# Lecture 1: Matlab Environment, Basic Math Operators BE0B17MTB - Matlab 

Miloslav Čapek, Viktor Adler, Pavel Valtr, Michal Mašek, and Vít Losenický<br>Department of Electromagnetic Field<br>Czech Technical University in Prague<br>Czech Republic<br>valtrp@fel.cvut.cz

September 24, 2019
Winter semester 2019/20

## Outline

1. MATLAB Environment
2. Scalars, Vectors, Matrices
3. Basic Math Operations
4. Excercises


## The Matlab Environment



## The Matlab Environment - Panels

## 1. Command Window

2. Workspace
3. Command History - not activated, to activate $\rightarrow$
4. Current Folder
5. Current Folder - Details
6. Current Working Directory
7. Status ("Busy" when Matlab is executing your code)
8. Search in documentation


## Preferences



## Documentation


>> help \% MATLAB help
>> demo \% tutorials

## The Help Structure

- Command:

```
>> help sin
```

- Output:

```
sin Sine of argument in radians.
    sin(X) is the sine of the elements of X.
    See also asin, sind, sinpi.
    Reference page for sin
```


## The Documentation Structure I.

- Command:

```
>> doc sin
```

1. Documentation page
2. Search field
3. Documentation contents
4. Bookmarks of this page


## The Documentation Structure II.

- Check the origin of the function.
- Several functions with the same name may exist.
- Functions types by origin:
- Matlab core functions - most of them build-in, some are available for editing (not recommended!).
- Functions from installed toolboxes.
- User-created functions.
- Calling priority for functions will be discussed later.
- During this course, always open a function from core installation.

| $\sin \mid$ | MATLAB |
| :--- | ---: |
| Functions |  |
| $f x \sin$ - Sine of argument in radians | Symbolic Math Toolbox |
| $f x \sin -$ Symbolic sine function | Fixed-Point Designer |
| $f x \sin -$ Sine of fixed-point values | MATLAB |
| $f x \operatorname{sind}$ - Sine of argument in degrees | MATLAB |
| $f x \sinh$ - Hyperbolic sine of argument in radians |  |
| $n 136$ more |  |

## Workspace Browser

- List of variables.
- Deleting/modification of existing variables.
- Saving/loading.
- Values, Class and Memory information.
- Other information can be added: size, min, max, ...
- All information can be obtained using Matlab functions that we learn later, e.g., $\min , \max , \max$, length.
- Fast data plotting option (in ribbon).




## Matlab Commands

- Matlab is cAsE sEnSiTiVe!
- Almost entirely, with certain exceptions (properties of graphics objects, ...).
- Pay attention to typos and variable names (see later).
- New versions of Matlab offer certain options.

```
>> AA = [llll}
>> Aa
```

- Beware of different syntax in Mathematica.
- Following syntax is incorrect both in Matlab and Mathematica:

```
>> Sin(pi/2) % function names start with lower case
>> cos[pi/2] % function input is in parentheses ()
```

- Will be discussed in the next lectures.


## Naming Conventions

- Names of variables can have max. 63 characters starting with letter (>> namelengthmax)
- Letters and numbers are allowed, other symbols (colon ":", hyphen "-" and others) are not.
- Underscore is allowed in the variable name "_" (not at the beginning, though!).
- Lowercase letters in the names of scalars and variables ( $\mathrm{a}=17.59$; ).
- Matrix names usually start with a capital letter ( $\mathrm{A}=[\mathrm{I}$ ]; ).
- Iteration variables, variables used in for cycles usually named $m, n, k$, etc.
- It is advisable to avoid $\mathbf{i}$ and $j$ (complex unit).
- Chose the names to correspond to the purpose of the variable.
- Avoid, if possible, standalone letter "1" (to be confused with one " 1 ") and predefined variables in Matlab environment (see later).
- Choose names corresponding to the meaning of each particular variable.
- Avoid using names of existing functions or scripts (overloading can occur).
- The same conventions are valid for names of functions and scripts.


## Variable Names

- Examples of valid variable names:

```
a, A, b, c, x1, x2, M_12, test1, matrix_A, fx, fX
```

- Examples of invalid variable names:

```
1var % starts with a number (not possible in MATLAB)
matrix A % contains space
coef.a % possible only if coef is of type 'struct'
Test-1 % algebraic expressing: ans = Test - 1
f(y) % makes sense when using symbolic expressinos
```

- Examples of valid numbers in Matlab,
- Pay attention to imaginary unit:

```
3, -66, +0.0015, .015, 1.6025e-10, 3i, 3.17e5i, -3.51j
```


## Functions who, whos

- Function who lists all variables in Matlab Workspace.
- Wide variety of options.
- Functions whos lists the variable names + dimension, size and data type of the variables or displays content of a file.
- Wide variety of options.

```
>> whos('-file', 'matlab.mat');
```

```
>> a = 15; b = true; c = 'test'; d = 1 + 5j;
>> who
>> whos
>> Ws = whos;
```


## Workspace - Output Deletion

- To clean (erase) command window:

```
>> clc
```

- To clean one (or more) variable(s):

```
>> clear % whole Workspace is deleted
>> clear XX % variable XX is deleted
>> clear XX YY % variables XX and YY are deleted
>> clear z* % everything starting with 'z' is deleted
```

- clear has a number of other options (graphics, I/O)


## Command History Window

- Command History window stores all commands from the Command Window.
- Command History is accessible though $\uparrow$ or $\downarrow$.
- it is possible to filter out past commands by, e.g.:
$\gg A=[+\uparrow$.
- It is possible to copy-and-paste entire Command History: SHIFT / CTRL / CTRL + A $\rightarrow$ CTRL +C .


## Matrices in Matlab

- Matrix is a basic data structure in Matlab.
- There are following variables types depending on size:
- scalar: $1 \times 1$
- vector: $M \times 1$ or $1 \times N$
- matrix: $M \times N$
- array (multidimensional matrices):

$$
M \times N \times P \times Q \times R \times \ldots
$$

- Matrices can be complex.
- It can contains text as well (beware the length).
- $M$-by- $N$ matrix:



## Matrix Creation

- Following techniques are available:
- element-by-element entering (suitable for small matrices only),
- colon notation ":" to define elements of series,
- generation by built-in functions,
- generation of matrices in m-files,
- import and export from/to external files(.mat, .txt, .xls, ...).


## Matrix Construction Element-by-element I.

- Test following commands to construct matrices by element enumeration.
- Suitable for small matrices only.

```
>> a1 = -1
```

```
>> v1 = [lllll}-1001
```

>> v1 = [lllll}-1001
>>v2=[-1;0;1]

```
>>v2=[-1;0;1]
```

>> a2 $=[-1]$ \% brackets are redundant

```
>>M1 = [-1 0}101; -2 0 2] [
>> M2 = [-1 -2; 0 0 ; 1 2]
>> M3 = [[l-1 -2]; [0 0}]][% inner brackets are redundant
```

$$
\begin{gathered}
a_{1}=a_{2}=-1 \\
\mathbf{v}_{1}=\left[\begin{array}{rrr}
-1 & 0 & 1
\end{array}\right] \\
\mathbf{v}_{2}=\left[\begin{array}{r}
-1 \\
0 \\
1
\end{array}\right] \\
\mathbf{M}_{1}=\left[\begin{array}{rrr}
-1 & 0 & 1 \\
-2 & 0 & 2
\end{array}\right] \\
\mathbf{M}_{2}=\left[\begin{array}{rr}
-1 & -2 \\
0 & 0 \\
1 & 2
\end{array}\right] \\
\mathbf{M}_{3}=\left[\begin{array}{rr}
-1 & -2 \\
0 & 0
\end{array}\right]
\end{gathered}
$$

## Matrix Construction Element-by-element II.

- Construct following matrices:
- Matrix values are defined inside square brackets [],
- semicolon ";" separates individual rows of a matrix.

$$
\mathbf{A}=\left[\begin{array}{rr}
-1 & -1 \\
1 & -1
\end{array}\right] \quad \mathbf{B}=\left[\begin{array}{lll}
1 & 2 & 3 \\
4 & 5 & 6 \\
7 & 8 & 9
\end{array}\right]
$$

## Matrix Construction

- Semicolon placed at the end of a command suppresses display of the output in Command Window.

```
>> a = 1
>> b = 5;
```

- When there is more than one command on the same line, comma is used to separate each of the commands.

```
>> a = 1, b = 5
>> a = 1; b = 5;
```

- Note: it is possible to copy and paste code including " $\gg$ "
- Row vs column vector:

```
>> c = [11 0 0}
>> d = [0; 0; 1]
```


## Basic Math Operators I.

- Operator types:
- arithmetics:
- matrix,
- vector,
- relational,
- logical and other (to be mentioned later ...).
- Other operations using Matlab functions:
- complex conjugate,
+ addition
- subtraction
* multiplication
- power
transpose
\ left matrix division
/ right matrix division
- sum, determinant, square root,
- and hundreds of other functions ...


## Operator Precedence in Matlab

- According to the following table:
$\checkmark$ see Matlab $\rightarrow$ Language Fundamentals $\rightarrow$ Operators and Elementary Operations $\rightarrow$ Arithmetic

| 1 | parentheses | () |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2 | transpose, power | 1 | . ${ }^{\prime}$ | - | - |  |  |  |  |  |  |  |
| 3 | unary plus, unary minus, logical negation | + | - | ~ |  |  |  |  |  |  |  |  |
| 4 | multiplication, division | * | .* | / | $\backslash$ | . $/$ | .$\$  \hline 5 & addition, subtraction & + & - & & & &  \hline 6 & colon operator & : & & & & &  \hline 7 & relation operators & $<$ | > | <= | >= | == | $=$ |
| 8 | logical AND (element-wise) | \& |  |  |  |  |  |  |  |  |  |  |
| 9 | logical OR (element wise) | I |  |  |  |  |  |  |  |  |  |  |
| 10 | logical AND (short-circuit) | \&\& |  |  |  |  |  |  |  |  |  |  |
| 11 | logical OR (short-circuit) | \\| |  |  |  |  |  |  |  |  |  |  |

## Basic Math Operators II.

- Type in following commands:
- Zero can be omitted with a decimal number beginning with zero (not recommended).

```
>> a3 = -2/4
>> a4=-0.5
>> a5 = -. 5
```

- What is the difference between $a_{3}, a_{4}$ and $a_{5}$ ?
- Beware the precedence of operators (wee see in the next slides):

```
>> 3*5*6
>> a1 = 15
>> a2 = 10;
>> a2/a3
>> a2/a3*a4
>> a2/(a3*a4)
```

- Explain the difference between $a 2 / a 3 * a 4$ and $a 2 /(a 3 / a 4)$.
- Verify the rules of operator precedence from the previous slide.


## Lengthy commands in Matlab

- It is suitable to structure command blocks for clarity:
- next line: SHIFT + ENTER

```
>> A = [1 1 1 1]; B = [2 2 2]; % SHIFT + ENTER
C = [2 3 2 2];
```

- Three dots notation:
- For continuation of the same command on the next line.
- Compare results:

```
>> A1 = [lllll}\begin{array}{ll}{1}&{1}\end{array}\ldots
2 3]
```

```
>> A2 = [lll}\begin{array}{ll}{1}&{1}
2 3]
```


## Basic Math Functions I.

- Math functions in Matlab are generally divided in three groups:
- Scalar:
- Function operates over individual elements of a matrix,
- e.g.: sin, sqrt, log, factorial.
- Vector:
- Function operates over individual rows/columns of a matrix,
- e.g.: sum, max.
- Matrix:
- Function operates over a whole matrix,
- e.g.: det, trace.


## Basic Math Functions II.

- Using Matlab help, calculate the following expression: $a \sin ^{2}(\alpha)+a \cos ^{2}(\alpha)-a$
- Use numerical values your own choice.
- Verify following logarithmic identity: $\log _{10}(a)+\log _{10}(b)-\log _{10}(a b)=0$
- Find sum of all elements in individual rows of the following matrix:

$$
T=\left[\begin{array}{rrrr}
\frac{1}{2} & \frac{1}{3} & \frac{1}{4} & \frac{1}{5} \\
6 & 7 & 7 & 9 \\
0.2 & 0.3 & 0.4 & 0.5
\end{array}\right]
$$

## Basic Math Functions III.

- Assume following vectors $\mathbf{u}=(1,2,3)$ and $\mathbf{v}=(3,2,1)$.
- Calculate:

$$
\begin{array}{lc}
\mathbf{u} \mathbf{v}^{\mathrm{T}} & \mathbf{v} \mathbf{u}^{\mathrm{T}} \\
\mathbf{v}^{\mathrm{T}} \mathbf{u} & \mathbf{u}^{\mathrm{T}} \mathbf{v} \\
\mathbf{u} \cdot \mathbf{v} & \mathbf{u} \times \mathbf{v}
\end{array}
$$

- Following functions are needed:

$$
\begin{aligned}
\mathbf{A} & =\left[\begin{array}{ll}
1 & 2 \\
3 & 4 \\
5 & 6
\end{array}\right] \\
\mathbf{A}^{\mathrm{T}} & =\left[\begin{array}{lll}
1 & 3 & 5 \\
2 & 4 & 6
\end{array}\right]
\end{aligned}
$$

- transpose (.') of a matrix,
- dot scalar product,
- cross product.
- What is the result of the above mentioned operations?


## Matrix Division in Matlab

- Two cases are distinguished:
- left division ( $\backslash$ - mldivide),
- right division (/ - mrdivide).
- Solution of a linear system of equations:
- A is an invertible (regular) matrix,
- b is a row (column) vector.

$$
\begin{array}{rlrl}
\hline \mathbf{A} & \mathrm{x}=\mathrm{b} & \mathrm{x}^{\mathrm{T}} & \mathbf{A}=\mathbf{b}^{\mathrm{T}} \\
\mathbf{A x}=\mathbf{b} & \mathbf{x}^{\mathrm{T}} \mathbf{A}=\mathbf{b}^{\mathrm{T}} \\
\mathbf{x}=\mathbf{A}^{-1} \mathbf{b} & \mathbf{x}^{\mathrm{T}}=\mathbf{b}^{\mathrm{T}} \mathbf{A}^{-1}
\end{array}
$$

```
>> x = A\ b
```

```
>> x = (b.' / A).'
```


## Basic Math Functions IV.

- Find the sum of diagonal elements (trace of a matrix) of the matrix $\mathbf{T}$ with elements coming from normal distribution with mean equal to 10 and standard deviation equal to 4 .
- Find determinant of matrix $\mathbf{U}$.

$$
\mathbf{U}=\left[\begin{array}{ccc}
1 & 2 & 3 \\
0 & 2 & 0 \\
0 & -2 & -1
\end{array}\right]
$$

```
>>U = [1 2 2 3; 0 2 0; ...
0
1];
```

```
>> T = 10 + 4*randn(7, 7);
```

```
>> T = 10 + 4*randn(7, 7);
```

- Solve the linear system of equations:

$$
\begin{array}{rlrl}
x_{1}+2 x_{2}+3 x_{3} & =6 & \mathbf{A x} & =\mathbf{b} \\
4 x_{1}+5 x_{2}+6 x_{3} & =15 & \mathbf{x} & =\mathbf{A} \\
7 x_{1}+8 x_{2}+x_{3} & =16 &
\end{array}
$$

## Predefined Values in Matlab

- Matlab contains several predefined values:
- eps - precision of single/double numbers (Determines the shortest distance between two single/double numbers).
- ans - answer - most recent answer.
- NaN - not a number (every expressing containing NaN is NaN )
- NaN can be used advantageously in some cases.
- Inf - infinite number (variable Inf can be used in calculation:))
- Pay attention to Inf propagation throughout your code (use allowed operations only).
- i, j-complex unit.
- They are all basically functions (without input parameter).
- Check results of the following expressions:

```
>> t1 = 10/0 % t1 = Inf
>> t2 = 0/0 % t2 = NaN
>> t3 = t1*5 % t3 = Inf
>> t4 = t1 + t2 % t4 = NaN
```

- pi, intmin, intmax, realmin, realmax, ... (functions)


## Format of Command Line Output

- Up to now we have been using basic setup.
- Matlab offers number of other formatting options
- Use format style.
- Output format does not change neither the computation accuracy nor the accuracy of stored results (eps, realmax, realmin, ...still apply).

| style | format description |
| :---: | :--- |
| short | fixed 4 decimal points are displayed |
| long | 15 decimal points for double precision, 7 decimal points for single precision |
| shortE | floating-point format (scientific notation) |
| longE | -//- |
| bank | two decimal points only (eur - cents) |
| rat | MATLAB attempts to display the results as a fraction |
| compact | suppressed the display of blank lines |
| and others... | note: omitting style parameter restores default setup |

## Format of Command Line Output

- Try following output format settings:
- Each format is suitable for different type of problems.

```
>> s = [-5 1/2 1/3 10*pi sqrt(2)];
>> format long; s
>> format rat ; s
>> format bank; s
>> format hex; s
>> format +; s
>> format; s
```

- There exist other formats with slight differences.
- Check doc format
- Later, we will learn how to use formatted conversion into strings (commands sprintf and fprintf).


## Complex Numbers I.

- More entry options in Matlab.

```
>> C1 = 1 + 1j % prefered
>> C2 = 1 + 5i % prefered
>> C3 = 1 + i
>> C4 = 1 + j5
>> C5 = sqrt(-1)
>> C6 = complex (1, 2)
```

- Frequently used functions:

| real,imag | real and imaginary part of a com- <br> plex number |
| :---: | :--- |
| conj | complex conjugate <br> abs |
| absolute value of a complex num- |  |
| ber |  |
| complex | angle in complex plane [rad] <br>  <br> isrealreal and imaginary components <br> checks if the input is a complex |
| i, jumber (more on that later) | complex unit <br> $c p l x p a i r ~$ |
| sort complex numbers into com- <br> plex conjugate pairs |  |

real,imag real and imaginary part of a complex number
conj complex conjugate
abs absolute value of a complex num- ber
angle angle in complex plane [rad] constructs complex number from real and imaginary components checks if the input is a complex number (more on that later) sort complex numbers into complex conjugate pairs

## Complex Numbers II.

- Create complex number $z=1+1 \mathrm{j}$ and its complex conjugate $s=z^{*}$.
- Switch between Cartesian and polar form (find $|z|$ and $\varphi$ ).


$$
\begin{aligned}
& z=\operatorname{Re}\{z\}+\operatorname{Im}\{z\}=a+\mathrm{j} b \\
& z=|z| \mathrm{e}^{\mathrm{j} \varphi},|z|=\sqrt{a^{2}+b^{2}} \\
& z=|z|(\cos \varphi+\mathrm{j} \sin \varphi)
\end{aligned}
$$

- Verify Moivre's theorem:

$$
\begin{aligned}
& z^{n}=\left(|z| \mathrm{e}^{\mathrm{j} \varphi}\right)^{n} \\
& z^{n}=|z|^{n}(\cos (n \varphi)+\mathrm{j} \sin (n \varphi))
\end{aligned}
$$

## Exercises

## Exercise I.

- Following forces were localized at point $\mathbf{P}$ in $x y$ plane:

$$
\begin{array}{ll}
\mathbf{F}_{1}=[2,2] & \mathbf{F}_{3}=[2,0] \\
\mathbf{F}_{2}=[1,-3] & \mathbf{F}_{4}=[2,-1.5]
\end{array}
$$

- What is the direction of the resultant force $\mathbf{F}$ ?

- Normalize the resulting vector.

$$
\mathbf{n}_{\mathrm{F}}=\frac{\mathbf{F}}{|\mathbf{F}|}=\frac{\mathbf{F}}{\sqrt{F_{x}^{2}+F_{y}^{2}+F_{z}^{2}}}
$$

## Exercise II.

- Type-in following commands:

```
>> clear, clc;
>> w1 = [llllll}
```



```
>> w3 = [-2; -3; -4]
>> w4 = w1^2, w5 = w2 - w1
```

- Compare differences.
- What is the cause of error in calculation of w4 and w5?
- Try also:

```
>> w3*3, w1 - 3
```

>> w3*3, w1 - 3
>> w1 + [$$
\begin{array}{llll}{5}&{5}&{5}&{5}\end{array}
$$]
>> w1 + [$$
\begin{array}{llll}{5}&{5}&{5}&{5}\end{array}
$$]
>> w6 = 5*w1 - [3 5 6}] - w2

```
>> w6 = 5*w1 - [3 5 6}] - w2
```

- Calculate the norm (magnitude) of vector w1.
- Try more options.
- How to modify the calculation in the case of a complex vector?


## Exercise III.

- Calculate roots of the quadratic function:

$$
-2 x^{2}-5 x=3
$$

- First, rearrange the terms of the function.

$$
\begin{aligned}
& 2 x^{2}+5 x+3=0 \Rightarrow a=2, b=5, c=3 \\
& x_{1,2}=\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a}=\frac{-5 \pm \sqrt{25-24}}{4} \\
& x_{1}=-1, x_{2}=-\frac{3}{2}
\end{aligned}
$$

- Matlab provides particular function for calculation of roots a function, try to search it out.


## Exercise IV.

- Think over how many ways there are to calculate the length of hypotenuse when two legs of a triangle are given.
- Make use of various Matlab operators and functions.
- Consider also the case where the legs are complex numbers.


## Exercise V.

- Create an arbitrary vector $\mathbf{v}$ and rotate it around arbitrary angle $\alpha$ in $x z$ plane using rotation matrix $\mathbf{R}$.

$$
\begin{gathered}
\mathbf{v}^{\prime}=\mathbf{R} \mathbf{v} \\
\mathbf{R}=\left[\begin{array}{ccc}
\cos \alpha & 0 & -\sin \alpha \\
0 & 1 & 0 \\
\sin \alpha & 0 & \cos \alpha
\end{array}\right]
\end{gathered}
$$

## Exercise V.

- Use the following code and round the resulting number to:

```
>> r = 1 + 10*rand(1)
```

- nearest integer,
- nearest integer greater than $r$,
- nearest integer lower than $r$,
- zero,
- zero with precision of 2 decimal digits.
- Find remainder after $r$ is divided by 0.1.
- modulus vs. remainder after division


## Exercise VI.

- Find out the magnitude of a complex vector (avoid indexing).
- Use abs and sqrt.

$$
\begin{gathered}
\mathbf{Z}=\left[\begin{array}{ll}
1+1 \mathrm{j} & \sqrt{2}
\end{array}\right] \\
\|\mathbf{Z}\|=?, \quad \mathbf{Z} \in \mathbb{C}^{2}
\end{gathered}
$$

- Alternatively, use following functions:
- norm
- dot (dot product)
- hypot (hypotenuse)



# Questions? 

BE0B17MTB - Matlab<br>valtrp@fel.cvut.cz

September 24, 2019
Winter semester 2019/20

This document has been created as a part of BE0B17MTB course.
Apart from educational purposes at CTU in Prague, this document may be reproduced, stored, or transmitted only with the prior permission of the authors.
Acknowledgement: Filip Kozak.

