in \mathcal{X}$ and hidden states $y \in \mathcal{Y}$
- Inference rule:

$$h(x) \in \underset{y \in \mathcal{Y}}{\operatorname{arg\,max}} \sum_{y' \in \mathcal{Y}} p(y' \mid x) \ell(y', y)$$

• Learning: if the distribution $p_{\theta}(x, y)$ is known up to parameters $\theta \in \Theta$ only \Rightarrow estimate θ^* from training data $\mathcal{T}^m = \{(x^i, y^i) \in \mathcal{X} \times \mathcal{Y} \mid i = 1, ..., m\}$

Discriminative learning(1):

- Model only the **conditional** distributions $p(y \mid x)$
- Learning: if they are known up to parameters $\theta \in \Theta$ only \Rightarrow estimate θ^* by maximising the conditional likelihood on the training data

$$\theta^* \in \operatorname*{arg\,max}_{\theta \in \Theta} \sum_{i=1}^m \log p_\theta(y^i \mid x^i)$$

Inference rule: as above



Discriminative learning(2):

- Model the class of inference rules $h \in \mathcal{H}$ directly.
- Estimate the best inference rule h^* by minimising the empirical risk on the training data

$$h^* \in \underset{h \in \mathcal{H}}{\operatorname{arg\,min}} \frac{1}{m} \sum_{i=1}^m \ell(y^i, h(x^i))$$

Example (Gaussian Discriminative Analysis, Logistic Regression, Linear Classifier)

 $y = 0, 1, y \sim Bernoully(\alpha)$ and $x \in \mathbb{R}^n$, $x|y = 0 \sim \mathcal{N}(\mu_0, \Sigma)$, $x|y = 1 \sim \mathcal{N}(\mu_1, \Sigma)$. The distributions are

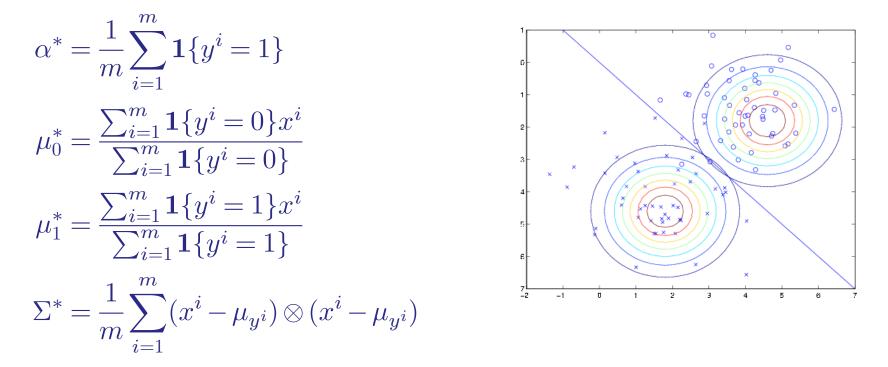
$$p(y) = \alpha^{y} (1 - \alpha)^{1 - y}$$

$$p(x \mid y = 0) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp\left[-\frac{1}{2}(x - \mu_{0}) \cdot \Sigma^{-1} \cdot (x - \mu_{0})\right]$$

$$p(x \mid y = 1) = \frac{1}{(2\pi)^{n/2} |\Sigma|^{1/2}} \exp\left[-\frac{1}{2}(x - \mu_{1}) \cdot \Sigma^{-1} \cdot (x - \mu_{1})\right]$$



Generative learning: Maximum likelihood estimator for training data $\mathcal{T}^m = \{(x^i, y^i) \mid i = 1, \dots, m\}$ gives



Discriminative learning(1): Notice that the posterior conditional probabilities can be expressed as

$$p(y \mid x) = \frac{\exp[y(\langle w, x \rangle + b)]}{1 + \exp[\langle w, x \rangle + b]},$$

i.e. logistic regression, where w and b are some functions of α , μ_0 , μ_1 and Σ .



Estimate \boldsymbol{w} and \boldsymbol{b} by maximising the conditional likelihood on training data

$$(w^*, b^*) \in \underset{w, b}{\operatorname{arg\,max}} \left\{ \sum_{i=1}^m \mathbf{1}\{y^i = 1\} (\langle w, x^i \rangle + b) - \sum_{i=1}^m \log(1 + \exp(\langle w, x^i \rangle + b)) \right\}$$

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The objective is concave in w and b. Its global optimum can be found by gradient ascent.

Discriminative learning(2): The optimal inference rule is a linear classifier. \Rightarrow Learn it by minimising the empirical risk. \Rightarrow SVM

The three methods will provide different decision boundaries when trained on the same dataset. Which one is better?

General answer:

- Generative learning makes stronger assumptions and is more data efficient when the assumptions are (nearly) correct.
- Discriminative learning makes weaker assumptions and is significantly more robust to deviations from model assumptions.

Consistency of the Maximum Likelihood estimator

Let $\mathcal{T}^m = \{z^i \mid i = 1, ..., m\}$ be i.i.d. generated from $p_{\theta_0}(z)$, with $\theta_0 \in \Theta$ unknown.

Which conditions ensure consistency of the MLE $\theta^* = \underset{\theta \in \Theta}{\operatorname{arg\,max}} \log p_{\theta}(\mathcal{T}^m)$?

$$\mathbb{P}_{\theta_0}(\|\theta_0 - \theta^*(\mathcal{T}^m)\| > \epsilon) \xrightarrow{m \to \infty} 0$$

Denote log-likelihood of training data $L(\theta, \mathcal{T}^m) = \frac{1}{m} \sum_{i=1}^m \log p_{\theta}(z^i)$

and expected log-likelihood $L(\theta) = \mathbb{E}_{\theta_0} (L(\theta, \mathcal{T}^m)) = \sum_{z \in \mathcal{Z}} p_{\theta_0}(z) \log p_{\theta}(z)$

Consider $L(\theta, \mathcal{T}^m) = L(\theta) + [L(\theta, \mathcal{T}^m) - L(\theta)]$ and prove that

- $\theta_0 = \underset{\theta \in \Theta}{\operatorname{arg\,max}} L(\theta)$ holds, i.e. the model is identifiable, and
- the Uniform Law of Large Numbers (ULLN) holds, i.e.

$$\mathbb{P}_{\theta_0}\left(\sup_{\theta\in\Theta} |L(\theta,\mathcal{T}^m) - L(\theta)| > \epsilon\right) \xrightarrow{m\to\infty} 0$$

for any $\epsilon > 0$.



Consistency of the Maximum Likelihood estimator

Identifiability of the model θ_0 is easy to prove if $p_{\theta_0}(z) \neq p_{\theta}(z)$ holds $\forall \theta \neq \theta_0$.

Let p(z), q(z) be two probability distributions s.t. $p \not\equiv q$. Then

$$\sum_{z \in \mathcal{Z}} p(z) \log p(z) > \sum_{z \in \mathcal{Z}} p(z) \log q(z)$$

follows from strict concavity of the function log(x):

$$\sum_{z \in \mathcal{Z}} p(z) \log \frac{q(z)}{p(z)} < \log \sum_{z \in \mathcal{Z}} \frac{q(z)p(z)}{p(z)} = \log 1 = 0$$

Sufficient conditions that ensure the **ULLN** e.g.:

• $\Theta \subset \mathbb{R}^k$ is compact, $L(\theta, \mathcal{T}^m)$ is continuous in θ and there is a function $d(z) \ge \log p_{\theta}(z)$ $\forall \theta$ with $\mathbb{E}_{\theta_0}(d(z)) < \infty$,

• $\log p_{\theta}(z)$ is a concave function of θ , $\Theta \subset \mathbb{R}^k$ is convex and $\theta_0 \in \operatorname{int} \Theta$.



Unsupervised generative learning:

- The joint p.d. $p_{\theta}(x,y)$, $\theta \in \Theta$ is known up to the parameter $\theta \in \Theta$,
- given training data $\mathcal{T}^m = \{x^i \in \mathcal{X} \mid i = 1, 2, \dots, m\}$ i.i.d. generated from p_{θ_0} .

How shall we implement the MLE

$$\theta^*(\mathcal{T}^m) = \underset{\theta \in \Theta}{\operatorname{arg\,max}} \frac{1}{m} \sum_{i=1}^m \log p_\theta(x^i) = \underset{\theta \in \Theta}{\operatorname{arg\,max}} \frac{1}{m} \sum_{i=1}^m \log \sum_{y \in \mathcal{Y}} p_\theta(x^i, y)$$

- If θ is a single parameter or a vector of homogeneous parameters \Rightarrow maximise the log-likelihood directly.
- If θ is a collection of heterogeneous parameters ⇒ apply the Expectation Maximisation Algorithm (Schlesinger, 1968, Sundberg, 1974, Dempster, Laird, and Rubin, 1977)



Because the original derivation of the algorithm is somewhat involved, we follow here an alternative approach by Minka (1998):

- Introduce auxiliary variables $\alpha_i(y) \ge 0$, for each $x^i \in \mathcal{T}^m$, s.t. $\sum_{y \in \mathcal{Y}} \alpha_i(y) = 1$
- Construct a lower bound of the log-likelihood $L(\theta, \mathcal{T}^m) \ge L_B(\theta, \alpha, \mathcal{T}^m)$
- Maximise this lower bound by block-wise coordinate ascent.

Construct the bound:

$$L(\theta, \mathcal{T}^m) = \frac{1}{m} \sum_{i=1}^m \log \sum_{y \in \mathcal{Y}} p_\theta(x^i, y) = \frac{1}{m} \sum_{i=1}^m \log \sum_{y \in \mathcal{Y}} \frac{\alpha_i(y)}{\alpha_i(y)} p_\theta(x^i, y) \geqslant$$
$$L_B(\theta, \alpha, \mathcal{T}^m) = \frac{1}{m} \sum_{i=1}^m \sum_{y \in \mathcal{Y}} \alpha_i(y) \log p_\theta(x^i, y) - \frac{1}{m} \sum_{i=1}^m \sum_{y \in \mathcal{Y}} \alpha_i(y) \log \alpha_i(y)$$



Maximise $L_B(\theta, \alpha, \mathcal{T}^m)$ by block-coordinate ascent:

Start with some $\theta^{(0)}$ and iterate

E-step Fix the current $\theta^{(t)}$, maximise $L_B(\theta^{(t)}, \alpha, \mathcal{T}^m)$ w.r.t. α -s. This gives

$$\alpha_i^{(t)}(y) = p_{\theta^{(t)}}(y \mid x^i).$$

M-step Fix the current $\alpha^{(t)}$ and maximise $L_B(\theta, \alpha^{(t)}, \mathcal{T}^m)$ w.r.t. θ .

$$\theta^{(t+1)} = \underset{\theta \in \Theta}{\operatorname{arg\,max}} \frac{1}{m} \sum_{i=1}^{m} \sum_{y \in \mathcal{Y}} \alpha_i^{(t)}(y) \log p_{\theta}(x^i, y)$$

This is equivalent to solving the MLE for complete training data.

Claims:

• The bound is tight if
$$\alpha_i(y) = p_{\theta}(y \mid x^i)$$
,

• The sequence of likelihood values $L(\theta^{(t)}, \mathcal{T}^m)$, t = 1, 2, ... is increasing, and the sequence $\alpha^{(t)}$, t = 1, 2, ... is convergent (under mild assumptions).



Example: A Naive Bayes model for string patterns

- $x = (x_1, \ldots, x_n)$ strings of length n over a finite alphabet \mathcal{B} ,
- k = 0, 1 string pattern class,
- joint distribution Naive Bayes model

$$p(x,k) = p(k) \prod_{j=1}^{n} p(x_j \mid k)$$

Learning problem: Given i.i.d. training data $\mathcal{T}^m = \{x^i \in \mathcal{B}^n \mid i = 1, 2, ..., m\}$, estimate the class probabilities p(k) and the conditional probabilities $p(x_j \mid k)$, $\forall x_j \in \mathcal{B}$, k = 1, 2 and j = 1, ..., n.

Applying the EM algorithm: Start with some model $p^{(0)}(k)$, $p^{(0)}(x_j | k)$ and iterate the following steps until convergence.



E-step Given the current model estimate $p^{(t)}(k)$, $p^{(t)}(x_j | k)$, compute the posterior class probabilities for each string x^i in the training data \mathcal{T}^m

$$\alpha_i^{(t)}(k) = p^{(t)}(k \mid x^i) = \frac{p^{(t)}(k) \prod_{j=1}^n p^{(t)}(x_j^i \mid k)}{\sum_{k'} p^{(t)}(k') \prod_{j=1}^n p^{(t)}(x_j^i \mid k')}$$

M-step Re-estimate the model by

$$p^{(t+1)}(k) = \frac{1}{m} \sum_{i=1}^{m} \alpha_i^{(t)}(k)$$
$$p^{(t+1)}(x_j = b \mid k) = \frac{\sum_{i: x_j^i = b} \alpha_i^{(t)}(k)}{\sum_{i=1}^{m} \alpha_i^{(t)}(k)}$$

